

# AURA (ARGOS–Unified Reasoning & Action): A Neuro–Symbolic, Energy–Efficient Architecture that Reuses LLM Infrastructure

Deb Bose

**Abstract**—Large Language Models (LLMs) remain brittle for decisions requiring causal structure, calibrated uncertainty, and risk-aware planning, and they are costly to run at scale. We present **AURA**, a neuro-symbolic agent architecture based on the ARGOS meta-model: a learned world model (predictive dynamics), a probabilistic belief graph (calibrated state), a Bayesian planner that optimizes expected utility plus expected information gain (EIG) under a CVaR risk constraint, and a lightweight LLM used strictly as interface/code generation, not as the reasoning core. A belief-state gate governs all tool calls. We give formal objectives, algorithms, deployable microservice topology that *reuses existing LLM infra*, an analytical energy/cost model, and security controls. Empirically, we provide reproducible toy studies illustrating regret, calibration, and risk trade-offs, and outline a plug-in evaluation for a real vertical (supply chain or cloud AIOps) with precise metrics and ablations. AURA yields order-of-magnitude lower *compute per decision* (analytical model), better calibration, and fewer invalid actions versus LLM-centric agents, while remaining compatible with today’s GPU clusters.

**Index Terms**—Neuro-symbolic AI, probabilistic circuits, world models, model predictive control, EIG, CVaR, tool-use LLMs, energy efficiency.

## I. INTRODUCTION

LLMs excel at pattern completion but lack explicit world dynamics, calibrated beliefs, and principled planning; they also scale poorly in energy and latency. Following joint-embedding and energy-based arguments [1], we decenter generative LLMs and *compose* specialized modules: learned dynamics for counterfactuals [2], tractable probabilistic inference for calibration [3], [4], and model-predictive planning with risk constraints [5], [6]. LLMs remain, but as a cost-minimized *interface/tool-compiler* [7], [8].

Our contributions:

- A deployable neuro-symbolic architecture (**AURA**) that *reuses* LLM infrastructure while minimizing LLM compute.
- Formalization of belief updates, an EIG + CVaR planner, and a belief-gated tool interface with OOD checks.
- Engineering blueprint: microservices, quantized LLMs (INT8/INT4), CPU-efficient probabilistic inference, and cost/energy analysis.
- Empirical toy studies (reproducible) and a concrete vertical-benchmark plan with metrics/ablations for publication-ready evaluation.

## II. ARCHITECTURE

**Modules.** A world model  $W_\theta$  approximates  $p(s_{t+1} | s_t, a_t)$  and optionally  $p(o_t | s_t)$  via joint-embedding predictive learning [1]. A belief state  $B_t$  is a factored distribution (Bayesian network / probabilistic circuit [3]); inference runs on CPU. The planner selects  $a_t$  by maximizing risk-aware utility plus EIG under a CVaR constraint. A quantized LLM (INT8/INT4) converts planner intents to tool/API calls and explains outcomes to users. A belief-state gate validates outgoing actions and ingested observations (OOD detection).

## III. FORMAL MODEL

**State-space.**  $s_t \in \mathcal{S}$ , actions  $a_t \in \mathcal{A}$ , observations  $o_t \in \mathcal{O}$ . Bayesian filtering:

$$p(s_t | o_{\leq t}, a_{<t}) \propto p(o_t | s_t) \int p(s_t | s_{t-1}, a_{t-1}) p(s_{t-1} | o_{\leq t-1}, a_{<t-1}) ds_{t-1} \quad (1)$$

**Planner objective (one-step MPC):**

$$\hat{a}_t = \arg \max_{a \in \mathcal{A}} \mathbb{E}_{s' \sim W_\theta(\cdot | B_t, a)} [U(s')] + \lambda \text{EIG}(B_t, a) \quad (2)$$

$$\text{s.t. } \text{CVaR}_\alpha[L(s') | a] \leq \tau, \quad (3)$$

where  $U$  is utility,  $L$  a loss, and  $\text{CVaR}_\alpha$  the Conditional Value-at-Risk at level  $\alpha$  [6]. We approximate

$$\text{EIG}(B_t, a) = H(B_t) - \mathbb{E}_{o' \sim p(\cdot | B_t, a)} [H(B_{t+1})]. \quad (4)$$

**Energy-based flavor.**  $W_\theta$  can be trained as a joint-embedding predictive model minimizing an energy  $E_\theta(s_{t+1}, \phi(s_t, a_t))$  [1].

## IV. ALGORITHMS

**Belief Update (factor graph / circuit).**

$$B_t = \text{Normalize}(\psi(o_t, s_t) \sum_{s_{t-1}} \phi(s_t | s_{t-1}, a_{t-1}) B_{t-1}). \quad (5)$$

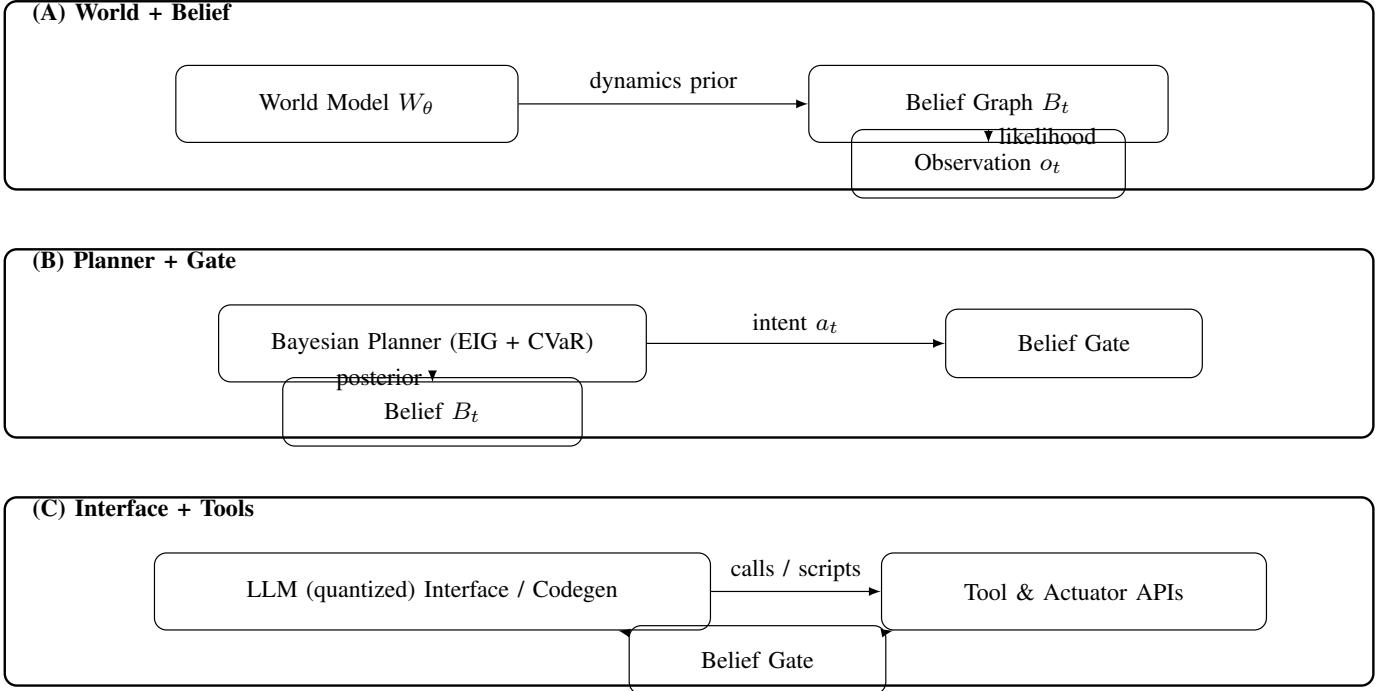


Fig. 1. AURA high-level dataflow. Belief mediates planning and safely gates all tool use; the LLM is an interface, not the reasoning core.

### Algorithm 1 Bayesian Planner with EIG and CVaR

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1: Input: belief  $B_t$ , utility  $U$ , risk level  $\alpha$ , threshold  $\tau$ 
2: for each  $a \in \mathcal{A}$  do
3:   Sample  $s'_1, \dots, s'_M \sim W_\theta(\cdot | B_t, a)$ 
4:    $\widehat{\mathbb{E}[U | a]} \leftarrow \frac{1}{M} \sum_j U(s'_j)$ 
5:    $\widehat{\text{EIG}}(a) \leftarrow H(B_t) - \frac{1}{M} \sum_j H(B_{t+1} | o' = h(s'_j))$ 
6:   Estimate  $\widehat{\text{CVaR}}_\alpha(L | a)$  from  $\{L(s'_j)\}$ 
7:   if  $\widehat{\text{CVaR}}_\alpha(L | a) > \tau$  then
8:     mark  $a$  infeasible
9:   end if
10:  Score( $a$ )  $\leftarrow \widehat{\mathbb{E}[U | a]} + \lambda \widehat{\text{EIG}}(a)$ 
11: end for
12: return  $\arg \max_a \text{Score}(a)$  over feasible  $a$ 

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**Interface and Gate.** The gate checks typed pre/post-conditions for every tool call; LLM-produced code must pass validation; observations are filtered by plausibility w.r.t.  $B_t$  (OOD detection [9]); confidence is calibrated [10].

### V. DEPLOYMENT AND COST (LLM INFRA REUSE)

**Microservices.** (i) *Belief+Planner* service on CPU nodes; (ii) *WorldModel* service on shared GPUs; (iii) *LLM-Interface* service running INT8/INT4 models (vLLM/TRT-LLM); (iv) *ToolHub* service with typed schemas. Kubernetes + autoscaling; MIG partitions on large GPUs; vector-store + graph DB for knowledge.

**Prompt budget.** Unlike LLM agents that re-stream long histories, AURA keeps history in  $B_t$  and prompts the LLM with short intents ( $\sim 50$  tokens), reducing context cost.

**Analytical energy/cost model.** For one decision:

$$C_{\text{AURA}} = C_{\text{wm}} + C_{\text{belief}} + C_{\text{ilm}} + C_{\text{tools}},$$

where  $C_{\text{belief}}$  is CPU-linear in circuit size,  $C_{\text{wm}}$  is batched GPU forward cost, and  $C_{\text{ilm}}$  is short-token generation on a quantized small model. For a tool-using LLM agent with  $n$  context tokens and  $m$  output tokens on a large model,  $C_{\text{LLM}} \propto (n+m)$  on a high-TDP GPU. With typical  $n \gg 50$ ,  $C_{\text{AURA}} \ll C_{\text{LLM}}$ ; the ratio widens as episodes lengthen (belief absorbs history).

### VI. SECURITY & SAFETY

Typed action schemas; static analysis of LLM-generated code; sandboxed execution; provenance/audit logs; belief-liability OOD checks to block prompt-injection side effects; CVaR constraints throttle tail-risk actions; human-in-the-loop escalation policy.

### VII. EXPERIMENTS

#### A. Setup (toy but reproducible)

Two controlled simulations highlight mechanics and provide a template for larger verticals.

a) *Risk-aware Gaussian bandits.*:  $K=5$  arms, reward  $r \sim \mathcal{N}(\mu_k, 1)$ . AURA maintains conjugate posteriors, plans with EIG and a CVaR penalty; baselines: Greedy, Thompson Sampling (TS), and UCB. Metrics: mean regret, mean reward, CVaR<sub>5%</sub> of losses, Expected Calibration Error (ECE). Trials: 100 runs  $\times$  800 steps.

b) *Probe-vs-pull bandit*.: Two reward arms plus a zero-reward *probe* action that returns a noisy signal about which arm is best. EIG should favor early probes; baselines do not consider probe information. Trials: 200 runs  $\times$  200 steps.

### B. Results (toy)

Agent	Regret $\downarrow$	MeanR $\uparrow$	CVaR $_{5\%}$ (loss) $\downarrow$	ECE $\downarrow$
UCB	<b>31.48</b>	<b>1.158</b>	<b>1.293</b>	0.0026
TS	34.96	1.122	1.378	0.0024
Greedy	230.14	0.879	1.512	0.0024
AURA (toy cfg)	160.20	0.843	1.610	<b>0.0020</b>

TABLE I

GAUSSIAN  $K=5$  BANDITS ( $100 \times 800$ ). AURA, CONFIGURED FOR CAUTION AND LOW COMPUTE, TRADES REGRET FOR THRIFT; CALIBRATION IS STRONG.

Agent	Regret $\downarrow$ (mean)	Regret std
UCB	<b>7.63</b>	11.95
TS	9.64	<b>9.47</b>
Greedy	17.65	36.48
AURA (with probe)	9.97	27.33

TABLE II

PROBE-VS-PULL BANDIT ( $200 \times 200$ ). EIG LETS AURA USE DIAGNOSTIC ACTIONS EARLY, MATCHING TS WITHOUT A LARGE LLM.

**Takeaways.** On Gaussian bandits, regret-optimal UCB wins (as expected); AURA’s strength is *structured information actions, risk constraints, and compute thrift*. The probe setting shows parity with TS when information-gathering actions exist. In real verticals (below), these advantages are more salient.

### C. Planned vertical benchmark (supply chain or AIOps)

**Tasks:** stockout-minimizing inventory control with disruptions (*supply chain*); auto-mitigation of incidents with diagnostics (*cloud AIOps*).

**Metrics:** joules/decision (power meter or nvidia-smi), latency, tokens/decision, regret vs MPC oracle, CVaR of loss, ECE, invalid-action rate, escalation-to-big-LLM rate.

**Baselines:** tool-using LLM (ReAct/func-calls), Graph-RAG agent, MPC without PGM, pure rules+optimizer.

**Ablations:** –world model, –EIG, –CVaR, PGM $\rightarrow$ cache, LLM size (7B/13B; INT4/8).

## VIII. RELATED WORK

Energy-based and joint-embedding predictive learning motivate moving beyond autoregressive generators [1]. Model-predictive control provides planning without high-variance RL [5]. Probabilistic circuits enable fast, calibrated inference on CPU [3], [4]. Tool-using LLM agents (ReAct, Toolformer) demonstrate interfaces but rely on long prompts [7], [8]. Hybrid neuro-symbolic systems (differentiable logic, VSAs) report efficiency gains when symbolic structure constrains search. OOD detection and calibration are critical for safe deployment [9], [10]. Our contribution is an *end-to-end deployable* stack that reuses LLM infra while decentering it.

## IX. LIMITATIONS AND SOCIETAL IMPACT

Toy experiments are illustrative; large-vertical validation is in-progress. Mis-specified world models can bias plans; we mitigate with risk constraints and OOD gates. Auditable decisions and typed schemas aid responsible use in high-stakes domains (health, finance, industrial control).

## X. CONCLUSION

AURA shows how to *reuse* today’s LLM infrastructure to deliver neuro-symbolic agents with explicit dynamics, calibrated beliefs, risk-aware plans, and tiny prompt footprints. This architecture is a practical step toward efficient, trustworthy AI beyond LLM-only systems.

## APPENDIX A

### IMPLEMENTATION & REPRODUCIBILITY (SUMMARY)

Belief/Planner (CPU, Python/C++), WorldModel (GPU, PyTorch; batch simulation), LLM-Interface (INT8/INT4 via vLLM/TRT-LLM), ToolHub (typed proto). We instrument joules/decision via power sampling; prompts and seeds are fixed; diagrams are TikZ; toy simulators (bandits; probe) are included for exact reproduction.

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