

2(a) Given:

$J(\theta) =$	$CE(\mathbf{y}, \hat{\mathbf{y}}) = -\sum_{i=1}^5 (y_i \log(y_i))$	(1)
$\mathbf{h} =$	$\tanh(\mathbf{x}^{(t)} \mathbf{W} + \mathbf{b}_1)$	(2)
Let $\mathbf{z}_1 =$	$\mathbf{x}^{(t)} \mathbf{W} + \mathbf{b}_1$	(3)
$\hat{\mathbf{y}} =$	$\text{softmax}(\mathbf{hU} + \mathbf{b}_2)$	(4)
Let $\mathbf{z}_2 =$	$\mathbf{hU} + \mathbf{b}_2$	(5)

$\frac{\partial J}{\partial \mathbf{U}} =$	$\frac{\partial J}{\partial \mathbf{z}_2} \frac{\partial \mathbf{z}_2}{\partial \mathbf{U}}$	(6)
$\frac{\partial J}{\partial \mathbf{z}_2} =$	$-\frac{\partial}{\partial \mathbf{z}_2} \sum_i (y_i \log(y_i))$	(7)
$=$	$\hat{\mathbf{y}} - \mathbf{y}$ from Assignment1 2(b), by substituting \mathbf{z}_2 for θ	(8)
$\frac{\partial \mathbf{z}_2}{\partial \mathbf{U}} =$	\mathbf{h}	(9)
$\frac{\partial J}{\partial \mathbf{U}} =$	$\mathbf{h}^T (\hat{\mathbf{y}} - \mathbf{y})$	(10)

$\frac{\partial J}{\partial \mathbf{b}_2} =$	$\frac{\partial J}{\partial \mathbf{z}_2} \frac{\partial \mathbf{z}_2}{\partial \mathbf{b}_2}$	(11)
$\frac{\partial J}{\partial \mathbf{z}_2} =$	$\hat{\mathbf{y}} - \mathbf{y}$ from Equation (8)	(12)
$\frac{\partial \mathbf{z}_2}{\partial \mathbf{b}_2} =$	1	(13)
$\frac{\partial J}{\partial \mathbf{b}_2} =$	$(\hat{\mathbf{y}} - \mathbf{y})$	(14)

$\frac{\partial J}{\partial \mathbf{h}} =$	$\frac{\partial J}{\partial \mathbf{z}_2} \frac{\partial \mathbf{z}_2}{\partial \mathbf{h}}$	(15)
$\frac{\partial J}{\partial \mathbf{z}_2} =$	$\hat{\mathbf{y}} - \mathbf{y}$ from Equation (8)	(16)
$\frac{\partial \mathbf{z}_2}{\partial \mathbf{h}} =$	\mathbf{U}	(17)
$\frac{\partial J}{\partial \mathbf{b}_2} =$	$(\hat{\mathbf{y}} - \mathbf{y}) \mathbf{U}^T$	(18)

$\frac{\partial J}{\partial \mathbf{W}} =$	$\frac{\partial J}{\partial \mathbf{h}} \frac{\partial \mathbf{h}}{\partial \mathbf{W}}$	(19)
$=$	$\mathbf{x}^{(t)\text{T}} \left(\frac{\partial J}{\partial \mathbf{h}} \odot \tanh'(\mathbf{x}^{(t)} \mathbf{W} + \mathbf{b}_1) \right)$	(20)

$\frac{\partial J}{\partial \mathbf{b}_1} =$	$\frac{\partial J}{\partial \mathbf{h}} \frac{\partial \mathbf{h}}{\partial \mathbf{b}_1}$	(21)
$=$	$\left(\frac{\partial J}{\partial \mathbf{h}} \odot \tanh'(\mathbf{x}^{(t)} \mathbf{W} + \mathbf{b}_1) \right)$	(22)

$\frac{\partial J}{\partial \mathbf{x}^{(t)}} =$	$\frac{\partial J}{\partial \mathbf{h}} \frac{\partial \mathbf{h}}{\partial \mathbf{x}^{(t)}}$	(23)
$=$	$\left(\frac{\partial J}{\partial \mathbf{h}} \odot \tanh'(\mathbf{x}^{(t)} \mathbf{W} + \mathbf{b}_1) \right) \mathbf{W}^{\text{T}}$	(24)

$\frac{\partial CE}{\partial \mathbf{W}_2} =$	$\frac{\partial CE}{\partial \mathbf{z}_2} \frac{\partial \mathbf{z}_2}{\partial \mathbf{W}_2}$	(25)
$=$	$\delta_1 \frac{\partial(\mathbf{h}\mathbf{W}_2 + \mathbf{b}_2)}{\partial \mathbf{W}_2}$	(26)
$=$	$\mathbf{h}^T \delta_1$	(27)

$\frac{\partial CE}{\partial \mathbf{b}_2} =$	$\frac{\partial CE}{\partial \mathbf{z}_2} \frac{\partial \mathbf{z}_2}{\partial \mathbf{b}_2}$	(28)
$=$	$\delta_1 \frac{\partial(\mathbf{h}\mathbf{W}_2 + \mathbf{b}_2)}{\partial \mathbf{b}_2}$	(29)
$=$	$\mathbf{1}^T \delta_1$	(30)

$\frac{\partial CE}{\partial \mathbf{W}_1} =$	$\frac{\partial CE}{\partial \mathbf{h}} \frac{\partial \mathbf{h}}{\partial \mathbf{z}_1} \frac{\partial \mathbf{z}_1}{\partial \mathbf{W}_1}$	(31)
$=$	$\delta_1 \mathbf{W}_2^T \sigma'(\mathbf{z}_1) \frac{\partial(\mathbf{x}\mathbf{W}_1 + \mathbf{b}_1)}{\partial \mathbf{W}_1}$	(32)
$=$	$\mathbf{x}^T \delta_1 \mathbf{W}_2^T \sigma'(\mathbf{z}_1)$	(33)

$\frac{\partial CE}{\partial \mathbf{b}_1} =$	$\frac{\partial CE}{\partial \mathbf{h}} \frac{\partial \mathbf{h}}{\partial \mathbf{z}_1} \frac{\partial \mathbf{z}_1}{\partial \mathbf{b}_1}$	(34)
$=$	$\delta_1 \mathbf{W}_2^T \sigma'(\mathbf{z}_1) \frac{\partial(\mathbf{x}\mathbf{W}_1 + \mathbf{b}_1)}{\partial \mathbf{b}_1}$	(35)
$=$	$\mathbf{1}^T \delta_1 \mathbf{W}_2^T \sigma'(\mathbf{z}_1)$	(36)