Dimitrios Boursinos

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EDUCATION

Vanderbilt University, Nashville TN

Ph.D., Electrical Engineering, GPA: 3.88/4

Expected 2021

Cell: (615) 668-0574

 Coursework: Cyber-Physical Systems; Detection & Estimation Theory; Network Security; Model-Integrated Computing; Statistical Pattern Recognition; Design & Analysis of Algorithms; Advanced Real-Time Systems

University of Patras, Patras, Greece

2016

- B.S. & M.S, Electrical and Computer Engineering
- Coursework: Algorithms & Data Structures; Pattern Recognition; Natural Language Technology; Intelligent Control; Microcomputers; Automatic Control Systems; Digital Control Systems; Electrical Machines I & II; Design of Dynamical Systems; Adaptive Control; Robotic Systems; Adaptive Control; Nonlinear Control

WORK EXPERIENCE

Vanderbilt University, Research Assistant, Assured Autonomy

 Developing robustness and assurance methods for Machine Learning Components with focus on classification and regression tasks. 	2018-2020
 Working on a project with Defense Advanced Research Project Agency (DARPA) and Northrop Grumman to estimate robustness levels of autonomous underwater vehicles. 	2018-2020
 Worked on a project by Boeing on safety verification of autonomous controllers on airplanes for navigation through an airport. 	2018-2019
Worked on robust visual perception from cameras for autonomous vehicle applications.	2018
 Developed Reinforcement Learning agents for autonomous vehicles using Deep Neural Networks for vehicle control and obstacle avoidance. 	2017
 Used Extended Kalman Filters as well as Particle Filters for localization of moving robots in indoor environments. 	2017

Vanderbilt University, Teaching Assistant, Deep Learning

• Experience teaching and communicating with students through weekly help sessions and replacing the professor when needed.

The City College of New York, Research Assistant, Biomedical Engineering

2015

- Designed and built a cost efficient electromyograph computer interface that supports 44 channels and connects to a computer over USB to be used on a robotic arm for amputees
- Applied learning algorithms to make the prosthetic adapt to each user's muscle electrical signals.

University of Patras

•	Designed and built a portable, non-contact ECG device intended as a low-cost, continuous	2016
	monitoring solution for persons at risk of cardiac problems. (Diploma Thesis)	2016
•	Motion analysis of robotic swarm formations cooperating for a common goal.	2015
•	Researched pattern recognition methods for detection of forgery in paintings.	2014

LANGUAGES and SKILLS

Python, C, C++, Tensorflow, Matlab, Simulink, Embedded Systems, Simulation Environments RTOS, Linux, Git, Latex, Docker, Embedded Linux

AWARDS

4th place in the 22nd National Olympiad in Computer Science