

Tabelle 1

	Anton Motor	Fabi IMU + Lok	Jasper + 3d Map	Mechanic		
KW 44	Hardware besorgen	Pi auseinandersetzen	Current state 3d mapping	Planning mechanic		
KW 45	—	Imu Auslesen	Ros 3d mapping, google mapping	Get Hardware		
KW 46	Hardware ansteuern	Lage aus IMU	Implement mapping	Build		
KW 47	Hardware sinnvoll ansteuern	Lage aus IMU	Merge with pose	Build		
KW 48	Gegensteuerung	IMU Merging	Merge with pose	Build		
KW 49	Mechanik Merging	Mechanik Merging	Visual	Mechanik Merging		
KW 50	Mechanikfertigstellung	Meachanikfertigstellung	Mechanikfertigstellung	Mechanikfertigstellung		
KW 51	Test	Test	Test	Track optimization		
KW 52	—	—	—	—		
KW01	—	—	—	—		
KW 02	Präsentation / GUI	Presentation / GUI	Presentation / Visual 3d map	Presentation / Track optimization / Krater building		
KW 03	Completed	Completed	Completed	Completed		
KW 04	Actual Presentation	Actual Presentation	Actual Presentation	Actual Presentation		