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Foundations of AI

Project 3

Implement a Planning Search

Due Date 2018-02-09

In this project I defined a group of problems in classical Planning Domain Definition Language for the air cargo domain discussed in the lectures. I set up the problems for search and experimented with various automatically generated heuristics. This is my analysis of the results.

Given three problems in the Air Cargo Action Schema:

Action(Load(c, p, a),
 PRECOND: $\text{At}(c, a) \wedge \text{At}(p, a) \wedge \text{Cargo}(c) \wedge \text{Plane}(p) \wedge \text{Airport}(a)$
 EFFECT: $\neg \text{At}(c, a) \wedge \text{In}(c, p)$)

Action(Unload(c, p, a),
 PRECOND: $\text{In}(c, p) \wedge \text{At}(p, a) \wedge \text{Cargo}(c) \wedge \text{Plane}(p) \wedge \text{Airport}(a)$
 EFFECT: $\text{At}(c, a) \wedge \neg \text{In}(c, p)$)

Action(Fly(p, from, to),
 PRECOND: $\text{At}(p, \text{from}) \wedge \text{Plane}(p) \wedge \text{Airport}(\text{from}) \wedge \text{Airport}(\text{to})$
 EFFECT: $\neg \text{At}(p, \text{from}) \wedge \text{At}(p, \text{to})$)

- Problem 1 initial state and goal:

Init($\text{At}(C1, \text{SFO}) \wedge \text{At}(C2, \text{JFK})$
 $\wedge \text{At}(P1, \text{SFO}) \wedge \text{At}(P2, \text{JFK})$
 $\wedge \text{Cargo}(C1) \wedge \text{Cargo}(C2)$
 $\wedge \text{Plane}(P1) \wedge \text{Plane}(P2)$
 $\wedge \text{Airport}(\text{JFK}) \wedge \text{Airport}(\text{SFO})$)

Goal($\text{At}(C1, \text{JFK}) \wedge \text{At}(C2, \text{SFO})$)

- Problem 2 initial state and goal:

Init($\text{At}(C1, \text{SFO}) \wedge \text{At}(C2, \text{JFK}) \wedge \text{At}(C3, \text{ATL})$
 $\wedge \text{At}(P1, \text{SFO}) \wedge \text{At}(P2, \text{JFK}) \wedge \text{At}(P3, \text{ATL})$
 $\wedge \text{Cargo}(C1) \wedge \text{Cargo}(C2) \wedge \text{Cargo}(C3)$
 $\wedge \text{Plane}(P1) \wedge \text{Plane}(P2) \wedge \text{Plane}(P3)$
 $\wedge \text{Airport}(\text{JFK}) \wedge \text{Airport}(\text{SFO}) \wedge \text{Airport}(\text{ATL})$)

Goal($\text{At}(C1, \text{JFK}) \wedge \text{At}(C2, \text{SFO}) \wedge \text{At}(C3, \text{SFO})$)

- Problem 3 initial state and goal:

Init($\text{At}(C1, \text{SFO}) \wedge \text{At}(C2, \text{JFK}) \wedge \text{At}(C3, \text{ATL}) \wedge \text{At}(C4, \text{ORD})$
 $\wedge \text{At}(P1, \text{SFO}) \wedge \text{At}(P2, \text{JFK})$
 $\wedge \text{Cargo}(C1) \wedge \text{Cargo}(C2) \wedge \text{Cargo}(C3) \wedge \text{Cargo}(C4)$
 $\wedge \text{Plane}(P1) \wedge \text{Plane}(P2)$
 $\wedge \text{Airport}(\text{JFK}) \wedge \text{Airport}(\text{SFO}) \wedge \text{Airport}(\text{ATL}) \wedge \text{Airport}(\text{ORD})$)

Goal($\text{At}(C1, \text{JFK}) \wedge \text{At}(C3, \text{JFK}) \wedge \text{At}(C2, \text{SFO}) \wedge \text{At}(C4, \text{SFO})$)

Uninformed Search Strategies Analysis:

I chose to try 4 different strategies for each of the three given problems. See the results below.

For P1

```
python run_search.py -p 1 -s 1
```

```
python run_search.py -p 1 -s 3
```

```
python run_search.py -p 1 -s 5
```

```
python run_search.py -p 1 -s 7
```

Search Strategy	Node Expansions	Goal Tests	New Nodes	Time Elapsed	Optimal
breadth first search	43	56	180	0.0369	Yes
depth first search	12	13	48	0.009	no
uniform cost search	55	57	224	0.044	yes
greedy best first	7	9	28	0.006	yes

For P2

```
python run_search.py -p 2 -s 1
```

```
python run_search.py -p 2 -s 3
```

```
python run_search.py -p 2 -s 5
```

```
python run_search.py -p 2 -s 7
```

Search Strategy	Node Expansions	Goal Tests	New Nodes	Time Elapsed	Optimal
breadth first search	3401	4672	31049	9.802	yes
depth first search	350	351	3142	1.766	no
uniform cost search	4761	4763	43206	13.254	yes
greedy best first	550	552	4950	1.523	yes

For P3

```
python run_search.py -p 3 -s 1
```

```
python run_search.py -p 3 -s 3
```

```
python run_search.py -p 3 -s 5
```

```
python run_search.py -p 3 -s 7
```

Search Strategy	Node Expansions	Goal Tests	New Nodes	Time Elapsed	Optimal
breadth first search	14491	17947	128184	48.966	yes
depth first search	1948	1949	16253	22.734	no
uniform cost search	17783	17785	155920	56.652	yes
greedy best first	4031	4033	35794	12.947	yes

Heuristic Search Strategies Analysis:

For P1

python run_search.py -p 1 -s 8

python run_search.py -p 1 -s 9

python run_search.py -p 1 -s 10

Search Strategy	Node Expansions	Goal Tests	New Nodes	Time Elapsed	Optimal
a* search h_1	55	57	224	0.05	yes
a* search h_ignore_preconditions	41	43	170	0.05	yes
a* searchh_pg_levelsum	55	57	224	3.98	no

For P2

python run_search.py -p 2 -s 8

python run_search.py -p 2 -s 9

python run_search.py -p 2 -s 10

Search Strategy	Node Expansions	Goal Tests	New Nodes	Time Elapsed	Optimal
a* search h_1	4761	4763	43206	13.24	yes
a* search h_ignore_preconditions	1450	1452	13303	6.382	yes
a* searchh_pg_levelsum	--	--	--	> 10 minutes	no

For P3

python run_search.py -p 3 -s 8

```
python run_search.py -p 3 -s 9
python run_search.py -p 3 -s 10
```

Search Strategy	Node Expansions	Goal Tests	New Nodes	Time Elapsed	Optimal
a* search h_1	17783	17785	155920	57.329	yes
a* search h_ignore_preconditions	5003	5005	44586	23.854	yes
a* searchh_pg_levelsum	--	--	--	> 10 minutes	no

Analysis

For uninformed searches it appears that breadth first search works best for smaller data sets, however when you look at larger data sets as in the P3 problem it shifts to looking like greedy best first is faster and uses less memory. Just looking at the tables it would appear that depth first search looks to perform the best for small and larger data sets, however I learned from the lectures specifically in Lesson 10 Search the lecture that stated this was 21. Search Comparison 1, that depth first is not an optimal search strategy so I excluded it from my choice of optimal search strategies.

In considering the heuristic search strategies, I would exclude a* search_pg_levelsum as for P2 and P3 it failed to meet the specified criteria of running in less than ten minutes. I am thinking this is most likely because I still have more to learn and my implementation was subpar. With that exclusion you can see from the tables provided that a* search h_ignore_preconditions performed better than a* search h_1. For my implementation of these heuristic searches then I would definitely choose a* search h_ignore_preconditions as the optimal search strategy.

If you were to compare between the two types of searches, uninformed vs heuristic, you can see that breadth first still performs the best for smaller data sets and greedy best first is the best for larger data sets. I would have expected a heuristic search to perform better than an uninformed search strategy, so I again am left to wonder and speculate that it may be a lack of my implementation and could be perfected with more study and time.