

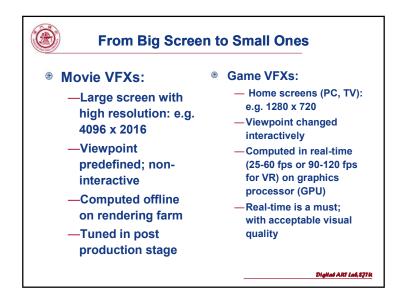


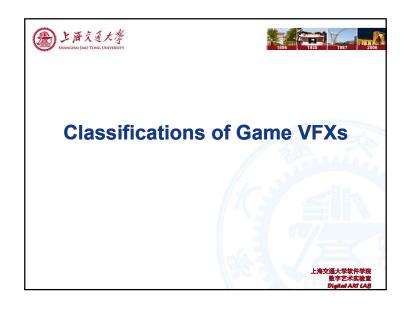
### Introduction

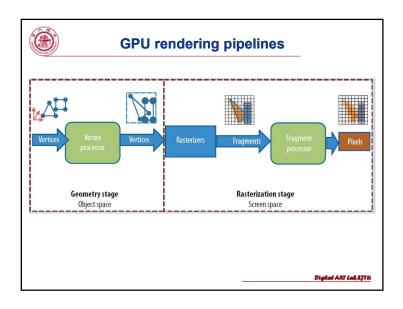
- © Computer games:
  - —A virtual world simulating a real or imagined world
- **<sup>⊕</sup> Visual effects (VFXs) in computer games** 
  - -All graphics effects
  - -with special purposes
- Purposes:
  - Simulate certain phenomena in our lives (e.g. lighting and shadowing, fire)
  - Evoke an immersive illusion or a special emotional feeling (e.g. motion blur → sense of motion, fog → sense of mystery)

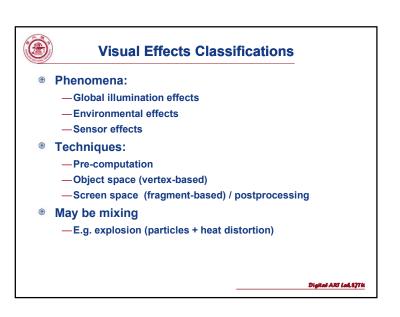
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Computation stage	Global illumination effect	Environmental effect	Sensor effect	Flexibility	Computational complexity
Precomputation (offline)	Irradiance, shadow, color bleeding, precomputed radiance transfer (PRT), ambient occlusion (AO), irradiance volume	Skybox	None	Static scene	Scene complexity and level of detail
Object space (real-time)	Shadow, reflection, refraction, AO	Fog, sun shaft, smoke, fire, water, clouds, rain, snow, explosions	Motion blur	Dynamic scene	Scene complexity, level of detail, and screen resolution
Screen space (real time)	Refraction, color bleeding, SSAO, SSDO	Fog, sun shaft, rain, snow, heat distortion	Depth of field, motion blur, bloom, glare, afterimage, tone mapping, color correction, lens distortion, vignetting, chromatic abbreviation, film grain, night vision, thermal vision	Dynamic scene	Screen resolution only





### **Typical Visual Effects Workflow**

- Visual effects artist
  - —conceive a visual effect
  - —Painting tool quickly draw a conceptual image
  - Realize the effect using an existing tool (e.g. game editor plugin module)
  - -Ask for a suitable tool

- Programmer
  - —Implement a tool and provide parameters for the artist to control
- Iteration
- **Trends:** 
  - —programmer doing more work
  - —automate the production process

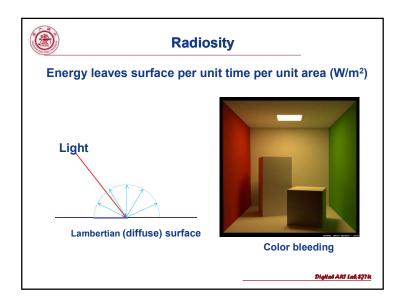
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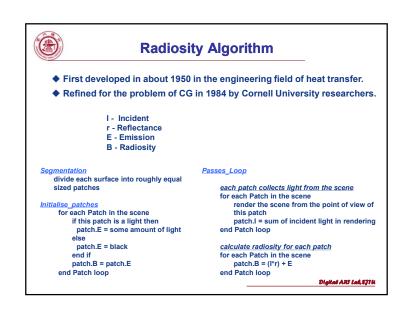


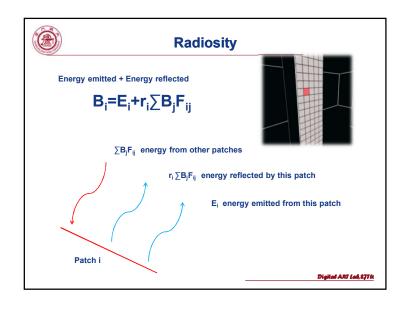
# **Global illumination effects**

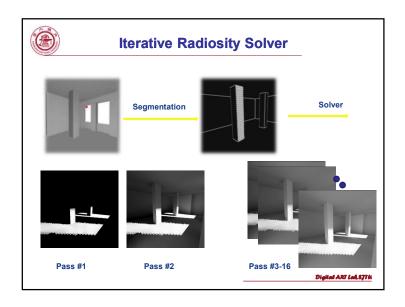
- direct illumination vs. indirect illumination
- Model indirect illumination effects and complex phenomenon
  - -reflection
  - -refraction
  - -color bleeding
  - -soft shadows
  - **—...**
- More complexity
  - -Light sources
  - -Materials
  - -Light transport paths

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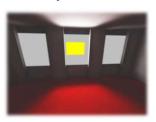






### **Light Map**

- ® Radiosity is too slow for real time computation
- A light map is a 3D engine light data structure which contains the brightness of surfaces in a game.
- Light maps are pre-computed and used for static scenes/objects.





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## Light map tech (offline pre-lighting)

- Assume static relationship of light and scene object
  - —the GI light transport will be constant for static scenes
  - pre-computation of light transport result and store at pervertex or per-texel (exitance value, irradiance value or irradiance direction)
    - View-independent effects: (such as Lambertian diffuse reflection): store exitance value
    - View-dependent effects (such as normal map, mirror reflection): store irradiance value and direction, and calculate at run time
- dynamic object are treated in additional

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### **Evolution of Light map techniques**

- Light maps
  - -1996, Quake:
    - · static light map
  - -1999, Quake III:
    - · per-vertex lighting
    - · hardware acceleration
  - -2004, Doom 3:
    - · per-pixel lighting
    - dynamic shadows
  - -2007, Halo 3:
    - dynamic Gl
    - Spherical harmonic light maps



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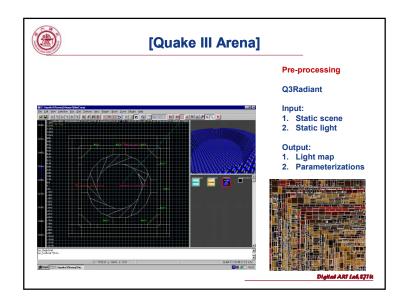


### [Quake III Arena]

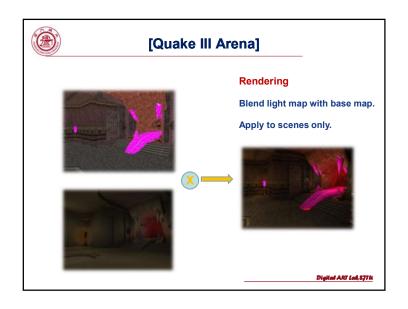
- Tech Info
  - · Publisher: Activision
  - · Developer: id Software
  - · Genre: Sci-Fi First-Person Shooter
  - · Release Date: Dec 2, 1999
  - Minimum System Requirements
    - · System: PII 233 or equivalent
  - RAM: 64 MB
  - · Video Memory: 8 MB
  - · Hard Drive Space: 70 MB
- Official Site
  - www.quakelive.com

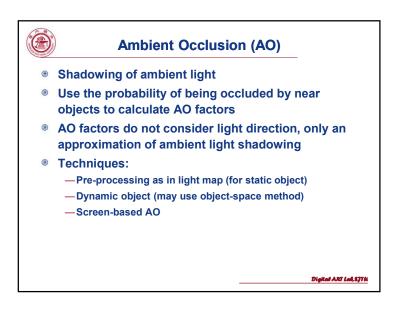


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### **Ambient Occlusion (AO)**

- Shadowing of ambient light
- $L_i(\mathbf{l}) = L_A$
- -the softest shadow
- ambient light lacks any directional variation (so without AO, objects appear flat)

$$E(\mathbf{p},\mathbf{n}) = \int_{\Omega} L_A \cos \theta_i d\omega_i = \pi L_A$$

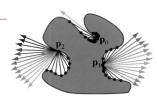






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- $^{\scriptsize \textcircled{\$}}$  Use the probability of being occluded by near objects to calculate AO factors (visibility v(p,l))
- AO factors do not consider light direction, only an approximation of ambient light shadowing

$$E(\mathbf{p}, \mathbf{n}) = L_A \int_{\Omega} v(\mathbf{p}, \mathbf{l}) \cos \theta_i d\omega_i$$

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**⊕** AO factor K<sub>A</sub> (ambient visibility: value [0,1])

$$k_A(\mathbf{p}) = rac{1}{\pi} \int_{\Omega} v(\mathbf{p}, \mathbf{l}) \cos heta_i d\omega_i.$$

$$E(\mathbf{p}, \mathbf{n}) = k_A(\mathbf{p})\pi L_A$$

- Techniques:
  - -Pre-processing as in light map (for static object)
  - Dynamic object (may use object-space method)
  - -Screen-based AO

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### **Ambient Occlusion**

From Ubisoft's Endwar (AO map)







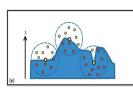
- Object space methods:
  - -dependent on scene complexity





### **SSAO**

- Screen space ambient occlusion
  - -independent of scene complexity
  - -depth buffer as a height field
  - —samples neighborhood points and computes the number of points passing the depth test.
- © Crytek's SSAO (Crysis, 2007)
  - -Only 16 texture fetches per pixel
  - —Use random rotated kernel
  - -make the noise high-frequency
  - -Post-blur step
  - Edge-preserving blur





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### **Optimization**

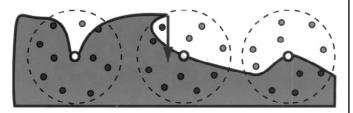
- a brute force method
  - require about 200 texture reads per pixel for good visual quality.
  - -not acceptable for real-time rendering on GPU
- In order to get high quality results with <u>far fewer</u> <u>reads</u>
  - sampling is performed using a randomly-rotated kernel
  - —The kernel orientation is repeated every N screen pixels in order to have <u>only high-frequency noise</u> in the final picture.

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### Crytek's SSAO

- The algorithm
  - is executed purely on GPU and implemented as a pixel shader
  - analyzing the scene depth buffer which is stored in a texture.
  - For every <u>pixel</u> on the screen, the pixel shader samples the depth values around the current pixel and tries to compute the amount of occlusion from each of the sampled points.
  - In its simplest implementation, the occlusion factor depends only on the depth difference between sampled point and current point.





### **Optimization**

- In the end, this high frequency noise is greatly removed by a NxN post-process blurring step taking into account depth discontinuities
  - using methods such as comparing adjacent normals and depths.
- Such a solution allows
  - a reduction in the number of depth samples per pixel to about 16 or less while maintaining a high quality result,
  - —and allows the use of SSAO in real-time applications like computer games.

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### **SSAO**

- Advantages:
  - Independent from scene complexity
  - no data pre-processing, no loading time
  - dynamic scenes
  - consistent way for every pixel
  - no CPU usage completely on GPU
  - easily integrated into any modern graphics pipeline
- Disadvantages:
  - local and often view-dependent (dependent on adjacent texel depths)
  - Blurring noise may cause bleeding at object edges

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