

## Homework Assignment #8

Name grading

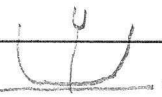
due in class Friday, October 28

**Cover sheet : Staple this page in front of your solutions.**Write the *answers* (without calculations) on this page;write the detailed *solutions* on your own paper.

[37] Problem 4.26.\*

*Answer: What is  $dE/dt$ ?*

$dE/dt = m y dg/dt$


 ← 1 point 1 point

[38] Problem 4.28 and 4.29.\*\*\*[computer]


For #4.29, hand in the computer program and any plots. Check plot. ← 1 pt.*Answer: What is the period for #4.29 part (d)?*

3.708 time units

 ← 2 pt 3 points

[39] Problem 4.33.\*\*[computer]

Hand in the computer program and any plots.

*Answer: Did you hand in the computer results?*Check the plots of  $U(\theta)$  for  $b = 0.9 r$  and  $b = 1.1 r$ .

 ← 2 points 2 points

[40] Problem 4.34.\*\*

*Answer: What is the period if the length is 1 m?*

2.007 seconds

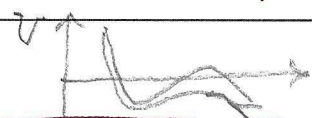
 ← 2 points 2 points

[40x] Problem 4.37.\*\*\*[computer]

Hand in the computer program and any plots.

*Answer: Did you hand in the computer results?* Check the plots of  $U$  vs  $\phi$  .2pt.*Answer: What is the critical ratio  $m/M$ ?* ~~0.7426~~

0.7246

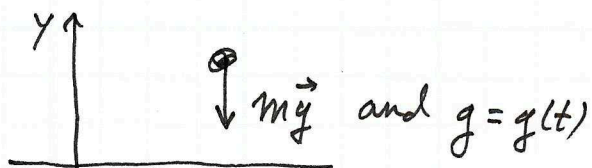

 ← 1 pt 3 points

[40xx] Problem 4.38.\*\*\*[computer]

Hand in the computer program and any plots.

*Answer: Did you hand in the computer results?* Check the plot of  $\tau$  vs  $\phi$  .2pt*Answer: **Explain** what becomes of  $\tau$  as the amplitude of oscillation approaches**The period approaches infinity because  $\phi = \pi$  is a point of (unstable) equilibrium.*
 ← 1 pt 3 points

14 total

[37] Problem 4.26

(A) Let  $V = mgy$ . Then  $-\nabla V = -mg\hat{e}_y = \vec{F}$

(B) Let  $E = \frac{1}{2}mv^2 + mgy$ .

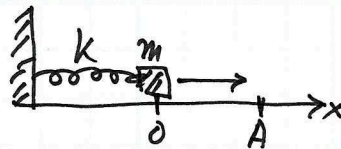
$$\begin{aligned}
 \text{Then } \frac{dE}{dt} &= \frac{1}{2}m 2v \frac{dv}{dt} + m\ddot{y}y + mg \frac{dy}{dt} \\
 &= mv_y \frac{dv_y}{dt} + mg(+v_y) + m\ddot{y}y \\
 &= v_y ( \underbrace{ma_y + mg}_{=0 \text{ by Newton's second law}} ) + m\ddot{y}y \\
 &\quad \text{ } ma_y = F_y = -mg
 \end{aligned}$$

$$\frac{dE}{dt} = m\ddot{y}y$$

So  $E$  is not constant if  $\ddot{y} \neq 0$ .

## [38] Problem 4.28

Mass on a spring. The mass is given a kick at  $t=0$  and then moves out to maximum displacement  $x_{\max} = A$ .



(A) Conservation of energy

$$E = \frac{1}{2} m \dot{x}^2 + \frac{1}{2} k x^2 = \frac{1}{2} k A^2$$

$$\boxed{\omega^2 = \frac{k}{m}}$$

Thus  $\dot{x} = \pm \sqrt{\omega^2 (A^2 - x^2)}$

(B) As  $m$  moves from 0 to  $A$ , the time integral is

$$t = \int_0^x \frac{dx'}{\dot{x}'} = \int_0^x \frac{dx'}{\sqrt{\omega^2 (A^2 - x'^2)}}$$

$$= \frac{1}{\omega} \arcsin\left(\frac{x}{A}\right)$$

(C) Thus  $x(t) = A \sin \omega t \leftarrow$  simple harmonic motion

with period  $T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{m}{k}}$

Problem 4.29 Mass in the potential  $U(x) = Kx^4$ .

(A) Plot  $U$  versus  $x$ . ← Mathematica output

(B) The mass is given a kick, and then oscillates between  $x_{\max} = +A$  and  $x_{\min} = -A$ ; by conservation of energy,

$$\frac{1}{2} m \dot{x}^2 + Kx^4 = KA^4 \Rightarrow \dot{x} = \pm \sqrt{\frac{2K}{m} (A^4 - x^4)}$$

Time  $t = \int_0^x \frac{dx'}{\dot{x}'} = \sqrt{\frac{m}{2K}} \int_0^x \frac{dx'}{\sqrt{A^4 - x'^4}}$

The period of oscillation is  ~~$\tau$~~   $\tau$  when  $\tau/4$  = the time to go from 0 to A.

$$\tau = 4 \int_0^A \sqrt{\frac{m}{2k}} \frac{dx'}{\sqrt{A^4 - x'^4}} = \sqrt{\frac{8m}{k}} \int_0^A \frac{dx}{\sqrt{A^4 - x^4}}$$

(C) Change the variable of integration to

$$u = x/A \Rightarrow$$

$$\tau = \sqrt{\frac{8m}{k}} \frac{1}{A} \int_0^1 \frac{du}{\sqrt{1-u^4}} = \frac{C}{A} \quad \begin{array}{l} \text{is proportional} \\ \text{to } 1/A \end{array}$$

(D) Calculate C using Mathematica.

← Mathematica  
output

$$\int_0^1 \frac{du}{\sqrt{1-u^4}} = 1.311; \quad \text{for } m=1, k=1, A=1, \quad C = 3.708.$$



[39] Problem 4.33

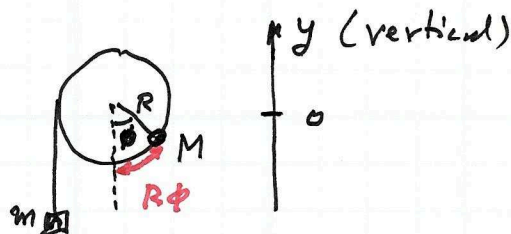
(A) Equation (4.59) was derived in class.

$$U(\theta) = mg \{ (r+b) \cos(\theta) + r\theta \sin(\theta) \}$$

(B) Plot  $U$  for  $b = 0.9r$  and  $1.1r$ . ← Mathematica output

(C) Interpretation:

- For  $b = 0.9r$ , the configuration  $\theta = 0$  is a stable equilibrium; also there are two unstable equilibrium points at  $\theta = \pm 0.54$ .
- For  $b = 1.1r$ , the only equilibrium point is  $\theta = 0$ , and it is unstable.

[40x] Problem 4.37

(A) The potential energy

$$U = Mg y_M + mg y_m \quad \text{where} \quad \begin{cases} y_M = -R \cos \phi \\ y_m = -R - R \phi \end{cases}$$

$$U(\phi) = -MgR \cos \phi - mgR - mgR \phi$$

*the answer on page 756 has a different constant.*

(B) Equilibrium positions occur where  $\frac{dU}{d\phi} = 0$ .

$$\frac{dU}{d\phi} = MgR \sin \phi - mgR = 0$$

$$\therefore \sin \phi = m/M$$

$$\sin \phi = m/M$$

- If  $m > M$  then there is no equilibrium position.
- If  $m = M$  then there is equilibrium at  $\phi = \pi/2$
- If  $m < M$  then there are two equilibrium points, at  $\phi = \pi/2 \pm \alpha$  where  $\cos \alpha = m/M$ ;  
 $\phi = \pi/2 + \alpha$  is unstable and  $\phi = \pi/2 - \alpha$  is stable.

(C) Plot  $U(\phi)$  for  $m = 0.7M$  and  $m = 0.8M$ .

Mathematica output

If the masses are released from rest at  $\phi = 0$  :  
 then for  $m = 0.7M$  they undergo oscillations;  
 and for  $m = 0.8M$  they will not oscillate, and  
 $m$  will fall until it hits the floor.

(D) The critical value of  $m/M$  is the value  
 such that the equilibrium point at  $\phi = \pi/2 + \alpha$   
 occurs with  $U(\phi) = -1$ .

$$\begin{aligned} \text{T.e. solve } U(\phi) &= MgR \sin \alpha - mgR - mgR \left( \frac{\pi}{2} + \alpha \right) \\ &= MgR \sin \alpha - mgR \left( 1 + \frac{\pi}{2} + \alpha \right) \\ &= -1 \quad \text{and } \cos \alpha = m/M. \end{aligned}$$

Use Mathematica  $\Rightarrow \frac{m}{M} = 0.7246$  Mathematica output

## [40] Problem 4.34 (The simple pendulum)

(A) The potential energy  $U(\phi)$  is

$$U(\phi) = mgy = mgl(1 - \cos\phi)$$

The energy is

$$E = \frac{1}{2}mv^2 + U = \frac{1}{2}m\dot{\phi}^2 + mgl(1 - \cos\phi)$$

(B) The energy is constant, so  $dE/dt = 0$ ;

$$m\dot{\phi}^2 + mgl\sin\phi \dot{\phi} = 0$$

Thus  $\ddot{\phi} = -\frac{g}{l}\sin\phi$

This is the same as  $I\alpha = \Gamma$  (torque about the suspension pt.)

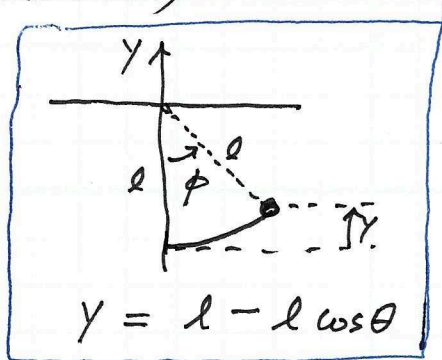
because  $I = ml^2$ ,  $\alpha = \ddot{\phi}$ , and  $\Gamma = -lmg\sin\phi$

(C) For small  $\phi$ , approximate  $\sin\phi \approx \phi$

Then  $\ddot{\phi} = -\frac{g}{l}\phi = -\omega^2\phi$  where  $\omega = \sqrt{\frac{g}{l}}$

Small oscillations are harmonic, with

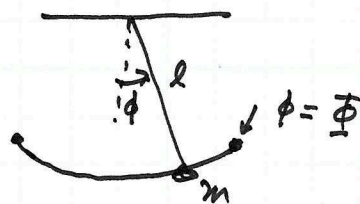
period  $= \tau = \frac{2\pi}{\omega} = 2\pi\sqrt{\frac{l}{g}}$ .





## [40xx] Problem 4.38 (Simple Pendulum)

↳ not limited to small angles

(A) Let  $\Phi$  = amplitude of oscillation.Calculate  $\tau$  = period of oscillation.

By conservation of energy,

$$\frac{1}{2} m l^2 \dot{\phi}^2 + mgl(1 - \cos \phi) = mgl(1 - \cos \Phi)$$

$$\dot{\phi}^2 = \frac{2g}{l} (\cos \phi - \cos \Phi)$$

The time calculation

$$dt = \frac{d\phi}{\dot{\phi}} \Rightarrow t = \int_0^{\Phi} \frac{d\phi'}{\pm \sqrt{\frac{2g}{l} (\cos \phi' - \cos \Phi)}}$$

Consider one quarter cycle, as  $\phi$  goes from 0 to  $\Phi$ .

$$\frac{\tau}{4} = \sqrt{\frac{l}{2g}} \int_0^{\Phi} \frac{d\phi'}{\sqrt{\cos \phi' - \cos \Phi}} = \sqrt{\frac{l}{4g}} \int_0^{\Phi} \frac{d\phi'}{\sqrt{\sin^2 \Phi/2 - \sin^2 \phi'/2}}$$

$$(\text{note: } \cos \phi = \cos^2 \frac{\phi}{2} - \sin^2 \frac{\phi}{2} = 1 - 2\sin^2 \frac{\phi}{2})$$

Also,  $\sqrt{\frac{l}{4g}} = \frac{1}{2} \frac{\tau_0}{2\pi} = \frac{\tau_0}{4\pi}$  where  $\tau_0$  = the period of small oscillations =  $2\pi \sqrt{\frac{l}{g}}$

$$\tau = \frac{\tau_0}{\pi} \int_0^{\Phi} \frac{d\phi'}{\sqrt{\sin^2 \Phi/2 - \sin^2 \phi'/2}}$$

Change the variable of integration. Let  $u = \frac{\sin \phi'/2}{\sin \Phi/2}$ 

$$du = \frac{1}{2} \frac{\cos \phi'/2}{\sin \Phi/2} d\phi' = \frac{1}{2\alpha} \sqrt{1 - \sin^2 \phi'/2} d\phi' = \frac{1}{2\alpha} \sqrt{1 - \alpha^2 u^2} d\phi' \quad \alpha = \sin \frac{\Phi}{2}$$

$$\text{denominator} = \sqrt{\alpha^2 - \alpha^2 u^2} = \alpha \sqrt{1 - u^2}$$

$$\therefore \tau = \frac{\tau_0}{\pi} \int_0^1 \frac{2\alpha du}{\sqrt{1 - \alpha^2 u^2}} \frac{1}{\alpha \sqrt{1 - u^2}} = \frac{2\tau_0}{\pi} \int_0^1 \frac{du}{\sqrt{1 - u^2} \sqrt{1 - \alpha^2 u^2}} \quad (4.103)$$

$$= K(\alpha^2)$$



(c) Use Mathematica to get  $K(Q^2)$

where  $Q = \sin \Phi/2$ .

Plot  $\sigma/\sigma_0 = \frac{2}{\pi} K(\sin^2 \frac{\Phi}{2})$  versus  $\Phi$ .

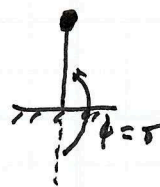
Mathematica  
output

The limit of  $\sigma/\sigma_0$  as  $\Phi$  approaches  $\pi$  is  $\infty$ ,

because  $\Phi = \pi$  is an equilibrium point,

(The inverted pendulum)

although unstable.

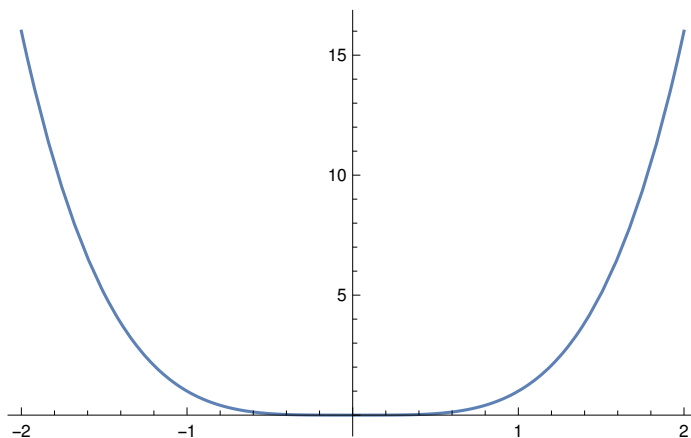


## Problem 4.29

Mass in the potential  $U(x) = k x^4$ .

■ (a)

```
Plot[x^4, {x, -2, 2}]
```



If the mass starts at  $x = 0$  and is given a kick toward positive  $x$ , it will oscillate between  $x_{\max} = +A$  and  $x_{\min} = -A$ .

■ (d) Use *Mathematica* to calculate the integral

```
theintegral = NIntegrate[1 / Sqrt[1 - u^4], {u, 0, 1}]
```

```
SetPrecision[theintegral, 10]
```

```
theperiod = Sqrt[8 * m / k] * theintegral / A
```

```
theperiod /. {m -> 1, k -> 1, A -> 1}
```

```
1.31103
```

```
1.311028777
```

```
3.70815  $\sqrt{\frac{m}{k}}$ 
```

```
A
```

```
3.70815
```

## Problem 4.33

- (a) Eq 4.59 was derived in class

$$U(\theta) = mg \left\{ (r + b) \cos[\theta] + r \theta \sin[\theta] \right\}$$

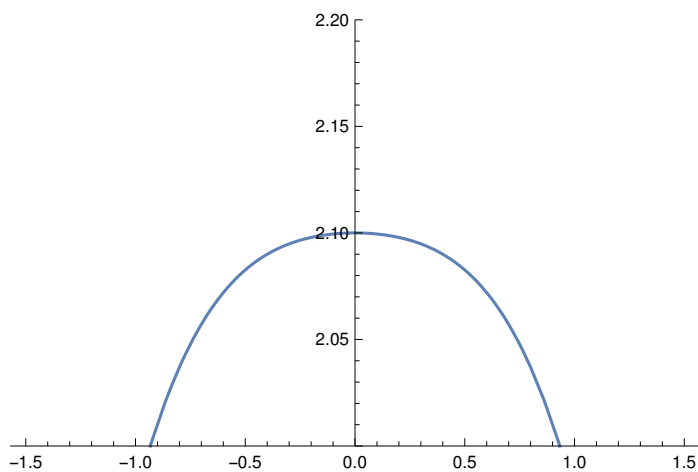
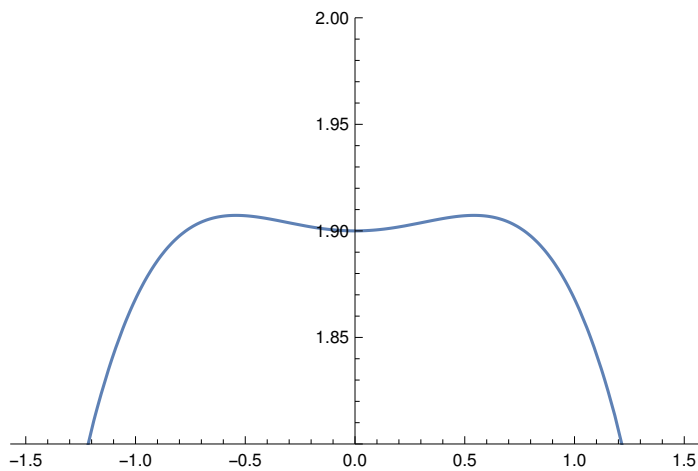
## ■ (b) Plot U for $b = 0.9 r$ and $1.1 r$

```

{r, m, g} = {1, 1, 1}
U[θ_] := m * g * ((r + b) * Cos[θ] + r * θ * Sin[θ])
p1 = Plot[
  U[θ] /. b → 0.9 r,
  {θ, -Pi/2, Pi/2}, PlotRange → {{-Pi/2, Pi/2}, {1.8, 2.0}}]
p2 = Plot[
  U[θ] /. b → 1.1 r,
  {θ, -Pi/2, Pi/2}, PlotRange → {{-Pi/2, Pi/2}, {2.0, 2.2}}]

```

```
{1, 1, 1}
```



## ■ (c) Interpretations

For  $b = 0.9 r$  :

the configuration  $\theta = 0$  is a stable equilibrium;



also there are two unstable equilibrium points  
at  $\theta = +0.54$  and  $-0.54$

For  $b = 1.1 r$  :

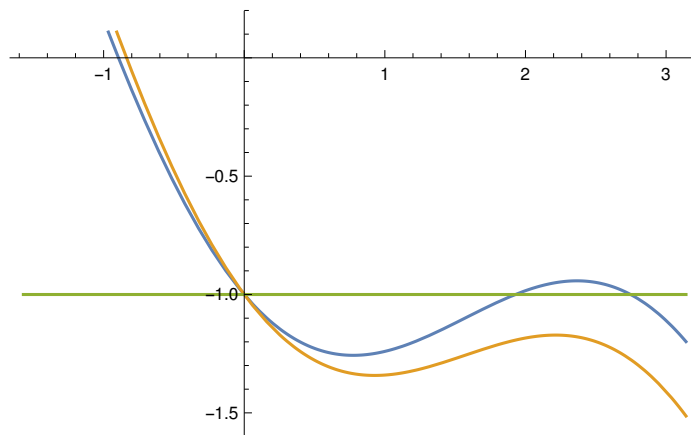
the only equilibrium point is  $\theta = 0$ , and it is unstable.

## Problem 4.37

- (c) Plot  $U(\phi)$  for  $m = 0.7 M$  and  $m = 0.8 M$ .  
Assume the masses are released from rest at  $\phi = 0$ ;  
i.e., the energy is  $U(0)$ .

```
Remove["Global`*"]
{M, g, R} = {1, 1, 1}
U[phi_] := -M * g * R * Cos[phi] - m * g * R * phi
Plot[
  {U[phi] /. m -> 0.7 M, U[phi] /. m -> 0.8 M, U[0]},
  {phi, -Pi/2, Pi}]
```

```
{1, 1, 1}
```



Interpretations:

The case  $m = 0.7 M$  (blue curve) will undergo oscillations  
between  $\phi = 0$  and  $\phi = 1.8$ .

The case  $m = 0.8 M$  (orange curve) will run away as  $m$  falls down until it hits the ground.

- (d) The critical value of  $m/M$  is the value such that the equilibrium point at  $\phi = \pi/2 + \alpha$  occurs with  $U[\phi] = -1.0$ .

```

 $\phi_{eq} = \text{Pi} / 2 + \text{ArcCos}[m / M]$ 
val[ratio_] := U[ $\phi_{eq}$ ] /. m / M → ratio
FindRoot[val[r] == -1.0, {r, 0.7}]
 $\frac{\pi}{2} + \text{ArcCos}[m]$ 
{r → 0.724611}

```

Critical ratio is  $m/M = 0.7246$  .

## Problem 4.38 : the simple pendulum

The period is given by Equation 4.103:

$$\tau = \tau_0 \frac{2}{\pi} \int_0^1 \frac{du}{\sqrt{1-u^2} \sqrt{1-A^2 u^2}}$$

where  $\tau_0 = 2\pi \sqrt{l/g}$  and  $A = \text{Sin}[\Phi/2]$

The integral is the complete elliptic integral of the first kind,  $K(A^2)$ .

■ (b) Plot  $\tau/\tau_0$  for amplitudes  $0 \leq \Phi \leq 3$ .

```
 $\tau_{\text{ratio}}[\Phi_] := 2/\text{Pi} * \text{EllipticK}[(\text{Sin}[\Phi/2])^2]$ 
Plot[\math{\tau_{\text{ratio}}[\Phi]}, {\Phi, 0, 3},
PlotRange -> {{0, Pi}, {0.5, 3}}]
```

