

- [Main Page](#)
- [Data Structures](#)
- [Files](#)
- [File List](#)
- [Globals](#)

param.h File Reference

ARToolkit global structure (parameters) subroutines. [More...](#)

```
#include <AR/config.h>
```

Data Structures

struct	ARParam <i>camera intrinsic parameters.</i> More...
struct	ARSPParam

Functions

int	arParamGet (double global[][3], double screen[][2], int data_num, double mat[3][4]) <i>XXXBK.</i>
int	arParamDecomp (ARParam *source, ARParam *icpara, double trans[3][4]) <i>XXXBK.</i>
int	arParamDecompMat (double source[3][4], double cpara[3][4], double trans[3][4]) <i>XXXBK.</i>
int	arParamIdeal2Observe (const double dist_factor[4], const double ix, const double iy, double *ox, double *oy) <i>Convert ideal screen coordinates of a vertex to observed ones.</i>
int	arParamObserve2Ideal (const double dist_factor[4], const double ox, const double oy, double *ix, double *iy) <i>Convert observed screen coordinates of a vertex to ideal ones.</i>
int	arParamChangeSize (ARParam *source, int xsize, int ysize, ARParam *newparam) <i>change the camera size parameters.</i>
int	arParamSave (char *filename, int num, ARParam *param,...) <i>save a camera intrinsic parameters.</i>
int	arParamLoad (const char *filename, int num, ARParam *param,...) <i>load the camera intrinsic parameters.</i>
int	arParamDisp (ARParam *param) <i>display parameters.</i>
int	arsParamChangeSize (ARSPParam *source, int xsize, int ysize, ARSPParam *newparam)
int	arsParamSave (char *filename, ARSPParam *sparam)
int	arsParamLoad (char *filename, ARSPParam *sparam)
int	arsParamDisp (ARSPParam *sparam)
int	arsParamGetMat (double matL[3][4], double matR[3][4], double cparaL[3][4], double cparaR[3][4], double matL2R[3][4])

Detailed Description

ARToolkit global structure (parameters) subroutines.

This file contains principal routines for loading, saving, and modify camera parameters for of ARToolkit library. Different structures are used for modify in run-time this parameters in the library. A file structure is use for input/output.

Remarks:

History :

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Version:

4.1

Date:

01/12/07

Function Documentation

int	arParamChangeSize (ARParam * <i>source</i> ,
	int <i>xsize</i> ,
	int <i>ysize</i> ,

```

        ARParam * newparam
    )

```

change the camera size parameters.

Change the size variable in camera intrinsic parameters.

Parameters:

source name of the source parameters structure
xsize new length size
ysize new height size
newparam name of the destination parameters structure.

Returns:

0

```

int arParamDecomp( ARParam * source,
                   ARParam * icpara,
                   double trans[3][4]
                   )

```

XXXBK.

XXXBK

Parameters:

source XXXBK
icpara XXXBK
trans XXXBK

Returns:

XXXBK

```

int arParamDecompMat( double source[3][4],
                     double cpara[3][4],
                     double trans[3][4]
                     )

```

XXXBK.

XXXBK

Parameters:

source input camera matrix
cpara camera parameter to be set
trans XXXBK

Returns:

XXXBK

```

int arParamDisp( ARParam * param )

```

display parameters.

Display the structure of the camera instrinsic parameters argument.

Parameters:

param structure to display

Returns:

0

```

int arParamGet( double global[][3],
                double screen[][2],
                int data_num,
                double mat[3][4]
                )

```

XXXBK.

XXXBK

Parameters:

global XXXBK

```

screen   XXXBK
data_num XXXBK
mat      XXXBK

```

Returns:

XXXBK

```

int int arParamIdeal2Observ( const double dist_factor[4],
                             const double ix,
                             const double iy,
                             double *    ox,
                             double *    oy
                             )

```

Convert ideal screen coordinates of a vertex to observed ones.

Ideal coordinates mean that the distortion of the camera is compensated (so a straight line looks straight). In observed coordinates the camera-distortion is not compensated and thus a straight line is not shown really straight.

Parameters:

dist_factor distortion factors of used camera
ix x in ideal screen coordinates
iy y in ideal screen coordinates
ox resulted x in observed screen coordinates
oy resulted y in observed screen coordinates

Returns:

0 if success, -1 otherwise

```

int arParamLoad( const char * filename,
                 int         num,
                 ARParam *   param,
                 ...
                 )

```

load the camera intrinsic parameters.

Load camera intrinsic parameters in the ARToolkit Library from a file (itself, an output of the calibration step).

Parameters:

filename name of the parameters file.
num number of variable arguments
param result of the loaded parameters

Returns:

0 if success, -1 if Error (file not found, file structure problem)

```

int arParamObserv2Ideal( const double dist_factor[4],
                         const double ox,
                         const double oy,
                         double *    ix,
                         double *    iy
                         )

```

Convert observed screen coordinates of a vertex to ideal ones.

Ideal coordinates mean that the distortion of the camera is compensated (so a straight line looks straight). In observed coordinates the camera-distortion is not compensated and thus a straight line is not shown really straight.

Parameters:

dist_factor distortion factors of used camera
ox x in observed screen coordinates
oy y in observed screen coordinates
ix resulted x in ideal screen coordinates
iy resulted y in ideal screen coordinates

Returns:

0 if success, -1 otherwise

```

int arParamSave( char *   filename,
                int      num,
                ARParam * param,
                ...
                )

```

)

save a camera intrinsic parameters.

Save manipulated camera intrinsic parameters in a file.

Parameters:

filename name of the parameters file.

num number of variable arguments

param parameters to save

Returns:

0 if success, -1 if Error (file not found, file structure problem)

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