Intermediate Graphics & Animation Programming

GPR-300
Daniel S. Buckstein

Keyframe Systems Weeks 10 – 11

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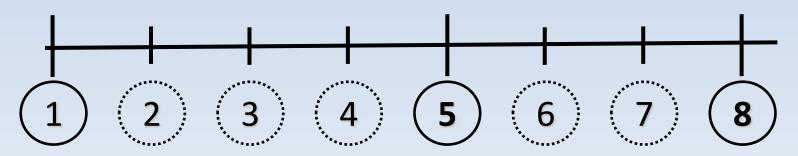
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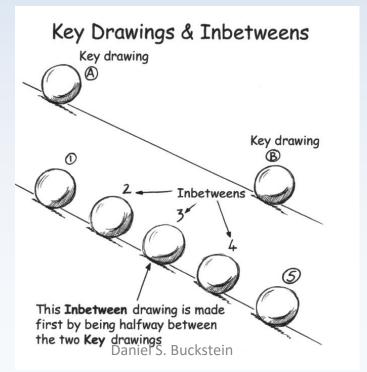
- Familiarize yourself with the 12 principles of animation
- Main takeaway for animation programming:
 All else means nothing without timing
- Today we look at the straight-ahead and poseto-pose principle
- These describe two main types of animation

- Straight-ahead animation:
- Frame-by-frame
- Example: stop-motion \rightarrow
- Pros: full control over every single detail
- Cons: a lot of work, very time consuming to complete



- Pose-to-pose animation:
- Create keyframes, resolve in-betweens later
- Technique: onion-skinning
- Pros: keyframes are fixed, in-betweens are variable and can be adjusted as-needed





- Computer animation works because of poseto-pose
- We define keyframes and let algorithms take care of the in-betweens!
- Straight-ahead is useful for only some applications, like sprite animation
- For complex things, there is simply too much data... we need to make our lives easier!

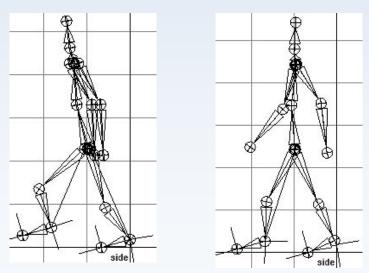
- Straight-ahead animation:
- Every frame is a keyframe!



- So what is a keyframe, really?
- Can be defined as "Frames that are more important or denote some key moment or action in a sequence"
- This is the theoretical definition
- In practice, keyframes are just poses
- Keyframes put the 'pose' in "pose-to-pose"

(both of them!)

- Keyframes:
- A keyframe is just a known pose for whatever object or character we are dealing with
- Example: walk cycle



Keyframe 30 Daniel S. Buckeyframe 50

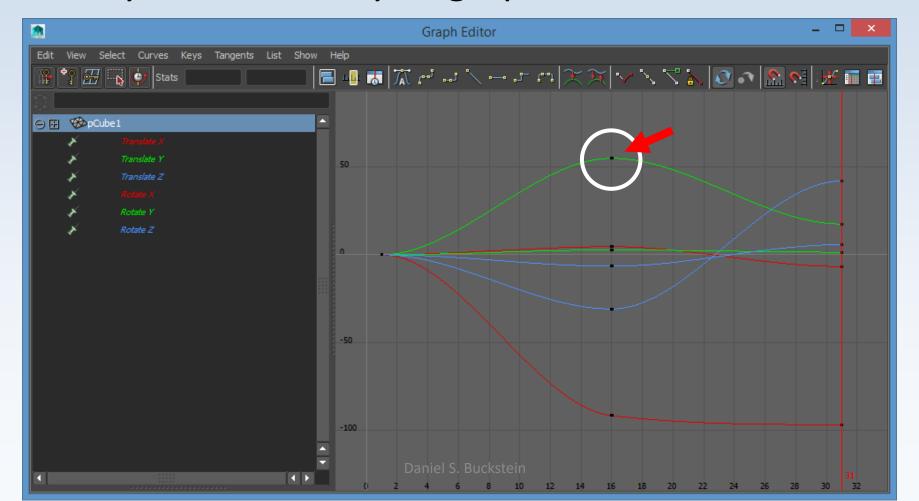
http://users.design.ucla.edu/~cariesta/MayaCourseNotes



http://www.cs.utexas.edu/~okan/papers/s2003/pictures/fig1.jpg

- Keyframes:
- Even calling a keyframe a "known pose" is too specific...
- A pose is really just the state of a set of data
- A keyframe is fundamentally just the known values in a set of data
- Each individual variable can have keyframes, so really keyframes are just known numbers!

Keyframes in Maya's graph editor:



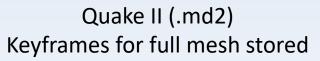
- Pose:
- A pose is just a set of data that is keyframed
- Has keyframes and in-betweens for all values
- Pose itself can be keyframed...
- This just means that all of its values have a keyframe at the same time

What kinds of data describe a pose?

- Position (vector)
- Orientation (rotation matrix or quaternion)
- Sometimes scale (uniform, non-uniform)

- Games use keyframes extensively
- Many different applications:
- Morph targets
 - Mesh is deformed into poses, we just morph between full meshes
- Skeletal animation
 - Bones define the poses, mesh conforms to bones
- What else???





http://www.youtube.com/watch?v=NUHudbgxWfY

http://www.youtube.com/watch?v=rO37U8KLRws



.md3
separate meshes
keyframes stored



.md5
only keyframes of
skeleton stored

http://www.youtube.com/watch?v=y I7tMfiU&feature=related

http://www.youtube.com/watch?v=
tzyuIsdT8GY&feature=results video
&playnext=1&list=PL342E78FF3096F

http://www.youtube.com/w atch?v=5ulVvAqtaQ&feature=BFa&list=P L342E78FF3096F00E&lf=res ults video

- Problems:
- Inflexible
- Hard to incorporate keyframe animation into physics
 - Both have their own way of controlling things
- Hard to interact with an object while it undergoes keyframe animations
 - Frames are determinate, interactions are not!

- But on the bright side, good advantages:
- Keyframe animation (pose-to-pose) is very easy to implement on a computer!
- Can tweak animations effectively to achieve desired effect, outcome, sequences

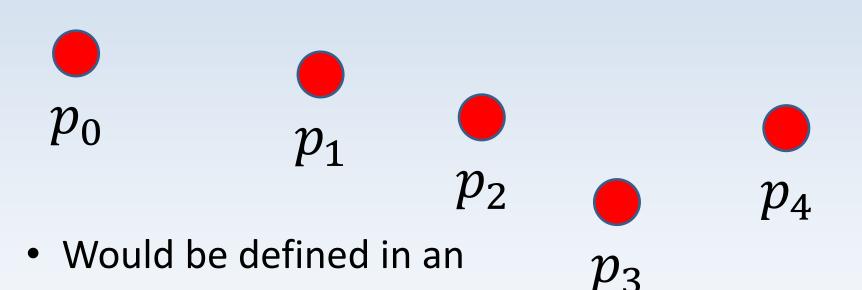
- Now we have all the words in "pose-to-pose" covered... what next?
- Let's apply LERP to keyframe animation!
- How would you build a simple keyframed locomotion system?
- I.e. actual walking aside, how would we get Watson from location to location?
 - ...instead of having him creepily teleport

- Determine what your keyframes actually represent, data-wise
- Examples (again):
 - Position
 - Orientation
 - Scale
 - Whatever other property
 you may be concerned with

 For Watson, let's keep it simple and say that one keyframe is just a known position in space

 Create a bunch of these to determine our "path" that Watson is to follow, store in some kind of list

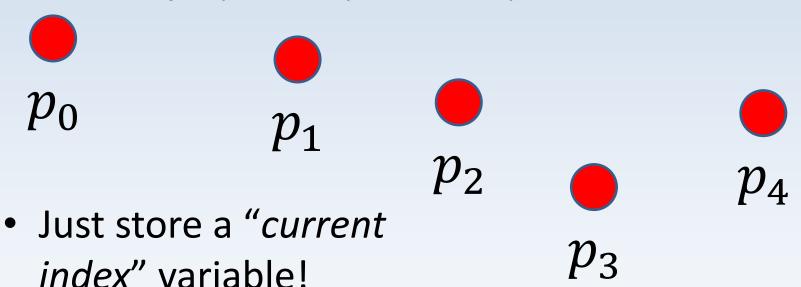
Watson's locomotion keyframes:



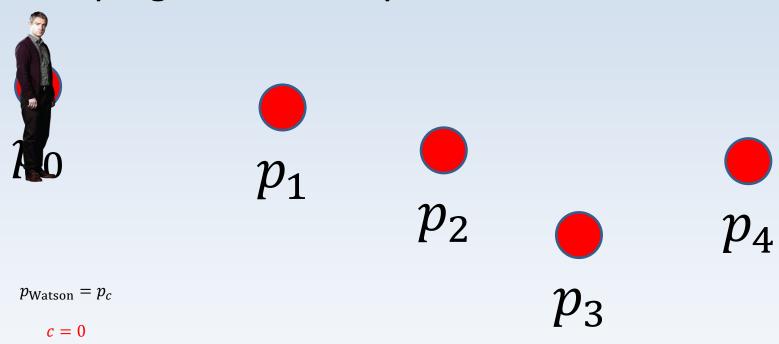
array or list of some sort...

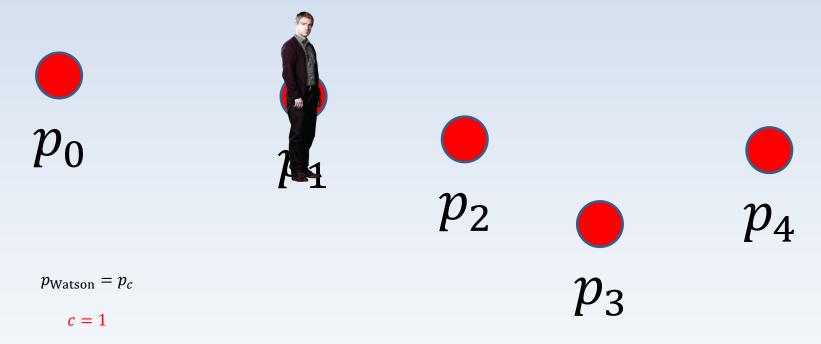
The subscripts are just indices!!!

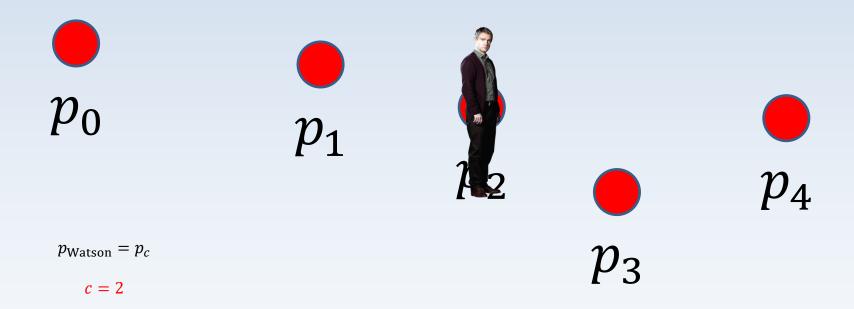
- How do we toggle the current keyframe?
 - I.e. jump from keyframe to keyframe?

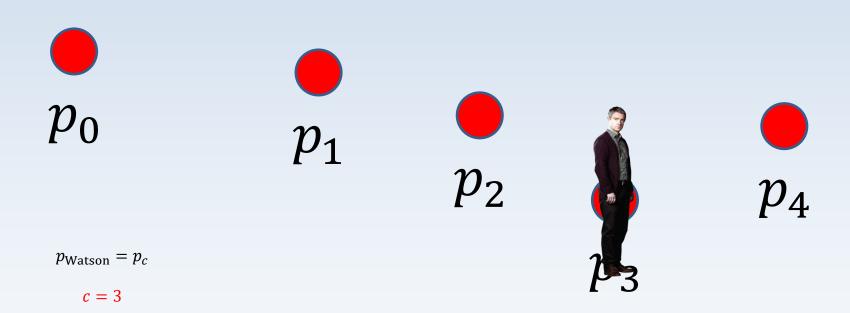


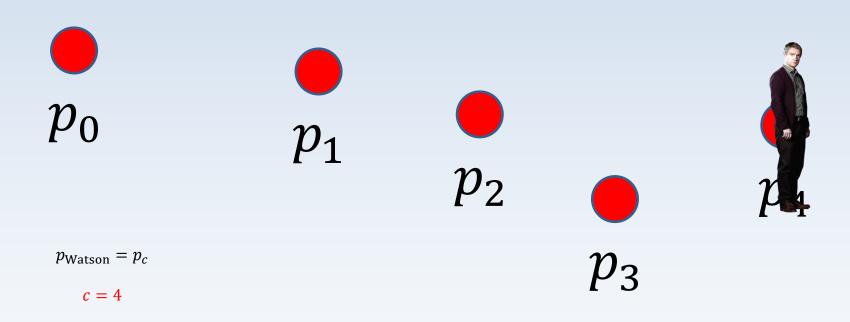
Example: 'c'



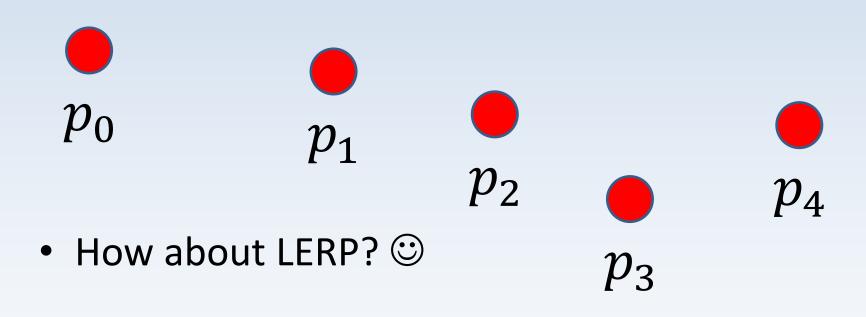




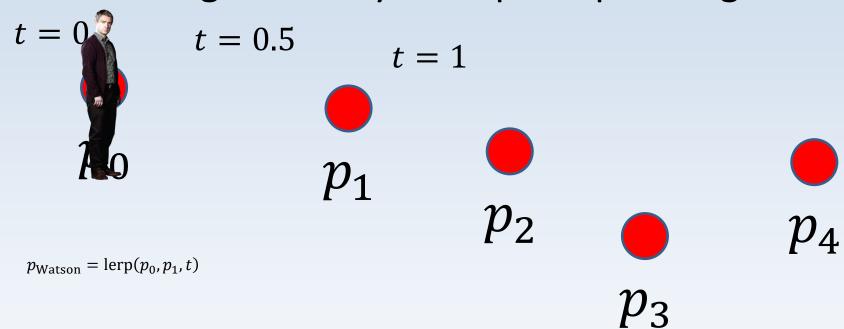




How do we move smoothly from p0 to p1?

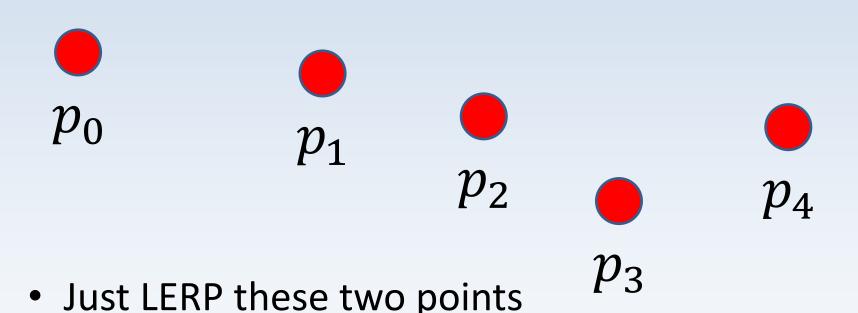


Moving smoothly from p0 to p1 using LERP:



Remember, right now we have control over 't'

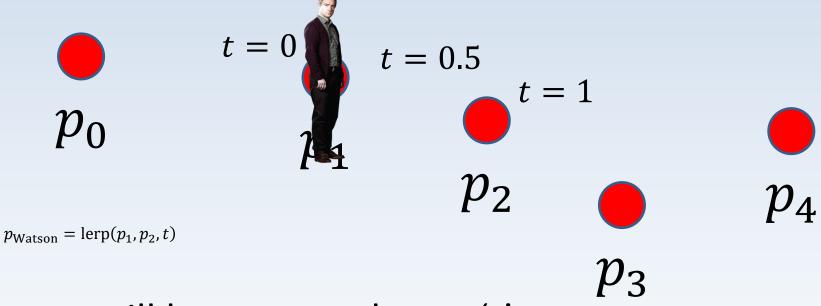
How do we move smoothly from p1 to p2?



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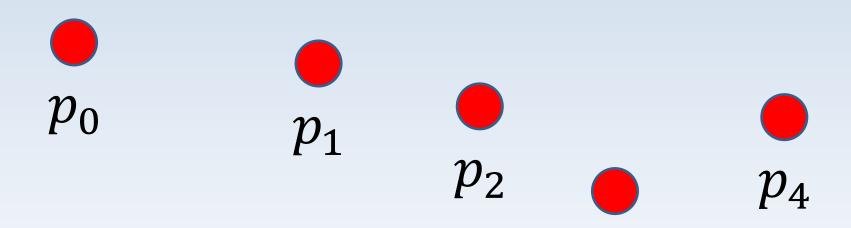
instead of p0 and p1, rinse & repeat!

Moving smoothly from p1 to p2 using LERP:



...still have control over 't'

So what is the actual algorithm used here?



- Upon reaching new location... p_3
- ...reset t and increment current index!!!

Moving smoothly from "pose to pose":



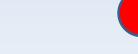
$$t = 0.5$$

$$t = 1$$



 p_1





 $p_{\mathbf{2}}$

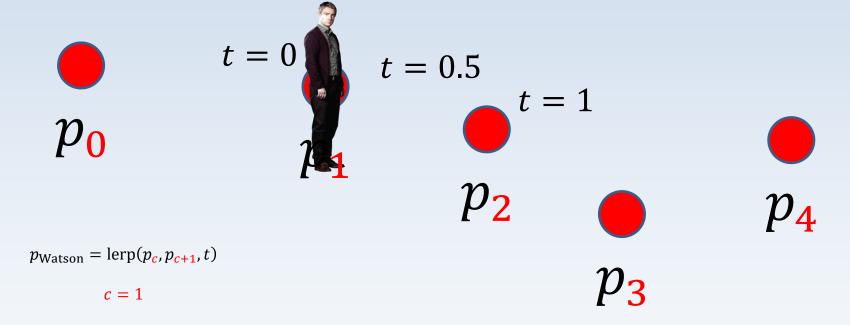


 $p_{f 4}$

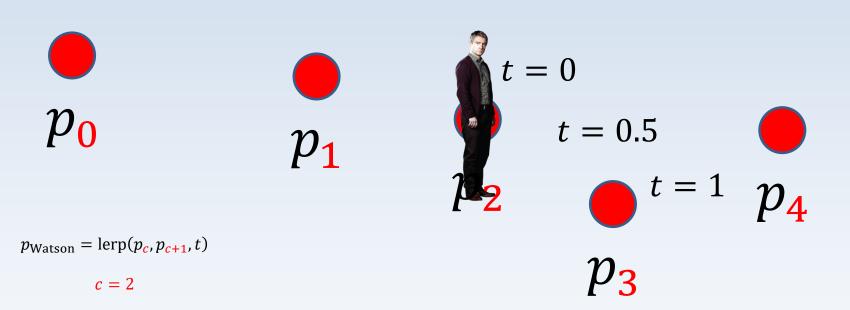
$$p_{\text{Watson}} = \text{lerp}(p_c, p_{c+1}, t)$$
$$c = 0$$

$$p_3$$

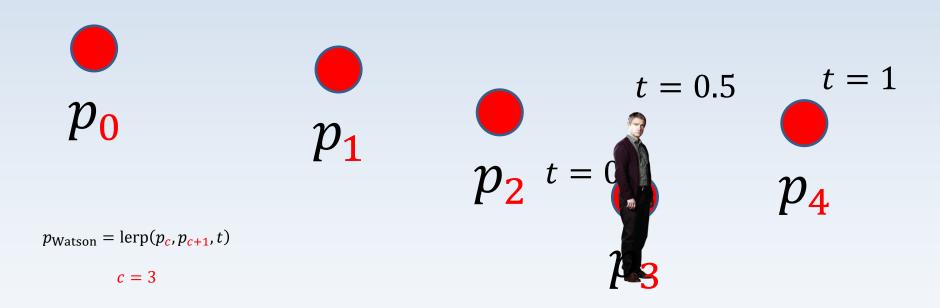
Moving smoothly from "pose to pose":



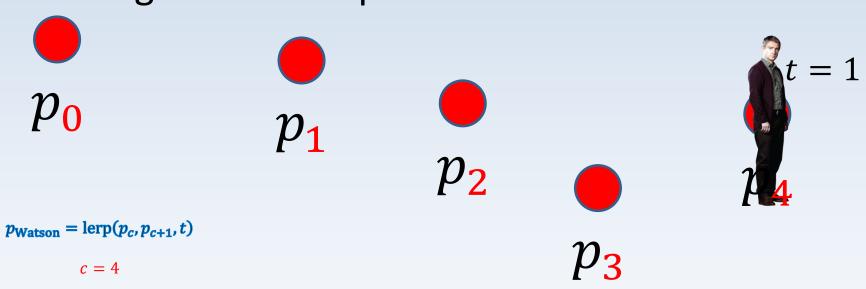
Moving smoothly from "pose to pose":



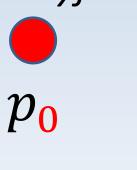
Moving smoothly from "pose to pose":



 Notice how the LERP call did not change once during that entire process!!!



 All we did was keep track of the current keyframe index











$$p_{\text{Watson}} = \text{lerp}(p_c, p_{c+1}, t)$$
 $c = 4$

$$p_3$$

- The index value is incremented... when???
- ...every time $t \ge 1$



 p_0



 p_1



 p_2



t = 1

$$p_{\text{Watson}} = \text{lerp}(p_c, p_{c+1}, t)$$

$$c = 4$$

$$p_3$$

- How would we play in reverse using the exact same LERP algorithm???
- Actually two very fast and simple solutions
- Think about it... what simple changes would result in reverse playback?

$$\operatorname{lerp}(p_0, p_1, t) = (1 - t)p_0 + (t)p_1$$

$$\uparrow \qquad \uparrow$$
METHOD 1 HINT
METHOD 2 HINT

- Summary:
- LERP is incredibly important for keyframed animation
- Locomotion is just one application
- Position is just one kind of data
- Literally everything else this year builds on this concept

- Summary:
- All of the above examples are written in their pure mathematical forms
- Luckily, all of it translates <u>directly</u> and <u>easily</u> into code!!!
- Algorithms are just functions
- Functions are math... get used to it [©]

The end.

Questions? Comments? Concerns?

