

Danny Stein
HW 5

i) Let N be Brownian Motion. Define X by $dX_t = K(\theta - X_t)dt + \sigma dW_t$ where K, θ, σ , and X_0 are constants.

a) Write $e^{Kt}X_t$ as the sum of a constant, a time integral, and an Itô integral w.r.t to Brownian motion, such that both integrands may depend on t but not on X .

$$J(e^{Kt}X_t) = e^{Kt}X_t dt + e^{Kt}(dN_t) + \frac{1}{2}K^2e^{2Kt}(dt)^2 + (\theta - X_t)^2$$

$$\partial(e^{Kt}X_t) = Ke^{Kt}X_t dt + e^{Kt}X_t(K(\theta - X_t) + \sigma dW_t)$$

$$(de^{Kt}X_t) = K\theta e^{Kt} dt + \sigma e^{Kt} dW_t$$

$$\int_0^t e^{Ks} dW_s = \int_0^t K\theta e^{Ks} ds + \int_0^t \sigma e^{Ks} dW_s$$

$$X_T = X_t e^{-K(T-t)} + \theta \left[1 - e^{-K(T-t)} \right] + \int_t^T \sigma e^{-K(T-s)} dW_s$$

b) $E[X_T | X_t = x] = x e^{-k(T-t)} + o(1 - e^{-k(T-t)})$

$$Var(X_T | X_t = x) = E\left[\left(\int_x^T ve^{-k(t-s)} dW_s\right)^2\right] =$$

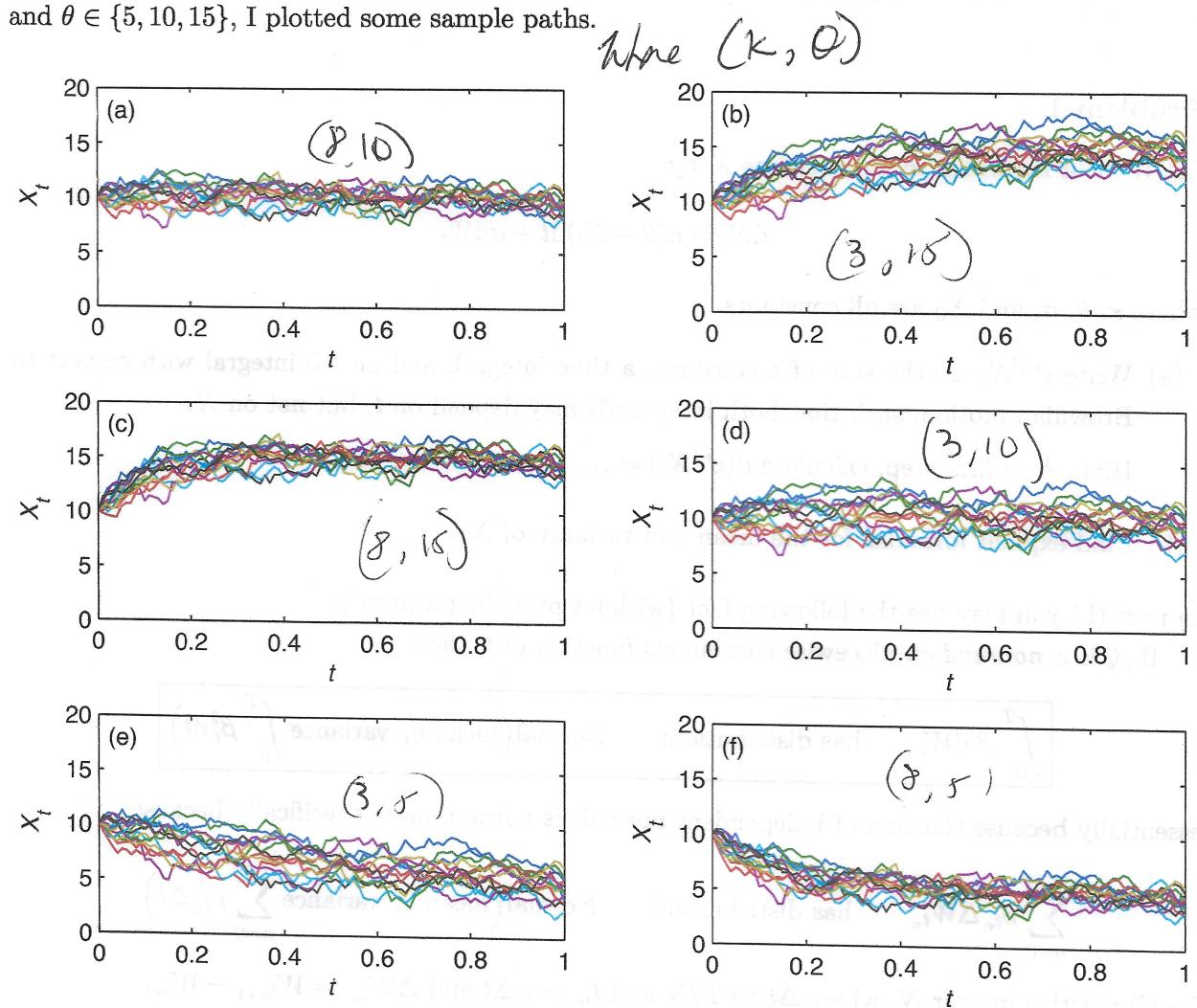
$$= \frac{\sigma^2}{2k} \left(1 - e^{-2k(T-t)}\right)$$

Problem 2

Here are 6 examples of the dynamics in Problem 1. All have the form

$$dX_t = \kappa(\theta - X_t)dt + \sigma dW_t$$

where $\sigma = 4$ and $X_0 = 10$ in all cases. For each of the $2 \times 3 = 6$ combinations of choices $\kappa \in \{3, 8\}$ and $\theta \in \{5, 10, 15\}$, I plotted some sample paths.



For each process (a,b,c,d,e,f), state the κ and the θ that I used to generate that process.
No justification necessary.

Hint: In each case the process is *mean-reverting*. Intuitively, θ is the mean reversion “level” or the “long-term mean”; and κ is the mean reversion “rate” or “speed”