



Figure 2. Screenshot from skiing game.

together with Kinect studio and a developer toolkit. Kinect studio is just for testing and the developer toolkit is a package of code examples.

For the displaying of the virtual skiing world, it took us almost no time to search for game engine, one of the team member knows how to use Unity 3D, certainly this becomes your choice of game engine.

3.3. Divide the work

The work of the project can be divided into two main parts, the input(Kinect) and output(the display). Chin Chung will work on Kinect, figure out how it works; Tomaz will work on the game engine, create a virtual 3D world for the user to ski on.

3.4. Unity

Unity is a development engine for the creation of 2D and 3D games and interactive content. It has multiplatform support and own asset store where you can download scripts, objects, scenes.. [2] We found kinect wrapper package[3] for Unity3D engine, which added us easy option to get collected data from kinect directly to our script code in unity. We used this data to calculate angle between different joints. With this angle we are then able to set intensity of turning sensitivity. To gamify our environment we put score counter in top left corner, which get increased by colliding character with advertised flags on the way down. To allow kinect detecting the human body and give user time to prepare we put countdown at the beginning of game.

Terrain. It has great support for creating terrain. In game we created simple terrain with mountains and put snow on it. For more flexible terrain we could create script or just few images of pre-defined heightmaps. Unity have option to generate terrain using heightmap.

Scripting. Unity support C#, javascript and Boo scripting languages. It also supports applying different language script on same object. We used such ability

for user movement in skiing game, using javascript and C# languages only.

3.5. Kinect

The first attempt to work on Kinect was a failure, not until I start working on it, I didn't notice the underlying problems. I did get the skeleton of the user, retrieving some data from it, but they are not very useful. I faced three main problems in this part.

C#. I did learn several languages before, but not C#. When I read the code, I understand them in a very low level, I recognize almost all the syntax, the loops, conditionals, declarations... etc. It took me really a lot of time to get to a higher level of understanding. The documentations from Microsoft was not very useful, it maybe enough for an experienced C# programmer, not for me.

Mathematics. After a lot of reading, I finally locate the part where the orientation of the nodes/joints are stored. The orientations of the nodes are expressed in rotation quaternions, an absolutely alien term for me. I checked the documentation, wikipedia and other sites, they all explain it is a very mathematical way. The main direction I studied is software engineering, the mathematics they are using are far beyond my level. I just leave the output in the form of rotation quaternion.

Developing environment. I used the Microsoft visual studio in the part, mainly because most tutorials on Kinect are also on this environment. Problem comes when my part needs to merge with the game engine, I have no idea how to do it. Just importing the scripts in visual studio was not enough, the scripts will not run automatically. Scripts need to link to game objects in order to get running. Also the displaying mechanism is very different in Visual Studio and Unity 3D, I don't know how to translate the code.

3.6. Rework

A replan is needed because the Kinect part and the Unity 3D part of the project was not mergeable. Another research is done to find Kinect code example directly in Unity 3D, not in Visual Studio.

Kinect in Unity 3D. Code example was found in Unity 3D wiki, this time the whole Kinect part is coded only in the game engine. Work done in Visual Studio is repeated in Unity 3D, it was a lot smoother than before because of the experience gained. Instead of the rotational quaternion, a simular axis system is used to compare the postions of the Joints.

C# and Javascript. The code is until not fully compatable, the graphics part uses Javascript and the Kinect part uses C#. A way to transfer data between

scripts in two languages is found, and the problem is fully solved.

4. Conclusions

We were able to make game playable by setting correct parameters such as speed, turning speed, gliding and gravity acceleration. Project has been successfully finished and requirements has been fullfilled.

References

- [1] SOLINA FRANC and BATAGELJ BORUT (2005) <http://black.fri.uni-lj.si/ski/>
- [2] UNITY 3D (2014) <http://docs.unity3d.com/ScriptReference/index.html>
- [3] MICROSOFT SDK http://wiki.etc.cmu.edu/unity3d/index.php/Microsoft_Kinect_-_Microsoft_SDK