# FunTAL: Reasonably Mixing a Functional Language with Assembly

<u>Daniel Patterson</u>,\* Jamie Perconti,\* Christos Dimoulas,† Amal Ahmed\* June 20, 2017

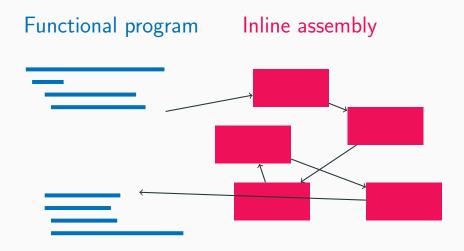
\* Northeastern University, † Harvard University

# Mixed language programs

#### Functional program



## Mixed language programs



#### Questions we want to answer

How to safely mix assembly with high-level code?

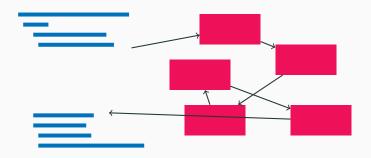
How to reason about equivalence of mixed programs?

#### Questions we want to answer

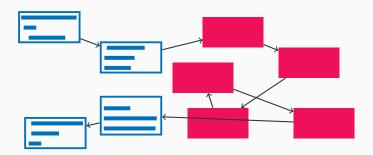
How to safely mix assembly with high-level code?

How to reason about equivalence of mixed programs?

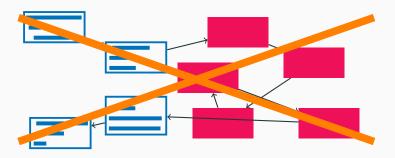
**Option 1:** Translate high-level code into continuation-passing style to match assembly control-flow.



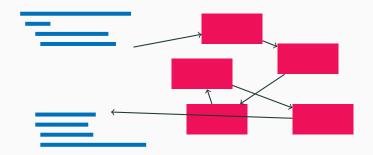
**Option 1:** Translate high-level code into continuation-passing style to match assembly control-flow.



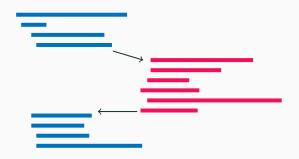
**Option 1:** Translate high-level code into continuation-passing style to match assembly control-flow.



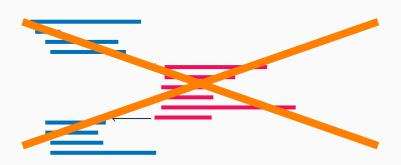
**Option 2:** Impose high-level call-stack control-flow onto assembly.



**Option 2:** Impose high-level call-stack control-flow onto assembly.



**Option 2:** Impose high-level call-stack control-flow onto assembly.



#### Our contributions

Allow safe mixing that allows high-level code to remain high-level and low-level code to remain low-level.

#### Our contributions

Allow safe mixing that allows high-level code to remain high-level and low-level code to remain low-level.

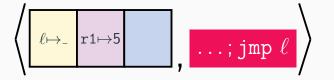
We do this via a novel notion of a **return marker**, which allows us to define the notion of an assembly **component**.

#### Fun: Functional language

- Simply typed lambda calculus (STLC)
- with (iso-)recursive types

[Morrisett, Crary, Glew, Walker '98]
heap registers stack instr. sequence
i.e., basic block  $mv r1, 5; ...; jmp \ell$ 

(Morrisett, Crary, Glew, Walker '98]heap registers stack
instr. sequence
i.e., basic block (heap registers stack) (heap registers stack)

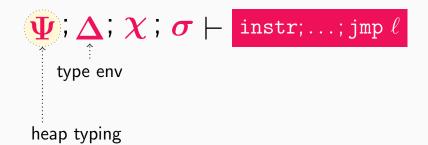


$$\Psi$$
 ;  $\Delta$  ;  $\chi$  ;  $\sigma$   $\vdash$  instr;...;jmp  $\ell$ 



heap typing

[Morrisett, Crary, Glew, Walker '98] heap registers stack instr. sequence i.e., basic block  $mv \ r1, 5; \dots; jmp \ \ell$ 



```
heap registers stack

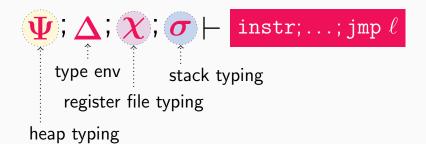
heap registers stack

instr. sequence
i.e., basic block

mv r1, 5; ...; jmp ℓ
```



```
| Morrisett, Crary, Glew, Walker '98|
| heap registers stack | instr. sequence |
| i.e., basic block | mv r1, 5; ...; jmp ℓ |
```



| [Morrisett, Crary, Glew, Walker '98]
| heap registers stack | instr. sequence |
| i.e., basic block | mv r1, 5; ...; jmp ℓ |



```
instr;...; jmp \ell : \forall [\Delta].\{\chi;\sigma\}
```

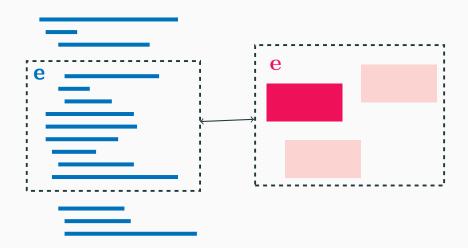
#### TAL types are preconditions

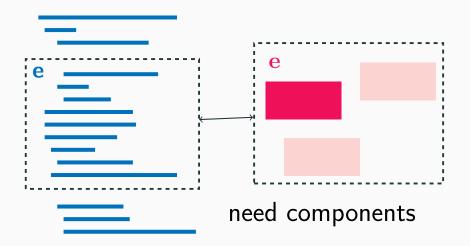
$$: orall [\Delta].\{\chi;\sigma\}$$

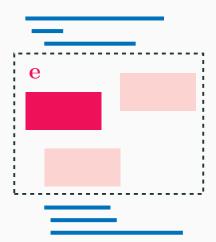
#### TAL types are preconditions

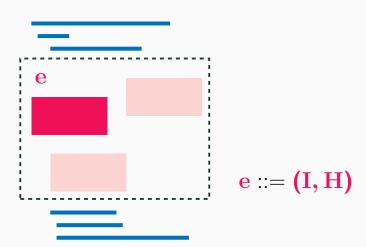
$$: orall [\Delta].\{\chi;\sigma\}$$

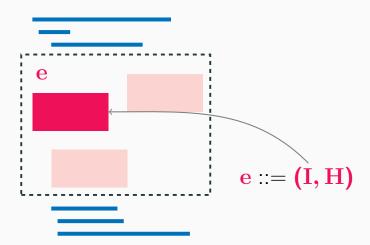
$$\chi_1; \sigma_1 \longrightarrow \chi_2; \sigma_2 \longrightarrow \chi_2; \sigma_2$$

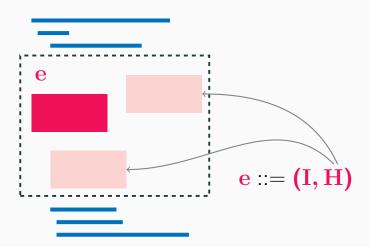


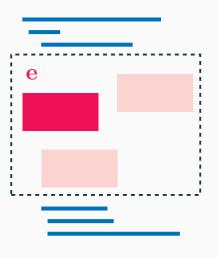












writing this program requires multi-language

[Matthews-Findler '07]

Combine syntaxes from languages S and T and introduce boundary terms.

$$^{\tau}ST(e_T) \mapsto^* {^{\tau}ST(v_T)} \mapsto v_S$$
 $TS^{\tau}(e_S) \mapsto^* TS^{\tau}(v_S) \mapsto v_T$ 

[Matthews-Findler '07]

Combine syntaxes from languages S and T and introduce boundary terms.

$$^{\tau}ST(e_{T}) \mapsto^{*} {^{\tau}ST(v_{T})} \mapsto v_{S}$$
 $TS^{\tau}(e_{S}) \mapsto^{*} TS^{\tau}(v_{S}) \mapsto v_{T}$ 

[Matthews-Findler '07]

Combine syntaxes from languages S and T and introduce boundary terms.

$$^{ au}ST(e_T)\mapsto^* {^{ au}ST(rac{oldsymbol{v_T}}{oldsymbol{v_T}}})\mapsto oldsymbol{v_S}$$
 $TS^{ au}(e_S)\mapsto^* TS^{ au}(oldsymbol{v_S})\mapsto oldsymbol{v_T}$ 

[Matthews-Findler '07]

Combine syntaxes from languages S and T and introduce boundary terms.

$$^{ au}ST(e_T)\mapsto^* {^{ au}ST(v_T)}\mapsto {\color{red}v_S} \ TS^{ au}(e_S)\mapsto^* TS^{ au}(v_S)\mapsto v_T$$

[Matthews-Findler '07]

Boundary translations rely on a cross-language type translation  $(\cdot)^+$ .

$$rac{e_{\mathcal{S}}: au}{TS^{ au}(e_{\mathcal{S}}): au^+} \qquad rac{e_{\mathcal{T}}: au^+}{{}^{ au}ST(e_{\mathcal{T}}): au}$$

#### Multi-languages in general

[Matthews-Findler '07]

Boundary translations rely on a cross-language type translation  $(\cdot)^+$ .

### Multi-languages in general

[Matthews-Findler '07]

Boundary translations rely on a cross-language type translation  $(\cdot)^+$ .

$$rac{e_{\mathcal{S}}: au}{TS^{ au}(e_{\mathcal{S}}): au^+} \qquad rac{e_{\mathcal{T}}: au^+}{{}^{ au}ST(e_{\mathcal{T}}): au}$$

$${}^{oldsymbol{ au}}\mathcal{F}\mathcal{T}(\mathbf{I},\mathbf{H})\mapsto^* {}^{oldsymbol{ au}}\mathcal{F}\mathcal{T}(\mathbf{v})\mapsto\mathbf{v}$$

$${}^{oldsymbol{ au}}\mathcal{F}\mathcal{T}(\mathbf{I},\mathbf{H})\mapsto^* {}^{oldsymbol{ au}}\mathcal{F}\mathcal{T}(\mathbf{v})\mapsto\mathbf{v}$$

(I, H):?

$${}^{oldsymbol{ au}}\mathcal{F}\mathcal{T}(\mathbf{I},\mathbf{H})\mapsto^* {}^{oldsymbol{ au}}\mathcal{F}\mathcal{T}(\mathbf{v})\mapsto\mathbf{v}$$

$$(I, H)$$
:?

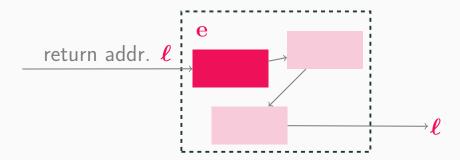
$$(I,H)\mapsto^*$$
?

$${}^{oldsymbol{ au}}\mathcal{F}\mathcal{T}(\mathbf{I},\mathbf{H})\mapsto^* {}^{oldsymbol{ au}}\mathcal{F}\mathcal{T}(\mathbf{v})\mapsto\mathbf{v}$$

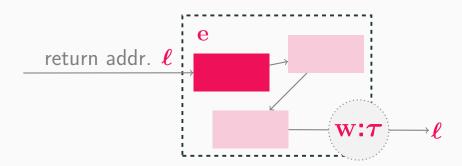
$$(I,H):$$
?

 $(I,H)\mapsto^*$ ?

### TAL components return to address



#### Return value passed to address



$$\Psi$$
;  $\Delta$ ;  $\chi$ ;  $\sigma$ ;  $\mathbf{q} \vdash (\mathbf{I}, \mathbf{H}) : \tau, \sigma'$ 

$$\Psi$$
;  $\Delta$ ;  $\chi$ ;  $\sigma$ ; ra $\vdash$  (I, H):  $\tau$ ,  $\sigma'$ 

{ra : type of codeblock expecting to be passed a  $\tau$  and stack  $\sigma'$ }

$$\Psi$$
;  $\Delta$ ;  $\chi$ ;  $\sigma$ ; ra $\vdash$  (I, H) :  $\tau$ ,  $\sigma'$ 

passed a  $\tau$  and stack  $\sigma'$ 

passed a  $\tau$  and stack  $\sigma'$ 

$$\Psi; \Delta; \chi; \sigma; 2 \vdash (I, H) : \tau, \sigma'$$
 at  $2$  : type of codeblock expecting to be

$${}^{oldsymbol{ au}}\mathcal{F}\mathcal{T}(\mathbf{I},\mathbf{H})\mapsto^* {}^{oldsymbol{ au}}\mathcal{F}\mathcal{T}(\mathbf{v})\mapsto\mathbf{v}$$

$${}^{oldsymbol{ au}}\mathcal{F}\mathcal{T}(\mathbf{I},\mathbf{H})\mapsto^* {}^{oldsymbol{ au}}\mathcal{F}\mathcal{T}(\mathbf{v})\mapsto\mathbf{v}$$

$$\mathbf{v} ::= (\mathtt{halt} \ \mathtt{r}_\mathtt{d}, \mathbf{H})$$

$$oldsymbol{ au} \mathcal{F} \mathcal{T}(\mathbf{I}, \mathbf{H}) \mapsto^* oldsymbol{ au} \mathcal{F} \mathcal{T}(\mathbf{v}) \mapsto \mathbf{v}$$
  $\mathbf{v} ::= ( ext{halt } \mathbf{r}_{ ext{d}}, \mathbf{H})$ 

$$\Psi; \Delta; \chi[\mathtt{r1}: au]; \sigma; \mathrm{end}\{ au; \sigma\} \vdash (\mathtt{halt}\ \mathtt{r1}, \mathbf{H}) : au, \sigma$$

$$egin{aligned} oldsymbol{ au} \mathcal{F} \mathcal{T}(\mathbf{I}, \mathbf{H}) &\mapsto^* oldsymbol{ au} \mathcal{F} \mathcal{T}(\mathbf{v}) &\mapsto \mathbf{v} \ &\mathbf{v} ::= (\mathtt{halt} \ \mathbf{r}_{\mathsf{d}}, \mathbf{H}) \end{aligned}$$

$$\Psi; \Delta; \chi[\mathtt{r1}: au]; \sigma; \mathbf{end}\{ au; \sigma\} \vdash (\mathtt{halt}\ \mathtt{r1}, \mathbf{H}) : au, \sigma$$

$$oldsymbol{ au} \mathcal{F} \mathcal{T}(\mathbf{I}, \mathbf{H}) \mapsto^* oldsymbol{ au} \mathcal{F} \mathcal{T}(\mathbf{v}) \mapsto \mathbf{v}$$
  $\mathbf{v} ::= ( ext{halt } \mathbf{r}_d, \mathbf{H})$ 

$$\Psi; \Delta; \chi[\mathbf{r1}: \tau]; \sigma; \mathrm{end}\{\tau; \sigma\} \vdash$$

$$(\mathrm{halt} \ \mathbf{r1}, \mathbf{H}): \tau, \sigma$$

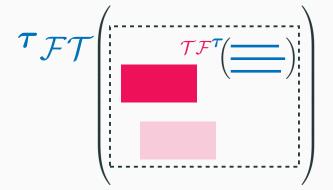
$$egin{aligned} oldsymbol{ au} \mathcal{F} \mathcal{T}(\mathbf{I}, \mathbf{H}) &\mapsto^* oldsymbol{ au} \mathcal{F} \mathcal{T}(\mathbf{v}) &\mapsto \mathbf{v} \ &\mathbf{v} ::= (\mathtt{halt} \ \mathbf{r}_\mathtt{d}, \mathbf{H}) \end{aligned}$$

$$\Psi; \Delta; \chi[\mathtt{r1}: \overline{\boldsymbol{\tau}}]; \sigma; \mathrm{end}\{\overline{\boldsymbol{\tau}}; \sigma\} \vdash (\mathtt{halt}\ \mathtt{r1}, \mathbf{H}): \overline{\boldsymbol{\tau}}, \sigma$$

$$\begin{array}{c} \boldsymbol{\tau}_{\mathcal{FT}(\mathbf{I},\mathbf{H})} \mapsto^* \ \boldsymbol{\tau}_{\mathcal{FT}(\mathbf{v})} \mapsto \mathbf{v} \\ \\ \mathbf{v} ::= (\mathtt{halt} \ \mathbf{r}_{\mathtt{d}},\mathbf{H}) \end{array}$$

$$\Psi; \Delta; \chi[\mathtt{r1}: \tau]; \sigma; \mathrm{end}\{\tau; \sigma\} \vdash (\mathtt{halt}\ \mathtt{r1}, \mathbf{H}) : \tau, \sigma$$

### Embedding Fun in TAL



import 
$$r_d, \mathcal{TF}^{\mathsf{T}}(\mathbf{v}) \mapsto mv r_d, \mathbf{w}$$

where  $\mathbf{v}: \tau \leadsto \mathbf{w}: \tau^+$ 

import 
$$r_d, \mathcal{TF}^{\mathsf{T}}(\mathbf{v}) \mapsto mv r_d, \mathbf{w}$$

where  $\mathbf{v}:\boldsymbol{\tau} \leadsto \mathbf{w}:\boldsymbol{\tau}^+$ 

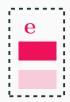
import 
$$r_d, \mathcal{TF}^{\tau}(v) \mapsto mv r_d, w$$

where  $\mathbf{v}: \boldsymbol{\tau} \leadsto \mathbf{w}: \boldsymbol{\tau}^+$ 

import 
$$\mathbf{r}_{d}, \mathcal{TF}^{\mathsf{T}}(\mathbf{v}) \mapsto \text{mv } \mathbf{r}_{d}, \mathbf{w}$$

where  $\mathbf{v}:\boldsymbol{\tau} \leadsto \mathbf{w}:\boldsymbol{\tau}^+$ 

# So far, q can be ra, n, end $\{\tau; \sigma\}$



So far,  $\mathbf{q}$  can be  $\mathbf{ra}$ ,  $\mathbf{n}$ ,  $\mathbf{end}\{\boldsymbol{\tau}; \boldsymbol{\sigma}\}$ 



$$\Psi$$
;  $\Delta$ ;  $\chi$ ;  $\sigma$ ; ra  $\vdash$  e :  $\tau$ ,  $\sigma'$ 

With these return markers, preconditions on e must specify all subsequent return markers.

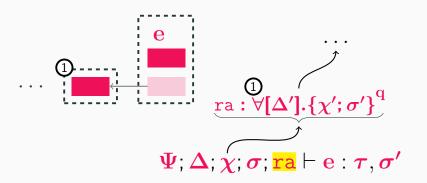
So far,  $\mathbf{q}$  can be  $\mathbf{ra}$ ,  $\mathbf{n}$ ,  $\mathbf{end}\{\boldsymbol{\tau}; \boldsymbol{\sigma}\}$ 



$$\Psi; \Delta; \chi; \sigma; \mathbf{ra} \vdash \mathbf{e} : \tau, \sigma'$$

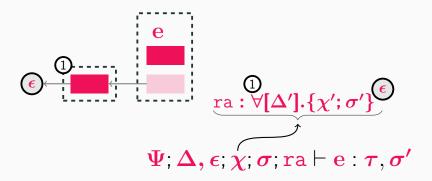
With these return markers, preconditions on e must specify all subsequent return markers.

So far, q can be ra, n,  $\operatorname{end}\{\tau;\sigma\}$ 



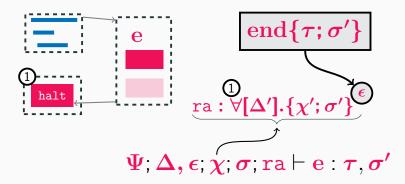
With these return markers, preconditions on e must specify all subsequent return markers.

# Components need polymorphic q



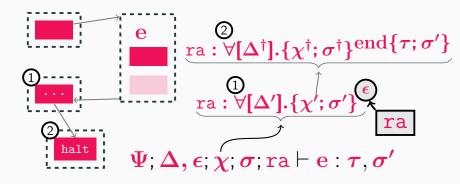
With polymorphic return marker  $\epsilon$ , caller instantiates with where control flows next.

# Components need polymorphic q



With polymorphic return marker  $\epsilon$ , caller instantiates with where control flows next.

# Components need polymorphic q



With polymorphic return marker  $\epsilon$ , caller instantiates with where control flows next.

### Questions we want to answer

How to safely mix assembly with high-level code?

How to reason about equivalence of mixed programs?

#### Questions we want to answer

How to safely mix assembly with high-level code? ✓

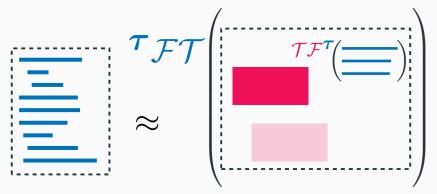
How to reason about equivalence of mixed programs?

#### Questions we want to answer

How to safely mix assembly with high-level code? ✓

How to reason about equivalence of mixed programs?

# Proving program equivalence



Need logical relation for multi-language.

$$\mathbf{e}: \boldsymbol{ au} pprox {}^{\scriptscriptstyle au} \mathcal{F} \mathcal{T} (\mathbf{e}: \boldsymbol{ au}^+)$$
 means

$$\mathbf{e} \mapsto^* \mathbf{v_1} \iff \mathcal{FT}(\mathbf{e}) \mapsto^* \mathbf{v_2}$$

and  $\mathbf{v_1} \approx \mathbf{v_2}$ 

$$\mathbf{e}: \boldsymbol{\tau} \approx {}^{\scriptscriptstyle T} \mathcal{F} \mathcal{T} (\mathbf{e}: \boldsymbol{\tau^+})$$
 means

$$\mathbf{e}\mapsto^*\mathbf{v_1}\iff\mathcal{FT}(\mathbf{e})\mapsto^*\mathbf{v_2}$$
 and  $\mathbf{v_1}\approx\mathbf{v_2}$ 

$$\mathbf{e}: \boldsymbol{ au} pprox {}^{\scriptscriptstyle au} \mathcal{F} \mathcal{T} (\mathbf{e}: \boldsymbol{ au}^+)$$
 means

$$\mathbf{e}\mapsto^*\mathbf{v_1}\iff\mathcal{FT}(\mathbf{e})\mapsto^*\mathbf{v_2}$$
 and  $\mathbf{v_1}\approx\mathbf{v_2}$ 

$$\mathbf{e}: \boldsymbol{ au} pprox {}^{\scriptscriptstyle au} \mathcal{F} \mathcal{T} (\mathbf{e}: \boldsymbol{ au}^+)$$
 means

$$\mathbf{e} \mapsto^* \mathbf{v_1} \iff \mathcal{FT}(\mathbf{e}) \mapsto^* \mathbf{v_2}$$

and  $v_1 \approx v_2$ 

$$\mathbf{e}: \boldsymbol{ au} pprox {}^{ au} \mathcal{F} \mathcal{T} (\mathbf{e}: \boldsymbol{ au}^+)$$
 means

$$\mathbf{e}\mapsto^* \mathbf{v_1} \iff \mathcal{FT}(\mathbf{e})\mapsto^* \mathbf{v_2}$$
 and  $\mathbf{v_1}\approx \mathbf{v_2}$ 

Write 
$$\mathbf{v_1} \approx \mathbf{v_2}$$
 as  $(\mathbf{v_1}, \mathbf{v_2}) \in \mathcal{V}(\boldsymbol{\tau})$ .

#### Equivalence of functions

$$(\lambda \mathsf{x.}\; \mathsf{e_1}, \lambda \mathsf{x.}\; \mathsf{e_2}) \in \mathcal{V}(oldsymbol{ au_1} o oldsymbol{ au_2})$$

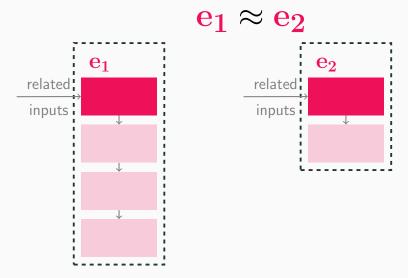
### Equivalence of functions

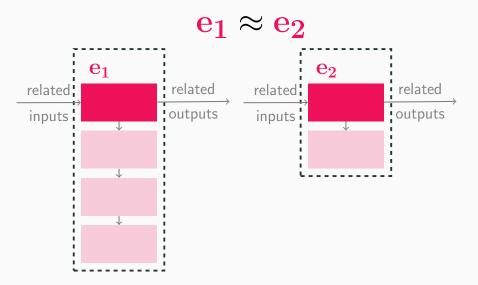
$$(\lambda \mathsf{x.}\ \mathsf{e}_1, \lambda \mathsf{x.}\ \mathsf{e}_2) \in \mathcal{V}(oldsymbol{ au}_1 o oldsymbol{ au}_2)$$

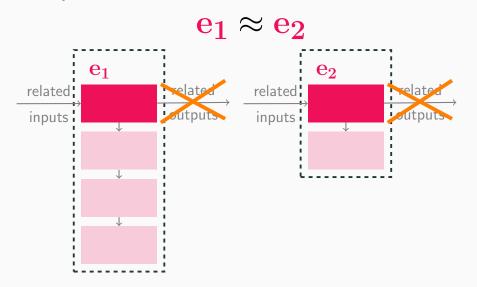
"Related inputs result in related outputs"

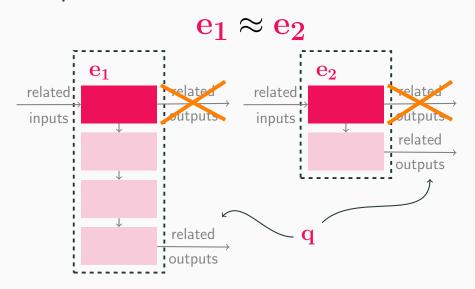
#### Equivalence of functions

"Related inputs result in related outputs"









## Questions we want to answer

How to safely mix assembly with high-level code? ✓

How to reason about equivalence of mixed programs?

## Questions we want to answer

How to safely mix assembly with high-level code?

How to reason about equivalence of mixed programs? ✓

Verification of some types of JIT transformations.

- Verification of some types of JIT transformations.
- Correctness for compilers targeting TAL
   (as suggested by [Perconti-Ahmed '14]).

- Verification of some types of JIT transformations.
- Correctness for compilers targeting TAL
   (as suggested by [Perconti-Ahmed '14]).
- Using return markers for slightly higher level (i.e., SSA-like) languages.

#### Conclusion

Return markers allow safe mixing of components where high-level code remains high-level and low-level remains low-level.

See paper for (much) more detail and a web-based interpreter for FunTAL.