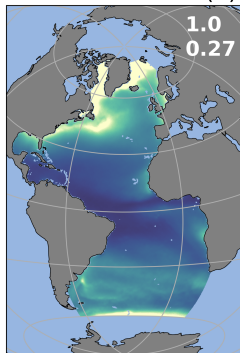


a

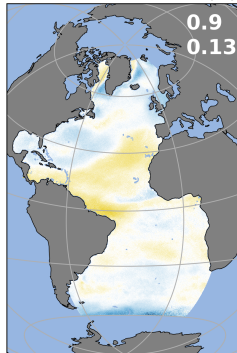
Noise model: PC (1)



0.0 0.5 1.0 1.5
 $\sigma(T_{2m})$ [°C]

b

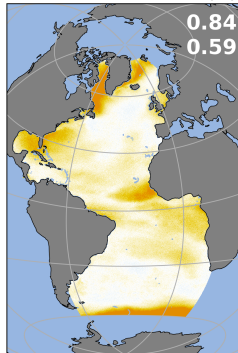
Noise model: PC (1)



-1 0 1
Skewness (T_{2m}) [-]

c

Noise model: PC (1)



-1 0 1
Kurtosis (T_{2m}) [-]

d

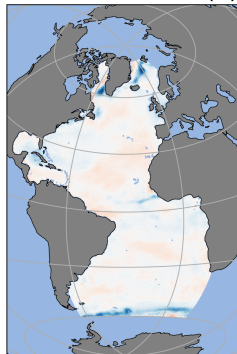
Noise model: PC (1)



-2 0 2
 $\Delta\sigma(T_{2m})$ [°C]

e

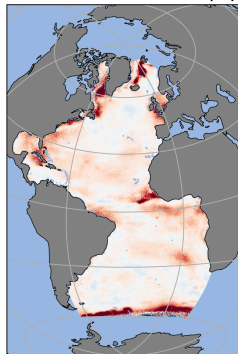
Noise model: PC (1)



-1 0 1
 Δ Skewness (T_{2m}) [-]

f

Noise model: PC (1)



-1 0 1
 Δ Kurtosis (T_{2m}) [-]