

Channel Estimation of Frequency Selective Channels Using Sparse Tensor Processing

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Abstract—The abstract goes here.

I. INTRODUCTION

Notation: A scalar is denoted in italic, e.g. a . A column vector is a bold lowercase letter, e.g. \mathbf{a} whose i th entry is $\mathbf{a}(i)$. A matrix is denoted by a bold uppercase letter, e.g. \mathbf{A} with (i, j) th entry $\mathbf{A}(i, j)$; $\mathbf{A}(:, j)$ is the j th column of \mathbf{A} . A third-order tensor is a caligraphic uppercase letter, e.g. \mathcal{A} with (i, j, k) th entry $\mathcal{A}(i, j, k)$. The $\text{vec}\{\cdot\}$ operator stacks the columns of its argument into one big column vector; \otimes stands for the Kronecker product and \odot is the Khatri-Rao product (column-wise Kronecker product) [1], [2].

II. SYSTEM MODEL

Consider a $N_r \times N_t$ channel matrix between transmitter and receiver that is frequency selective with N_c delay taps. Each tap is denoted as \mathbf{H}_d , $d = \{0, 1, \dots, N_c - 1\}$. The variable ρ denotes the average received power and $\mathbf{z}_n \sim \mathcal{N}(0, \sigma^2 \mathbf{I})$ the circularly symmetric complex Gaussian distributed noise vector, therefore, the received signal is expressed as

$$\mathbf{r}_{l,n} = \sqrt{\rho} \sum_{d=0}^{N_c-1} \mathbf{H}_d \mathbf{f}_l s_{n-d} + \mathbf{z}_{l,n}, \quad (1)$$

where s_n is the n th non-zero of the training frame of length $N + N_c - 1$

$$\mathbf{s} = [0, \dots, 0, s_1, s_2, \dots, s_N]. \quad (2)$$

At the receiver, and a RF combiner \mathbf{w}_k is applied over the training frame, so that the combiner output is expressed as

$$y_{k,l,n} = \sqrt{\rho} \mathbf{w}_k^H \sum_{d=0}^{N_c-1} \mathbf{H}_d \mathbf{f}_l s_{n-d} + z_{k,l,n}, \quad (3)$$

where $z_{k,l,n} = \mathbf{w}_k^H \mathbf{z}_{l,n}$. The output signal can be described in term of tensor notation

$$y_{k,l,n} = \mathcal{H} \times_1 \mathbf{w}_k^H \times_2 \mathbf{f}_l \times \mathbf{s}_n, \quad (4)$$

where \mathcal{H} is generated from the concatenation in the third dimension of the N_c delay taps. Assuming a collection of transmitter and receiver beams, i.e. $l = \{1, \dots, L\}$ and $k = \{1, \dots, K\}$, respectively, and the N time instants within

the training frame, we can express the signal model as the third-order tensor

$$\mathcal{Y} = \mathcal{H} \times_1 \mathbf{W} \times_2 \mathbf{F} \times_3 \mathbf{S} + \mathcal{Z} \times_1 \mathbf{W}, \quad (5)$$

where \mathbf{S} is toeplitz because there is a convolution operation over the third dimension.

III. CONCLUSION

The conclusion goes here.

ACKNOWLEDGMENT

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