## 1 Initial Conditions

The initial mass profile is given by the equilibrium torus configuration a là Stone 1999:

$$\frac{P}{\rho} = \frac{GM}{(n+1)R_0} \left[ \frac{R_0}{r} - \frac{1}{2} \left( \frac{R_0}{r \sin \theta} \right)^2 - \frac{1}{2d} \right]$$

and is derived in Papaloizou & Pringle 1984. In the above M is the mass of the central object,  $R_0$  is the characteristic radius of the disk, n is the polytropic index and d is a parameter that describes the distortion of the disk. which apparently follows from a polytropic equation of state  $p = a\rho^{\gamma}$ , where  $n = (\gamma - 1)^{-1}$ . If the polytropic equation of state  $\rho = AP^{\gamma}$  is used with  $\gamma = 1 + 1/n$ , then one obtains the following initial density profile.

$$\rho_0 = \left\{ \frac{GM}{(n+1)AR_0} \left[ \frac{R_0}{r} - \frac{1}{2} \left( \frac{R_0}{r \sin \theta} \right)^2 - \frac{1}{2d} \right] \right\}^n$$
 (1.1)

In the above there are four free(ish) parameters d,  $R_0$ , and A. We will want to control d and  $R_0$  directly, and will select A by specifying a total initial disk mass  $M_{d,0}$ . The details on how this accomplished is present below.

## 1.1 Specifying the total mass

We can obtain  $M_{d,0}$  by integrating (1.1) in the relevant regions:

$$M_{d,0} = 2\pi \left[ \frac{GM}{(n+1)AR_0} \right]^n R_0^3 I(d,\gamma) = \alpha A^{-n} R_0^{3-n} \text{ with } \alpha = 2\pi \left[ \frac{GM}{(n+1)} \right]^n I(d,\gamma)$$

where  $I(d, \gamma)$  is the following integral

$$I(d,\gamma) = \iint r^2 \sin\theta \, dr \, d\theta \, \left[ \frac{1}{r} - \frac{1}{2} \left( \frac{1}{r \sin\theta} \right)^2 - \frac{1}{2d} \right]^n \tag{1.2}$$

where the bounds of integration are set by the condition that  $\rho_0 > 0$ . The bounds are then set by the condition that

$$f(r,\theta) = \frac{1}{r^2} \left( \frac{1}{2\sin^2 \theta} \right) - \frac{1}{r} + \frac{1}{2d} = 0.$$

From this, we obtain the following boundaries

$$r_{\pm} = \left[ \sin^2 \theta \left( 1 \mp \sqrt{1 - 1/d \sin^2 \theta} \right) \right]^{-1}$$
 and  $\theta_{\pm} = \pm \arcsin d^{-1/2}$ .

and will allow us to evaluate (1.2) numerically. With this, one can find that

$$A = \left(\frac{M_{d,0}}{\alpha R_0^{3-n}}\right)^{-1/n}$$

NOTE: the  $\alpha$  above is *not*!! the viscousity parameter.

## 1.2 Initial velocity profile

The equilibrium configuration (1.1) is one of constant specific angular momentum  $h = \sqrt{GMR_0}$  (probably in the z direction), which leads to a velocity profile:

$$v_{\phi} = \frac{h}{r \sin \theta} = \frac{\sqrt{GMR_0}}{r \sin \theta}$$