

Local search algorithms

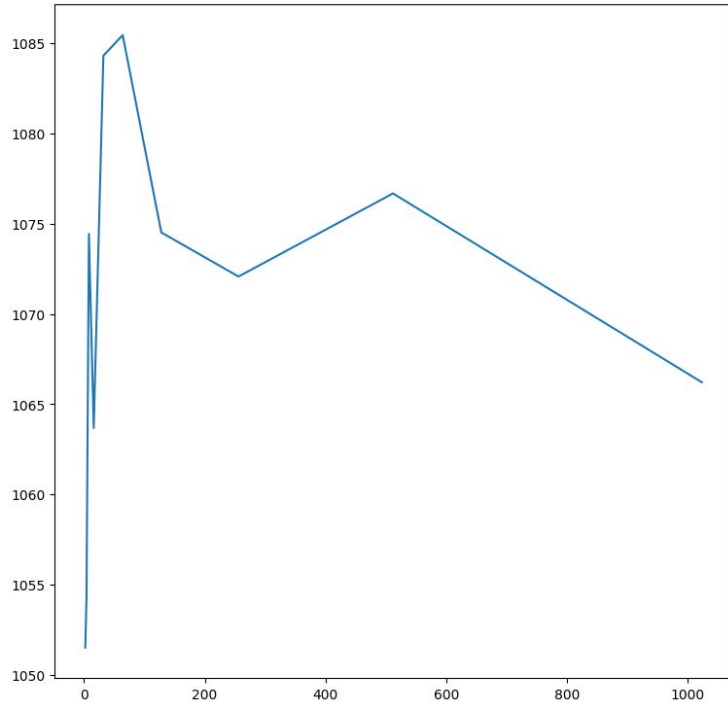
David Calle González 2023-1

Recocido simulado multistart con perturbación

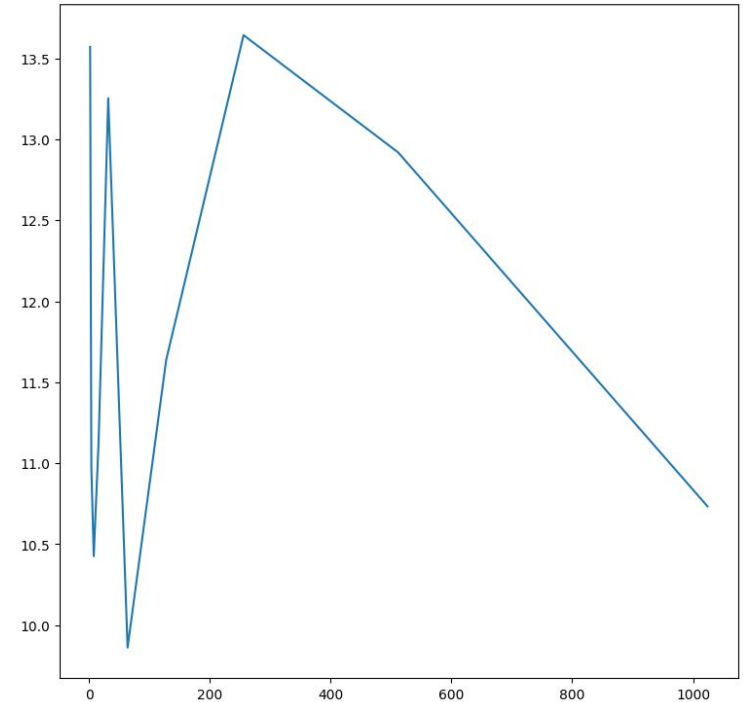
```
enhancedSolution = None
for i in range(nsol):
    comparativeSolution = Grasp(a=0.07)
    bestLocalSolution = comparativeSolution
    comparativeSolution = perturbe(comparativeSolution)
    T = Ti
    iter = 0
    while T > Tf:
        if iter == L;
            T = T*r
            iter = 0
        newSolution = GetNeighbourgh(bestLocalSolution, T)
        comparativeSolution = newSolution
        if dist(comparativeSolution) < dist(bestLocalSolution):
            bestLocalSolution = comparativeSolution
    if enhancedSolution == None or dist(bestLocalSolution) < dist(enhancedSolution):
        enhancedSolution = bestLocalSolution
return enhancedSolution
```

Recocido simulado multistart con perturbación

Ti vs función objetivo ($T_f = 0.01$, $L=15$, $r=0.5$, $nsol=1$)



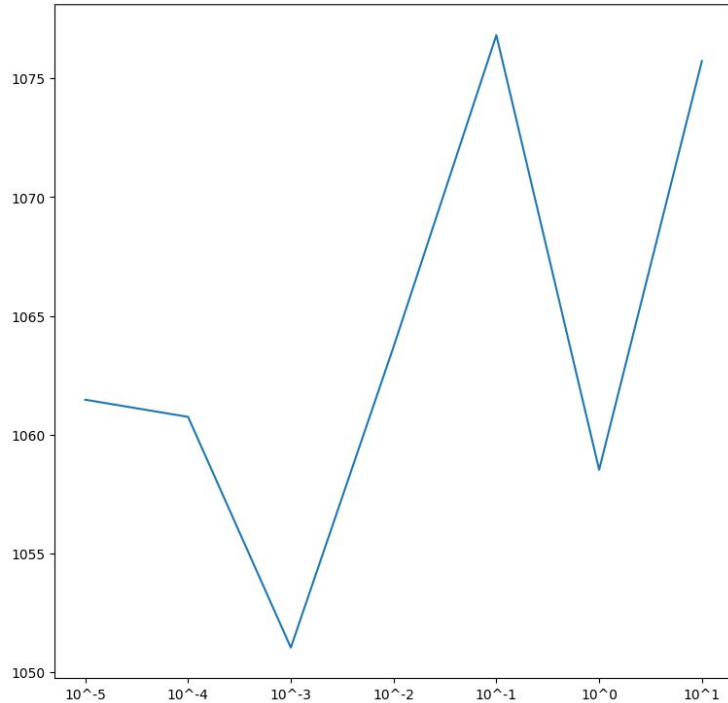
Ti vs tiempo de computo ($T_f = 0.01$, $L=15$, $r=0.5$, $nsol=1$)



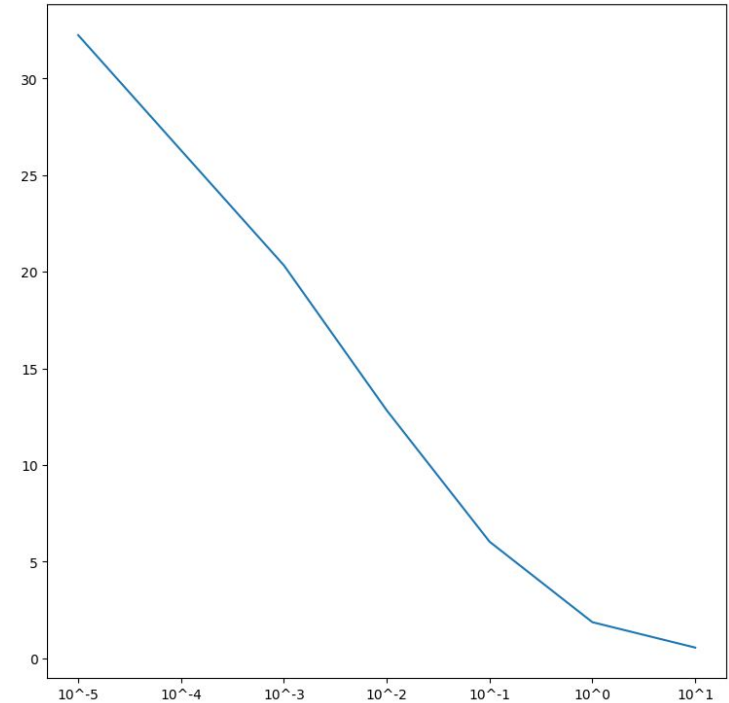
mtnrp4, $a=0.07$

Recocido simulado multistart con perturbación

Tf vs función objetivo ($T_i = 64$, $L=15$, $r=0.5$, $nsol=1$)



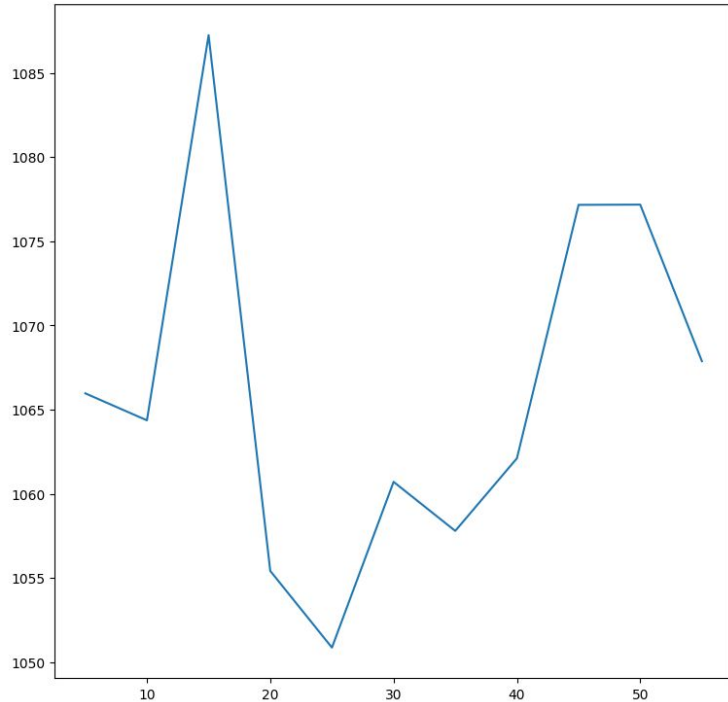
Tf vs tiempo de cómputo ($T_i = 64$, $L=15$, $r=0.5$, $nsol=1$)



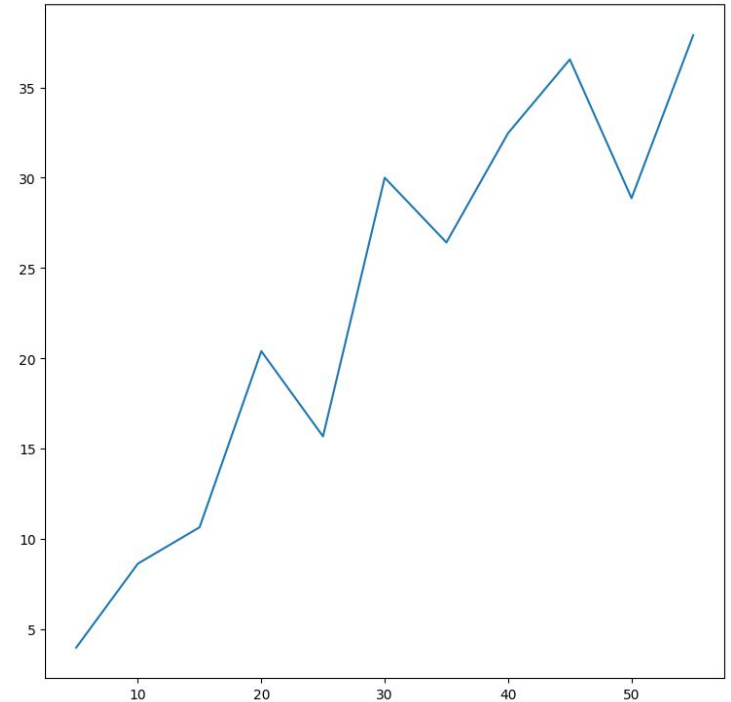
mtvrp4, $a=0.07$

Recocido simulado multistart con perturbación

L vs función objetivo ($T_i = 1024$, $T_f = 0.01$, $r = 0.5$, $nsol = 1$)



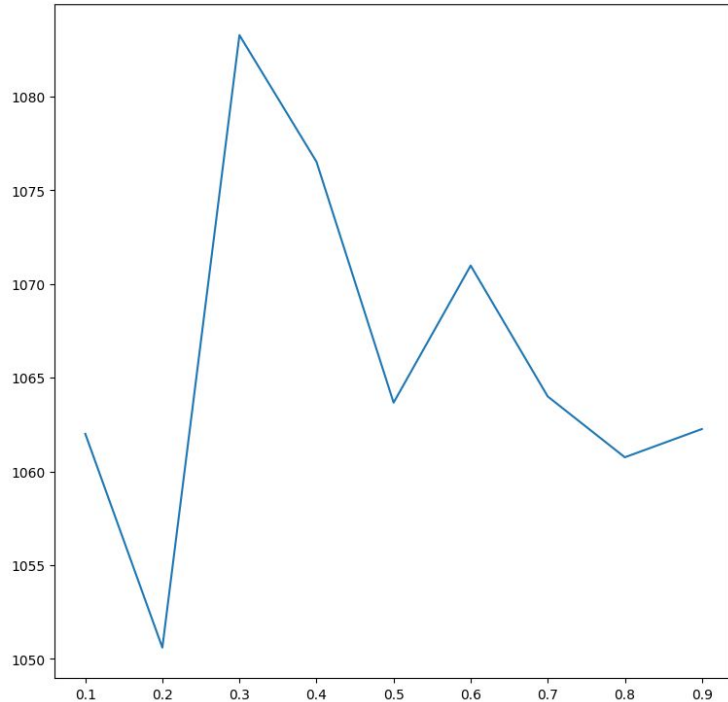
L vs tiempo de computo ($T_i = 1024$, $T_f = 0.01$, $r = 0.5$, $nsol = 1$)



mtvrp4, $a = 0.07$

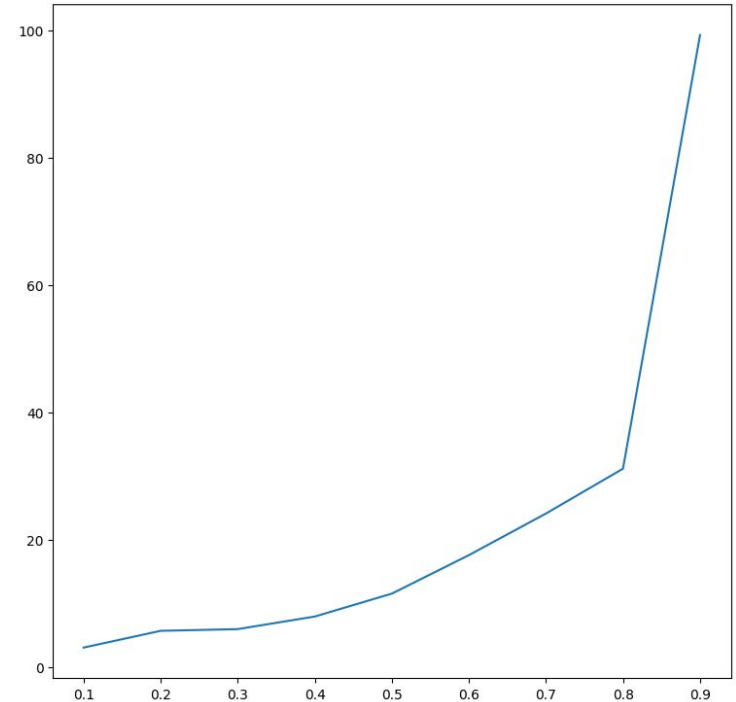
Recocido simulado multistart con perturbación

r vs tiempo de cómputo ($T_i=64$, $T_f=0.01$, $L=15$, $nsol=1$)



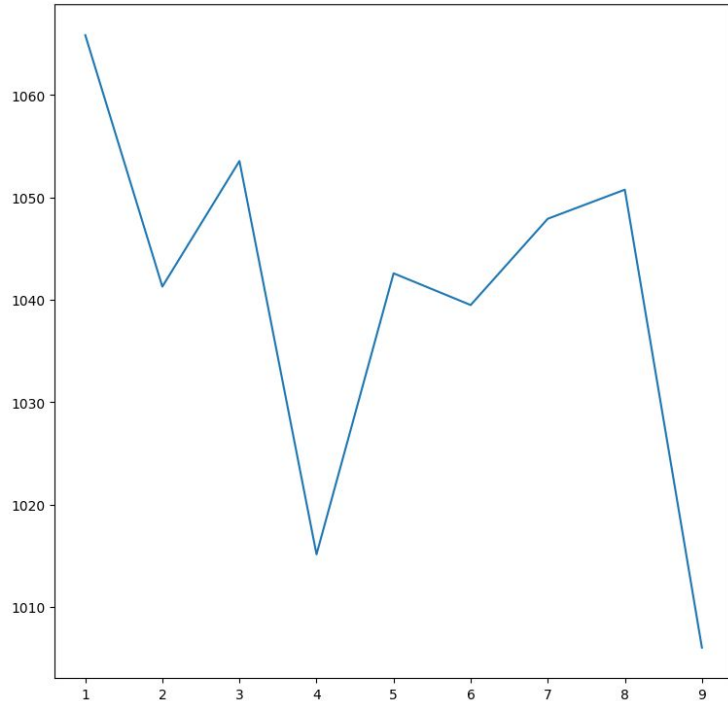
mtnrp4, $a=0.07$

r vs tiempo de cómputo ($T_i=64$, $T_f=0.01$, $L=15$, $nsol=1$)

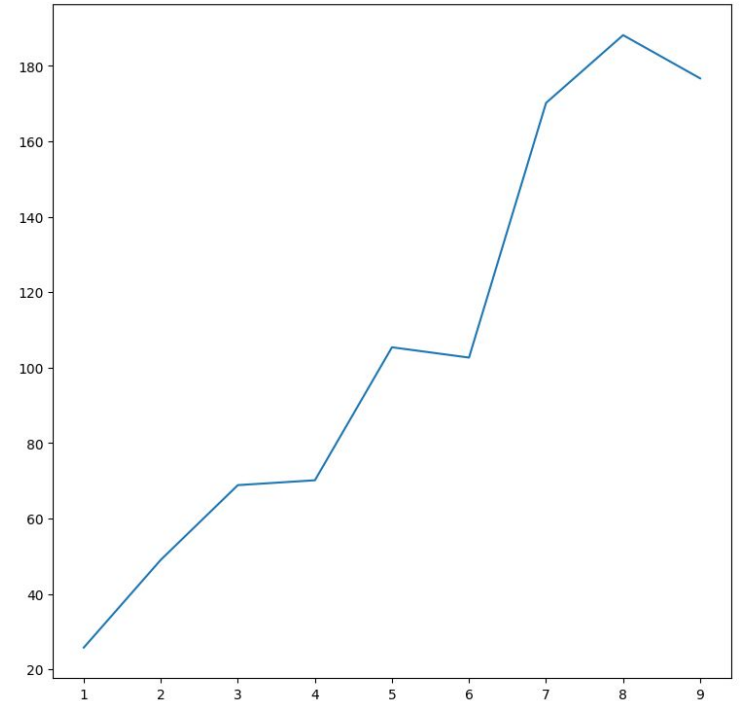


Recocido simulado multistart con perturbación

nsol vs función objetivo ($T_i = 1024$, $T_f = 0.01$, $L=25$, $r=0.5$)



nsol vs tiempo de cómputo ($T_i = 1024$, $T_f = 0.01$, $L=25$, $r=0.5$)



mtvrp4, $a=0.07$

VNS

```
bestSolution = initialSolution
algorithmIndex = 0
while algorithmIndex < length(neighbourhoodAlgorithms):
    newSolution = neighbourhoodAlgorithms[algorithmIndex](bestSolution)
    if newSolution != None and dist(newSolution) < dist(bestSolution)
        bestSolution = newSolution
        algorithmIndex = 0
    else:
        algorithmIndex += 1
return bestSolution
```

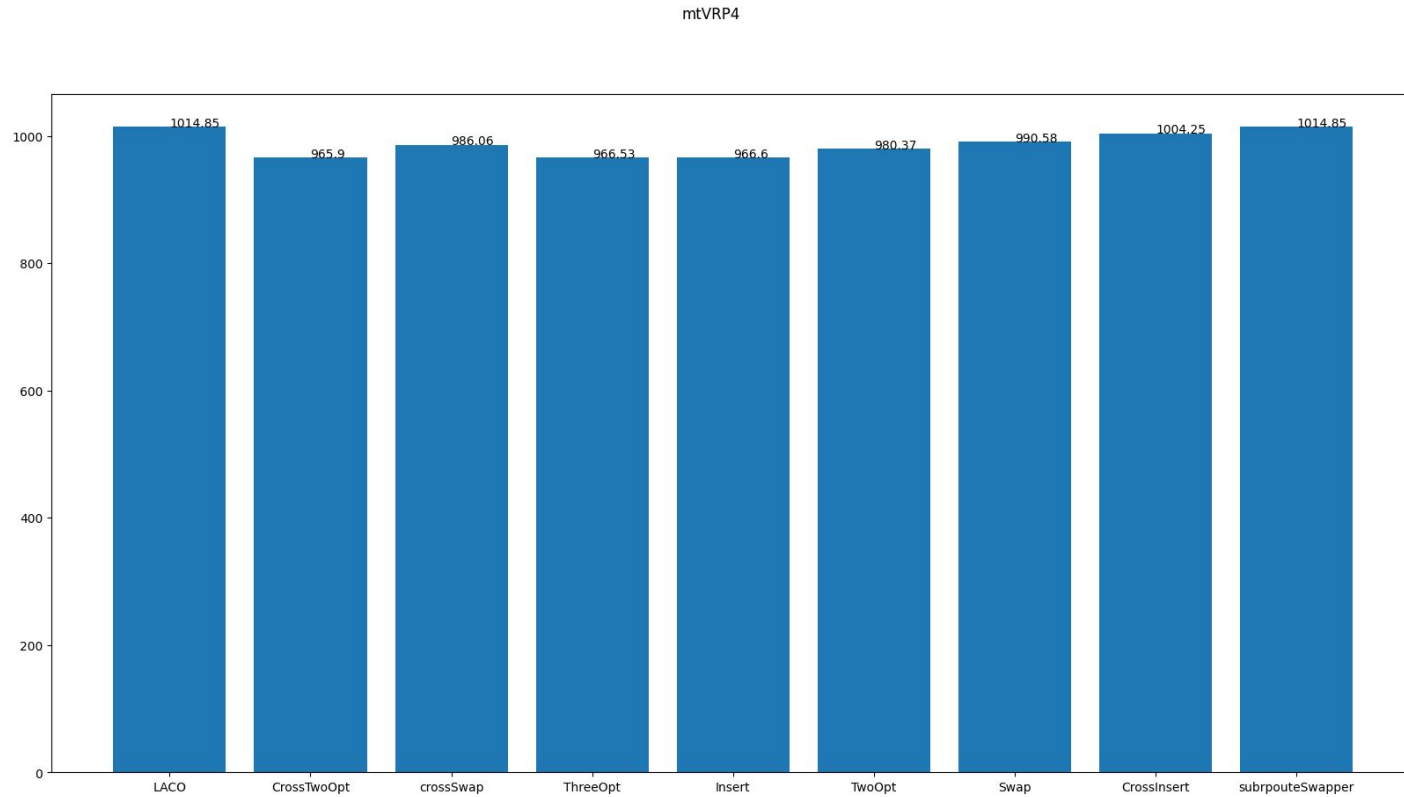

VNS local neighbourhoods

- Insert
- Swap
- TwoOpt
- ThreeOpt

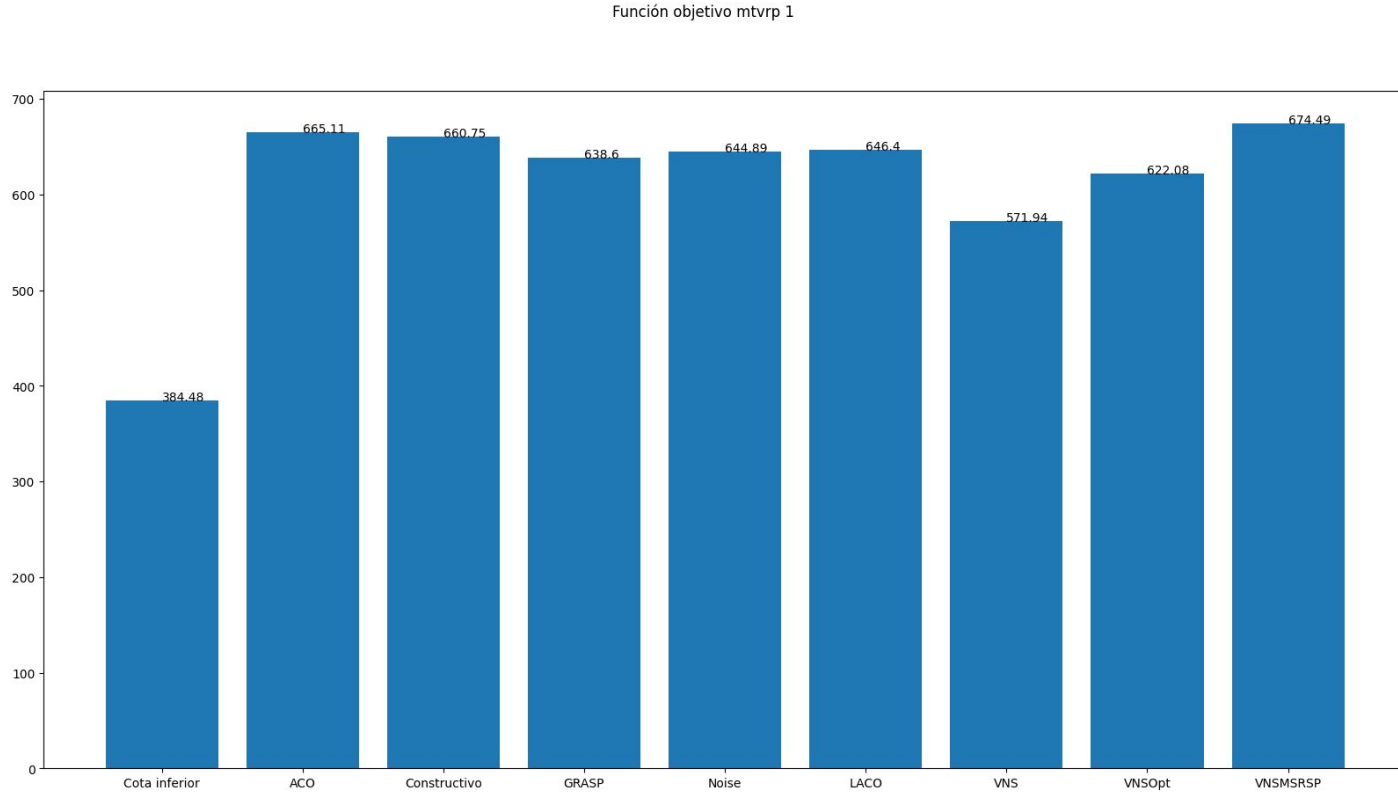
VNS cross neighbourhoods

- crossInsert
- crossSwap
- crossTwoOpt
- SubrouteSwapper

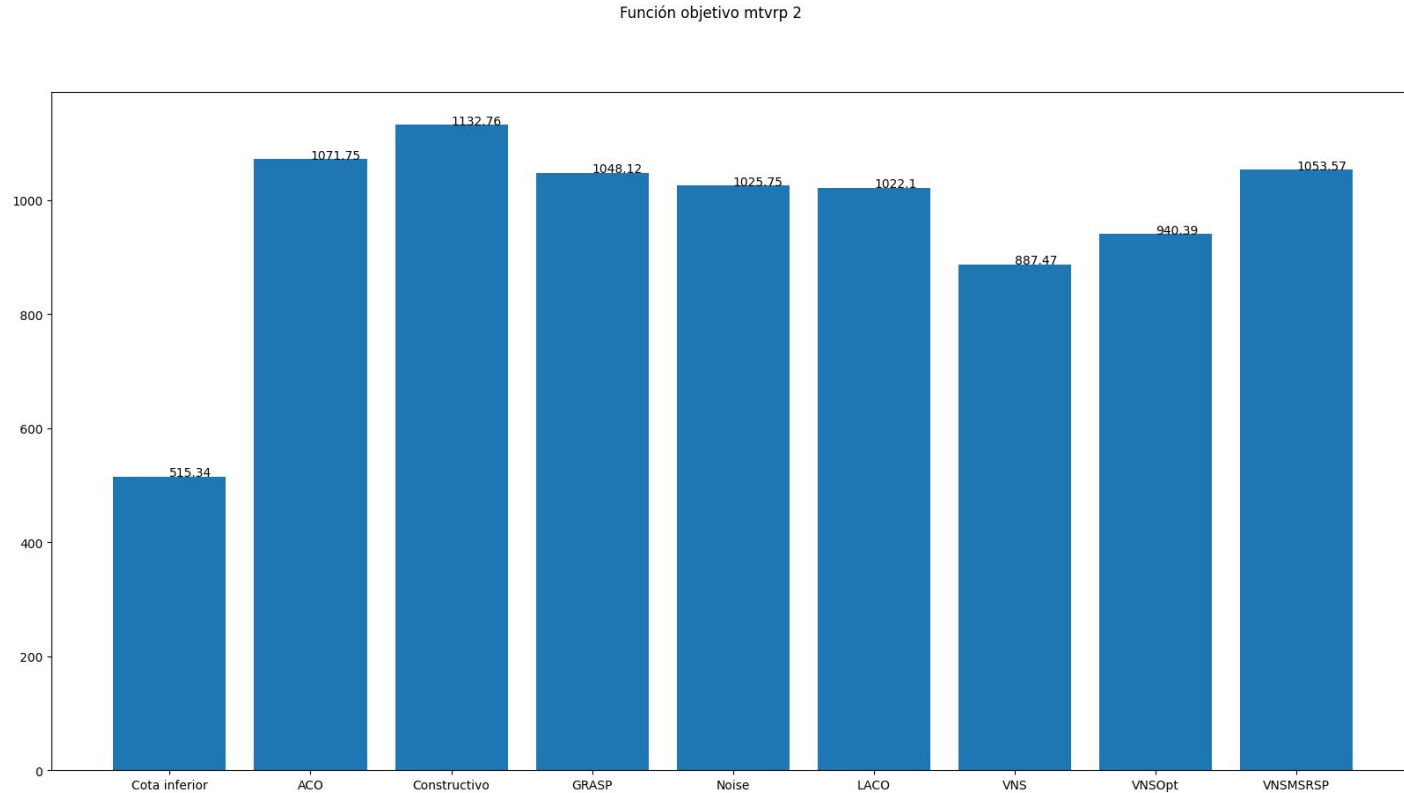
VNS



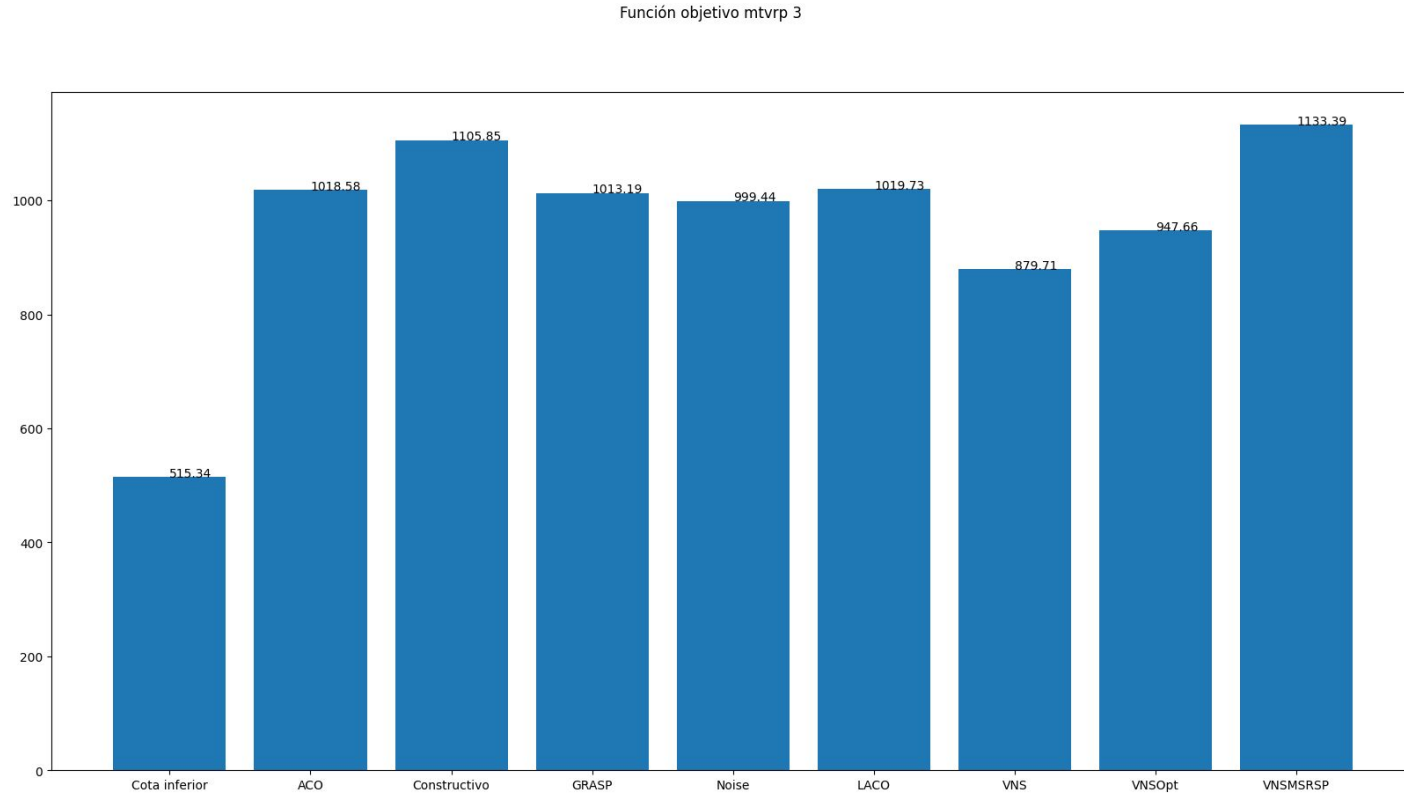
Comparación de algoritmos



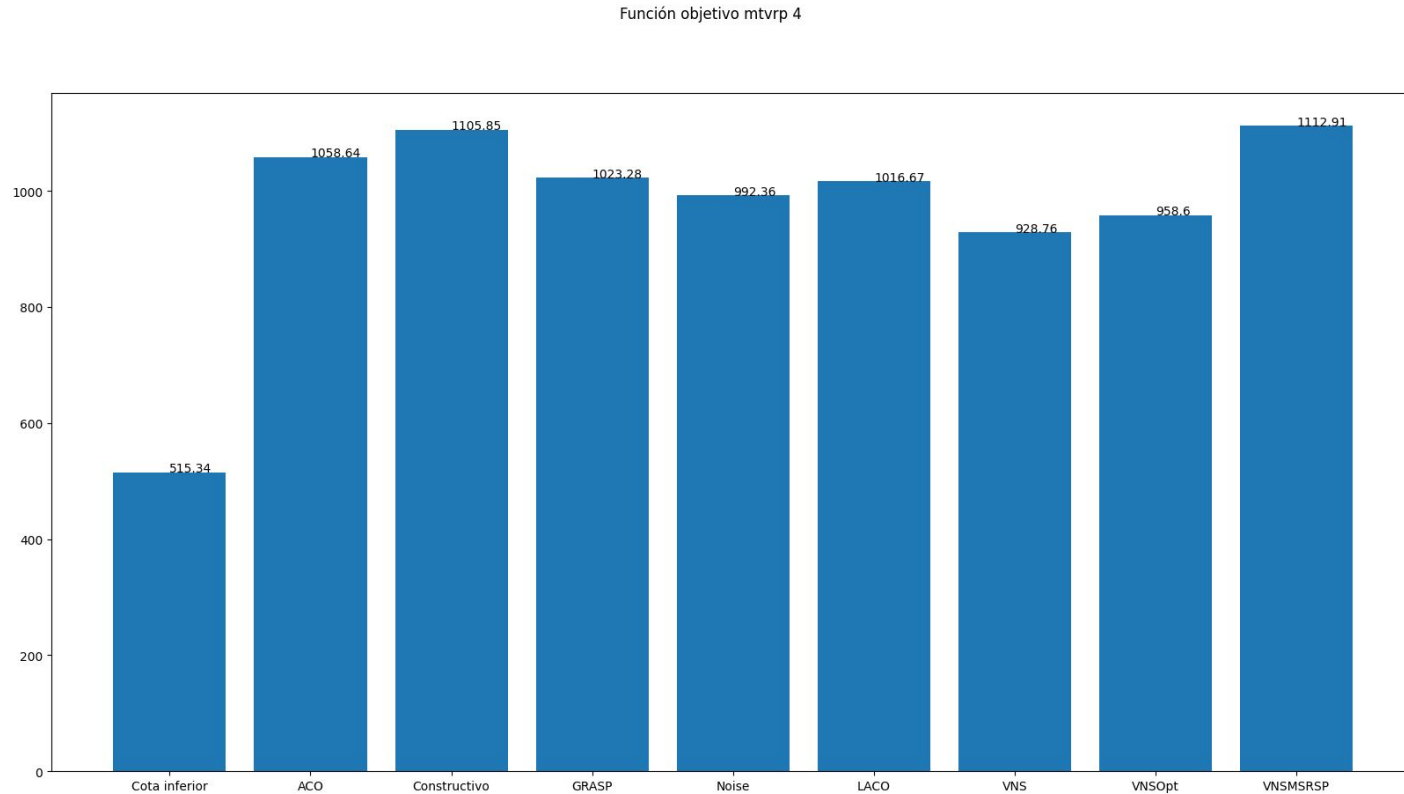
Comparación de algoritmos



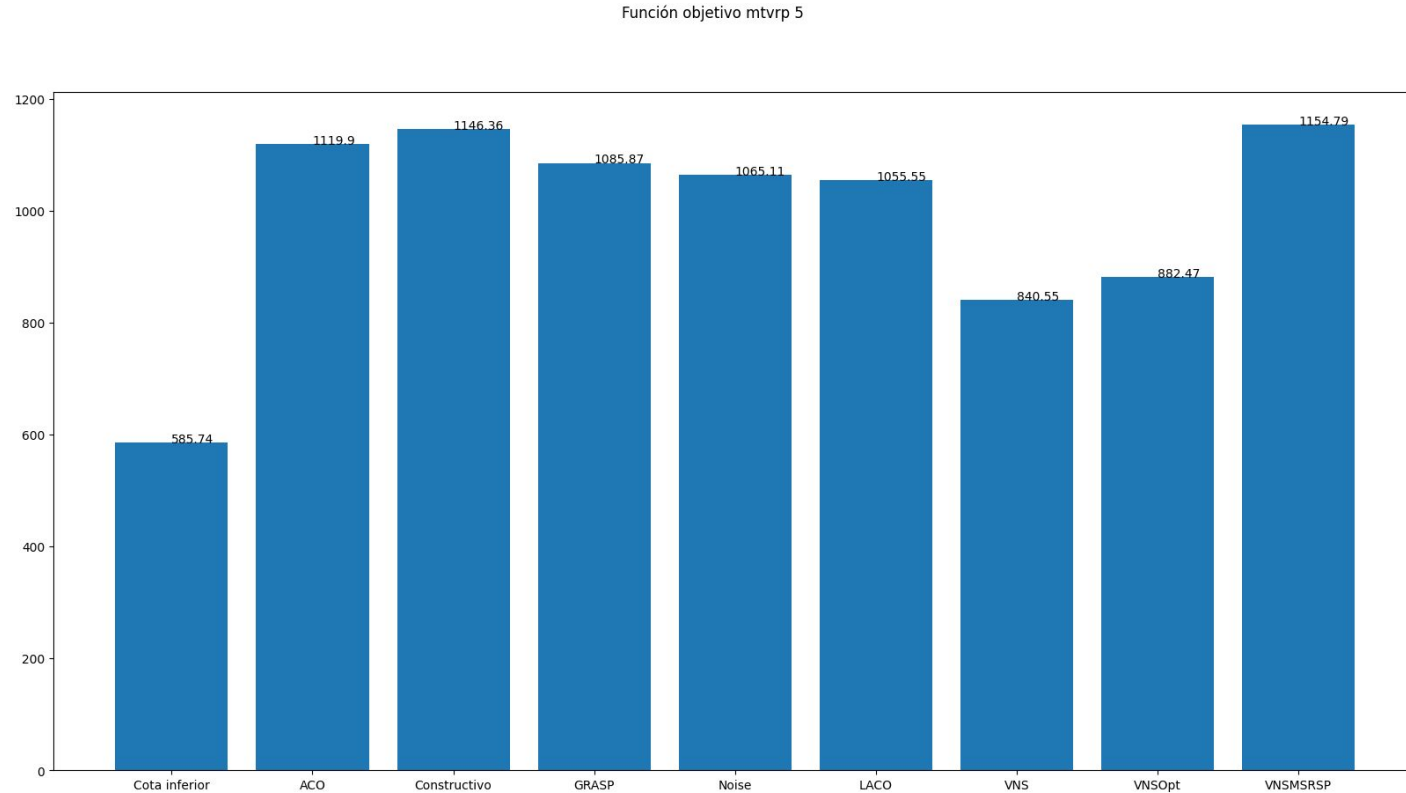
Comparación de algoritmos



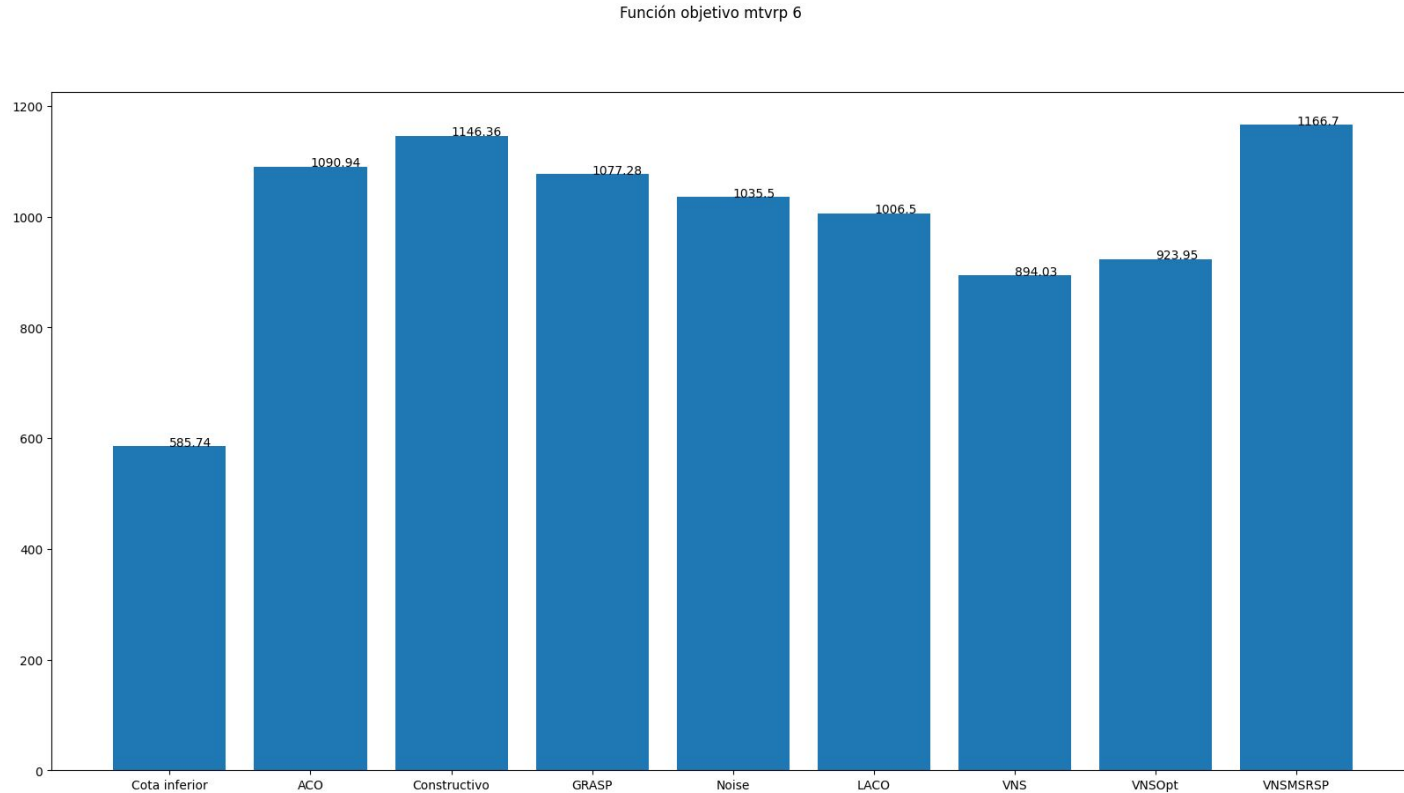
Comparación de algoritmos



Comparación de algoritmos

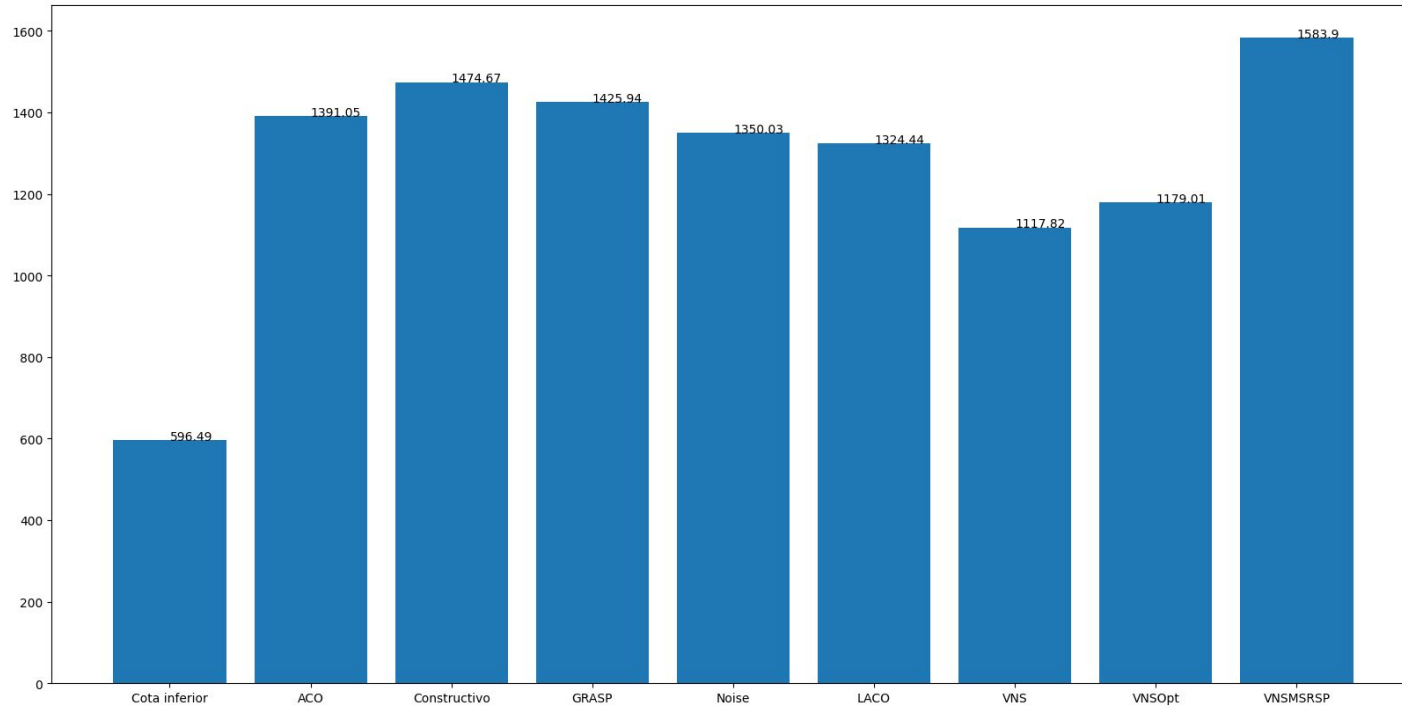


Comparación de algoritmos

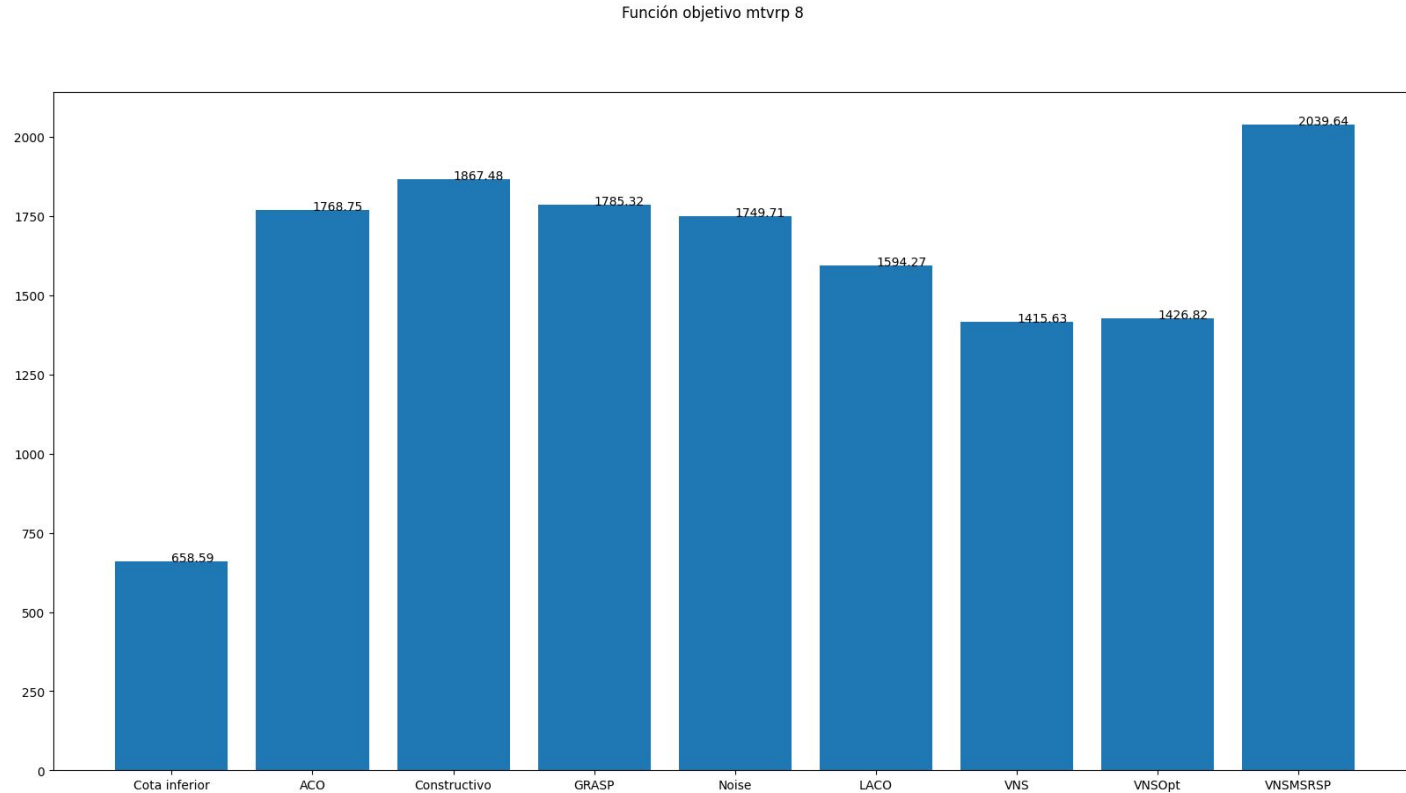


Comparación de algoritmos

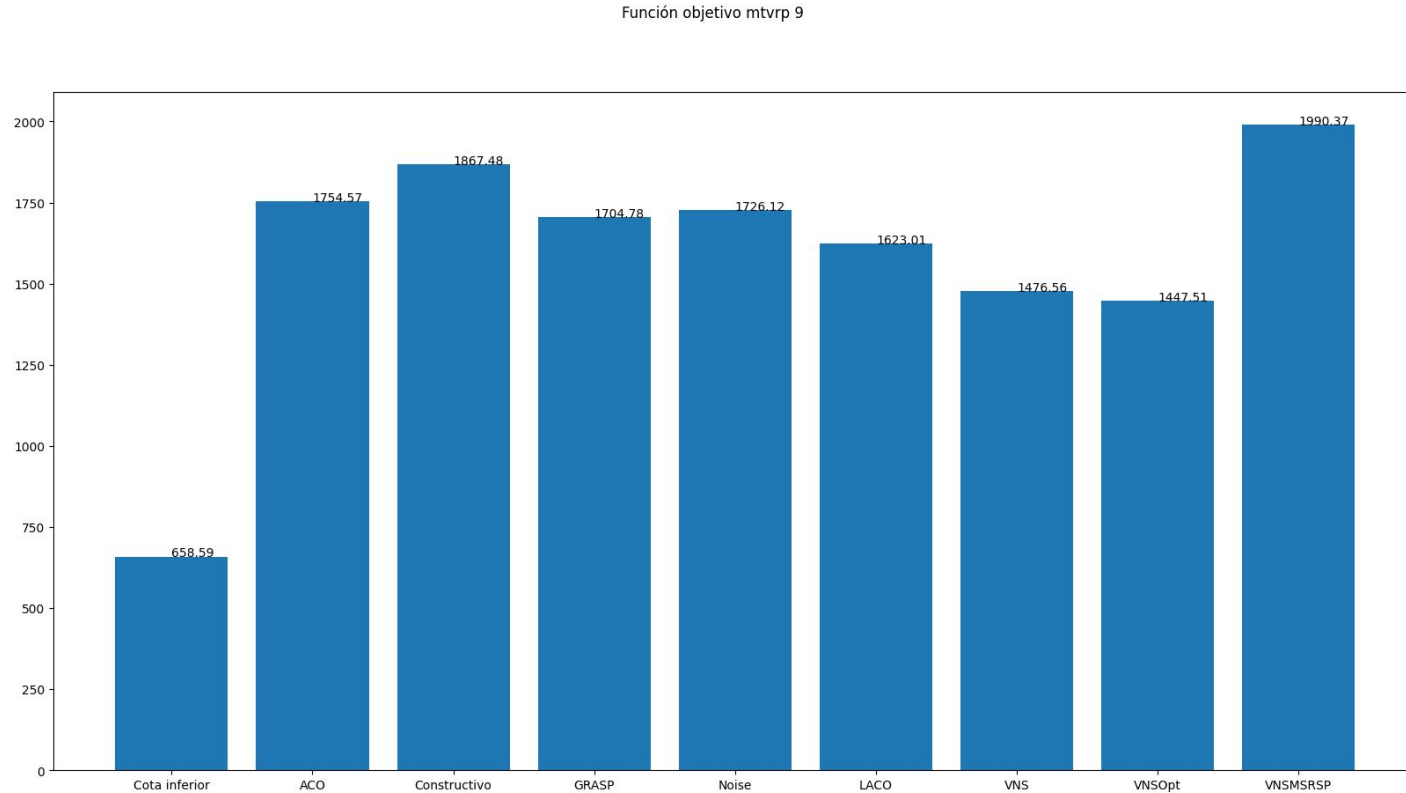
Función objetivo mtrvp 7



Comparación de algoritmos

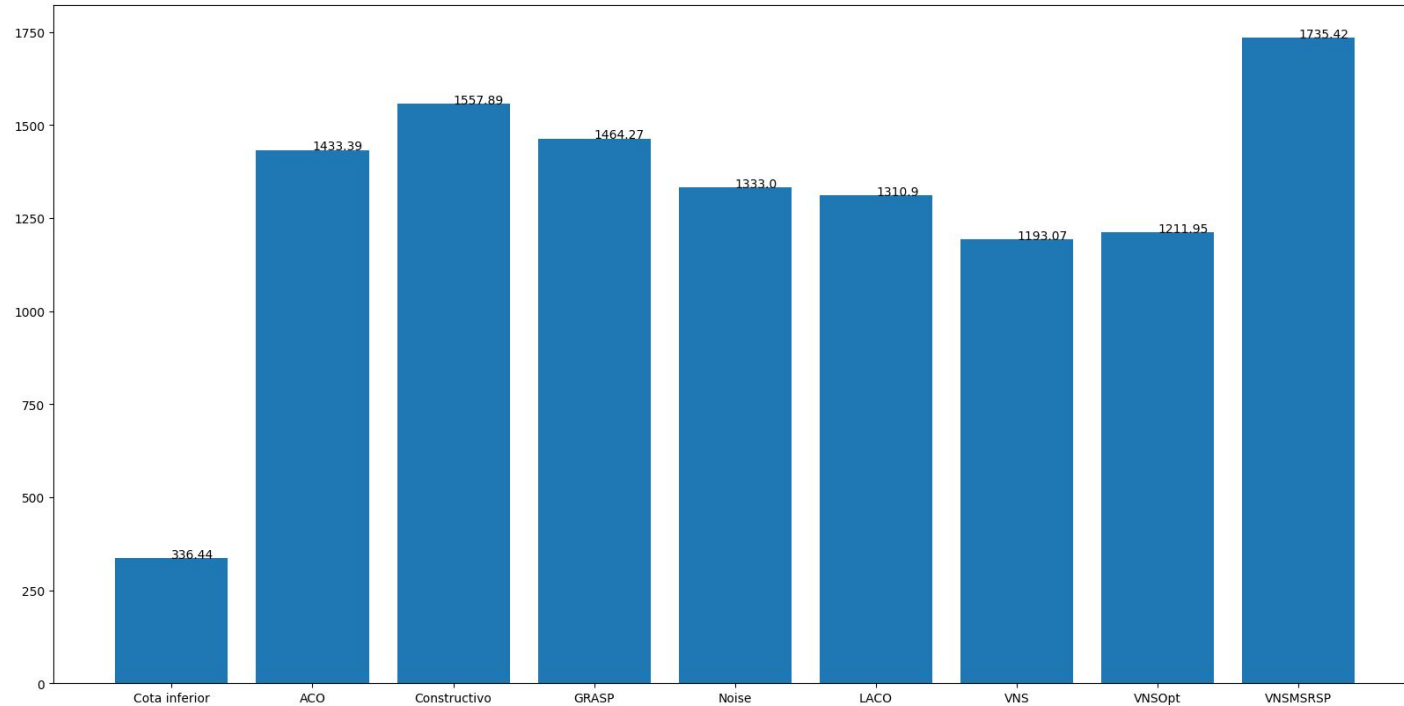


Comparación de algoritmos

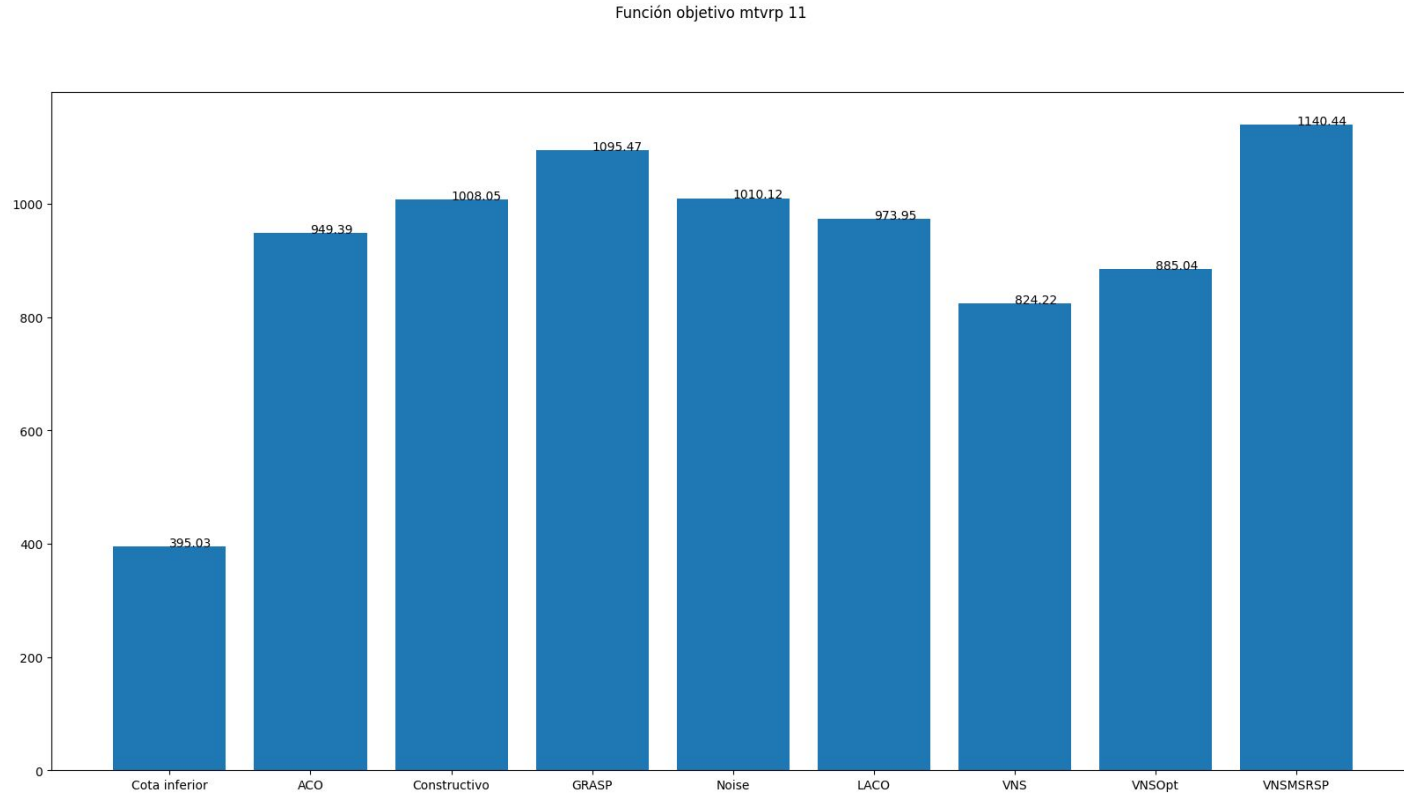


Comparación de algoritmos

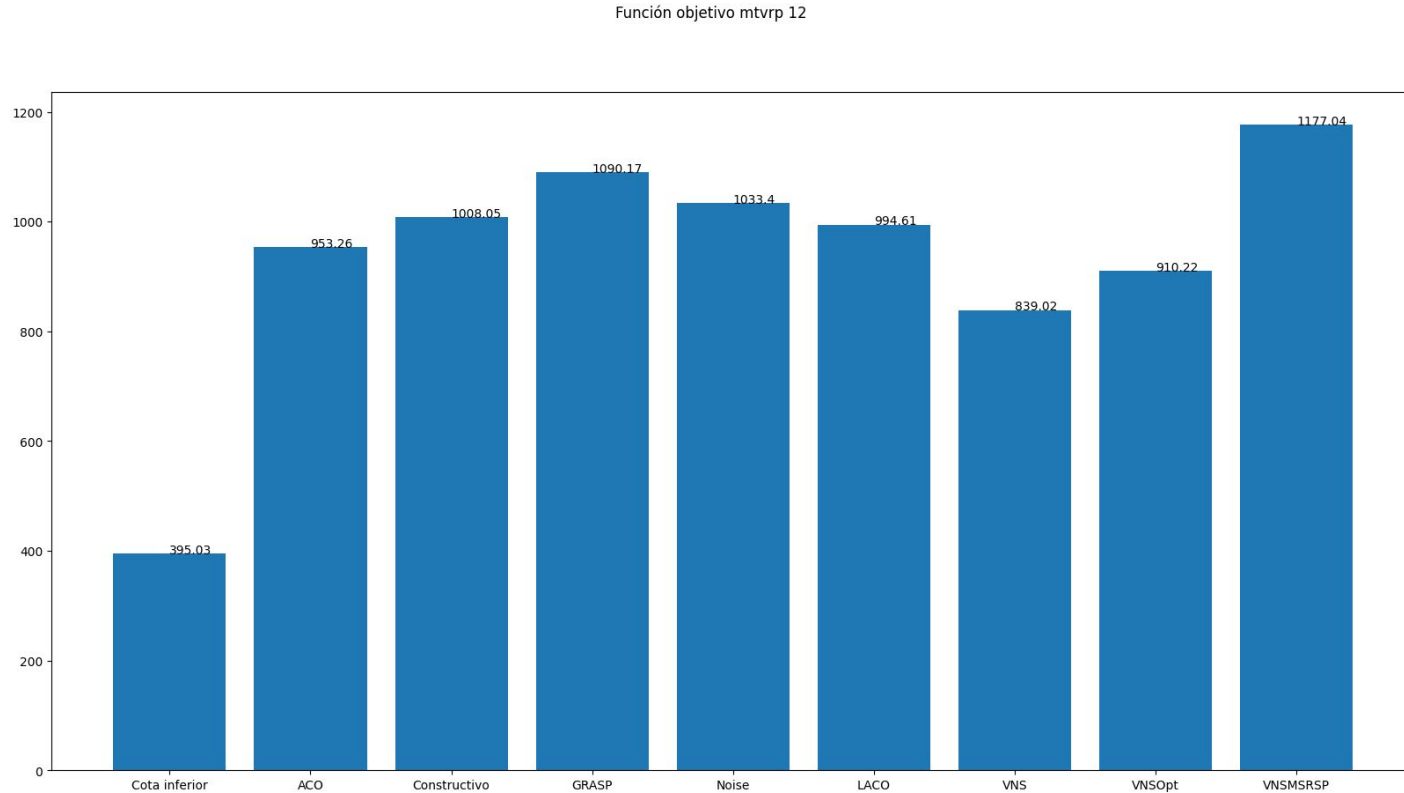
Función objetivo mtrvp 10



Comparación de algoritmos



Comparación de algoritmos



Comparación respecto a la cota inferior

