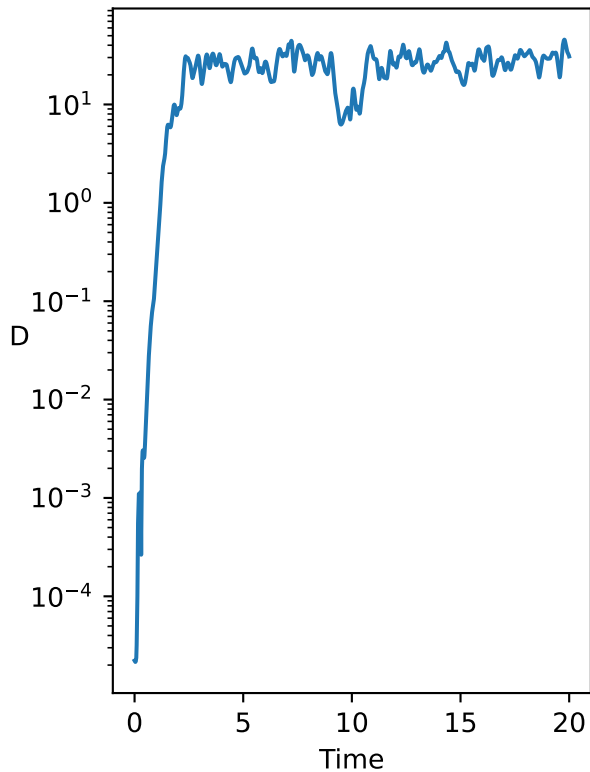


# Distance between Trajectories

## Using a small perturbation



## Using the Model v Actual

