Highly parallel auto-differentiate system for deep learning

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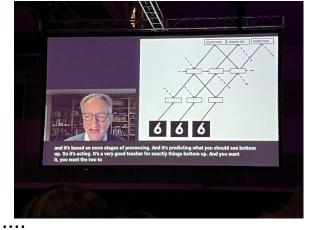
Overview

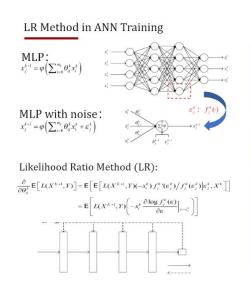
- Background & Related work
- Optimized primitives using GPU Tensor Cores
- High performance neural network training w/o BP
- Evaluations
- Future work

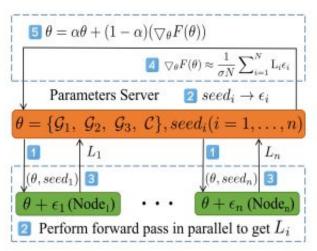
Background & Related work

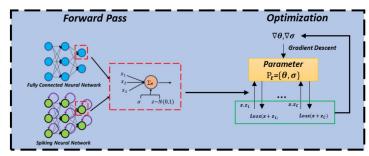
- Pattern: Big model, Big data, Big time
- Acceleration: CPU/GPU/TPU/NPU
- Optimization: Chain-rule based backpropagation

But in fact, chain rule is not the only way to get the gradient.......







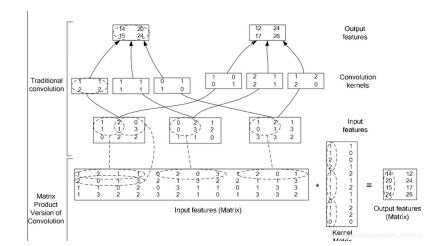


Optimized primitives using GPU tensor cores

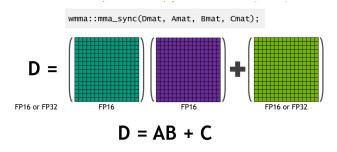
"Primitives" in NN:

- Convolutional layer
- Fully connected layer
- Element-wise activation
- Hadamard product

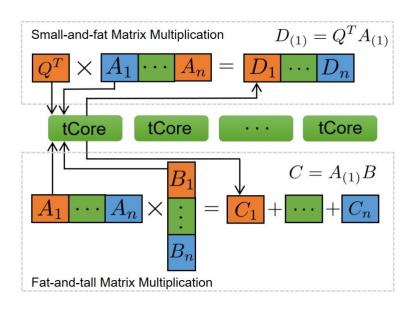
Matrix multiplications



Optimized primitives using GPU tensor cores

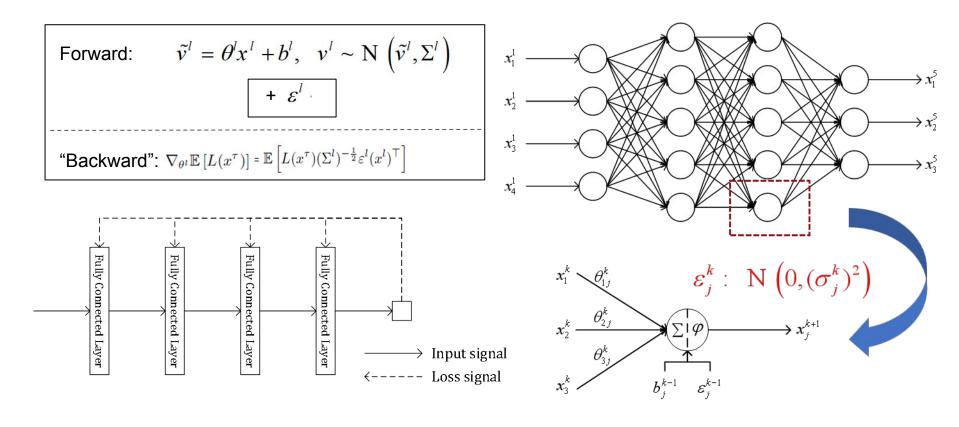






What we need to do is just to accelerate the matrix multiplications

Neural network training w/o BP



High performance neural network training w/o BP

$$f(H^{(l)},A) = \sigma \left(\widehat{D}^{-0.5} \widehat{A} \widehat{D}^{-0.5} H^{(l)} W^{(l)} \right)$$

$$\widehat{D} = \operatorname{diag}(A), \widehat{A} = A + I$$

$$f(H^{(l)},A) = \sigma \left(\widehat{D}^{-0.5} \widehat{A} \widehat{D}^{-0.5} H^{(l)} W^{(l)} + Z^{(l)} \right)$$

Forward:

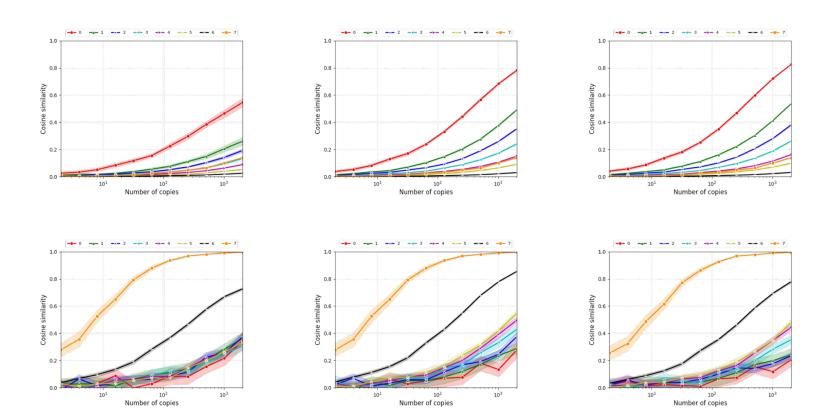
Backward:

$$(h_{t}, c_{t}) = \varphi(u_{t}, v_{t}), \quad u_{t} = \theta^{hh} h_{t-1} + b^{hh} + z_{t}^{hh}, \quad v_{t} = \theta^{xh} x_{t} + b^{xh} + z_{t}^{xh}$$

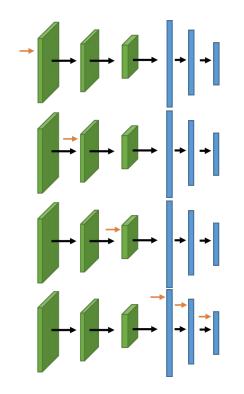
$$z_{t}^{hh} = (\Sigma^{hh})^{-\frac{1}{2}} \varepsilon_{t}^{hh}, \varepsilon_{t}^{hh} \sim N(0, I), \quad z_{t}^{xh} = (\Sigma^{xh})^{-\frac{1}{2}} \varepsilon_{t}^{xh}, \varepsilon_{t}^{xh} \sim N(0, I)$$

$$\nabla_{\theta^{hh}} \mathbb{E} \left[L(h, c; \omega) \right] = \mathbb{E} \left[L(h, c; \omega) \sum_{t=1}^{T} (\Sigma^{hh})^{-\frac{1}{2}} \varepsilon_t^{hh} h_t^{\top} \right]$$
$$\nabla_{\theta^{xh}} \mathbb{E} \left[L(h, c; \omega) \right] = \mathbb{E} \left[L(h, c; \omega) \sum_{t=1}^{T} (\Sigma^{xh})^{-\frac{1}{2}} \varepsilon_t^{xh} x_t^{\top} \right]$$

Problems & Challenges



Solutions for variance reduction



Layer-wise perturbation

$$I = \frac{1}{N} \sum_{i=1}^{N} g(\mathbf{X}_{i}) = \frac{1}{N} \sum_{i=1}^{N} G_{i}$$

$$= \frac{1}{n} \sum_{i=1}^{n} \frac{G_{2i-1} + G_{2i}}{2} = \frac{1}{n} \sum_{i=1}^{n} H_{i}$$

$$G_{i} = g(\mathbf{X}_{i}) \text{ and } H_{i} = \frac{G_{2i-1} + G_{2i}}{2}$$

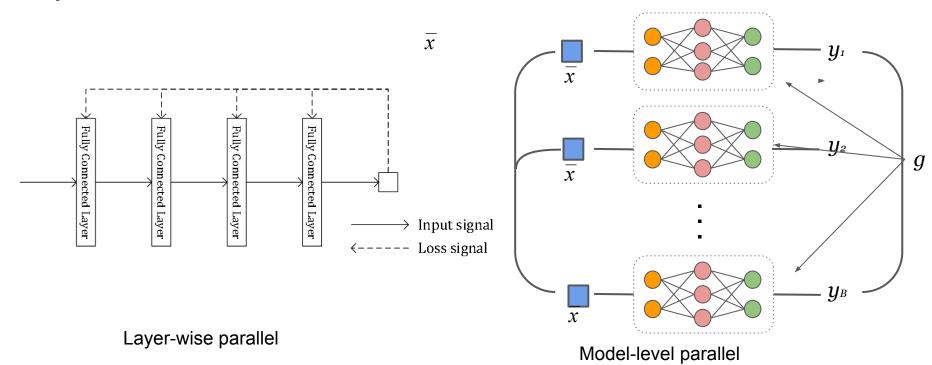
$$\sigma_{h}^{2} = \text{Var}(H_{i})$$

$$= \frac{1}{4} (\sigma_{g}^{2} + \sigma_{g}^{2} + 2\text{Cov}(H_{2i-1}, H_{2i}))$$

$$= \frac{1}{2} (\sigma_{g}^{2} + \text{Cov}(G_{2i-1}, G_{2i})).$$

Antithetic Variable

Implementations



Evaluations

Model	Meth od	Acc.	Time/epoch
MLP	BP	99.5	1 min 17 s
	LR-F	92.2	3 min 09 s
	LR-L	92.2	3 min 45 s
	LR-M	99.5	58 s

Model	Meth od	Acc.	Time/epoch
RNN	BP	88.3	3 min 15 s
	LR-F	84.2	4 min 35 s
	LR-L	84.3	5 min 27 s
	LR-M	88.4	2 min 20 s

Model	Meth od	Acc.	Time/epoch
GCN	BP	80.4	1 min 51 s
	LR-F	75.6	3 min 23 s
	LR-L	75.2	4 min 19 s
	LR-M	78.8	1 min 43 s

Results on MNIST dataset

Results on Ag-News dataset

Results on Cora dataset

Limitations & Future work

Improvement for the pure layer-wise parallel strategy

Fine-grained parallelism design

Better suitable data structure

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