

# Duc-Cuong VU, BSc.

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## Education

### Master of Science in Automation and Control (Jul 2024 - present)

School of Electrical - Electronics Engineering,  
Hanoi University of Science and Technology (HUST), Hanoi, Vietnam

- **Research project:** Design control structures for Parallel Platforms in Maritime applications
- **Funded by:** Master, PhD Scholarship Programme of Vingroup Innovation Foundation (VINIF)

### Bachelor of Science in Automation and Control (Oct 2020 - Mar 2024)

School of Electrical - Electronics Engineering,  
Hanoi University of Science and Technology (HUST), Hanoi, Vietnam

- **Excellent degree,** GPA: 3.71/4. Finished the 4-year BSc program in **just 3.5 years**.
- **Ranking:** 27/499 in the same cohort.
- **Bachelor Thesis:** Balancing, motion planning, and tracking control for ballbot systems [[pdf](#)] .  
**Thesis score:** 9.9/10 - The best thesis defense

## Work Experience

### Research Assistant (Oct 2021 - present)

The Mechatronics Engineering Group,  
School of Electrical - Electronic Engineering,  
Hanoi University of Science and Technology (HUST), Hanoi, Vietnam

- **Research topics:** Automation, Control Design, Robotics, Multi-agent Systems, Modeling and Simulation, Experiment systems.
- **Supervisor:** [Assoc.Prof.PhD. Tung Lam Nguyen](#) ([lam.nguyentung \[at\] hust.edu.com](mailto:lam.nguyentung@hust.edu.com)).
- **Skills acquired:** hardware design, numerical simulation and modeling, analysis, and interpretation of results, study conception, and design, draft manuscript preparation, ...

## Projects

### Member/Researcher (Mar 2025 - Dec 2025)

Advanced Control of a Ship-Mounted Stewart Platform for Marine Applications

- Field: Marine Robotics and Control Systems.
- International Collaboration of Korea Institute of Science and Technology and Institute for Control Engineering and Automation (HUST).
- Supervisors: [PhD. Minh Nhat Vu](#) and [Assoc.Prof.PhD. Tung Lam Nguyen](#)

### Member/Researcher (Jan 2025 - Dec 2027)

Robot navigation system integrating sensor network and wireless communication

- Field: Robotics and Control systems.
- Funded by Hanoi University of Science and Technology.
- Supervisors: [PhD. Chinh Hoang Duc](#) and [Assoc.Prof.PhD. Tung Lam Nguyen](#).

# Skills

Programming	Proficient in Python, C/C++, and MATLAB for algorithm development, numerical computation, and embedded system applications.
Simulation	Experienced with Simulink, Simscape, and MuJoCo for multi-domain physical modeling, robot dynamics simulation, and virtual prototyping.
Control & Math	Solid foundation in rigid body dynamics, control theories, motion control, optimization, and Guidance–Navigation–Control (GNC) systems.
Engineering	Hands-on experience with version control (Git), PCB design and debugging, 3D CAD modeling using SolidWorks, and designing experimental platforms for validation.
Systems	Familiar with Linux kernel development, real-time control architectures, and embedded systems programming for robotics and automation.
Research	Capable of conducting scientific research, writing academic publications, and presenting technical findings at international conferences. Experienced in literature review, hypothesis formulation, and experimental validation.

# Highlighted Publications

Journal	IEEE Access (ISI-Q2) (2025) CBFs-based Model Predictive Control for Obstacle Avoidance with Tilt Angle Limitation for Ball-Balancing Robots Minh Duc Pham, <b>Duc Cuong Vu</b> , Thi Thuy Hang Nguyen, Thi Van Anh Nguyen, Minh Nhat Vu, and Tung Lam Nguyen DOI: <a href="https://doi.org/10.1109/ACCESS.2025.3567474">10.1109/ACCESS.2025.3567474</a>
Journal	Results in Engineering (ISI-Q1) (2025) A novel approach of Consensus-based Finite-time Distributed Sliding Mode Control for Stewart platform manipulators motion tracking <b>Duc Cuong Vu</b> , Danh Huy Nguyen, and Tung Lam Nguyen DOI: <a href="https://doi.org/10.1016/j.rineng.2024.103872">10.1016/j.rineng.2024.103872</a>
Journal	International Journal of Robust and Nonlinear Control (ISI-Q1) (2024) Time-optimal trajectory generation and observer-based hierarchical sliding mode control for ballbots with system constraints <b>Duc Cuong Vu</b> , Minh Duc Pham, Thi Thuy Hang Nguyen, Thi Van Anh Nguyen, and Tung Lam Nguyen DOI: <a href="https://doi.org/10.1002/rnc.7358">10.1002/rnc.7358</a>

# Conferences

IEEE 12th International Conference on Control, Automation and Information Sciences (IEEE ICCAIS 2023) Hanoi, Vietnam
2024 International Conference on Advanced Technologies for Communications (IEEE ATC2024) Ho Chi Minh City, Vietnam
International Conference on Intelligent Systems and Networks (Springer ICISN 2023) Hanoi, Vietnam

# Honours & awards

Master, PhD Scholarship Programme Vingroup Innovation Foundation (VINIF)
Best Thesis Defense Award Hanoi University of Science and Technology