## Pedestrian Identification Using CNNs

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**Baseline Presentation** 

### **AGENDA**

1 QUESTION

What is the question we will be working on? Why is it interesting?

) DATA

Data source, size, and main features used. Summary statistics

N ALGORITHMS

What prediction algorithms will we use?

1/4 EVALUATION

How will we evaluate our results?
What is our chosen performance metrics and statistical tests?

CLOSING

Questions Thank You

Question

## Can we use CNN-based algorithms to effectively identify pedestrians on the street?

## Objective:

• Investigate the effectiveness of CNN-based algorithms in detecting pedestrians in real-world street environments

### Motivation:

- Pedestrian detection is a critical component of autonomous vehicle (AV) perception systems
- Ensures the safety of both AV users and pedestrians

### Context:

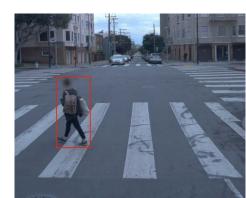
- AVs rely heavily on computer vision systems for situational awareness
- Detecting dynamic objects like pedestrians is more complex than identifying static objects



## Waymo Open Dataset

- Collected from Waymo's autonomous vehicles using 5 cameras and 5 lidars
- Has 11.8 million 2D bounding box annotations on camera images
  - Covers objects like vehicles, pedestrians, cyclists, and traffic signs
- Complements other datasets with:
  - 12.6 million 3D bounding boxes (lidar)
  - o 3D semantic segmentation labels
- Good for object detection, tracking, and scene understanding for autonomous driving





# 03

Algorithms

## Algorithms

#### Fast R-CNN

Fast Region-based Convolutional Neural network

 Identifies objects and draws boxes while classifying

#### Faster R-CNN

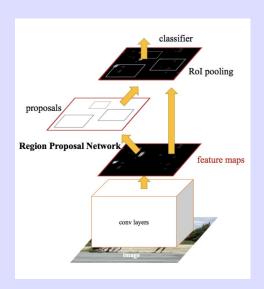
Improves Fast R-CNN by also using a region proposal network (RPN)

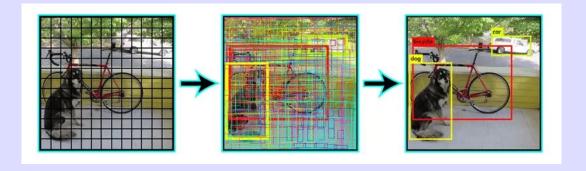
• Same as Fast R-CNN

#### YOLO

You Only Look Once

 Uses single CNN to predict bounding boxes and class probabilities for objects





## 04

Evaluation

## **Evaluations**

## **Quantitative Evaluation**

Examples include F1, precision, recall, or IoU (intersection over union) score to understand the models ability to detect or fail to detect pedestrians

## **Qualitative Evaluation**

Visually look at the predictions from the model to ensure they are correctly identifying all pedestrians and not mislabelling objects as pedestrians

## Thank you for listening