## PERSONAL INFORMATION



## **Dennis Benders**

- Krimpen aan den IJssel, The Netherlands
- **a** +31 (0)15 27 89874
- d.benders@tudelft.nl
- www.github.com/dbenders1
- in www.linkedin.com/in/dennisbenders

Gender Male | Date of birth 01/11/1997 | Nationality(-ies) Dutch

## WORK EXPERIENCE

#### 2021 - Present

# PhD Cognitive Robotics

Delft University of Technology, Delft Research topic: Safe Model Predictive Control (MPC) on mobile robots Ancillary activities:

- Involved in designing and building the mobile robotics lab in the CoR department (motion capture cameras, video cameras, network setup, workplaces, safety measures, etc.): see this and this page
- Responsible for building one of the drone platforms in the research group
- First department PhD representative
- Supervisor of several bachelor groups and master students
- Mentor of master robotics students

Topics of interest: robotics, MPC, software engineering, sustainability

# 2017 - 2018

# Student coordinator Study Choice Check Electrical Engineering

Delft University of Technology, Delft

The Study Choice Check (SCC) is meant to provide high school students more in-depth information about the study. The student coordinator of the SCC has the following tasks: taking care of the communication from university to student for the SCC days of the study Electrical Engineering, guiding the students at the SCC days, and designing the SCC online course.

#### 2016 - 2017

#### Student mentor

Delft University of Technology, Delft

A student mentor is assigned to a group of students to provide a confidential atmosphere and help them in the early phase of the study: guiding students during their first days at the university, organising weekly meetings to discuss recent topics and students' study progress, and being a continuously approachable person in case students encounter difficulties.

#### **EDUCATION AND TRAINING**

# 2018 - 2020

# Master Embedded Systems

Delft University of Technology, Delft

Specialisation: Systems and Control

Graduation project: Drone state estimation using brain-inspired parameter estimation theory

# 2015 - 2018

# **Bachelor Electrical Engineering**

Delft University of Technology, Delft *Minor:* Responsible innovation

#### 2009 - 2015High School VWO graduate

Krimpenerwaard College, Krimpen aan den IJssel

Profile project: "Solar scooter": adding a solar-powered electrical driveline to a normal scooter

#### PERSONAL SKILLS

#### Mother tongue(s)

Dutch

#### Other language(s)

UNDERSTANDING		SPEAKING		WRITING
Listening	Reading	Spoken interaction	Spoken production	
C1	C1	C1	C1	C1
B2	C1	B2	B2	B2

English German

> Levels: A1/A2: Basic user - B1/B2: Independent user - C1/C2: Proficient user Common European Framework of Reference (CEF) level

#### Communication skills

Team work: in teams (technical project teams as well as korfball teams) I have always been the type of person who is really striving for good communication and interaction between everyone who is involved within the team and outside the team.

Mediating skills: as a trust pupil I was trained to lead discussions between people who were having problems with each other and to work towards a solution in a constructive way.

# Organisational / managerial skills

When it comes to project work during my study, in most cases I am the one who takes the lead. This includes organising meetings, thinking about the software architecture, creating project plannings and working towards an atmosphere in which every team member is feeling comfortable.

## Computer skills

The following skills are rated on a scale from 1 (basic level) to 3 (good level):

- programming languages: C/C++ (3), Python (3), ROS (3), Matlab (2)
- tools: Microsoft Office (3), LaTEX (3), Git (3), GanttProject (1)
- operating systems: Windows (3), Linux (3)

# **Driving licence**

B, AM (2015)

## ADDITIONAL INFORMATION

# Hobbies

- sports: playing korfball, running and ice skating
- music: drumming and singing

# **PUBLICATIONS**

Pub<sub>1</sub>

Fred Bas, Ajith Anil Meera, Dennis Benders, and Martijn Wisse. Free energy principle for state and input estimation of a quadcopter flying in wind. In 2022 International Conference on Robotics and Automation (ICRA), pages 5389-5395. IEEE, 2022

Pub2

Anastasios Tsolakis, Dennis Benders, Oscar De Groot, Rudy R. Negenborn, Vasso Reppa, and Laura Ferranti. Colregs-aware trajectory optimization for autonomous surface vessels. IFAC-PapersOnLine, 55(31):269-274, 2022

Pub3

Dennis Benders, Johannes Köhler, Thijs Niesten, Robert Babuška, Javier Alonso-Mora, and Laura Ferranti. Embedded hierarchical mpc for autonomous navigation. arXiv preprint arXiv:2406.11506, 2024