## **Mohr's Circle**

Input stress tensor (generalized plane stress)

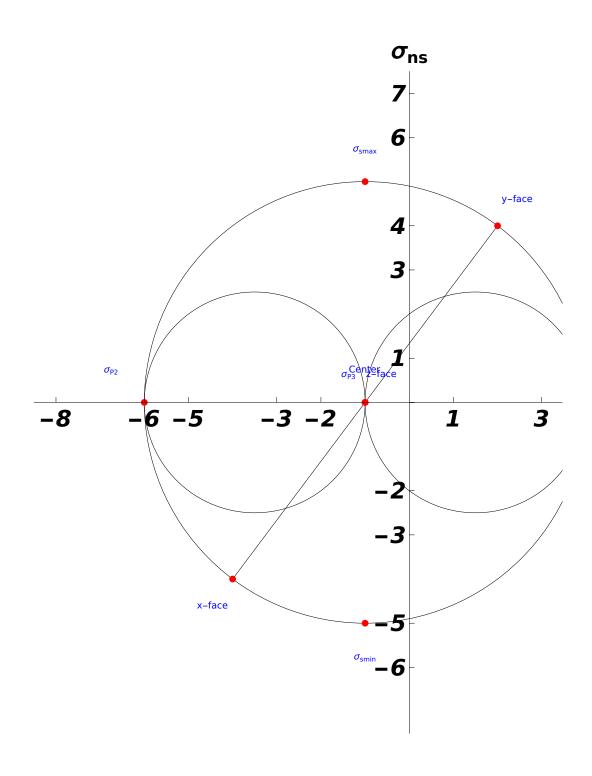
```
ClearAll["Global`*"]
sigma = \{\{7, 4, 0\}, \{4, 2, 0\}, \{0, 0, -1\}\};
sigma = \{\{-4, 4, 0\}, \{4, 2, 0\}, \{0, 0, -1\}\};
*sigma = \{\{4,5,0\},\{5,-3,0\},\{0,0,8\}\};
sigma={{-40,0,0},{0,-10,30},{0,30,-20}};
sigma={{-40,0,30},{0,-10,0},{30,0,-20}};
sigma=N[{{-40,0,30},{0,-10,0},{30,0,-20}}];
sigma={{4,5,0},{5,-3,0},{0,0,8}};
sigma=N[{{-40,0,30},{0,-10,0},{30,0,-20}}];
sigma=N[{{-4,0,6},{0,12,0},{6,0,8}}];
(*sigma=N[{{4,5,0},{5,-2,0},{0,0,8}}];*)
(*sigma=N[{{9,6,0},{6,-7,0},{0,0,-13}}];*)*)
If[sigma[[1, 2]] # 0, plane = "xy"];
If[sigma[[1, 3]] # 0, plane = "xz"];
If[sigma[[2, 3]] # 0, plane = "yz"];
If[plane == "xy", {givenpoints = {{sigma[[1, 1]], -sigma[[1, 2]]}},
      sigma[[2, 2]], sigma[[1, 2]], sigma[[3, 3]], 0}, center = (sigma[[1, 1]] + sigma[[2, 2]])/2,
    radius = Sqrt[((sigma[[1, 1]] - sigma[[2, 2]]) / 2) ^ 2 + sigma[[1, 2]] ^ 2]}];
If[plane == "xz", {givenpoints = {{sigma[[1, 1]], sigma[[1, 3]]}, {sigma[[2, 2]], 0},
      sigma[[3, 3]], -sigma[[1, 3]], center = sigma[[1, 1]] + sigma[[3, 3]]/2,
    radius = Sqrt[((sigma[[1, 1]] - sigma[[3, 3]]) / 2) ^ 2 + sigma[[1, 3]] ^ 2]}];
If[plane == "yz", {givenpoints = {{sigma[[1, 1]], 0}, {sigma[[2, 2]], -sigma[[2, 3]]},
      {sigma[[3, 3]], sigma[[2, 3]]}}, center = (sigma[[2, 2]] + sigma[[3, 3]]) / 2,
    radius = Sqrt[((sigma[[2, 2]] - sigma[[3, 3]])/2)^2 + sigma[[2, 3]]^2]]];
If[plane == "xy",
  {sigmaP1 = center + radius,
    sigmaP2 = center - radius,
    sigmaP3 = sigma[[3, 3]]}];
If[plane == "xz",
  {sigmaP1 = center + radius,
    sigmaP2 = sigma[[2, 2]],
    sigmaP3 = center - radius}];
If[plane == "yz",
  {sigmaP1 = sigma[[1, 1]],
    sigmaP2 = center + radius,
    sigmaP3 = center - radius}];
```

```
displaycenter = {(Min[sigmaP1, sigmaP2, sigmaP3] + Max[sigmaP1, sigmaP2, sigmaP3])/2, 0};
displaydim =
  1.5 * .5 * {Max[sigmaP1, sigmaP2, sigmaP3] - Min[sigmaP1, sigmaP2, sigmaP3], 2 * radius};
displayrange = {{displaycenter [[1]] - displaydim [[1]], displaycenter [[1]] + displaydim [[1]]},
   {displaycenter [[2]] - displaydim [[2]], displaycenter [[2]] + displaydim [[2]]}};
displayelement = .1 * ((displaydim [[1]] + displaydim [[2]]) / 2);
numticks = 10;
tickspacingx = Abs[displayrange [[1, 2]] - displayrange [[1, 1]]]/numticks;
tickspacingy = Abs[displayrange [[2, 2]] - displayrange [[2, 1]]]/numticks;
If[plane == "xy",
  circledata = {{center, 0, radius}, {(sigmaP2 + sigmaP3)/2, 0, Abs[sigmaP2 - sigmaP3]/2},
     {(sigmaP1 + sigmaP3)/2, 0, Abs[sigmaP1 - sigmaP3]/2}}];
If[plane == "xz",
  circledata = {{center, 0, radius}, {(sigmaP1 + sigmaP2)/2, 0, Abs[sigmaP1 - sigmaP2]/2},
     {(sigmaP2 + sigmaP3)/2, 0, Abs[sigmaP2 - sigmaP3]/2}}];
If[plane == "yz",
  circledata = {{center, 0, radius}, {(sigmaP1 + sigmaP2)/2, 0, Abs[sigmaP1 - sigmaP2]/2},
     {(sigmaP1 + sigmaP3)/2, 0, Abs[sigmaP1 - sigmaP3]/2}}];
largestcircle = 1;
rowmax = Dimensions[circledata, 1];
For[row = 1, row ≤ rowmax[[1]], row++,
  If[circledata[[row, 3]] > circledata[[largestcircle , 3]], largestcircle = row]
 }
]
circle1 := Graphics [{Circle [{circledata [[1, 1]], circledata [[1, 2]]}, circledata [[1, 3]]],
     Circle[{circledata[[2, 1]], circledata[[2, 2]]}, circledata[[2, 3]]],
     Circle[{circledata[[3, 1]], circledata[[3, 2]]}, circledata[[3, 3]]]},
    Axes → True,
   AxesLabel \rightarrow {Subscript[\sigma, nn], Subscript[\sigma, ns]},
    LabelStyle → Directive[Large, Bold],
   Ticks \rightarrow { Floor[Table[tickspacingx * Floor[.5 * n] * (-1) ^ Floor[1.5 * n],
         \{n, 0, Ceiling[(2 * Max[Abs[displayrange[[1]]]] + 1)/tickspacingx]\}]],
      Floor[Table[tickspacingy * Floor[.5 * n] * (-1) ^ Floor[1.5 * n],
         {n, 0, Ceiling[(2 * Max[Abs[displayrange [[2]]]] + 1) / tickspacingy ]}]]},
   TicksStyle → Directive[Small, Italic],
   PlotRange → displayrange,
    AspectRatio → 1];
```

```
If[plane == "xy",
  line1 := Graphics[Line[{givenpoints[[1]], givenpoints[[2]]}]]];
If[plane == "xz",
  line1 := Graphics [Line[{givenpoints [[1]], givenpoints [[3]]}]]];
If[plane == "yz",
  line1 := Graphics[Line[{givenpoints[[2]], givenpoints[[3]]}]]];
pointsdata = { givenpoints [[1]], givenpoints [[2]],
    givenpoints[[3]], {center, 0}, {sigmaP1, 0}, {sigmaP2, 0}, {sigmaP3, 0},
   {circledata[[largestcircle, 1]], circledata[[largestcircle, 3]]},
   {circledata[[largestcircle , 1]], -circledata[[largestcircle , 3]]}};
points1 := Graphics[
   {PointSize[Large], Red, Point[pointsdata]}
  ];
r1 = N[ pointsdata - ConstantArray [displaycenter , Dimensions [pointsdata , 1]] ];
dim = Dimensions[r1, 1];
r1norm = N[Table[{Norm[r1[[i]]], Norm[ r1[[i]]]}, {i, dim[[1]]}]];
r2 = ConstantArray [{0, 0}, dim[[1]]];
For[row = 1, row \leq dim[[1]], row++,
 If[ r1norm[[row, 1]] # 0, r2[[row]] = displayelement * r1[[row]] / r1norm[[row]] ]
]
annotationdata = ConstantArray [displaycenter, Dimensions [pointsdata, 1]] + r1 + r2;
dim = Dimensions[annotationdata, 1];
For[row = 1, row \leq dim[[1]], row++, {
    If[Abs[annotationdata [[row, 1]]] < displayelement ,</pre>
     { annotationdata [[row, 1]] =
       displayelement *(2*Ceiling[(Sign[annotationdata[[row, 1]]]+1)/2]-1),
      r2[[row]] = annotationdata [[row]] - pointsdata [[row]] }
   ],
   If[Abs[annotationdata [[row, 2]]] < displayelement ,</pre>
     { annotationdata [[row, 2]] =
       displayelement *(2 * Ceiling[(Sign[annotationdata[[row, 2]]] + 1)/2] - 1),
      r2[[row]] = annotationdata [[row]] - pointsdata [[row]] }
   ]
  }];
duplicates = {};
```

```
temparray = annotationdata;
dim = Dimensions [temparray , 1];
For[row1 = 1, row1 \leq dim[[1]] - 1, row1 ++,
 \{temp = \{row1\},\
  For[row2 = row1 + 1, row2 \leq dim[[1]], row2 ++,
    If[EuclideanDistance [temparray[[row2]], temparray[[row1]]]≤ displayelement &&
      temparray[[row2]] ≠ {},
     {temp = Append[temp, row2], temparray[[row2]] = {}}
   1
  ],
  If[Length[temp] > 1, duplicates = Append[duplicates, temp]]}
]
rmatrix[theta_] = {{Cos[theta], Sin[theta]}, {-Sin[theta], Cos[theta]}};
dim = Dimensions[duplicates, 1];
For[row = 1, row \leq dim[[1]], row ++,
 {numcollisions = Length[duplicates[[row]]],
  If[numcollisions > 1,
   {spread =
      (Pi/6)*(Range[0, numcollisions -1]-N[Median[Range[0, numcollisions -1]]]),
     For[col = 1, col ≤ Length[duplicates[[row]]], col++,
      r2[[ duplicates [[row, col]] ]] = r2[[ duplicates [[row, col]] ]].rmatrix[ spread[[col]] ]
    ]}
  ]}
]
annotationdata = ConstantArray [displaycenter , Dimensions [pointsdata , 1]] + r1 + r2;
annotation1 := Graphics[Text[Style["x-face", Larger, Blue], annotationdata[[1]]]];
annotation2 := Graphics[Text[Style["y-face", Larger, Blue], annotationdata [[2]]]];
annotation3 := Graphics[Text[Style["z-face", Larger, Blue], annotationdata[[3]]]];
annotation4 := Graphics[Text[Style["Center", Larger, Blue], annotationdata [[4]]]];
annotation5 :=
  Graphics[Text[Style[Subscript[\u00f3, P1], Larger, Blue], annotationdata[[5]]]];
annotation6 := Graphics[Text[Style[Subscript[\sigma, P2], Larger, Blue],
     annotationdata [[6]]];
annotation7 := Graphics[Text[Style[Subscript[\sigma, P3], Larger, Blue],
     annotationdata [[7]]]];
annotation8 := Graphics[Text[Style[Subscript[σ, smax], Larger, Blue],
     annotationdata [[8]]];
annotation9 := Graphics[Text[Style[Subscript[σ, smin], Larger, Blue],
     annotationdata [[9]]];
```

```
f1[x] = .466 * x - 7;
f2[x_] = -.466 * x + 7;
region1 := Plot[{f1[x], f2[x]}, {x, displayrange [[1, 1]], displayrange [[1, 2]]};
Show[circle1, line1, points1, annotation1, annotation2, annotation3,
 annotation4 , annotation5 , annotation6 , annotation7 , annotation8 , annotation9]
\{\{\{"\sigma = ", N[sigma] // MatrixForm\}\} // MatrixForm,
 {{"x-face", pointsdata[[1]]},
    {"y-face", pointsdata[[2]]},
    {"z-face", pointsdata[[3]]},
    {"Center", pointsdata[[4]]},
    {Subscript[\sigma, P1], pointsdata[[5]]},
    {Subscript [\sigma, P2], pointsdata [[6]]},
    {Subscript [\sigma, P3], pointsdata [[7]]},
    {Subscript [\sigma, smax], pointsdata [[8]]},
    {Subscript [\sigma, smin], pointsdata [[9]]}
  } // MatrixForm , N[{{"x-face", pointsdata[[1]]},
     {"y-face", pointsdata[[2]]},
     {"z-face", pointsdata[[3]]},
     {"Center", pointsdata[[4]]},
     {Subscript [\sigma, P1], pointsdata [[5]]},
     {Subscript [\sigma, P2], pointsdata [[6]]},
     {Subscript[\sigma, P3], pointsdata[[7]]},
     {Subscript[\sigma, smax], pointsdata[[8]]},
     {Subscript [\sigma, smin], pointsdata [[9]]}
    }] // MatrixForm }
```



$$\left\{ \left( \sigma = \begin{pmatrix} -4. & 4. & 0. \\ 4. & 2. & 0. \\ 0. & 0. & -1. \end{pmatrix} \right), \begin{pmatrix} x-face & \{-4, -4\} \\ y-face & \{2, 4\} \\ z-face & \{-1, 0\} \\ Center & \{-1, 0\} \\ \sigma_{P1} & \{4, 0\} \\ \sigma_{P2} & \{-6, 0\} \\ \sigma_{P3} & \{-1, 0\} \\ \sigma_{Smin} & \{-1, -5\} \end{pmatrix}, \begin{pmatrix} x-face & \{-4., -4.\} \\ y-face & \{2., 4.\} \\ z-face & \{-1., 0.\} \\ Center & \{-1., 0.\} \\ \sigma_{P1} & \{4., 0.\} \\ \sigma_{P2} & \{-6., 0.\} \\ \sigma_{P3} & \{-1., 0.\} \\ \sigma_{Smin} & \{-1., 5.\} \end{pmatrix}$$