



# LECTURE 1: INTRODUCTION

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# Outline

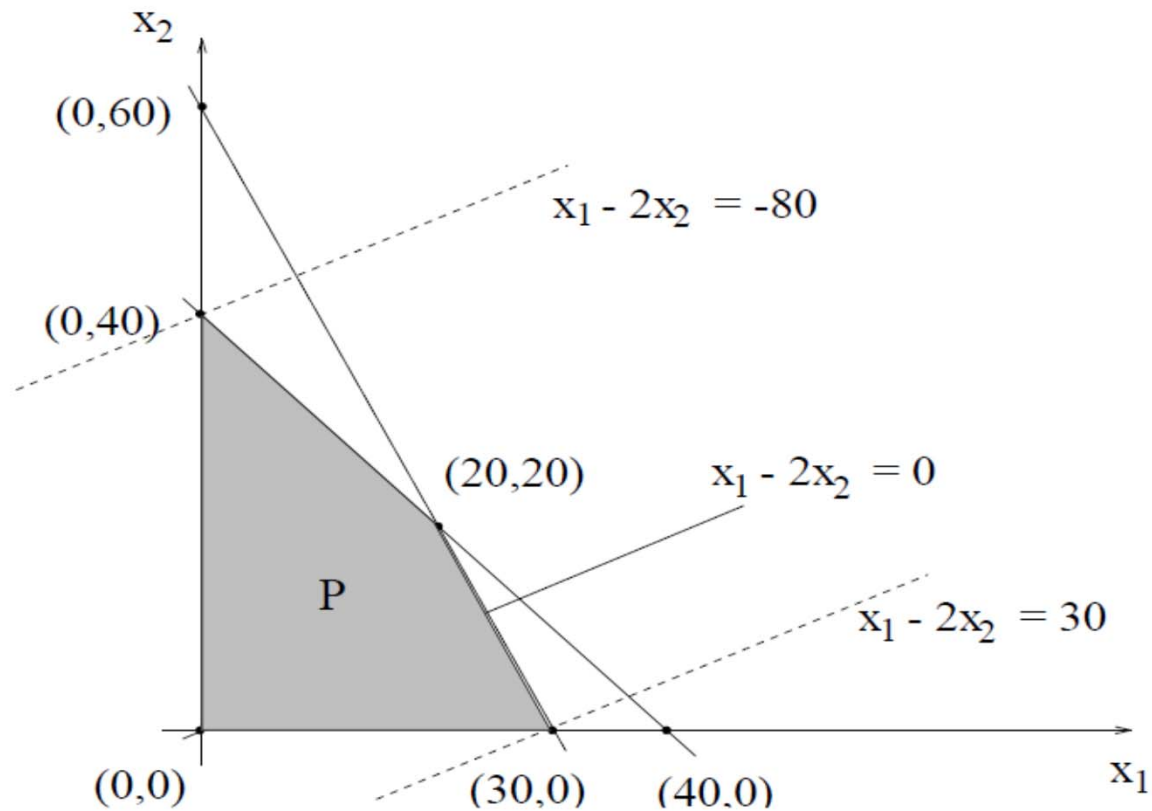
- What is Linear Programming?
- Why to study Linear programming?
- How to study Linear Programming?
- History of Linear Programming
- How to solve an LP problem?
- Where to go?

# What is Linear Programming (LP)?

- Optimize a **linear objective** function of decision variables subject to a set of **linear constraints**.
- Example

$$\begin{array}{ll}\text{Minimize} & x_1 - 2x_2 \\ \text{subject to} & x_1 + x_2 \leq 40 \\ & 2x_1 + x_2 \leq 60 \\ & x_1, x_2 \geq 0.\end{array}$$

# Graphic representation



$$\mathbf{P} = \{(x_1, x_2) \mid x_1 + x_2 \leq 40, 2x_1 + x_2 \leq 60, x_1, x_2 \geq 0\}$$

Feasible Domain

# General form

$$\begin{array}{ll} & \text{linear objective function} \\ \text{Minimize} & \underline{c_1x_1 + c_2x_2 + \cdots + c_nx_n} \\ \text{(Maximize)} & \end{array}$$

s. t.

$m$  linear constraints

$$\left\{ \begin{array}{l} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n \begin{matrix} (<) \\ (=) \\ (>) \end{matrix} b_1 \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n \begin{matrix} (<) \\ (=) \\ (>) \end{matrix} b_2 \\ \vdots \\ a_{m1}x_1 + a_{m2}x_1 + \cdots + a_{mn}x_n \begin{matrix} (<) \\ (=) \\ (>) \end{matrix} b_m \end{array} \right.$$

$$\underbrace{x_1, x_2, \dots, x_n}_{n \text{ decision variables}} \geq 0.$$

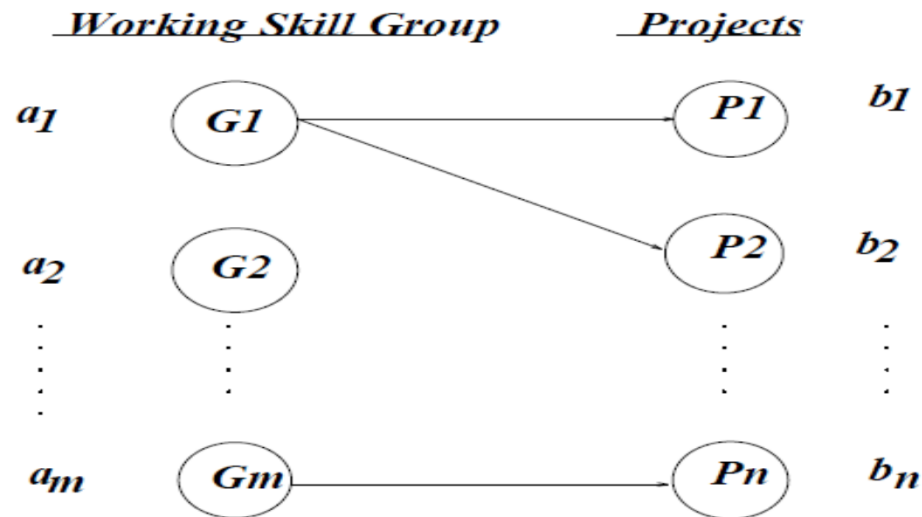
$n$  decision variables

# Why study LP ?

- Wide applications:
  - One of the most widely applied methodologies.
  - 85 % of Fortune 500 companies had used LP models.
- Passage to advanced subjects:
  - Nonlinear Programming
  - Network Flows
  - Integer Programming
  - Conic Programming
  - Semidefinite Programming
  - Robust Optimization

Reference: Operations Research, Vol. 50, No. 1, 2002

# Example – manpower allocation



- $x_{ij}$  = man-hours of skill  $i$  working on project  $j$

$$\begin{aligned}
 &\text{Minimize} && \sum_{i=1}^m \sum_{j=1}^n c_{ij} x_{ij} \\
 &\text{s. t.} && \sum_{i=1}^m x_{ij} \geq b_j, \quad j = 1, \dots, n \\
 &&& \sum_{j=1}^n x_{ij} \leq a_i, \quad i = 1, \dots, m \\
 &&& l_{ij} \leq x_{ij} \leq u_{ij}, \quad \forall i, j.
 \end{aligned}$$

# How to study LP ?

- Geometric intuition
- Algebraic manipulation
- Computer programming



# History of Linear Programming

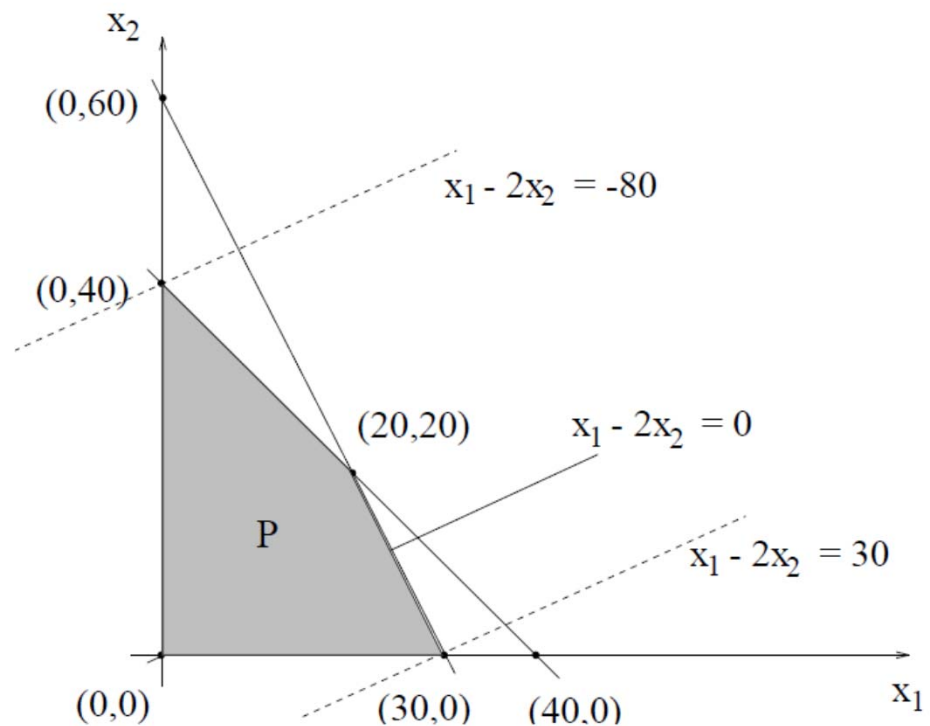
- **Conceived** by G. B. Dantzig (1947).
  - mechanized planning tool for a deployment, training, and logistical supply program in USAF.
- **Named** by T. C. Koopmans & G. B. Dantzig (1948).
- **Simplex Method** proposed by G. B. Dantzig (1948).
  - L. V. Kantorovich worked on a restricted class in 1939.
- Kantorovich & Koopmans received **the Nobel Prize** in Economic Science (1975).
  - Theory of optimum allocation of resources.

# History of Linear Programming

- **Ellipsoid Method** proposed by L. G. Khachian (1979).
  - First polynomial-time algorithm for LP.
- **Interior-Point Method** proposed by N. Karmarkar (1984).
  - First “good” polynomial-time algorithm for LP.

# How to solve an LP problem?

- What's special about LP?
  - **linear constraints** shape the feasible domain as a convex polyhedral set with a finite number of **vertices**.
  - **linear objective** function provides a **linear contour** of each fixed value.

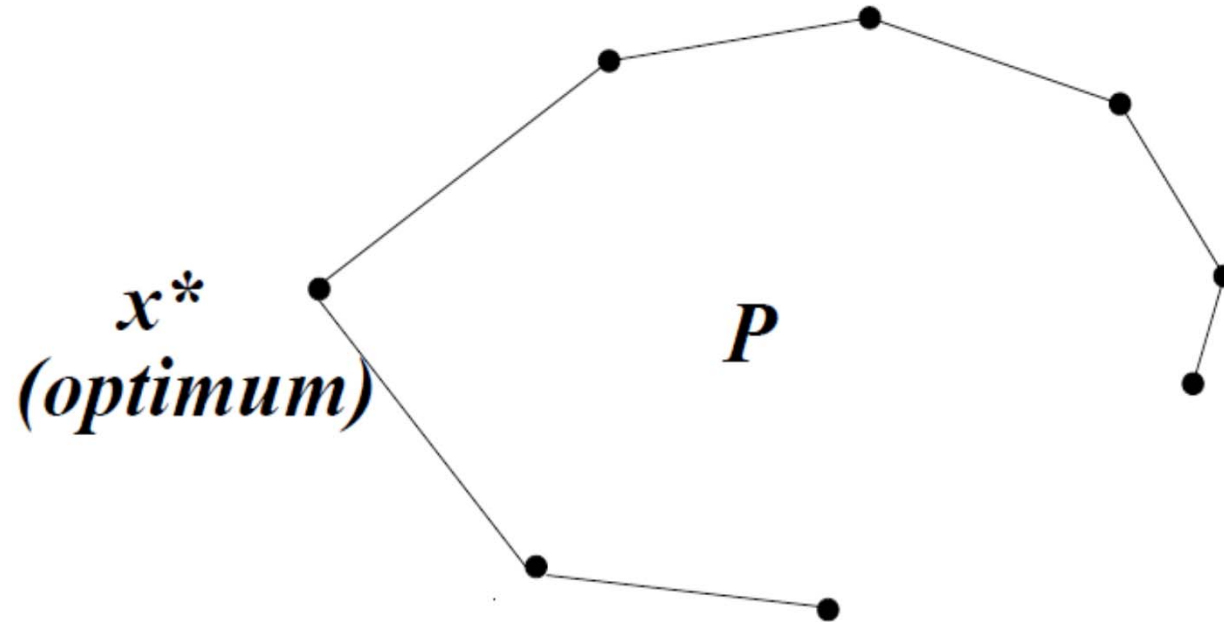


# Fundamental theorem of LP

- For a linear programming problem, if its feasible domain is not empty, then its **optimum** is either unbounded or is attained at least at one **vertex** of the feasible domain.

# How to find an optimal solution?

- Fact:



- Question: How to find  $x^*$  ?

# Different solution methods

- Enumeration Method
  - Find **all vertices** and choose the optimal one by comparison.
  - Impractical when  $C(n, m) = \frac{n!}{m!(n-m)!}$  is large.

$$n = 1000, m = 500 \implies C(n, m) > 10^{15}.$$

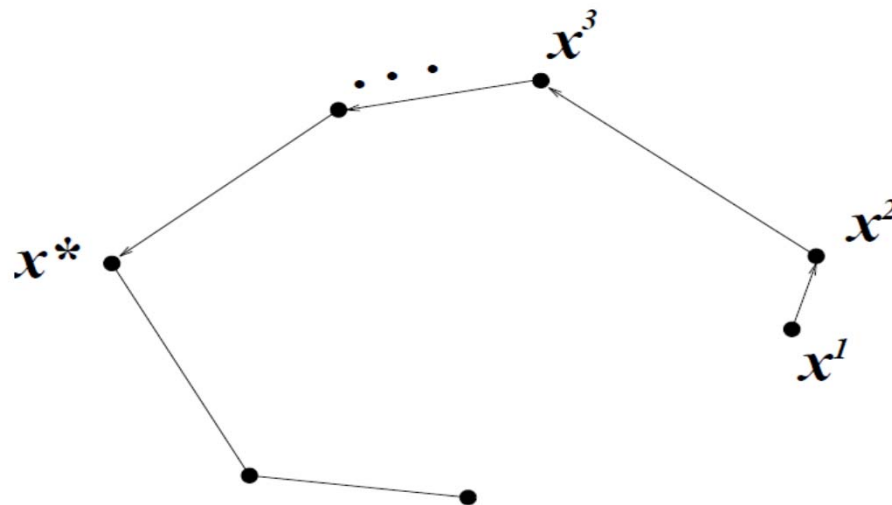
# Simplex Method

- Basic ideas: (walking on the boundary)

Step 1: Start at a **vertex**.

Step 2: If current **vertex** is optimal, STOP! Otherwise,

Step 3: Move to a better neighboring **vertex**. Go To Step 2.



# Is Simplex Method Good?

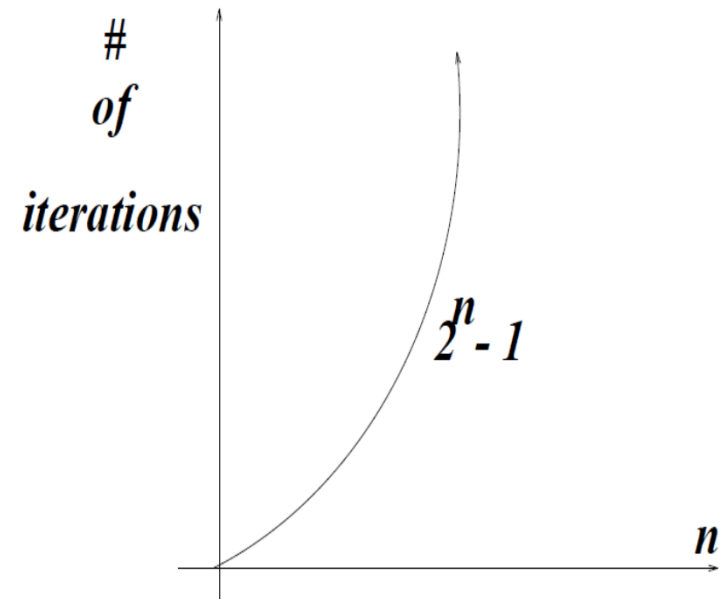
- (1) In general, the simplex method works well,  
it visits about

$$0.7159 m^{0.9522} n^{0.3109}$$

vertices.

- (2) In the worst case, Klee & Minty (1971)  
showed that it requires to traverse  $2^n - 1$   
vertices.

- (3) Problem of exponential-time algorithm.





## Polynomial Time Algorithm

An algorithm runs in polynomial time if the number of steps taken by an algorithm on any instance  $I$  is bounded by a polynomial in the size of  $I$ .

An algorithm runs in exponential time if it does not run in polynomial time.

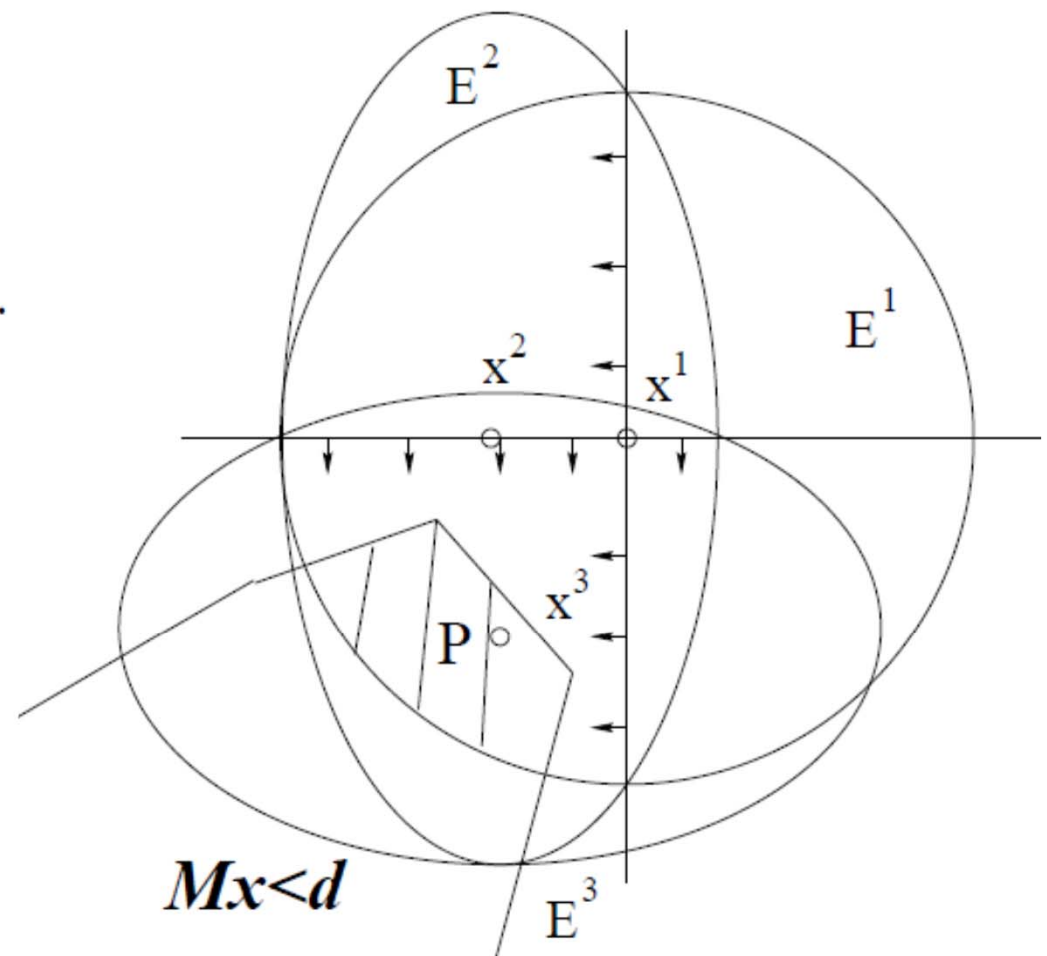
# Is there a polynomial-time algorithm for LP?

- Yes! - Ellipsoid Method by L. G. Khachian 1979.

Basic ideas:

Consider solving  $Mx < d$

$M : m \times n$ ,  $x \in R^n$ ,  $d \in R^m$ .



# Ellipsoid method

LP solution is characterized by the optimality conditions

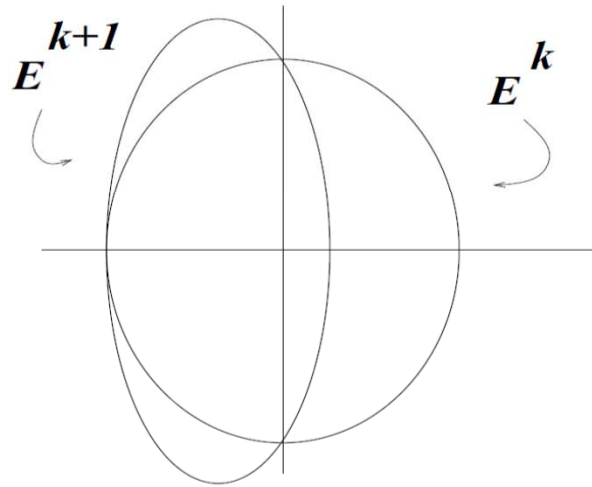
$$(*) \quad \begin{cases} \mathbf{c}^T \mathbf{x} - \mathbf{b}^T \mathbf{w} = 0 \\ \mathbf{A} \mathbf{x} \leq \mathbf{b}, \quad \mathbf{x} \geq \mathbf{0} \\ \mathbf{A}^T \mathbf{w} \geq \mathbf{c}, \quad \mathbf{w} \geq \mathbf{0} \end{cases}$$

# Ellipsoid method

Step 1: In the  $(\mathbf{x}, \mathbf{w})$  space, open a large ellipsoid  $E_0 = S(0, 2^{2L})$ .

Step 2: If the center of the current ellipsoid  $E^k$  solves  $(*)$ , then STOP. Otherwise, replace  $E^k$  by a smaller ellipsoid  $E^{k+1}$ .

Step 3: If  $Vol(E^{k+1})$  is small enough, STOP!  $(*)$  has no solution.



# Is ellipsoid method good?

(1) In theory, since

$$\frac{\text{Vol}(E^{k+1})}{\text{Vol}(E^k)} < e^{-\frac{1}{2}(n+1)}$$

the Ellipsoid Method terminates in polynomial-time.

(2) In practice, it is NOT as good as the Simplex Method.

Complexity =  $O(n^4 L^2)$ .

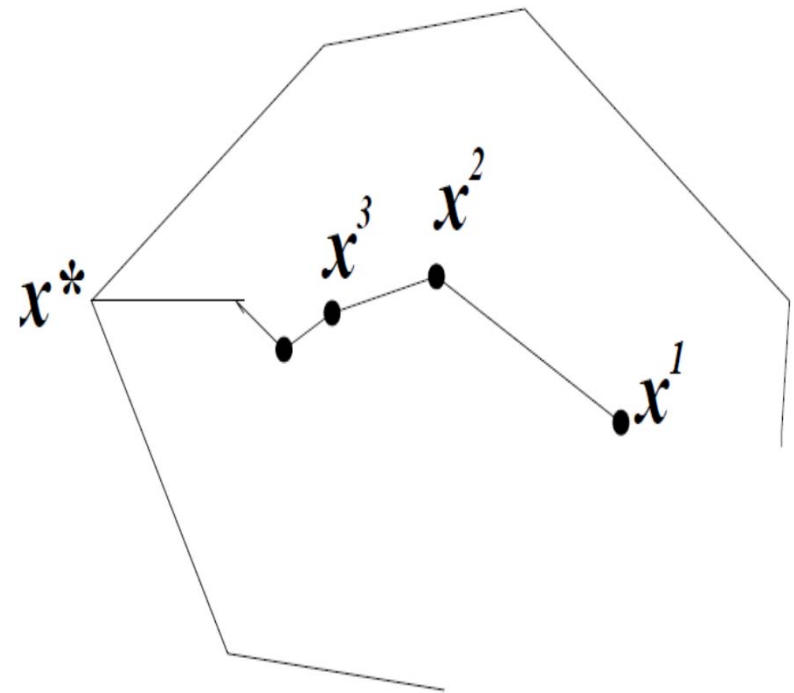
# Is there a good polynomial-time algorithm for LP?

- Yes! - Interior Point Method by Karmarkar in 1984.
- Basic ideas: (walk through interior)

Step 1: Start with an interior solution.

Step 2: If current solution is good enough, STOP. Otherwise,

Step 3: Check all directions for improvement and move to a better interior solution. Go to Step 2.



# Is interior point method good?

- (1) It is a polynomial-time algorithm with complexity =  $O(n^3 L)$ .
- (2) It outperformed the simplex method for large size LP.
- (3) 53 Netlib experiments.

# Where to go?

- Integration of Interior-point methods to develop hybrid algorithms for solving very large size LP for real-world applications by exploring:
  - special structure.
  - sparsity.
  - decomposition.
  - parallel computation.
- Nonlinear optimization with linear constraints.
- Conic Programming.
- Semidefinite Programming.
- Robust optimization