

Ensemble of Convolutional Neural Networks for Weakly-Supervised Sound Event Detection using Multiple Scale Input

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Large-Scale Weakly Supervised Sound Event Detection for Smart Cars

- **Task A : Audio Tagging**

- Multi class classification problem for 17 classes

- **Task B : Sound Event Detection**

- Multi class classification with timestamp
 - Training set does not include time information

Motivation

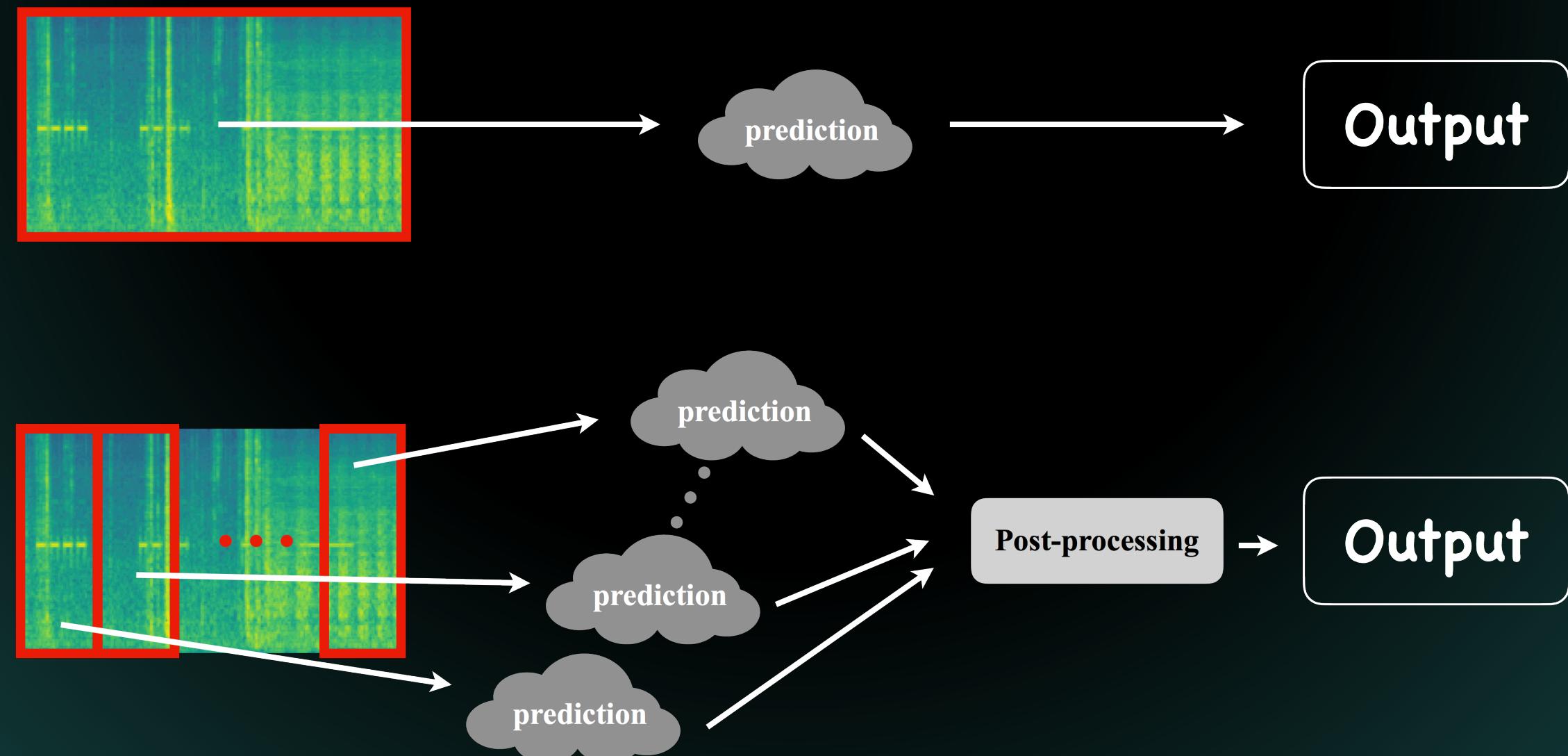
- **In automotive environment, the auditory perception ability is important**
 - Hearing can detect events in any direction
 - The more information we have, the fewer the accidents
- **It is the first large-scale learning problem for audio**
 - The amount of data is an important factor in machine learning

Our Approach

- We construct the system that find sound events in 1-second window
- We use multiple models with various length of the input audio
 - the global-input (the entire clip),
the separated-input (a portion of clip)
- We use background subtraction as preprocessing to remove stationary background noise

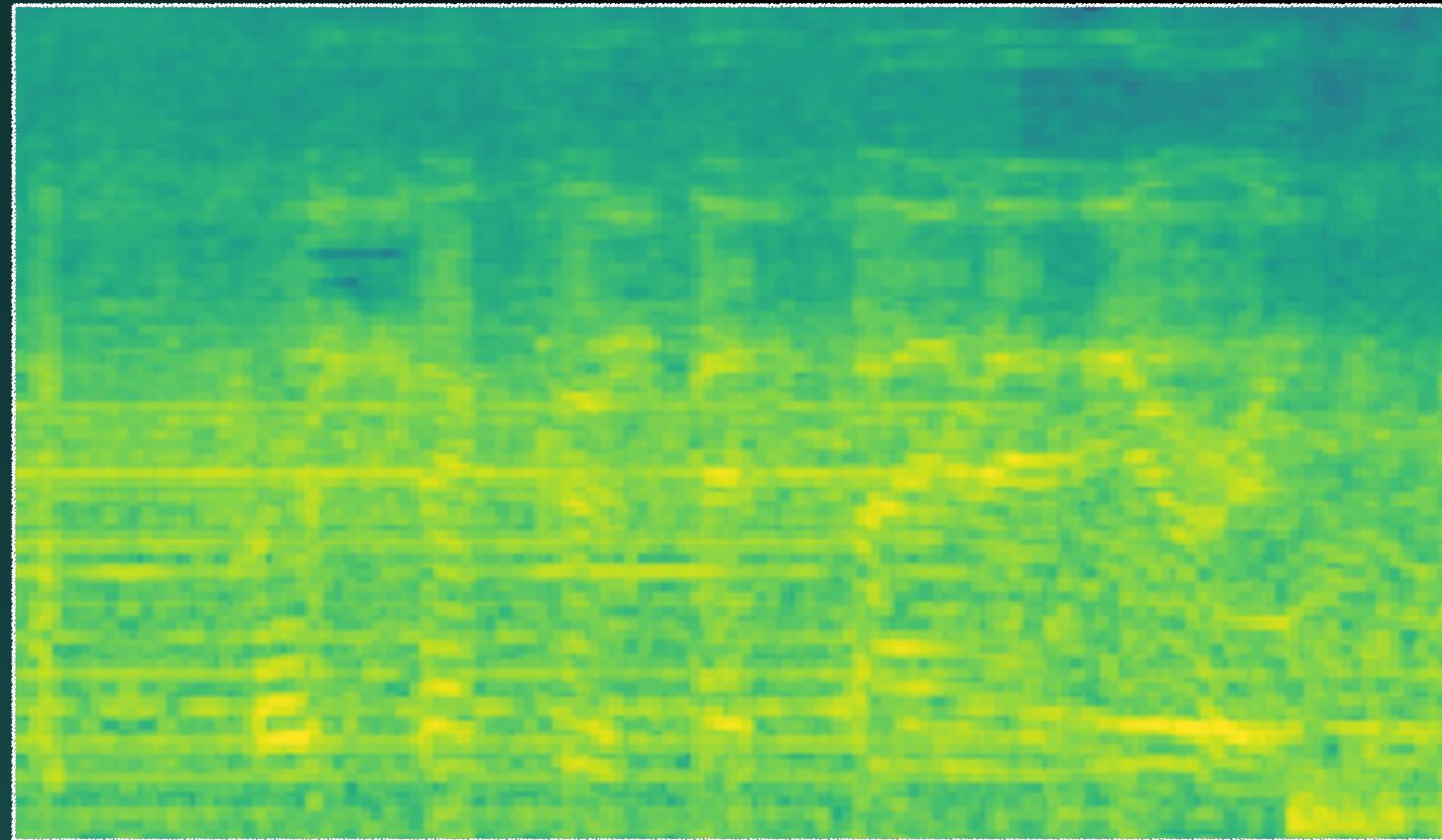
Our Approach | Network Design

- The input-output structure is one of the most difficult design factors
 - Conventional approaches use all or an part of audio clip as input
 - The optimal size of analysis window is not yet known

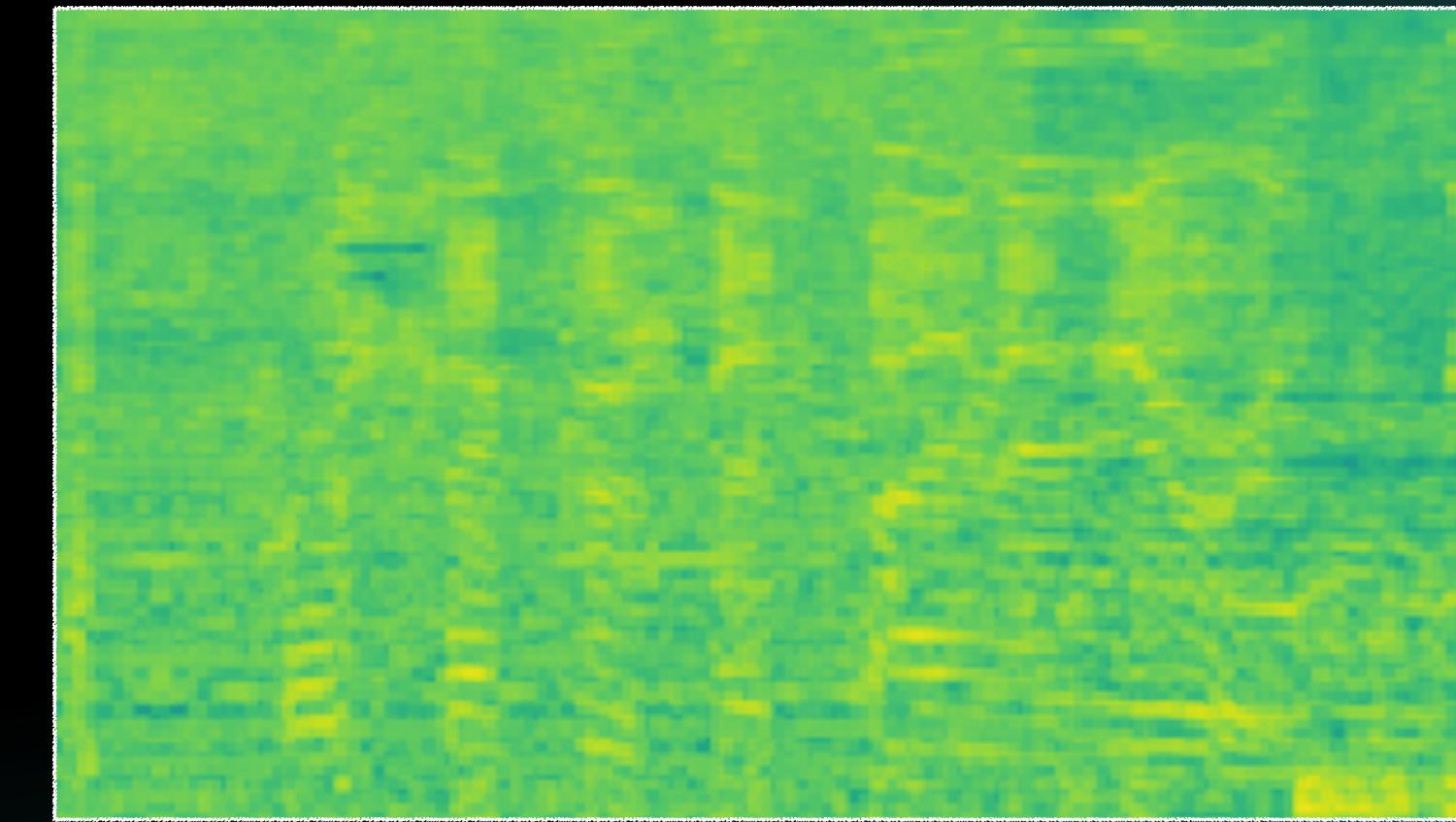


Our Approach | Background Subtraction

- To reduce noise , we introduce a classical signal processing method that subtracts the median value from the specific time window
 - The median values of Mel-spectrogram for each frequency bin are calculated and subtracted from the original one



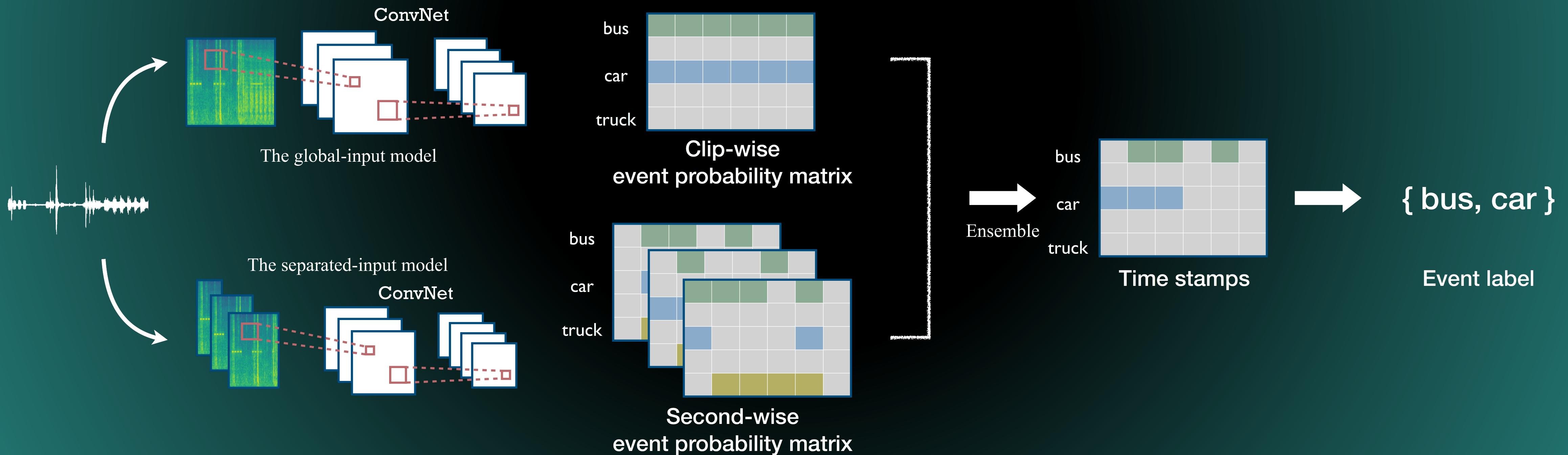
Original Mel-spectrogram



Mel-spectrogram with BS

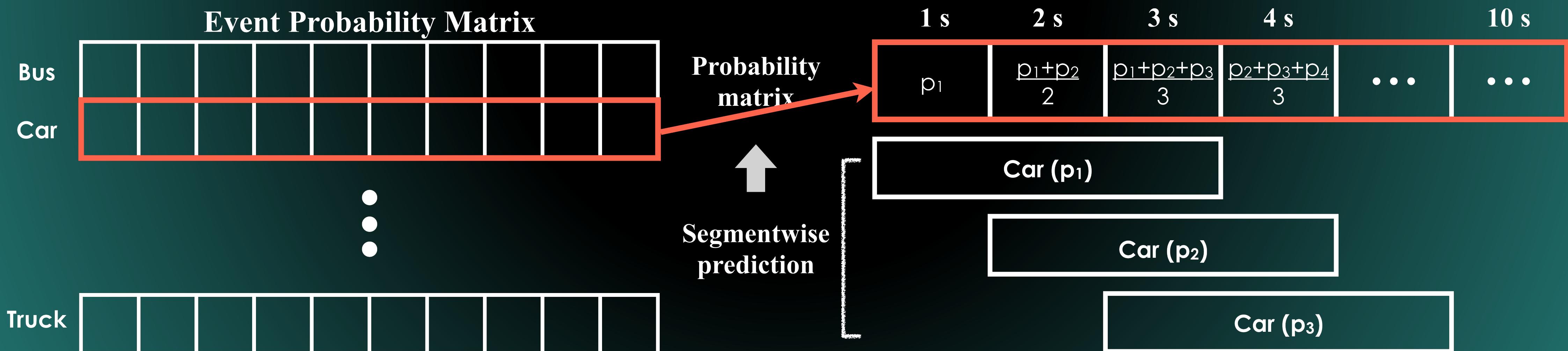
Proposed System | System Overview

- We use models with multi-scale inputs to determine if there is an event in 1-second window



Proposed System | Event Probability Matrix

- The various results corresponding to one clip are converted into a single probability matrix
 - The shape of probability matrix is (17×10) which correspond to the index of label and the time



Proposed System | Ensemble

- **How to use the global-input model**

- It can be used like any other models (*ClipAvg*), or it can have the greatest weight than any other models (*ClipGate*)

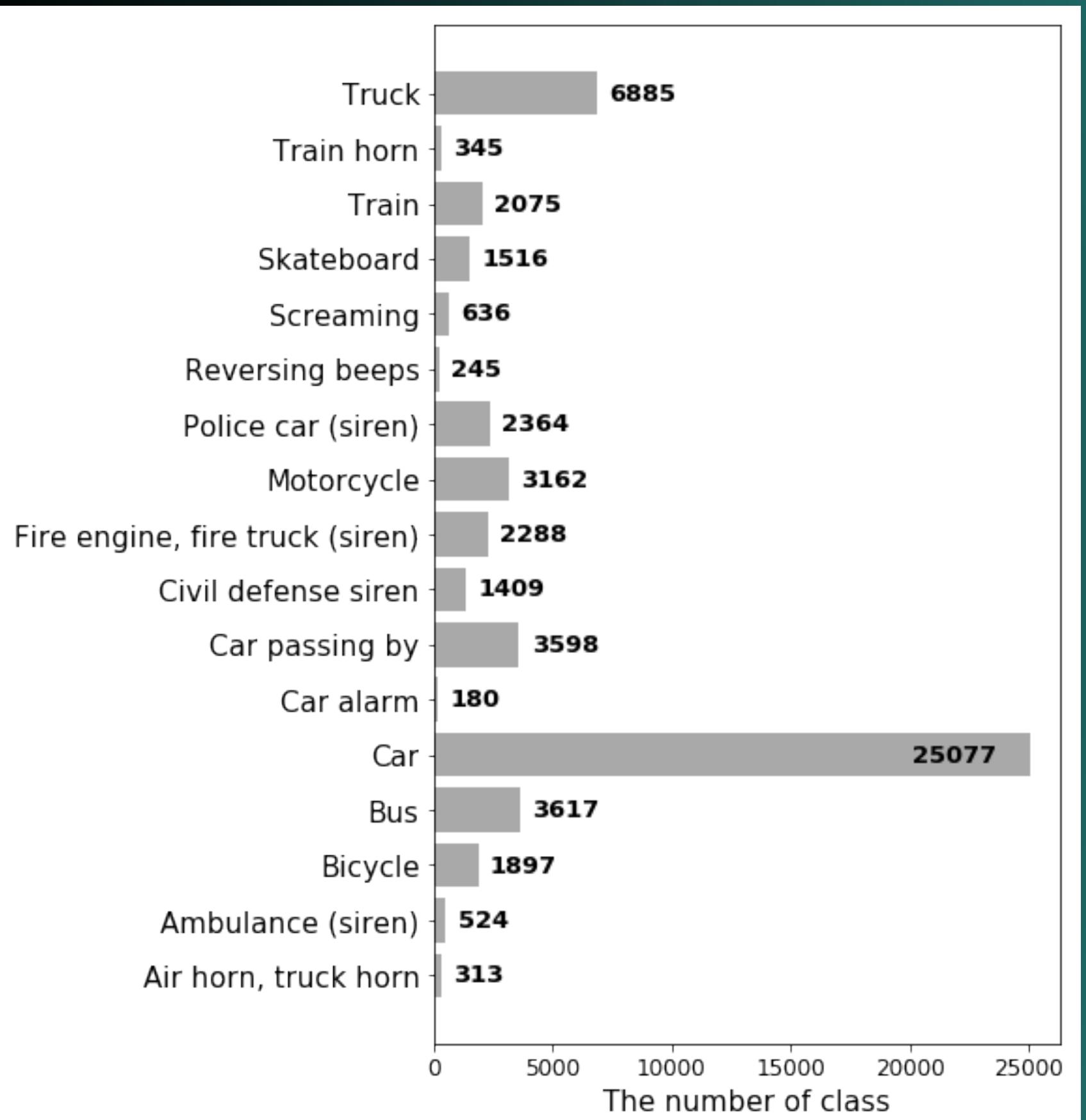
- **Ensemble methods for ensemble single models**

- Mean probability or weighted mean probability
- Weights for mean probability is chosen by iteratively adding a model that maximize the performance at that time

Experiments | Data Set

- **Subset of Google AudioSet**

- Up to 10 seconds of audio clips
- 51,172 training and 488 test set
- The training set includes 56,131 labels for 17 classes
- There is a heavy class imbalance in the training set



Experiments | Audio Preprocessing

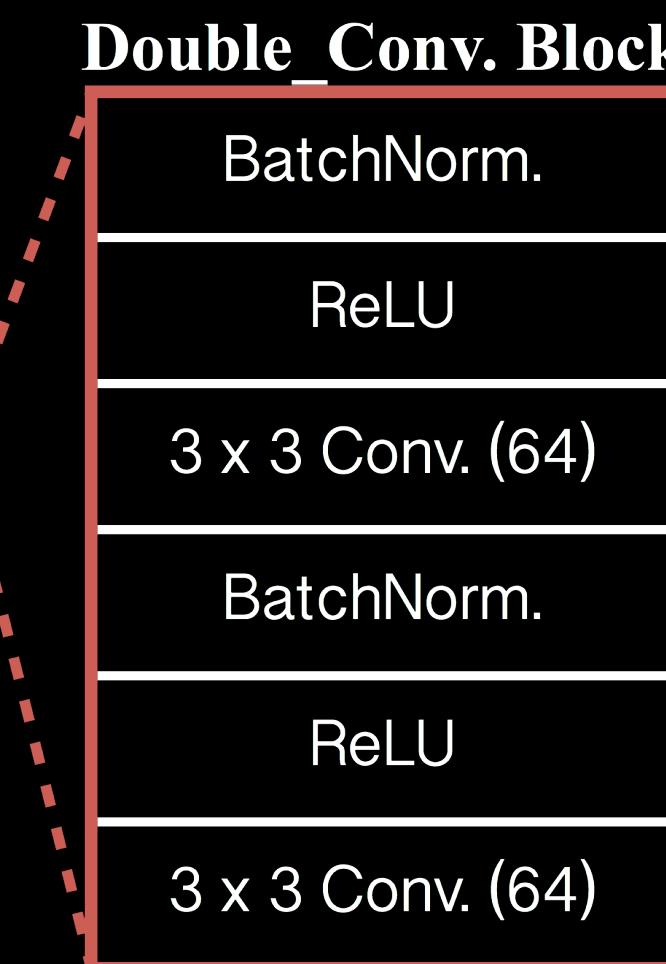
- Exclude the sample whose amplitude is always zero (14 clips)
- Clips which shorter than 10-second are zero-padded to equalize length (10,785 clips)
- The amplitude of the audio signal normalized to the full-range
- The signals are transformed to 128-bin log Mel-spectrogram
 - 2,048 fft points and hop size of 431 or 460
- (Additional) Background Subtraction

Experiments | Network Architecture

The global-input model (data shape)

Audio Input	(1, 441000)
Mel-spectrogram	(1, 128, 1024)
Double_Conv. block	
4 x 4 Max-pooling	(64, 32, 256)
Double_Conv. block	
4 x 4 Max-pooling	(64, 8, 64)
Double_Conv. block	
2 x 4 Max-pooling	(64, 8, 16)
Double_Conv. block	
2 x 4 Max-pooling	(64, 4, 4)
Double_Conv. block	
GlobalAveragePooling	(1024)
Output	(17)

Double_Conv. Block



The separated-input model (data shape)

Audio Input	(1, 44100 x n)
Mel-spectrogram	(1, 128, 96 x n)
Double_Conv. block	
4 x 4 Max-pooling	(64, 32, 24 x n)
Double_Conv. block	
4 x 3 Max-pooling	(64, 8, 8 x n)
Double_Conv. block	
2 x 2 Max-pooling	(64, 4, 4 x n)
Double_Conv. block	
2 x 2 Max-pooling	(64, 2, 2 x n)
Double_Conv. block	
GlobalAveragePooling	(256 x n)
Output	(17)

Results

- **Background subtraction**

- almost same result for both tasks
- BS with long time window degrades performance significantly

- **Ensemble**

- useful for subtask B, but not for A

Networks	Subtask A <i>F-1</i>	Subtask B <i>ER</i>
Baseline (MLP)	.1310	1.0200
10-second input (w/BS)	.4745 (.3378)	-
1s-segmented input (w/BS)	.4125 (.4373)	.7963 (.8362)
2s-segmented input (w/BS)	.4229 (.4316)	.8071 (.8007)
3s-segmented input (w/BS)	.4538 (.4561)	.7546 (.7610)
4s-segmented input (w/BS)	.4304 (.4313)	.7633 (.7718)
5s-segmented input (w/BS)	.4335 (.3588)	.8028 (.8431)
MeanProb of 5 models (w/BS)	.4408 (.4448)	.7667 (.7688)
MeanProb of 10 models	.4430	.7475
ClipAvg in 5 best models	.4762	.7167
ClipGate in 5 best models	.4745	.7287
*Ensemble selection (<i>F1</i>)	.5139	.7477
*Ensemble selection (<i>ER</i>)	.4831	.7021
*Ensemble selection (<i>F1-ER</i>)	.4885	.7089

Results | Submission Results

- The better performance observed in evaluation set
- The ensemble method does not change the system significantly

Networks	Subtask A		Subtask B	
	<i>F-1</i>	<i>ER</i>	<i>F-1</i>	<i>ER</i>
Baseline (MLP)	.182		.930	
ClipAvg in 5 best models	.523		.670	
ClipGate in 5 best models	.523		.670	
Ensemble selection (<i>F1</i>)	.526		-	
Ensemble selection (<i>ER</i>)	-		.670	
Ensemble selection (<i>F1-ER</i>)	.521		.660	

Conclusion

- We used approach that using a larger window for time stamp prediction
- We proposed the system that use the models with multi-scale input
- We proposed background subtraction as a preprocessing method to find a new feature representation in the input signal
- Our proposed models have been successfully trained, and the ensemble allows us to find events in a one-second window.

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