Suppose 2 particles satisfy both, then

$$M\frac{d^2R}{dt^2} = M_1\frac{1}{dt^2}\vec{r_1} + M_2\frac{d^2}{dt^2}\vec{r_2}$$

 $= \vec{F_1} + \vec{F_2} = \vec{F_4} + \vec{F_{21}} + \vec{F_{21}} + \vec{F_{21}}$

equating this with $\vec{F}^{(e)} = \vec{F}_1 + \vec{F}_2$, he have $\vec{F}_2 + \vec{F}_1 = 0$.

This is the weak law of action and reaction.

Expanding dL, ne have dL=dLF1×P,+F2×P2],

 $= \vec{F_1} \times \vec{F_1} + \vec{F_2} \times \vec{F_2}$

 $=\vec{r}_{1}\times[\vec{r}_{1}^{(e)}+\vec{r}_{2}]+\vec{r}_{2}\times[\vec{r}_{2}^{(e)}+\vec{r}_{12}]$

= FIX F1 + F2 × F2 + F1 × F1 + F2 × F12

The neak law of action and reaction implies $\vec{F}_{12} = -\vec{F}_{21}$, so $\vec{F}_1 \times \vec{F}_{21} + \vec{F}_2 \times \vec{F}_{12} = (\vec{F}_1 - \vec{F}_2) \times \vec{F}_{21} = \vec{F}_{12} \times \vec{F}_{21}$.

Tequating the above quantity with $\tilde{N}^{(e)} = \tilde{r}_1 \times \tilde{r}_1^{(e)} + \tilde{r}_2 \times \tilde{r}_3^{(e)}$, we have the [strong law of action and reaction, since $\tilde{r}_1 \times \tilde{r}_2 = 0$ indicates they are aligned.