

$$\textcircled{3} \quad V_{in} = V_R(t) + V_L(t) + V_{out}(t) = R i(t) + L \frac{d}{dt} i(t) + V_{out} =$$

$$\textcircled{A} \quad = RC \frac{d}{dt} V_{out}(t) + LC \frac{d}{dt} \frac{d}{dt} V_{out}(t) + V_{out}$$

$$V_{in} = LC \frac{d^2}{dt^2} V_{out}(t) + RC \frac{d}{dt} V_{out}(t) + V_{out}$$

$$\textcircled{B} \quad V_{in}(\omega) = (j\omega)^2 LC V_{out}(\omega) + j\omega RC V_{out}(\omega) + V_{out}(\omega) = (1 + j\omega RC + j^2 \omega^2 LC) V_{out}(\omega)$$

$$H(\omega) = \frac{V_{out}(\omega)}{V_{in}(\omega)} = \frac{1}{1 + j\omega RC + j^2 \omega^2 LC} = \frac{1}{(1 - \omega^2 LC) + j\omega RC}$$

$$\omega \rightarrow 0 \quad |H(\omega)| \rightarrow 1$$

$$\omega \rightarrow \infty \quad |H(\omega)| \rightarrow 0$$

Low Pass.

$$|H(\omega)| = \frac{1}{\sqrt{(1 - \omega^2 LC)^2 + (j\omega RC)^2}} = \frac{1}{\sqrt{1 - \omega^2 R^2 C^2 + C^2 L^2 \omega^4 - 2CL\omega^2}}$$

$$\textcircled{D} \quad \frac{d}{d\omega} |H(\omega)| = \frac{C\omega(2CL^2\omega^2 + CR^2 - 2L)}{(C^2\omega^2(L^2\omega^2 + R^2) - 2CL\omega^2 + 1)^{3/2}} = 0 \rightarrow$$

$$\rightarrow \underset{\omega=0}{C\omega} (2CL^2\omega^2 + CR^2 - 2L) = 0 \rightarrow 2CL^2\omega^2 + CR^2 - 2L = 0 \rightarrow \omega^2 = \frac{2L - CR^2}{2CL^2} \rightarrow$$

$$\rightarrow \omega = \sqrt{\frac{2L - CR^2}{2CL^2}} \text{ or } 0$$