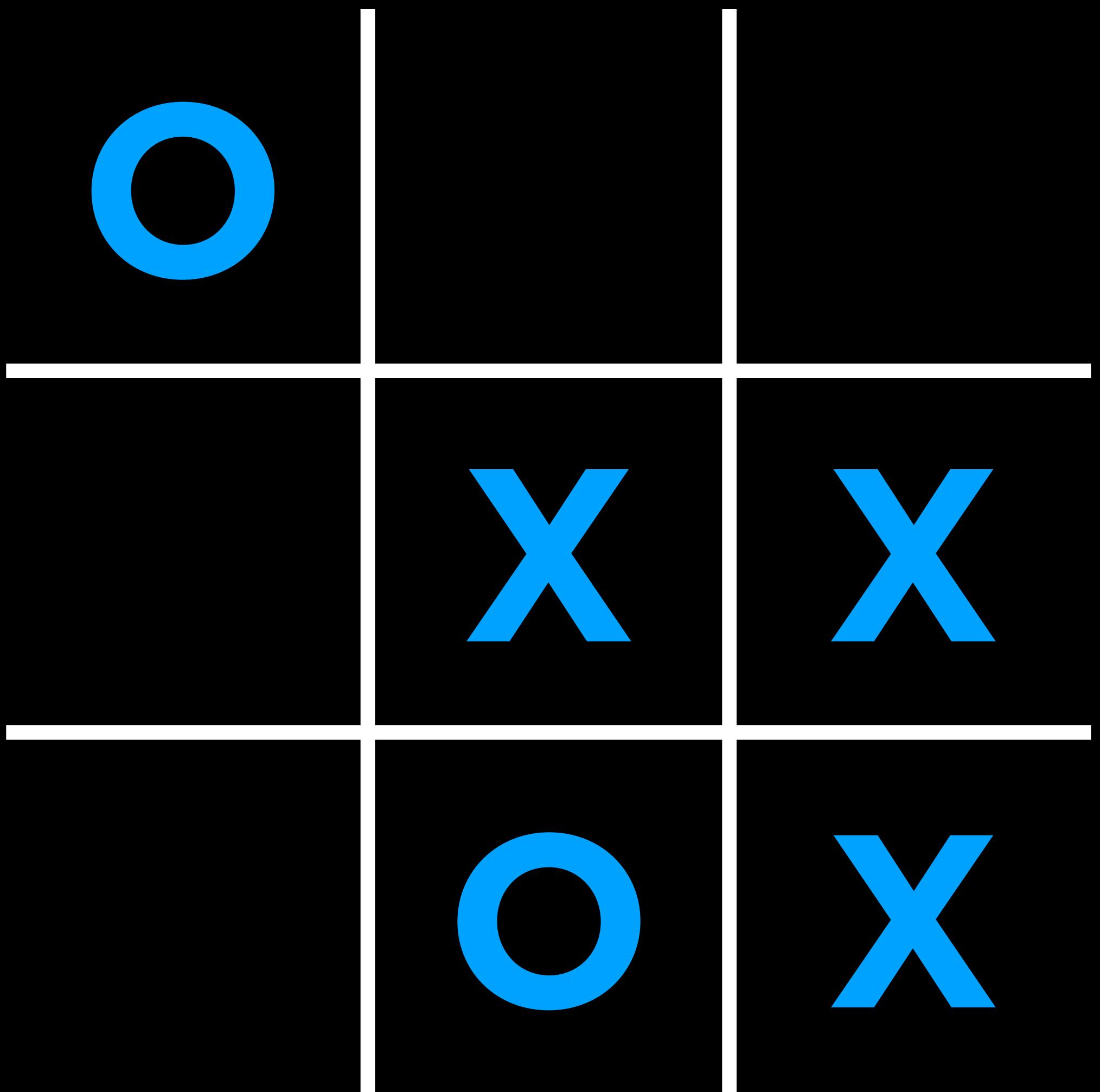


Introduction to  
**Artificial Intelligence**  
with Python

# Artificial Intelligence

# Search

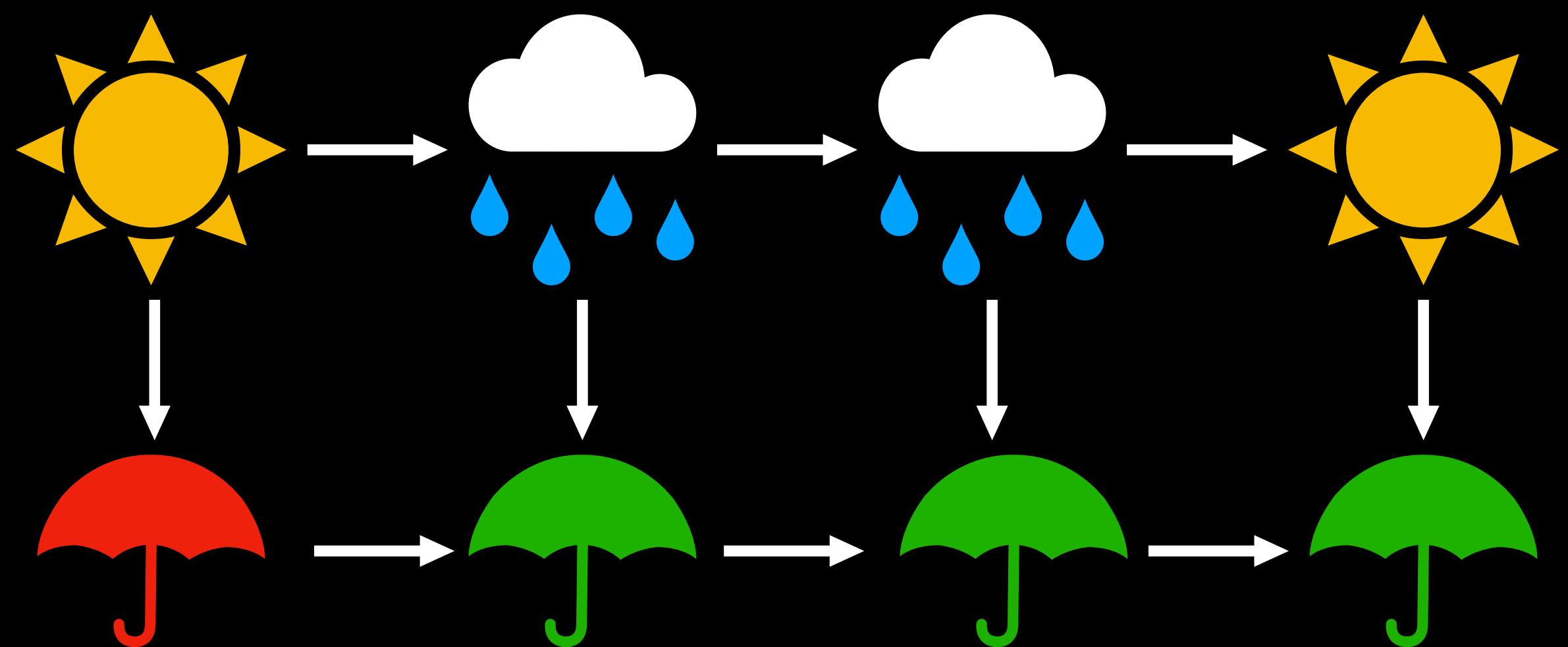


# Knowledge

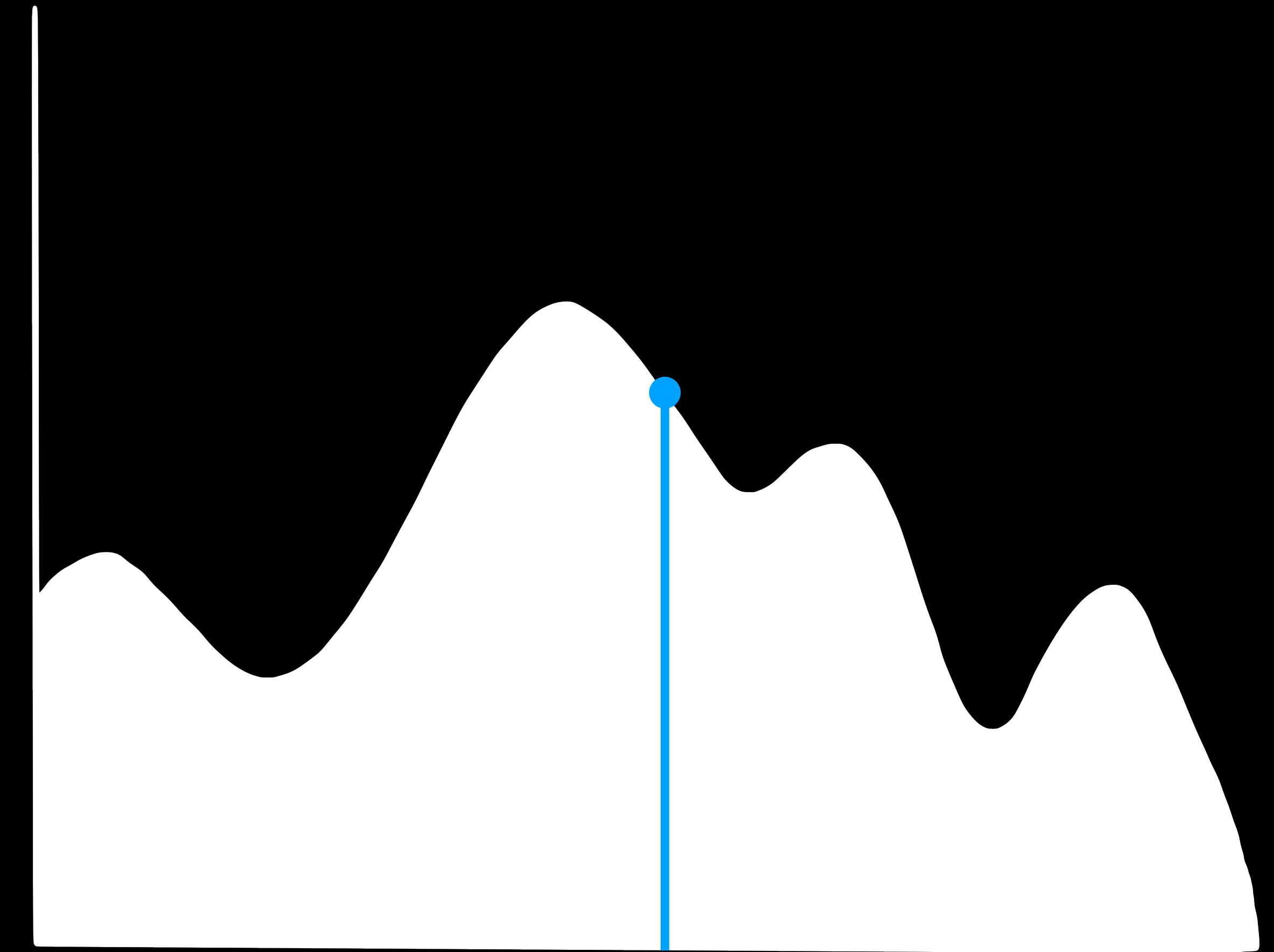
$$P \rightarrow Q$$

$$\frac{P}{Q}$$

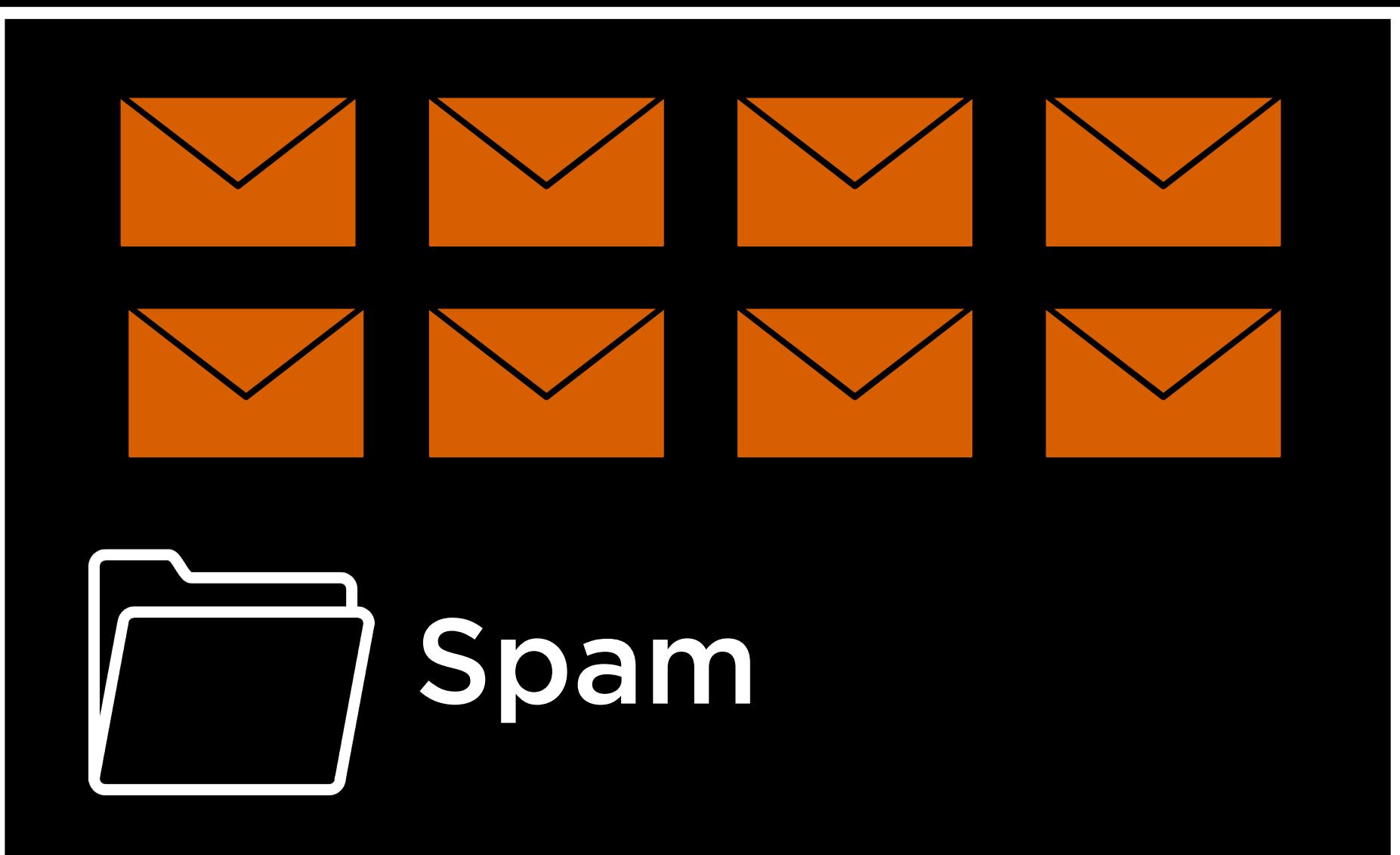
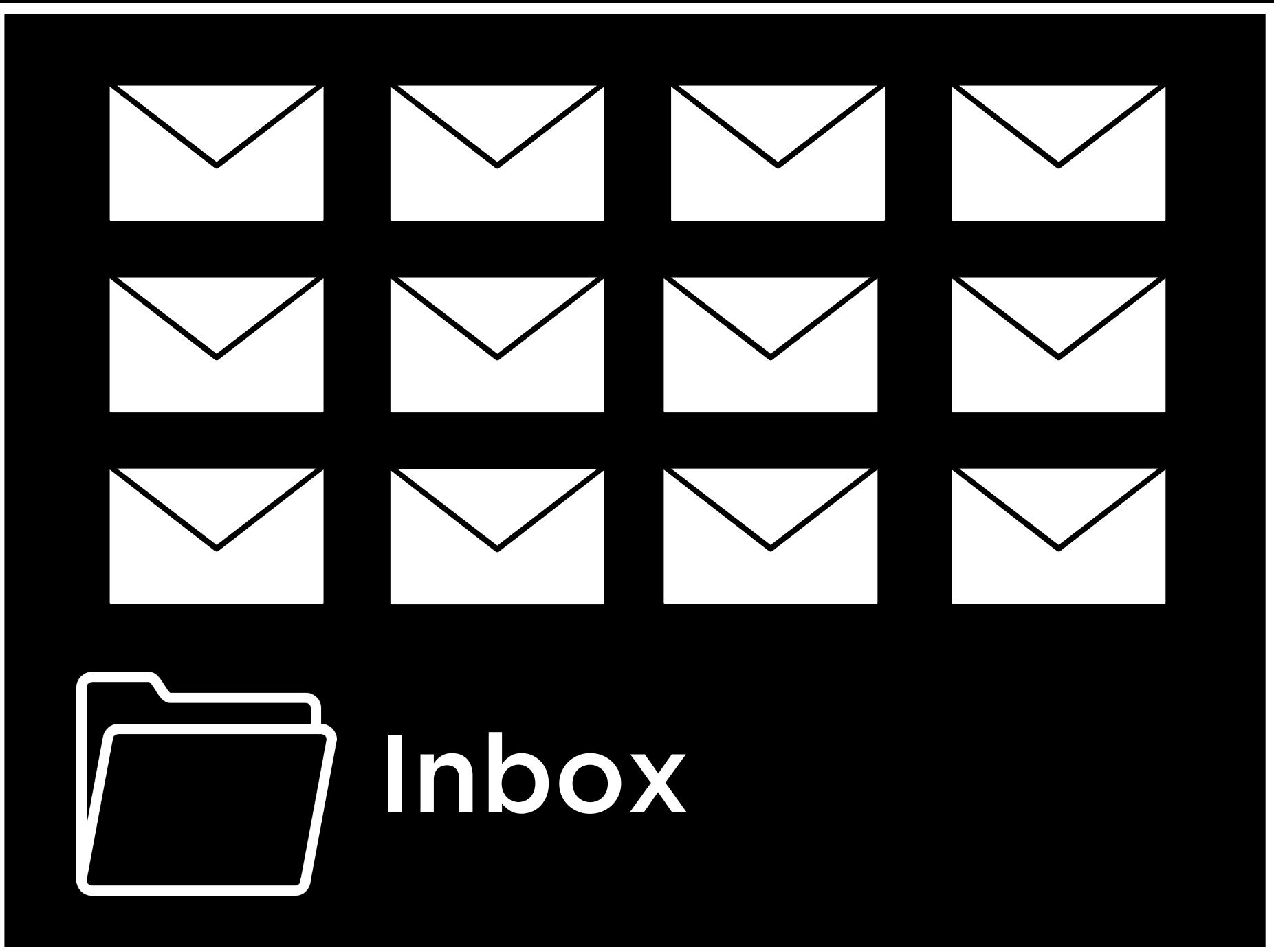
# Uncertainty



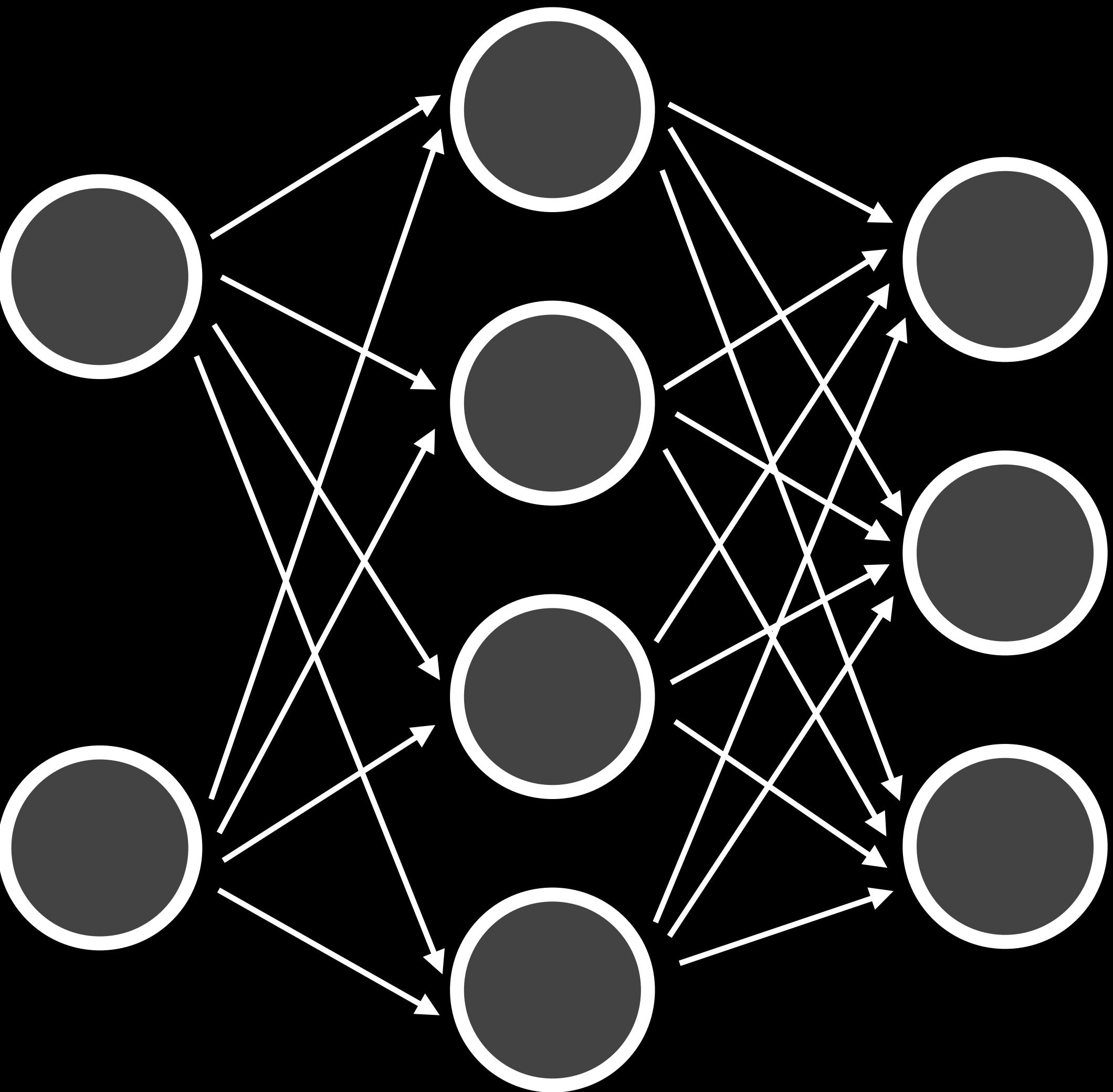
# Optimization



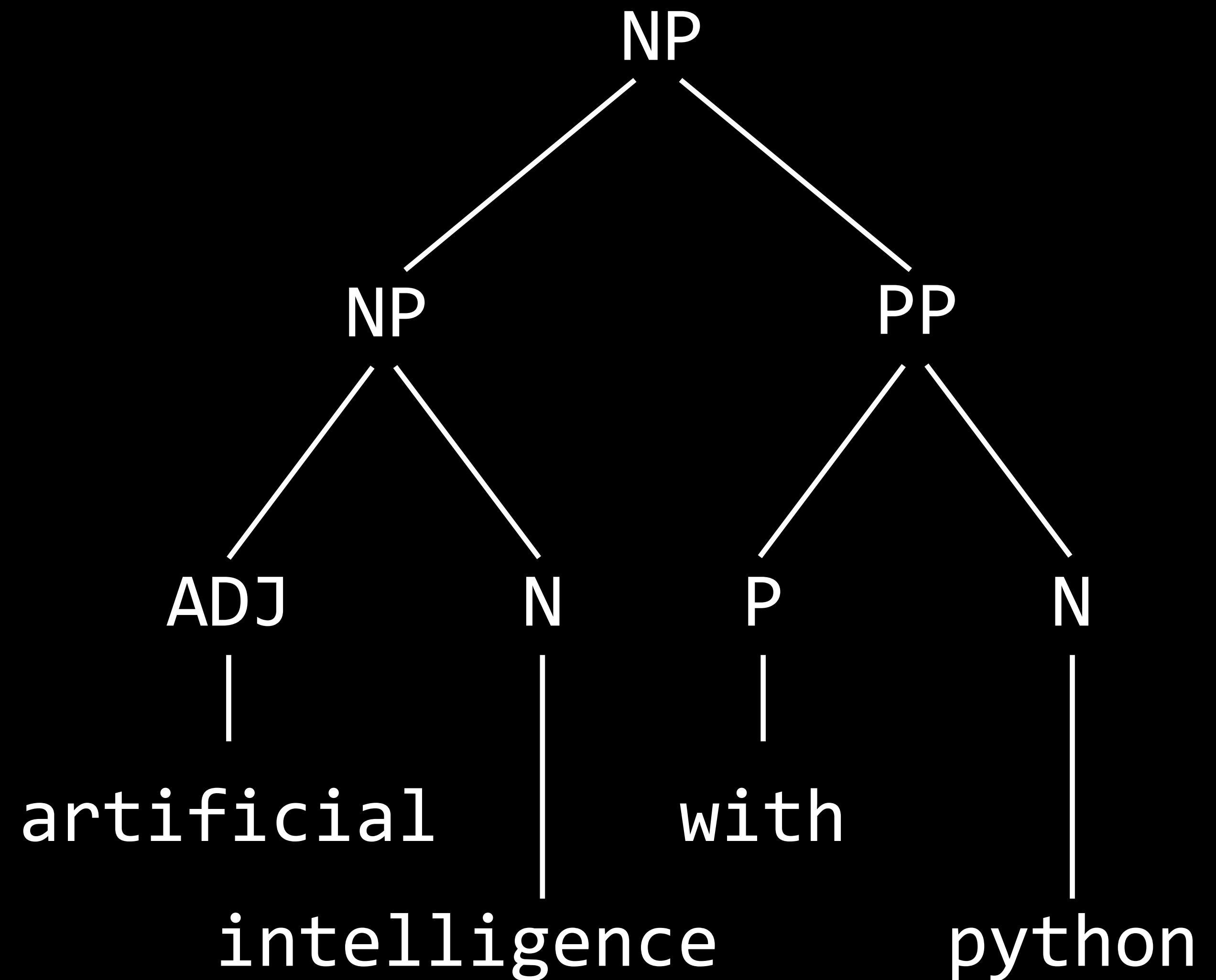
# Learning



# Neural Networks

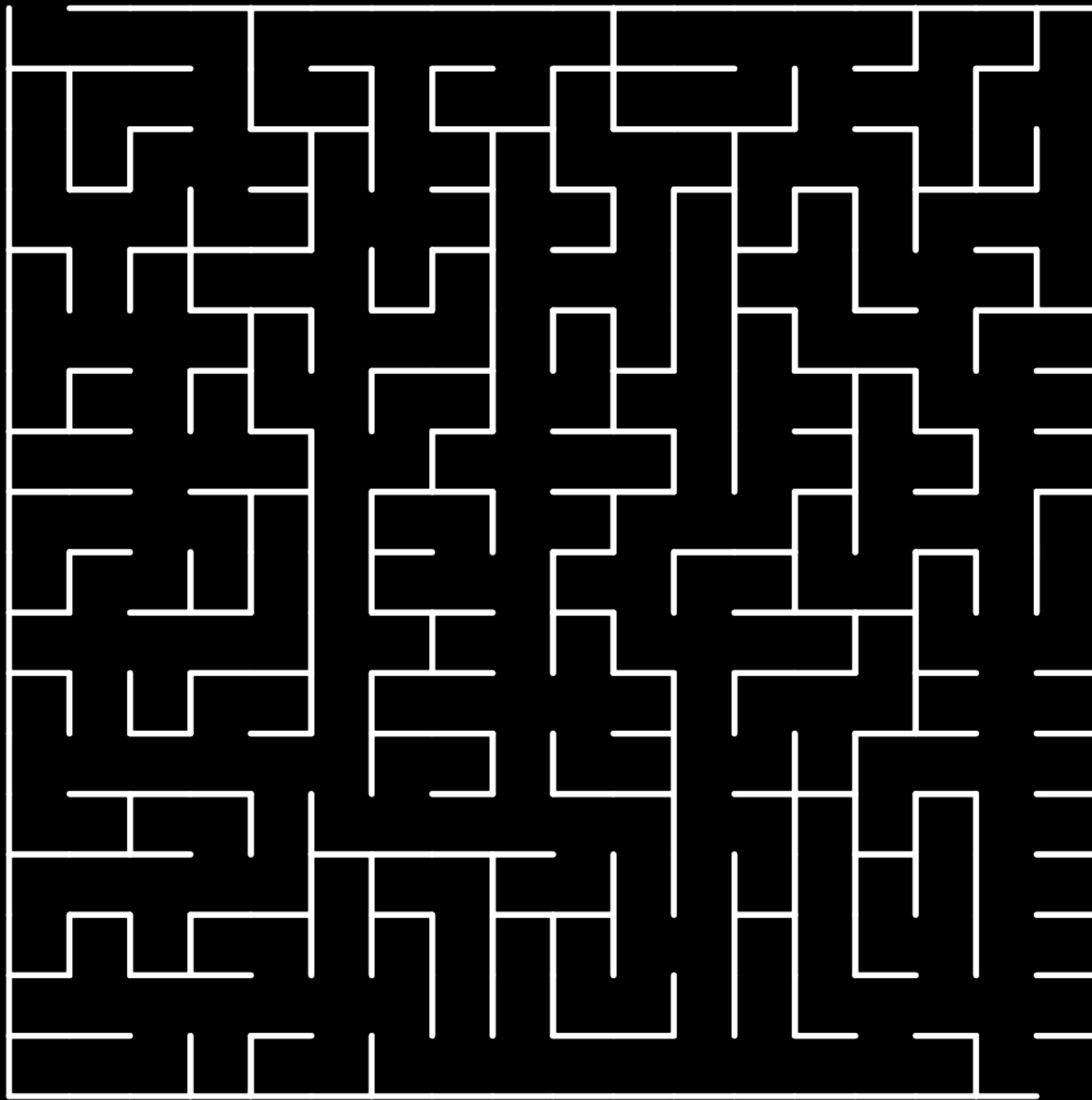


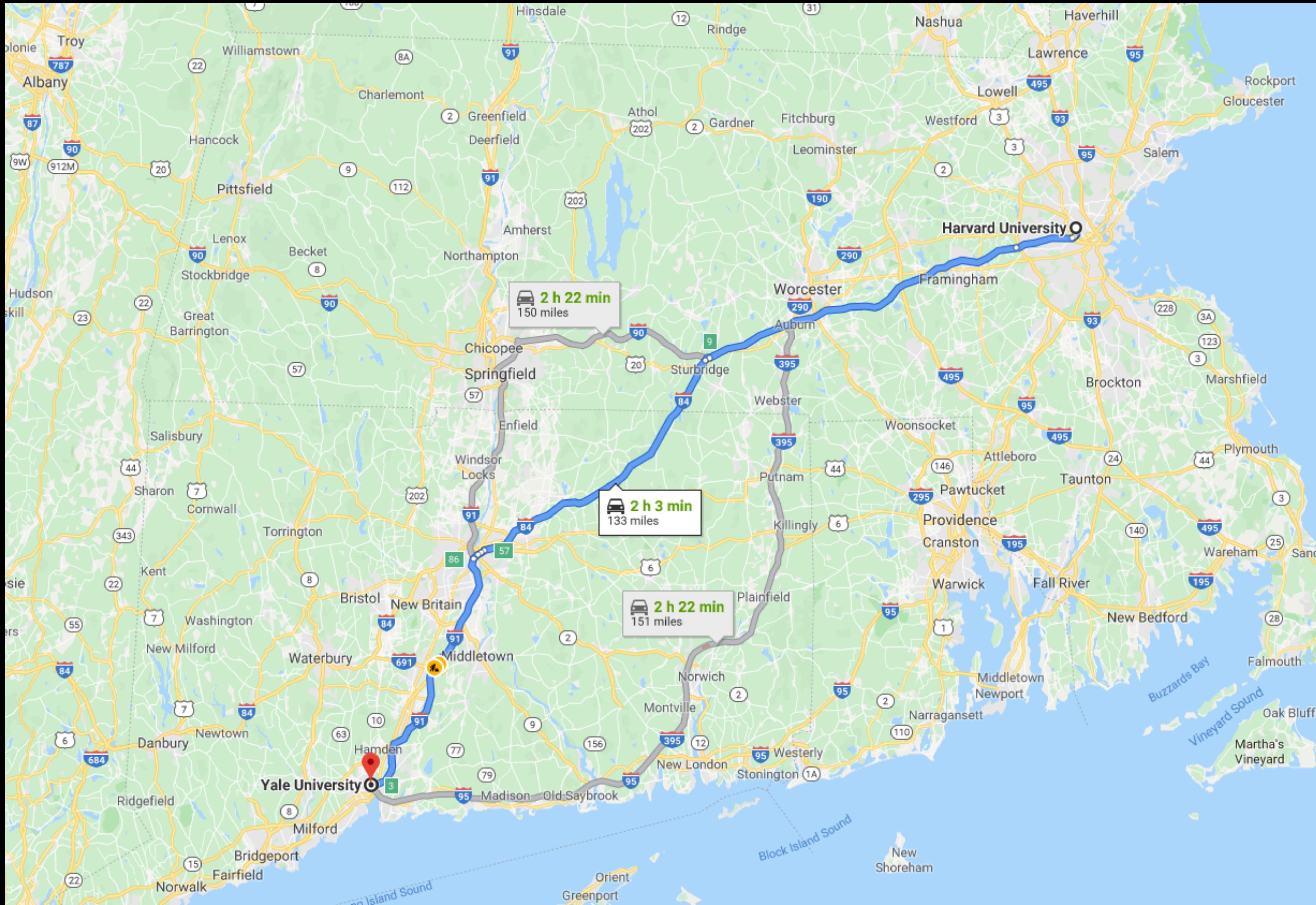
# Language



# Search

1	2	3	4
5	6	7	8
9	10	11	12
13	14	15	





# Search Problems

# agent

entity that perceives its environment  
and acts upon that environment

# state

a configuration of the agent and  
its environment

2	4	5	7
8	3	1	11
14	6		10
9	13	15	12

12	9	4	2
8	7	3	14
	1	6	11
5	13	10	15

15	4	10	3
13	1	11	12
9	5	14	7
6	8		2

# initial state

the state in which the agent begins

# initial state

2	4	5	7
8	3	1	11
14	6		10
9	13	15	12

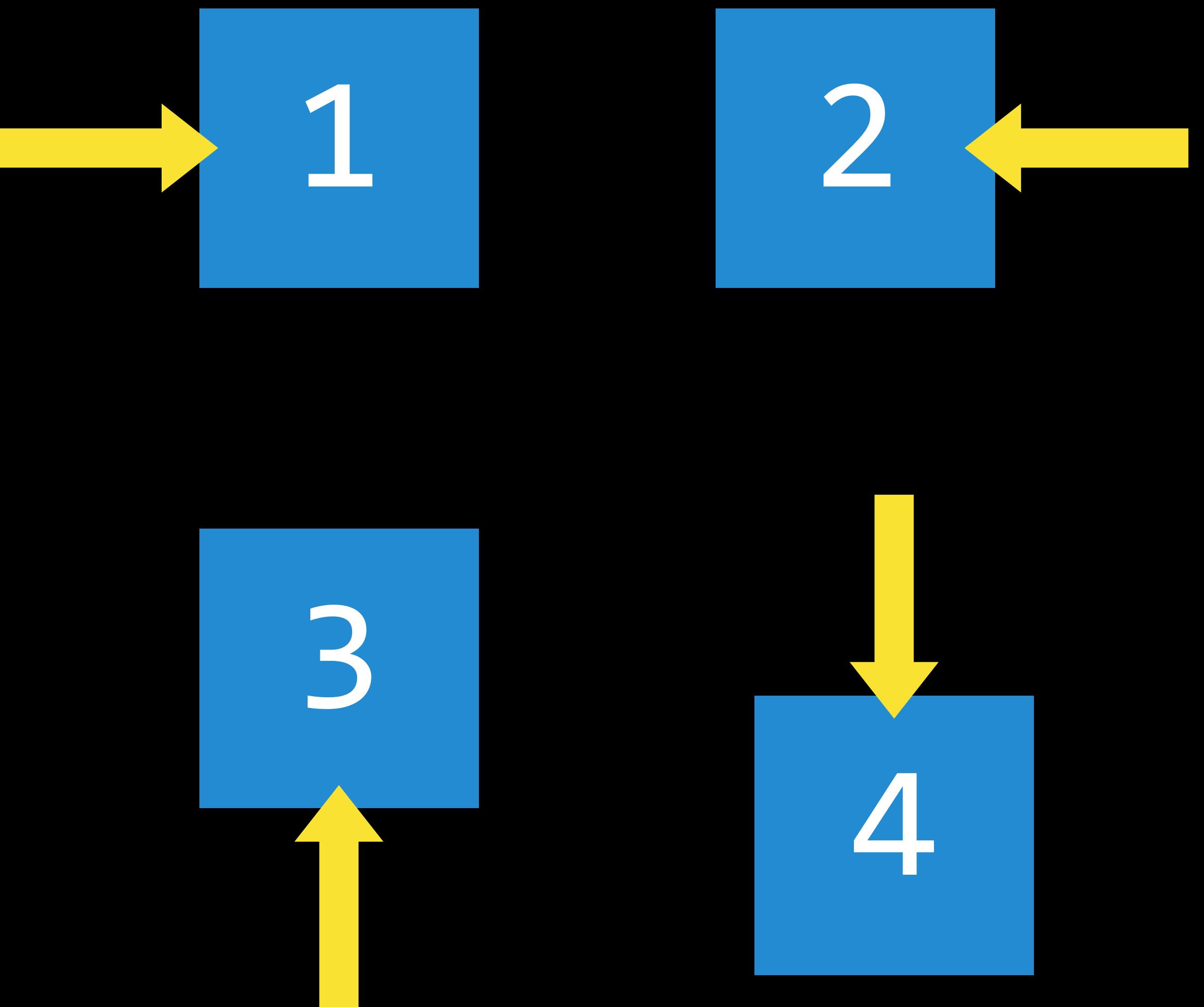
# actions

choices that can be made in a state

# actions

$\text{ACTIONS}(s)$  returns the set of actions that can be executed in state  $s$

actions



# transition model

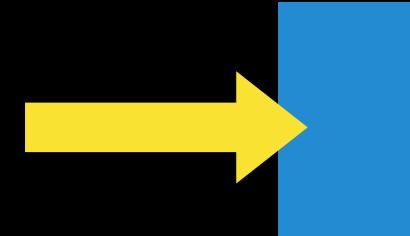
a description of what state results from performing any applicable action in any state

# transition model

$\text{RESULT}(s, a)$  returns the state resulting from performing action  $a$  in state  $s$

RESULT(

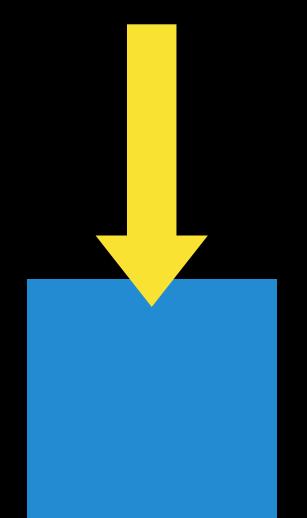
2	4	5	7
8	3	1	11
14	6	10	12
9	13	15	

,  ) =

2	4	5	7
8	3	1	11
14	6	10	12
9	13		15

RESULT(

2	4	5	7
8	3	1	11
14	6	10	12
9	13	15	

,  ) =

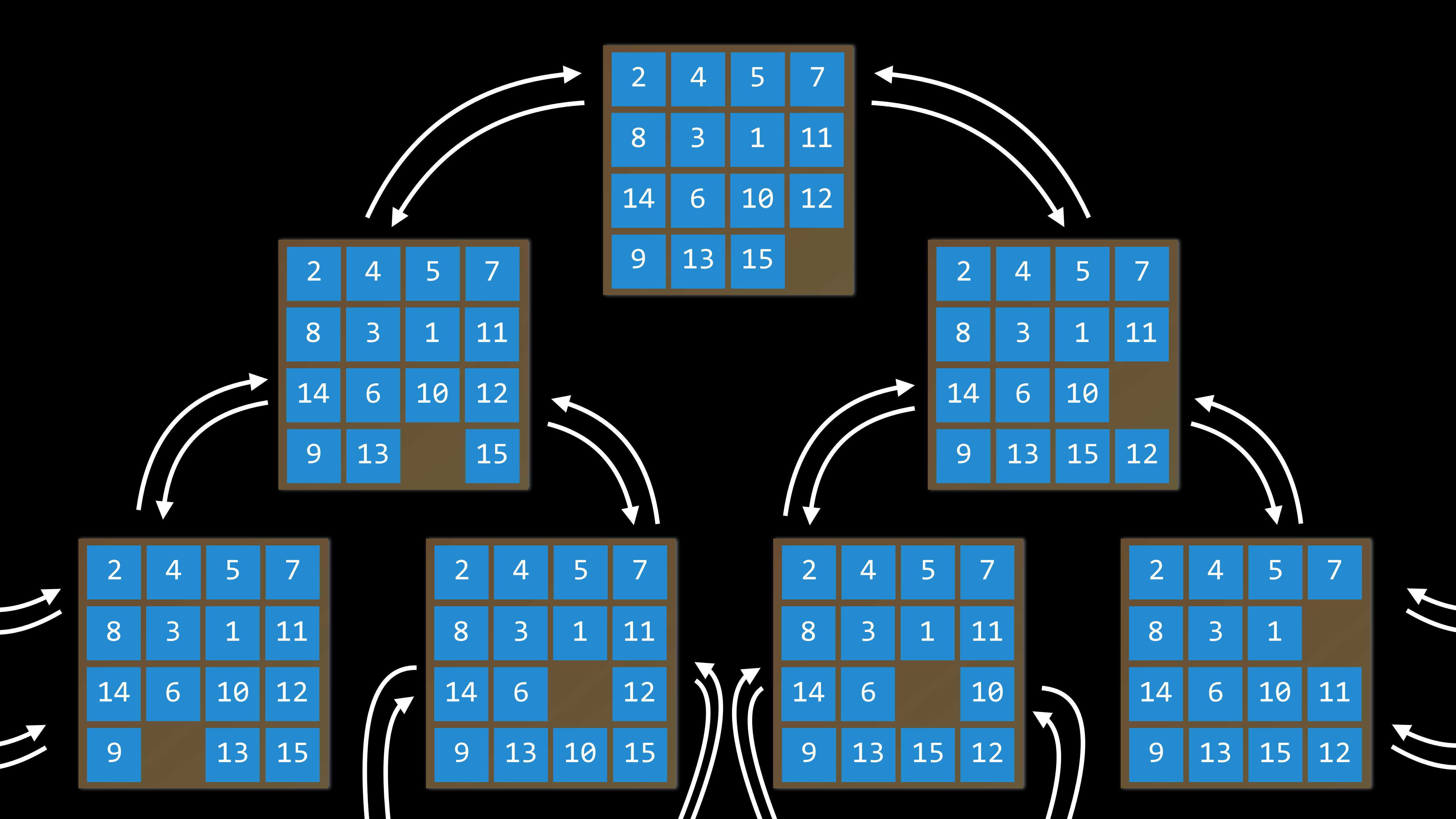
2	4	5	7
8	3	1	11
14	6	10	
9	13	15	12

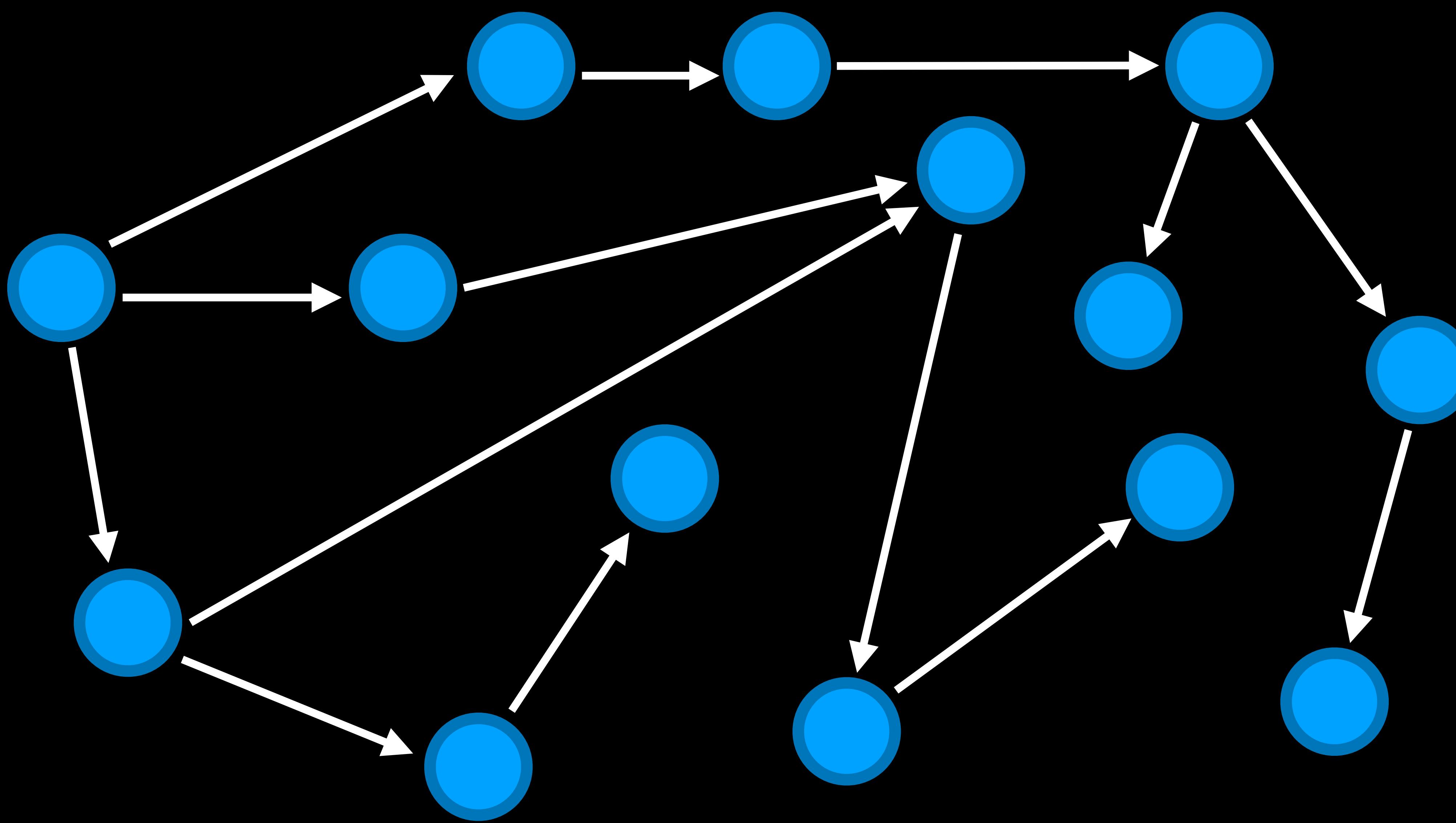
# transition model

$$\text{RESULT}(\begin{array}{|c|c|c|c|}\hline 2 & 4 & 5 & 7 \\ \hline 8 & 3 & 1 & 11 \\ \hline 14 & 6 & 10 & 12 \\ \hline 9 & 13 & 15 & \\ \hline \end{array}, \downarrow) = \begin{array}{|c|c|c|c|}\hline 2 & 4 & 5 & 7 \\ \hline 8 & 3 & 1 & 11 \\ \hline 14 & 6 & 10 & \\ \hline 9 & 13 & 15 & 12 \\ \hline \end{array}$$

# state space

the set of all states reachable from the initial state by any sequence of actions



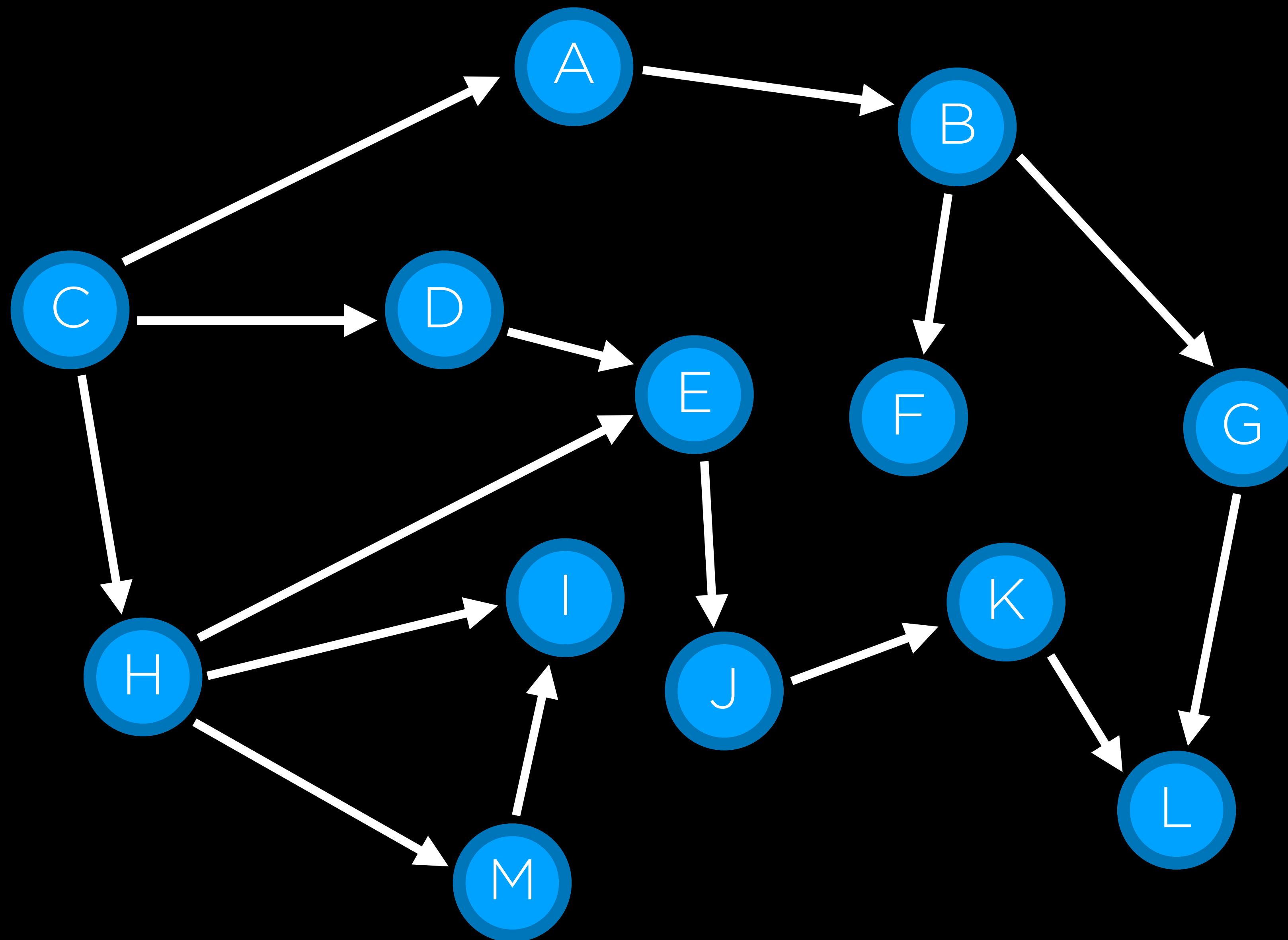


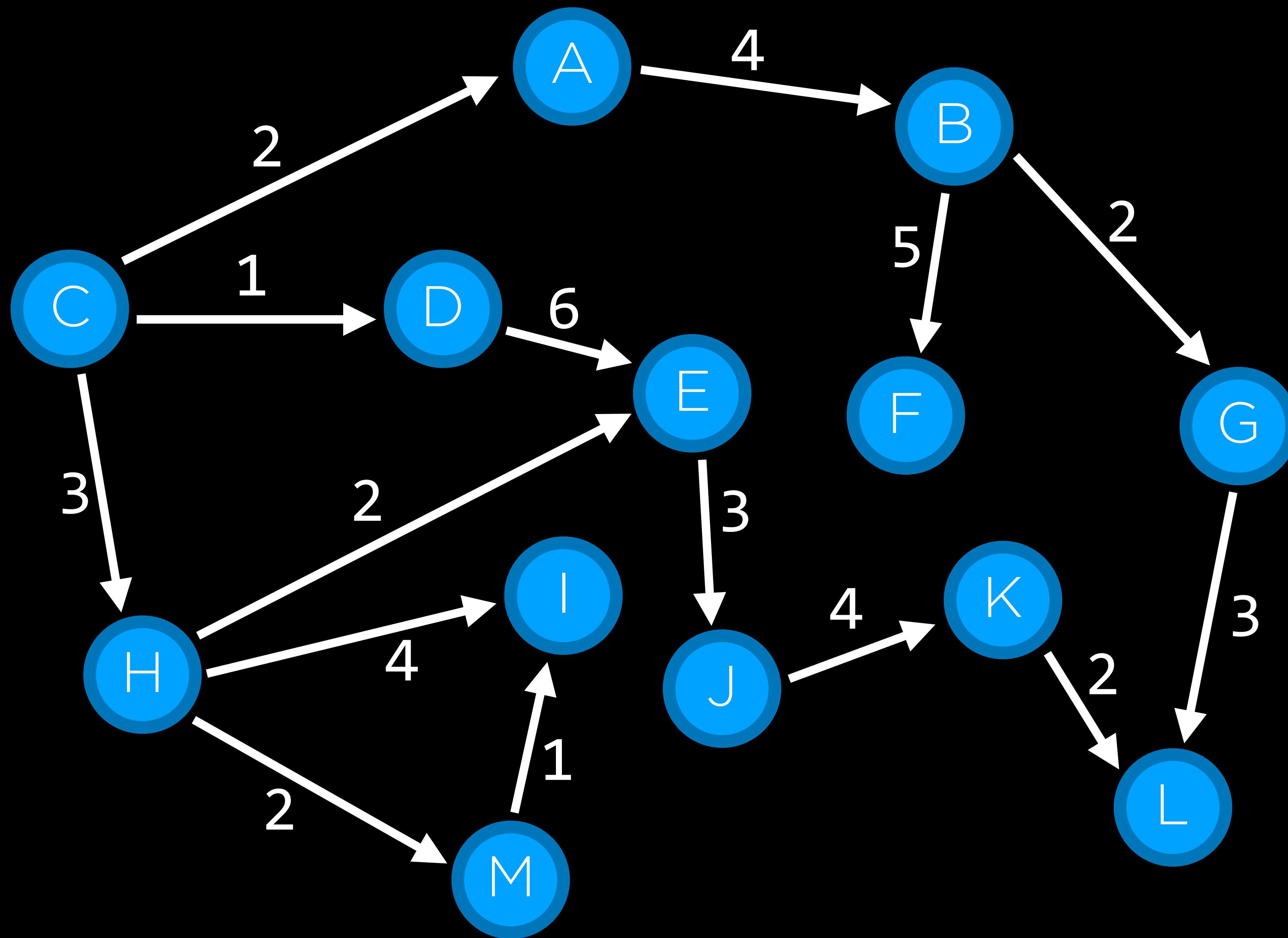
# goal test

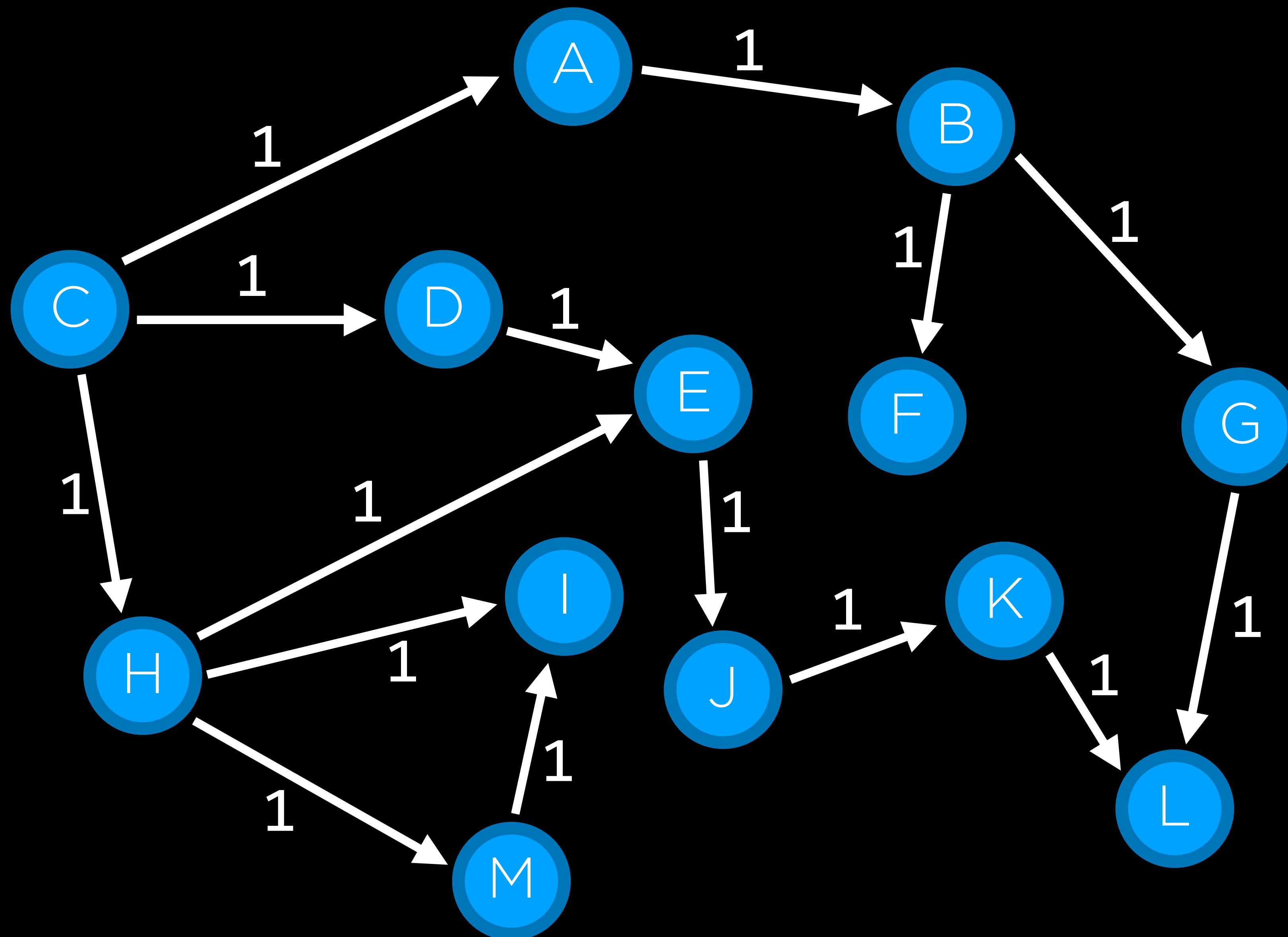
way to determine whether a given state  
is a goal state

# path cost

numerical cost associated with a given path







# Search Problems

- initial state
- actions
- transition model
- goal test
- path cost function

# solution

a sequence of actions that leads from the initial state to a goal state

# optimal solution

a solution that has the lowest path cost  
among all solutions

# node

a data structure that keeps track of

- a **state**
- a **parent** (node that generated this node)
- an **action** (action applied to parent to get node)
- a **path cost** (from initial state to node)

# Approach

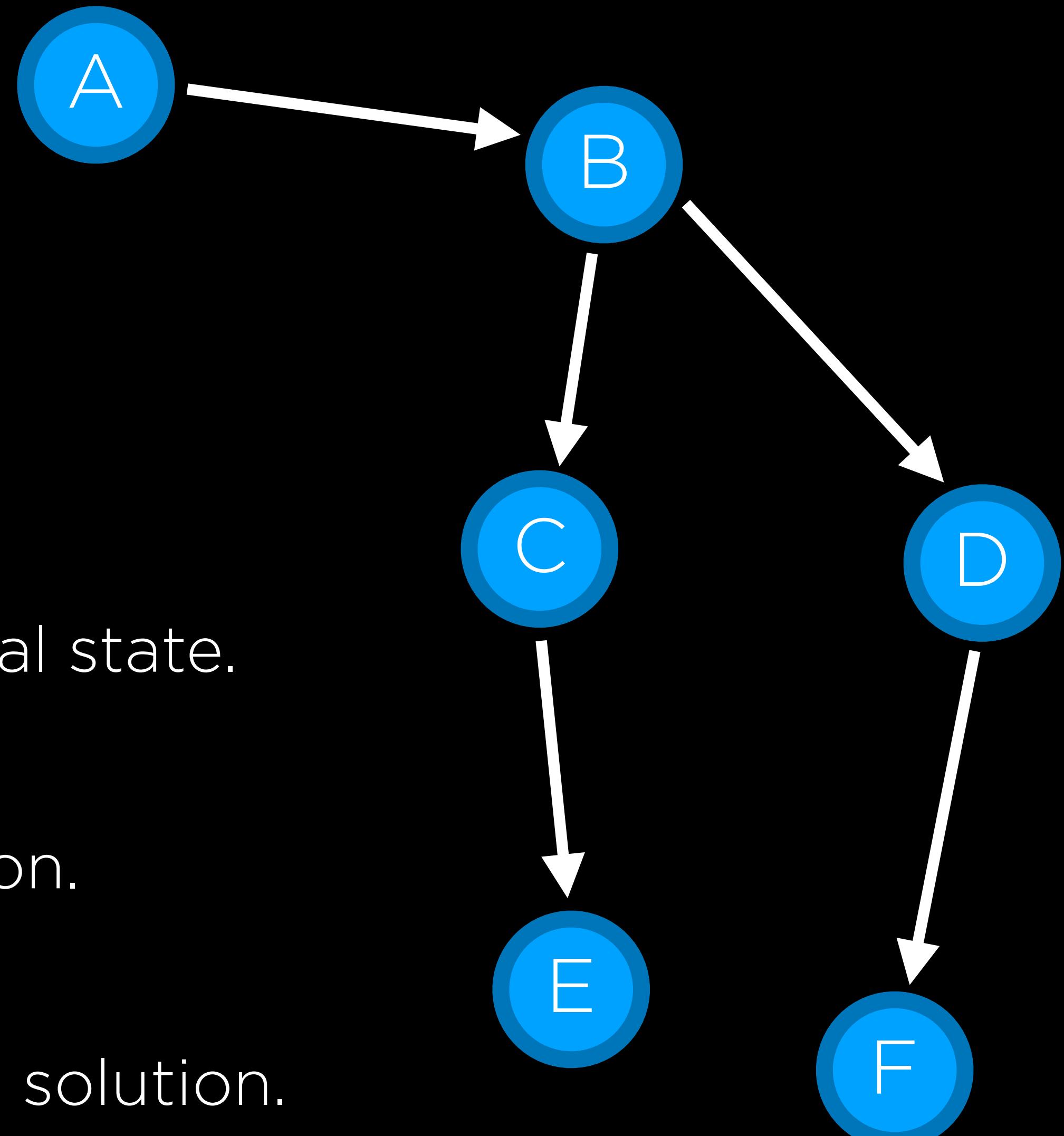
frontier is all nodes we can explore next and haven't yet explored

- Start with a **frontier** that contains the initial state.
- Repeat:
  - If the frontier is empty, then no solution.
  - Remove a node from the frontier.
  - If node contains goal state, return the solution.
  - **Expand** node, add resulting nodes to the frontier.

Find a path from A to E.

**Frontier**

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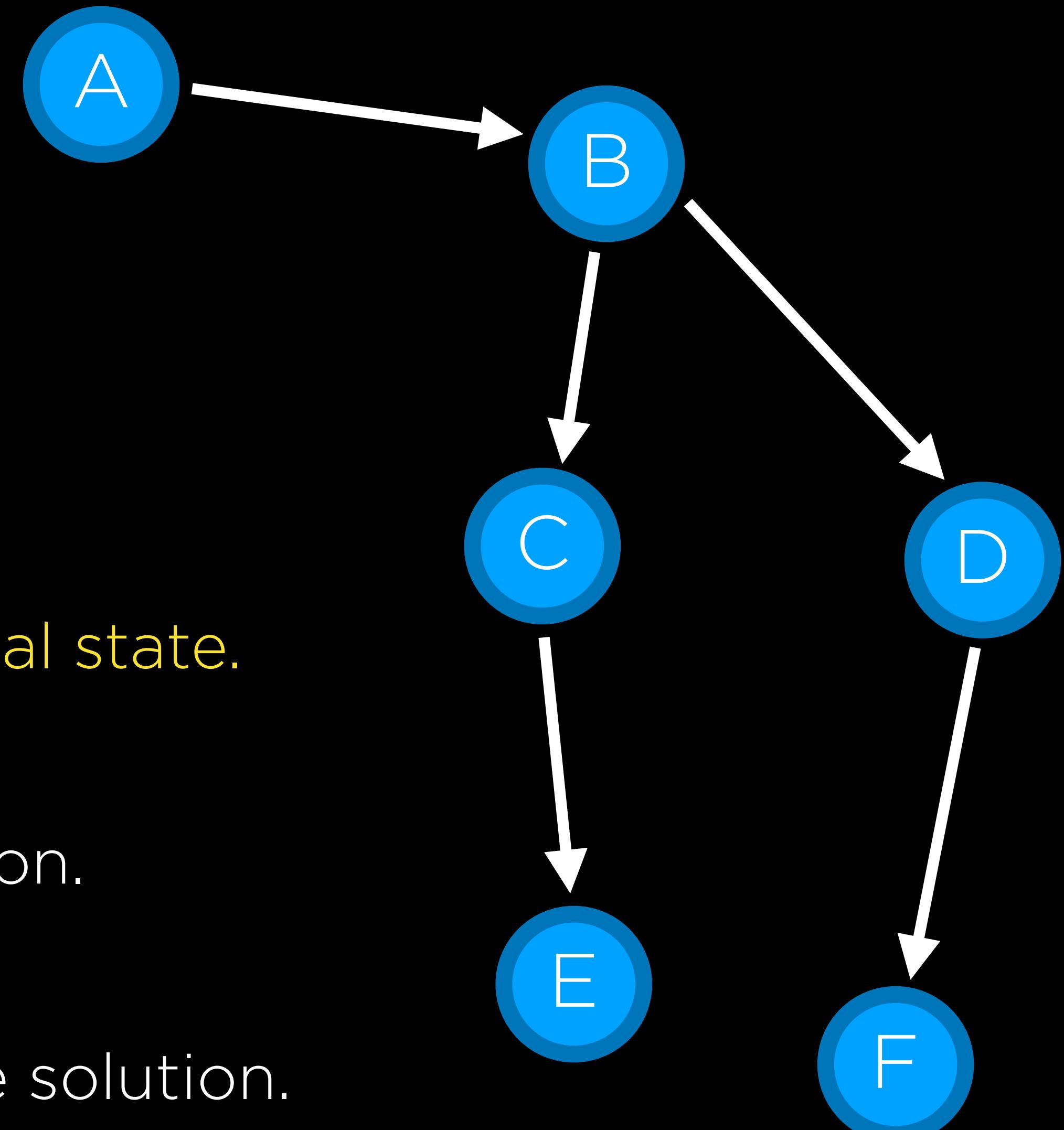


Find a path from A to E.

### Frontier



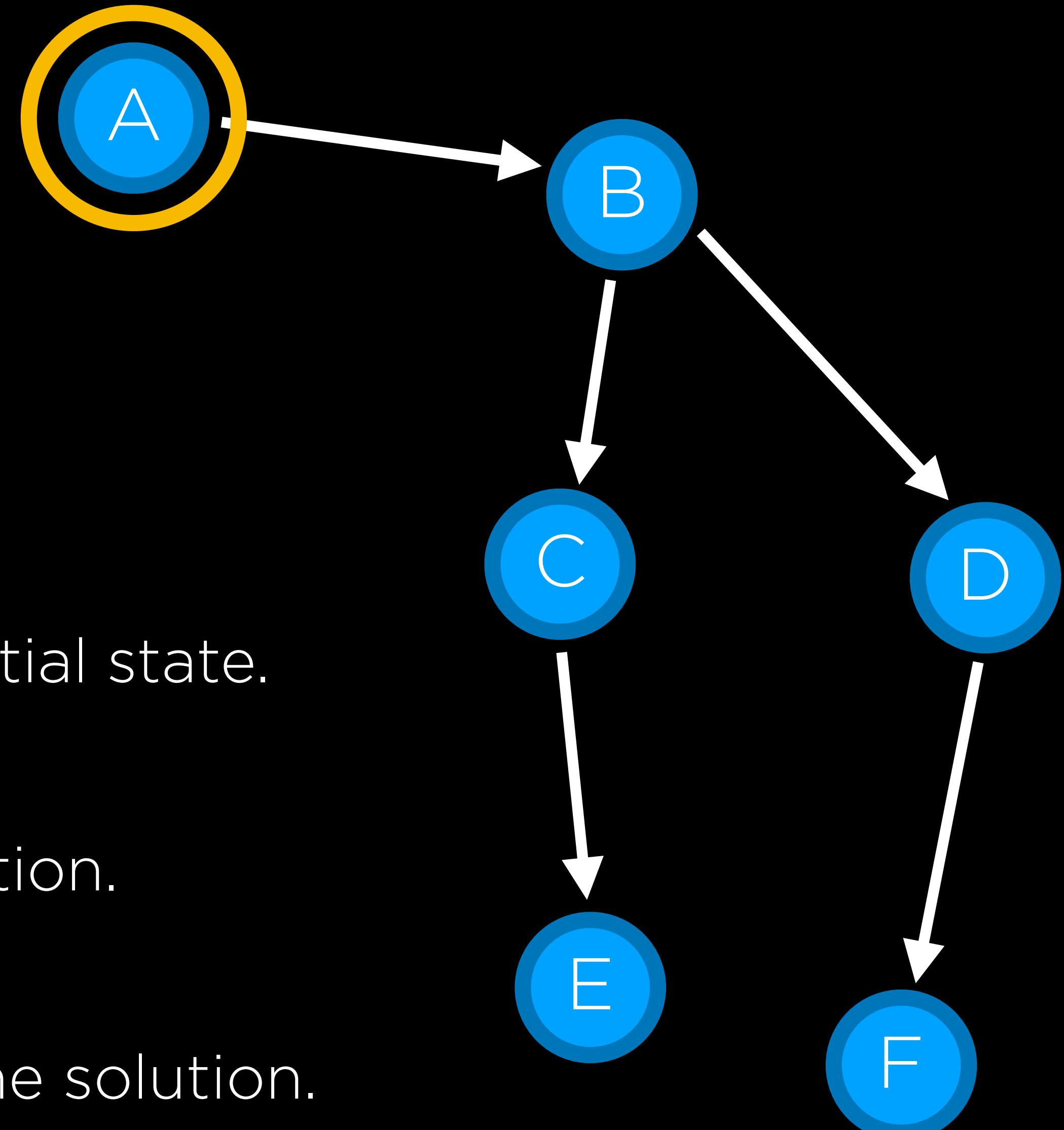
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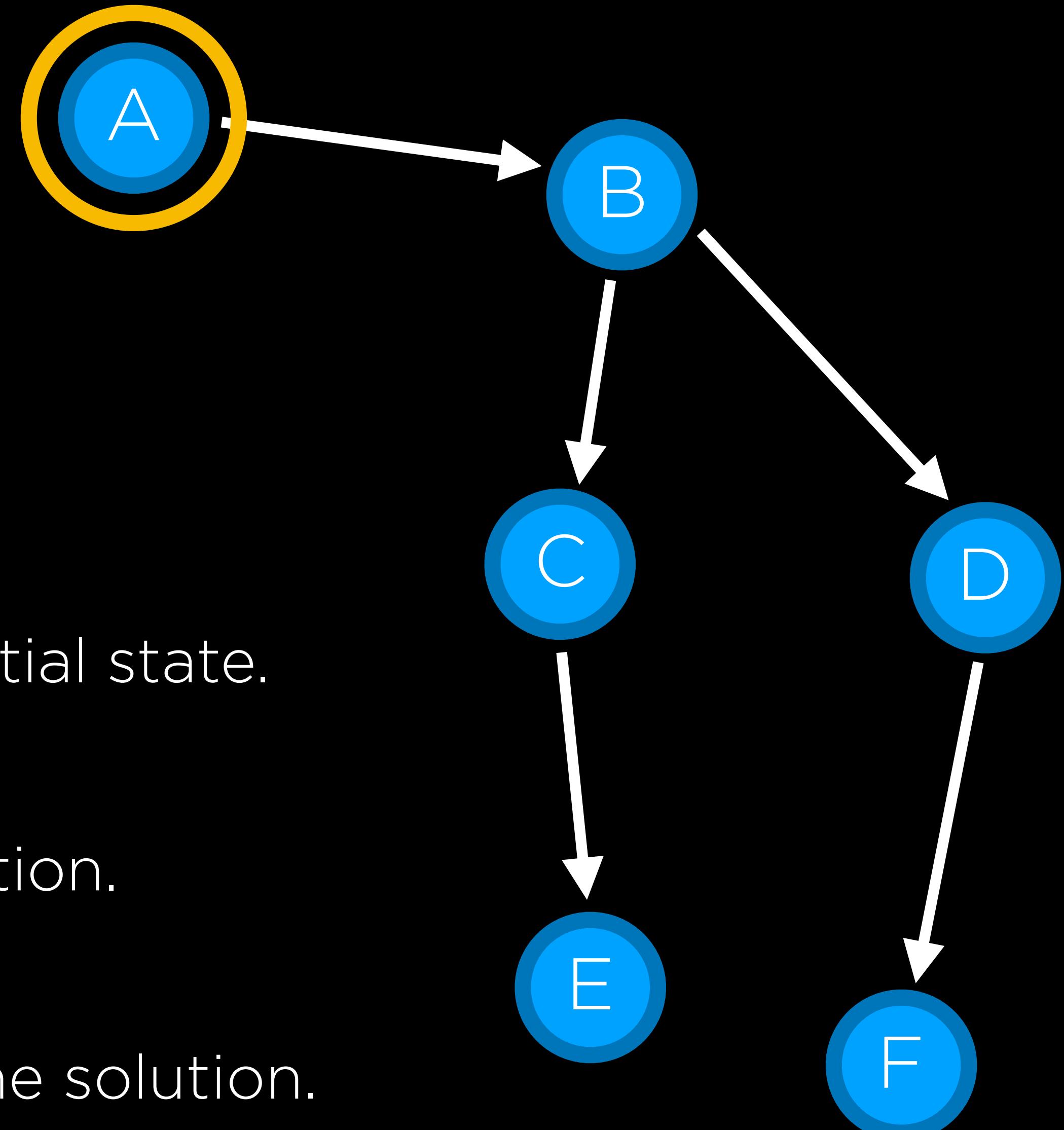


Find a path from A to E.

### Frontier



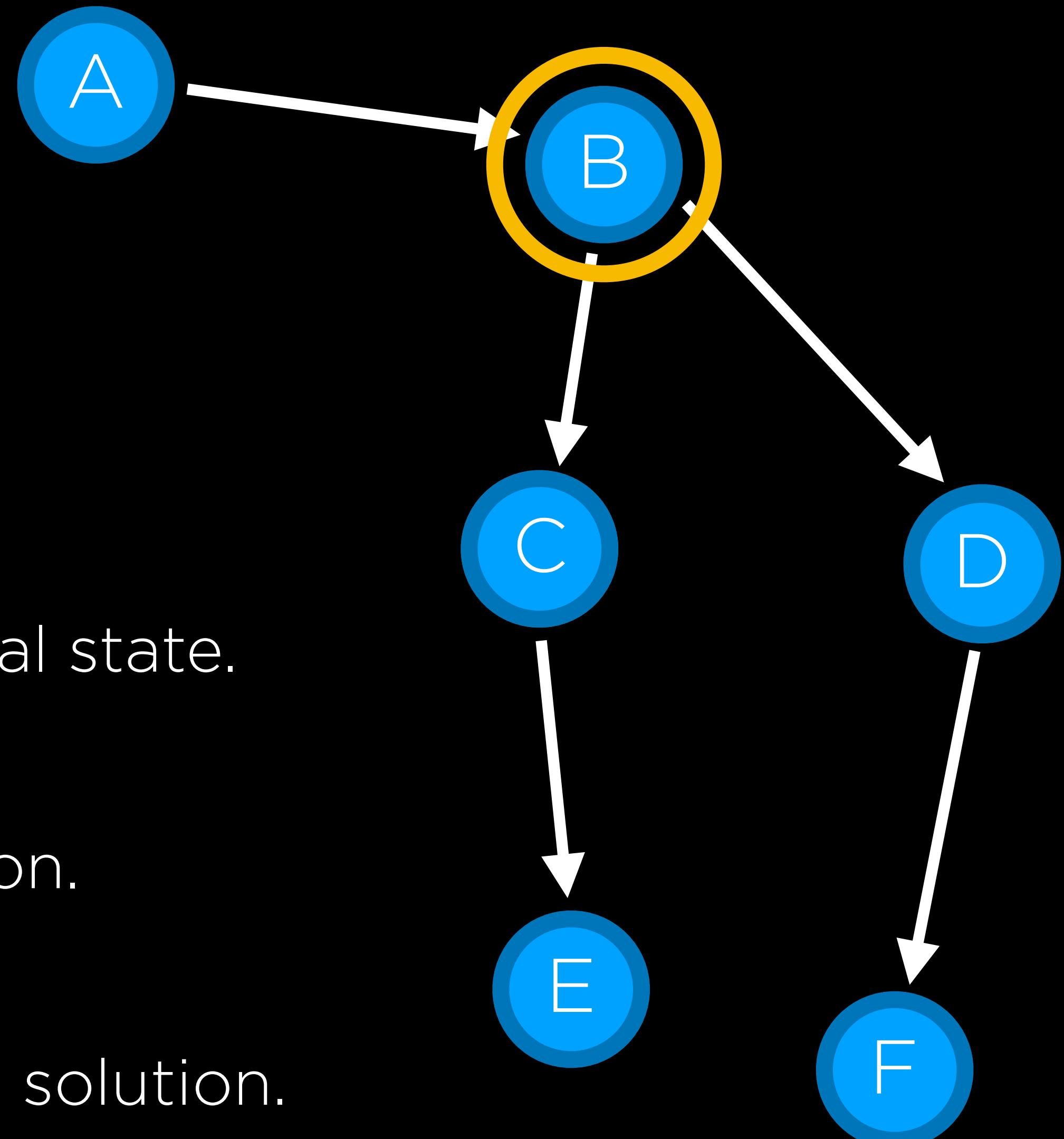
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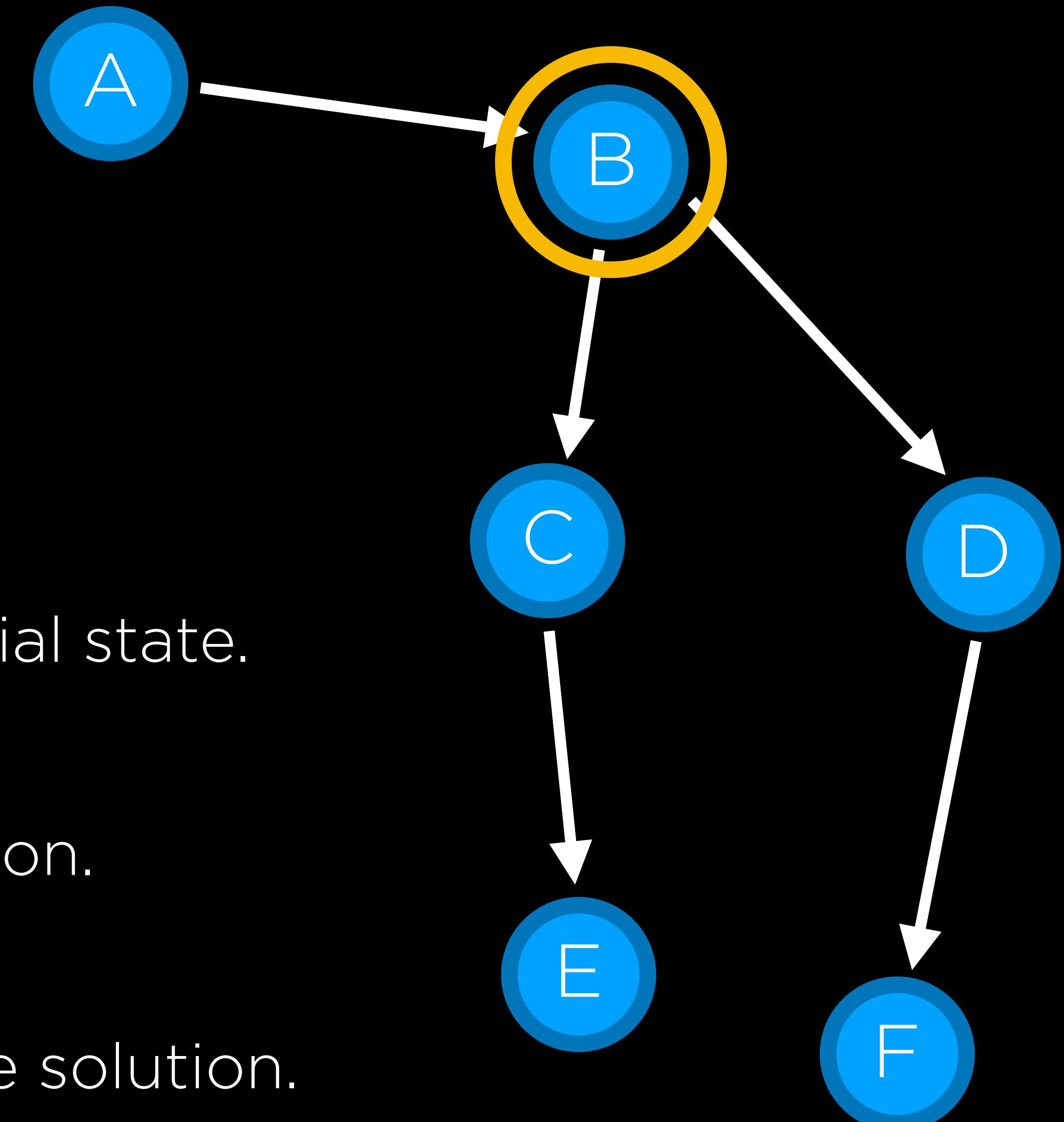
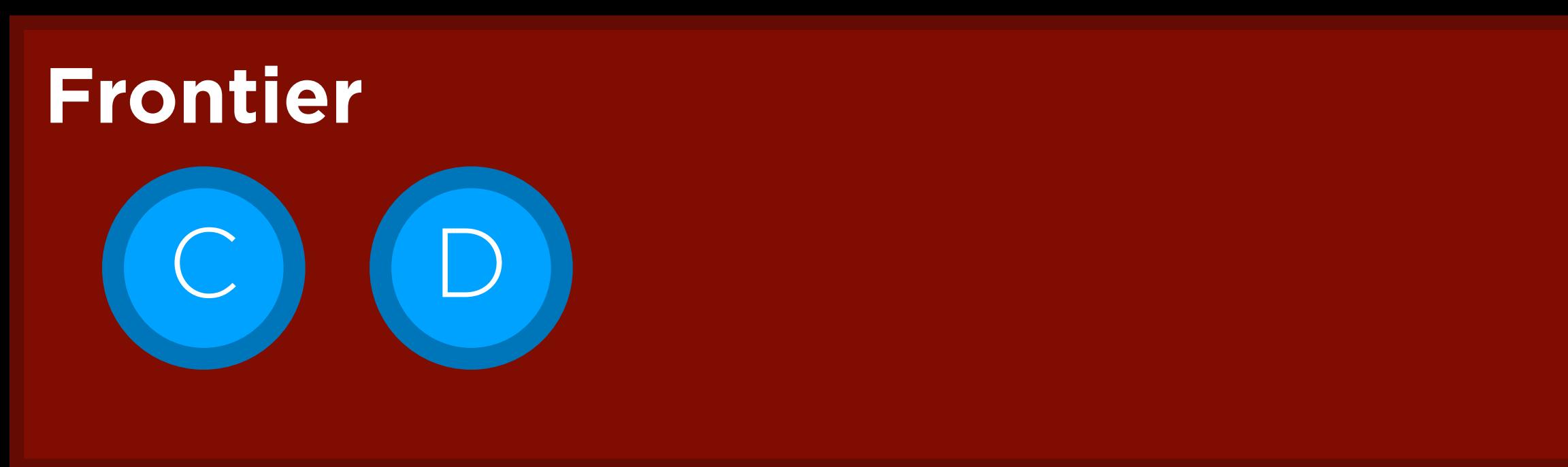
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Find a path from A to E.



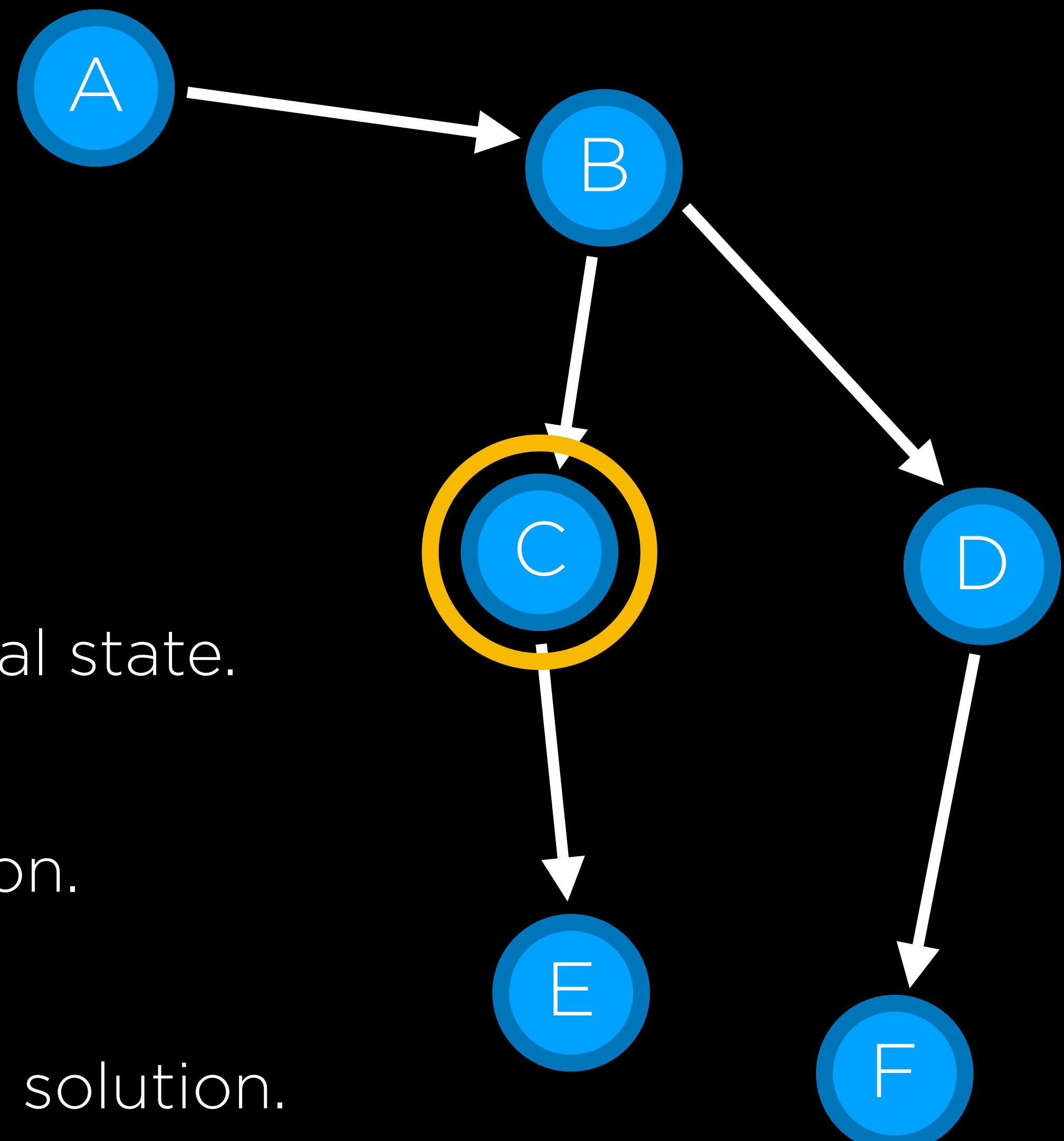
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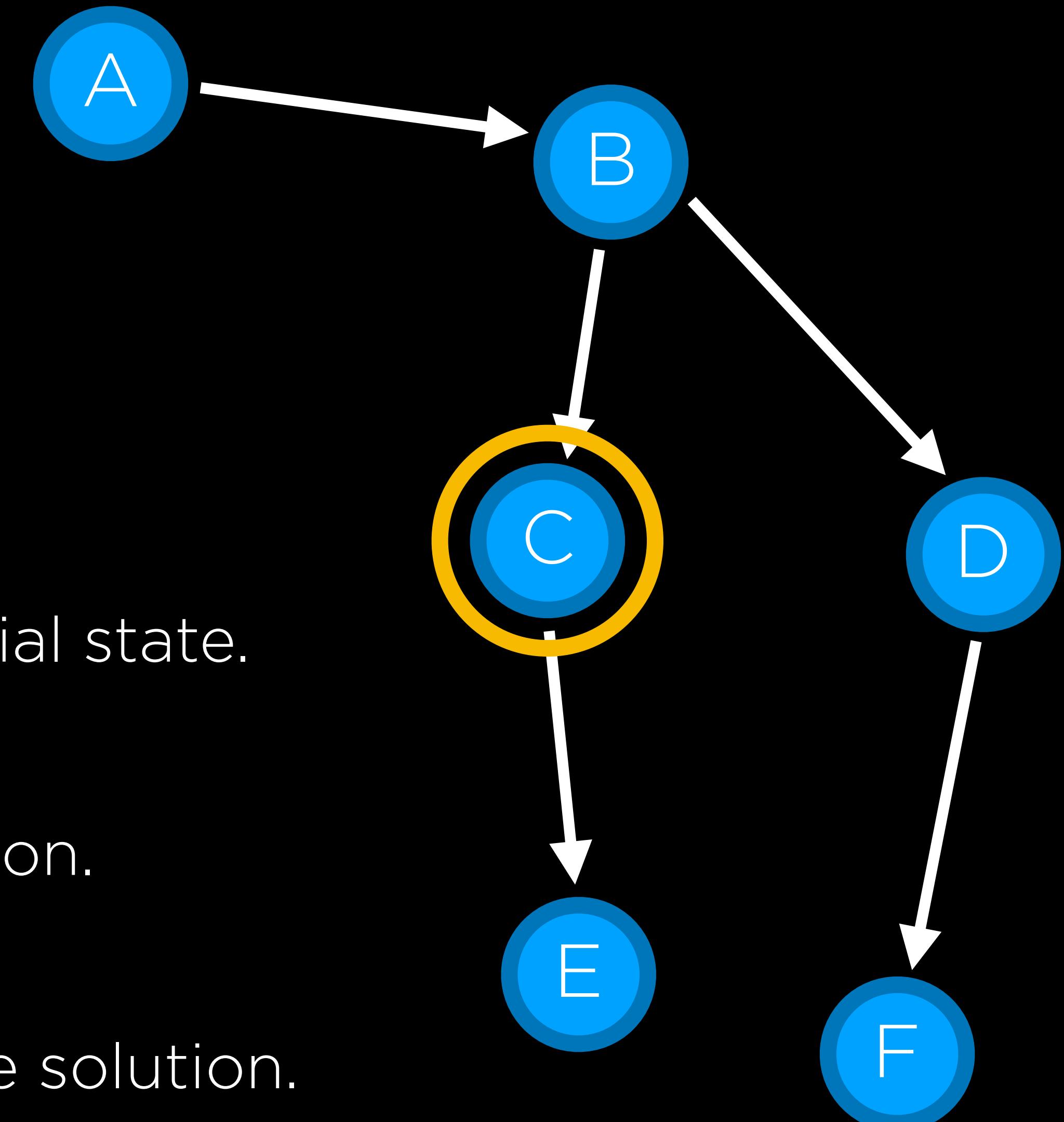
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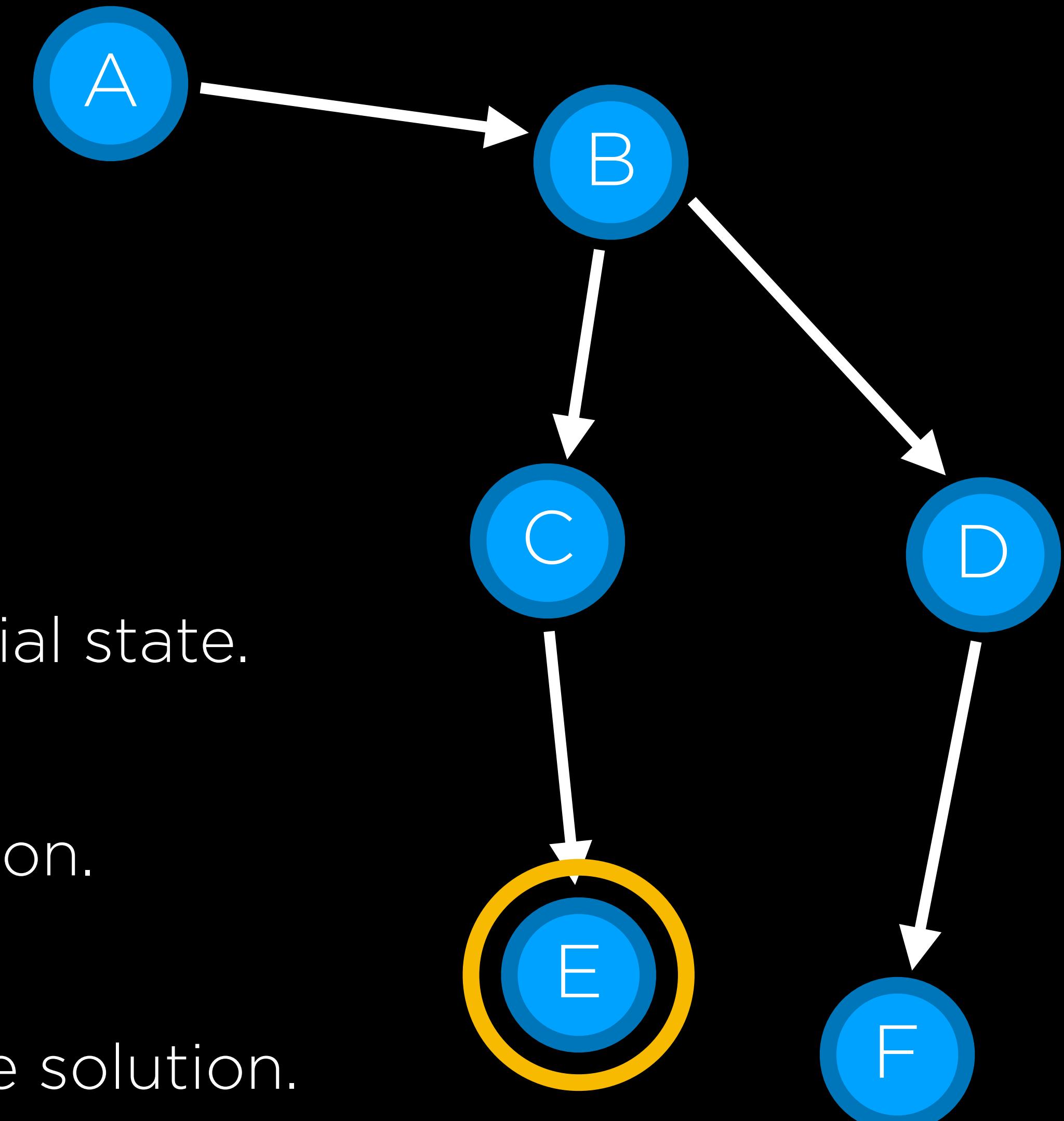


Find a path from A to E.



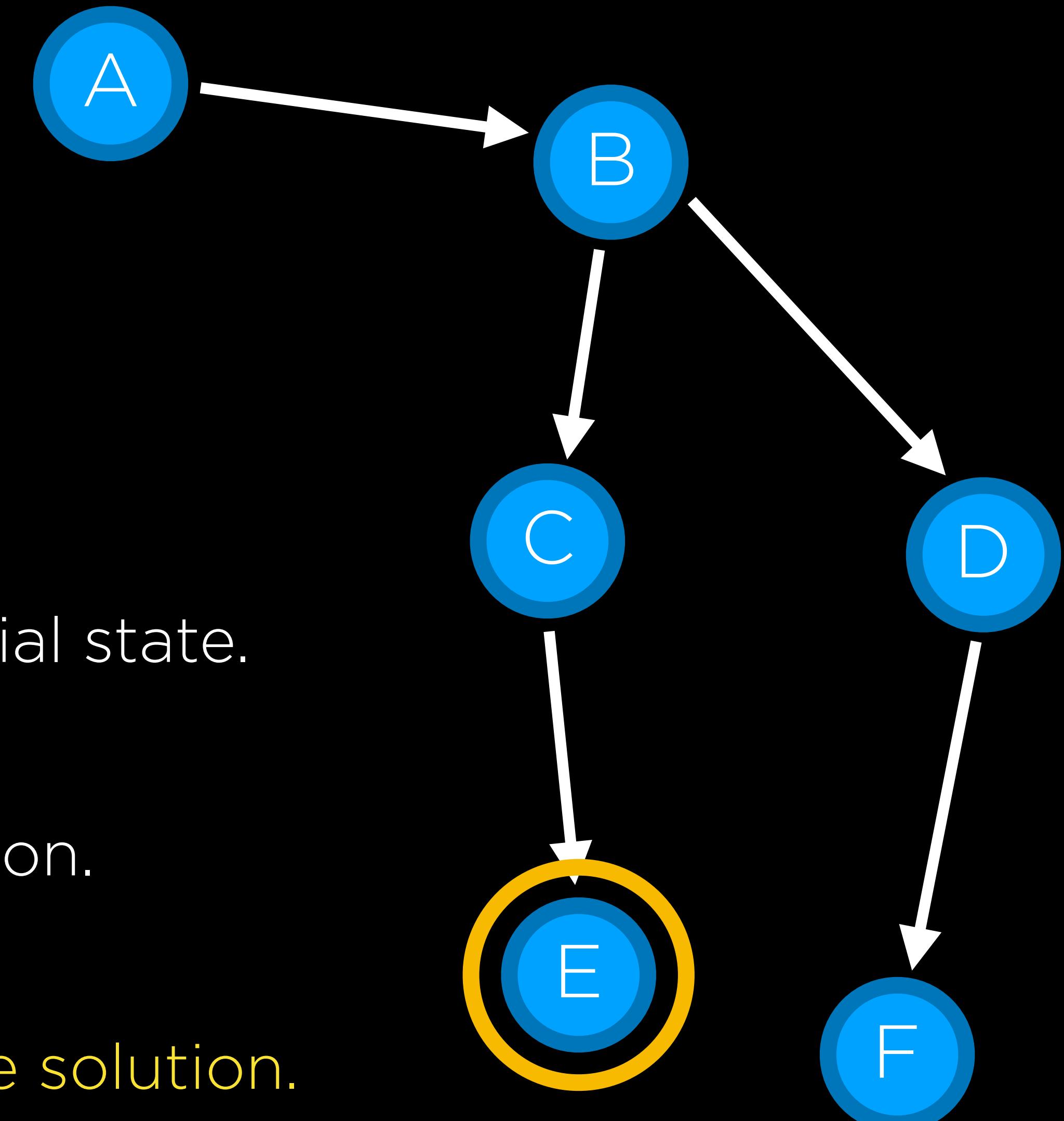
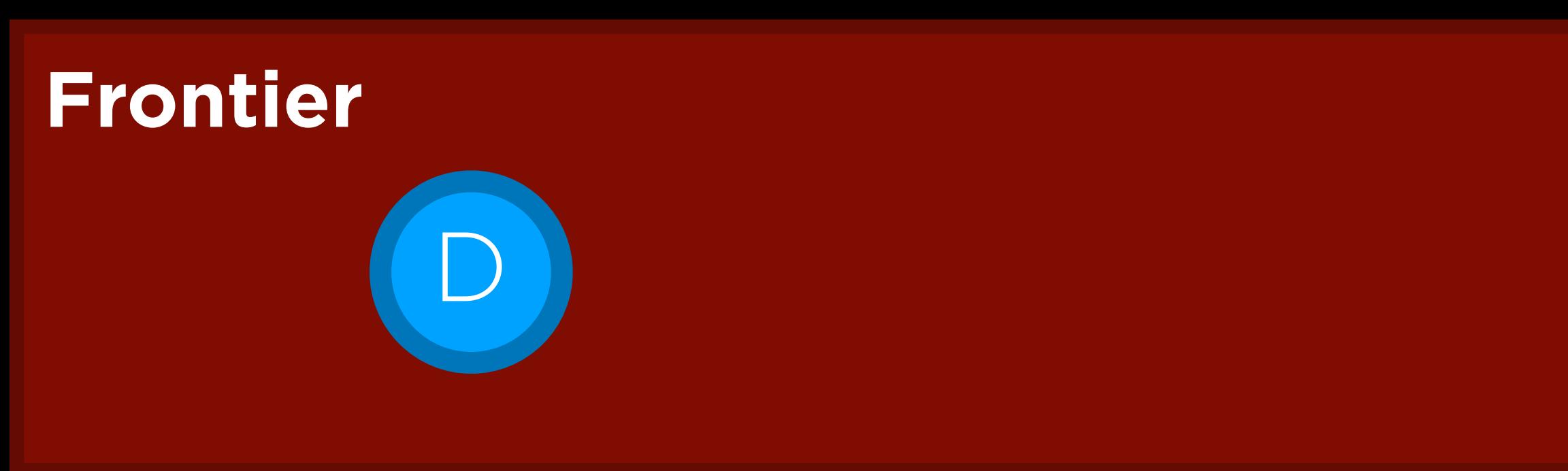
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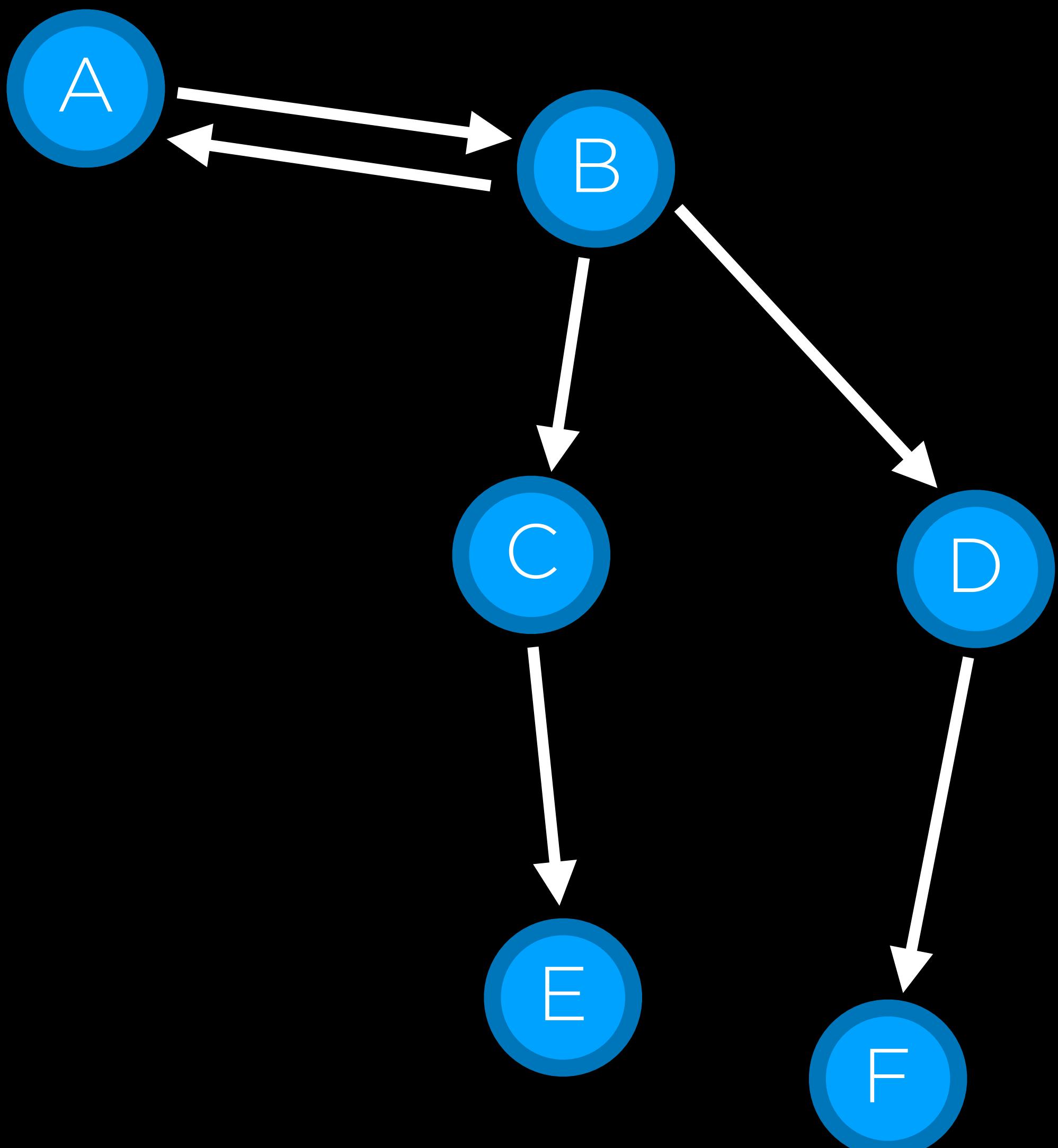
Find a path from A to E.



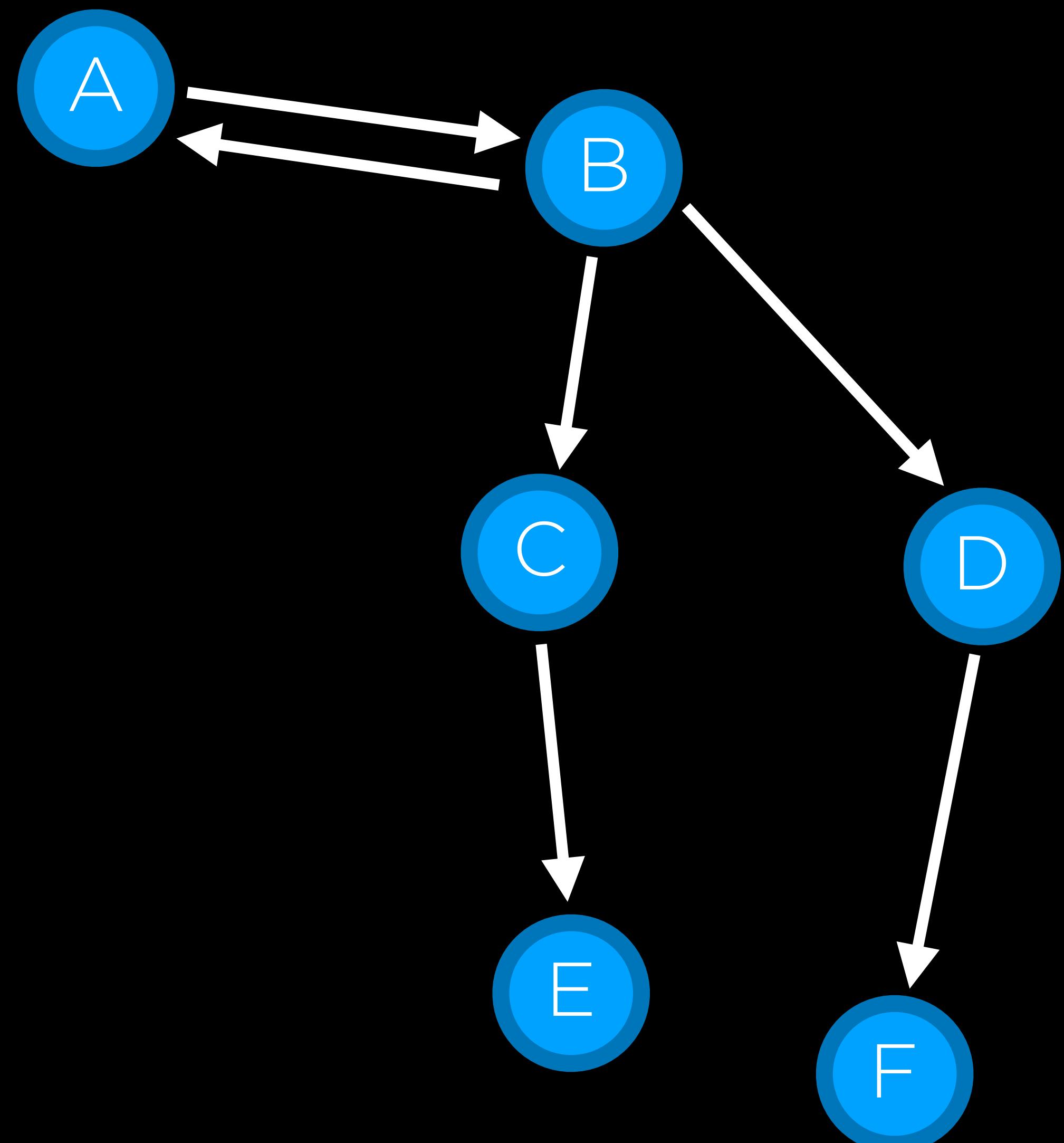
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What could go wrong?

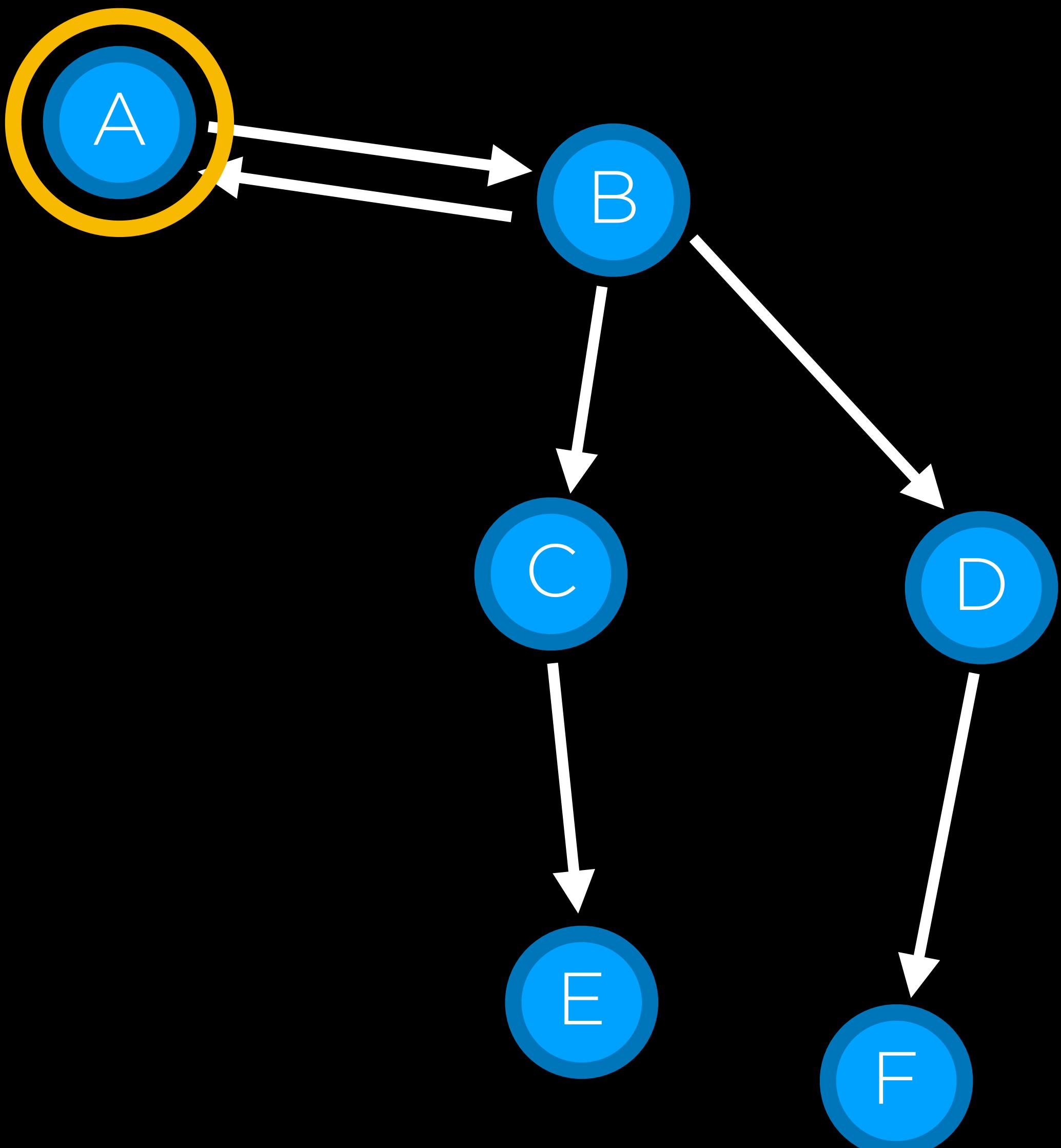
Find a path from A to E.



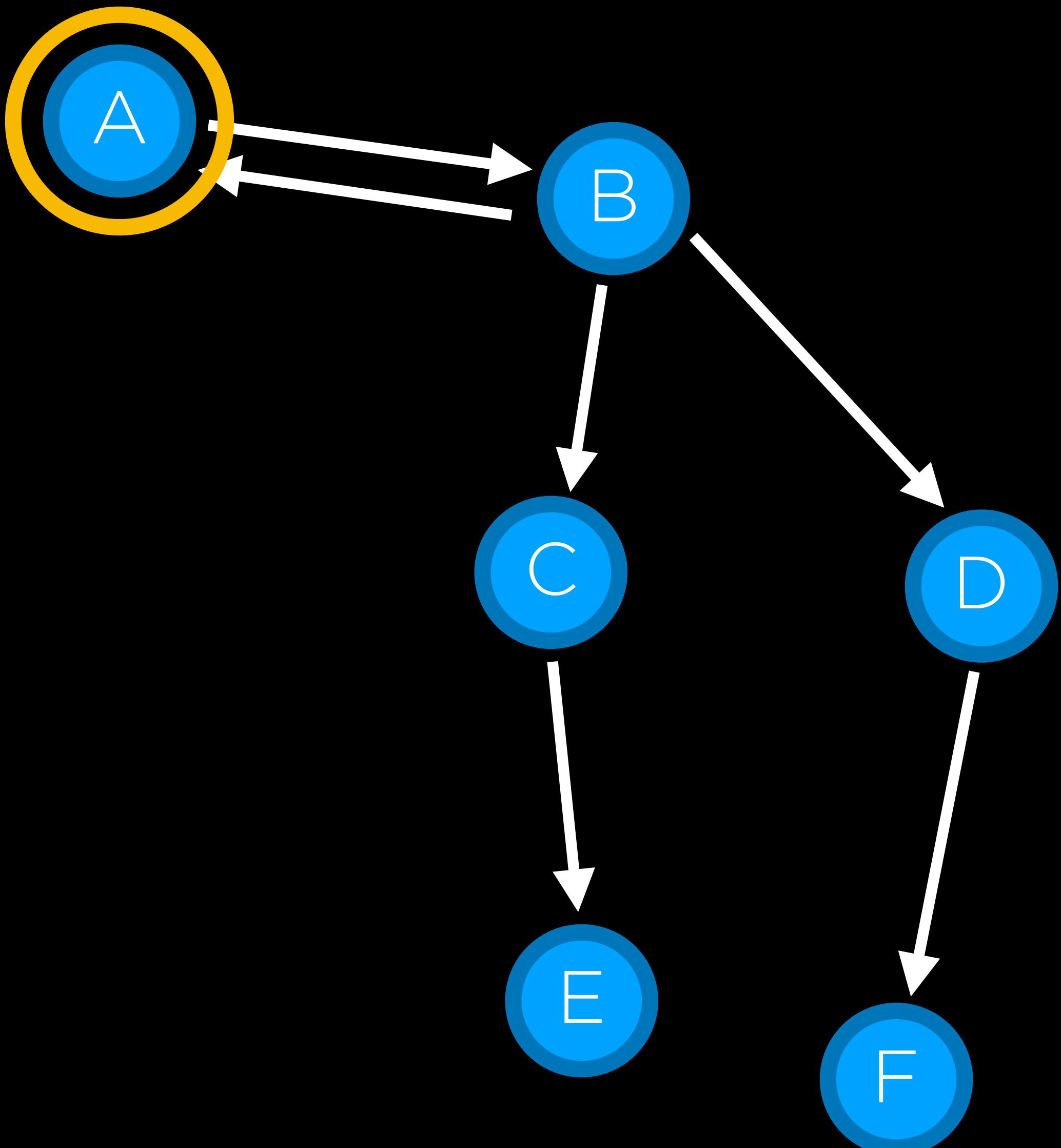
Find a path from A to E.



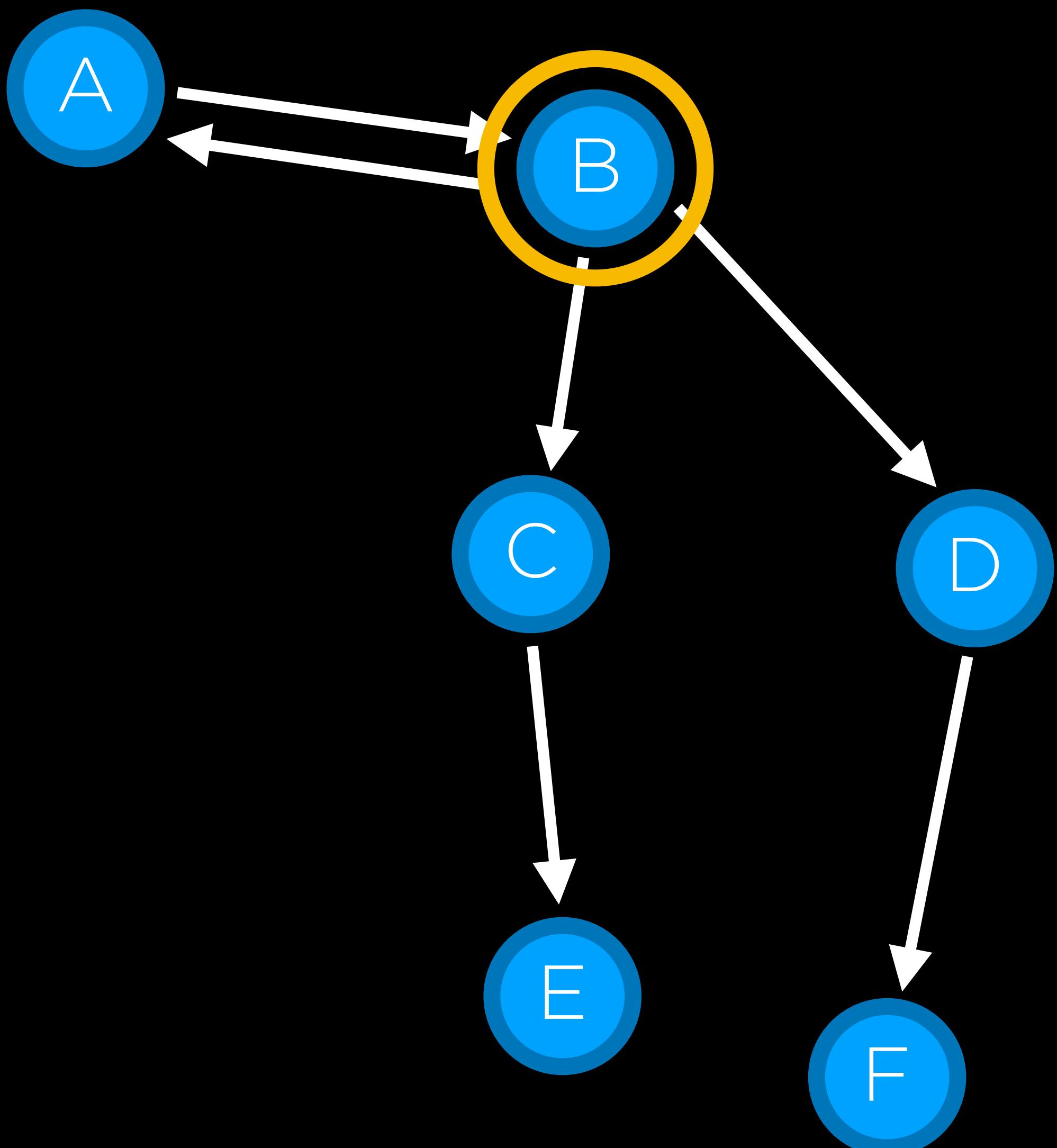
Find a path from A to E.



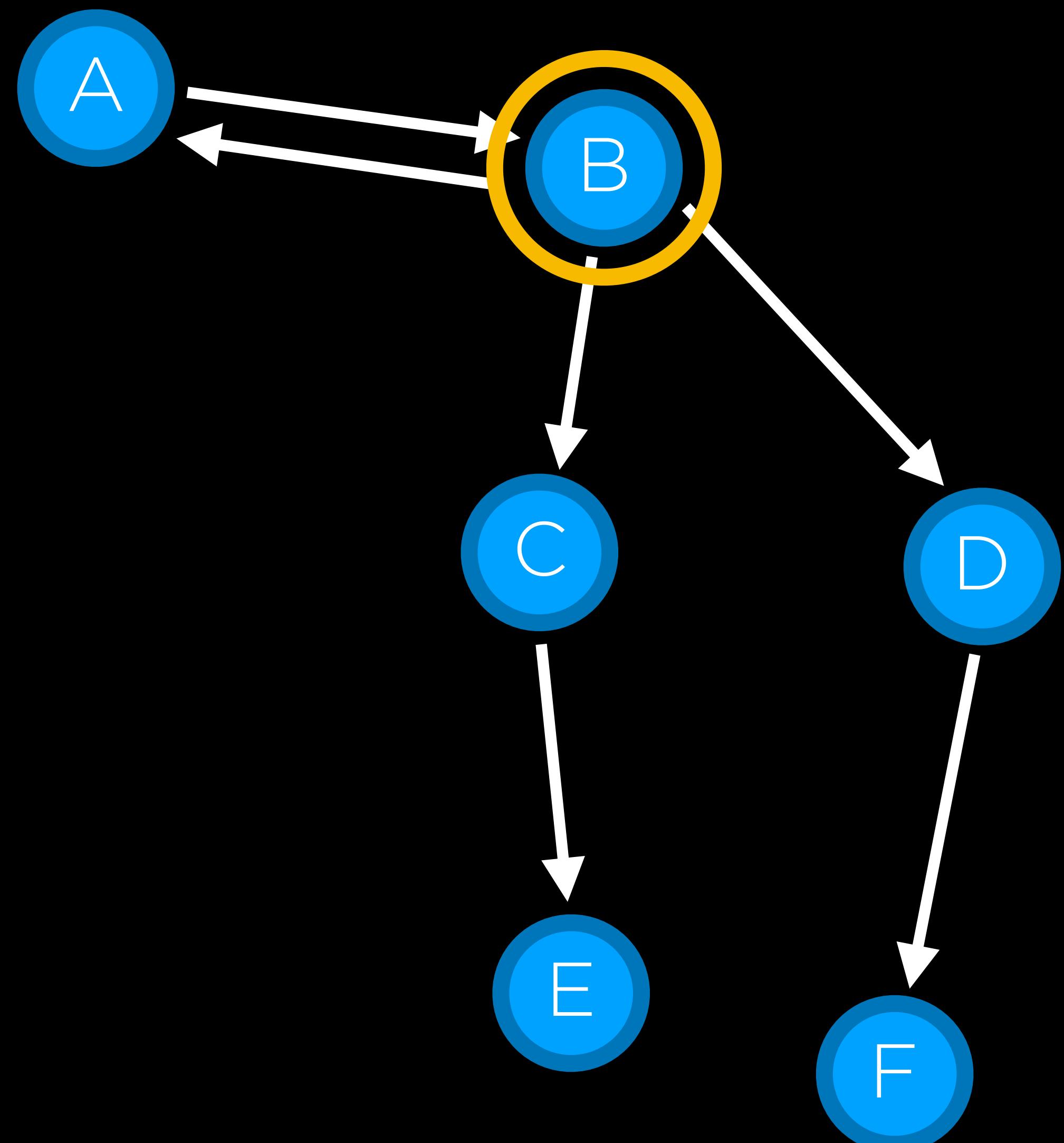
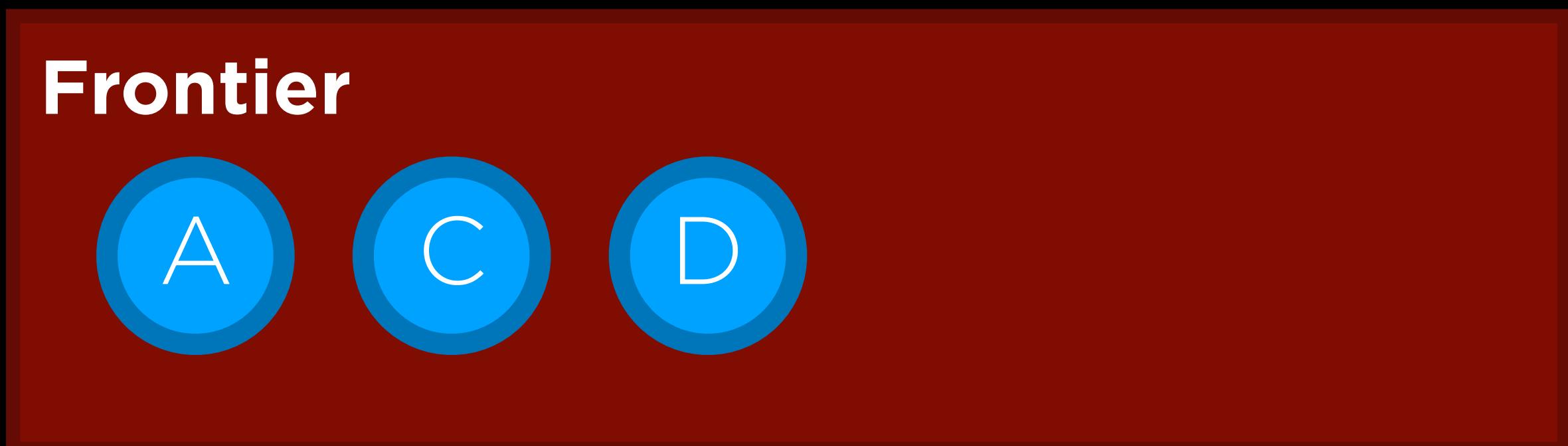
Find a path from A to E.



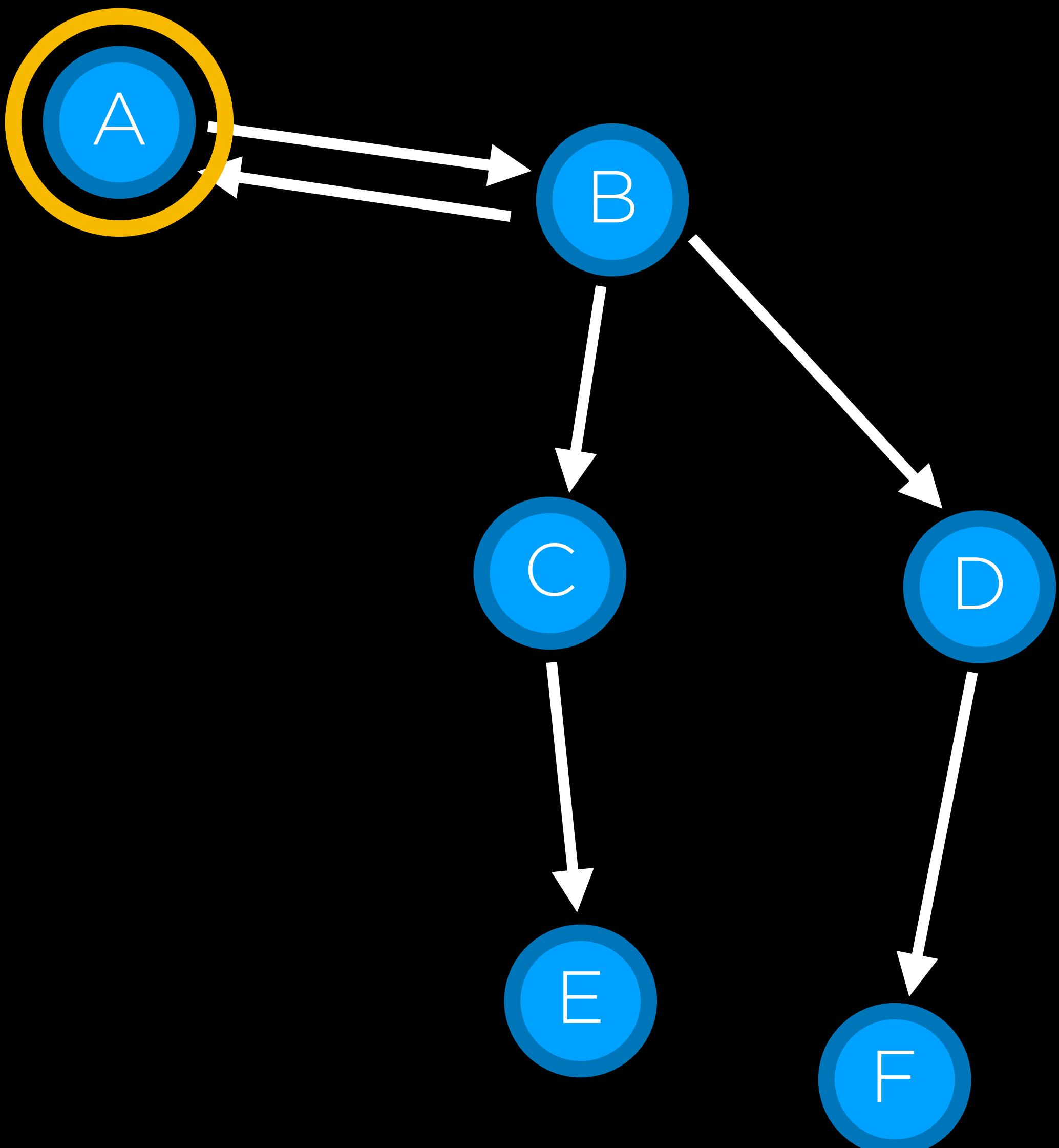
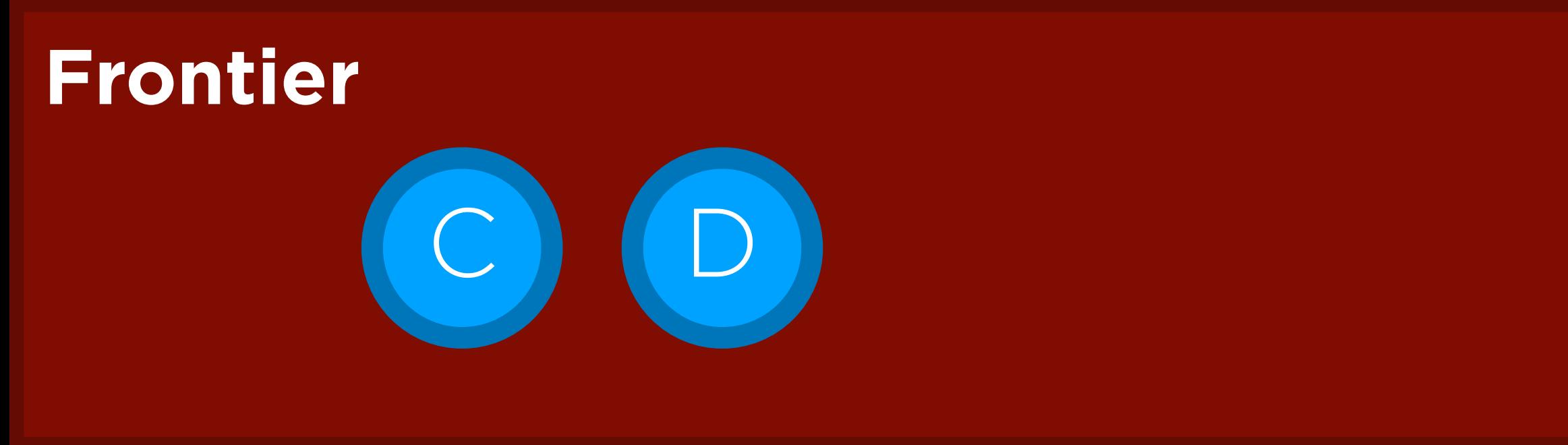
Find a path from A to E.



Find a path from A to E.



Find a path from A to E.



# Revised Approach

- Start with a **frontier** that contains the initial state.
- Start with an empty **explored set**.
- Repeat:
  - If the frontier is empty, then no solution.
  - Remove a node from the frontier.
  - If node contains goal state, return the solution.
  - Add the node to the explored set.
  - **Expand** node, add resulting nodes to the frontier if they aren't already in the frontier or the explored set.

# Revised Approach

- Start with a **frontier** that contains the initial state.
- Start with an empty **explored set**.
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  - **Expand** node, add resulting nodes to the frontier if they aren't already in the frontier or the explored set.

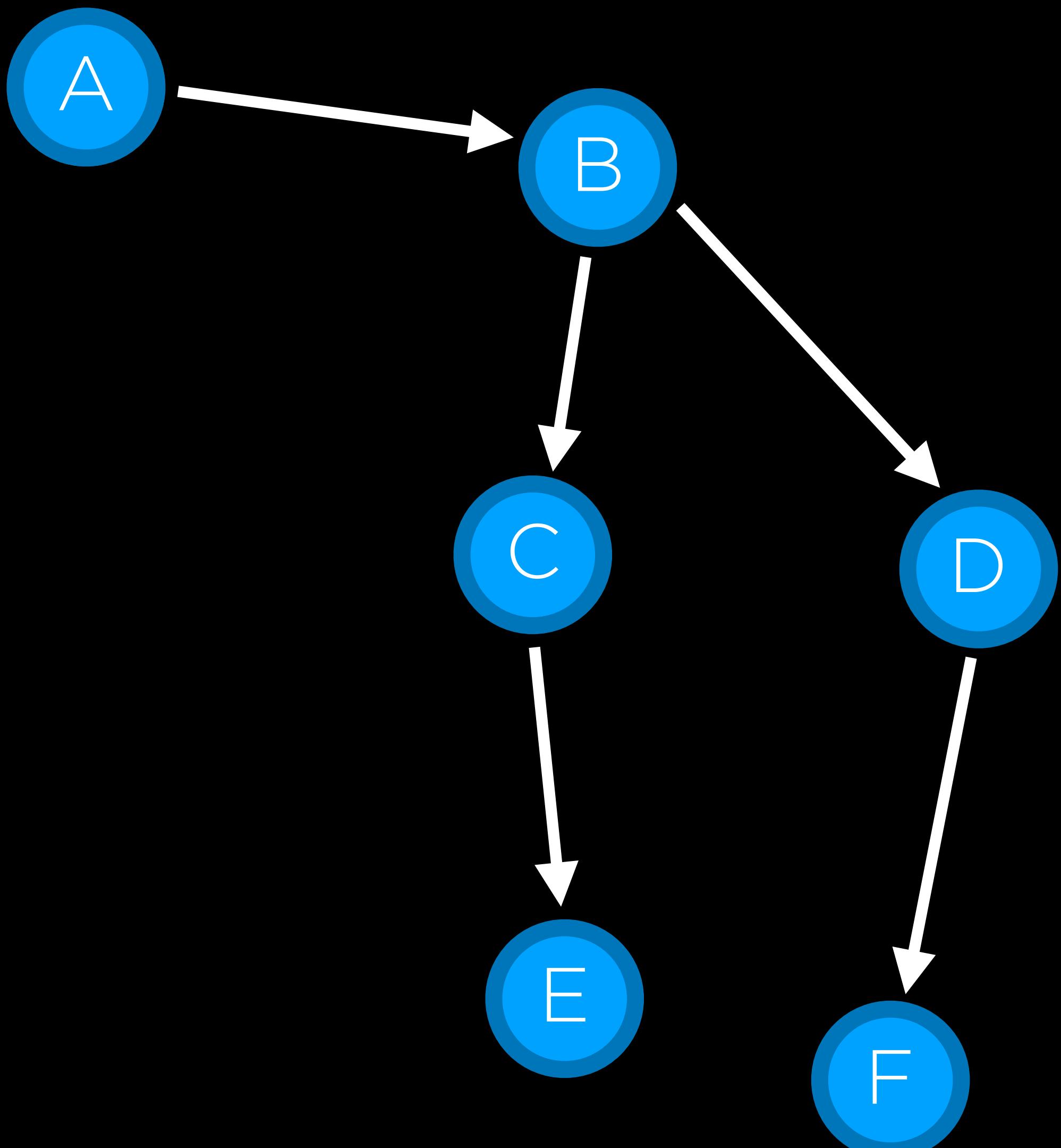
# stack

last-in first-out data type

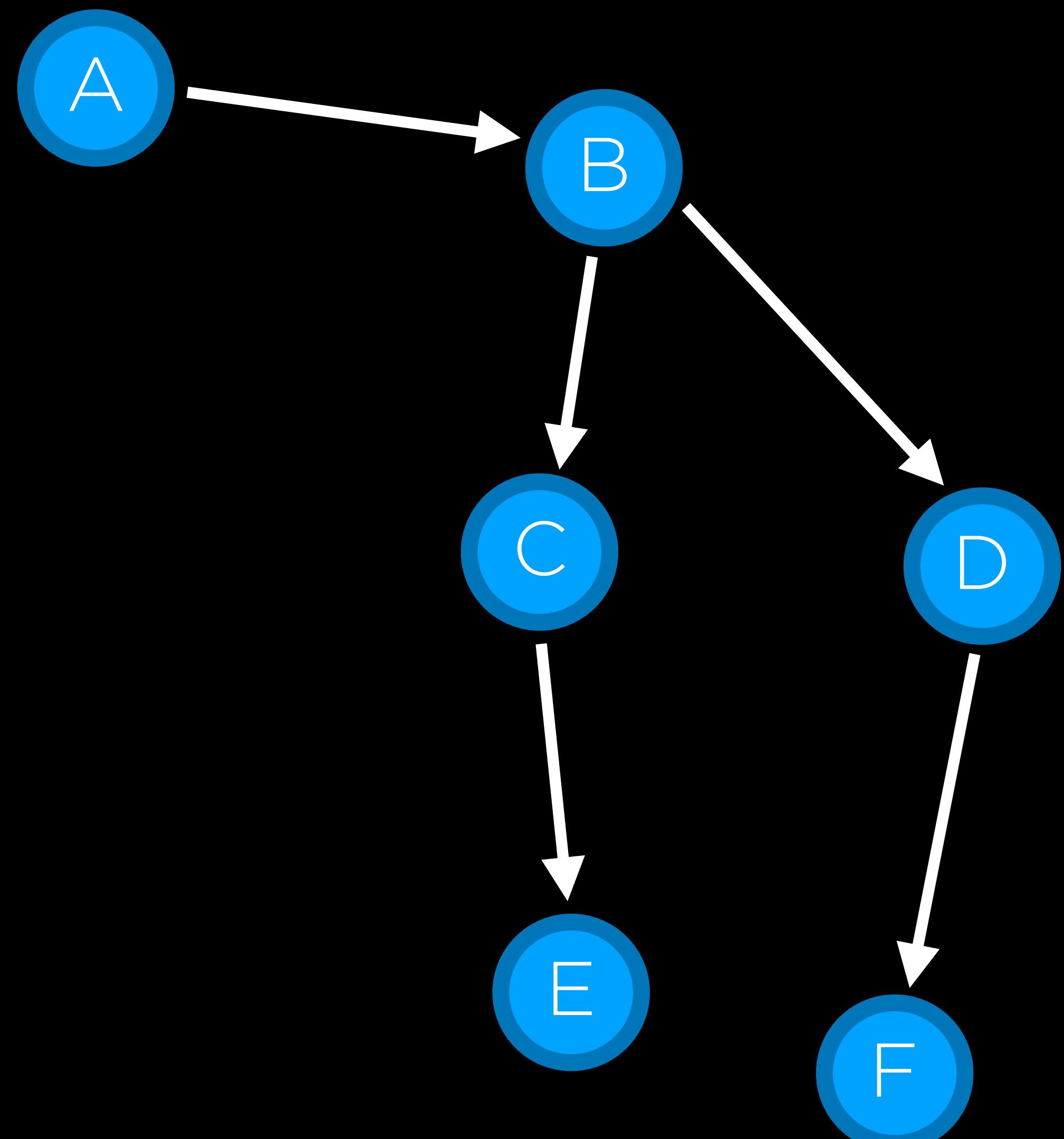
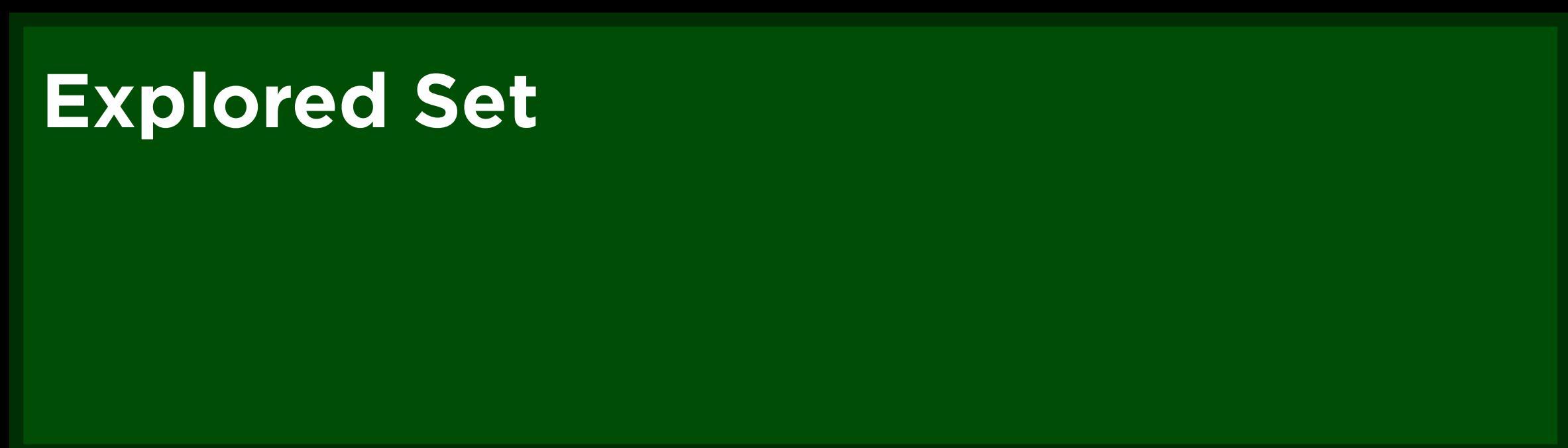
Find a path from A to E.

**Frontier**

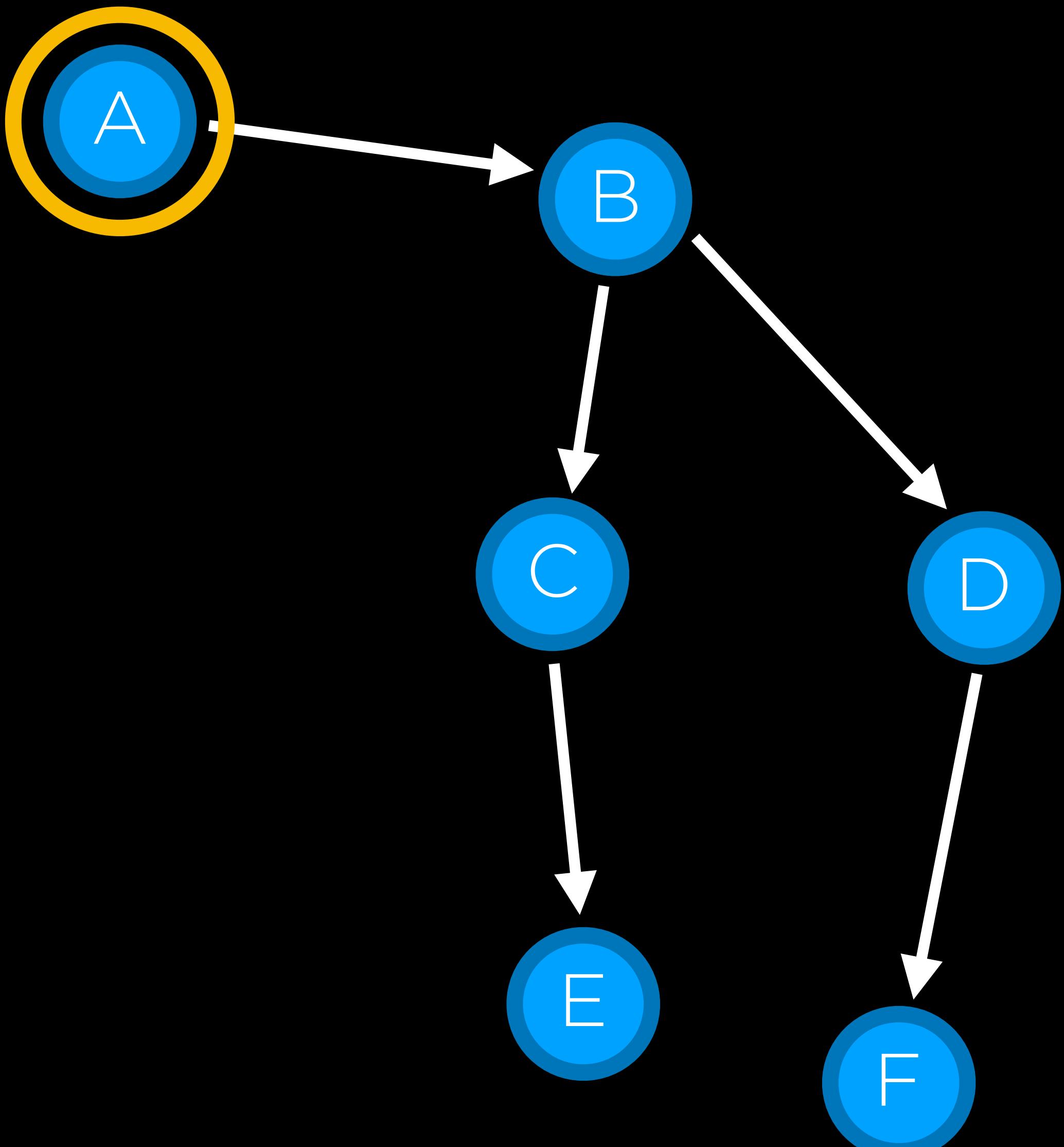
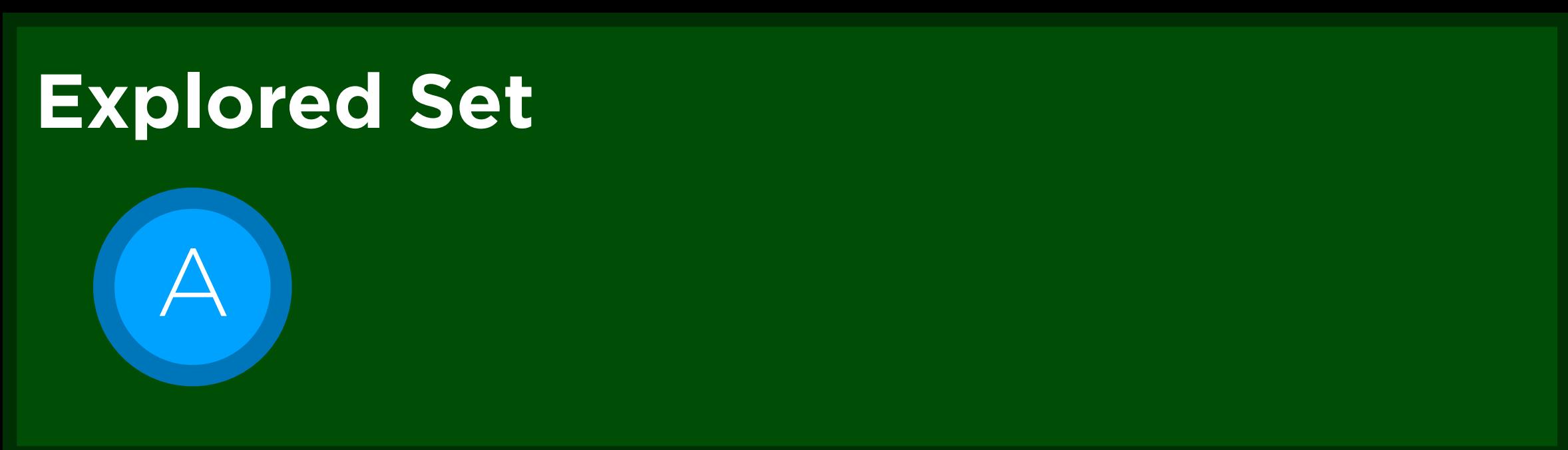
**Explored Set**



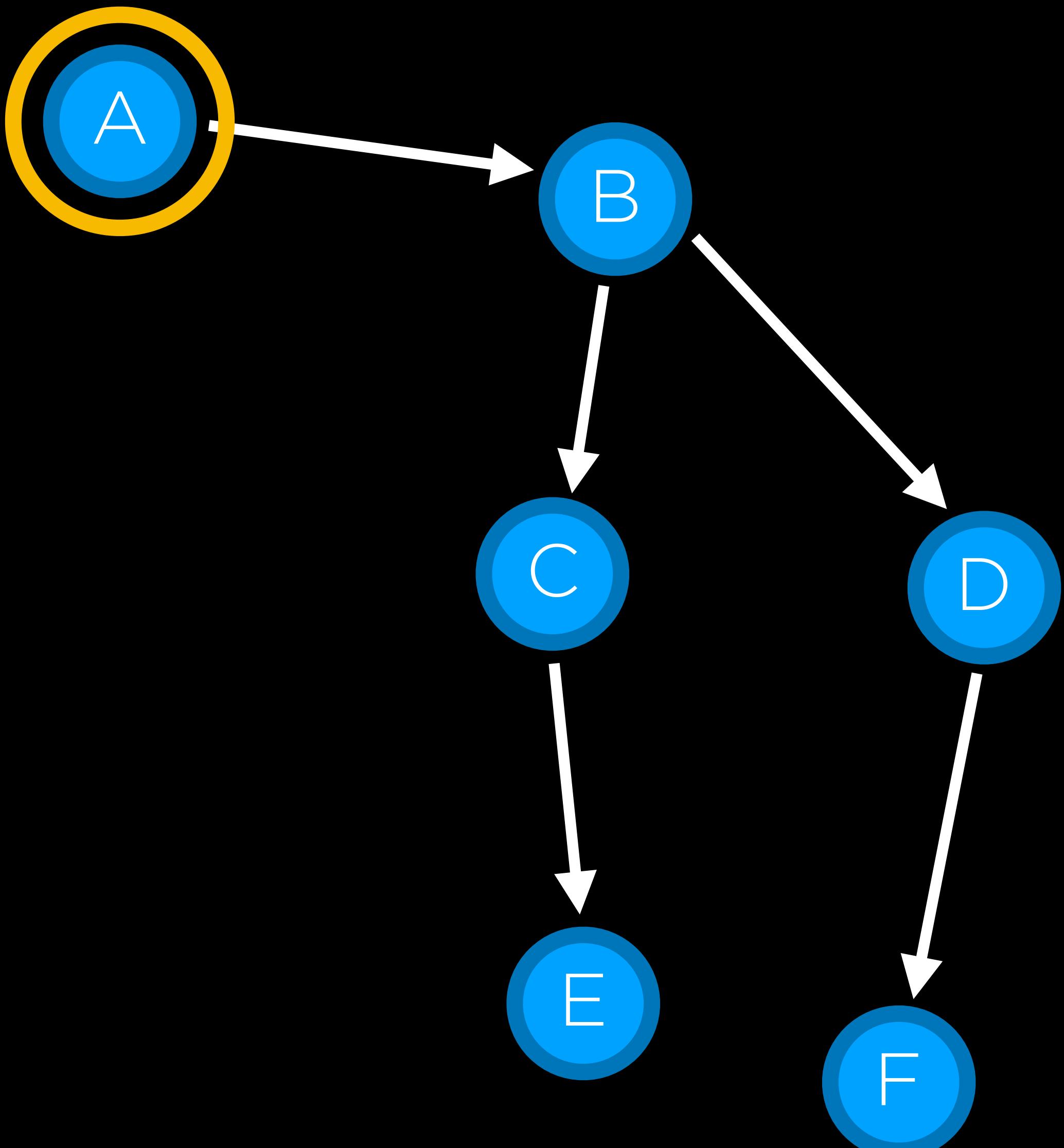
Find a path from A to E.



Find a path from A to E.



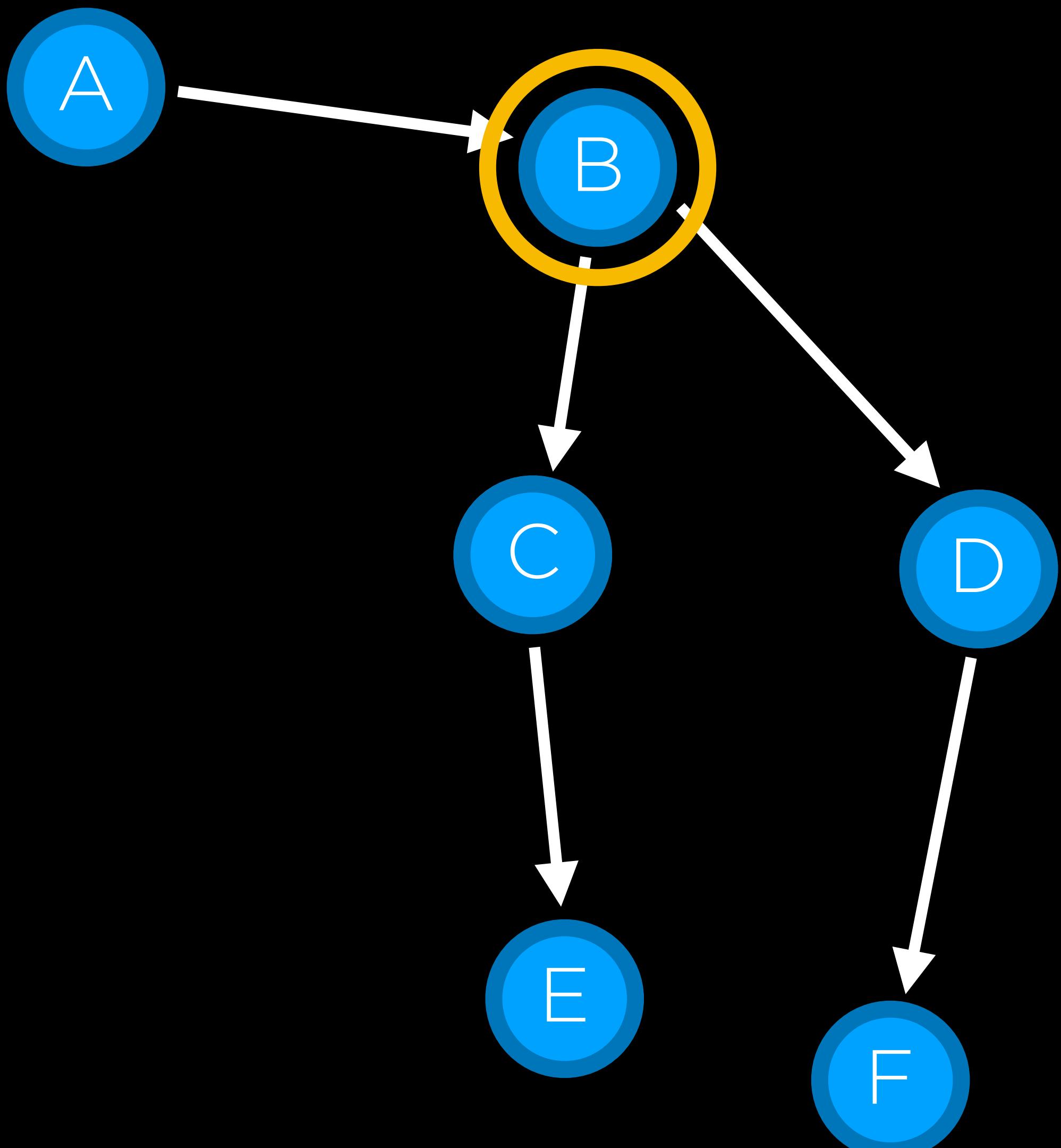
Find a path from A to E.



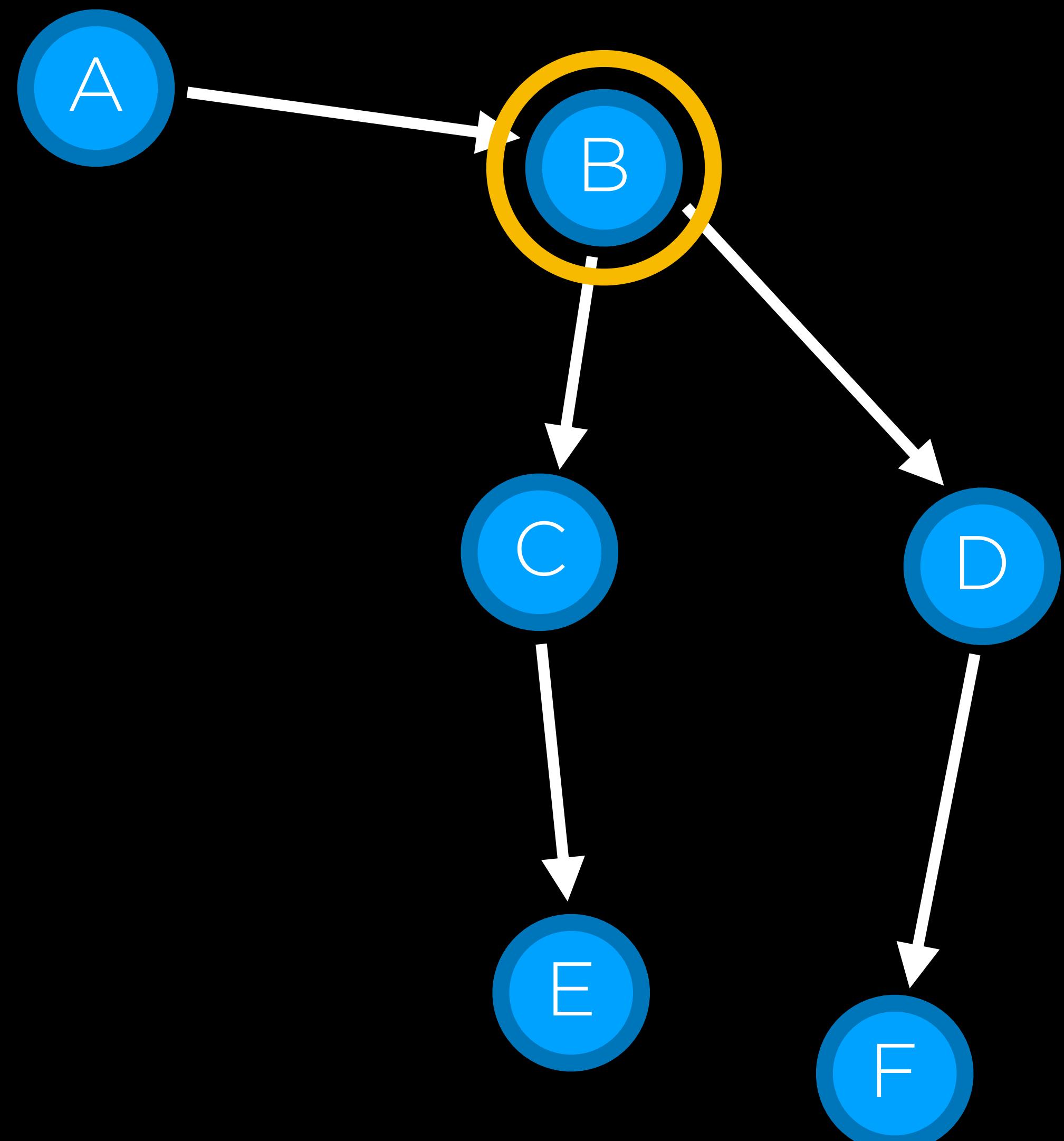
Find a path from A to E.

**Frontier**

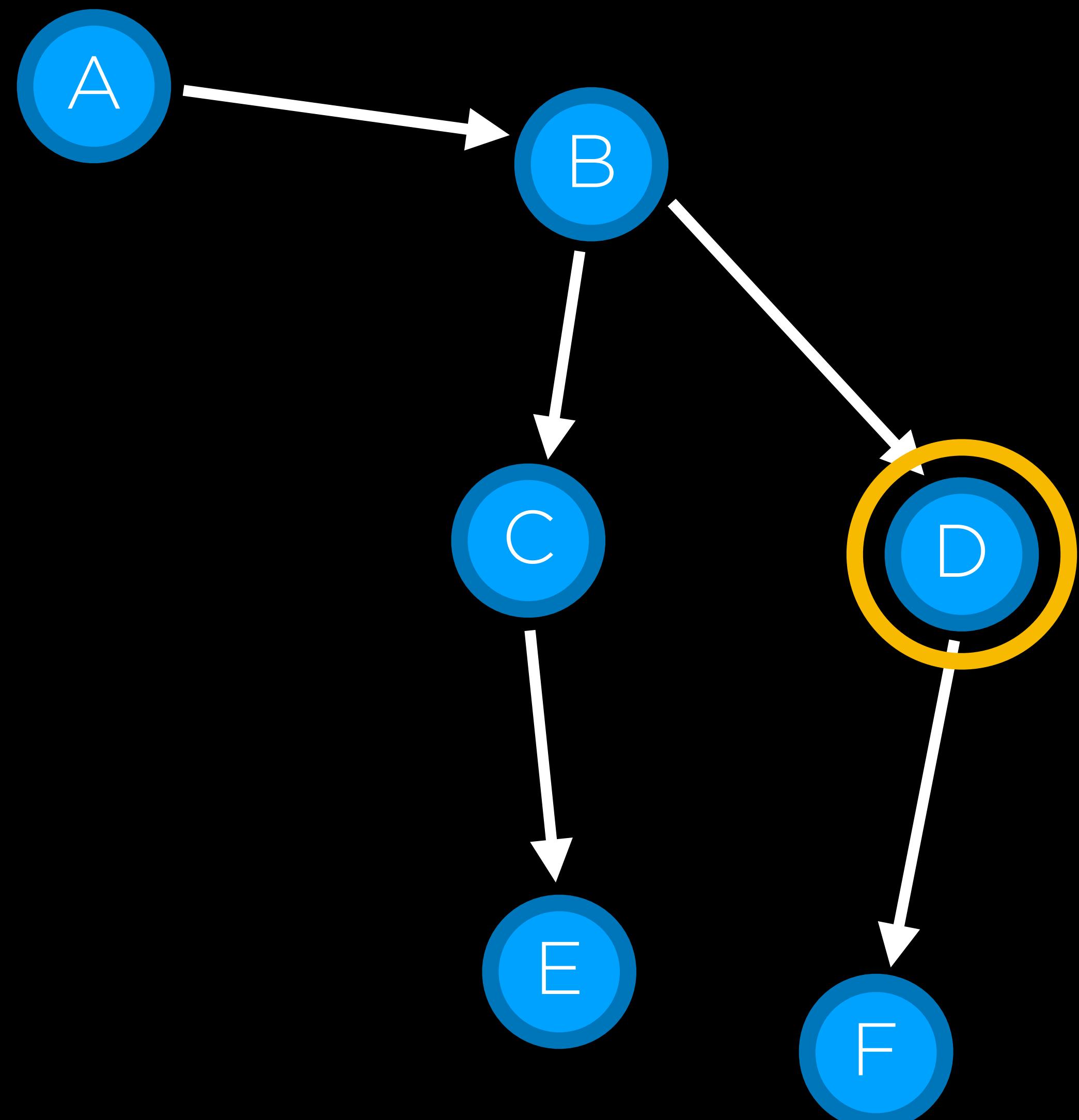
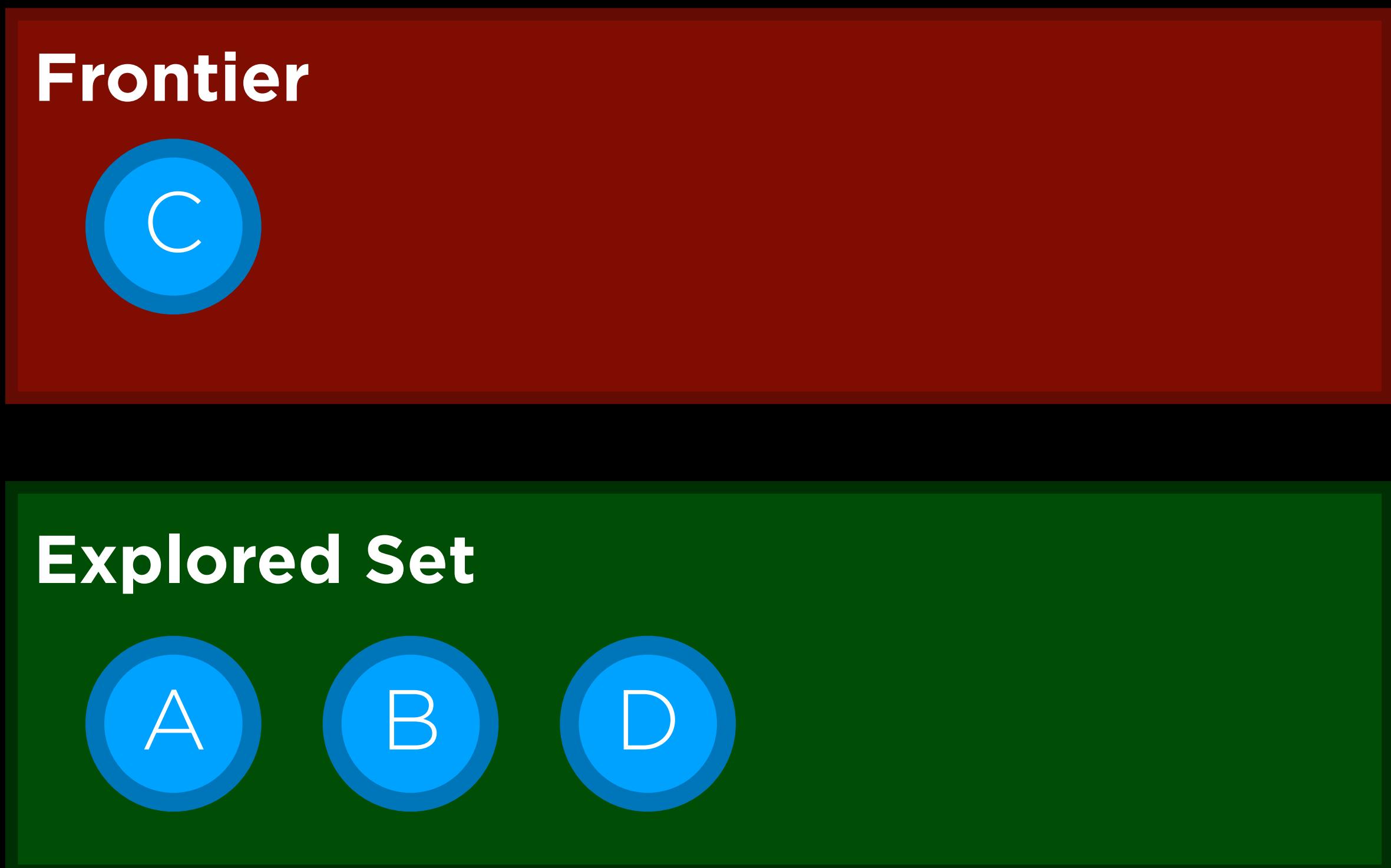
**Explored Set**



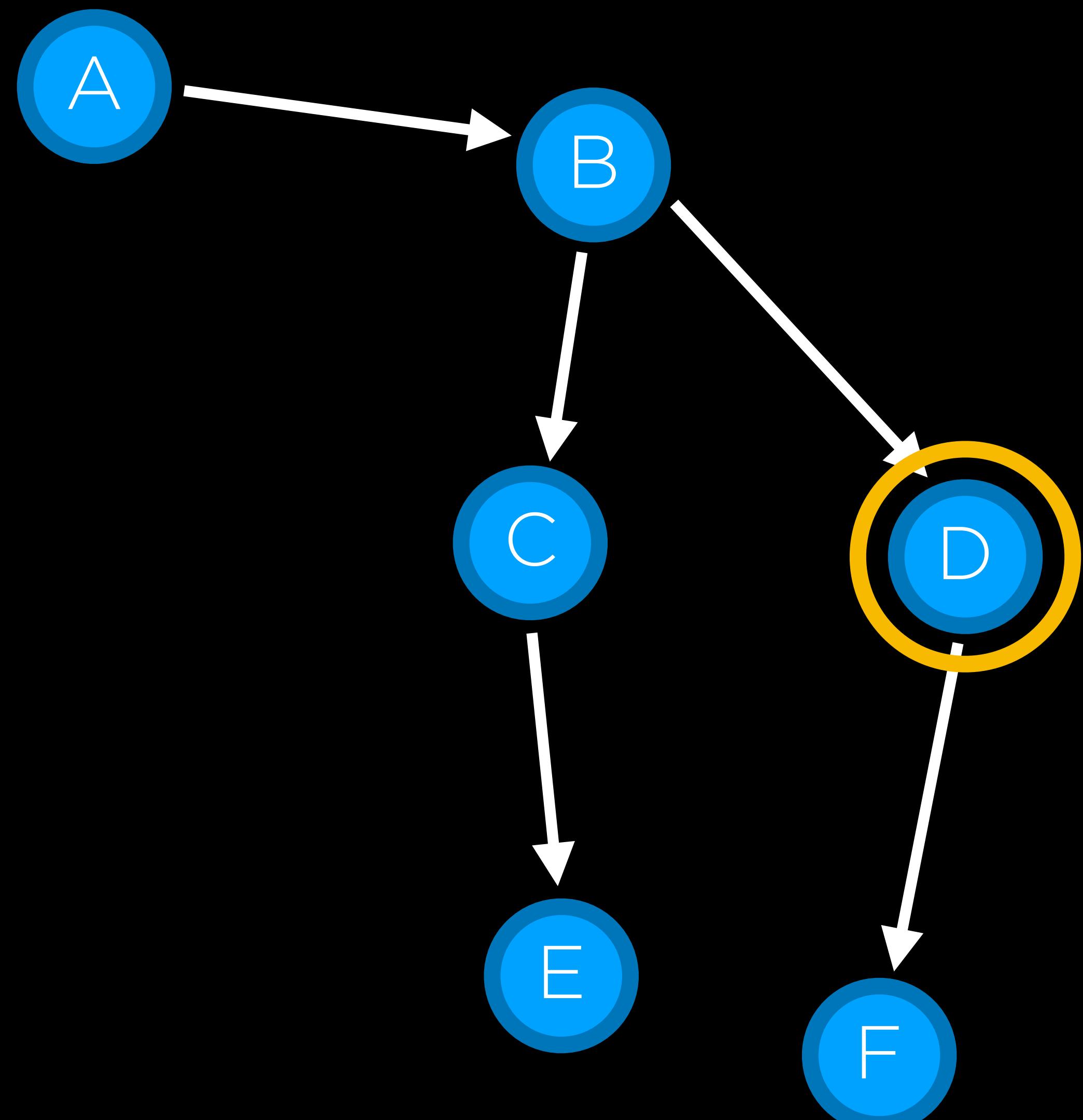
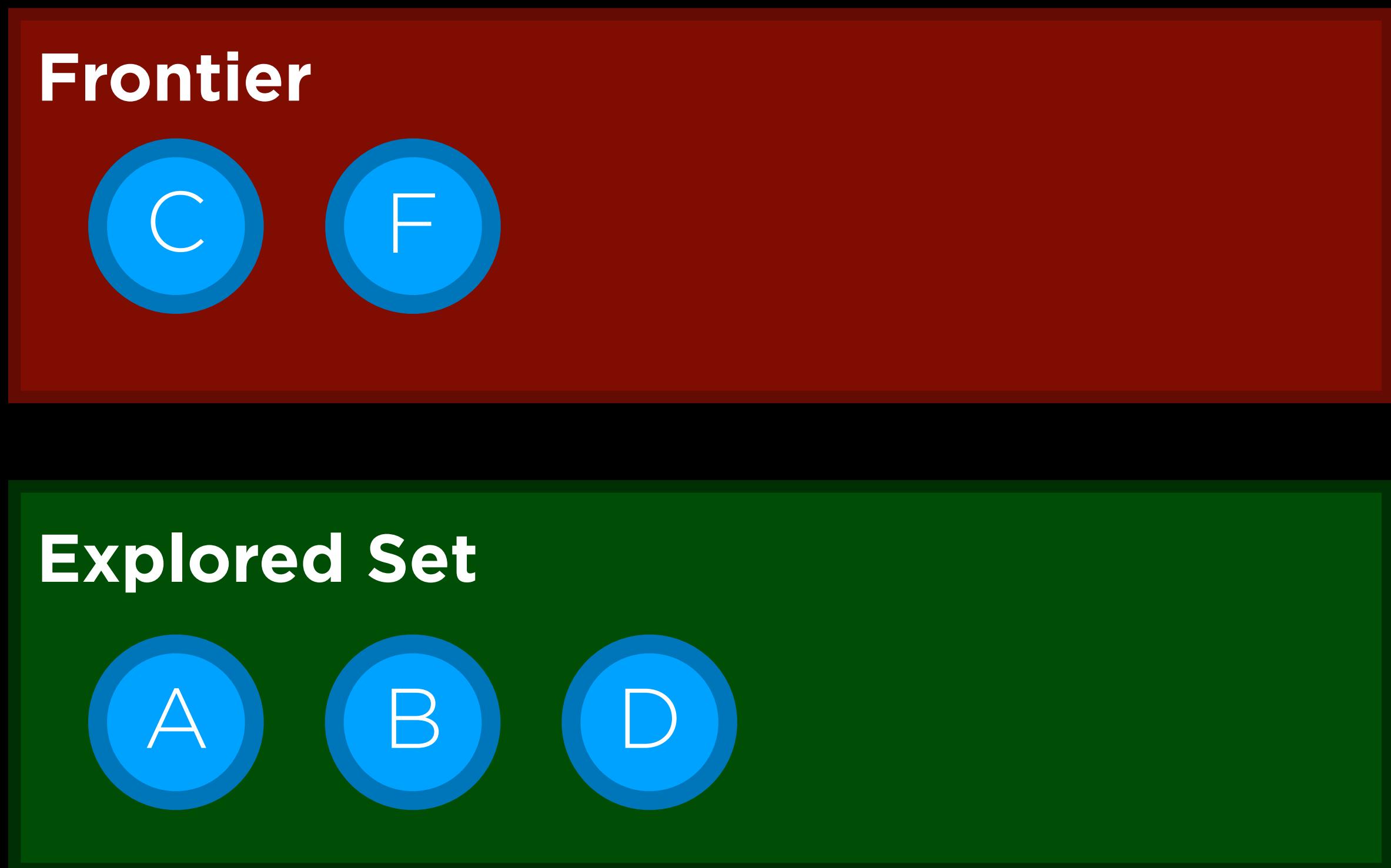
Find a path from A to E.



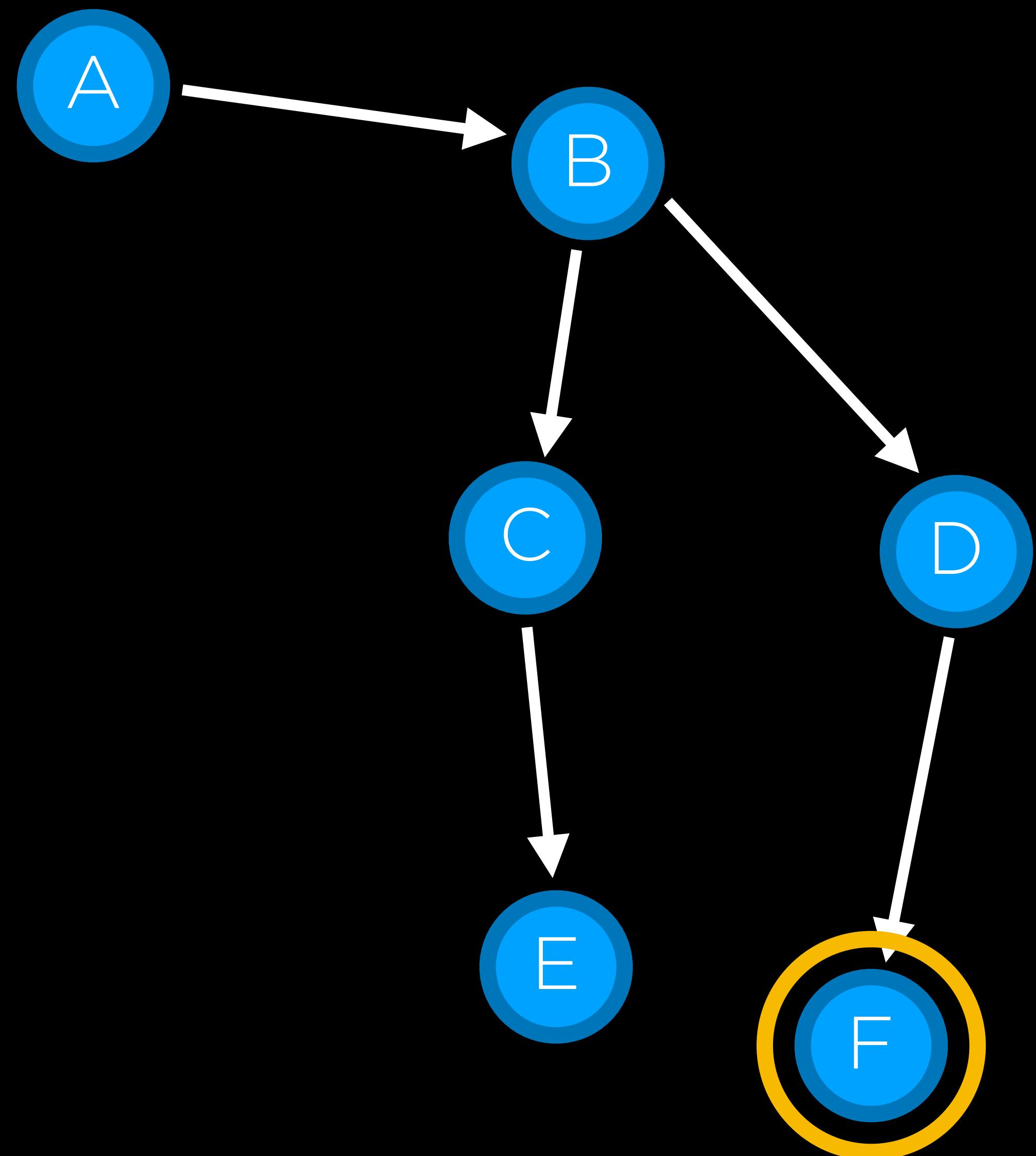
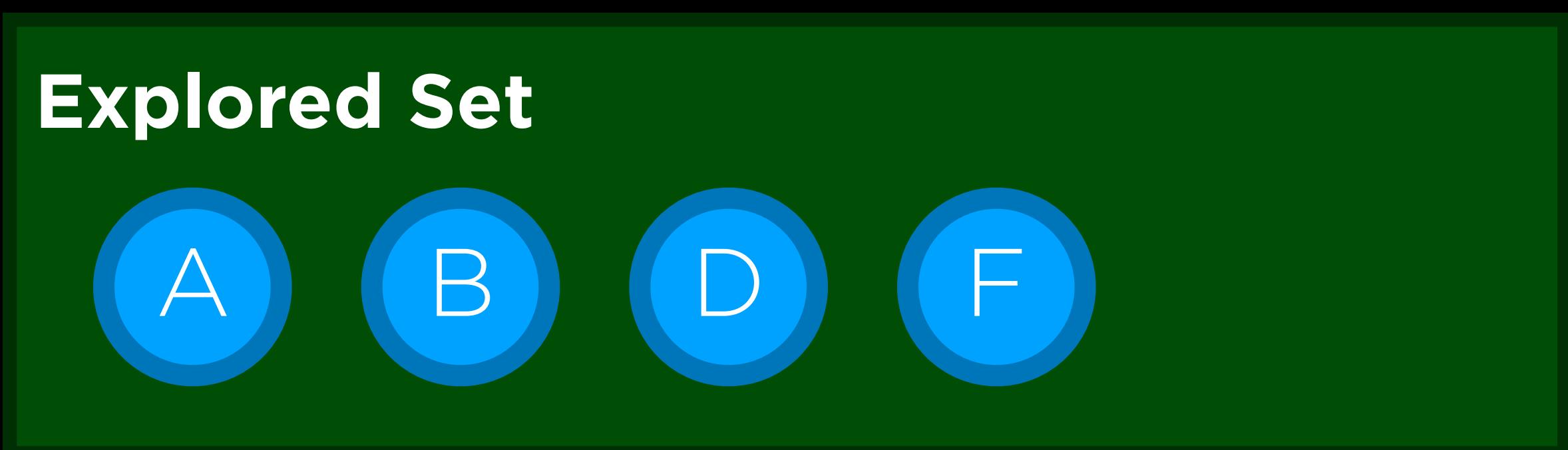
Find a path from A to E.



Find a path from A to E.



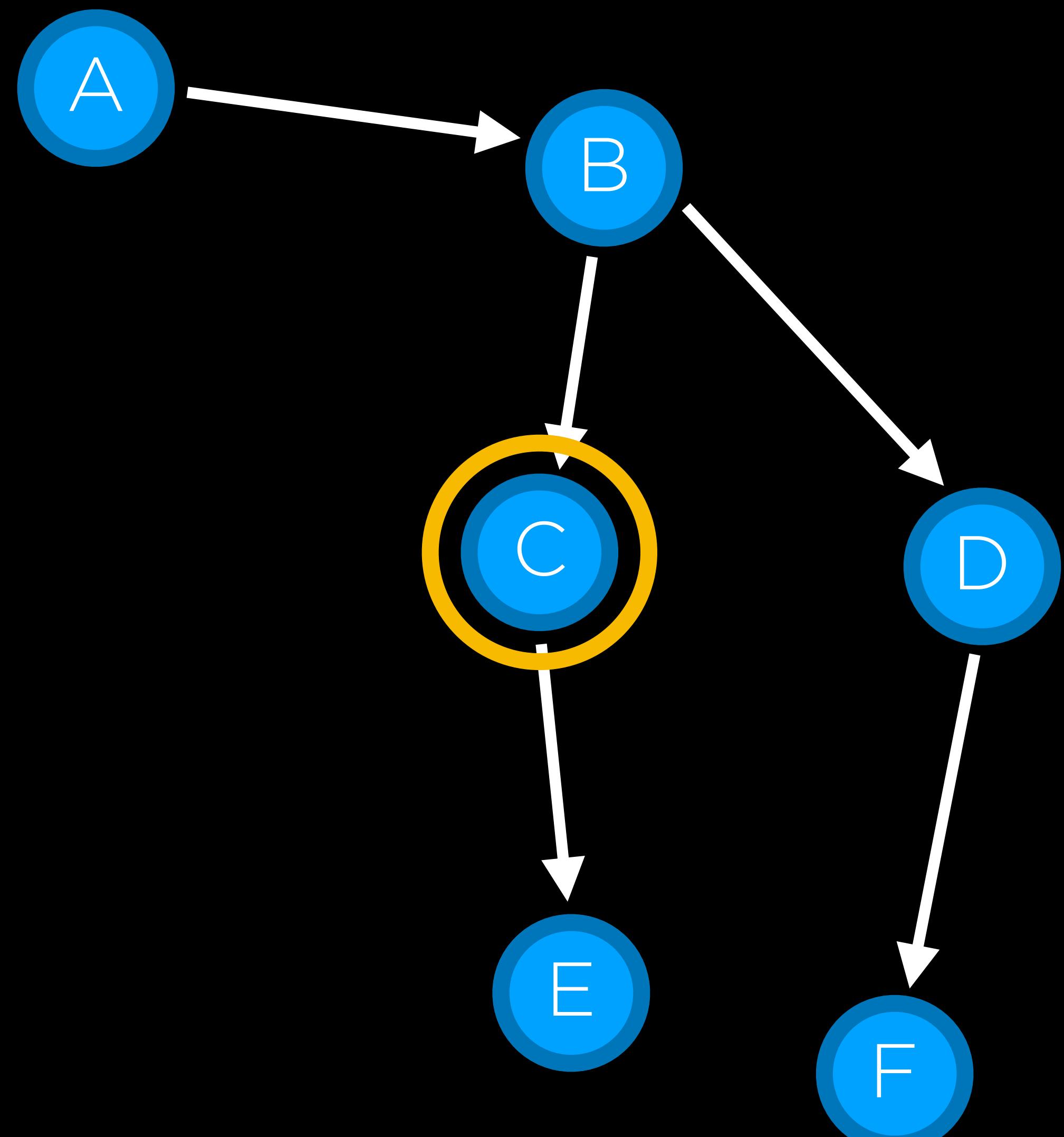
Find a path from A to E.



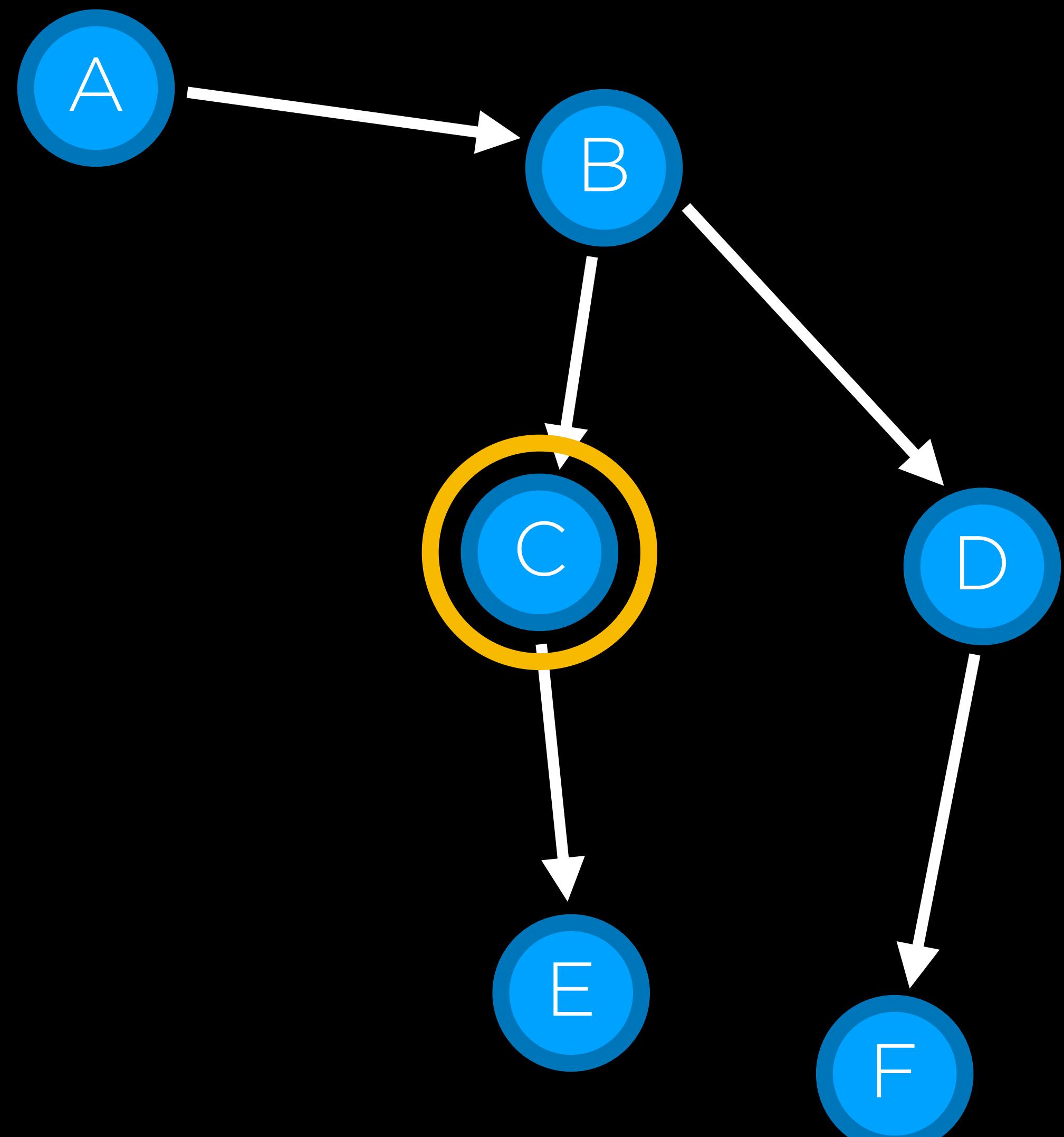
Find a path from A to E.

**Frontier**

**Explored Set**



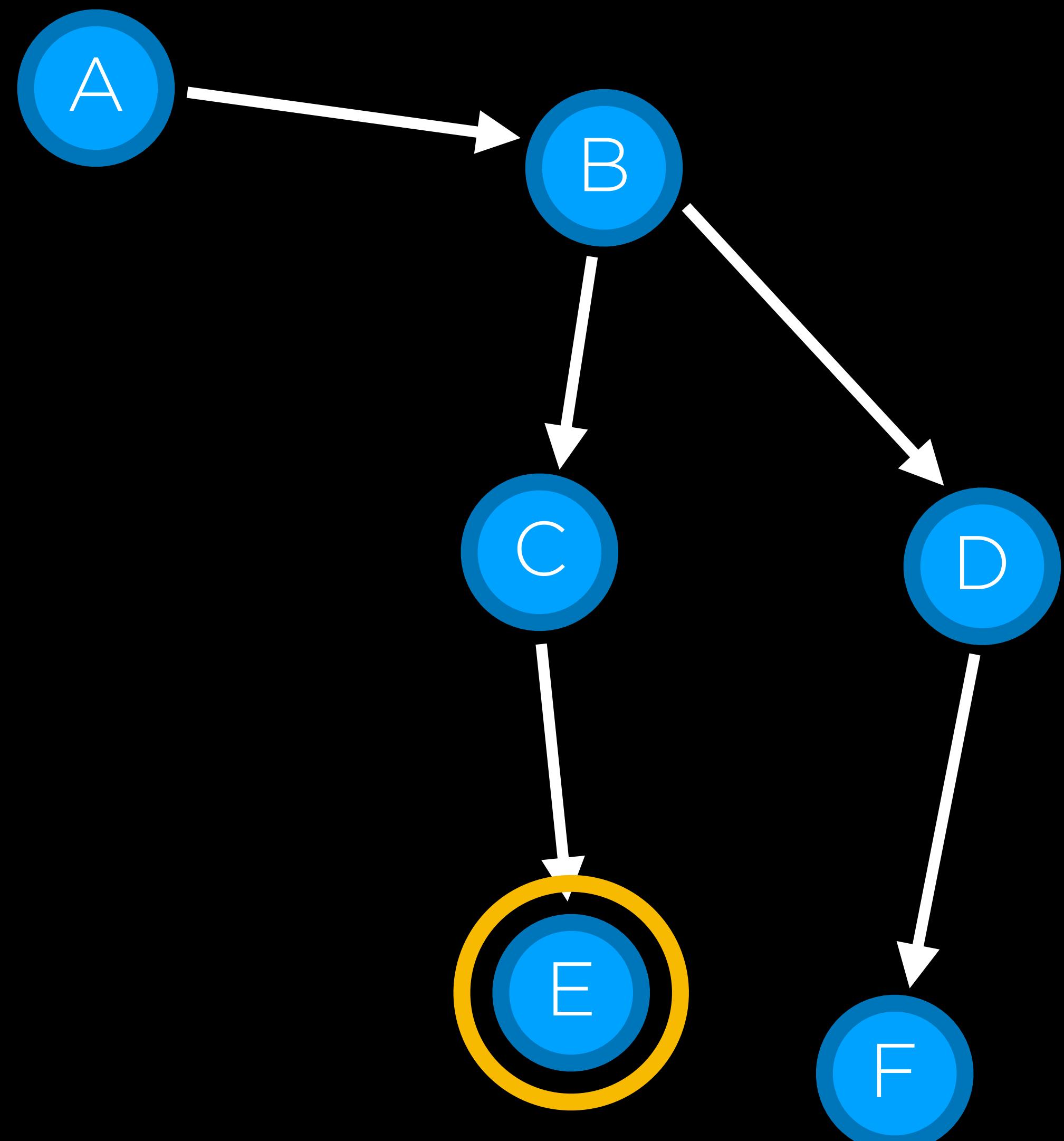
Find a path from A to E.



Find a path from A to E.

**Frontier**

**Explored Set**



# Depth-First Search

# depth-first search

search algorithm that always expands the deepest node in the frontier

# Breadth-First Search

# breadth-first search

search algorithm that always expands the shallowest node in the frontier

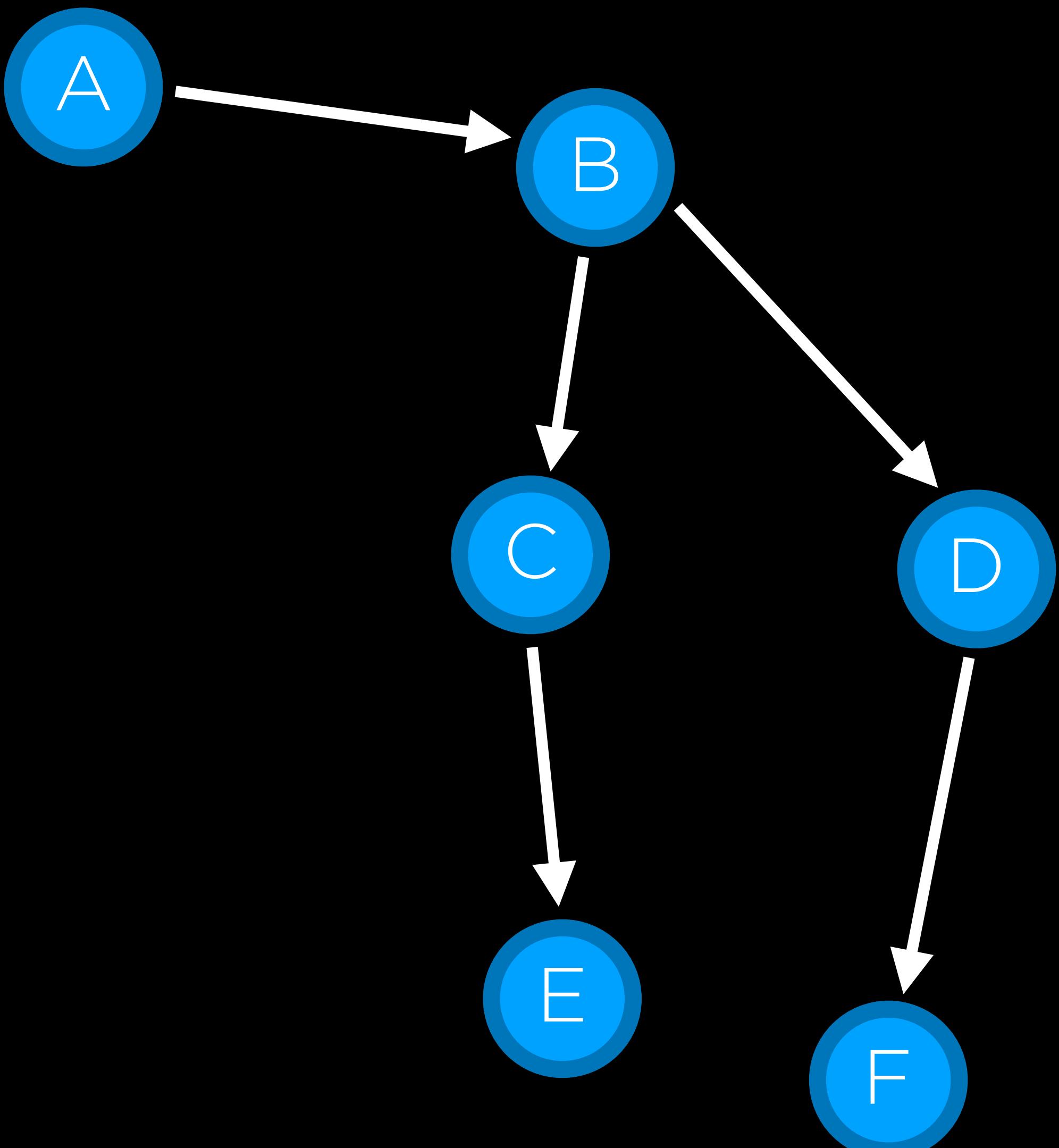
# queue

first-in first-out data type

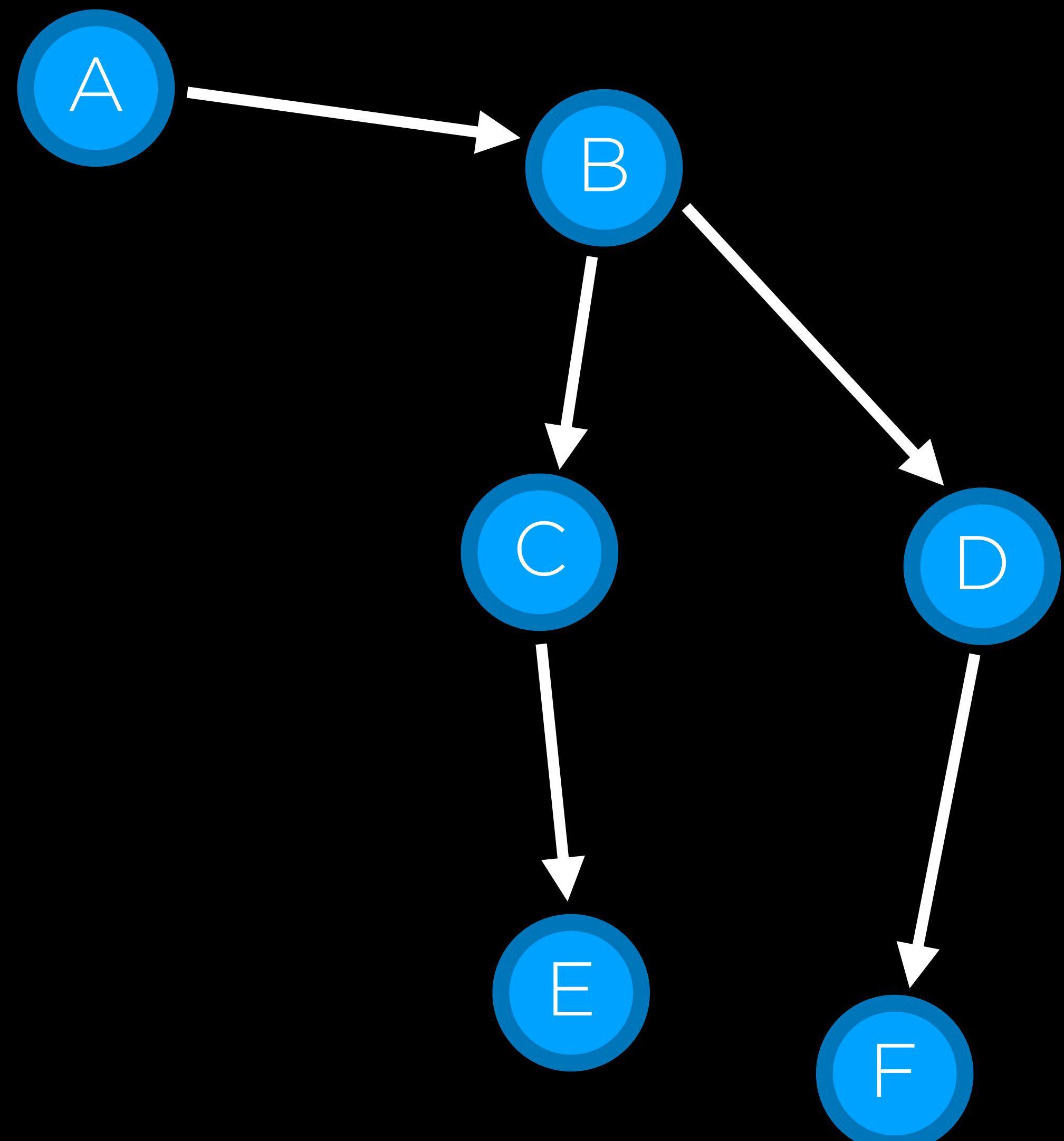
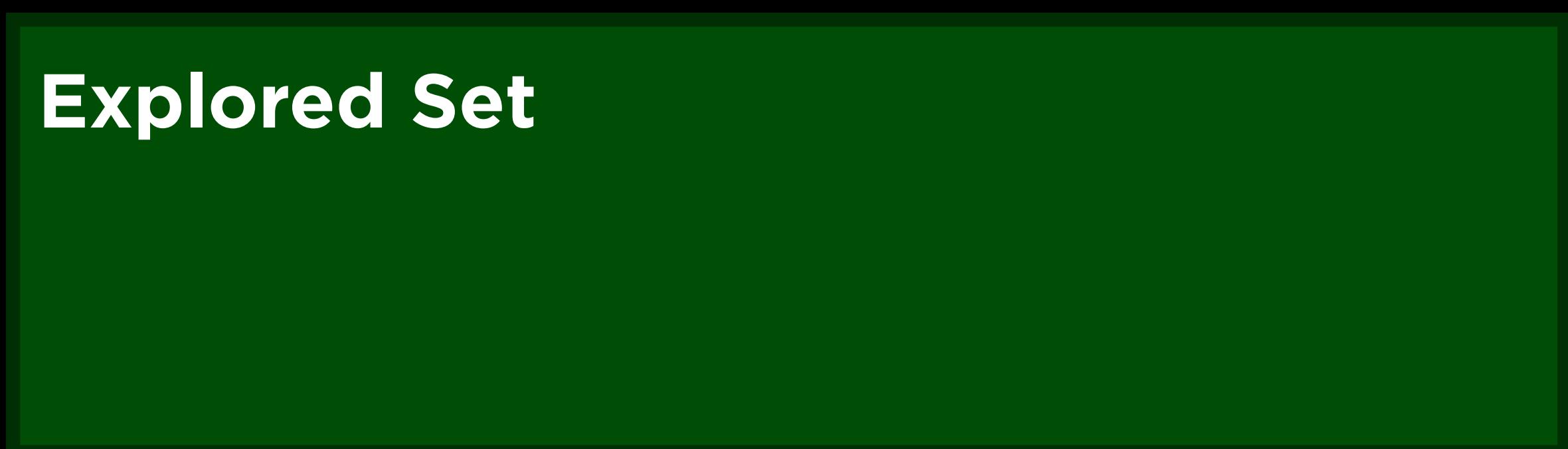
Find a path from A to E.

**Frontier**

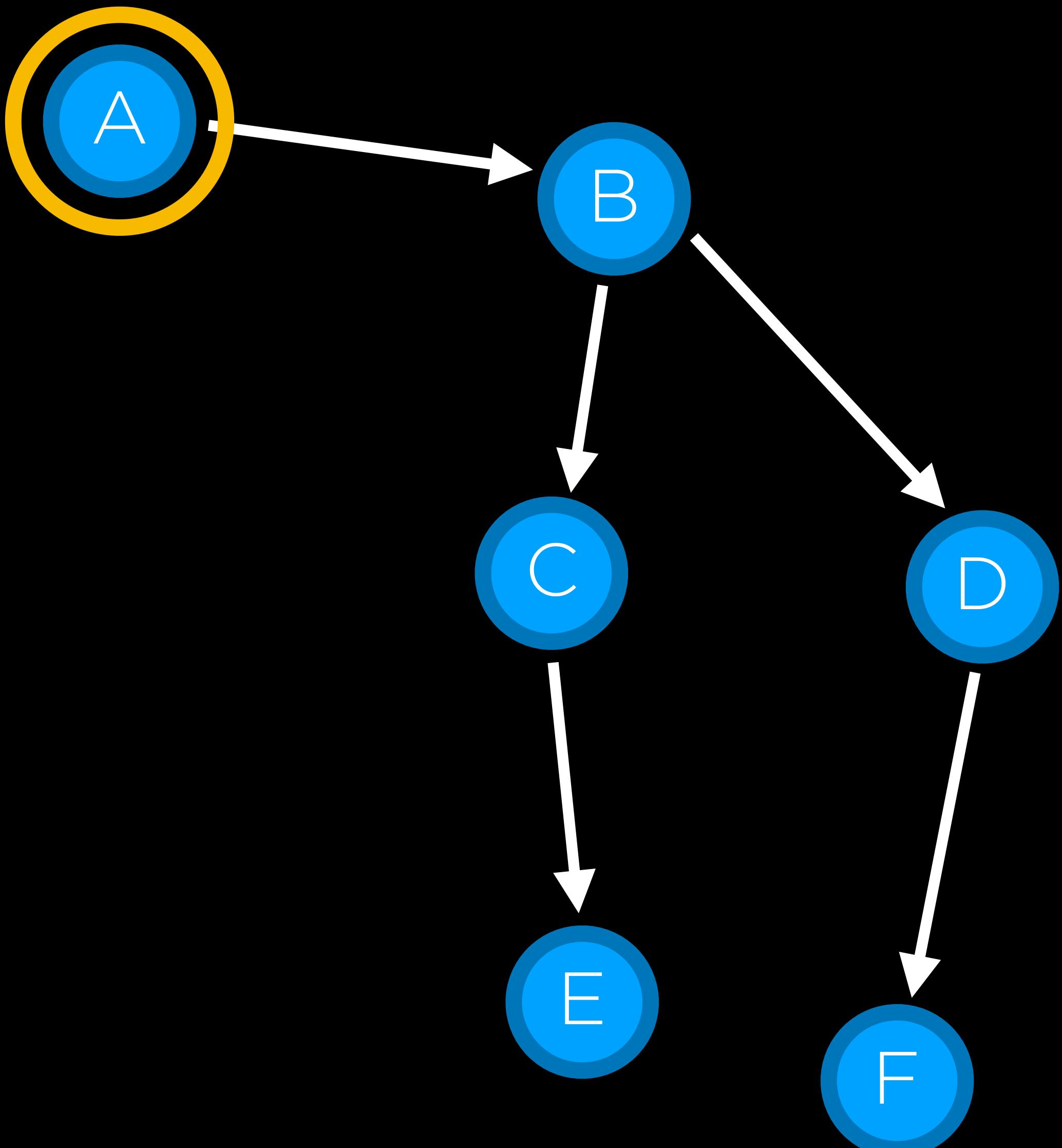
**Explored Set**



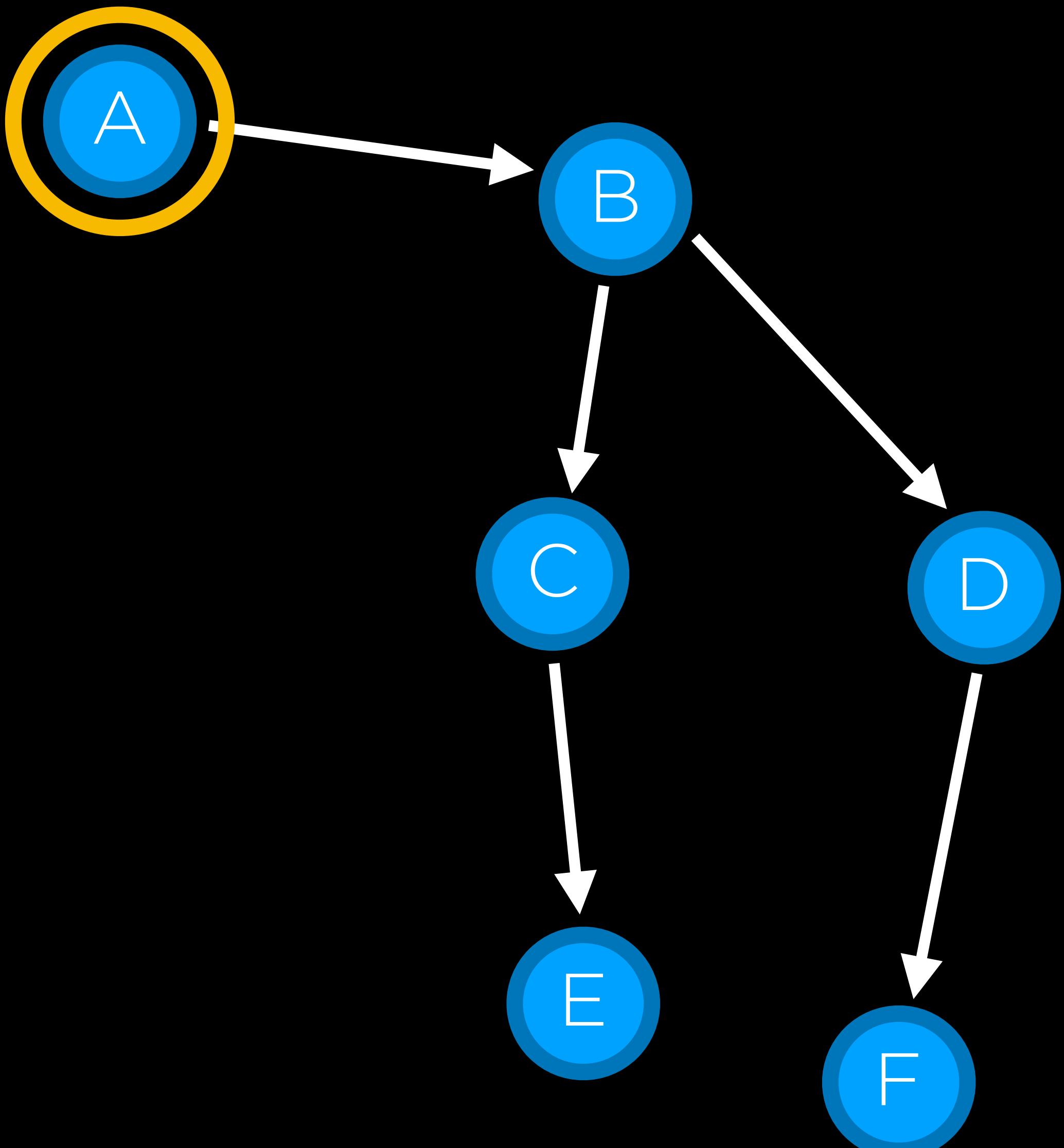
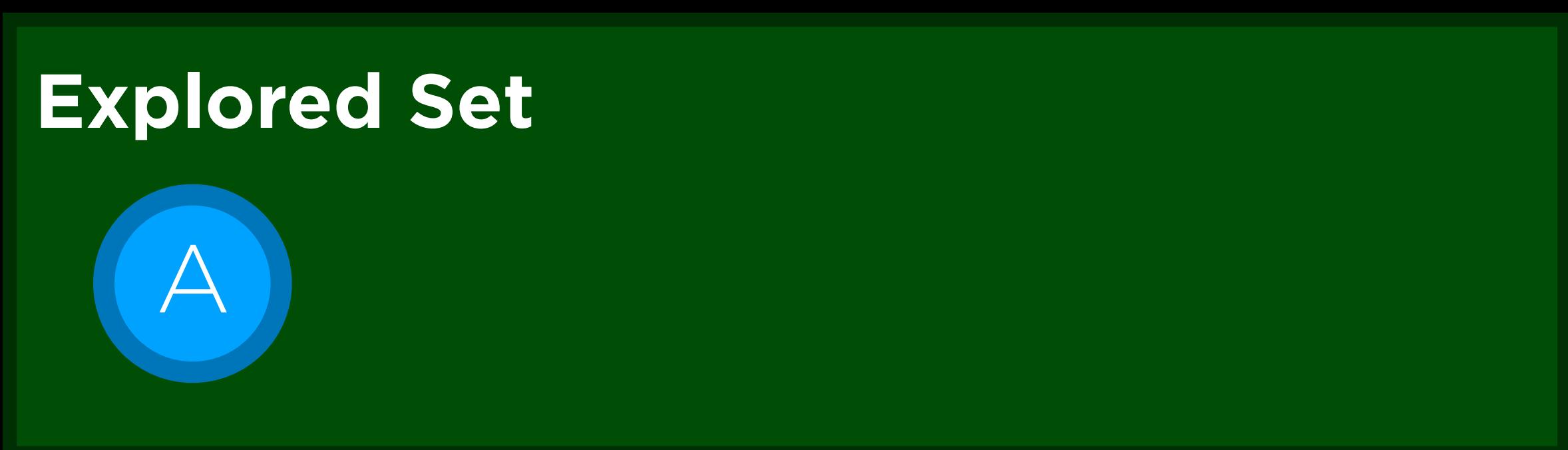
Find a path from A to E.



Find a path from A to E.



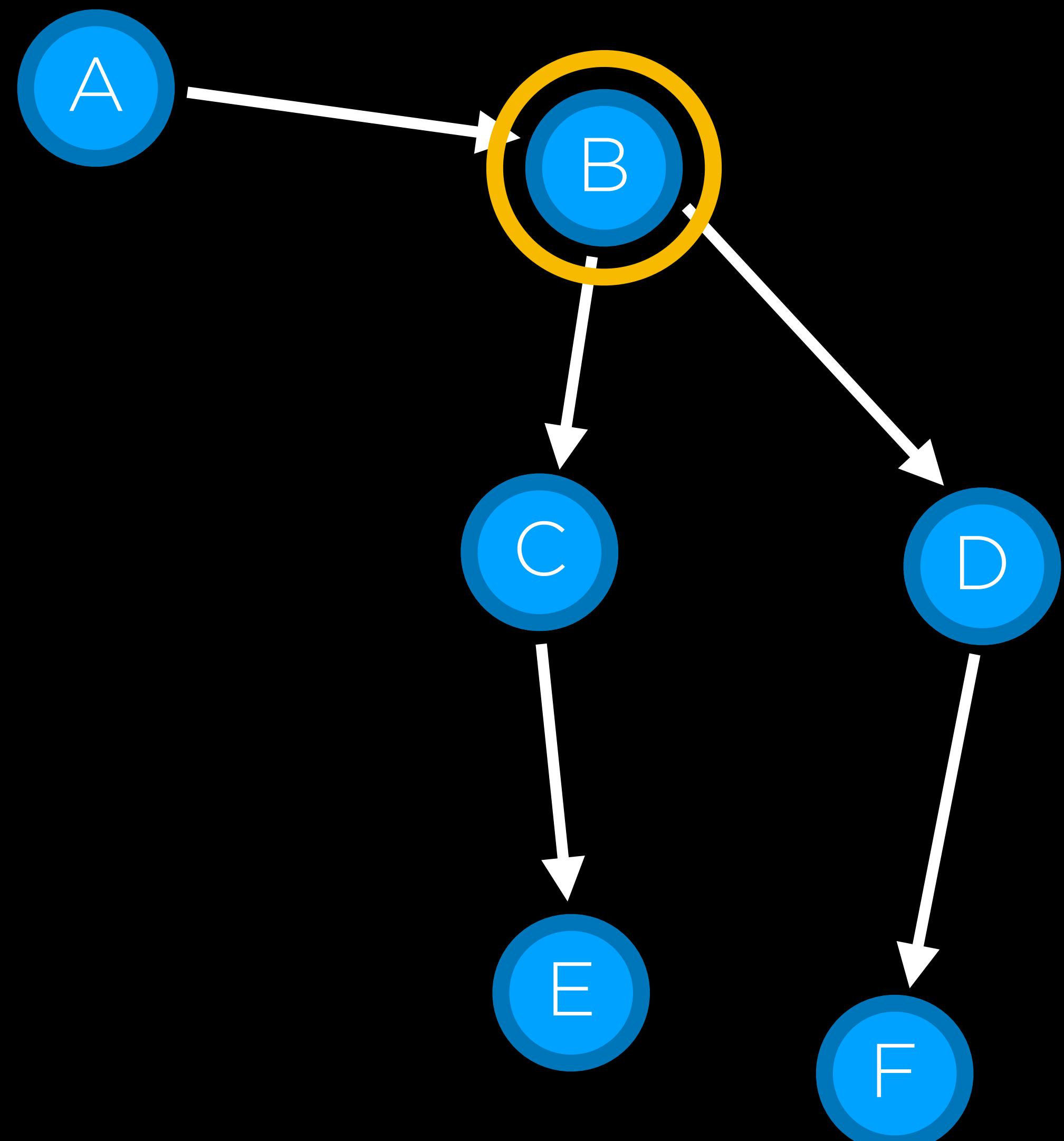
Find a path from A to E.



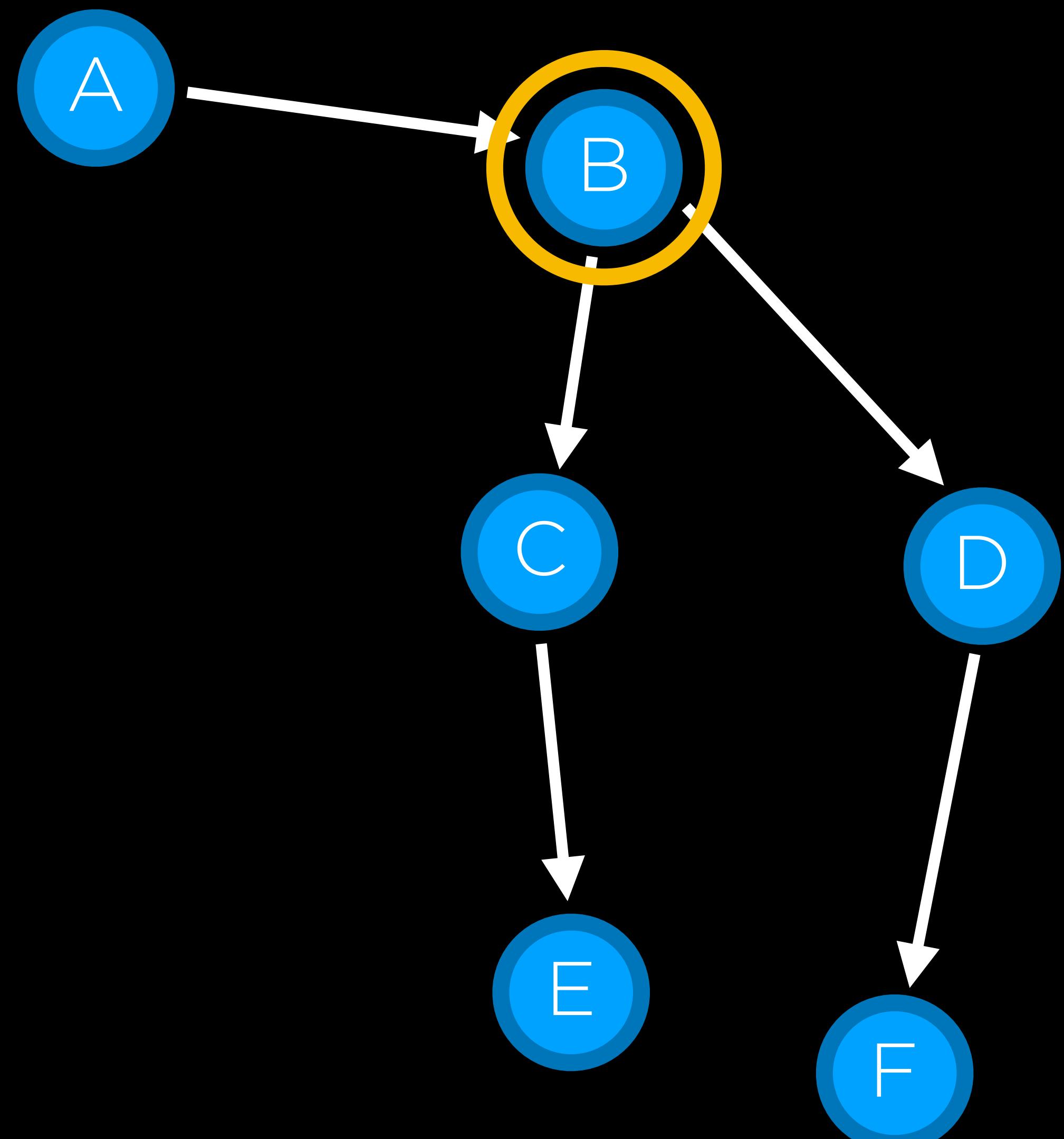
Find a path from A to E.

**Frontier**

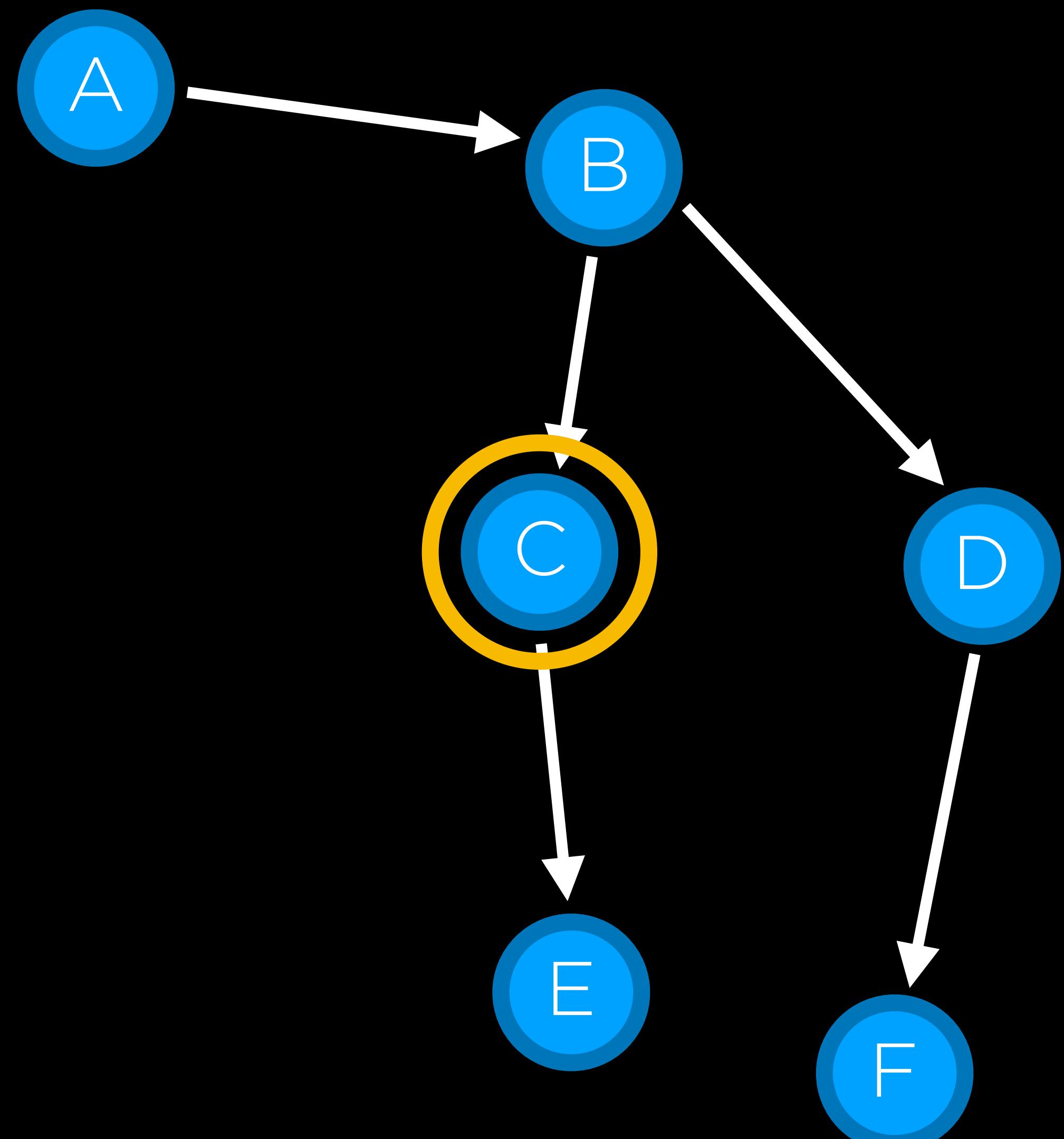
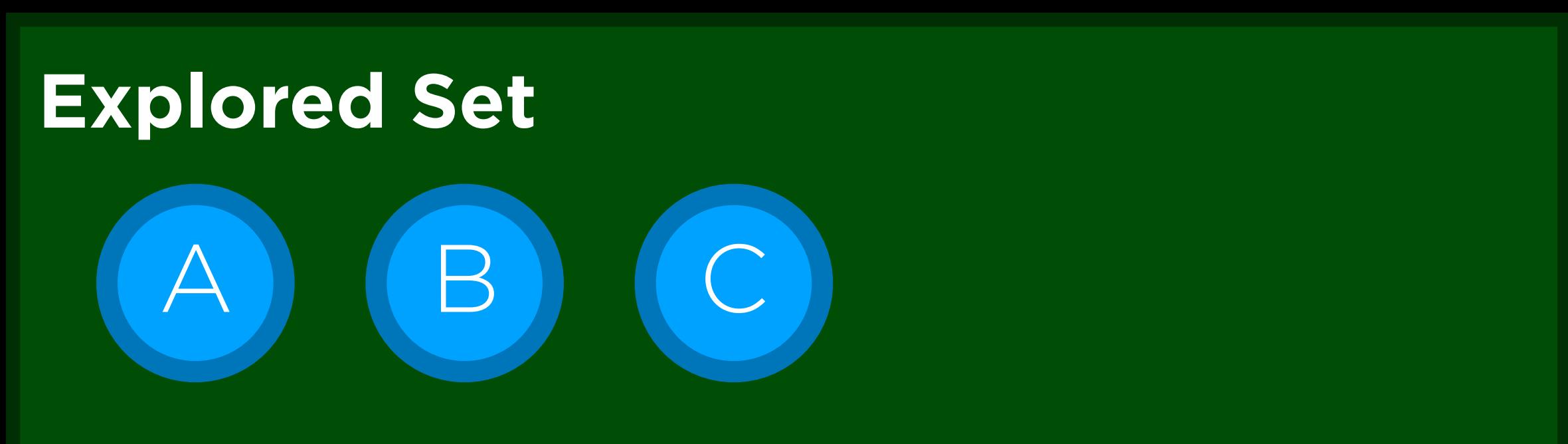
**Explored Set**



Find a path from A to E.

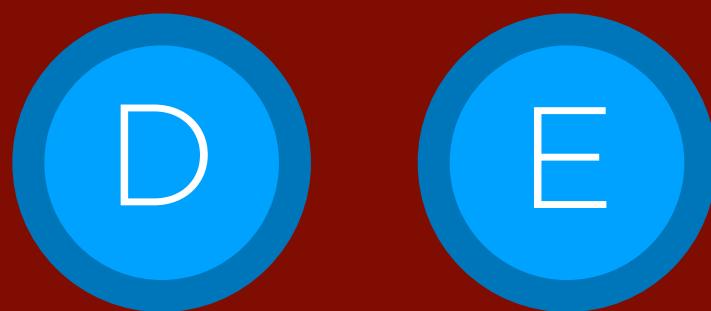


Find a path from A to E.

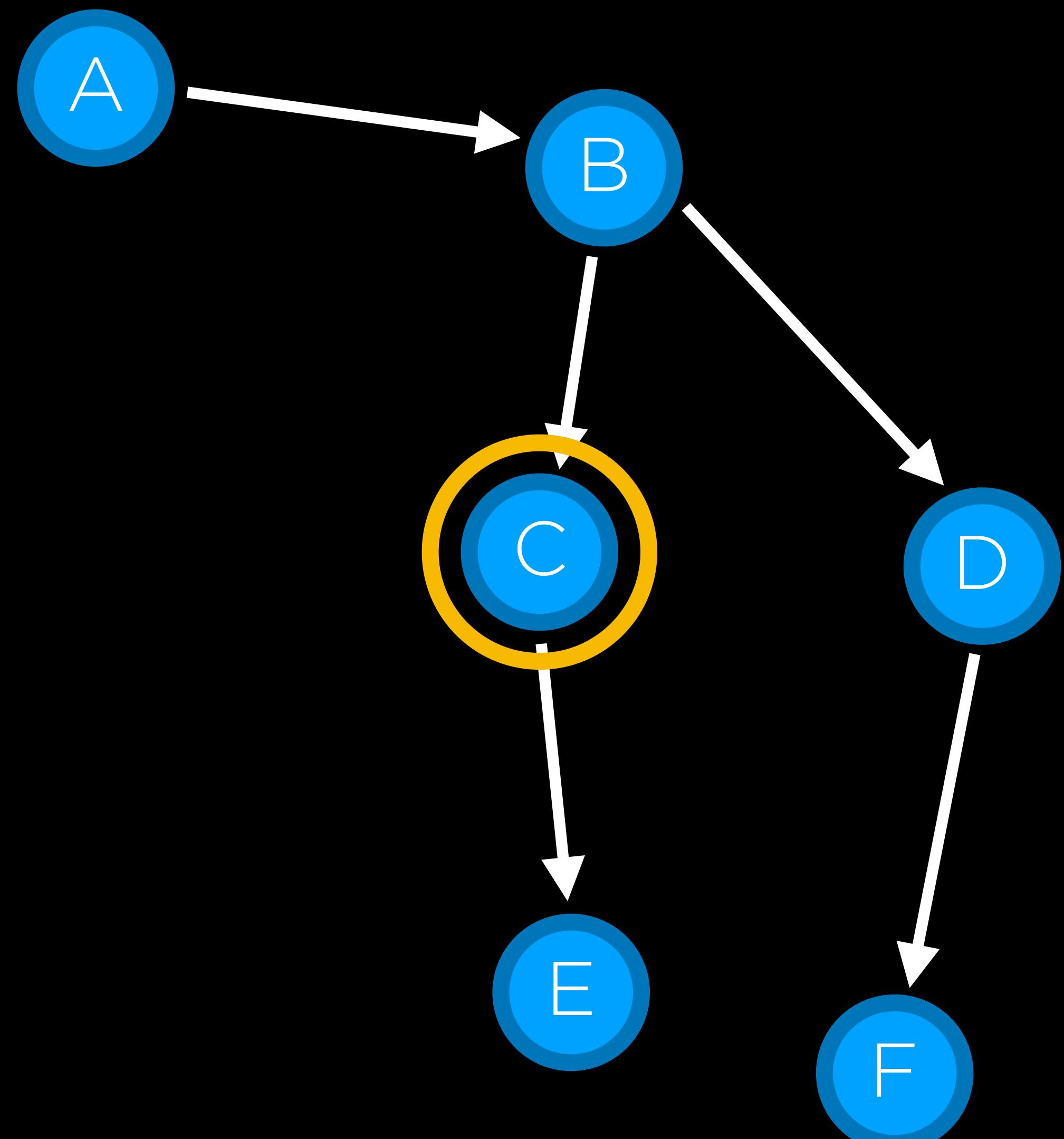


Find a path from A to E.

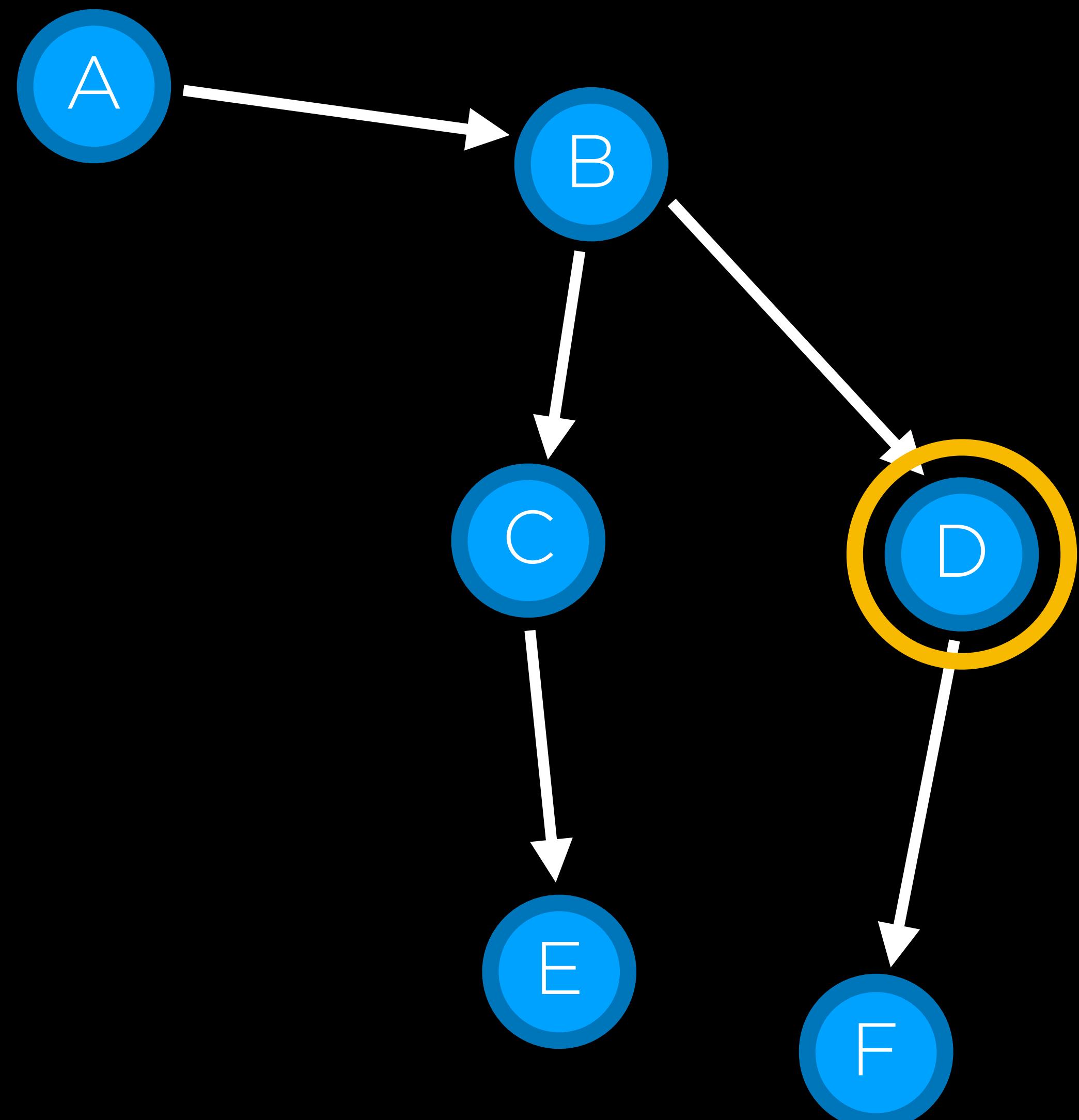
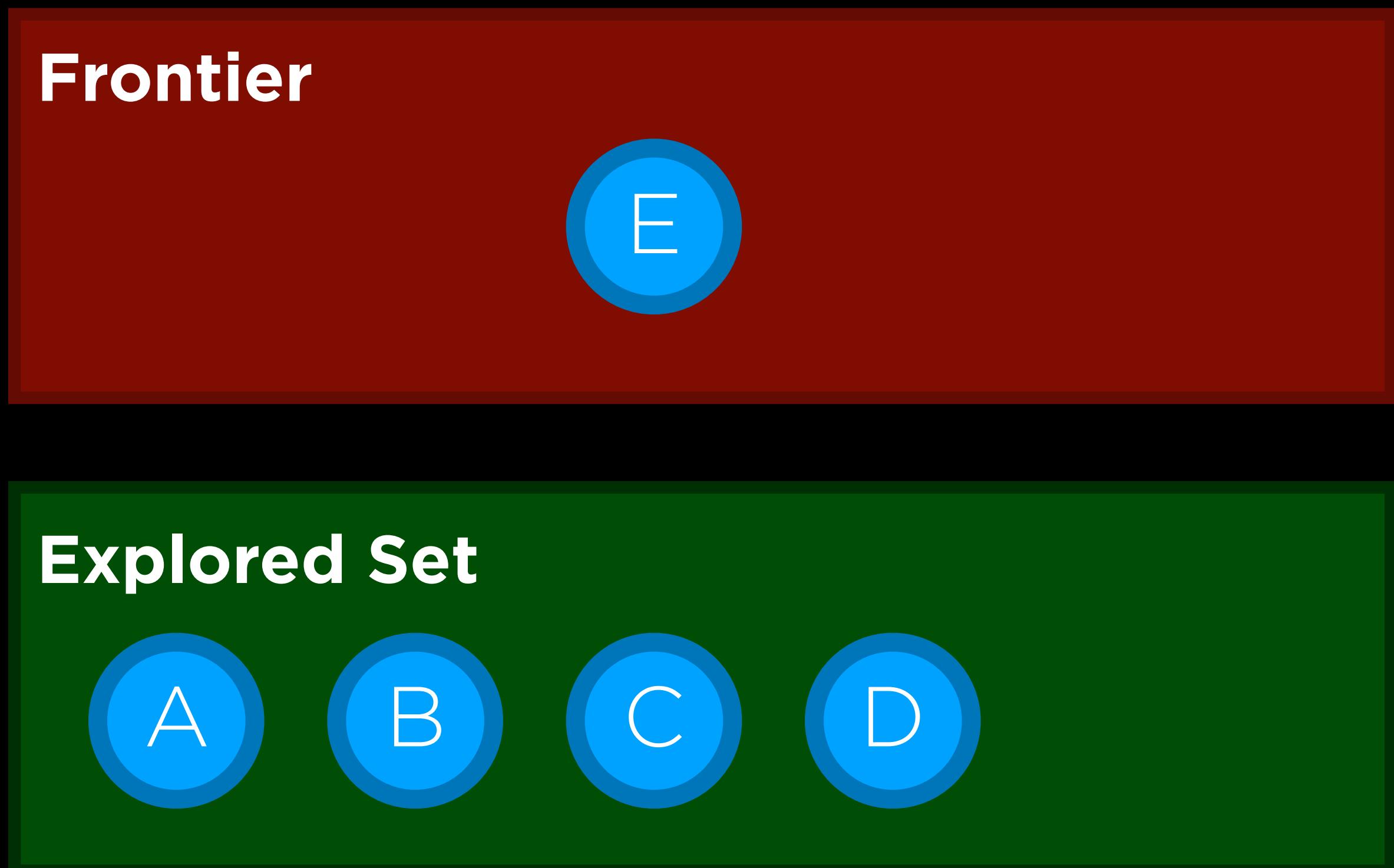
**Frontier**



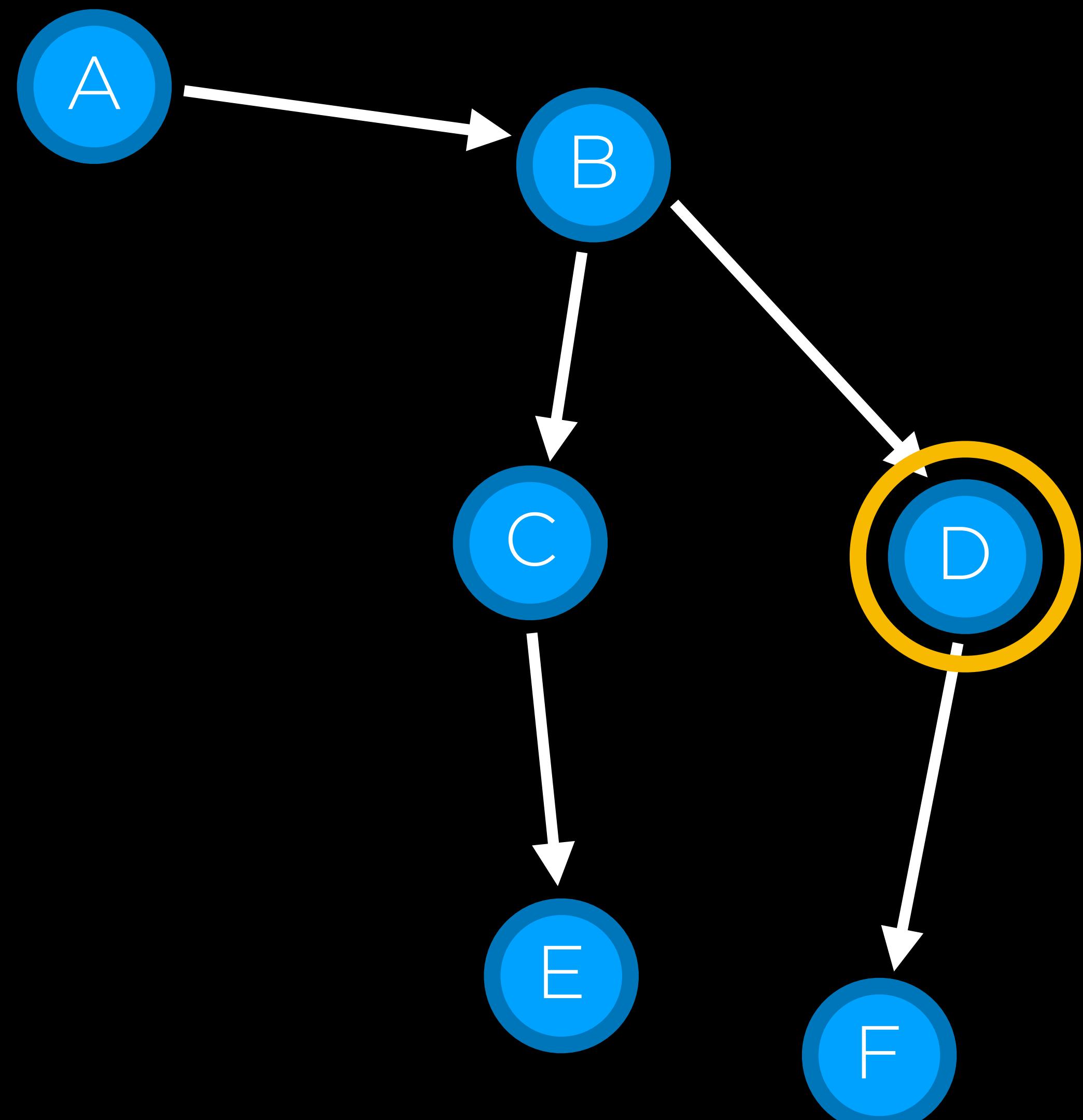
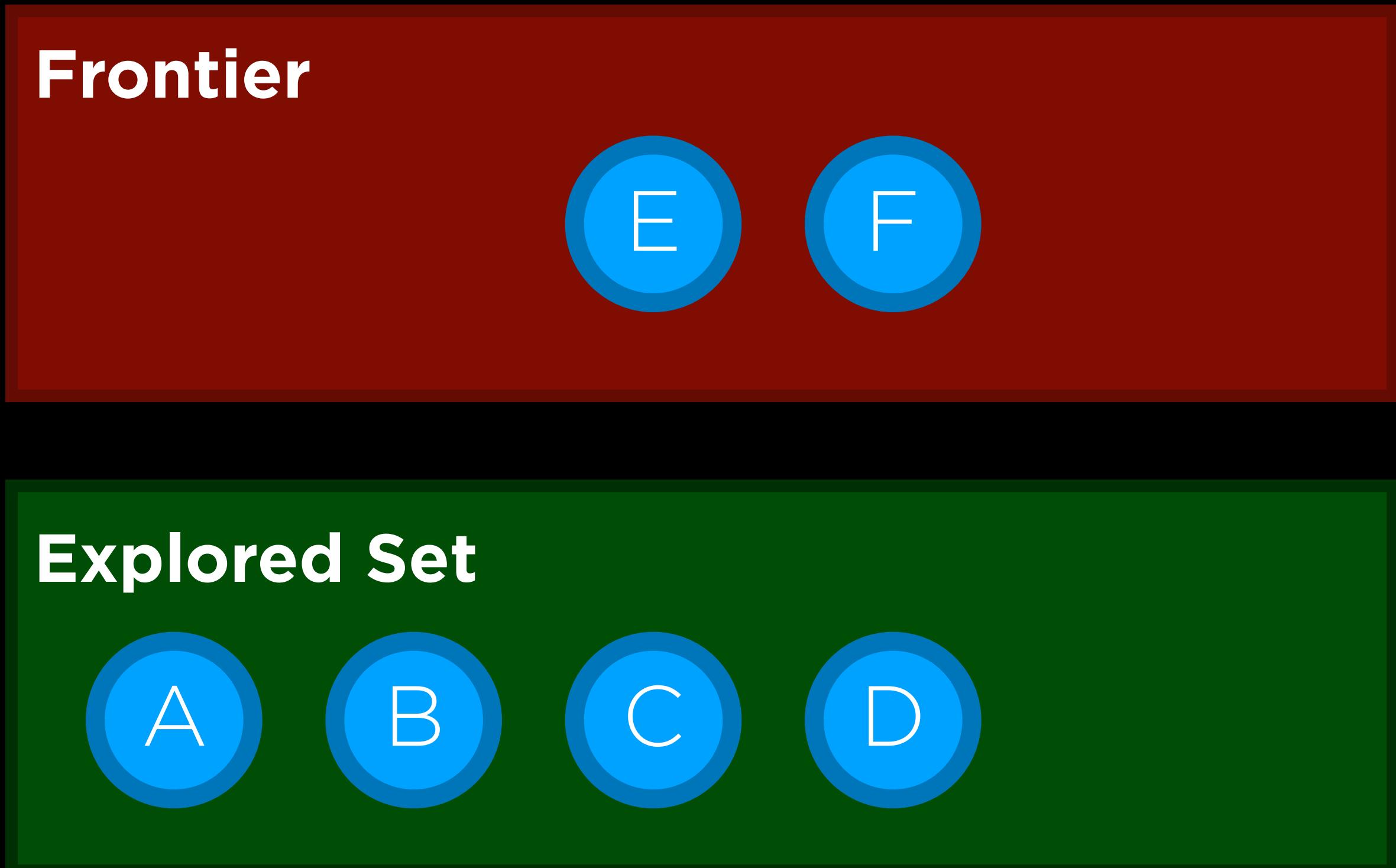
**Explored Set**



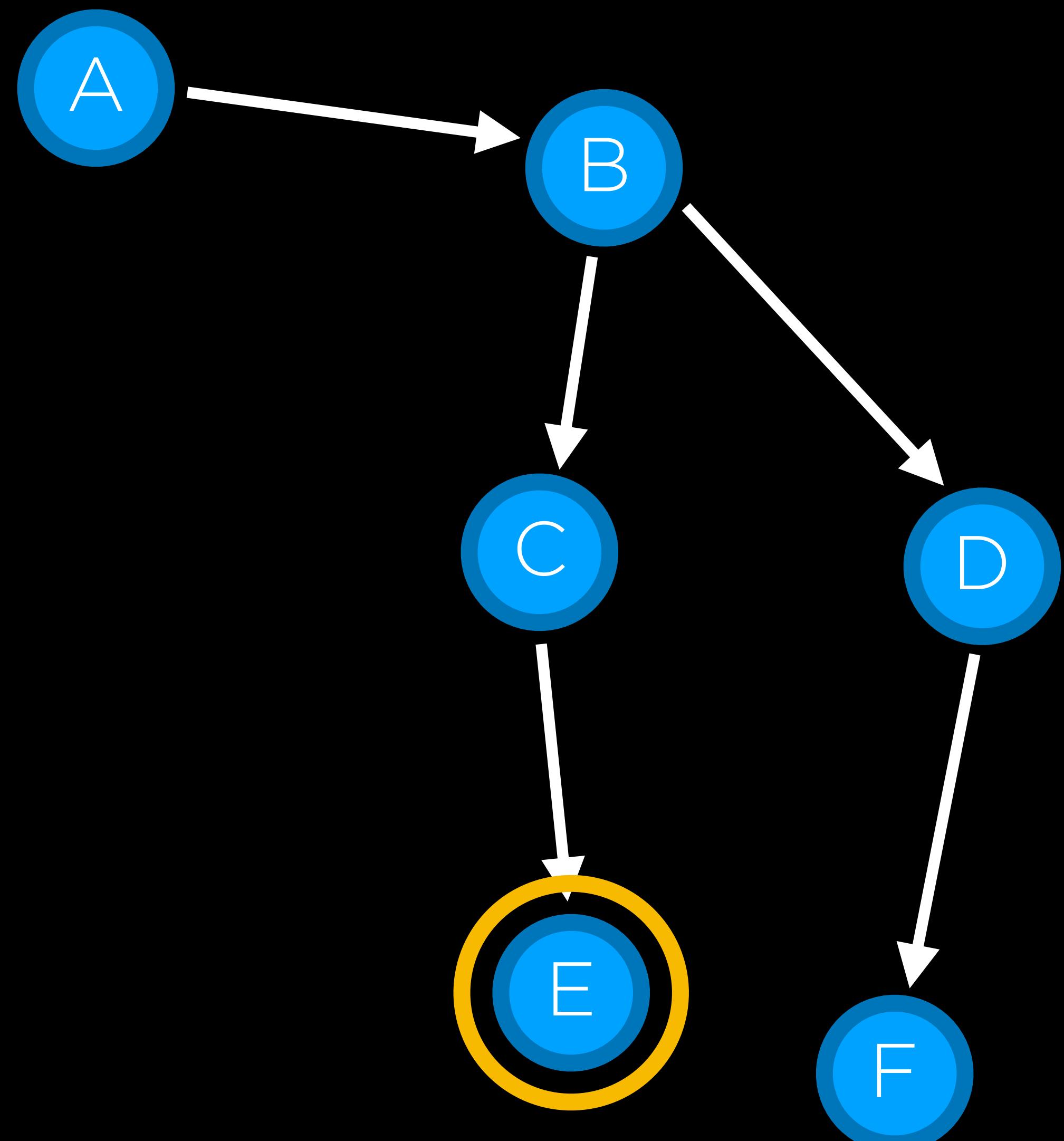
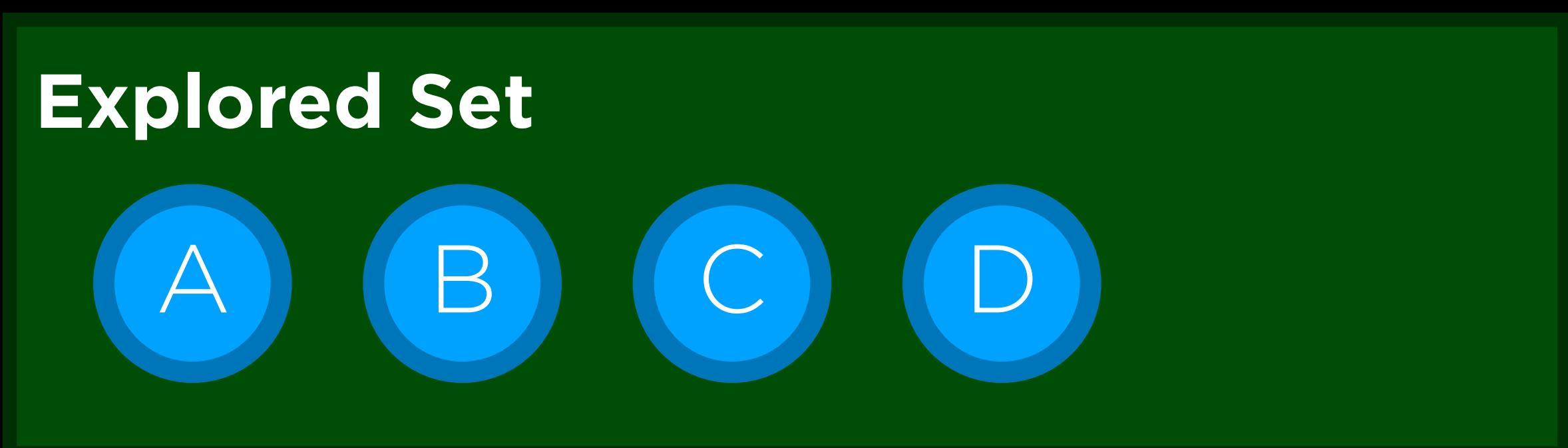
Find a path from A to E.



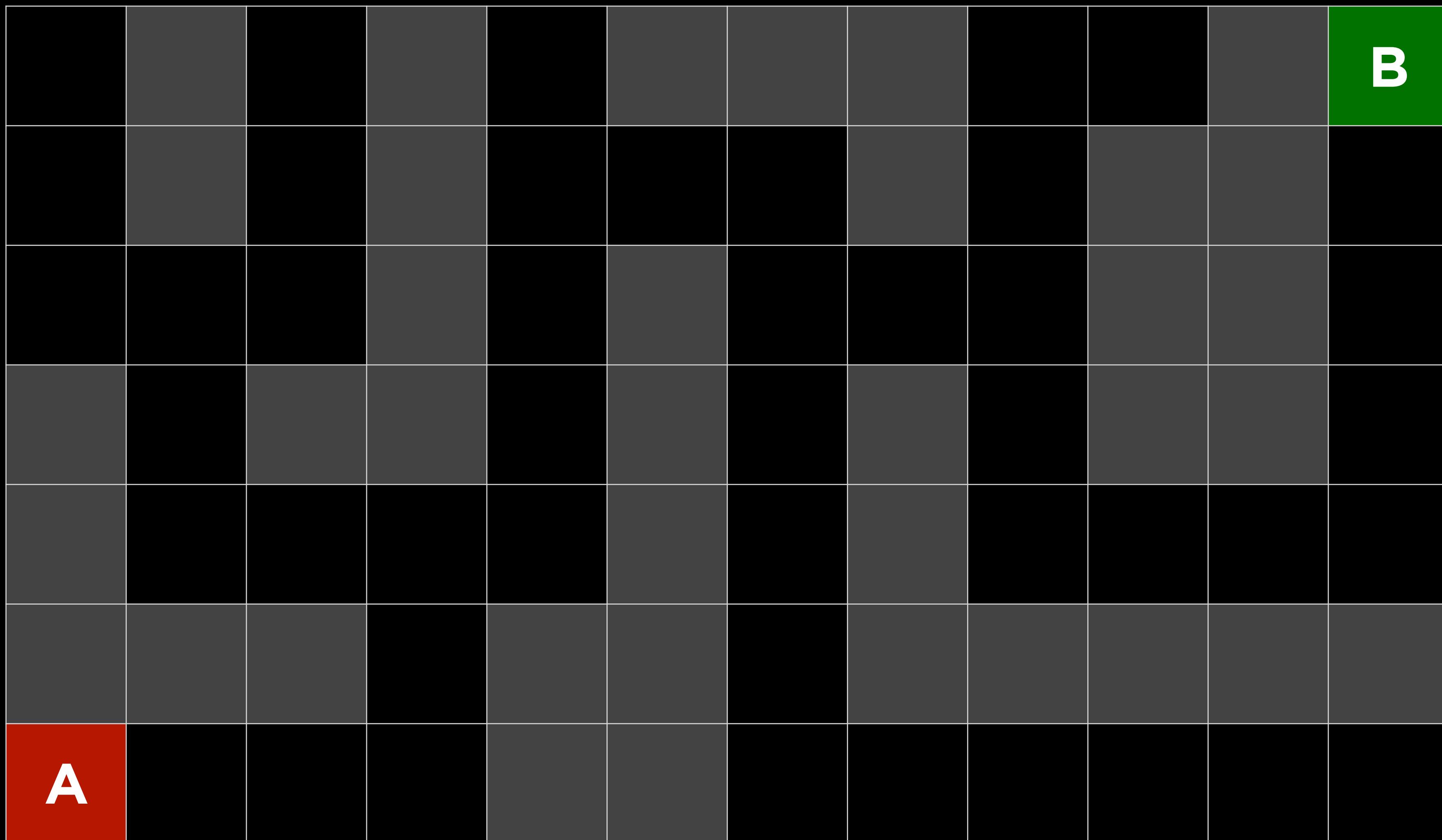
Find a path from A to E.



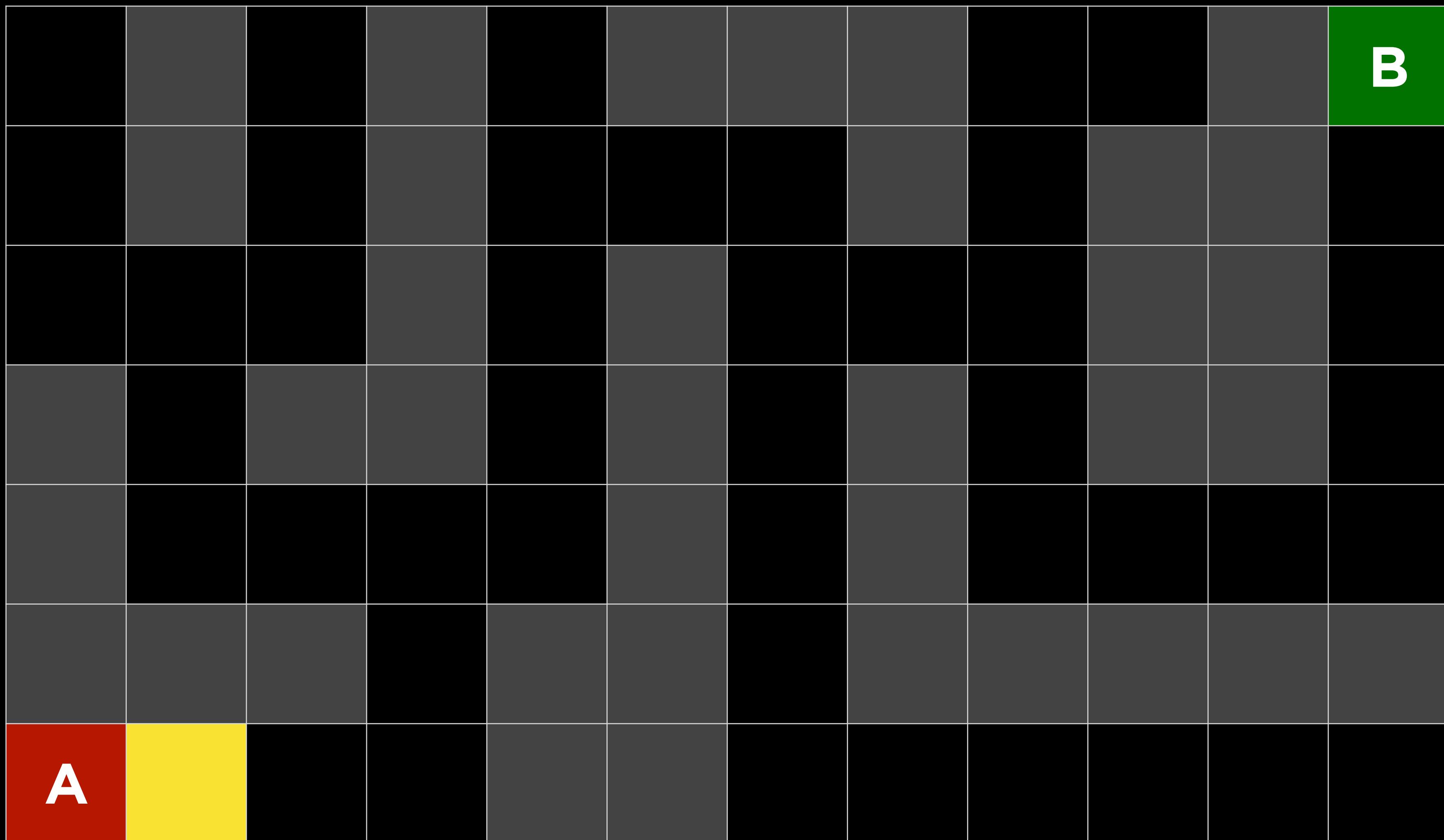
Find a path from A to E.



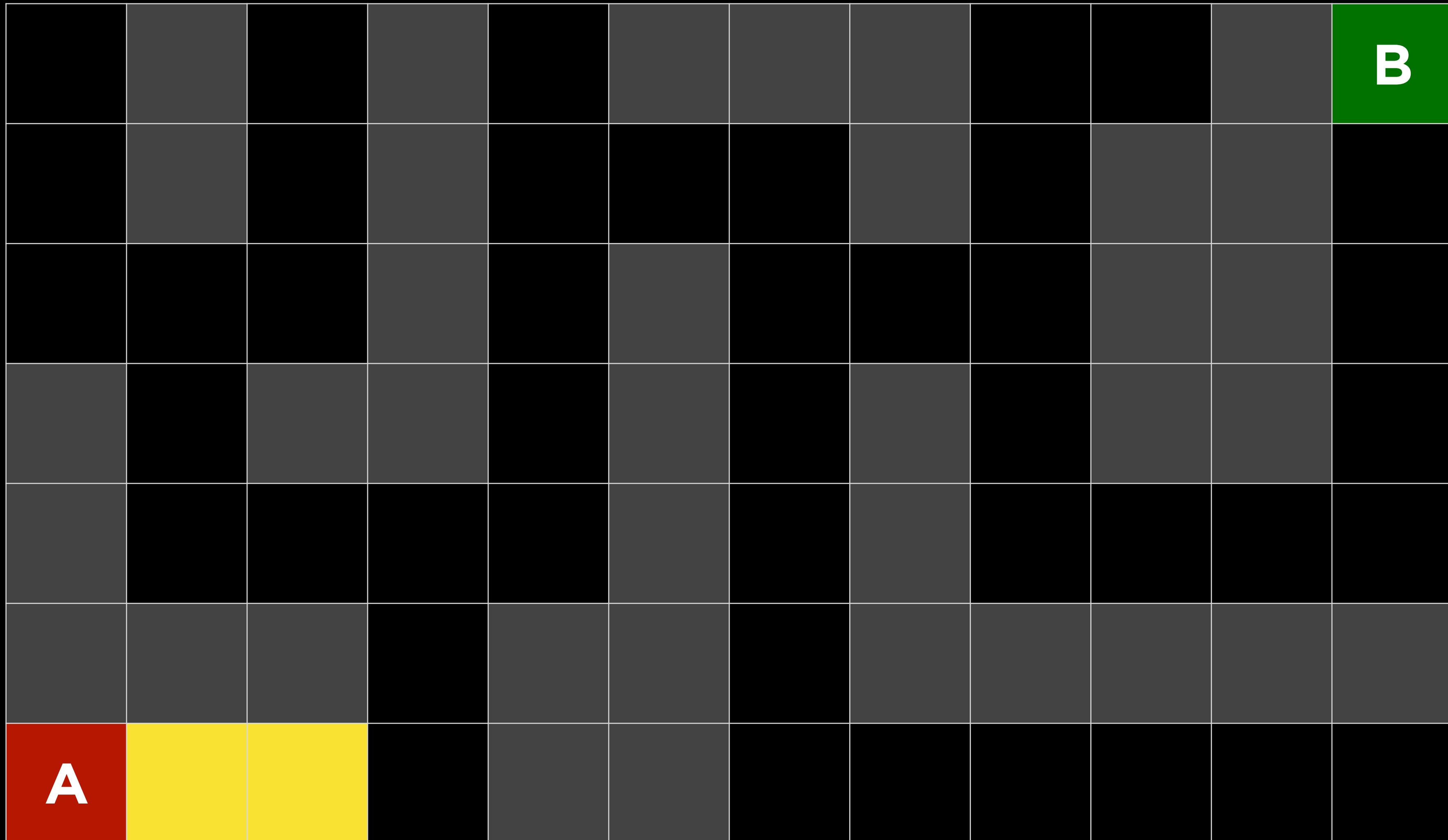
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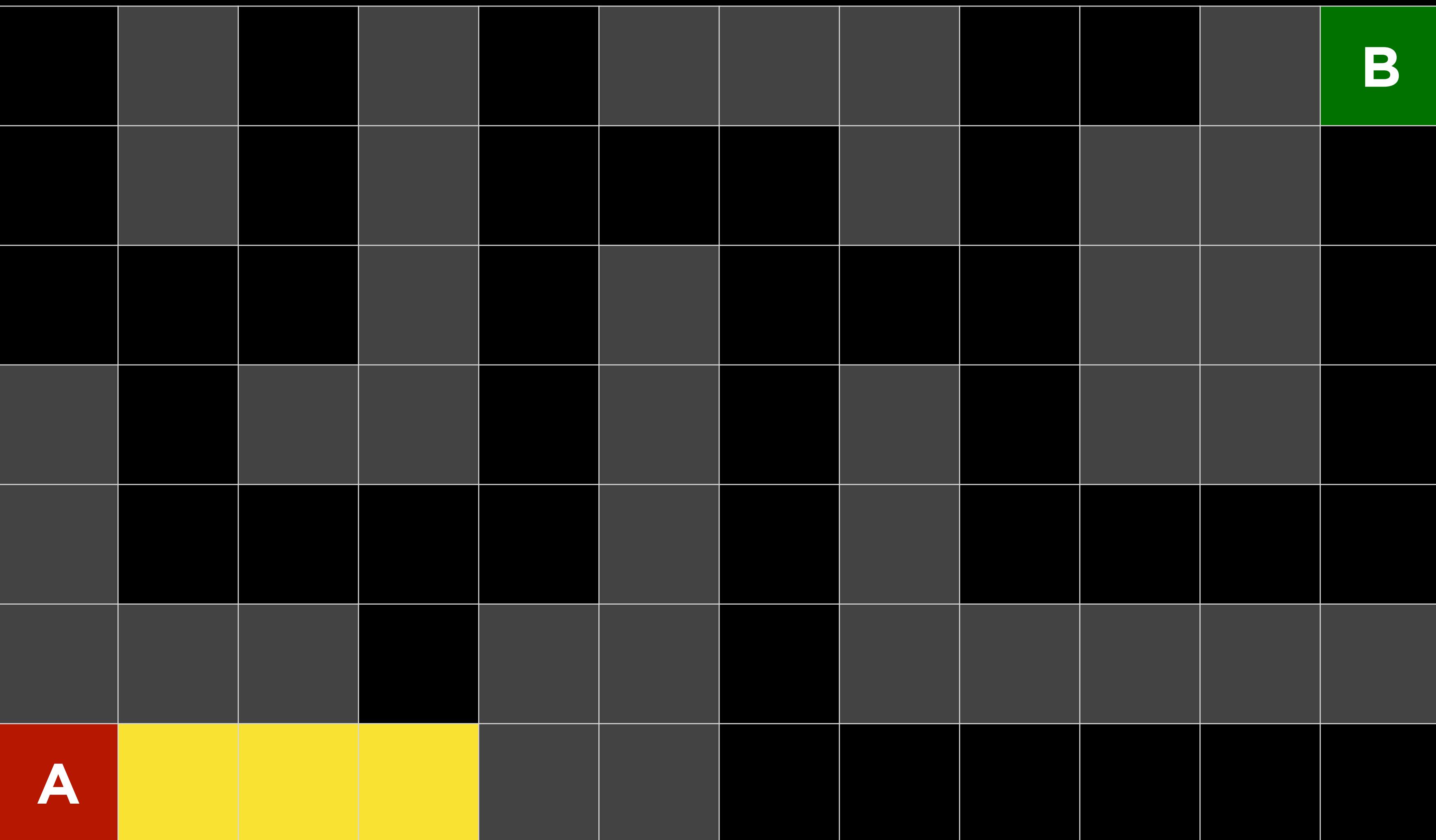
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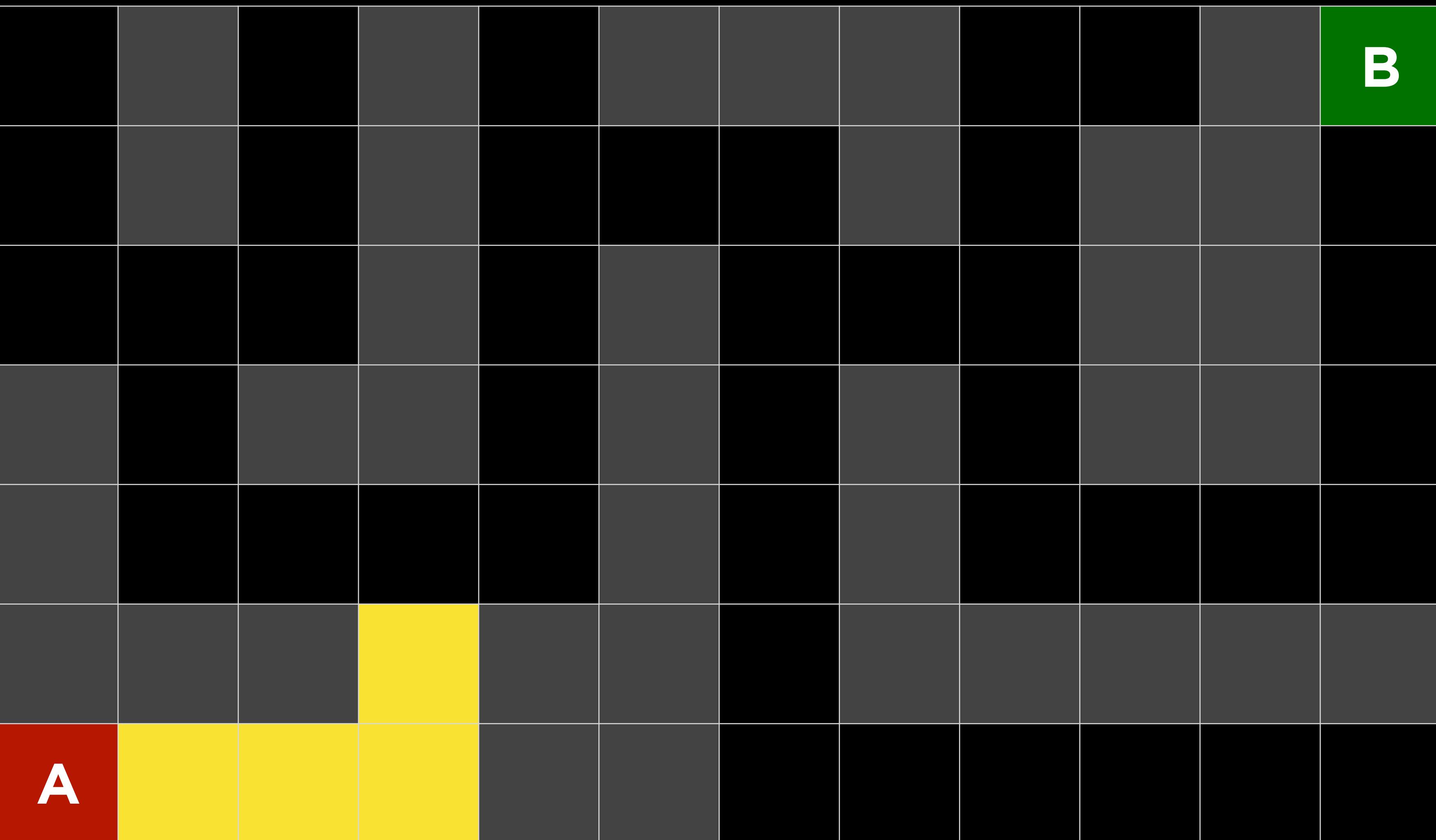
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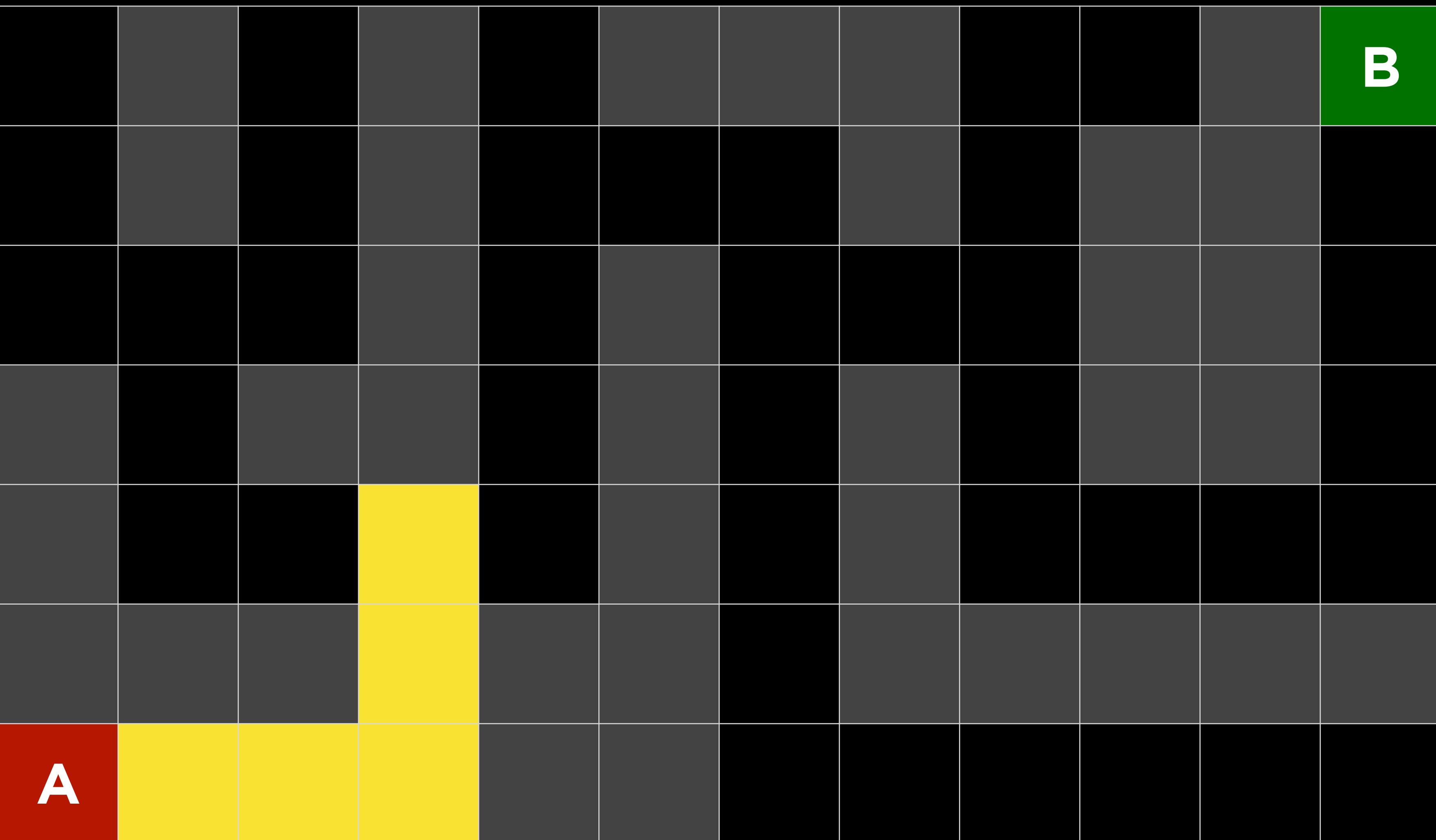
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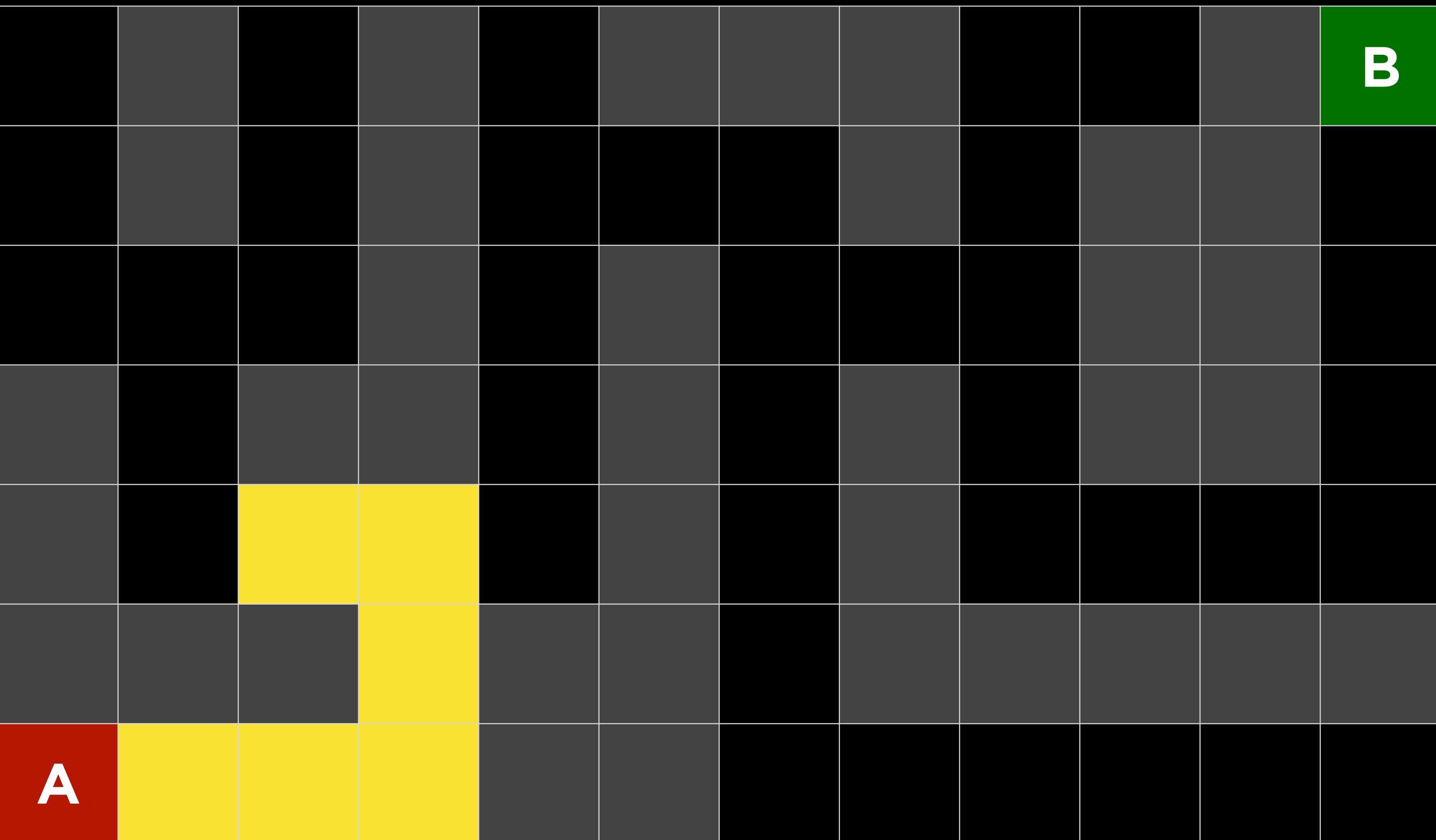
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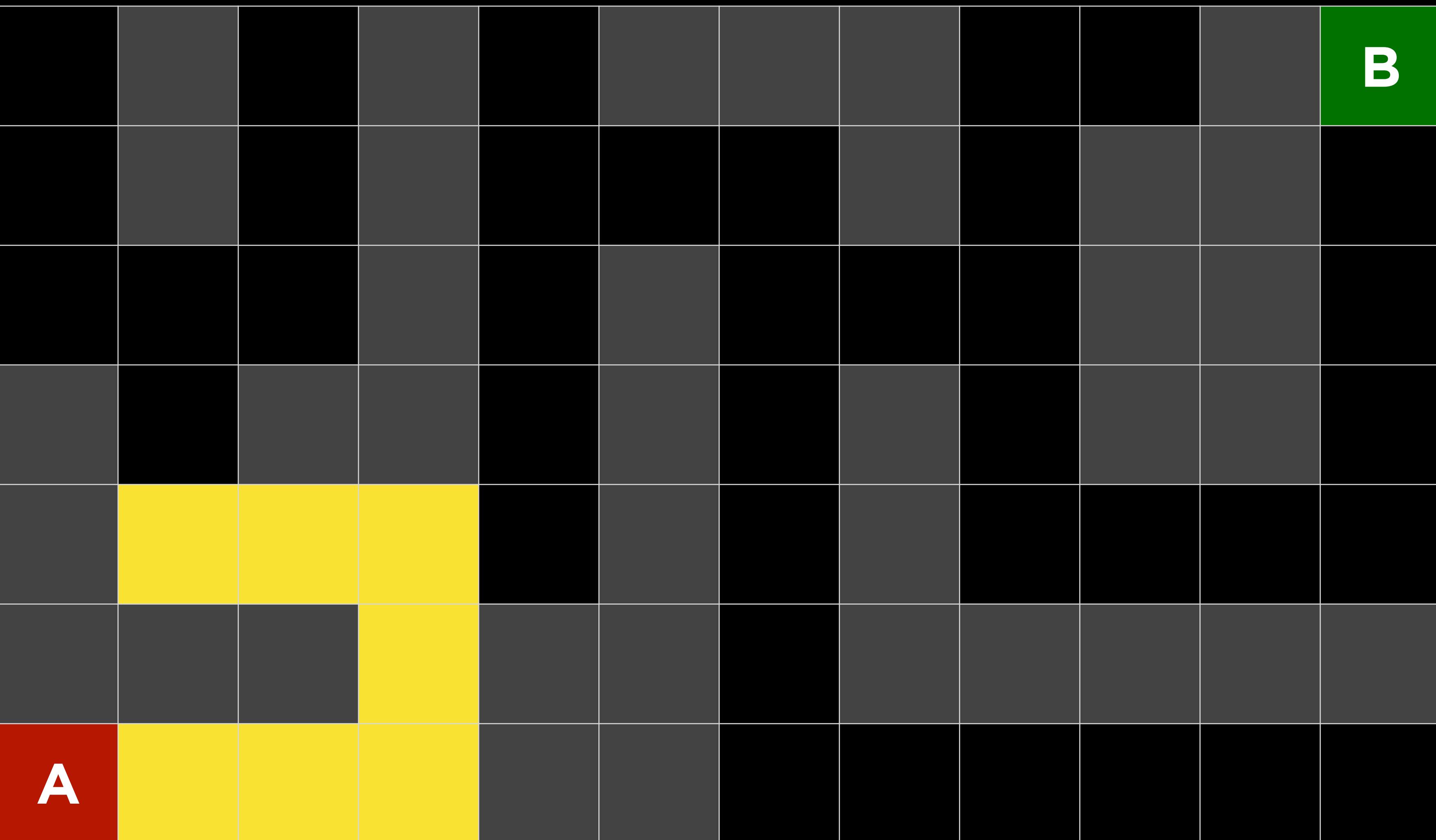
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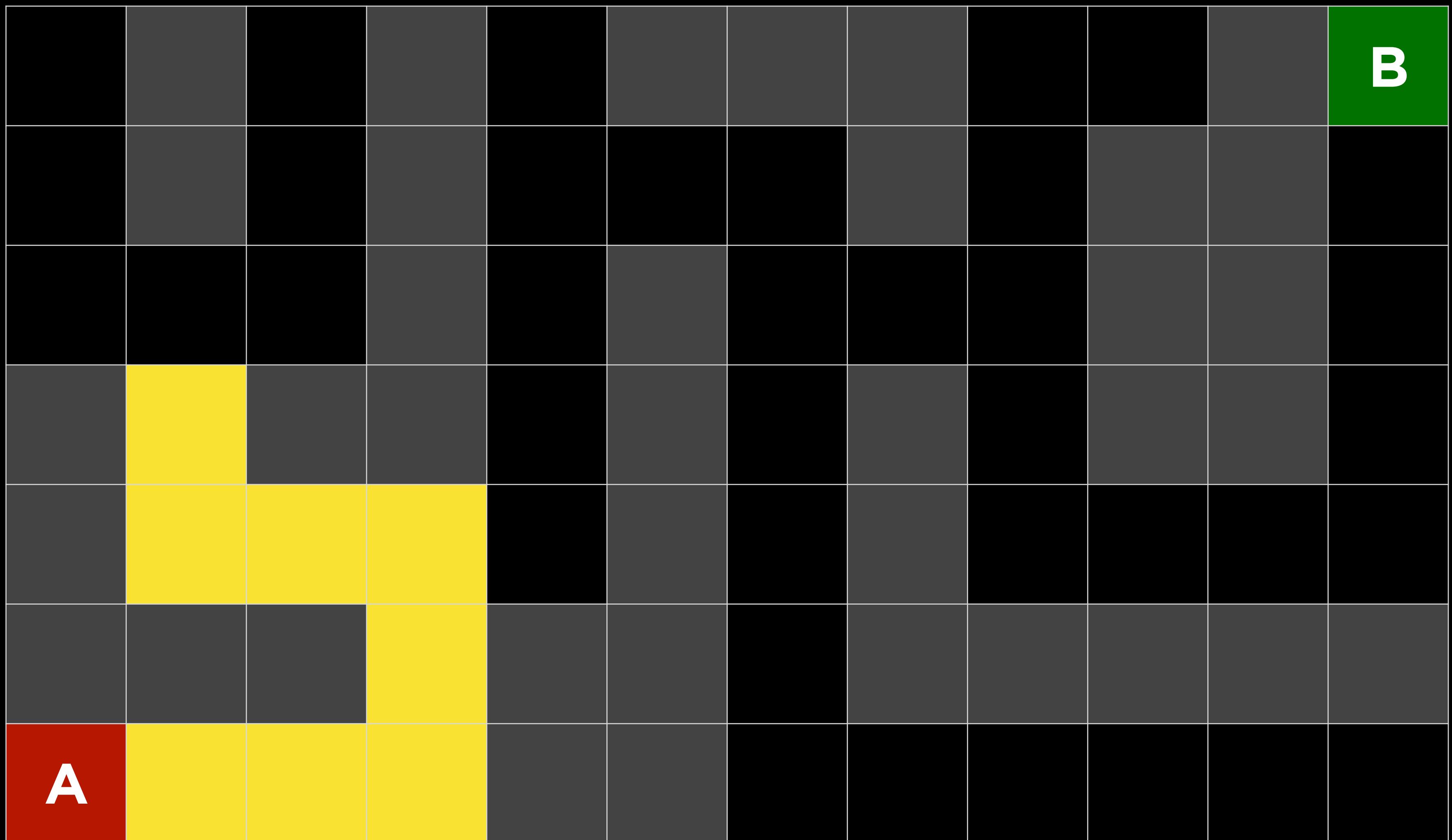
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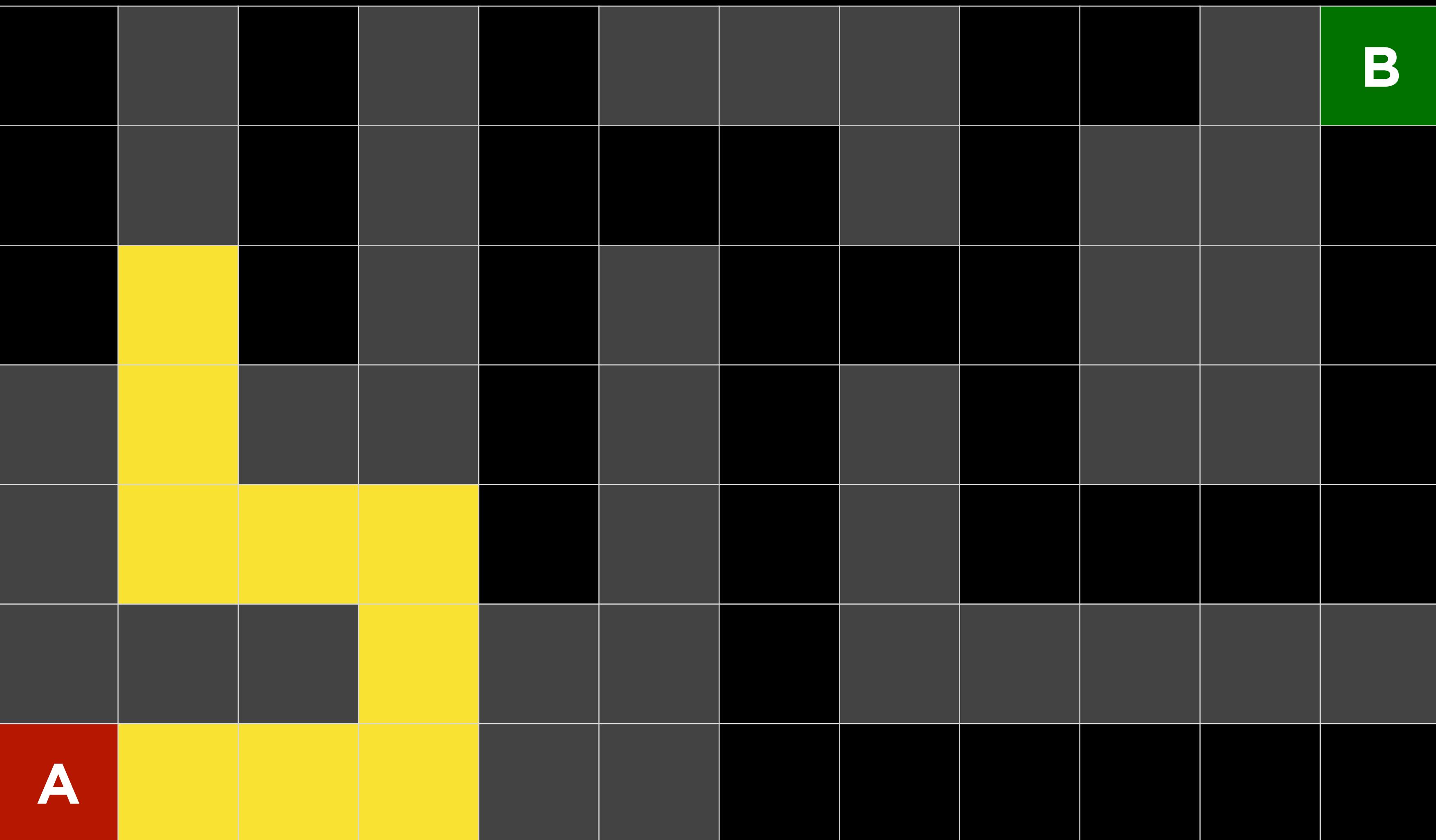
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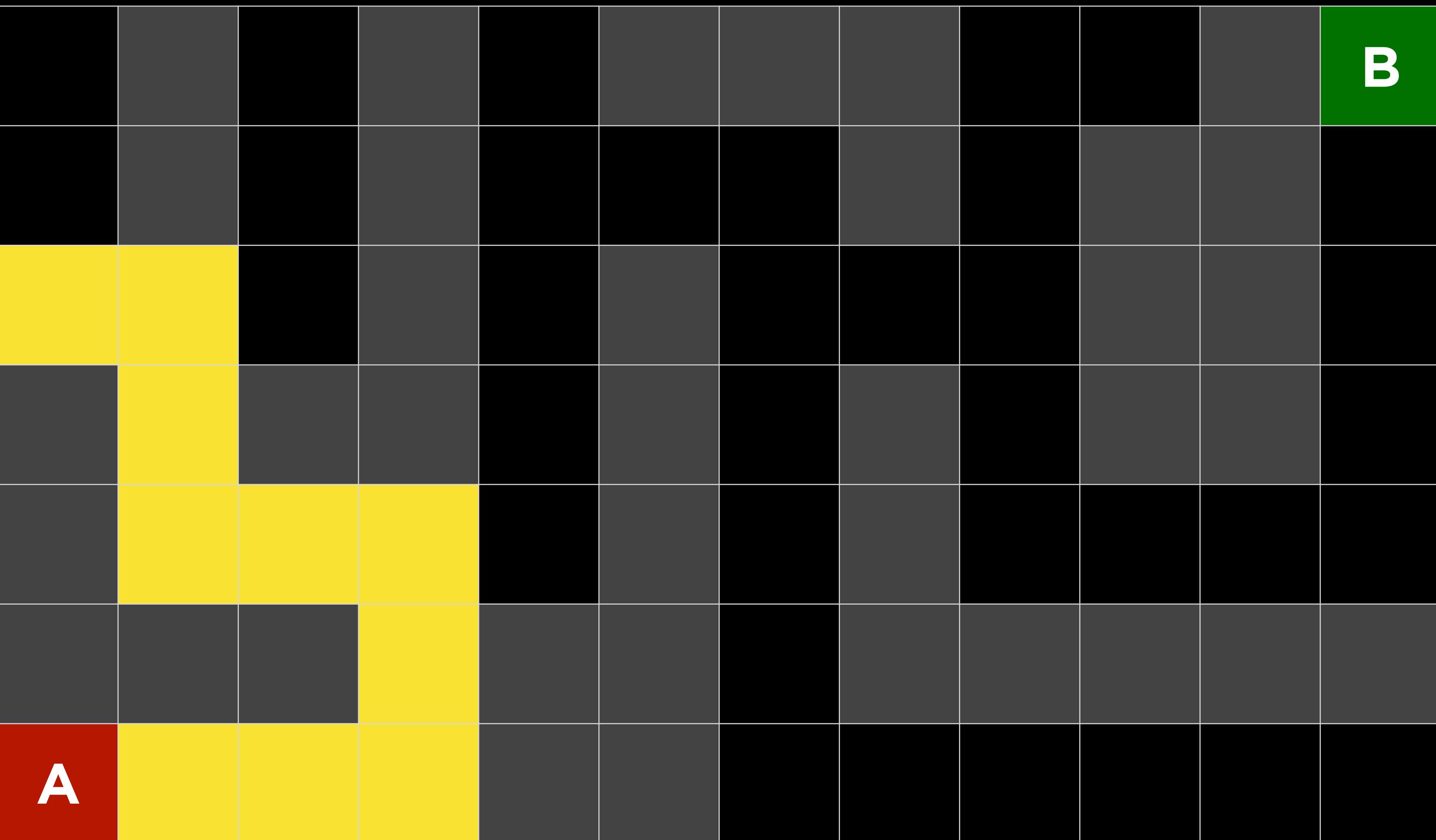
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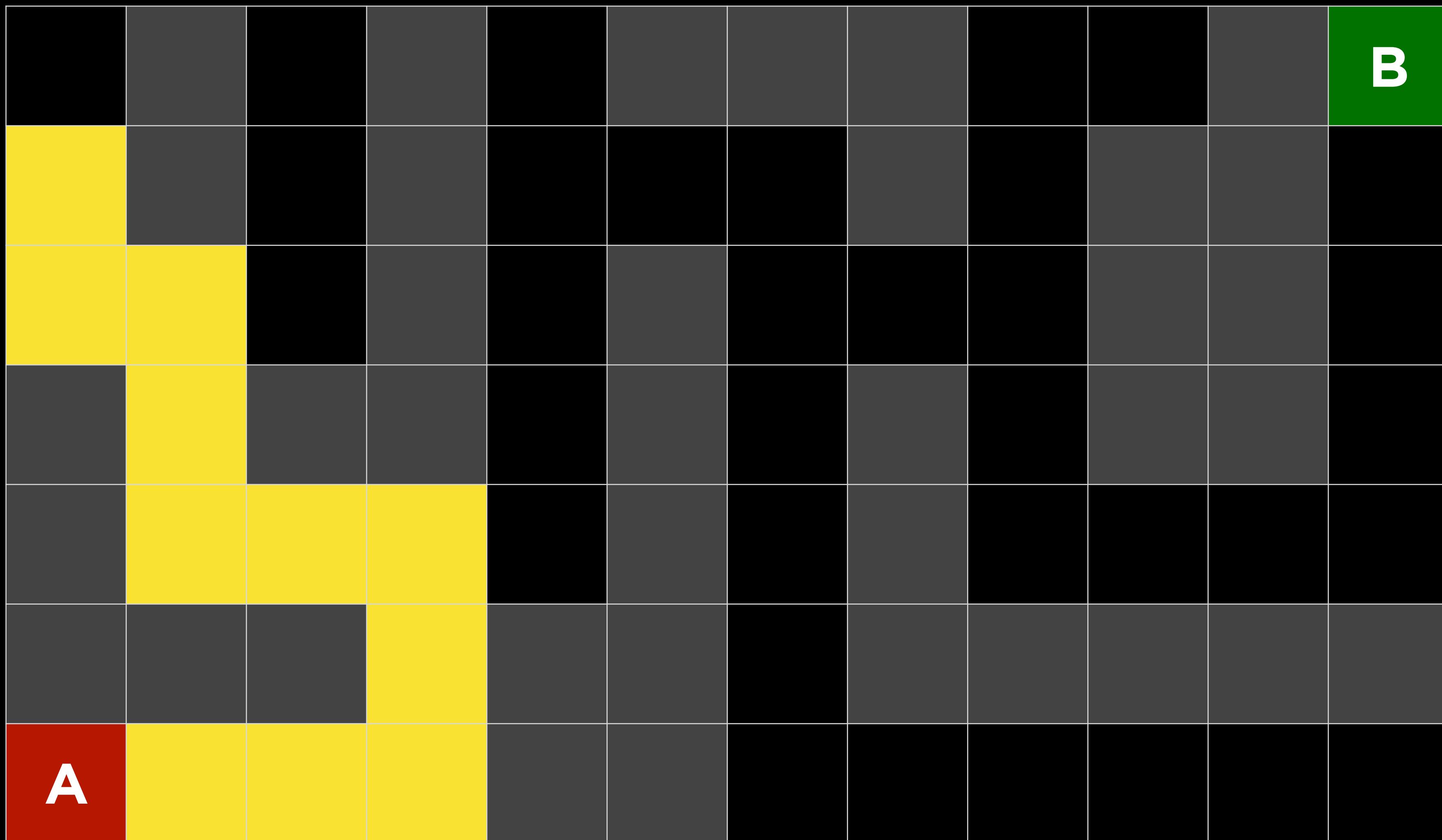
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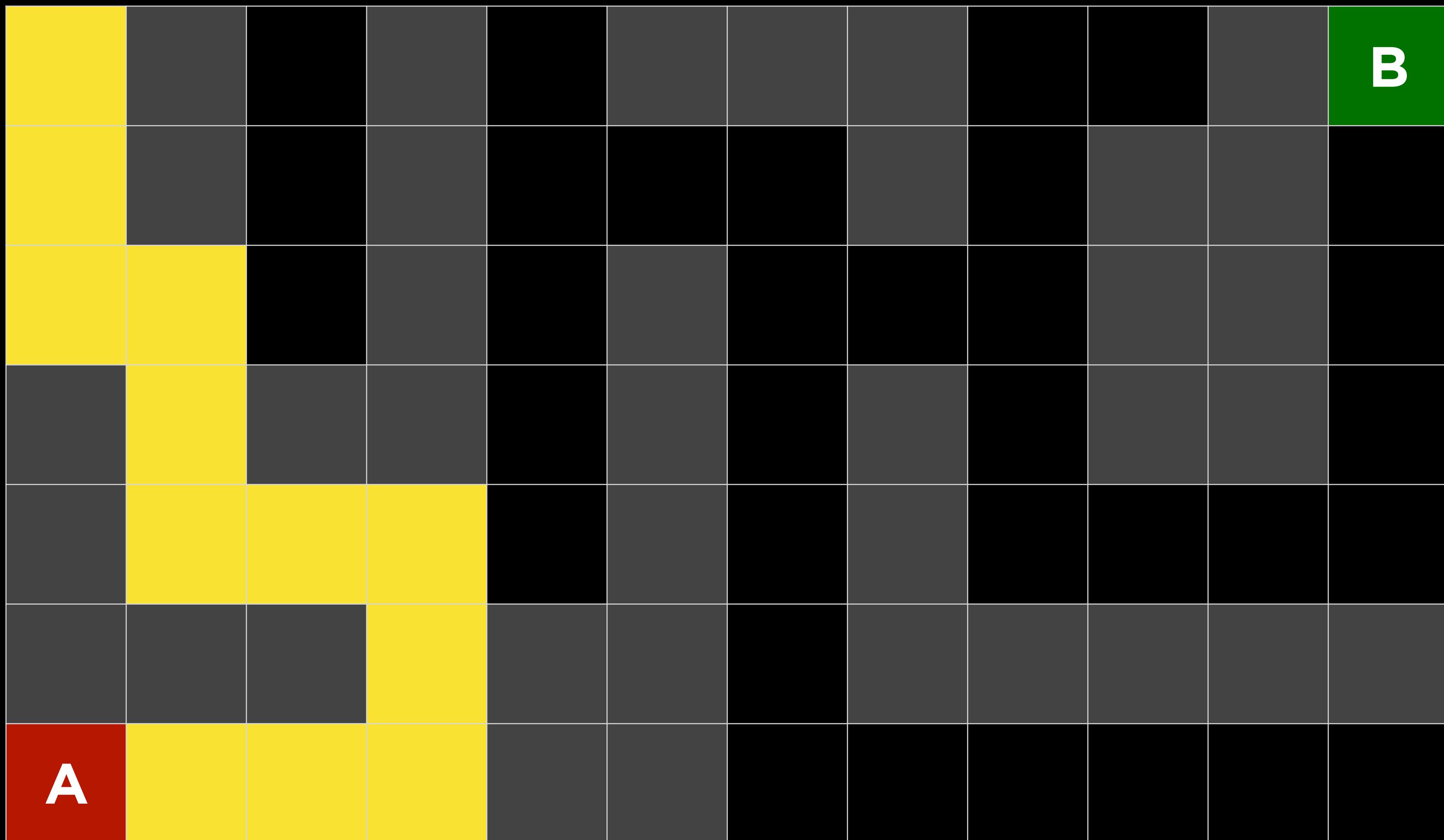
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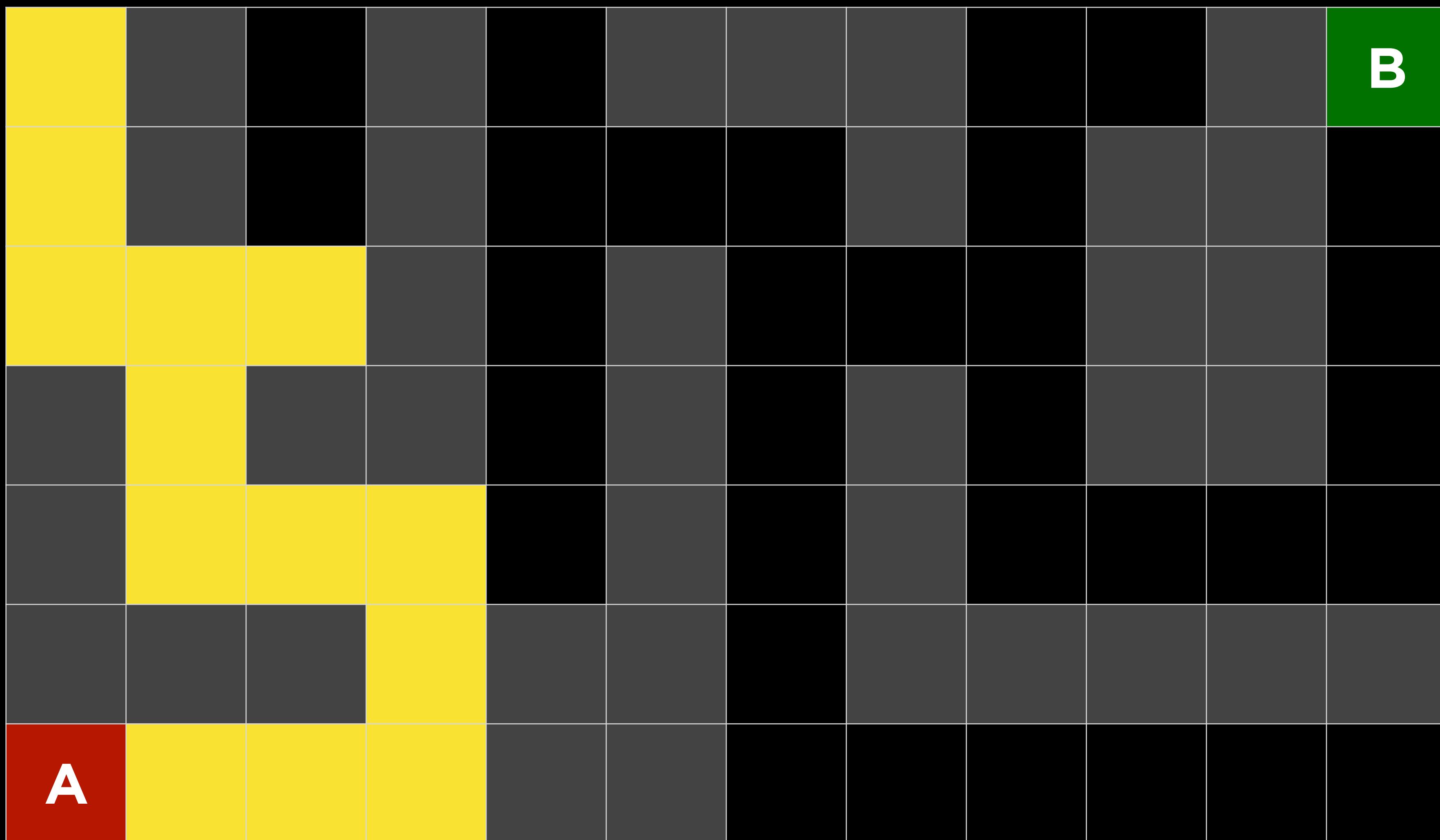
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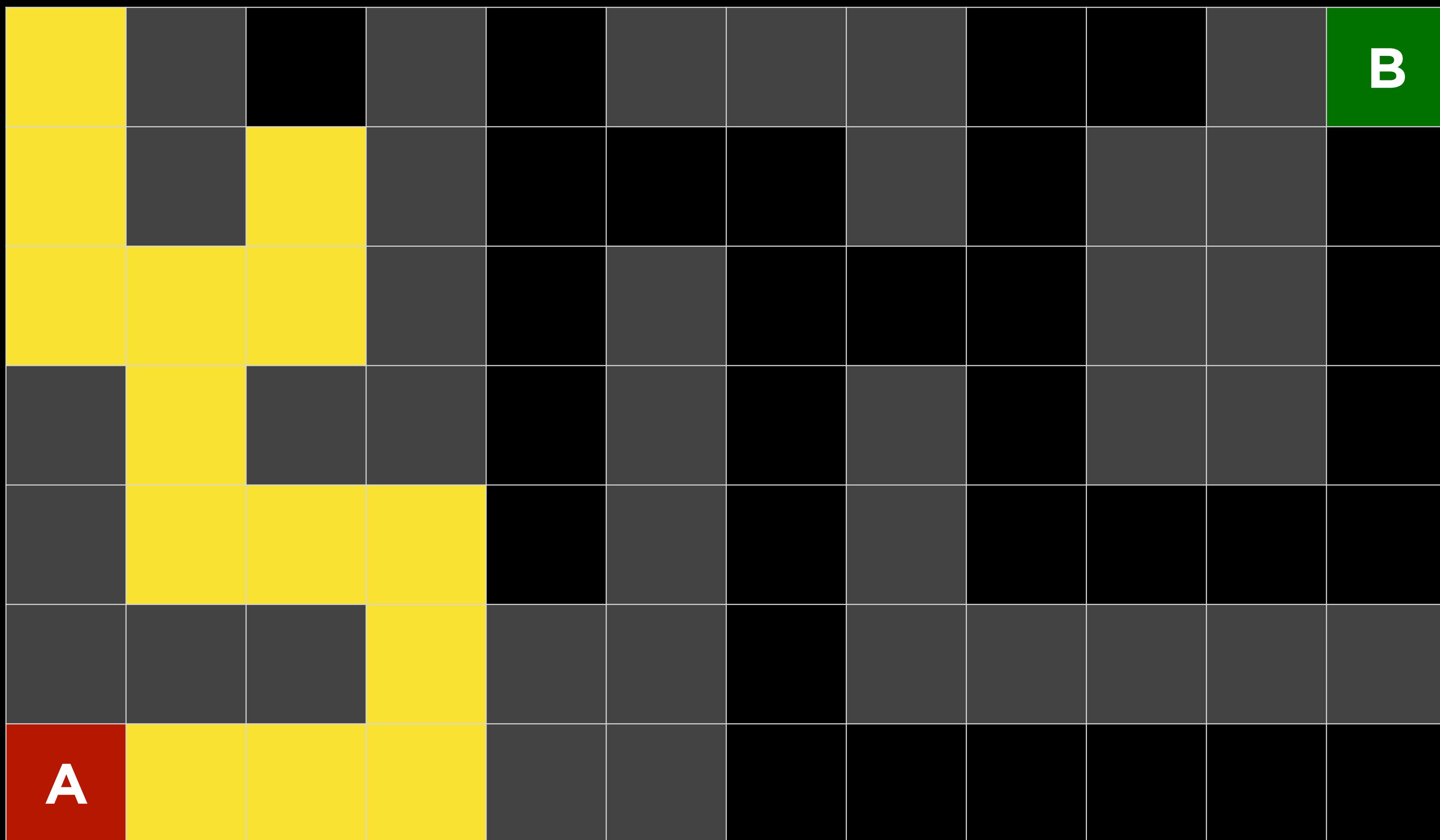
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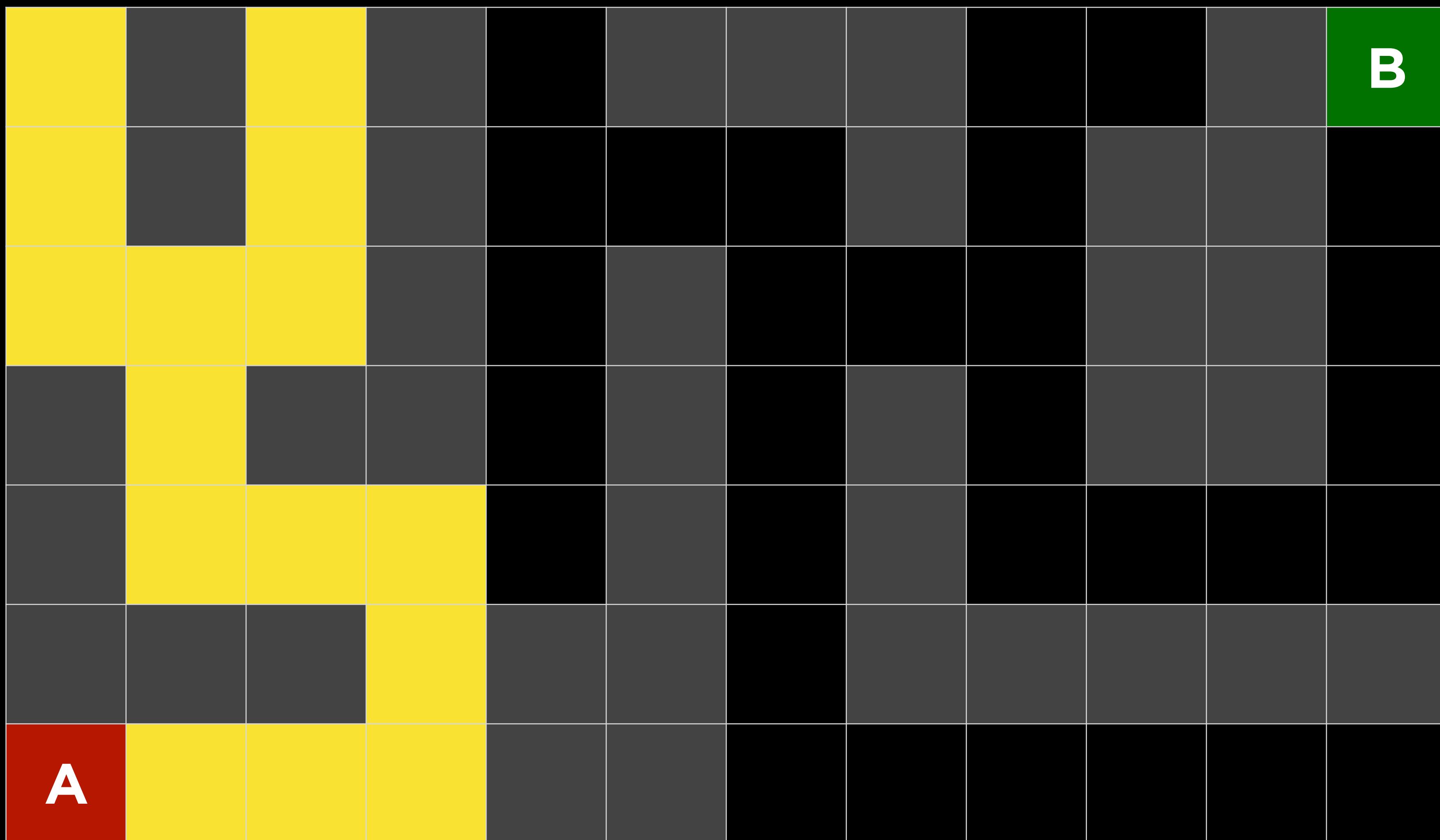
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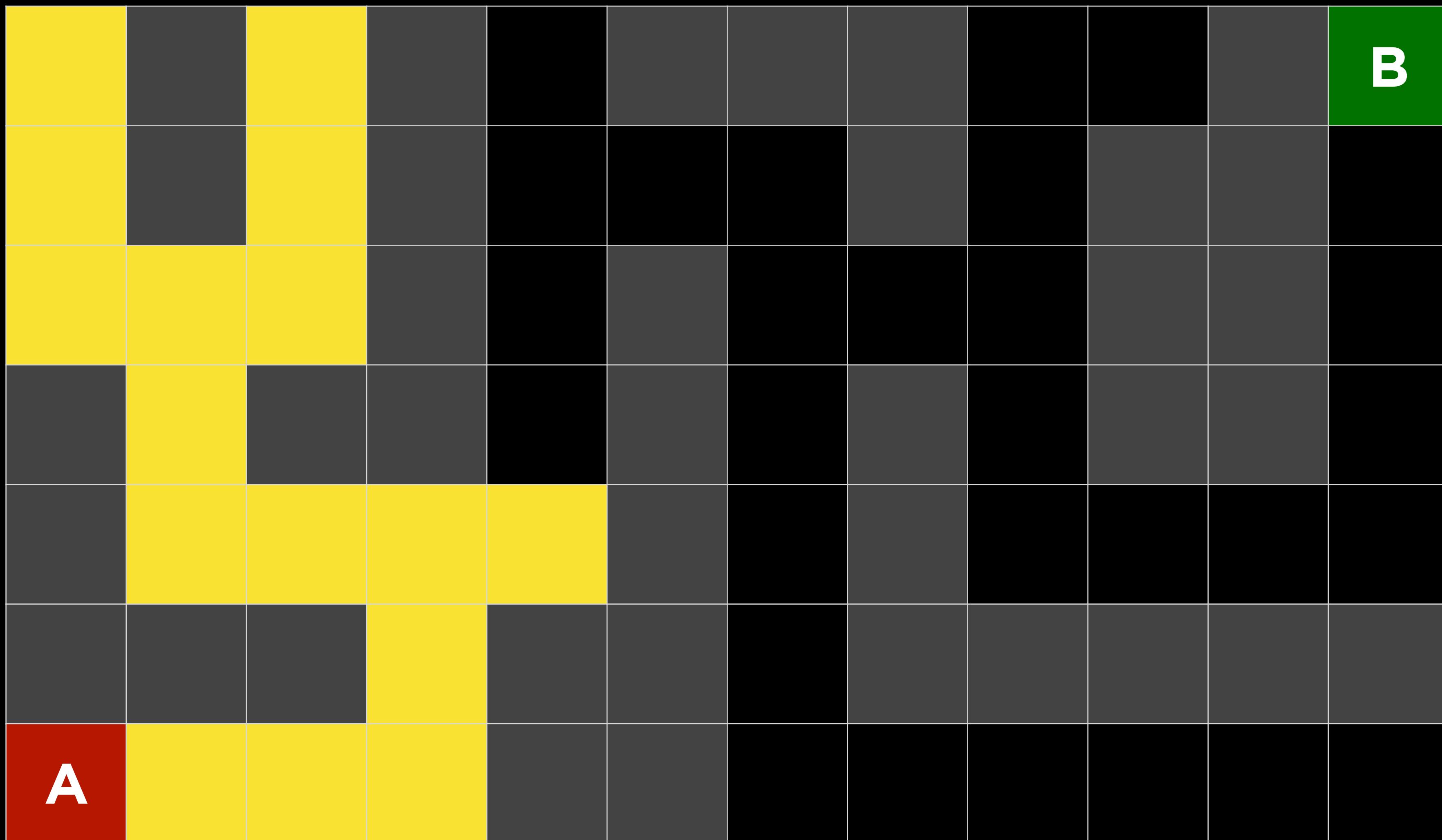
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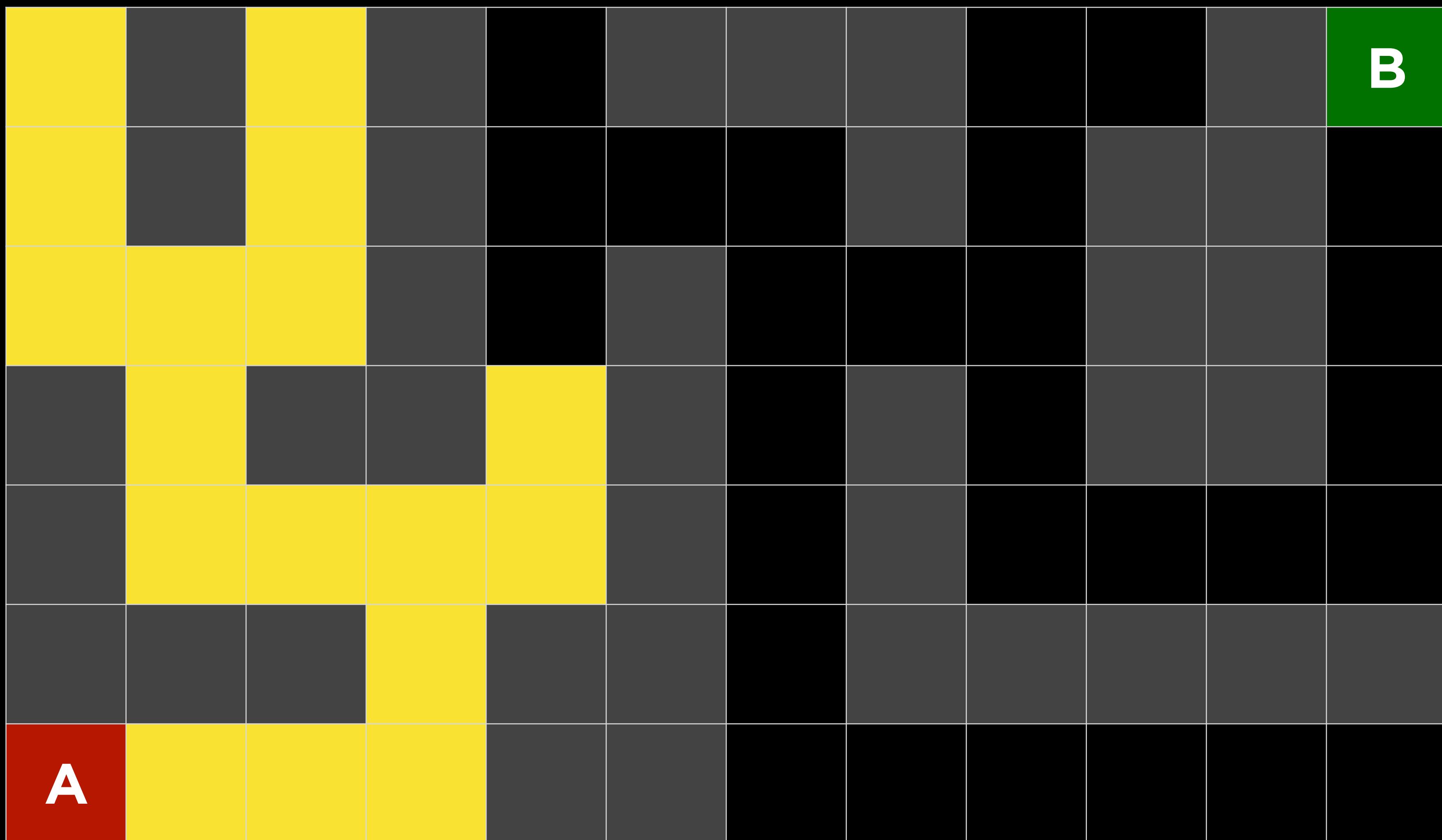
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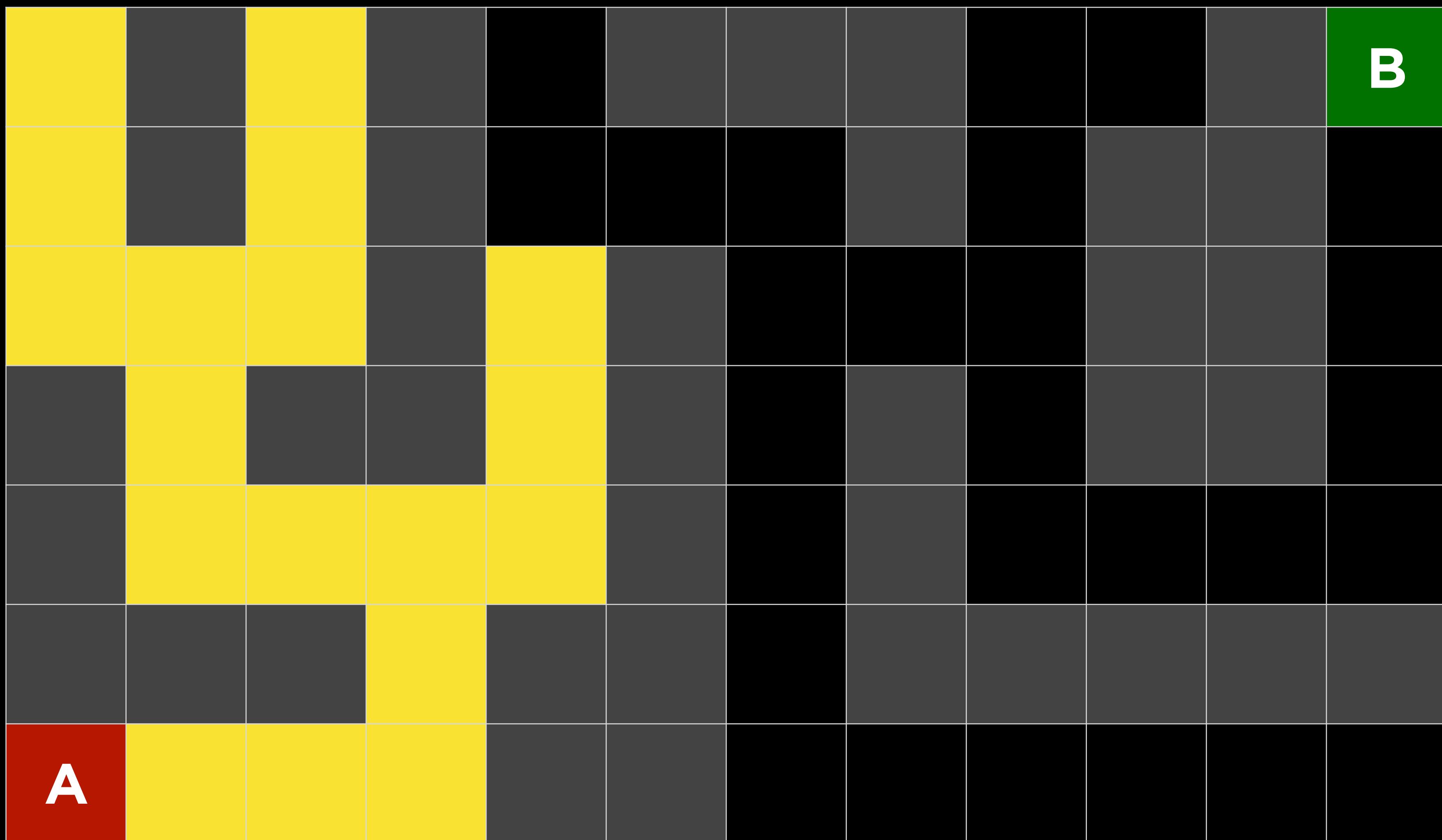
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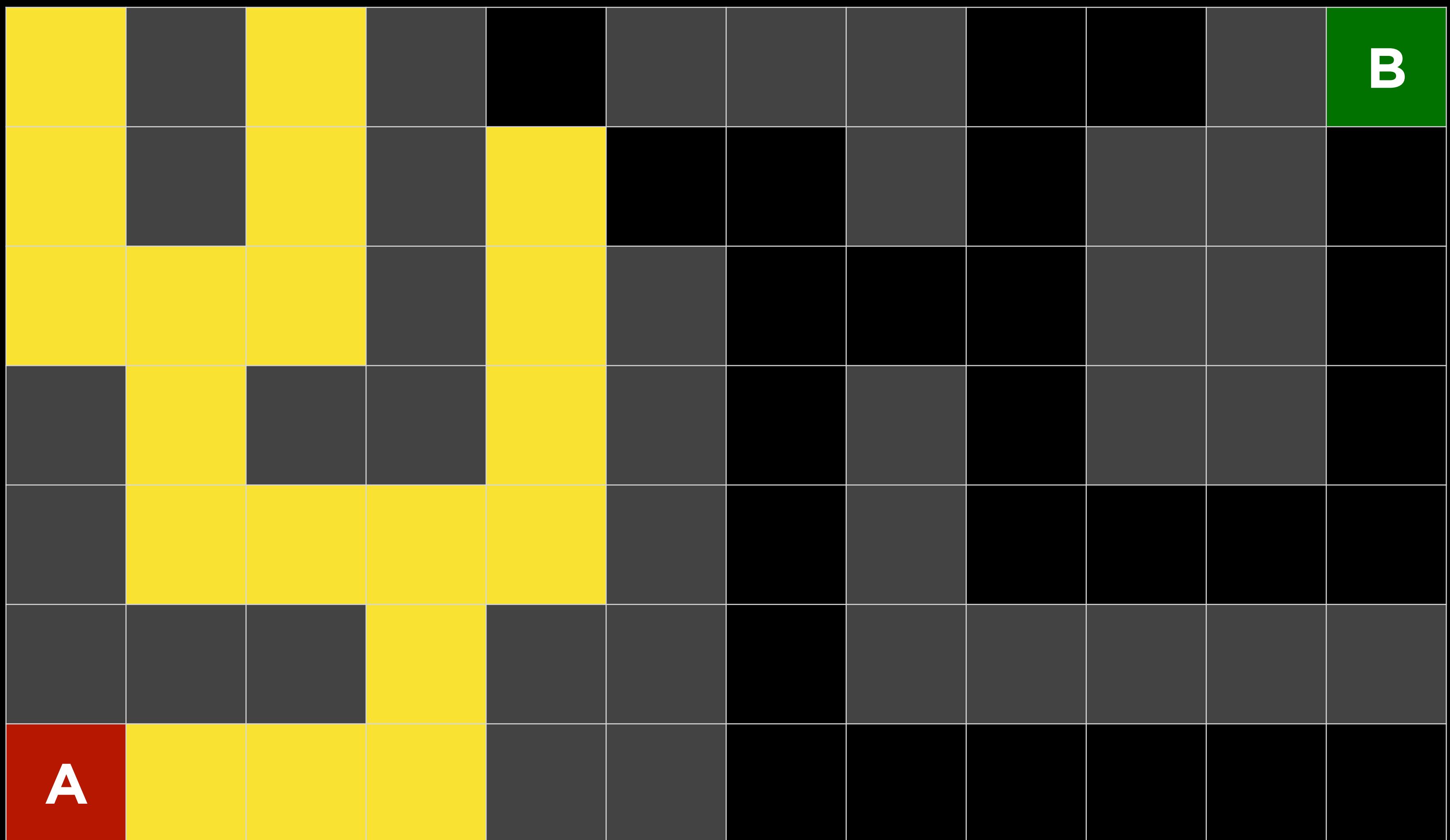
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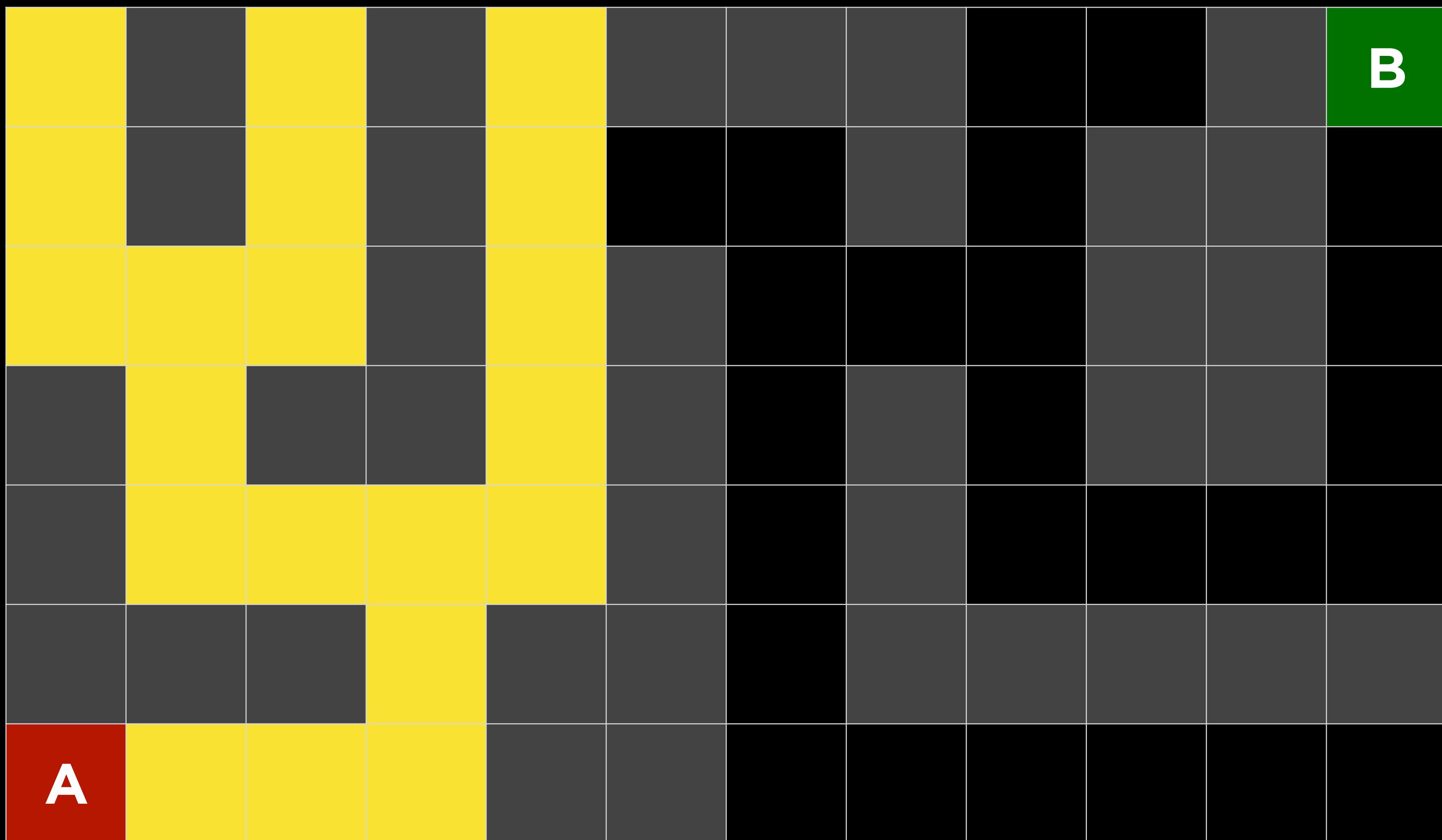
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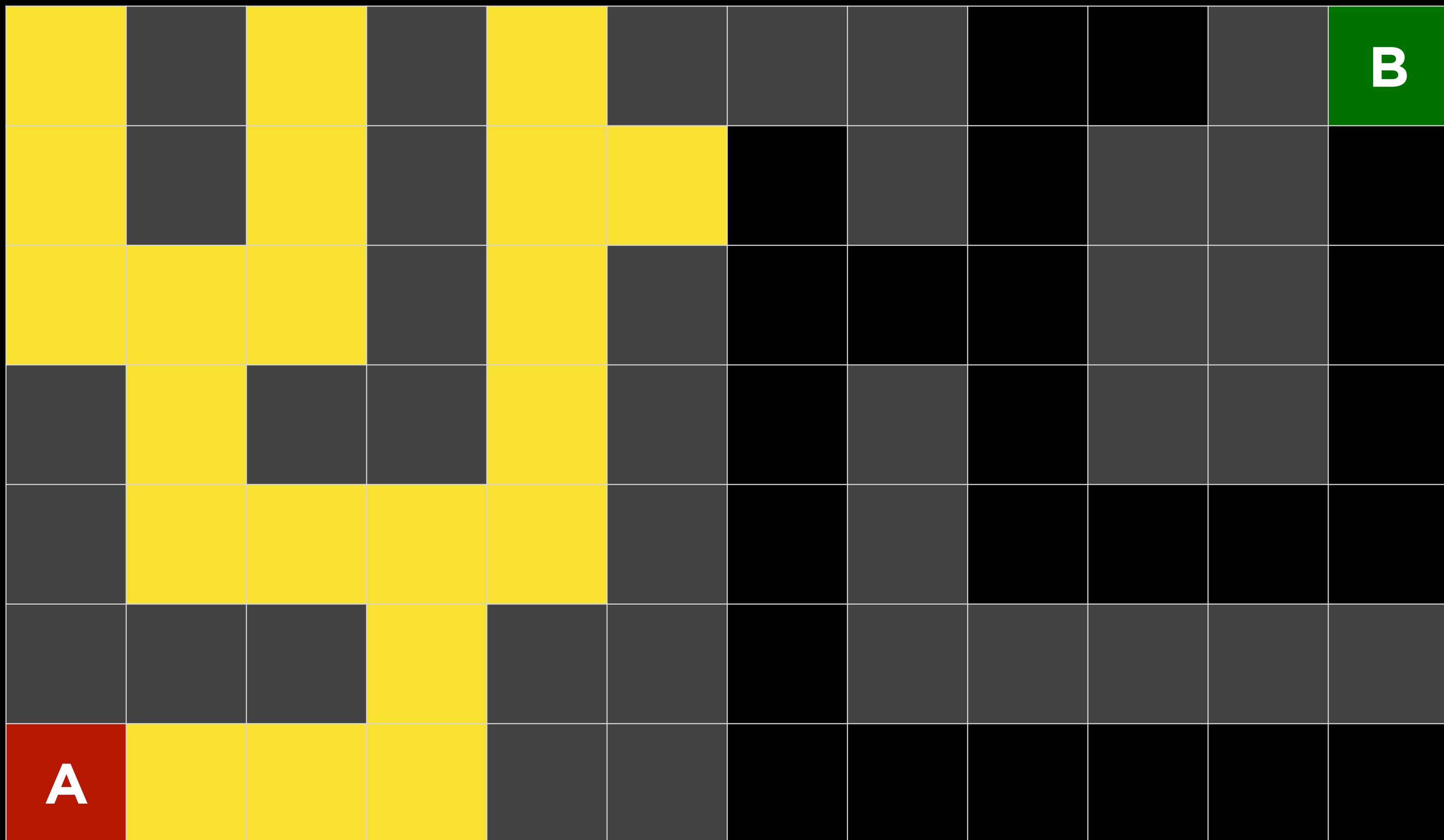
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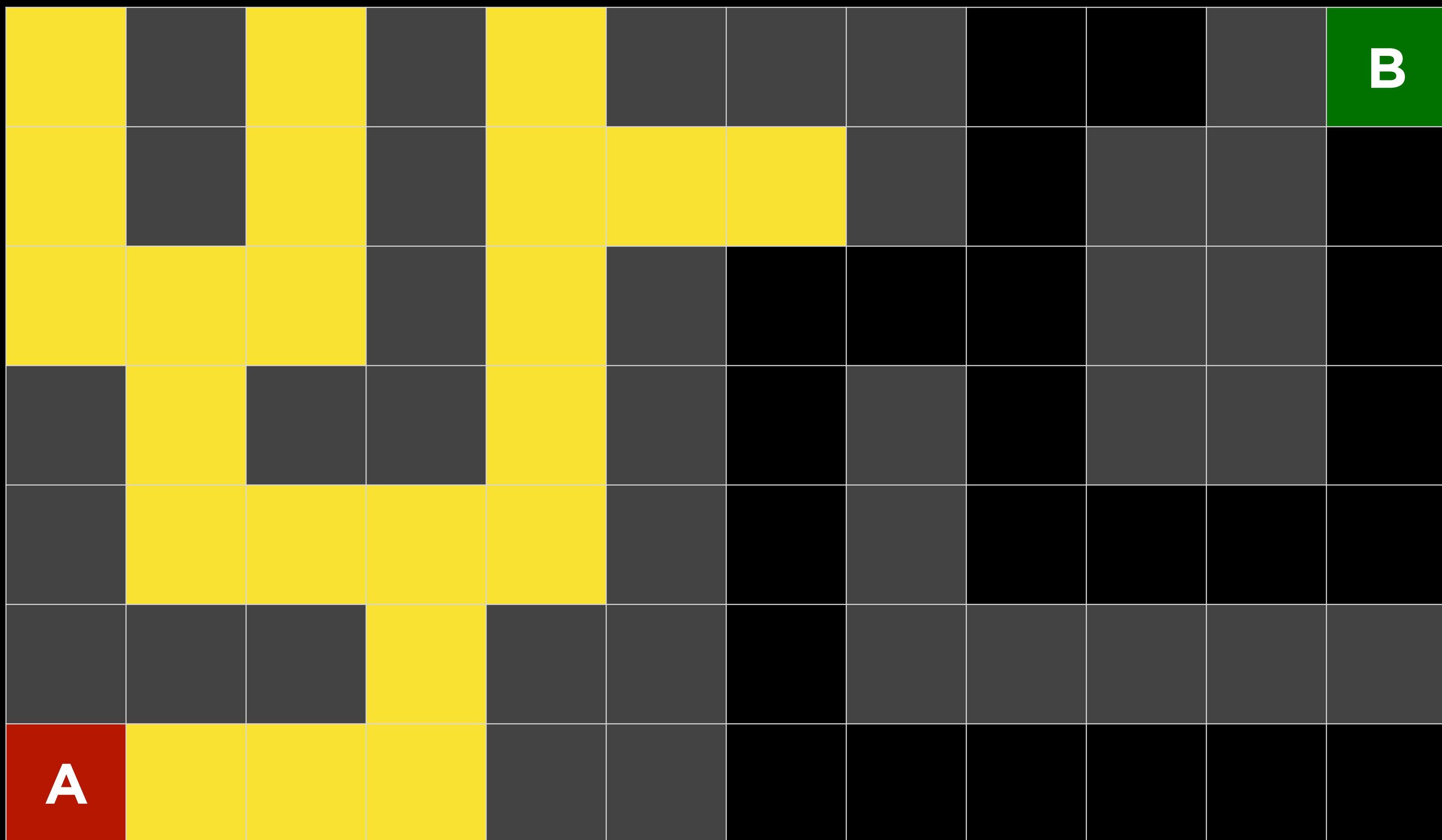
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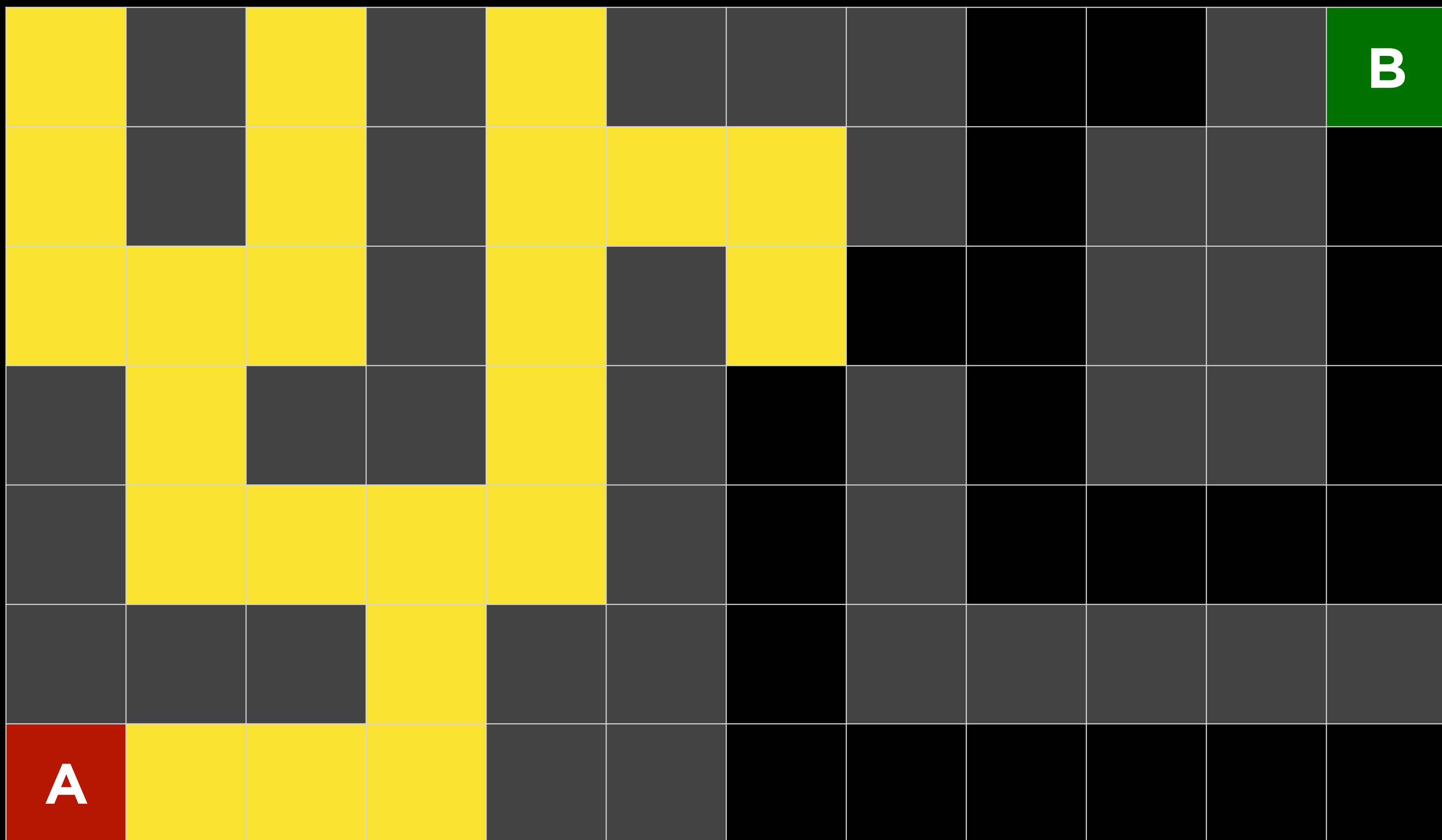
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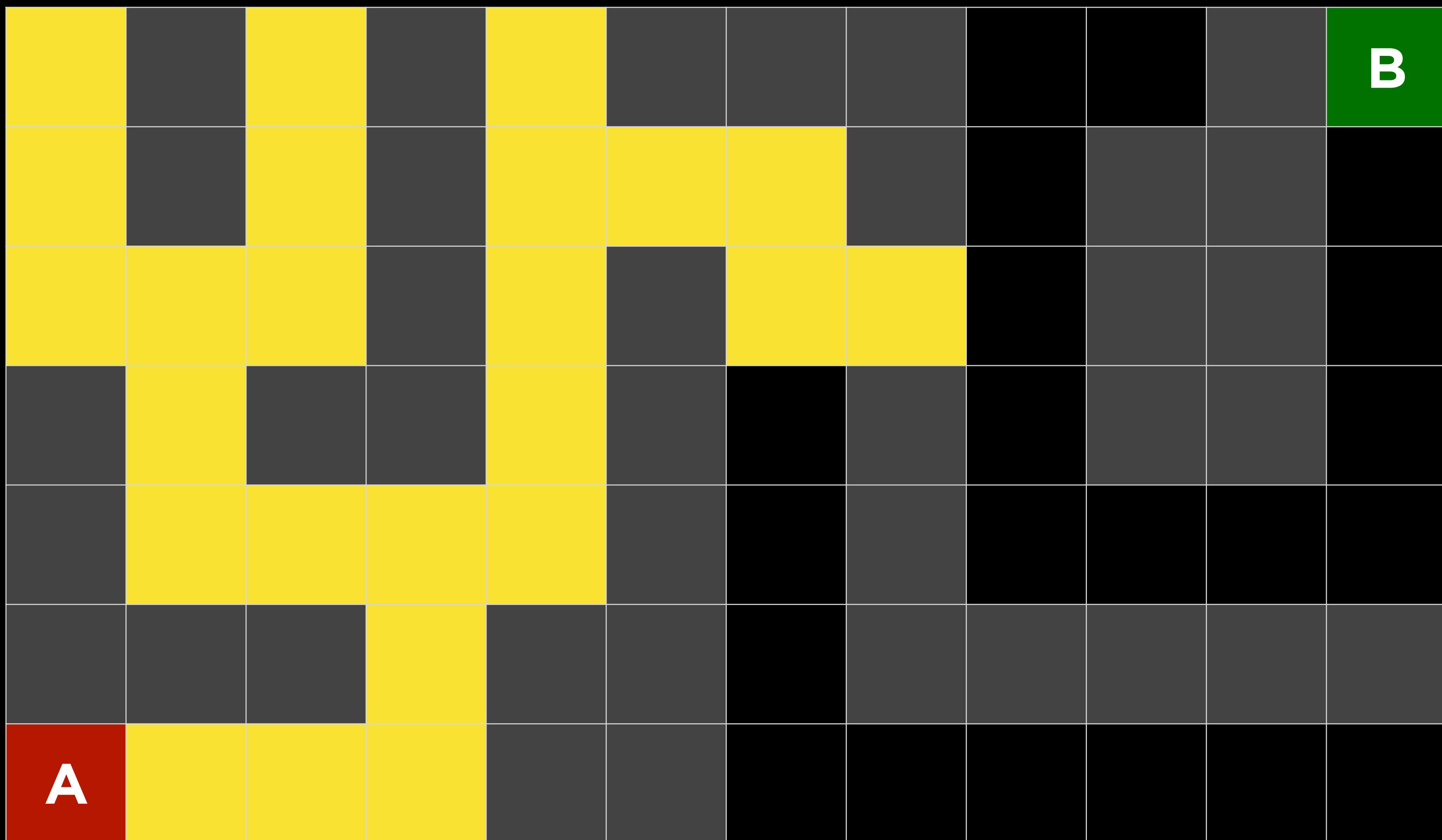
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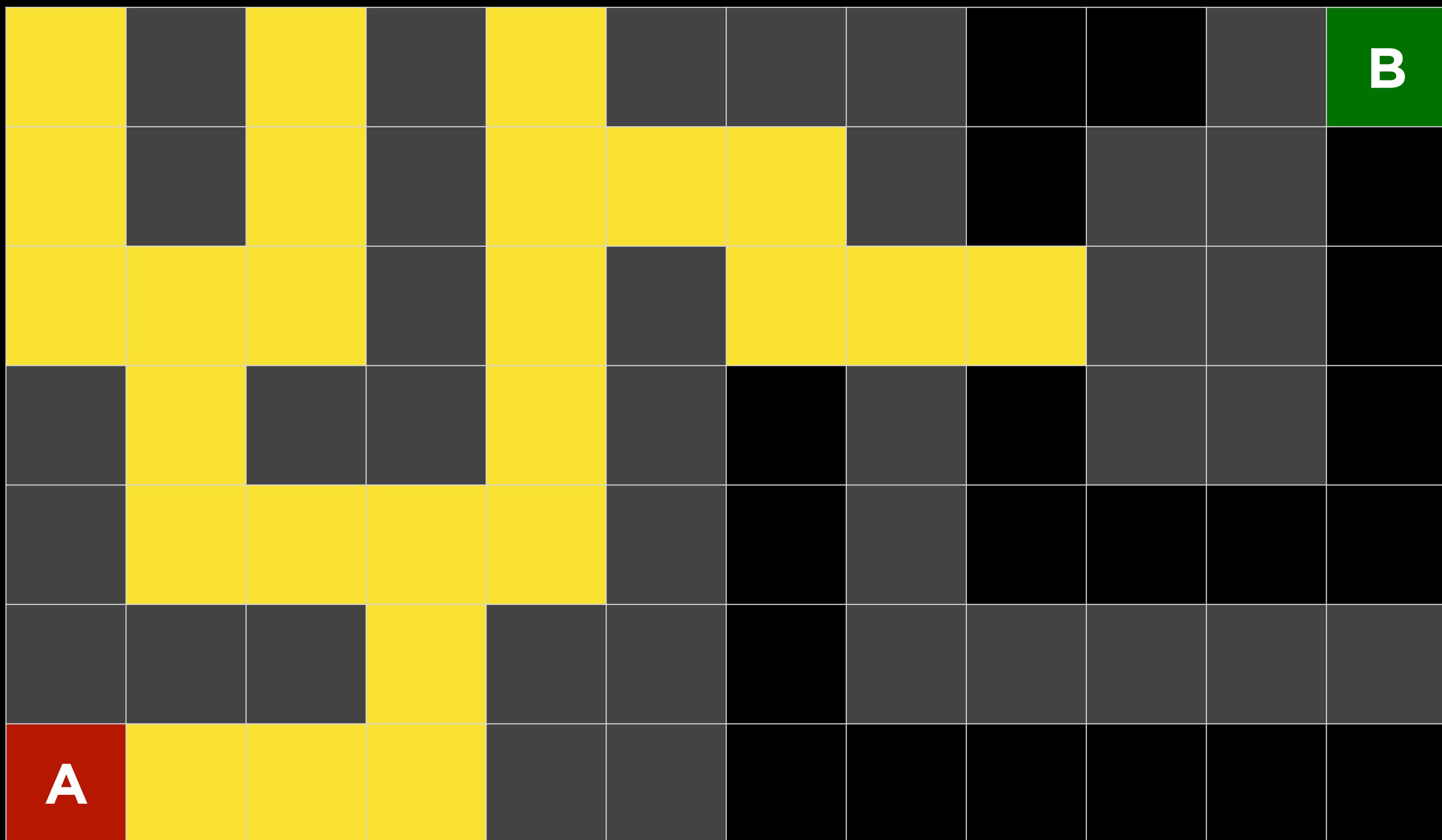
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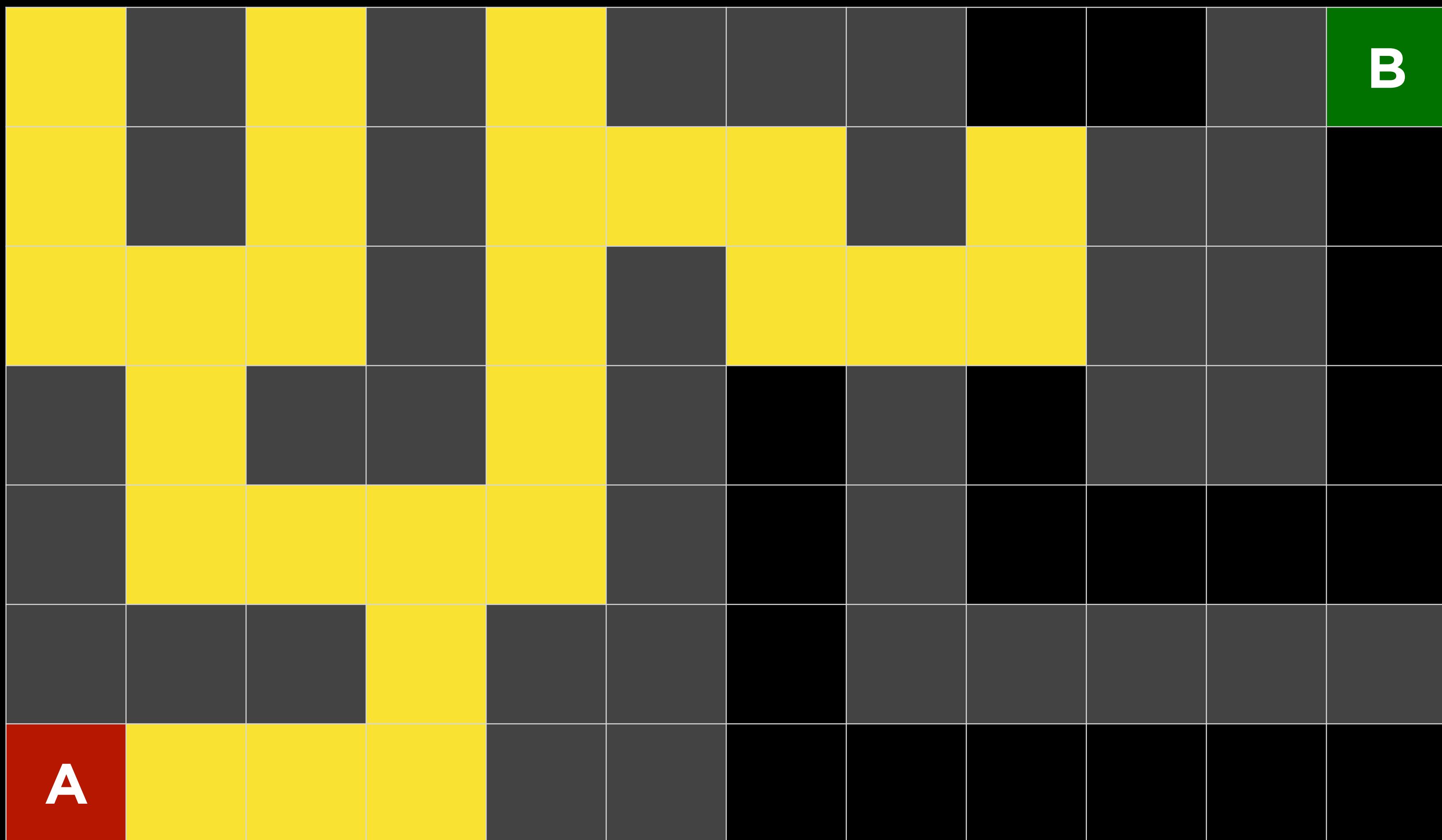
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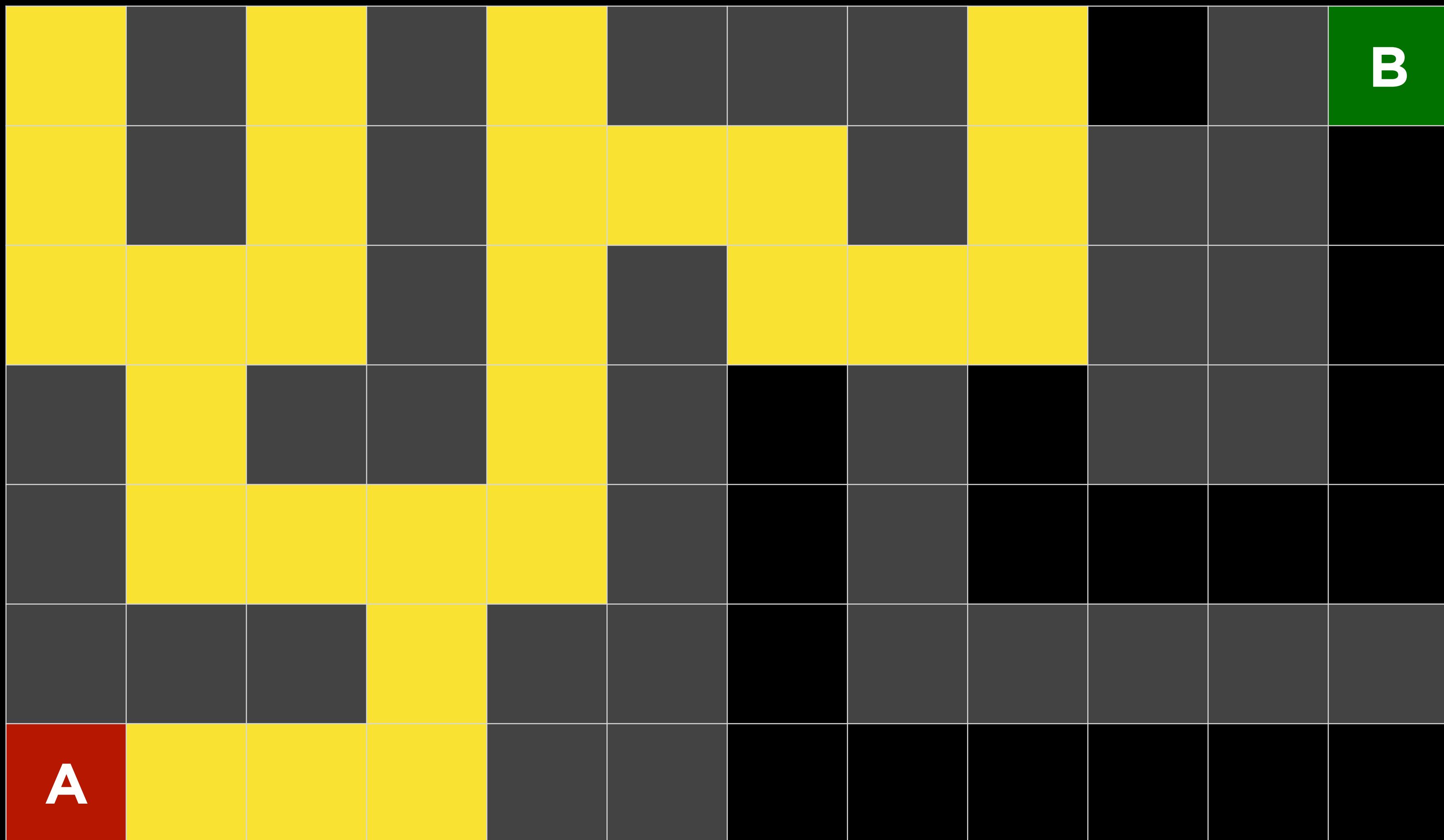
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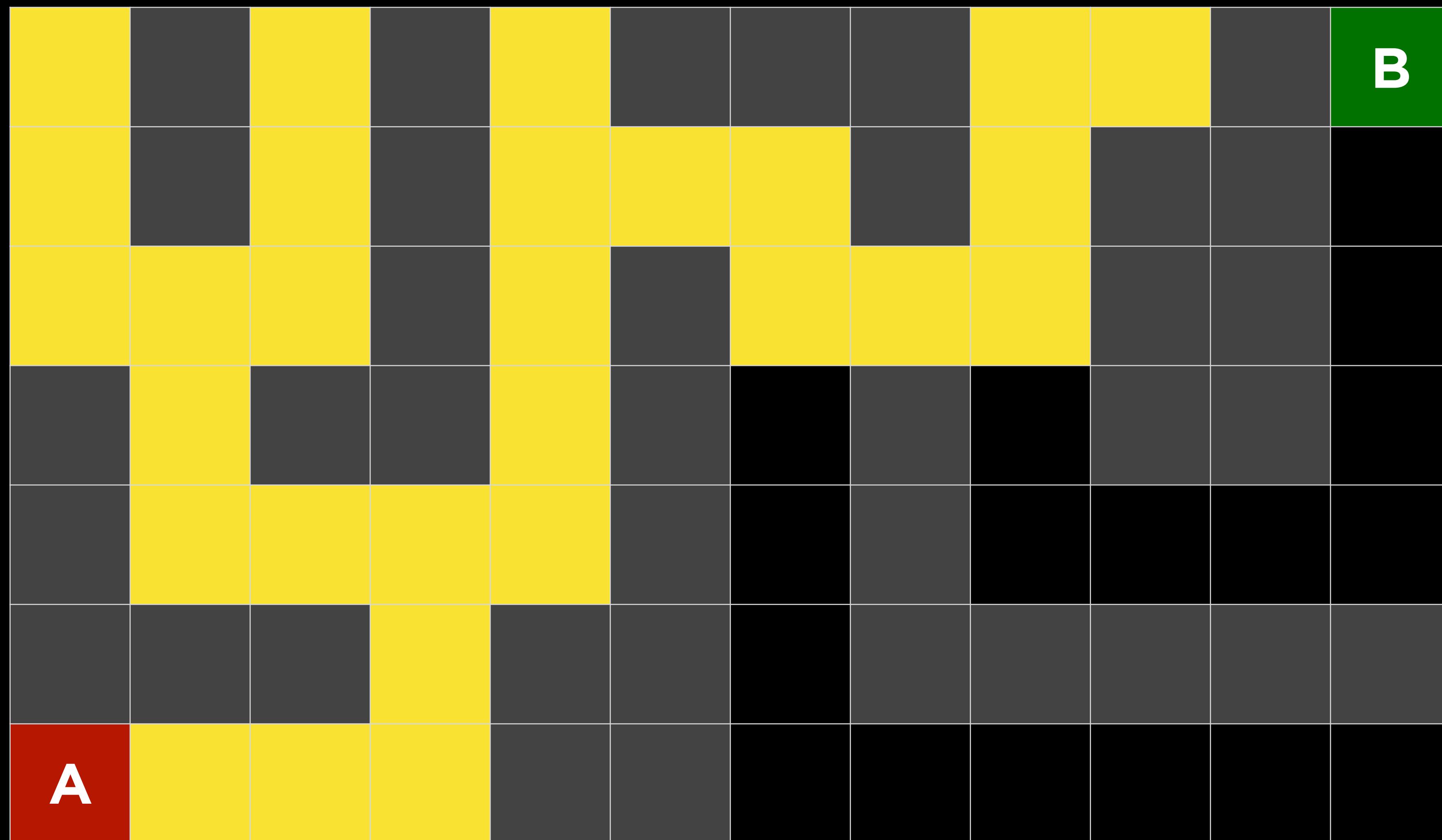
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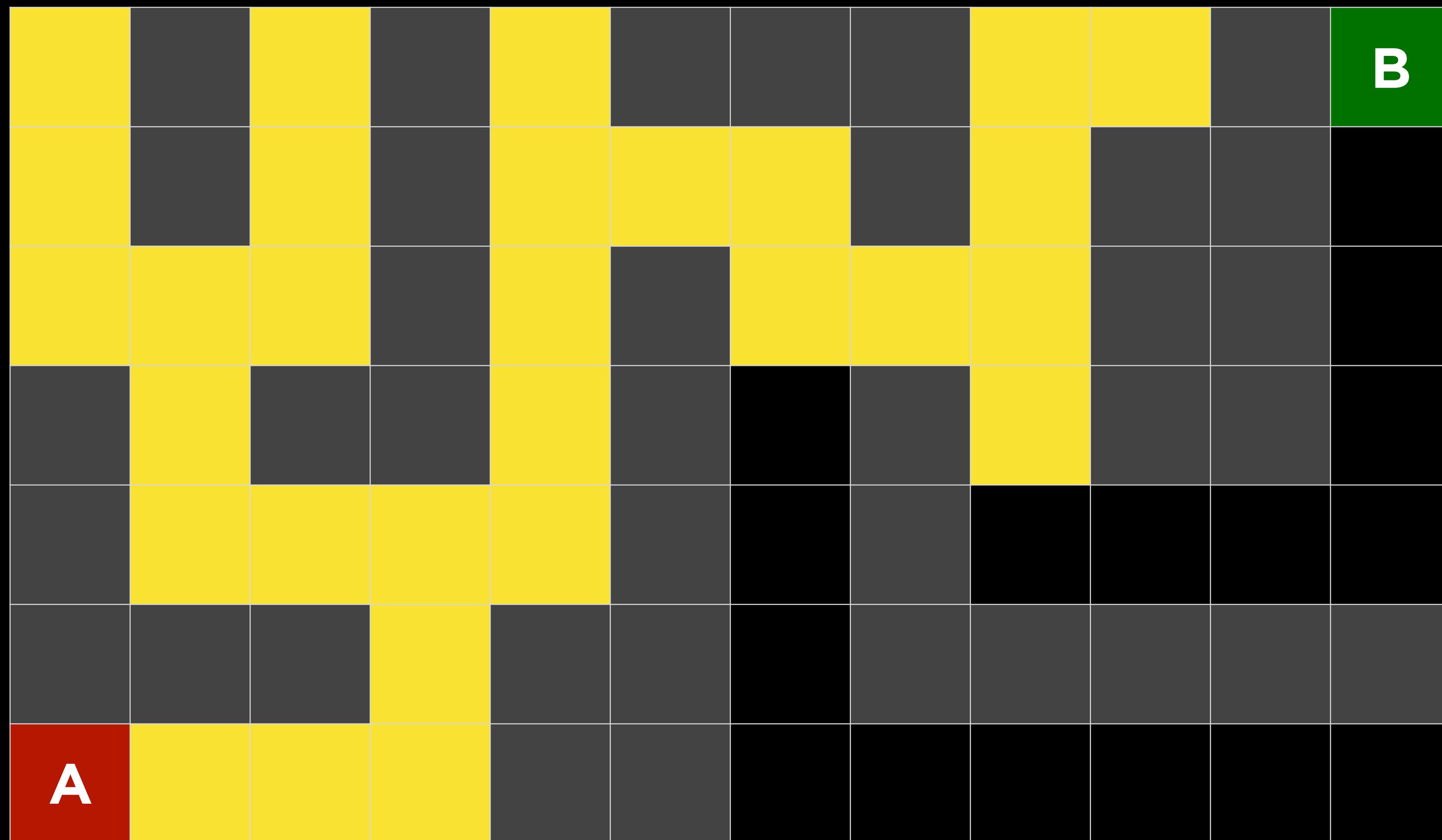
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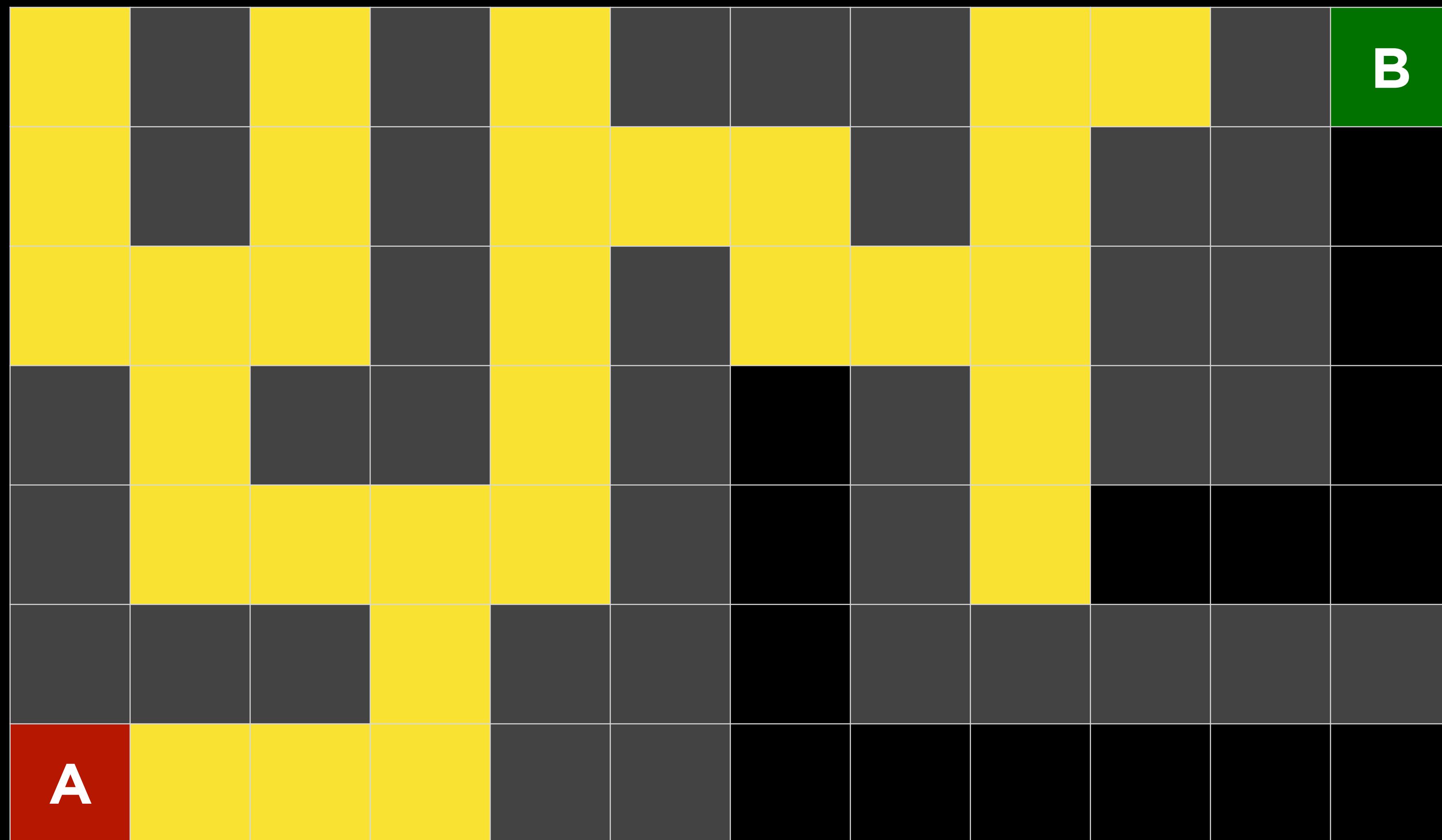
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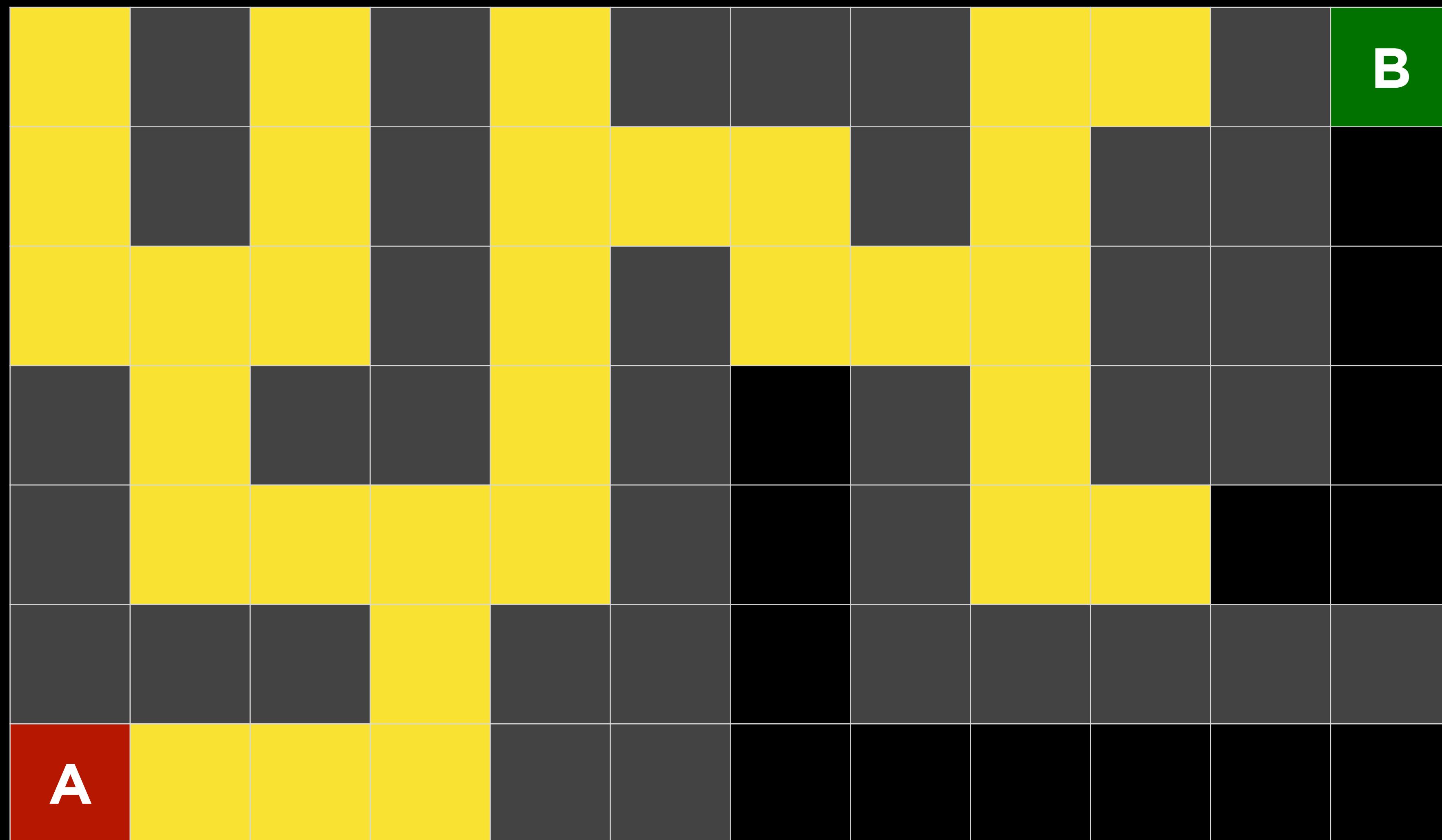
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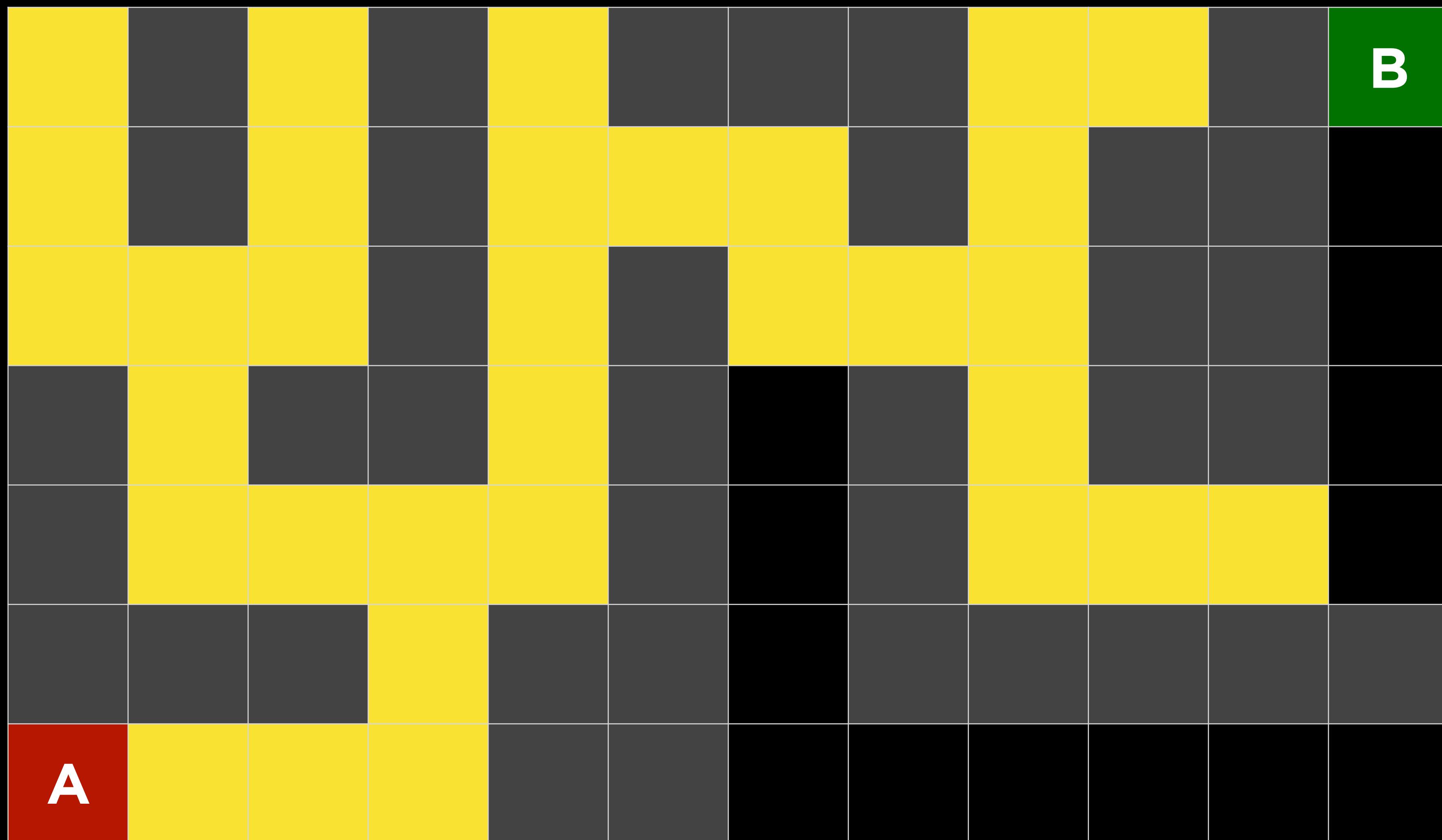
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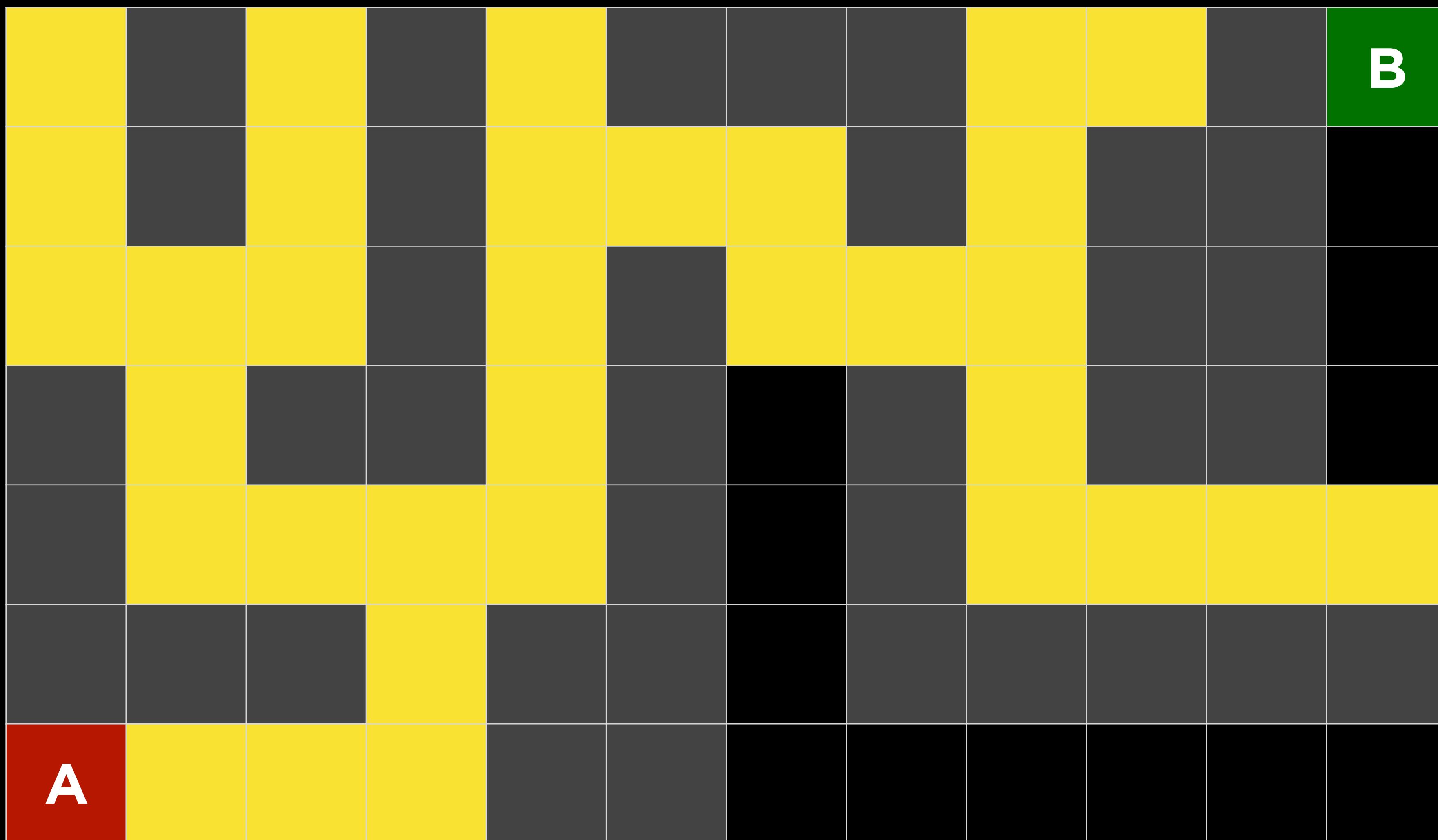
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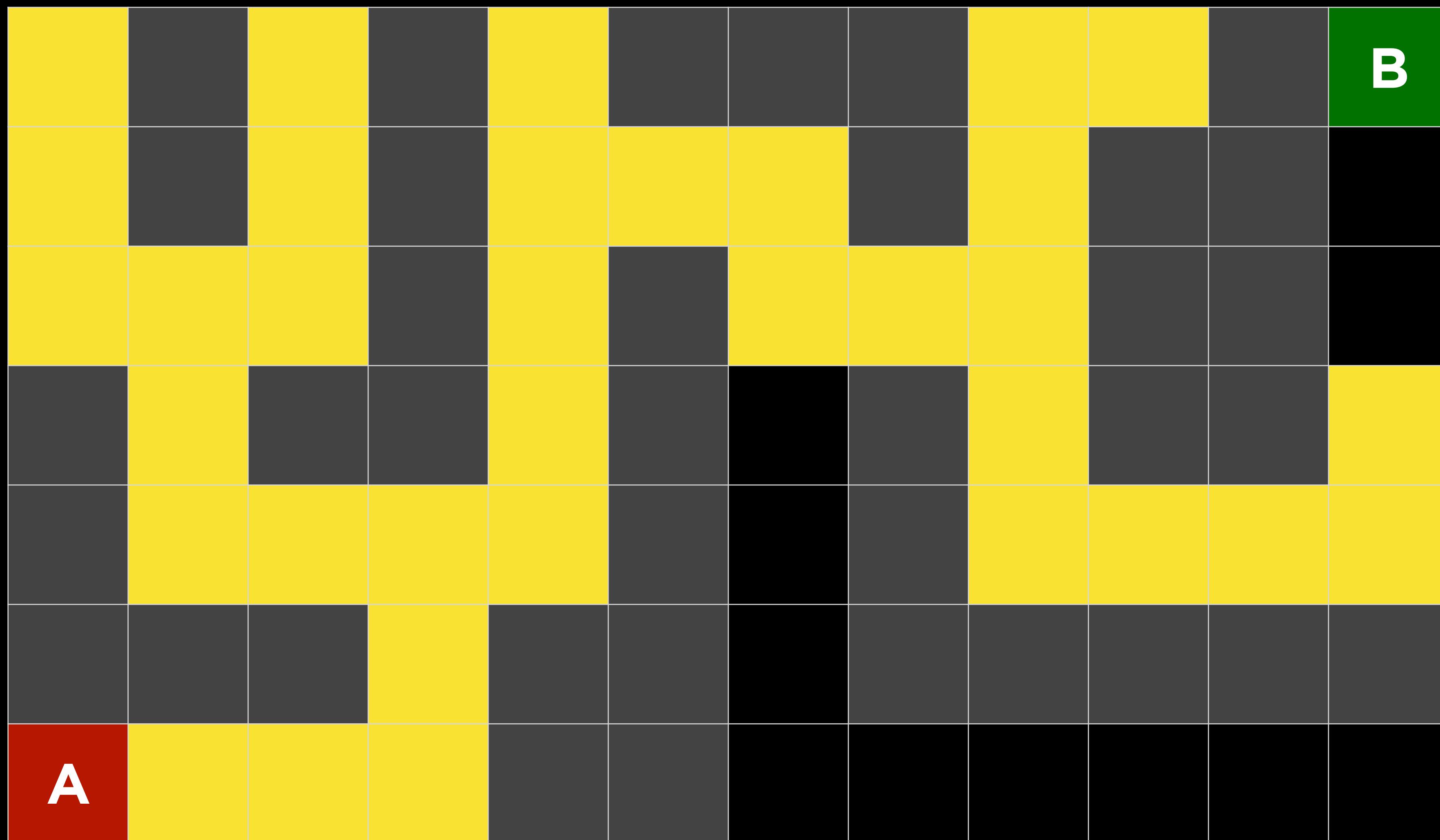
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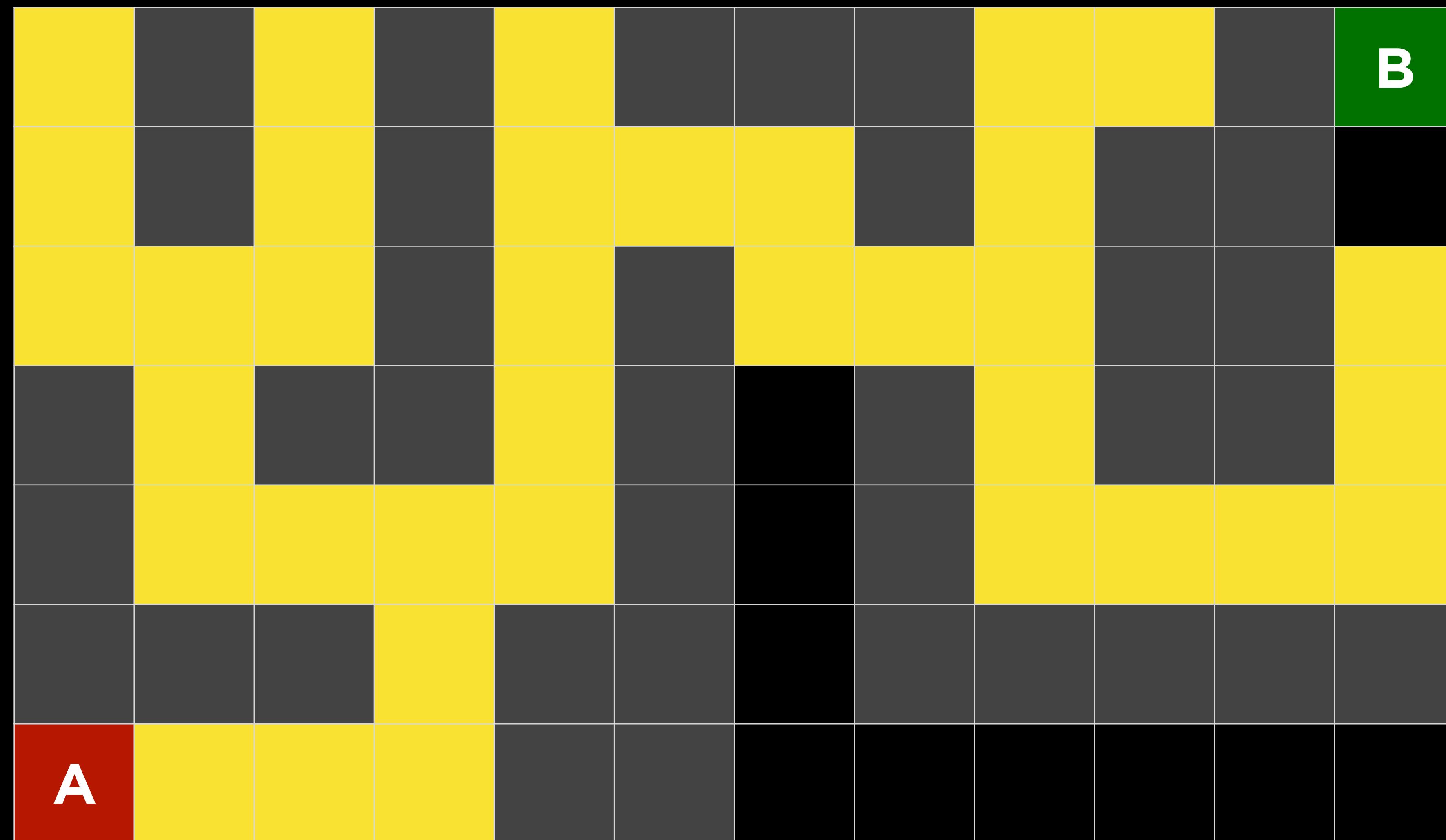
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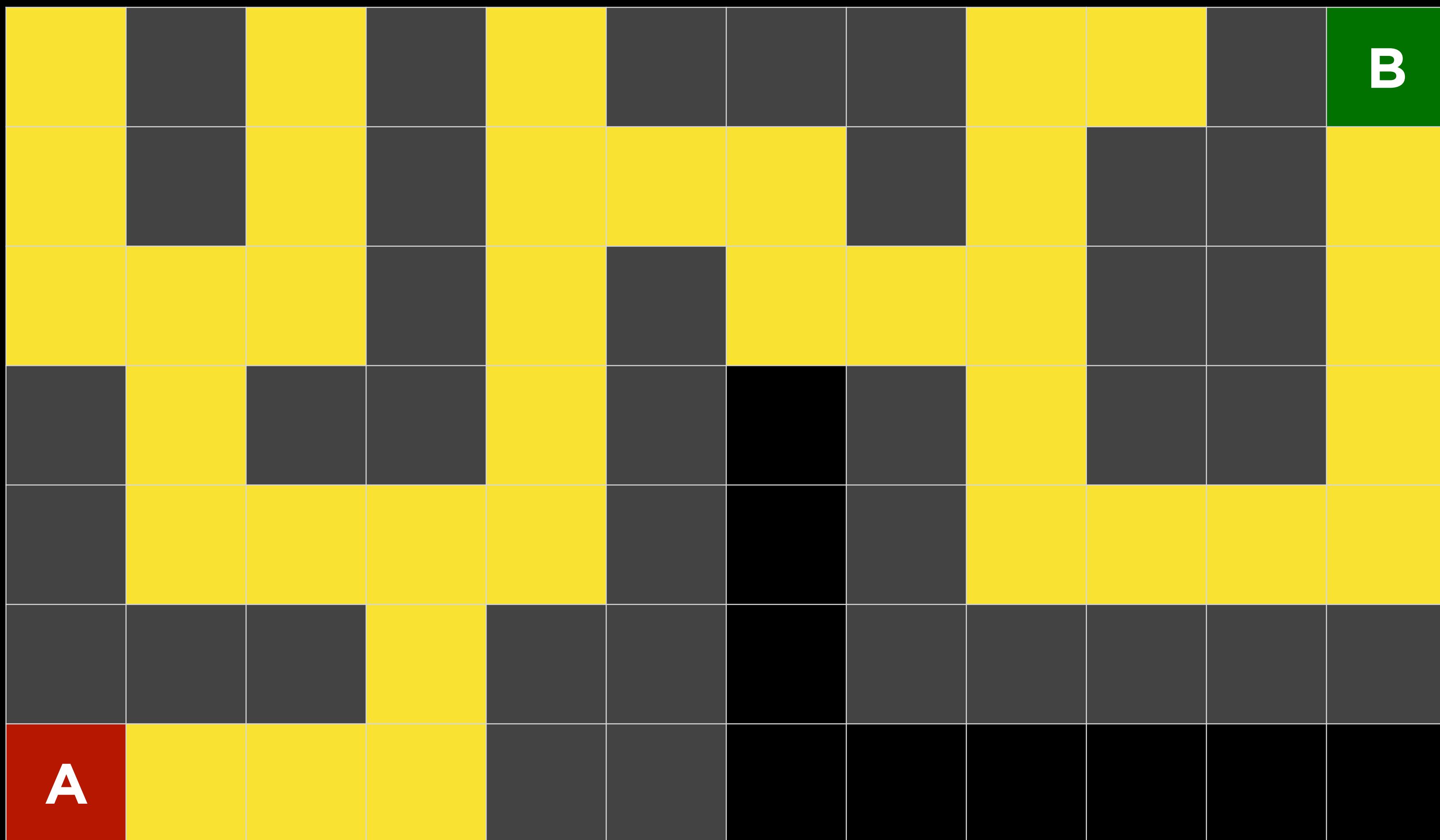
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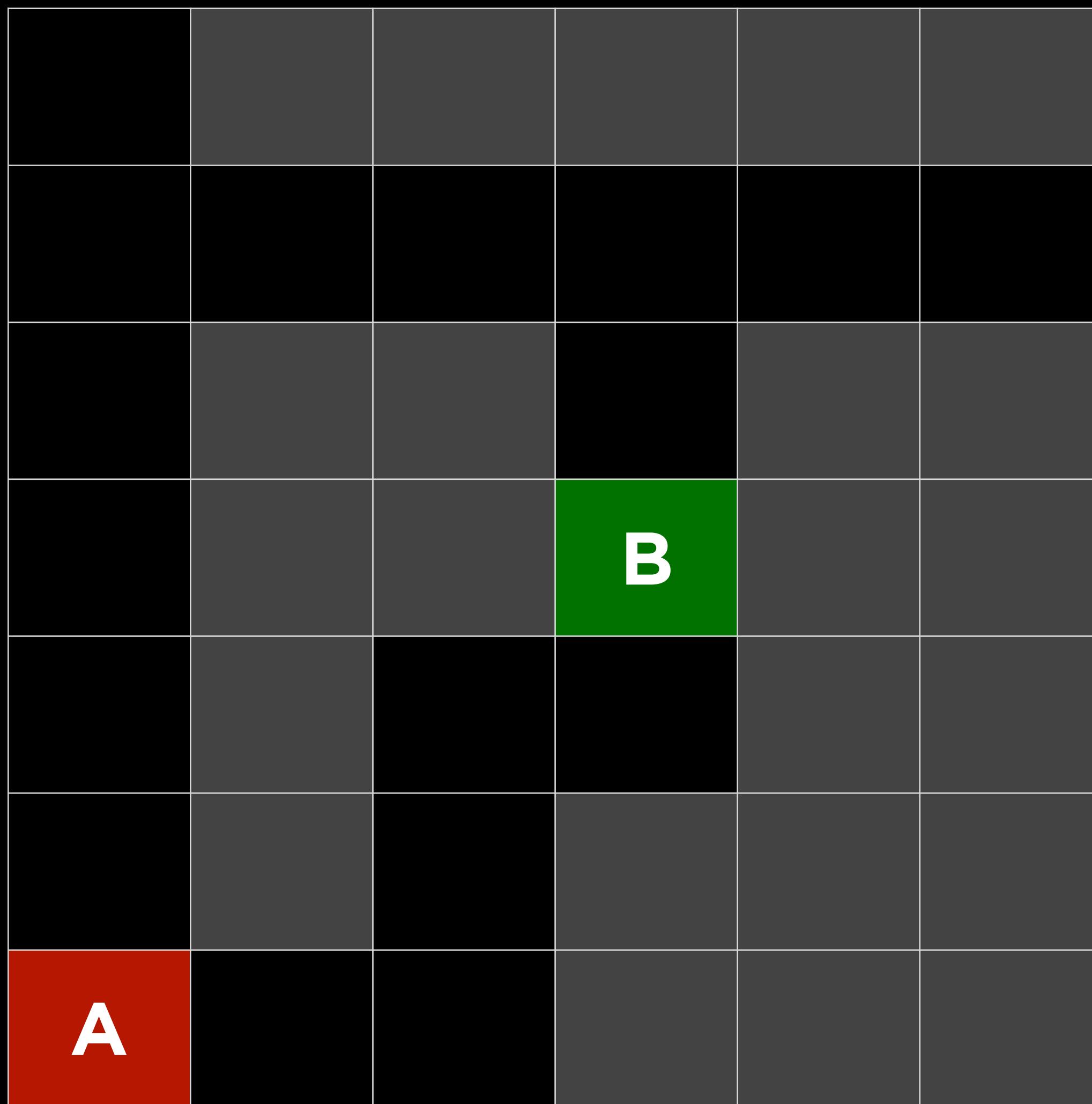
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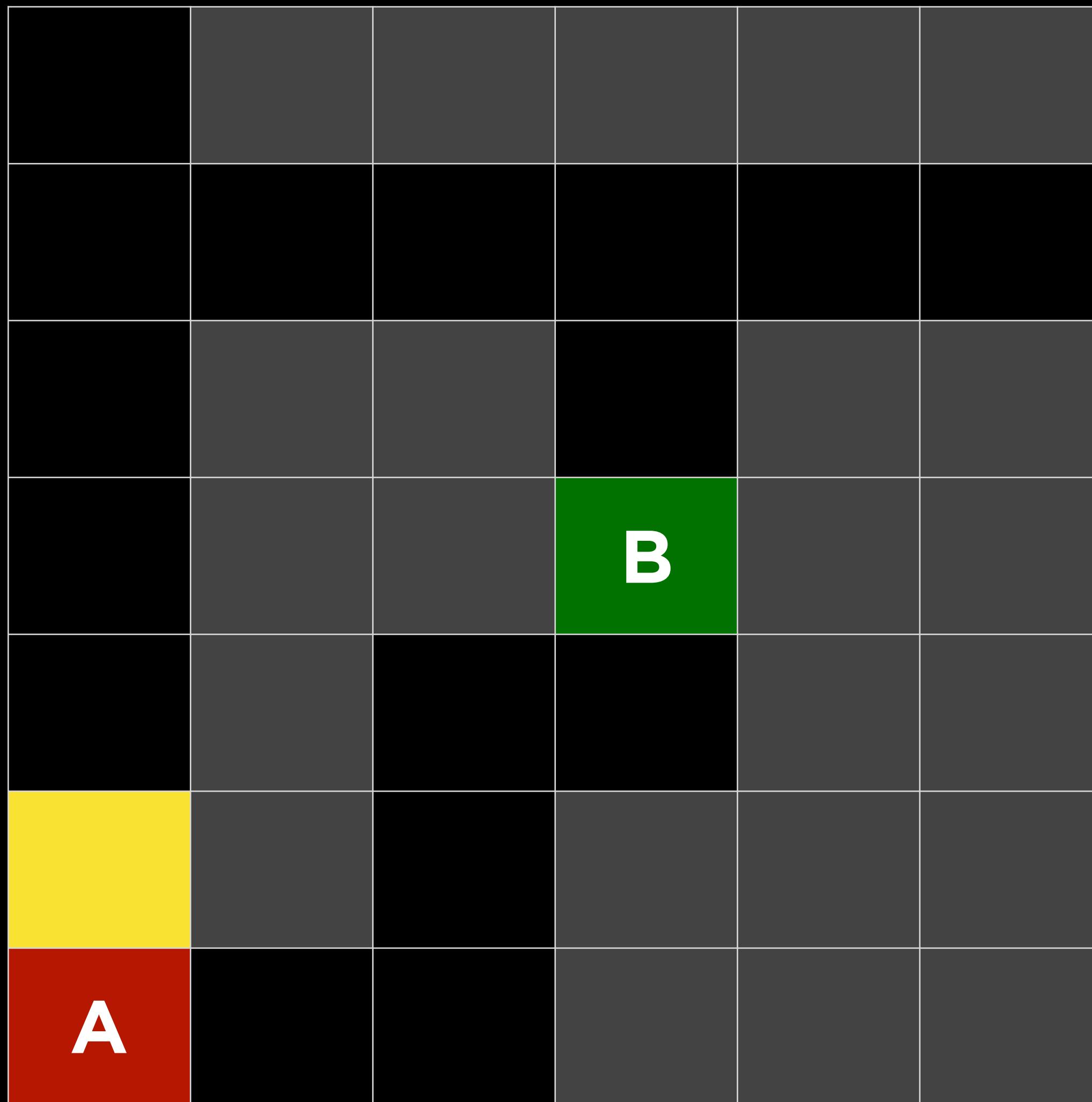
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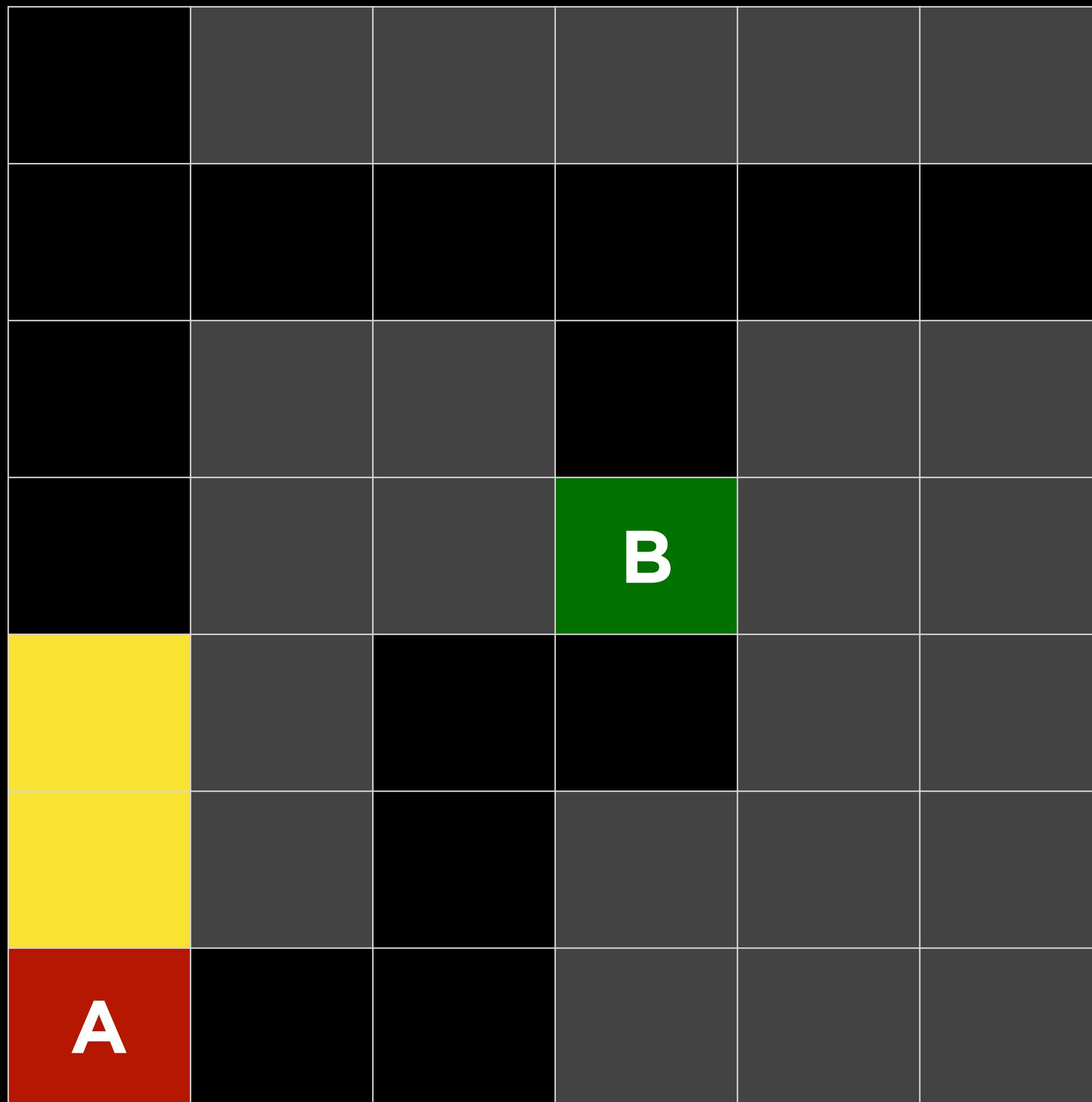
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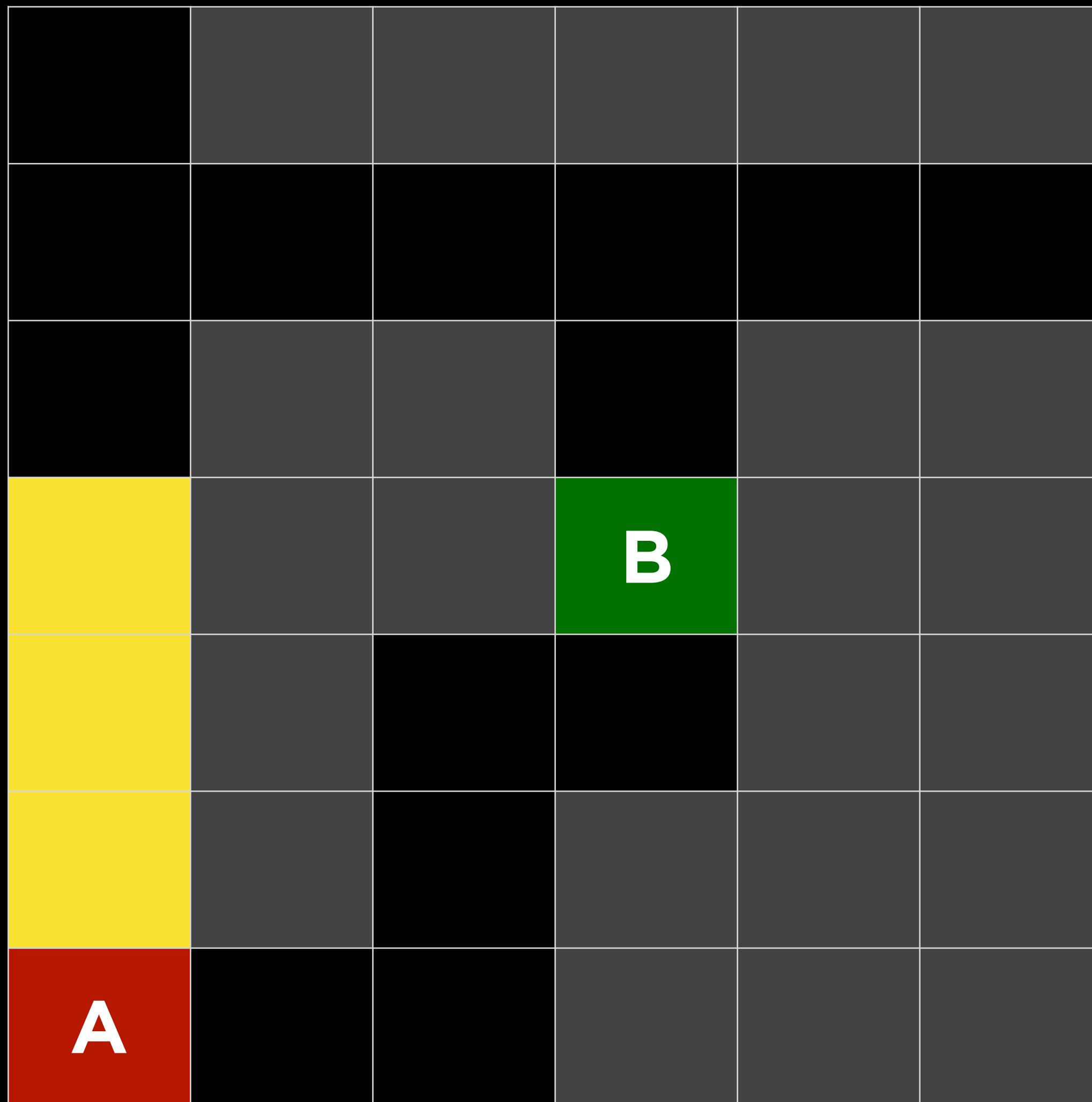
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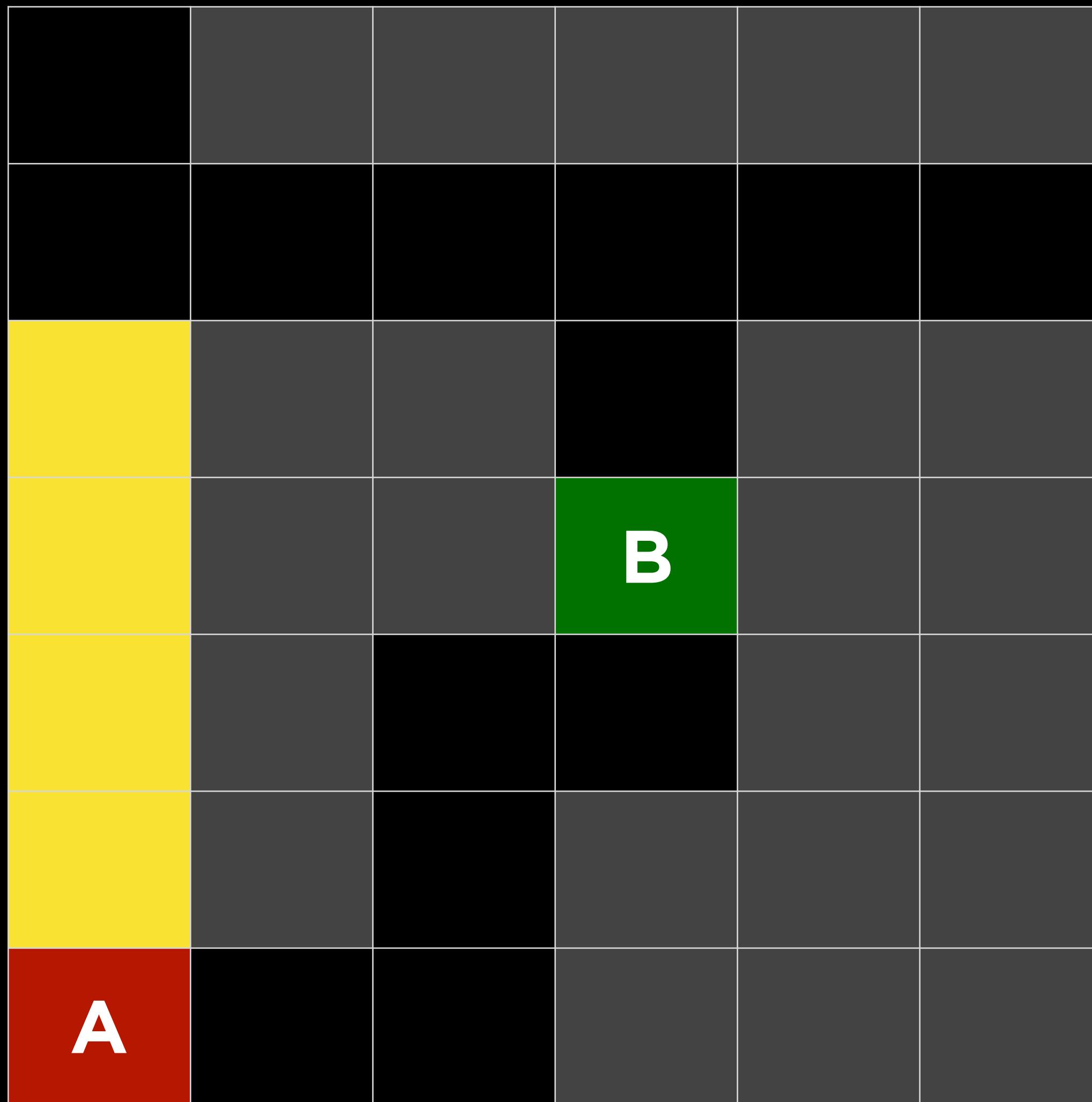
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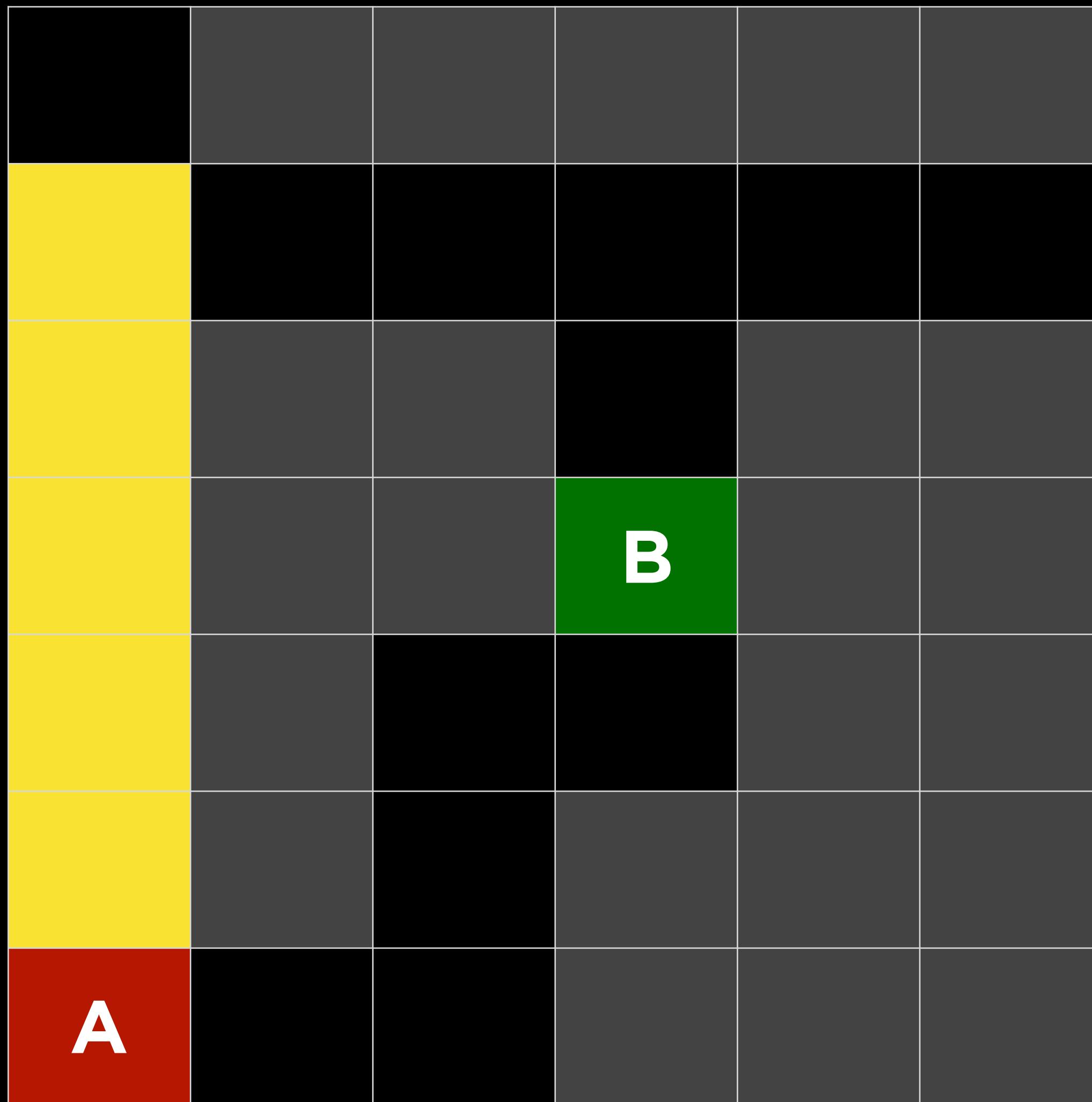
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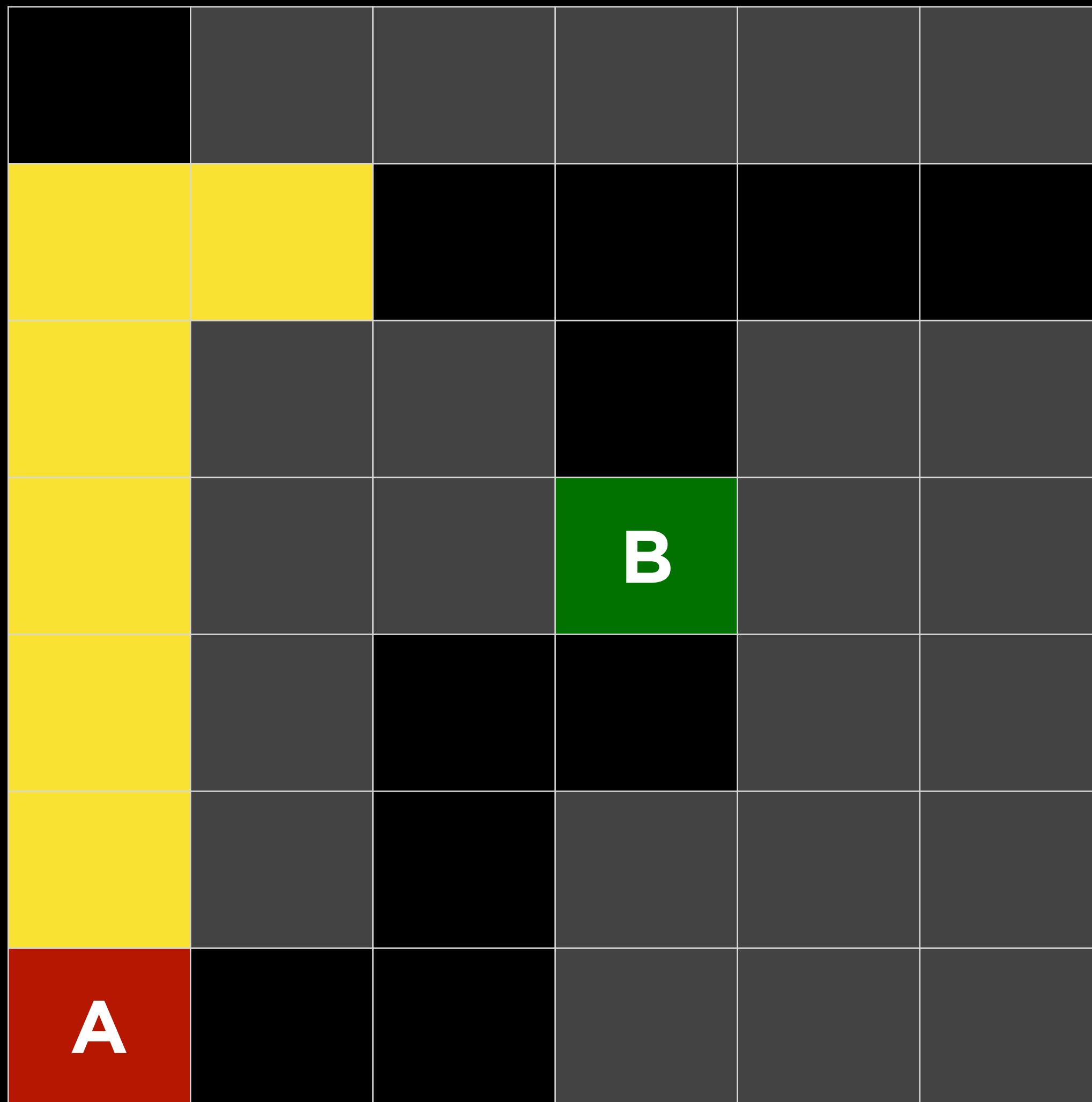
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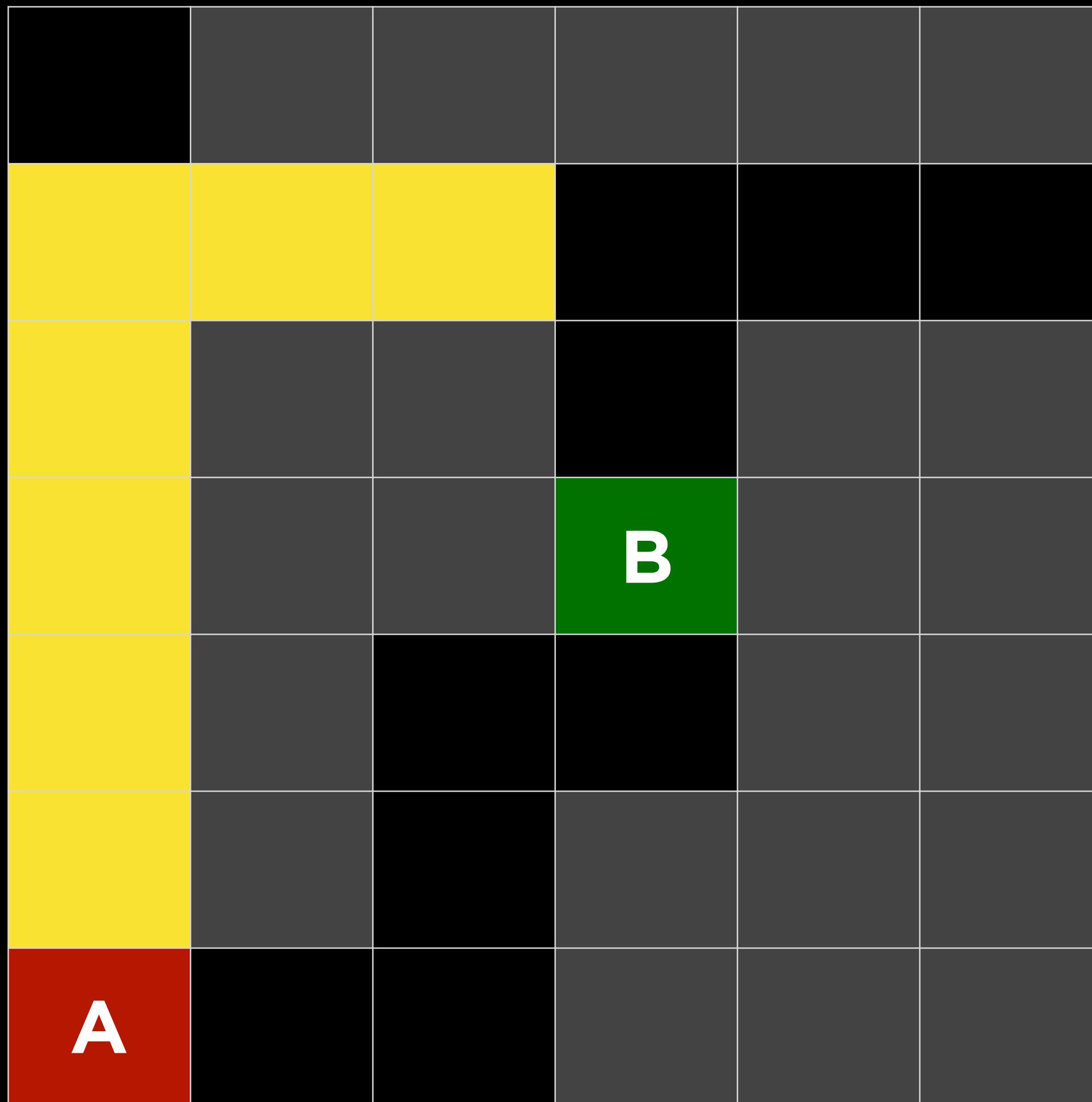
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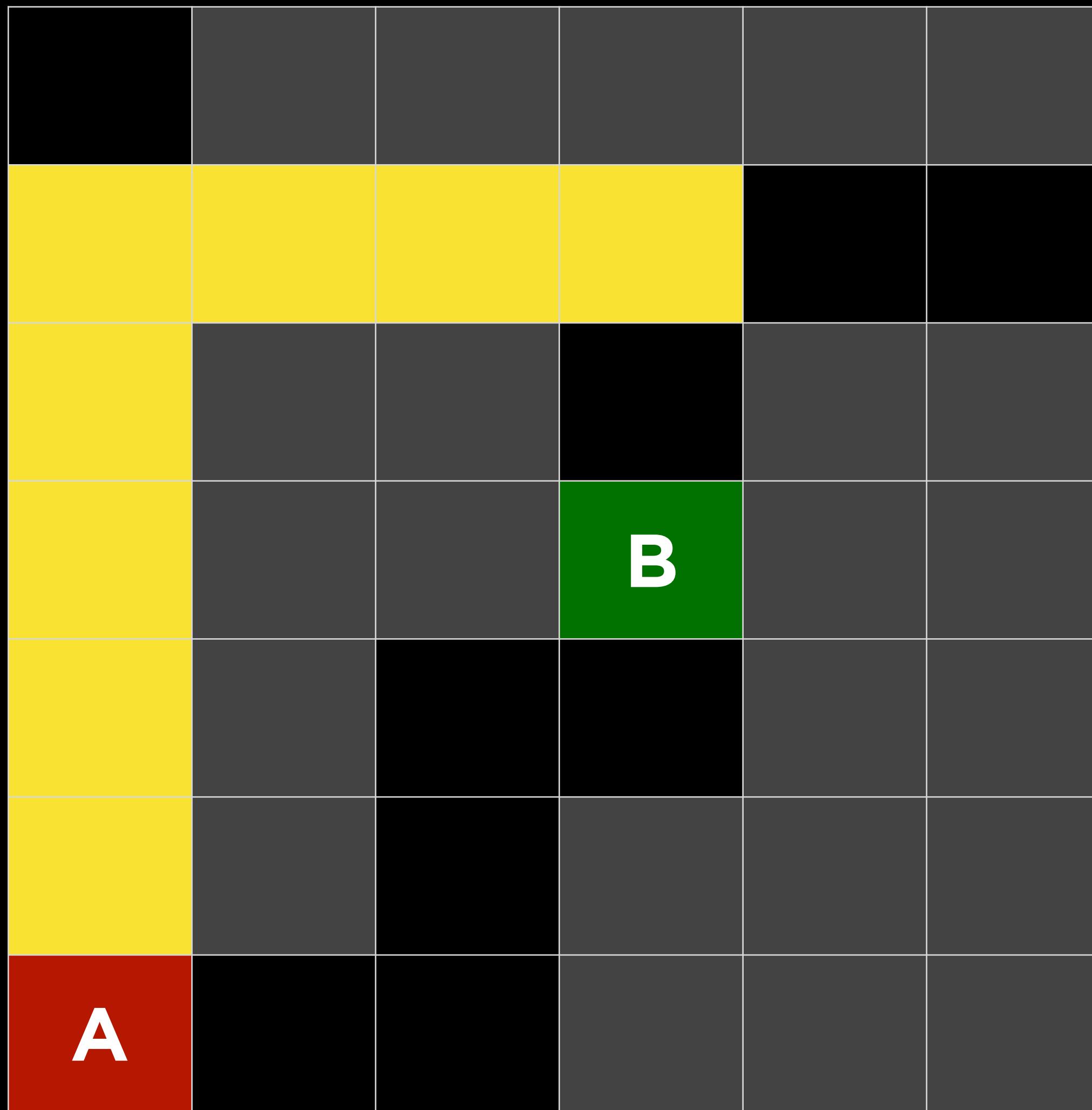
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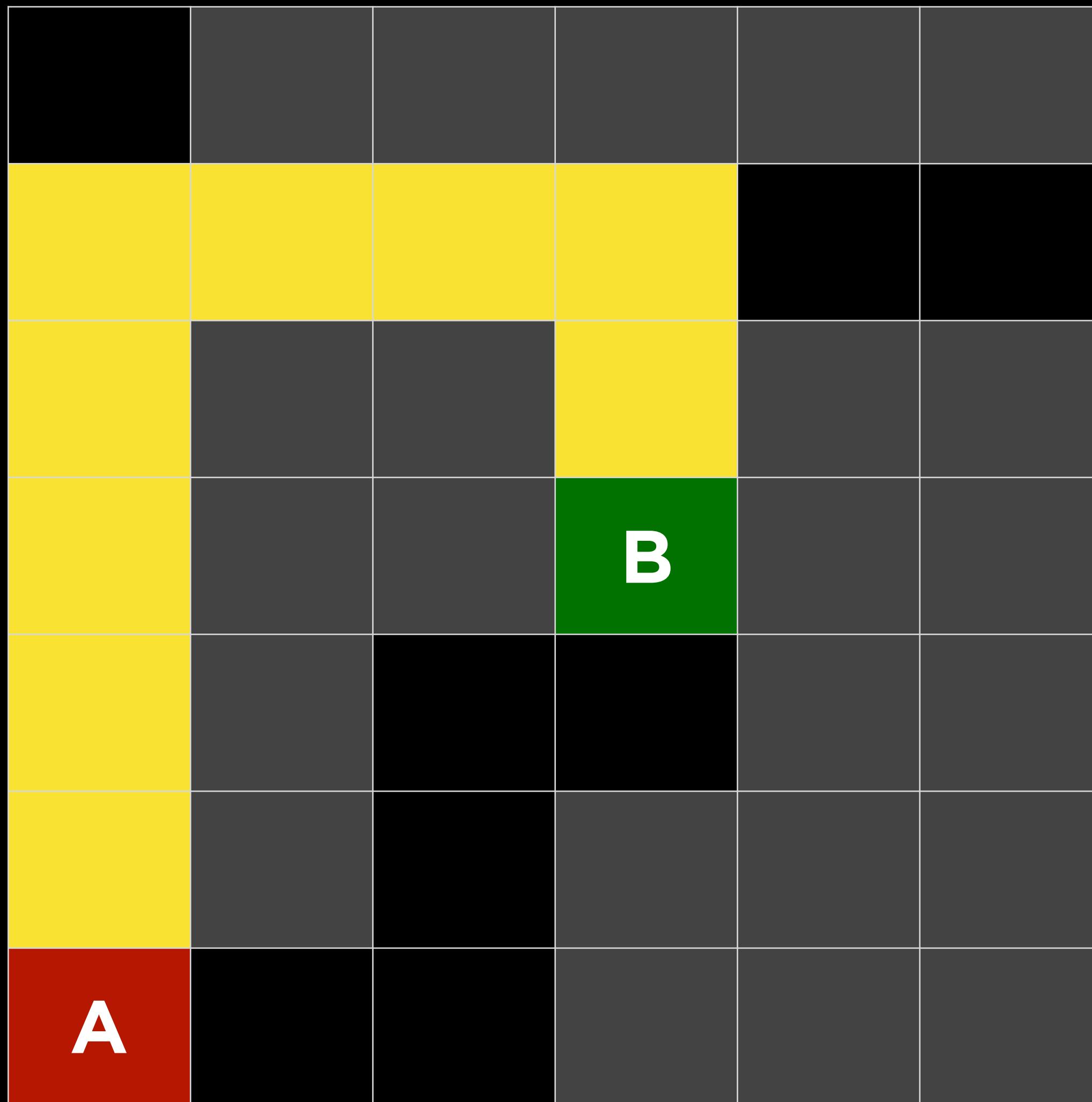
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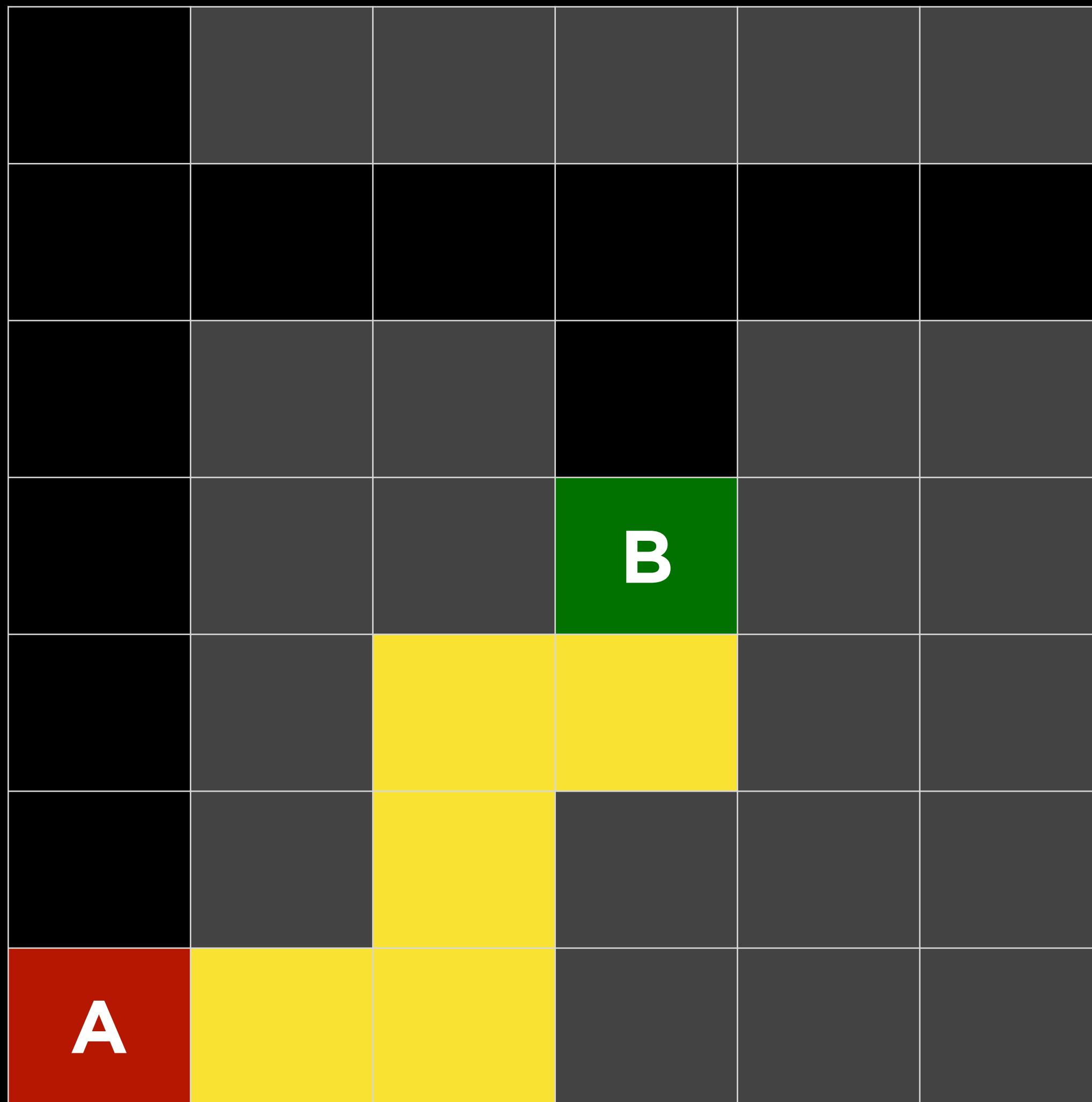
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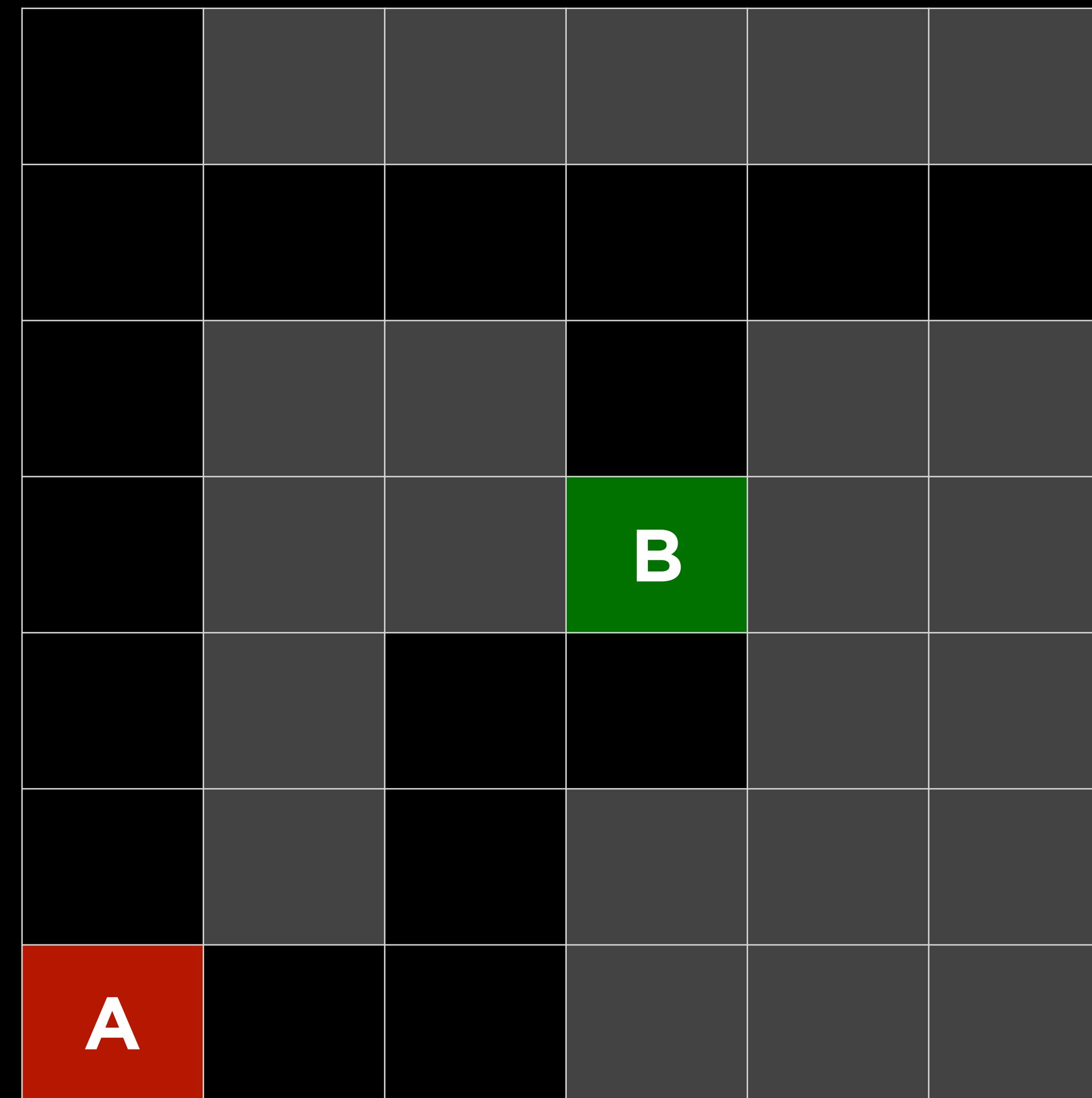
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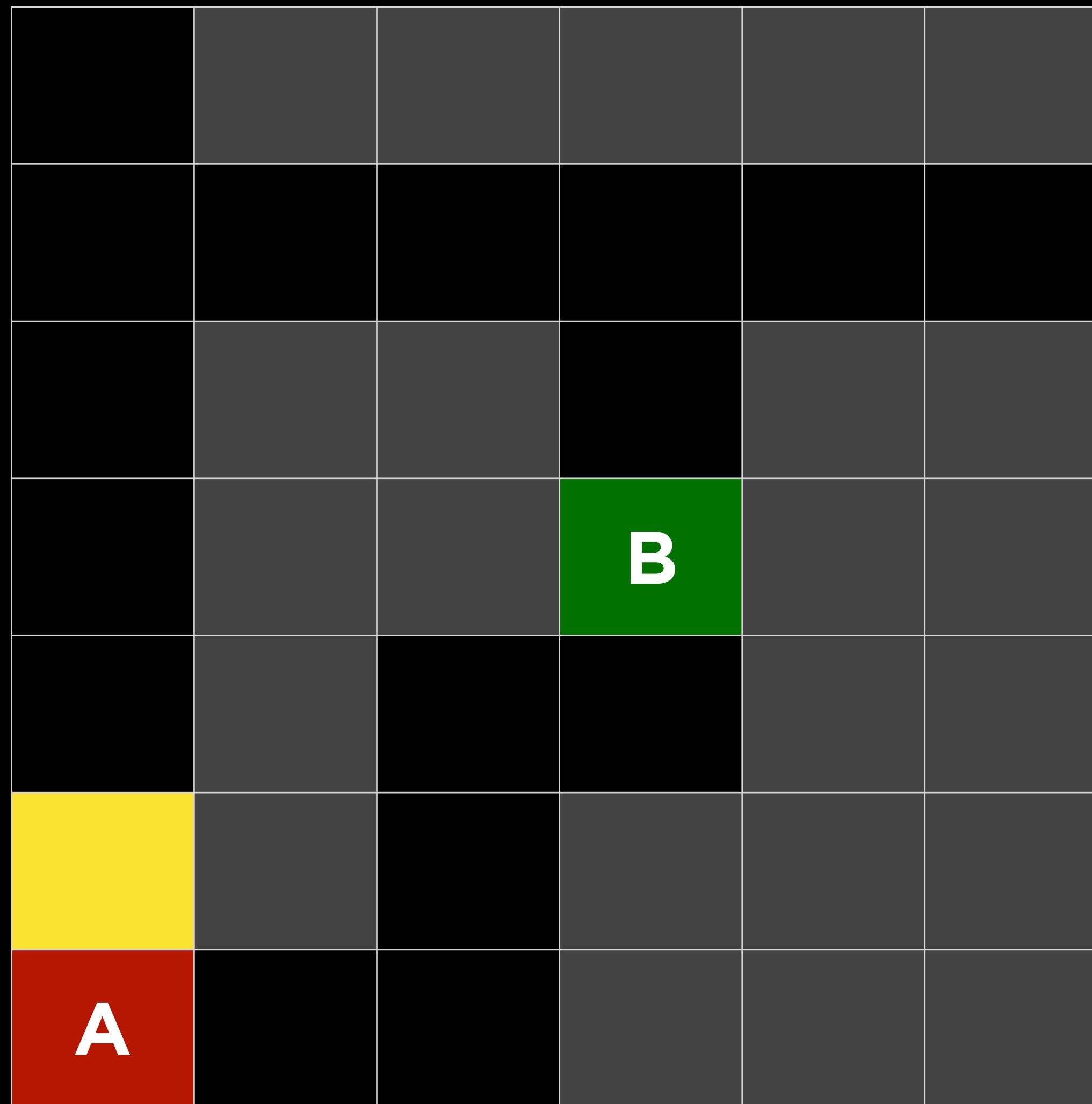
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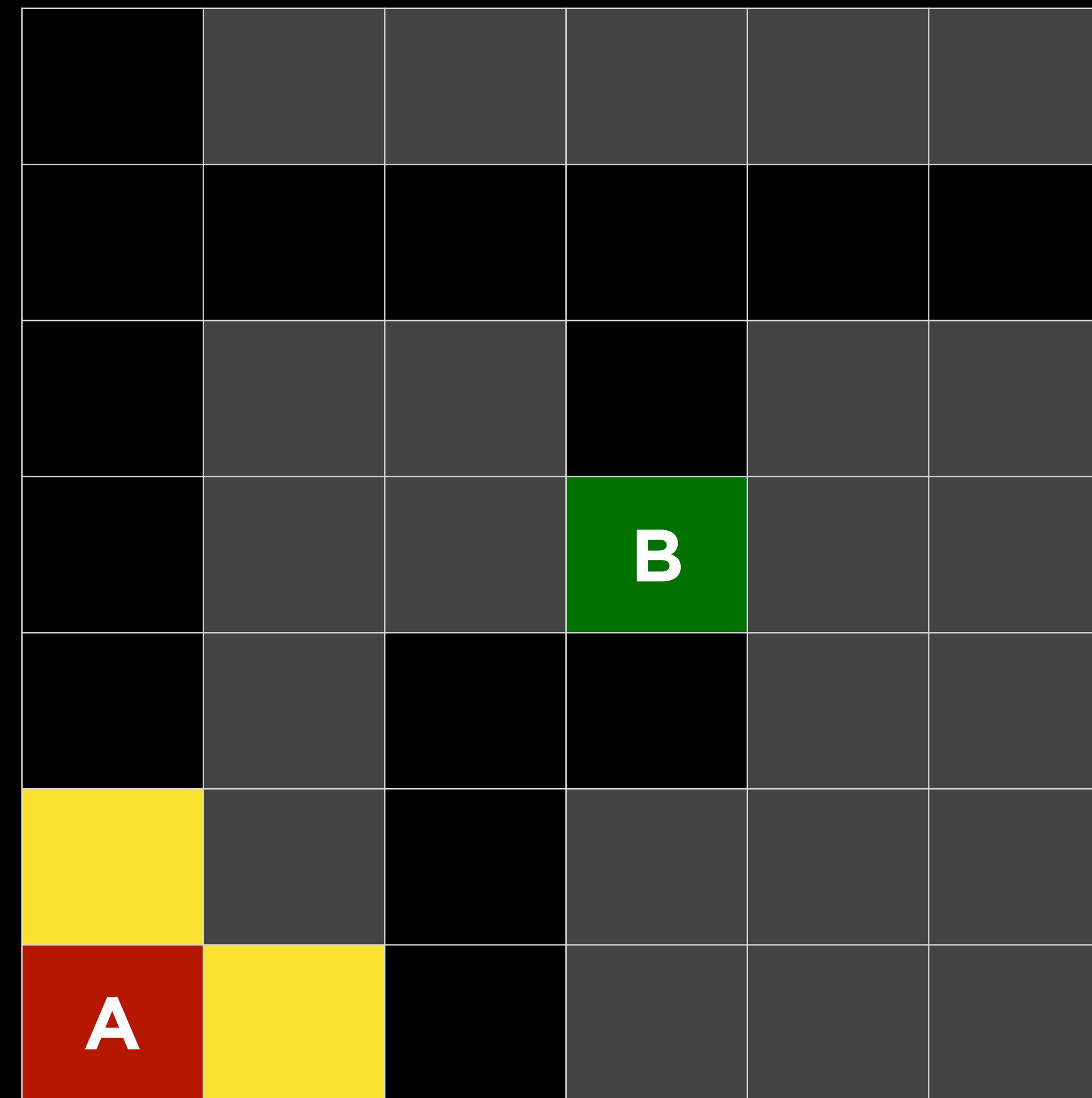
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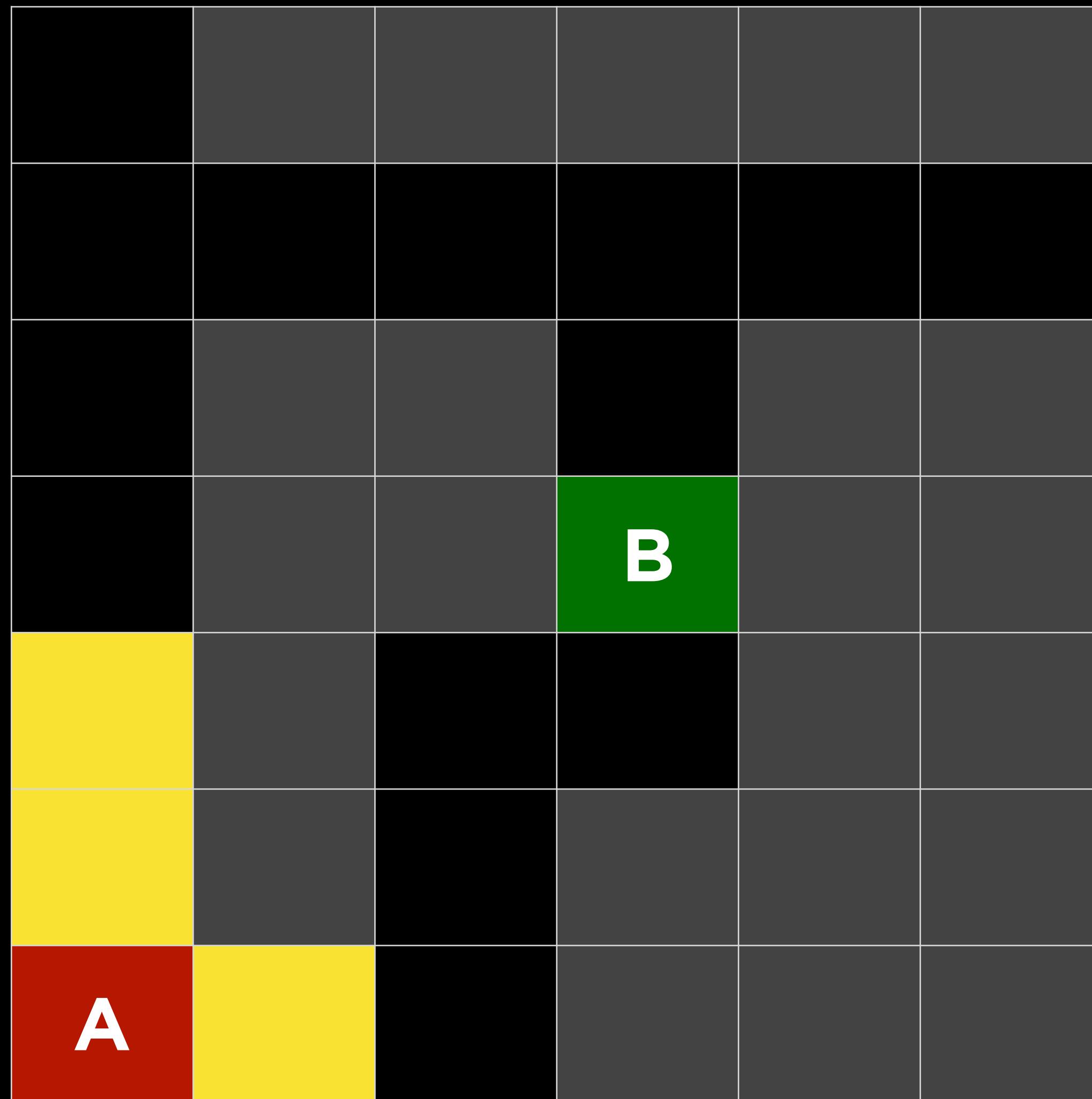
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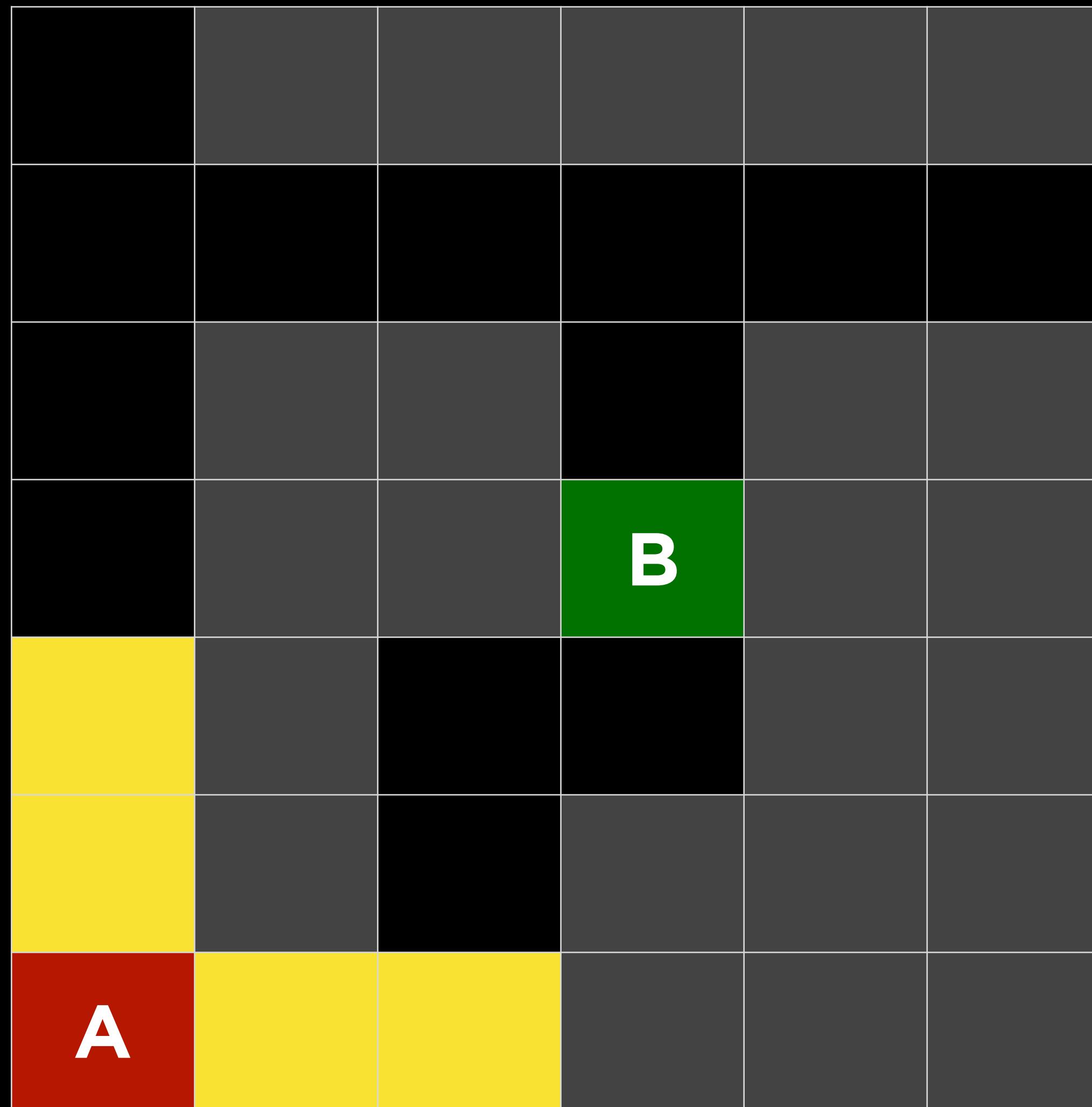
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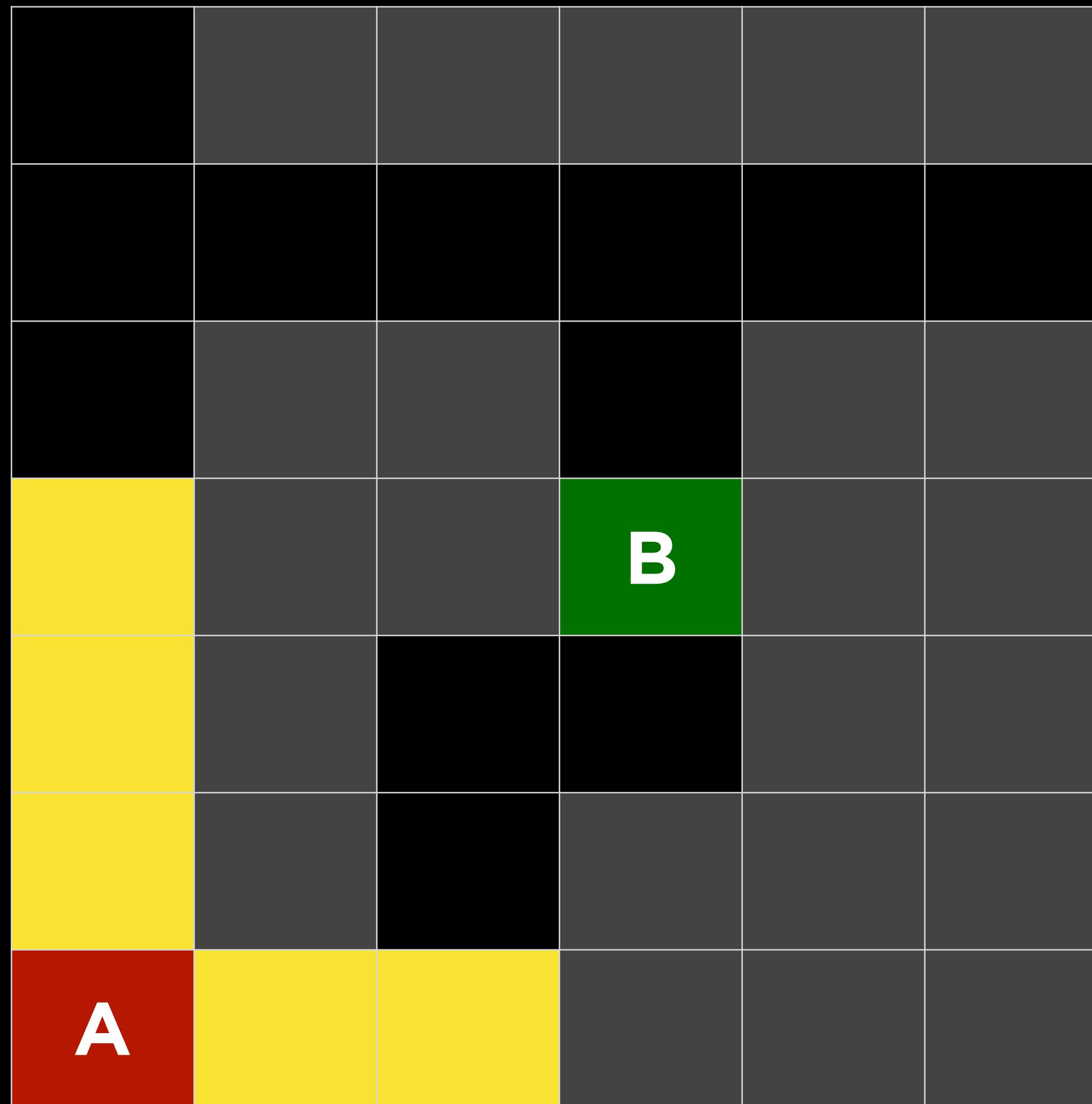
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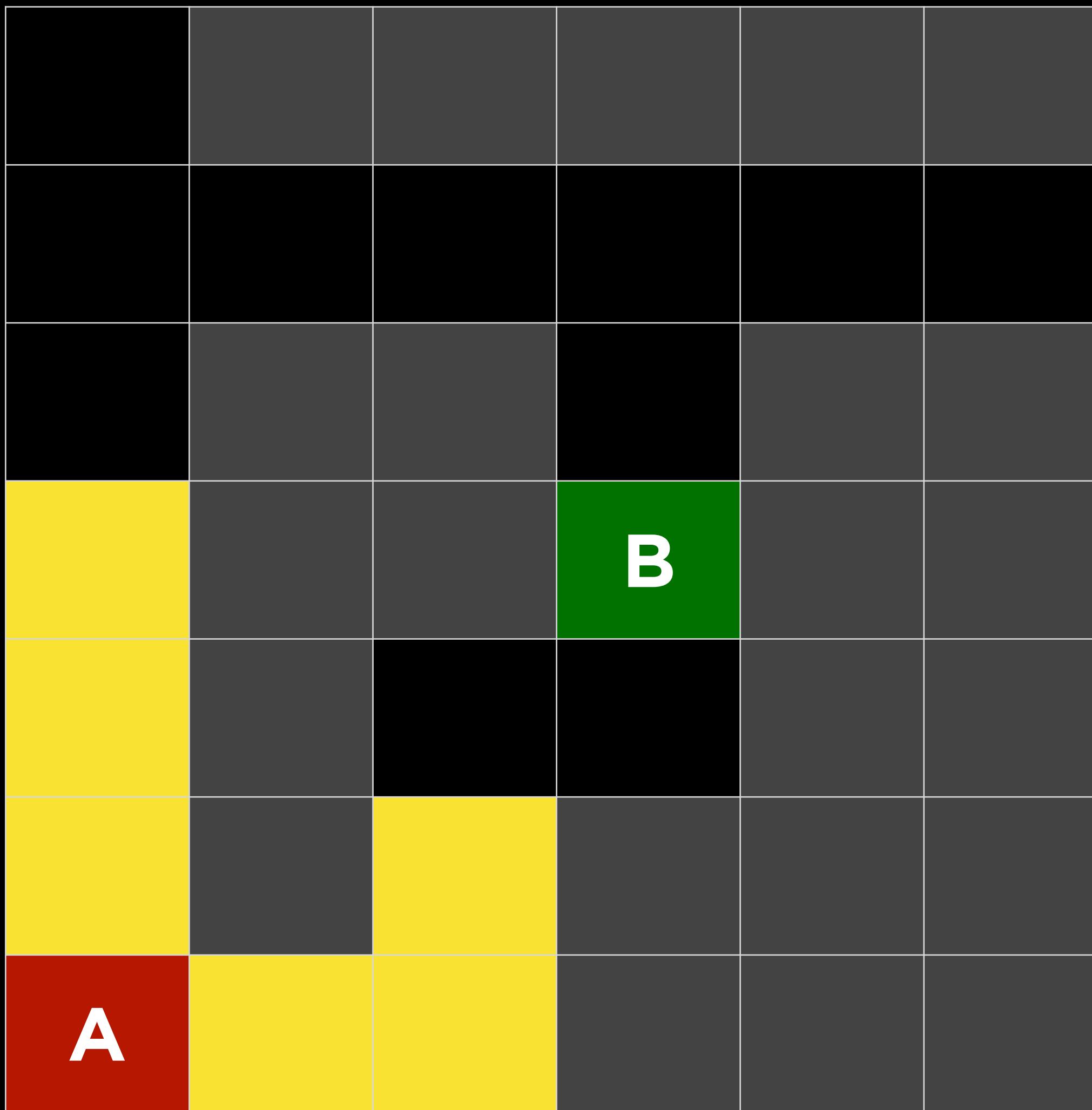
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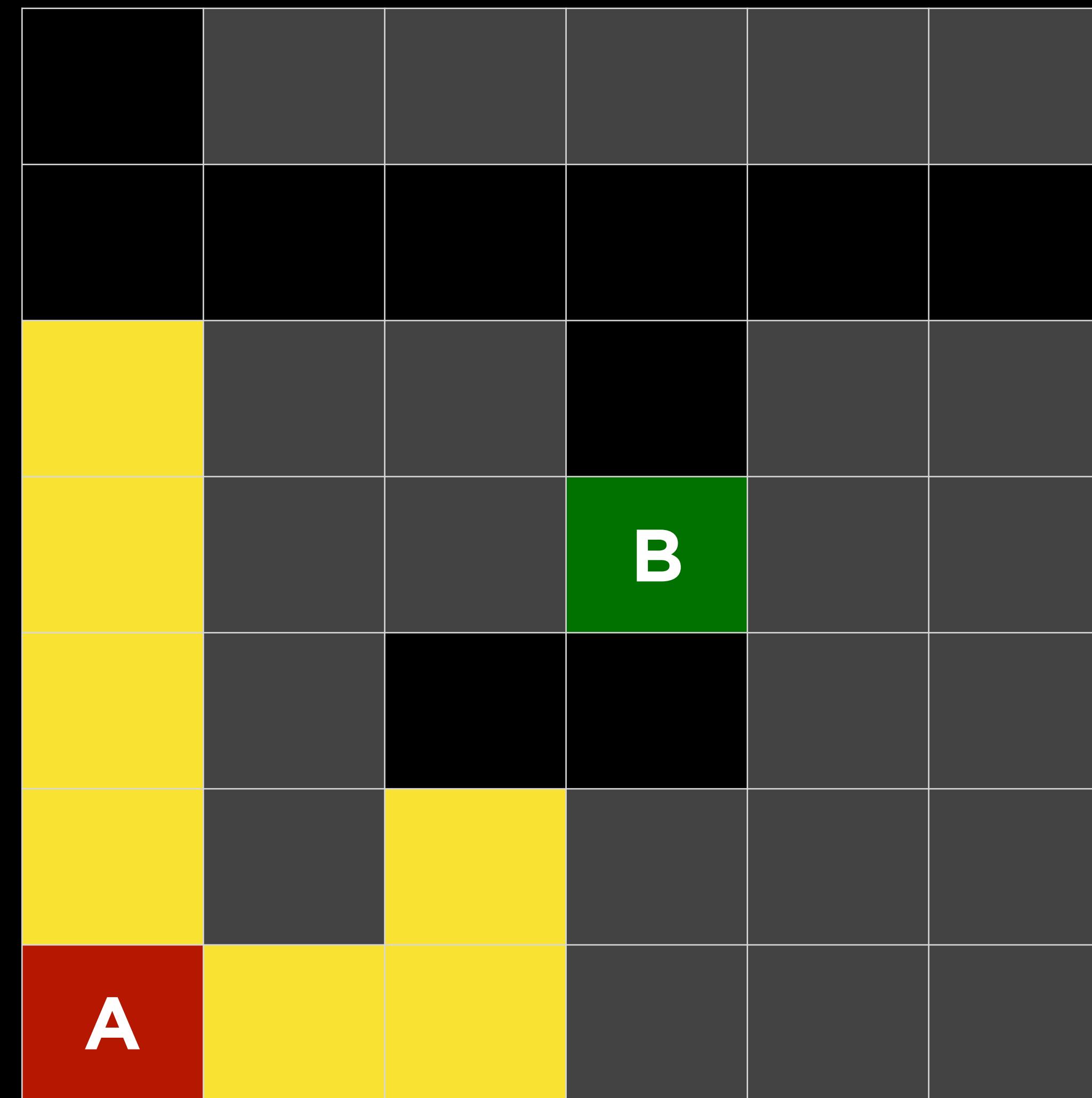
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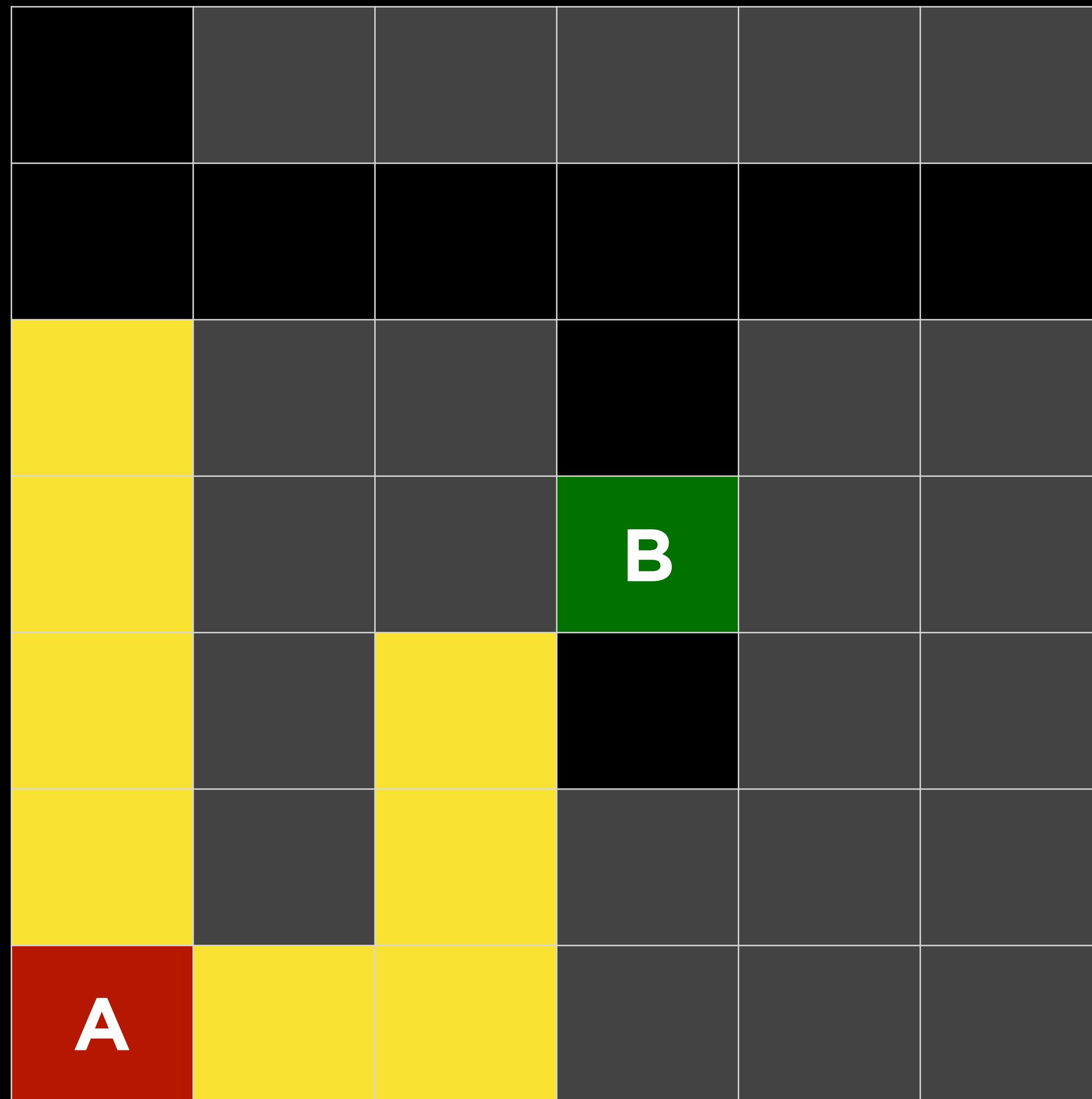
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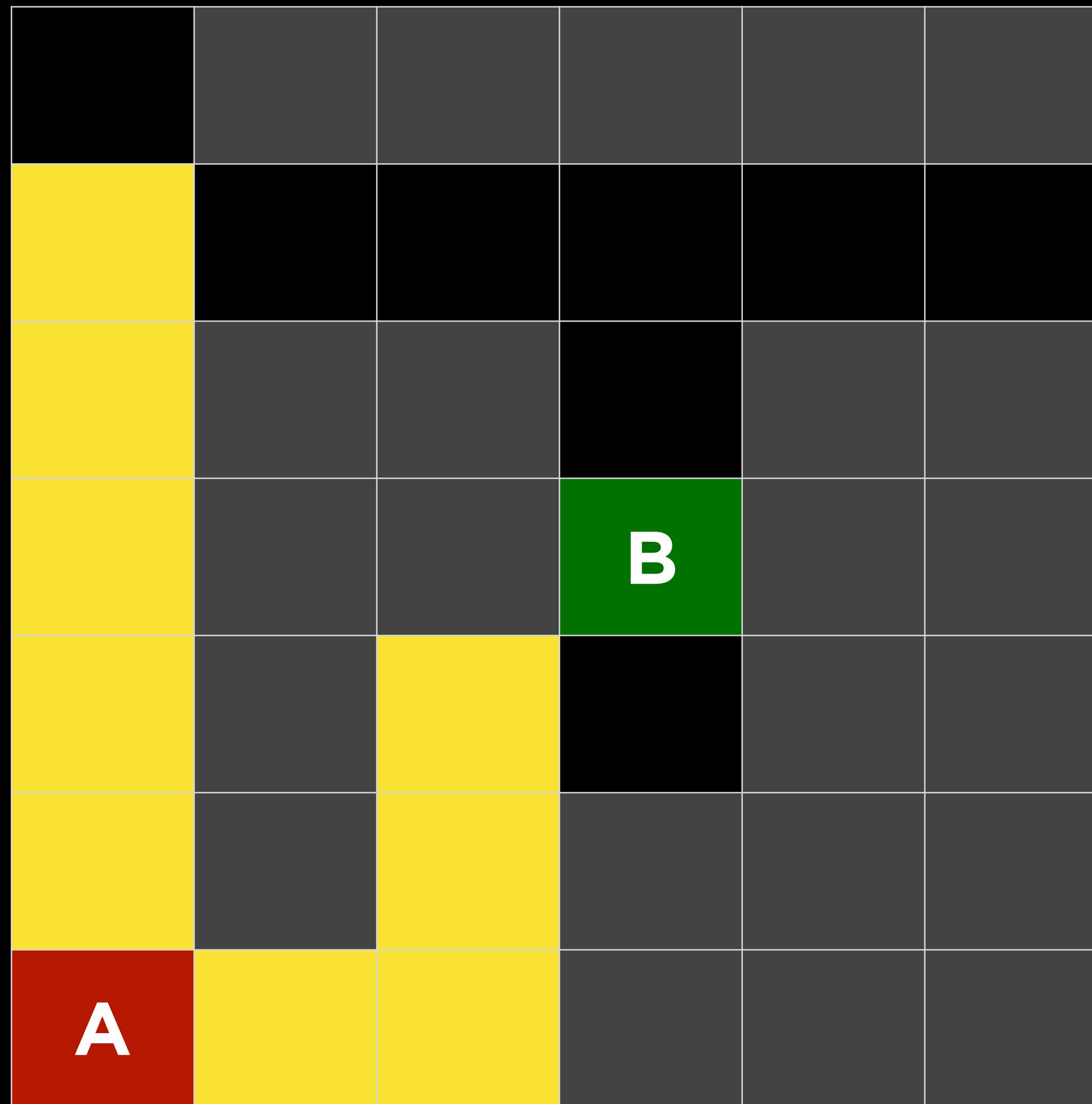
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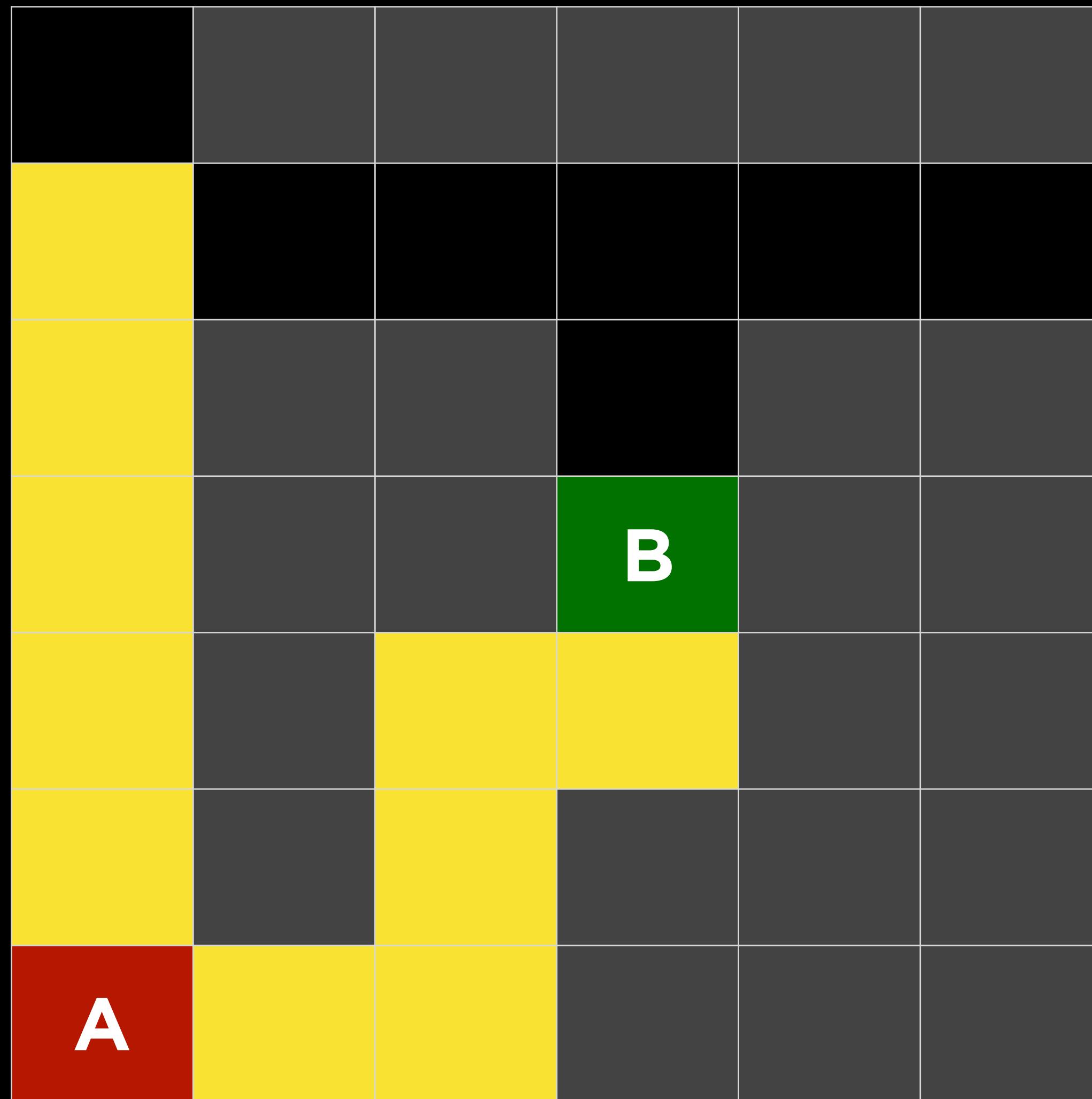
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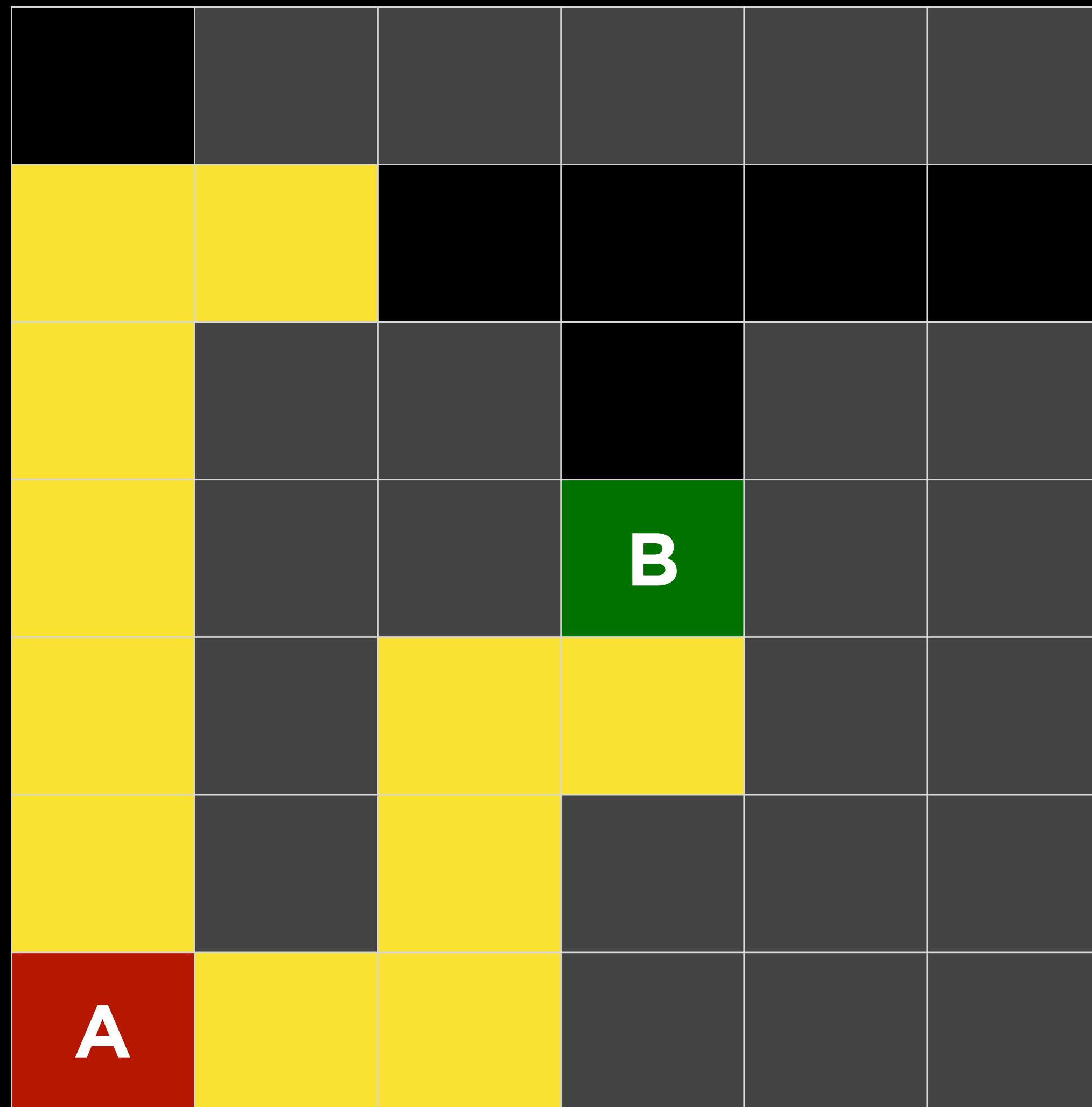
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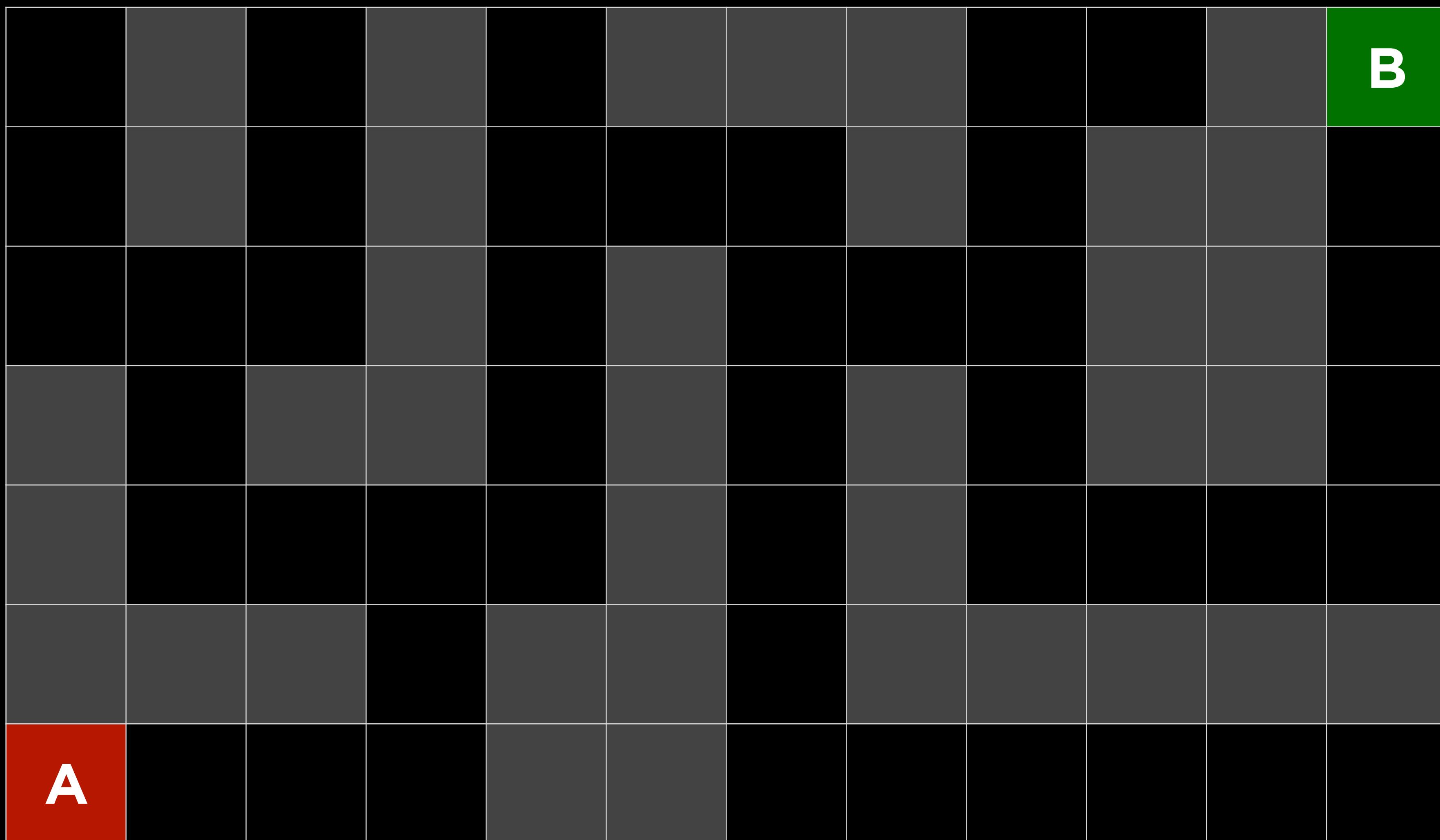
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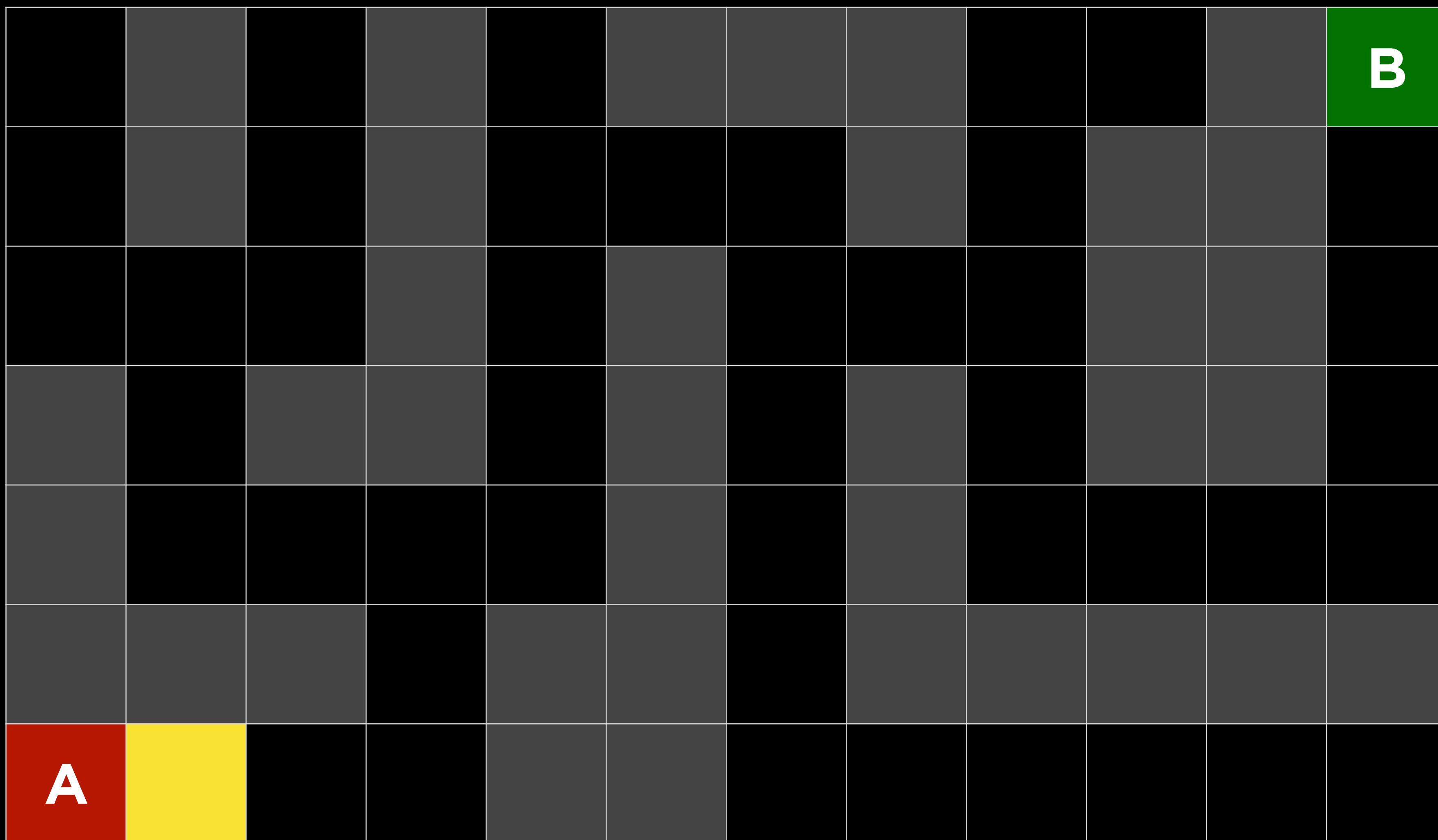
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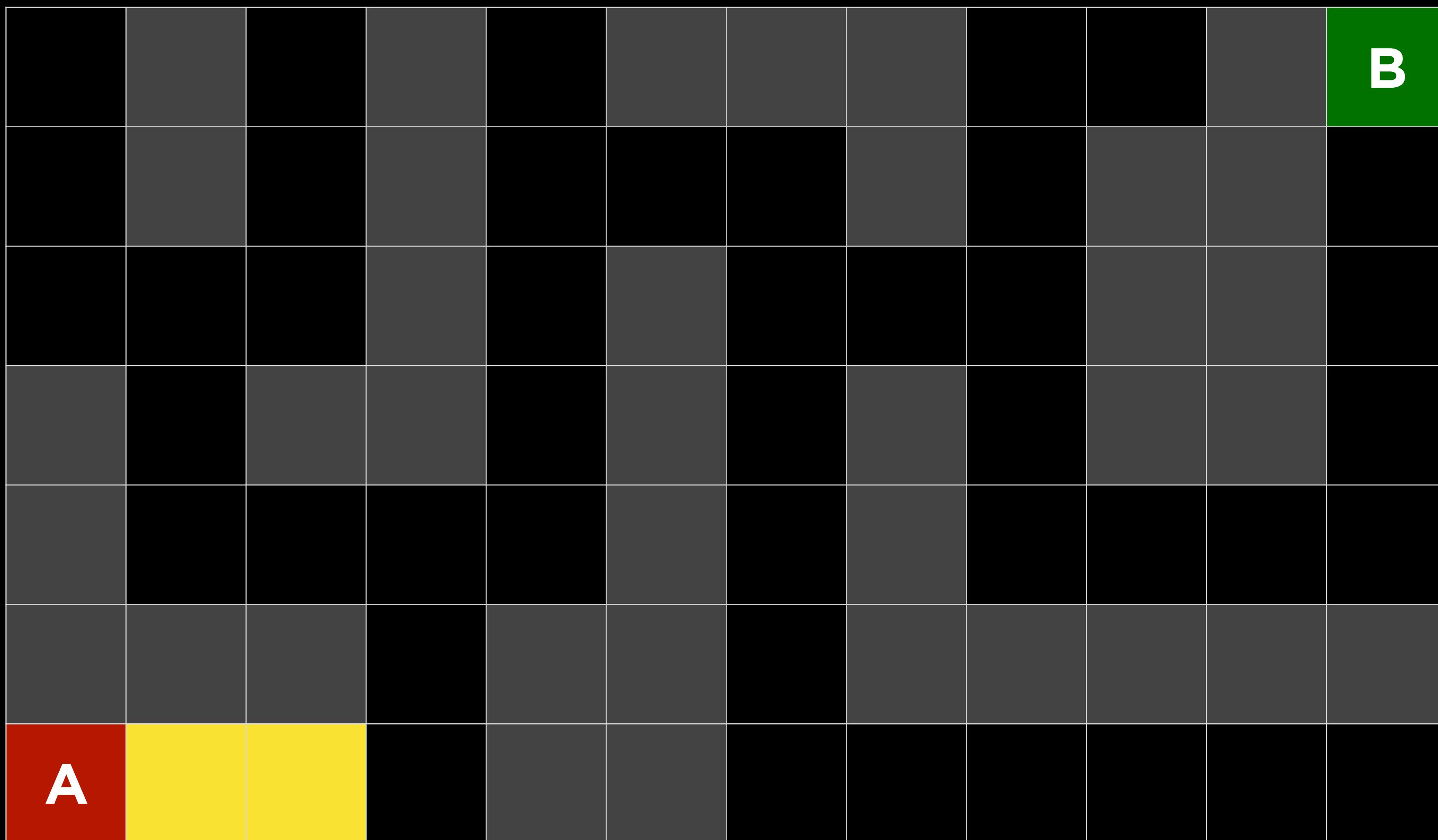
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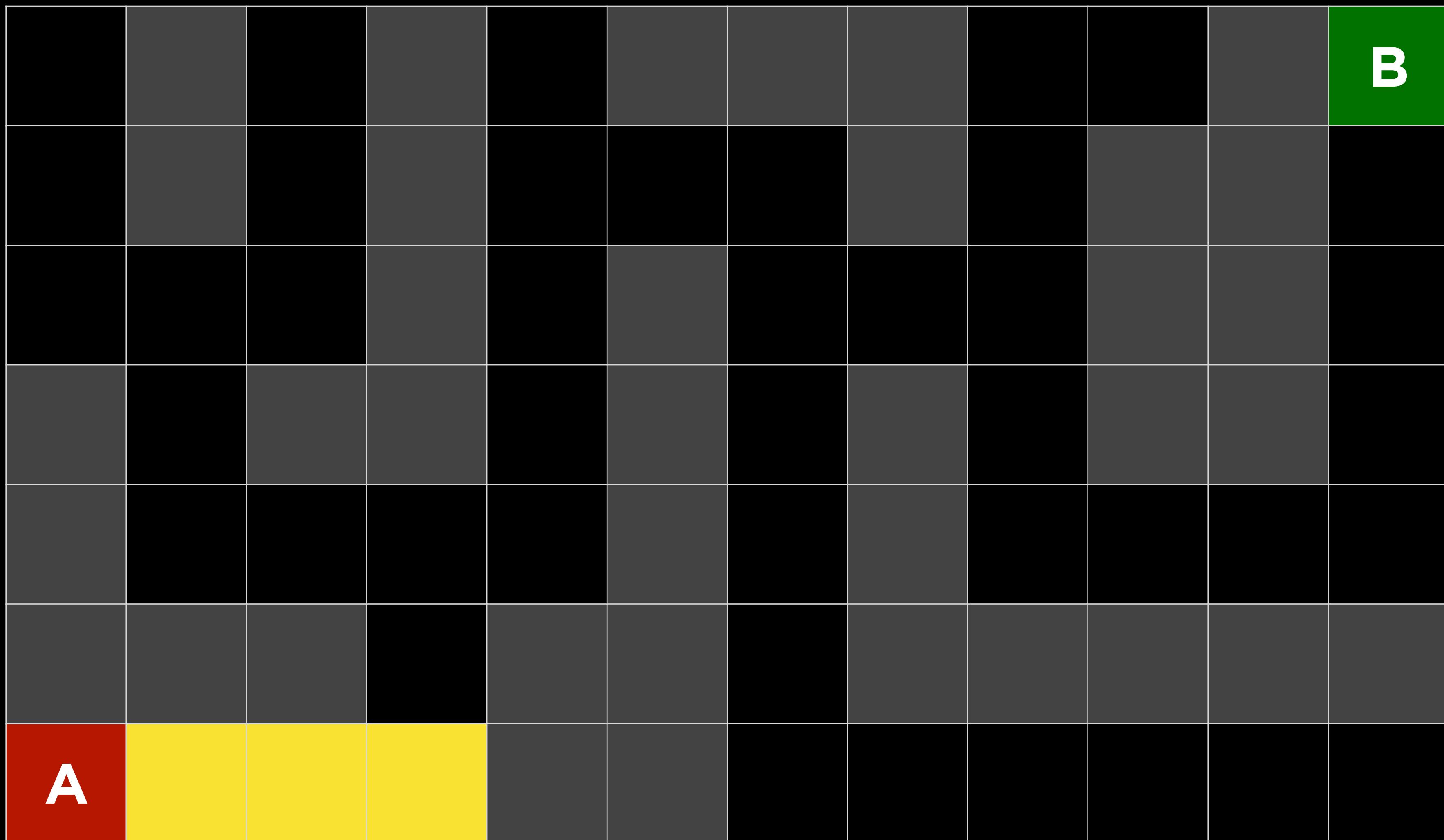
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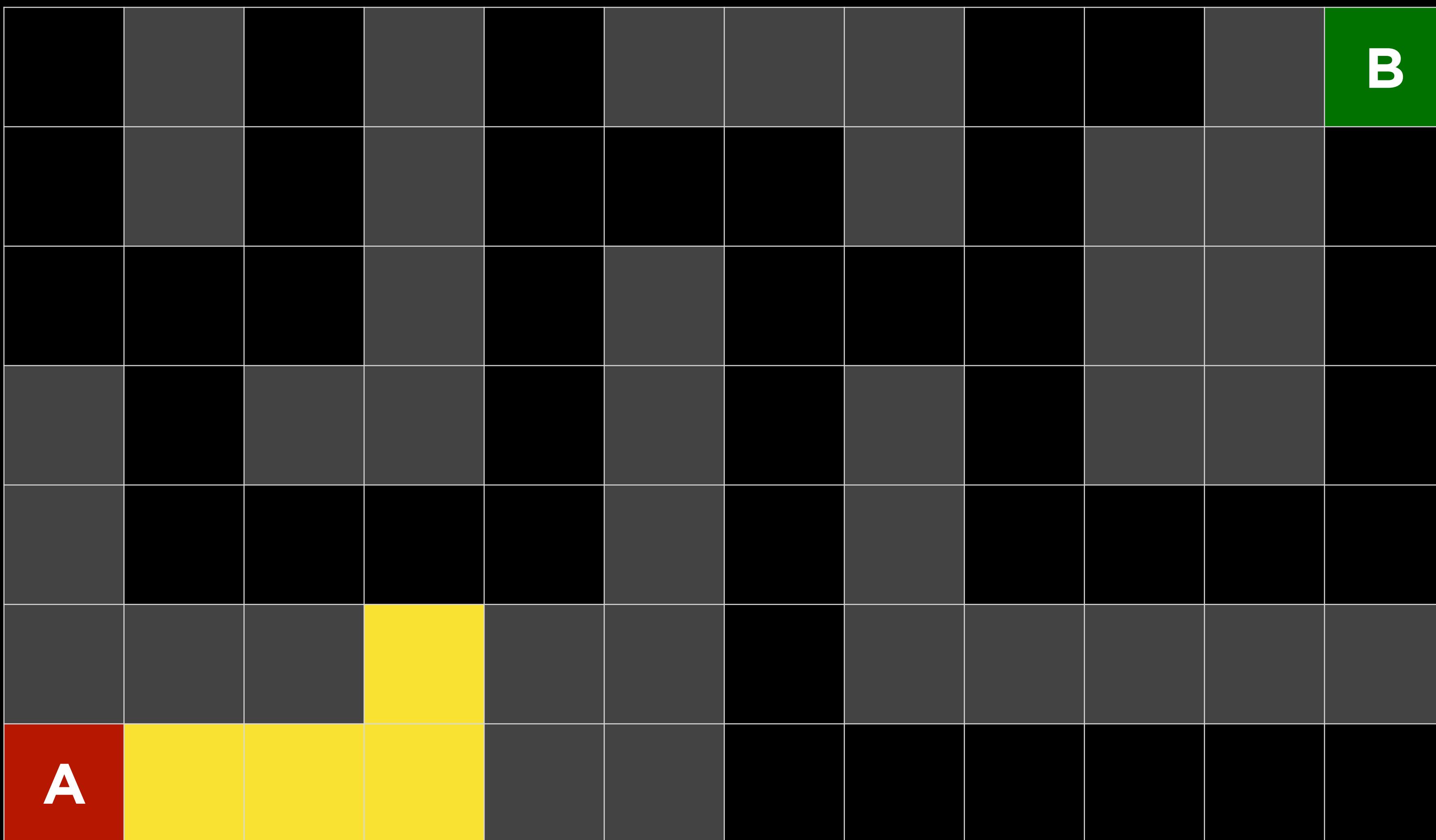
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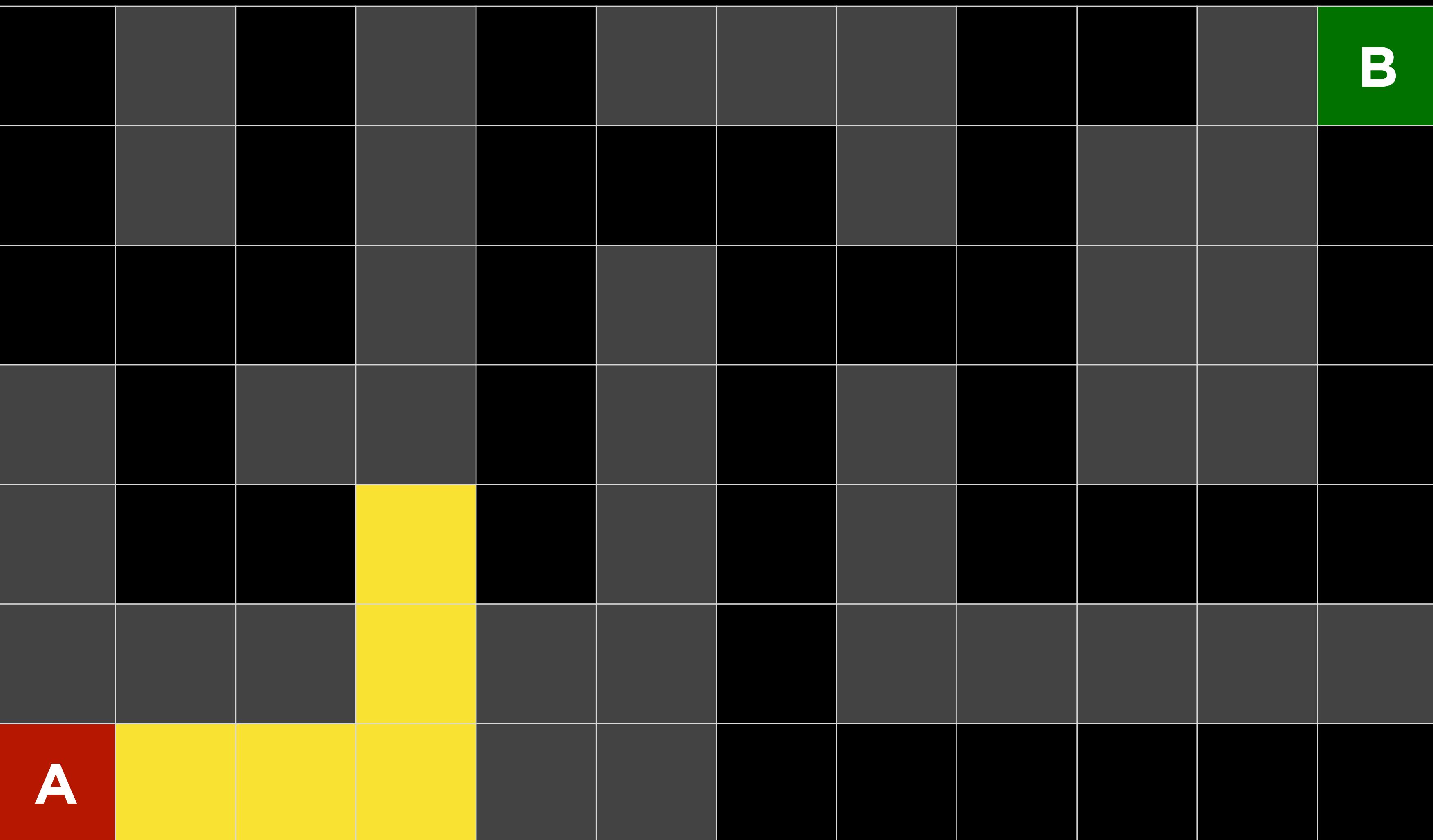
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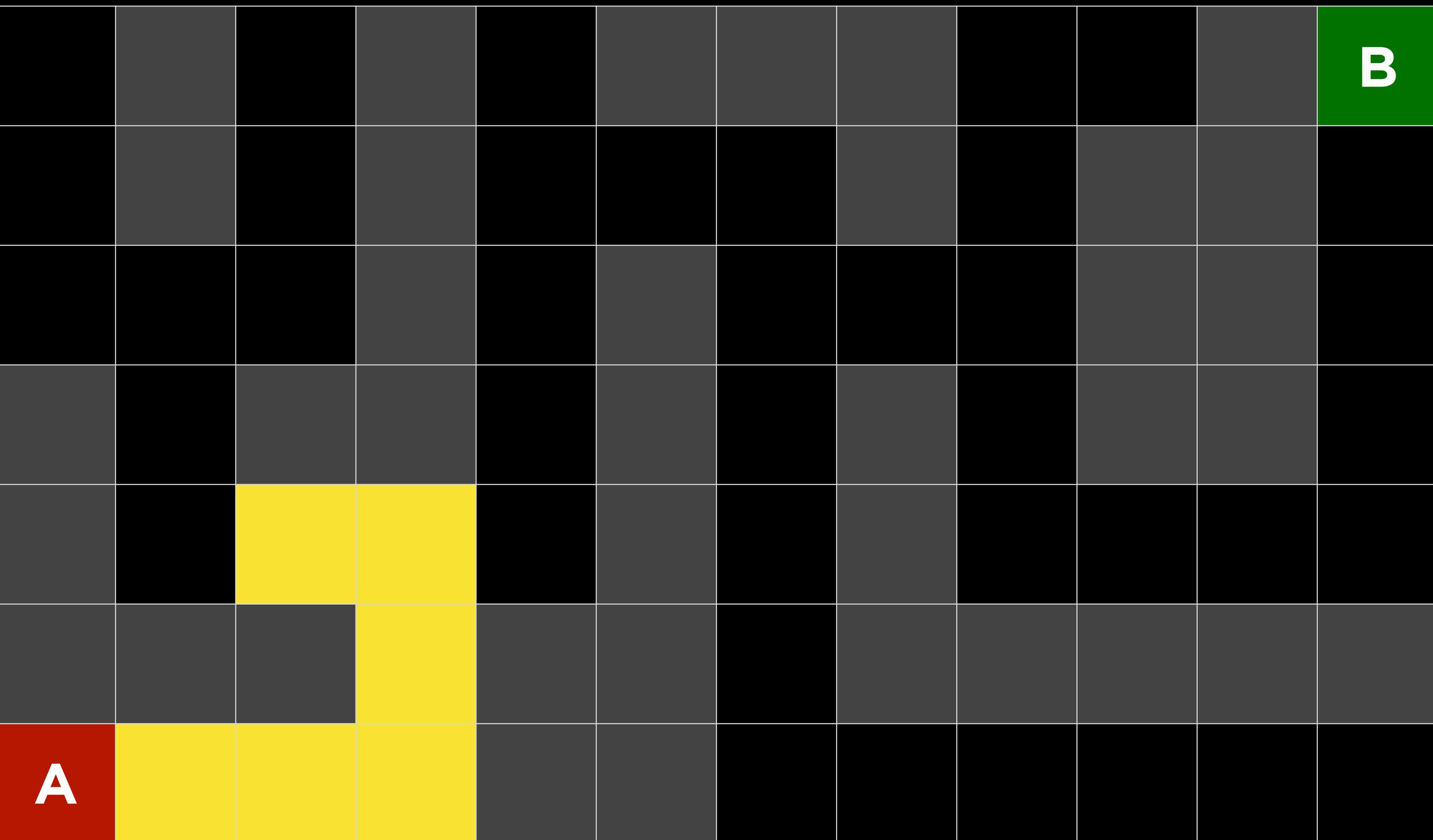
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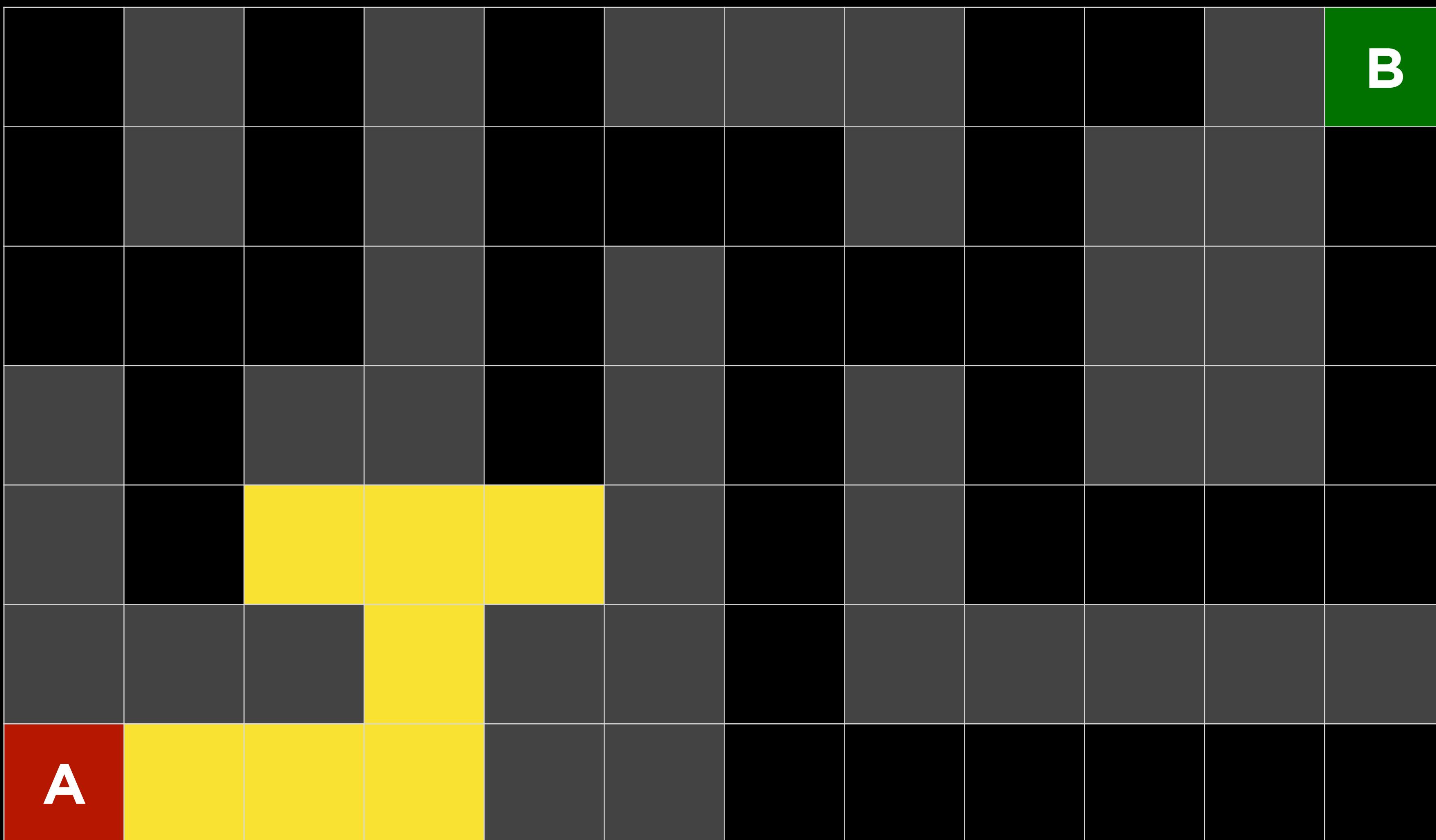
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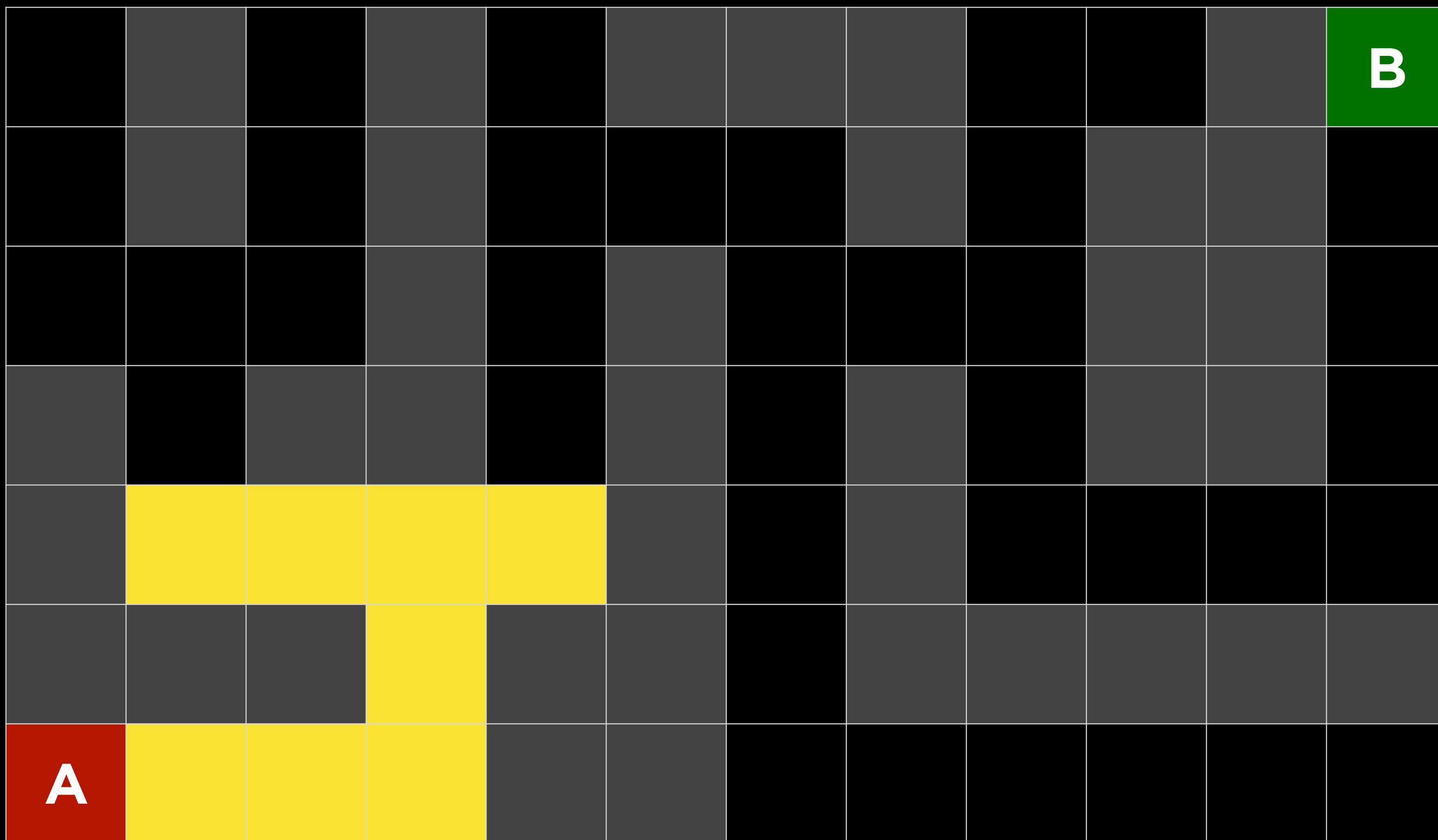
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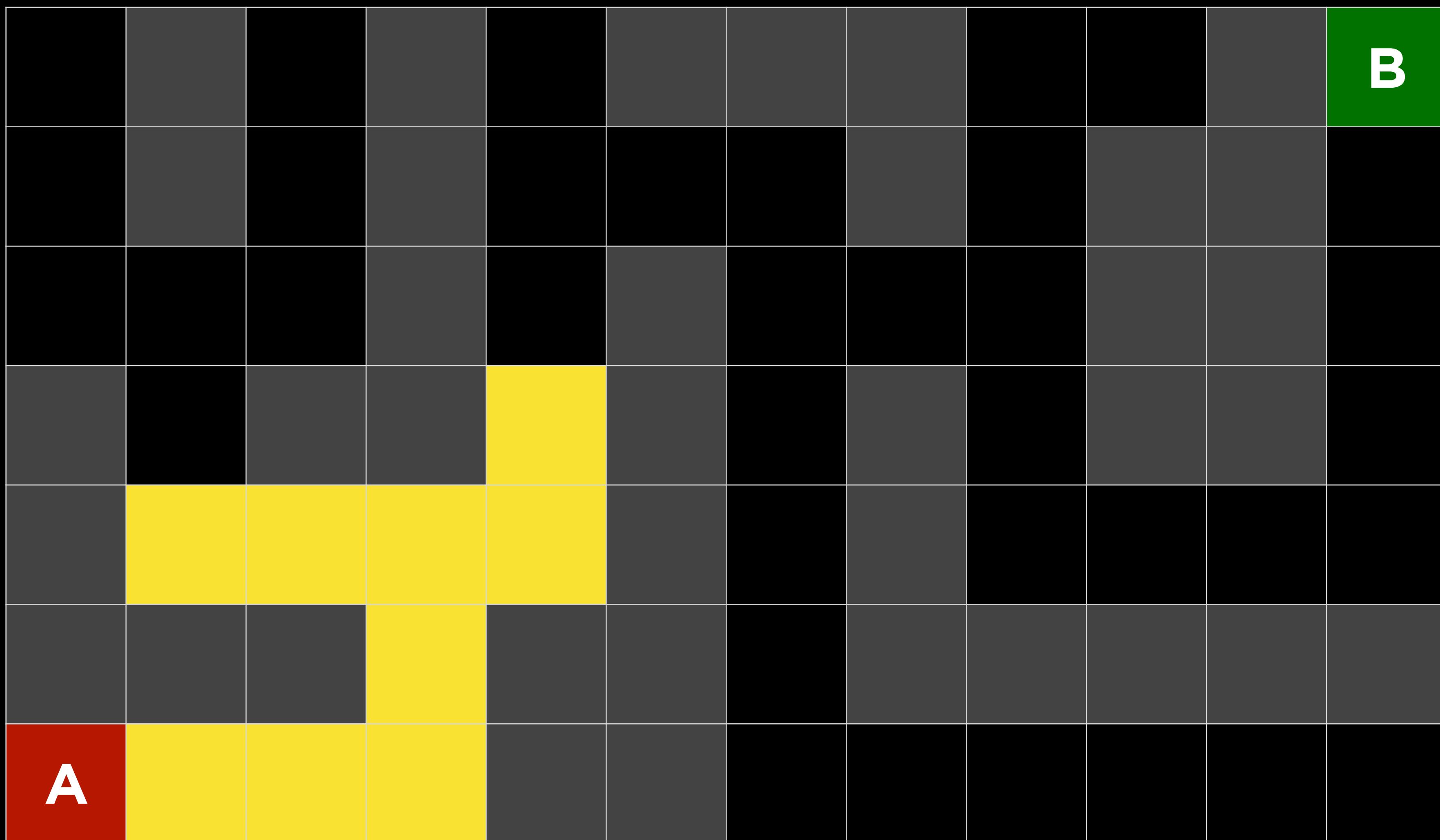
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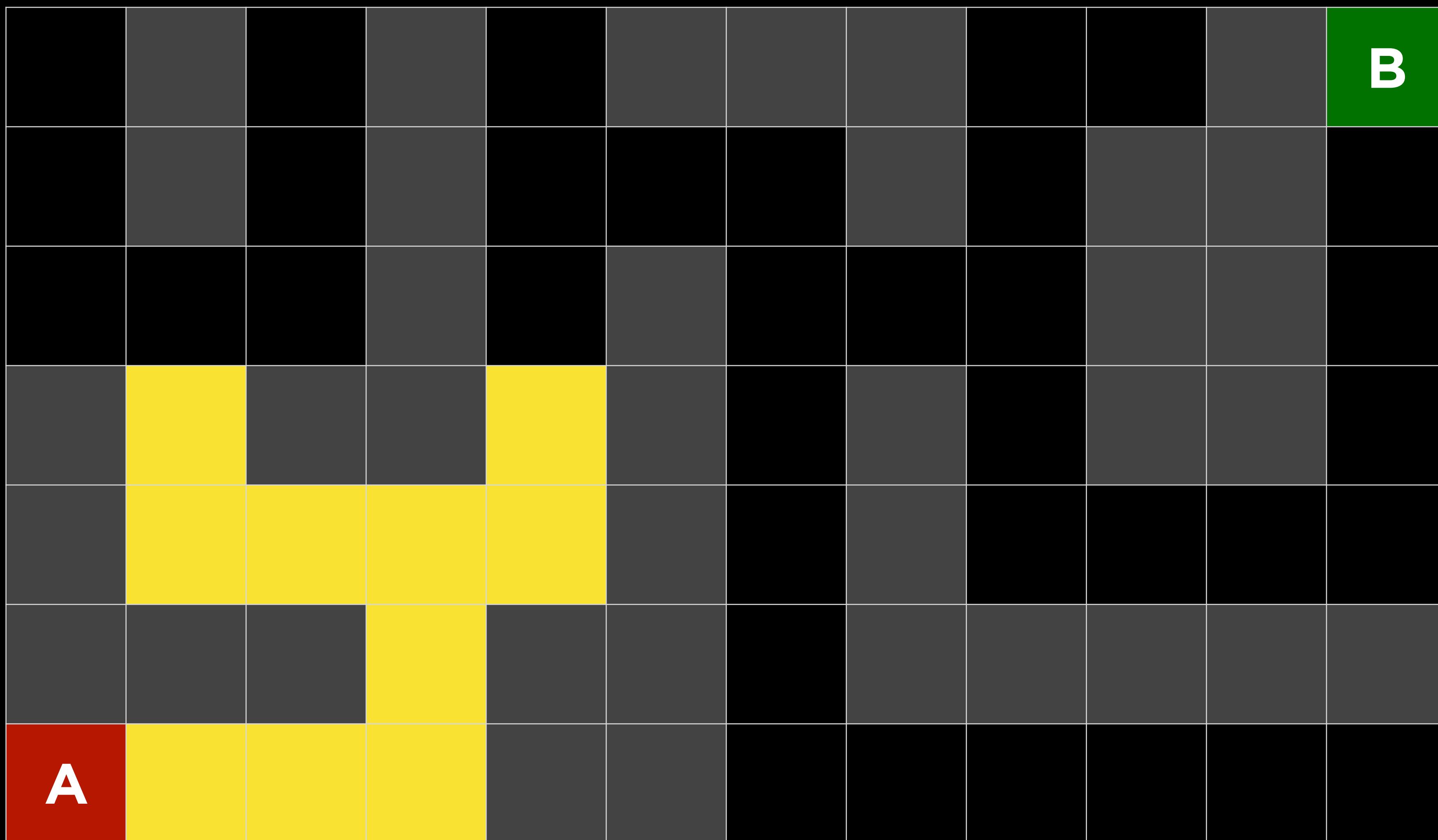
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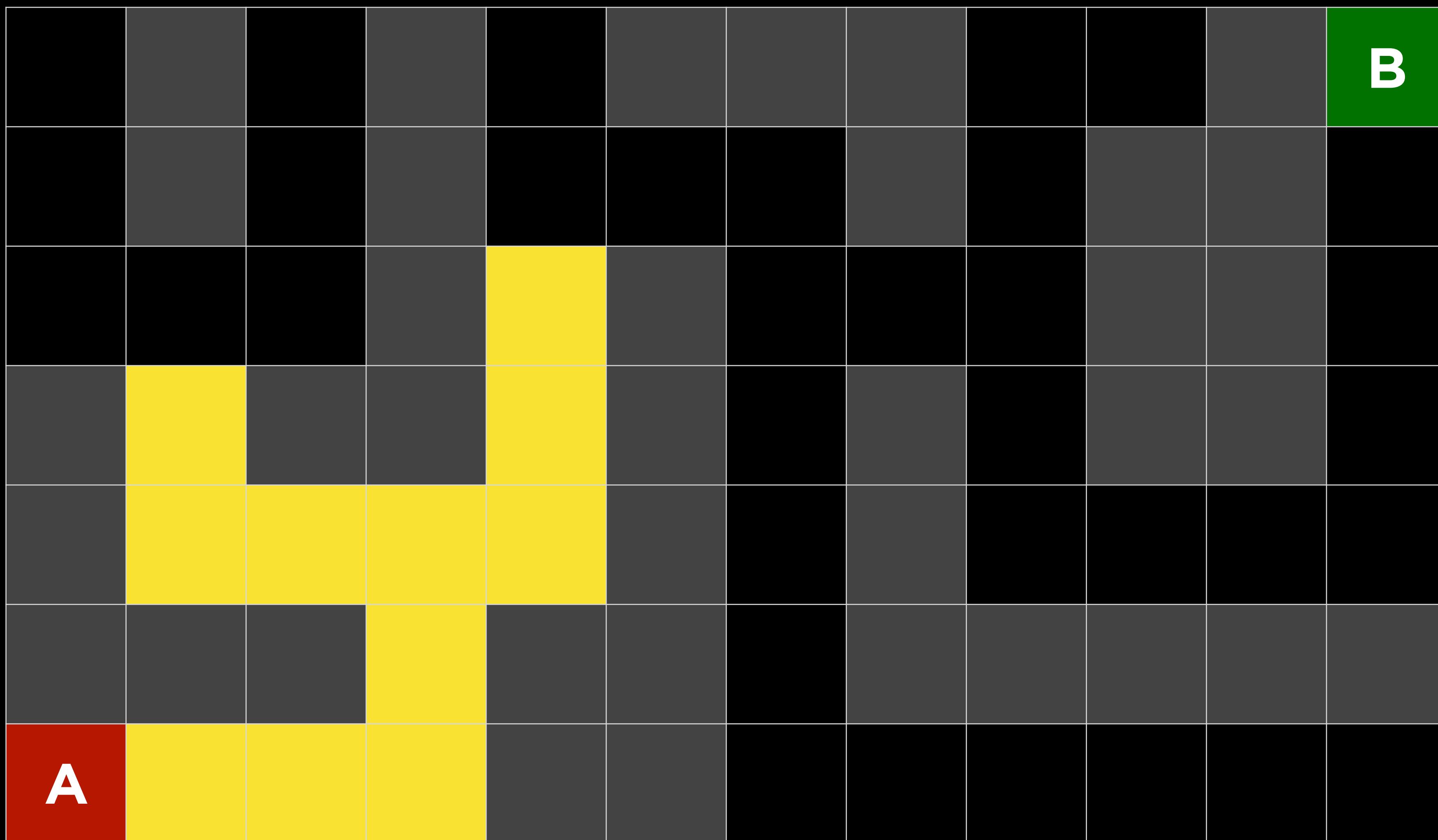
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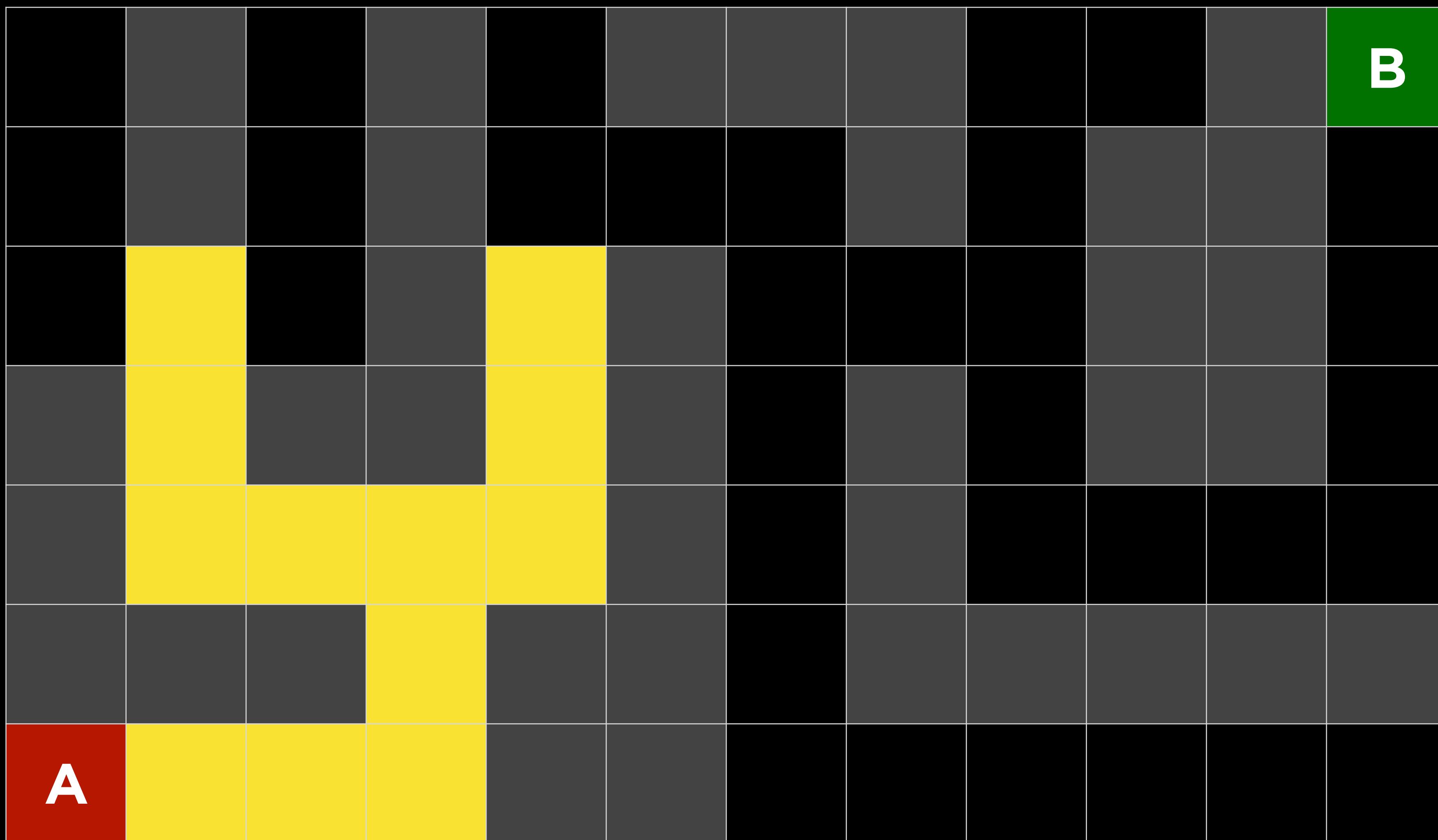
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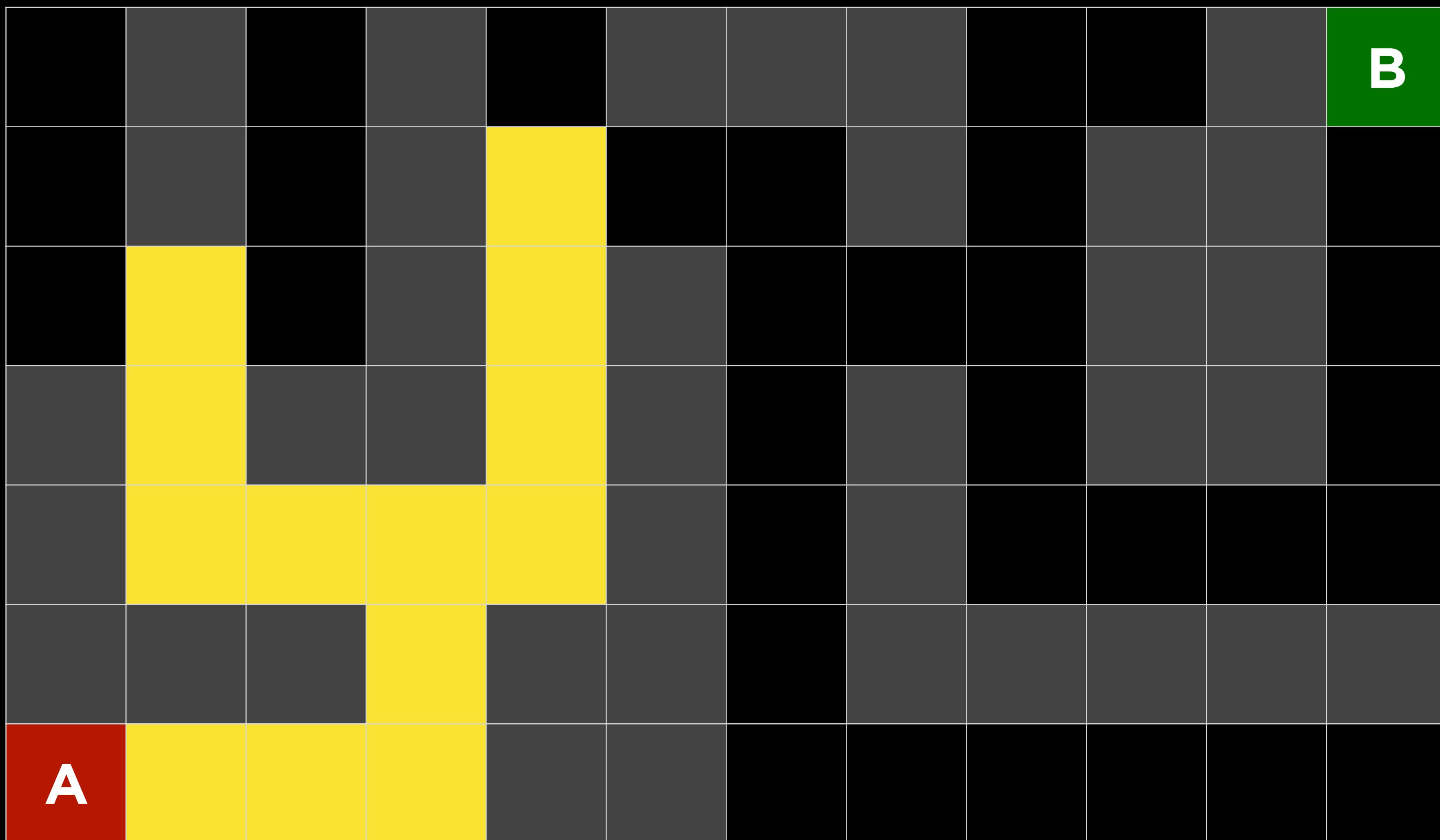
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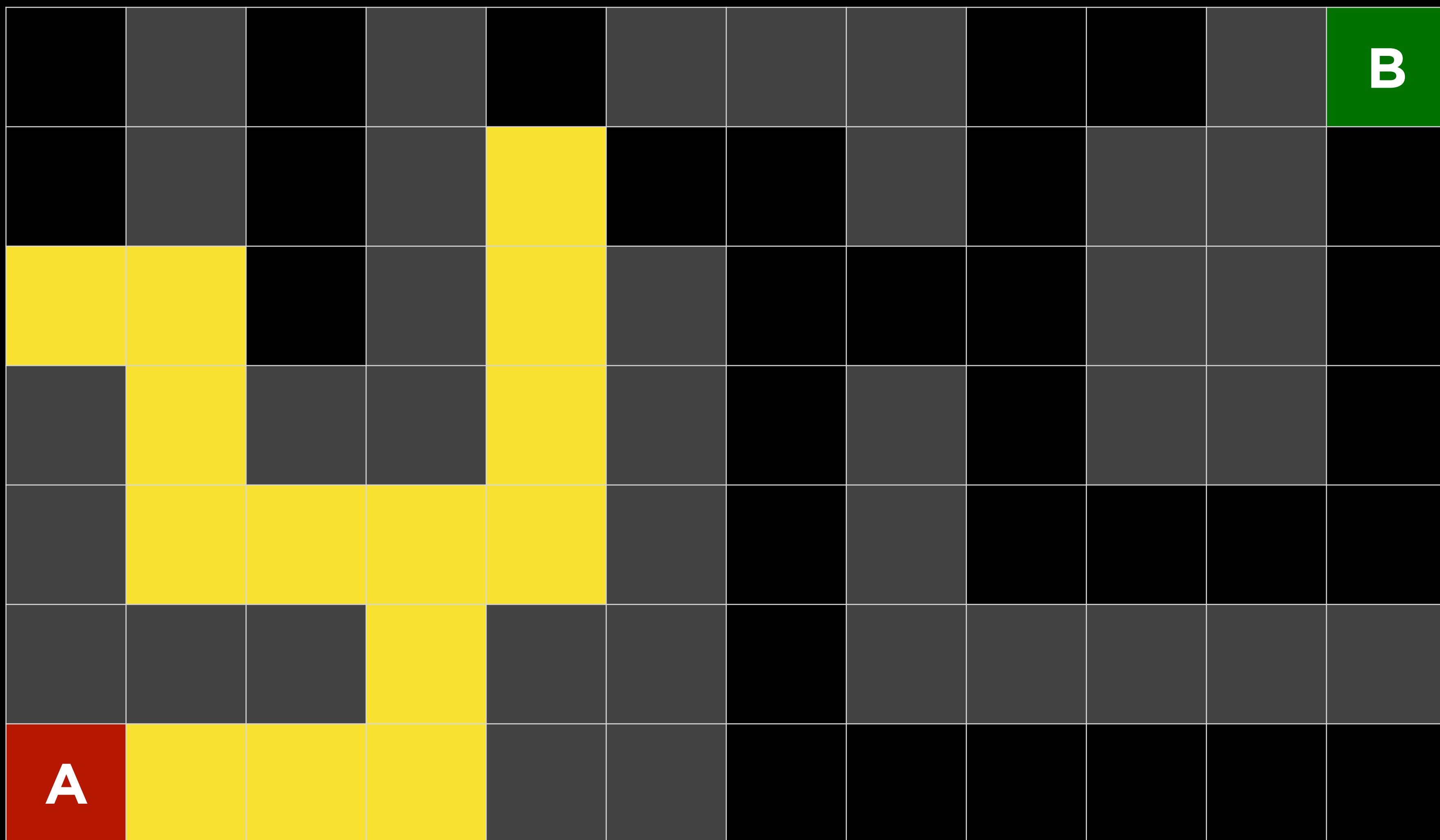
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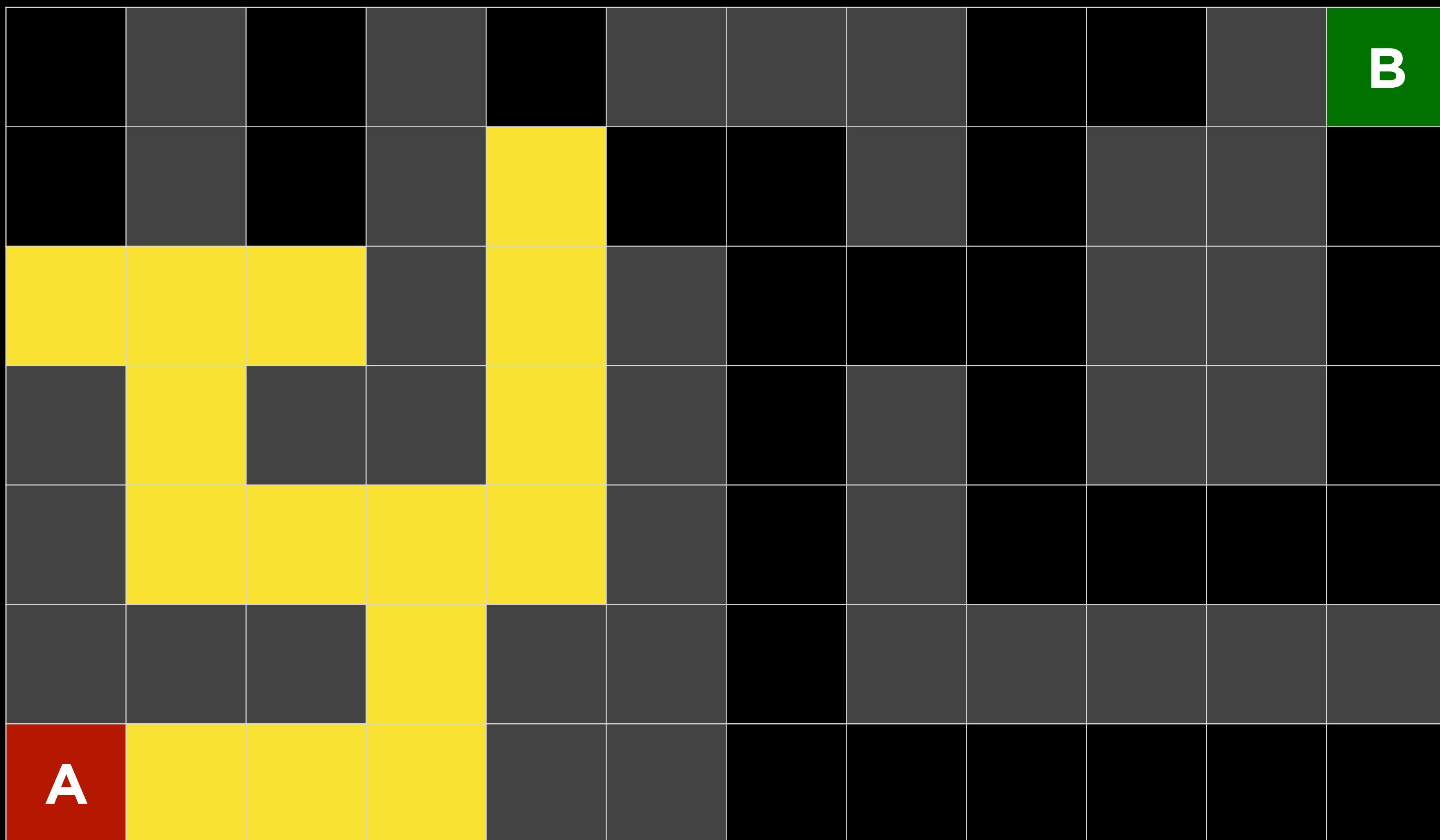
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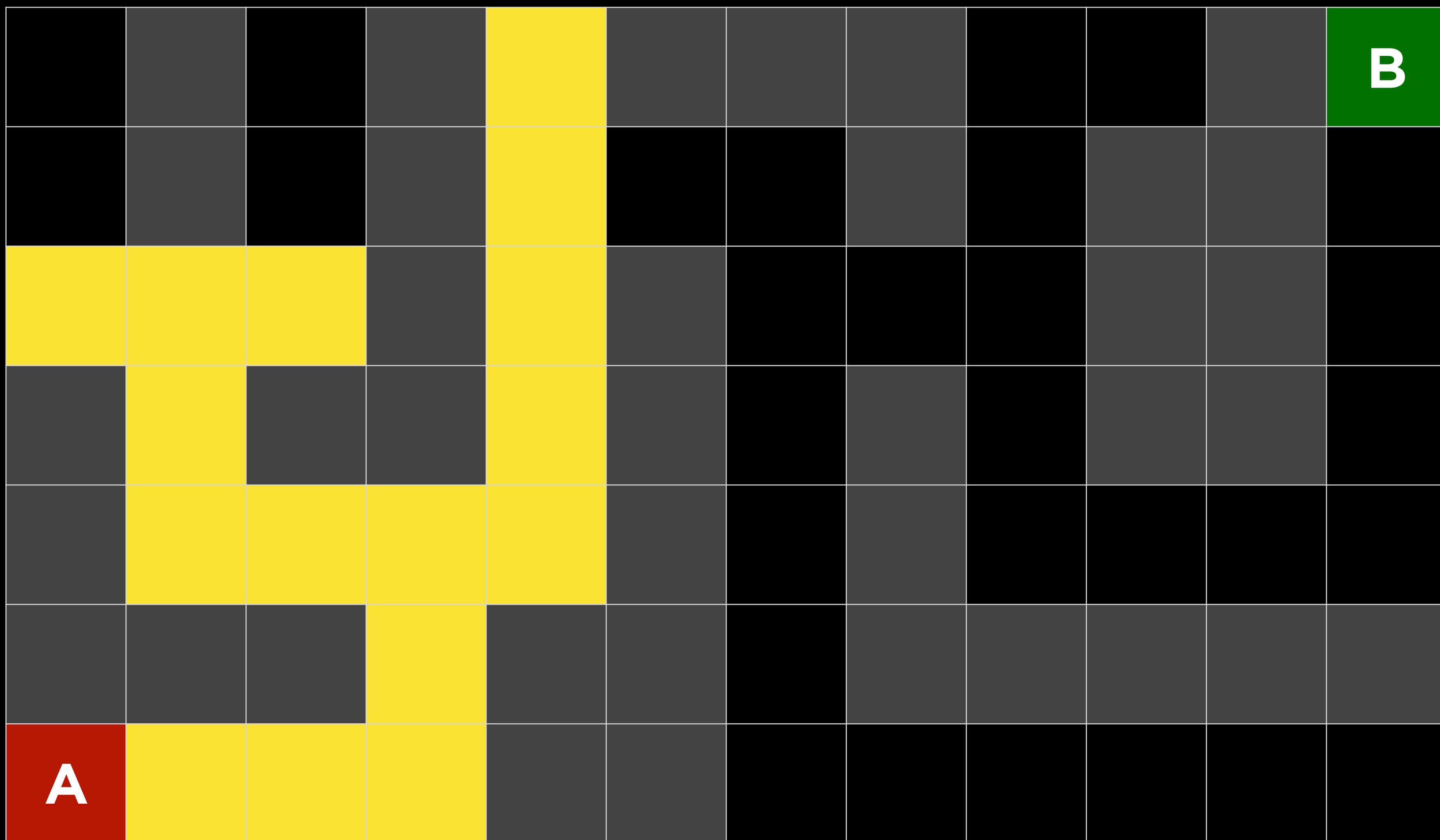
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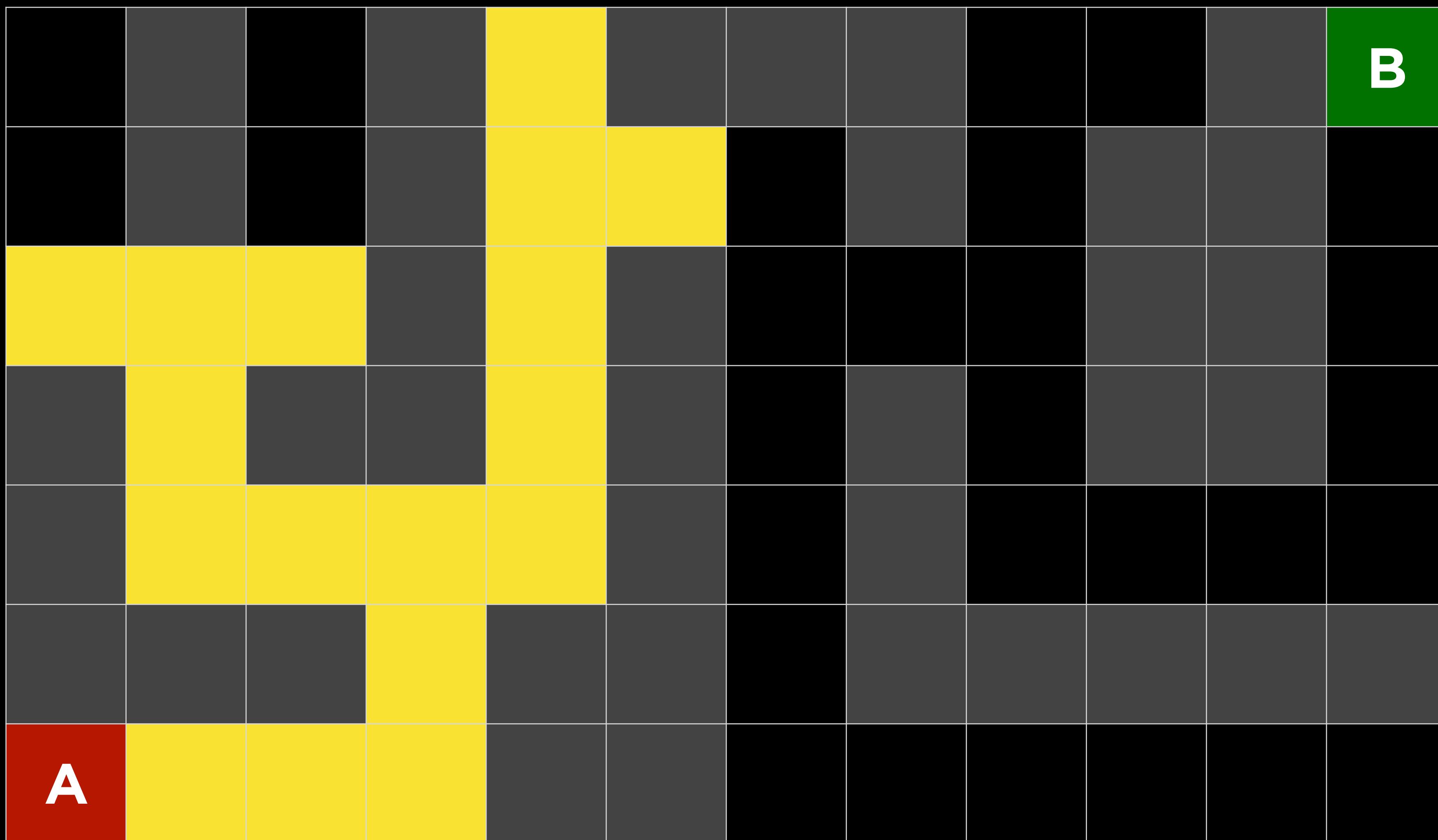
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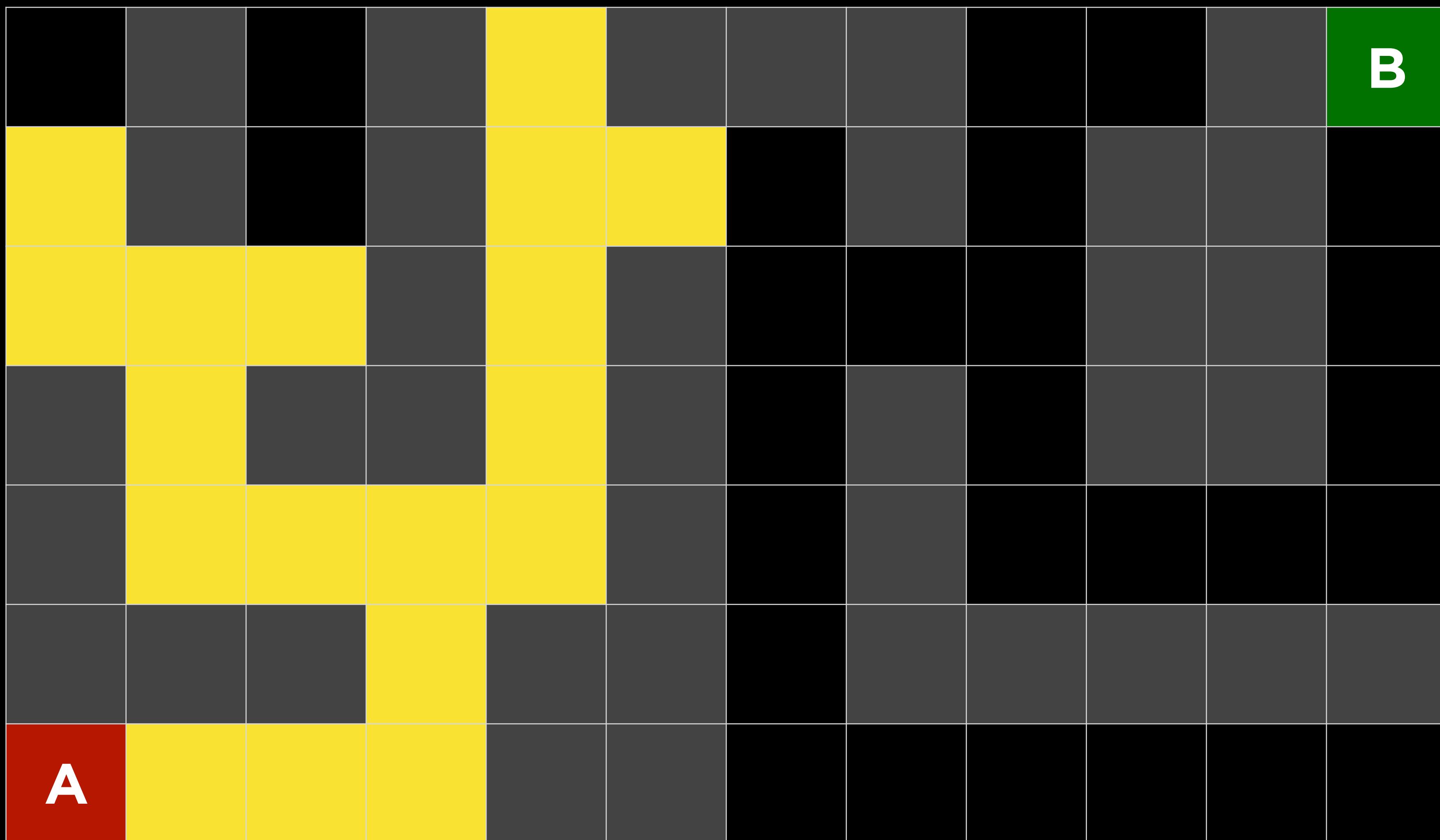
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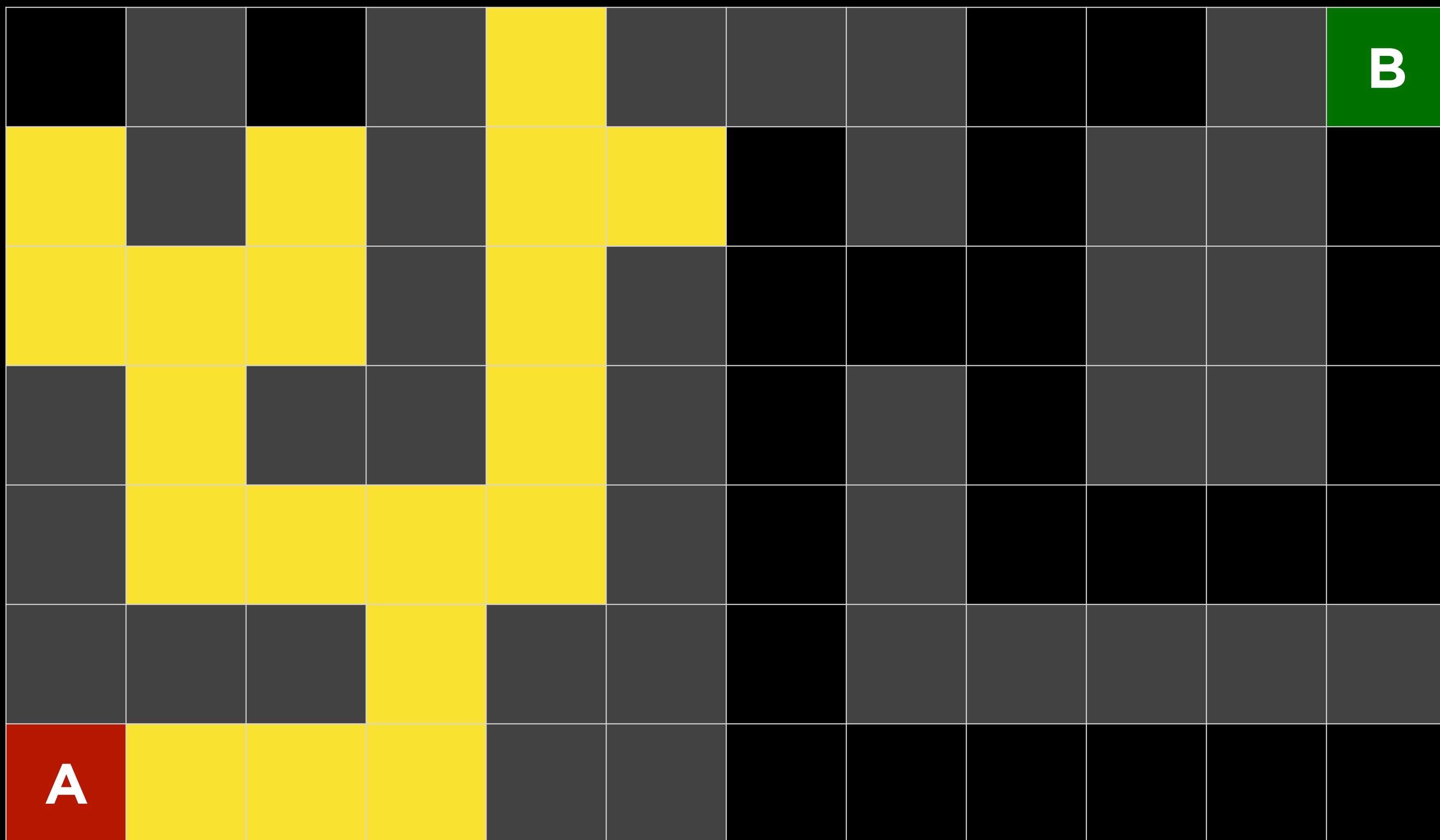
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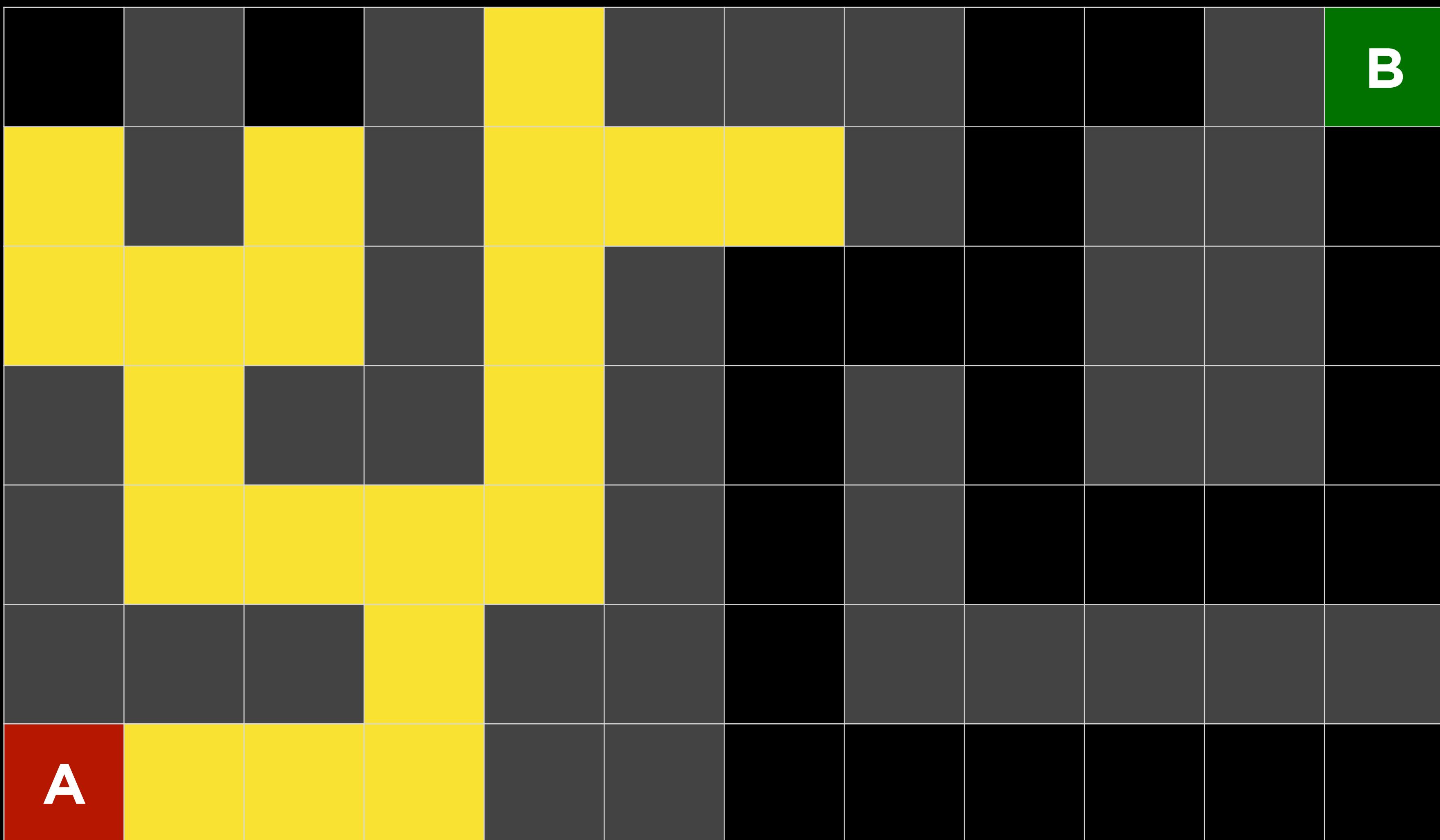
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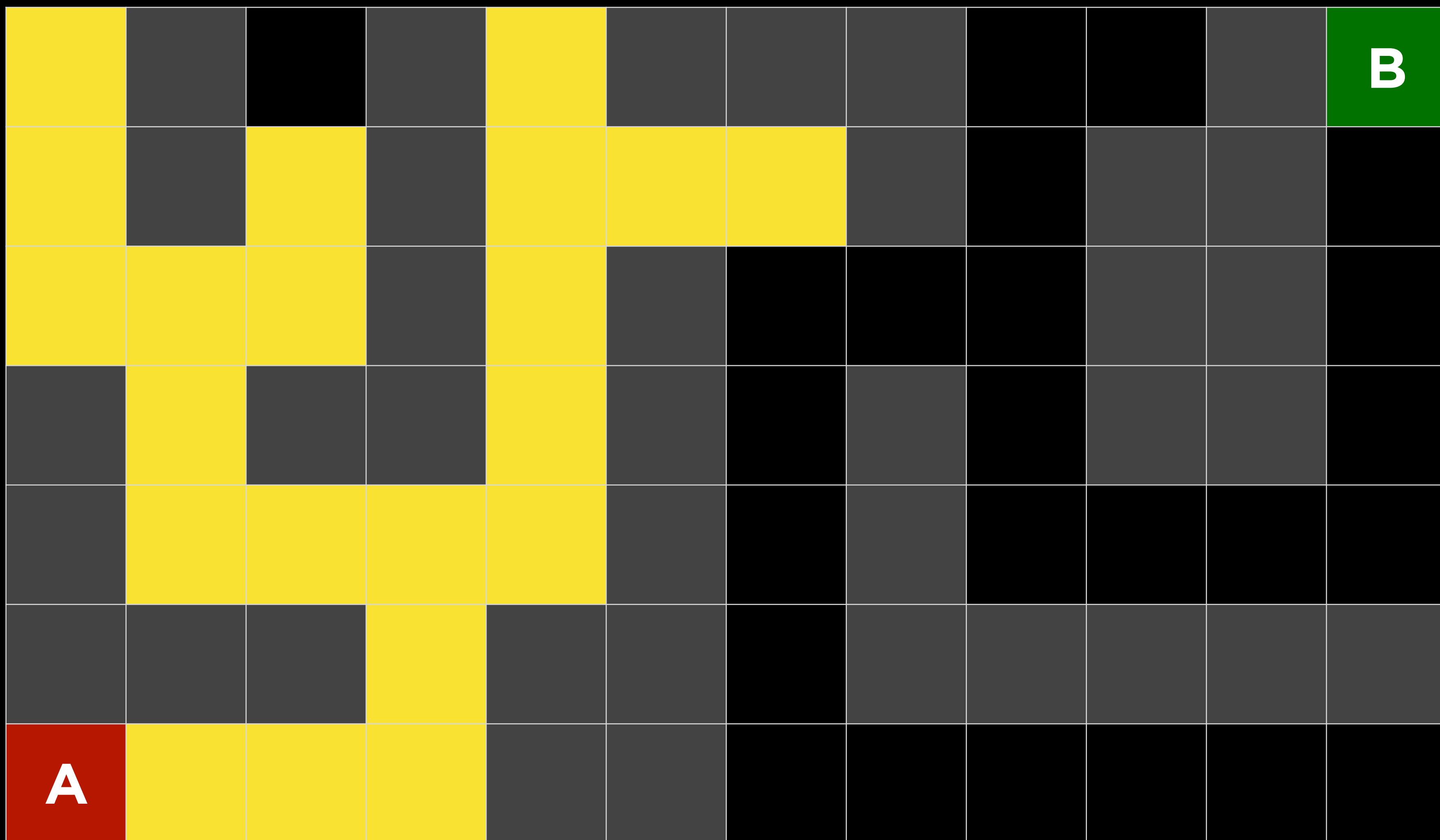
# Breadth-First Search



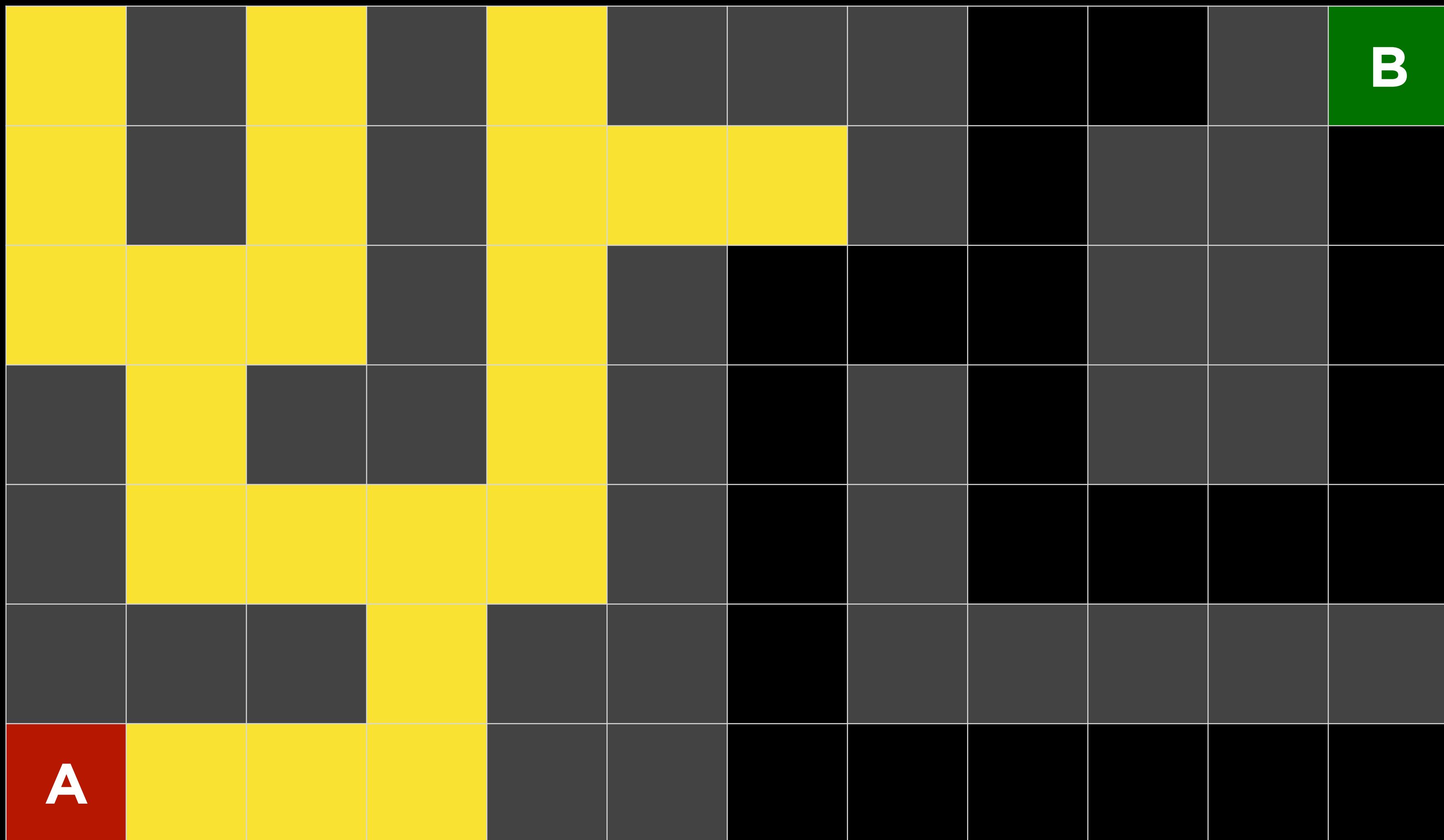
# Breadth-First Search



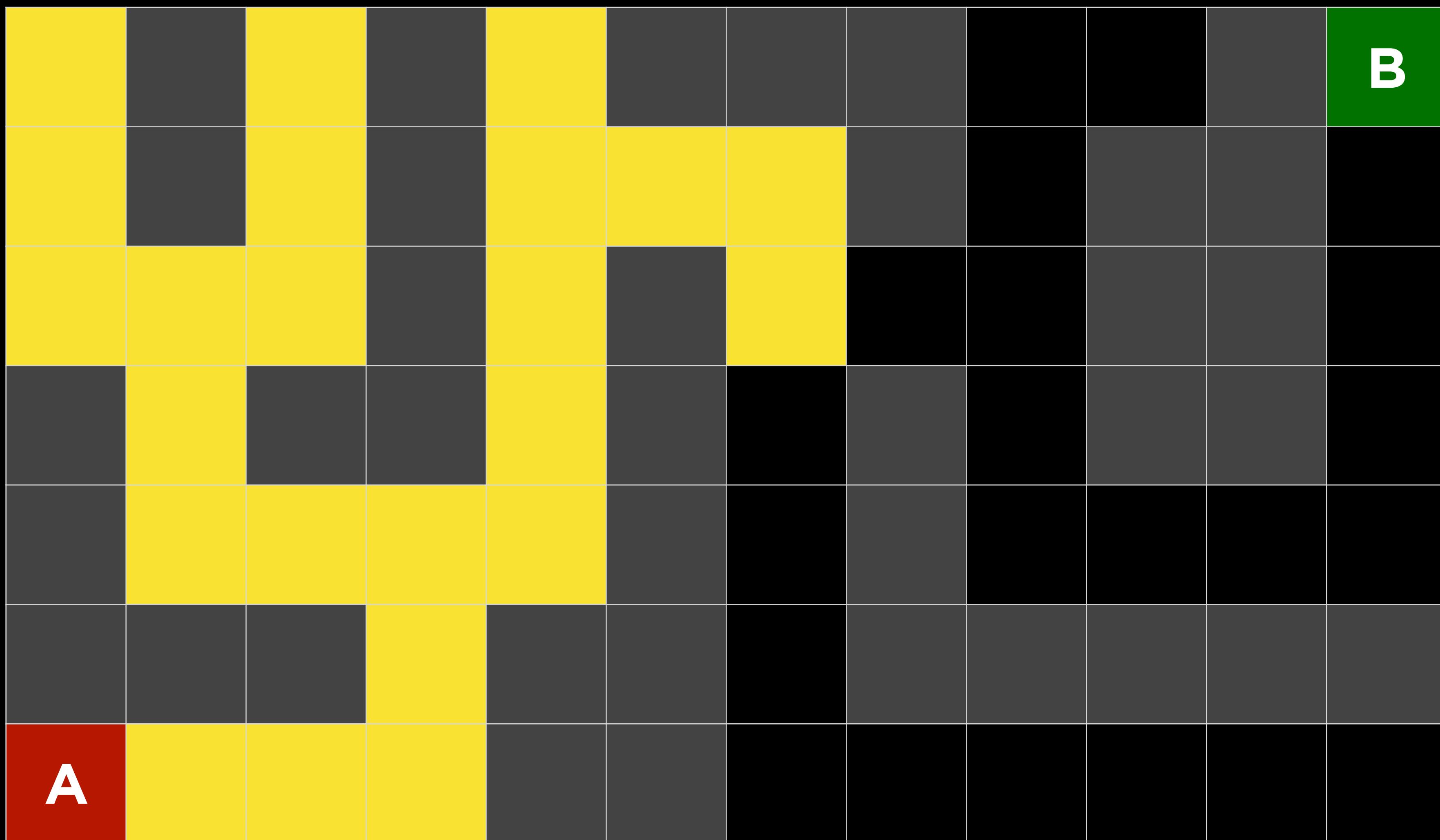
# Breadth-First Search



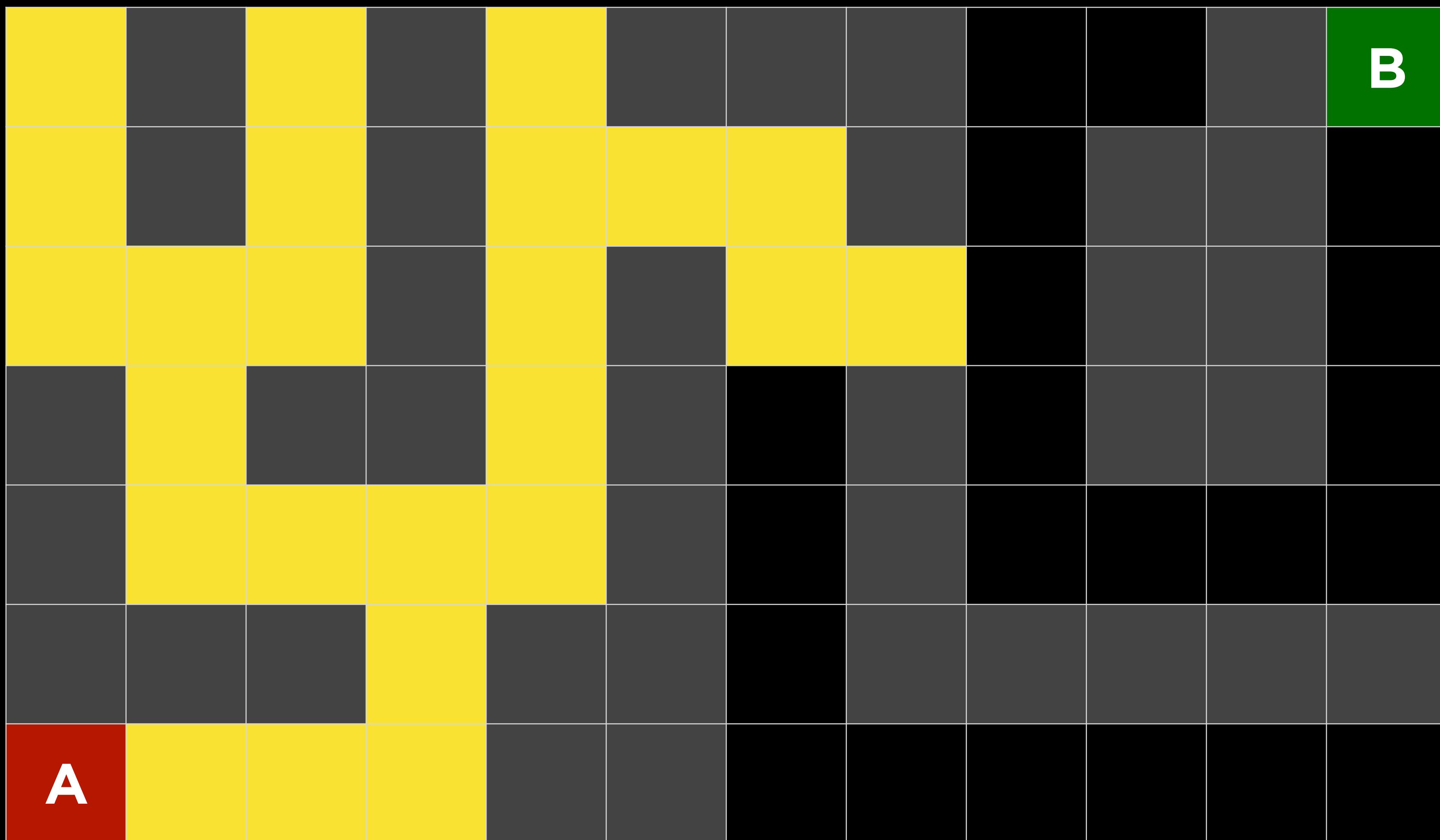
# Breadth-First Search



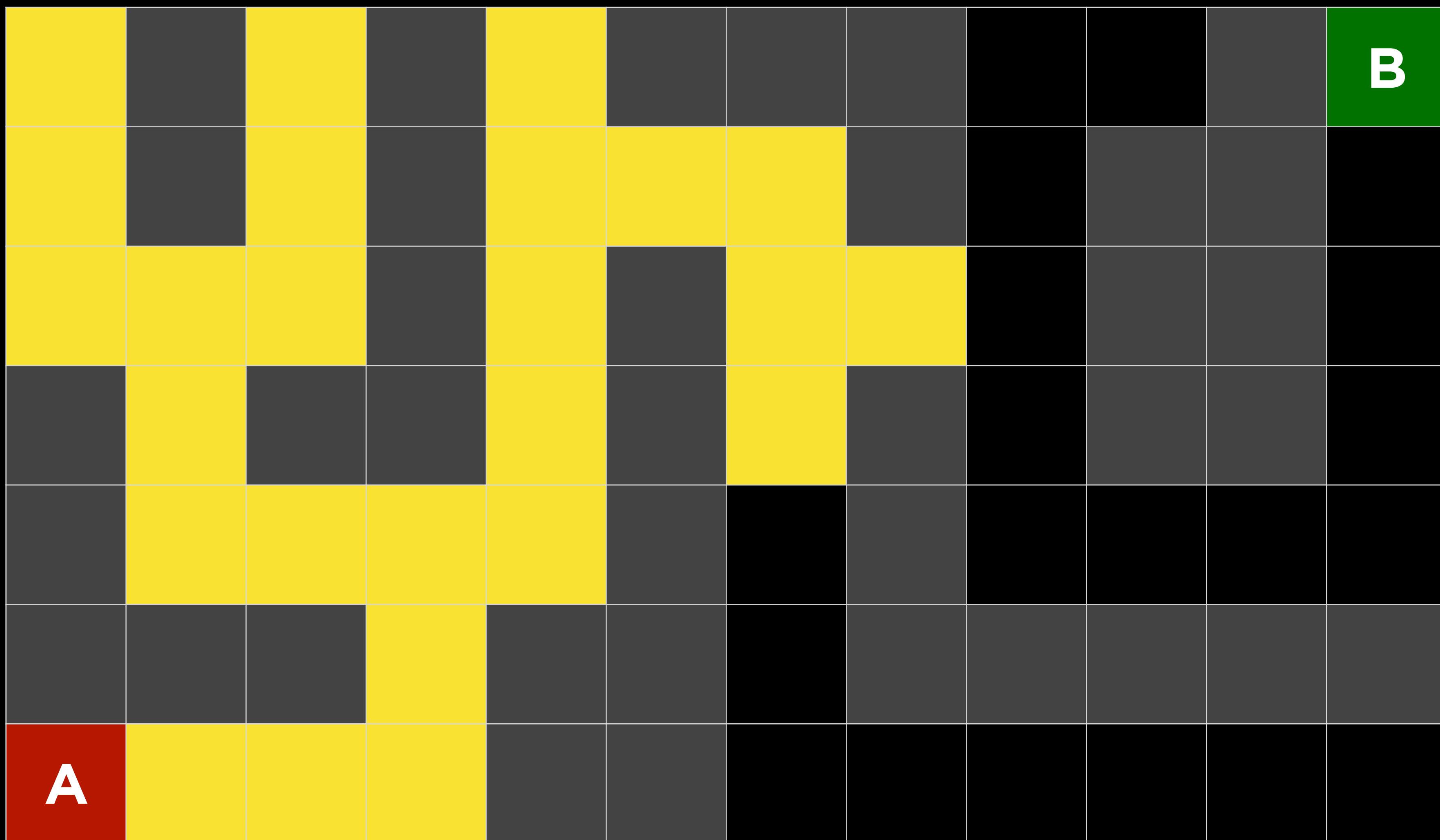
# Breadth-First Search



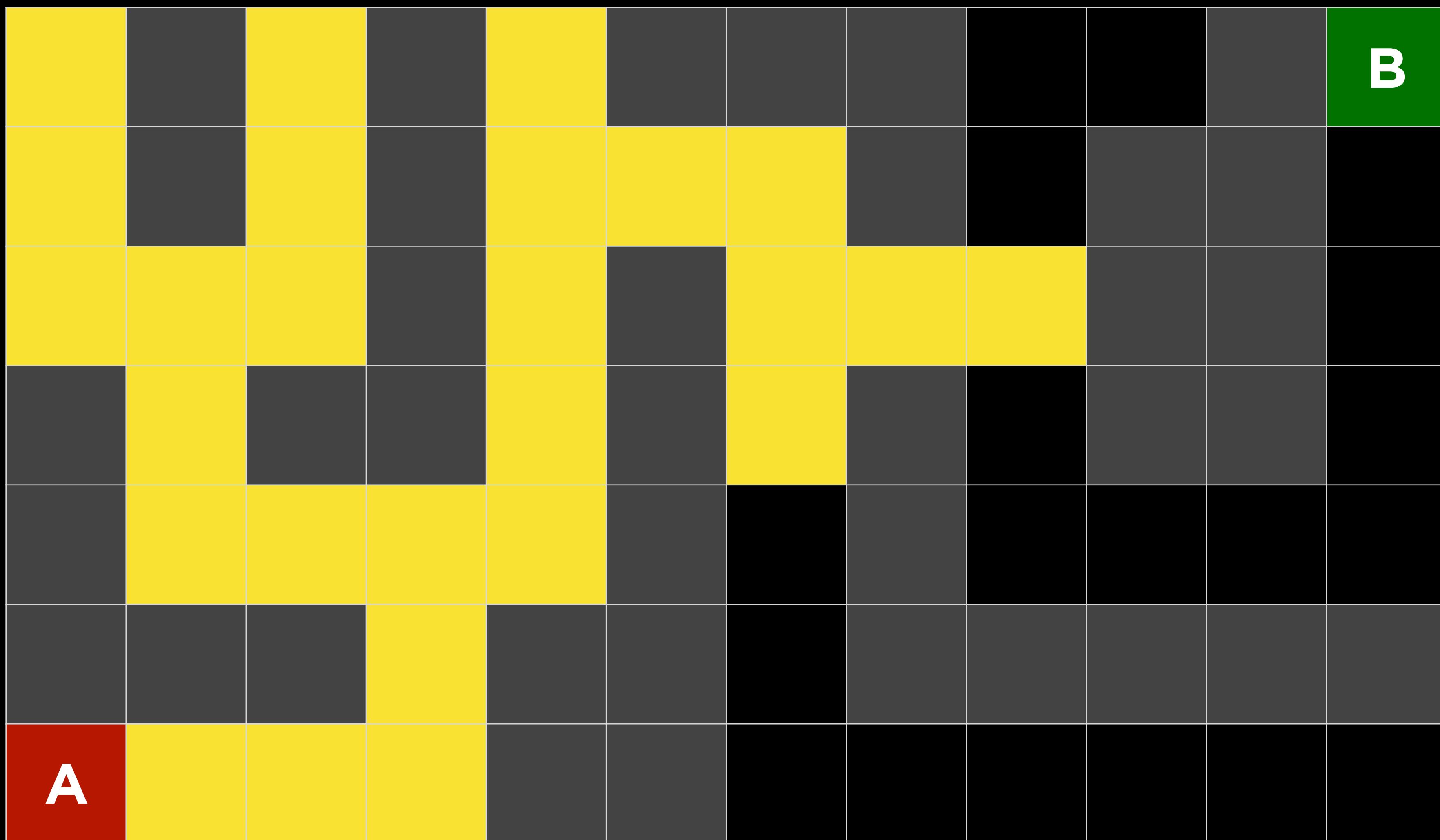
# Breadth-First Search



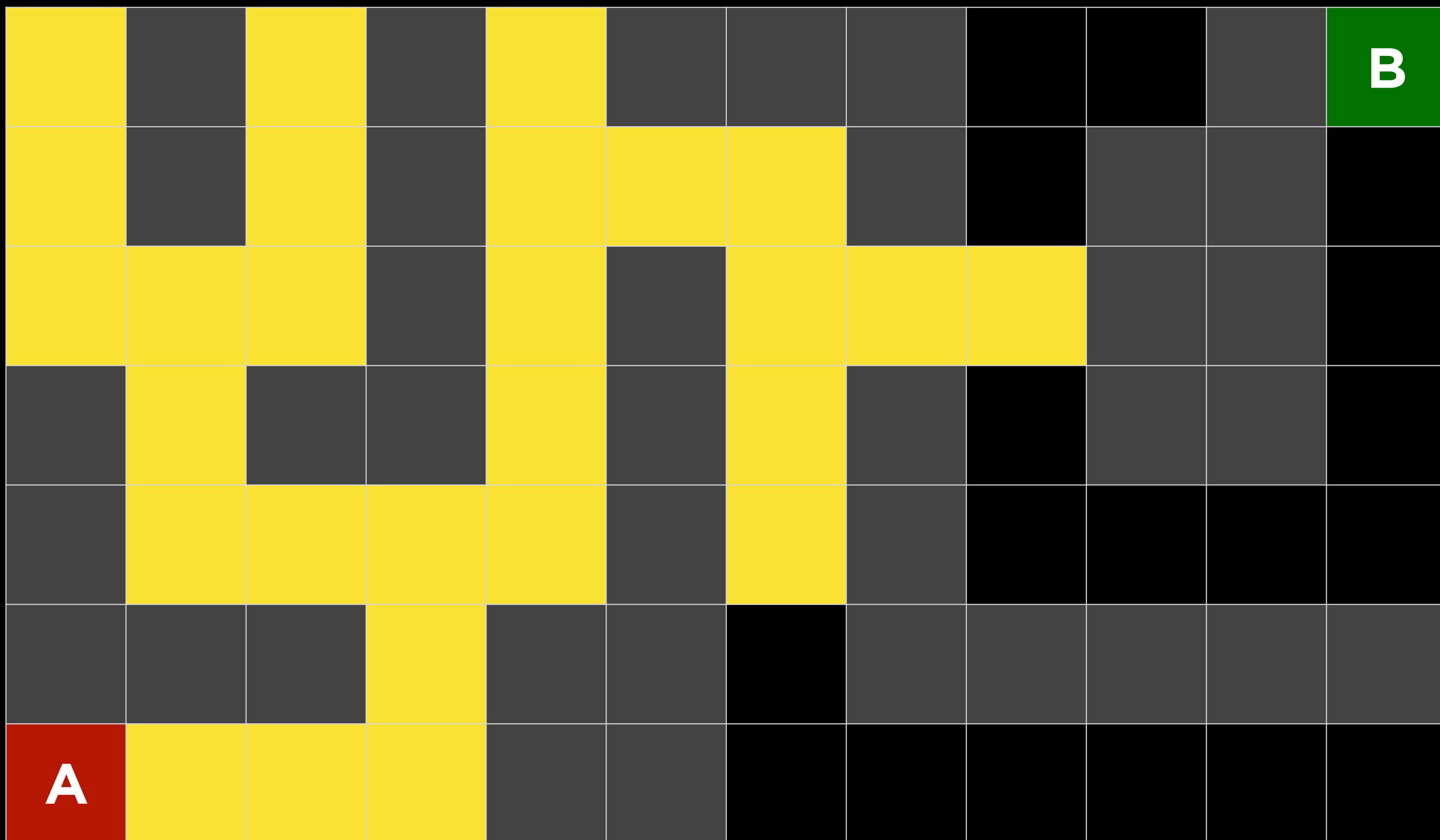
# Breadth-First Search



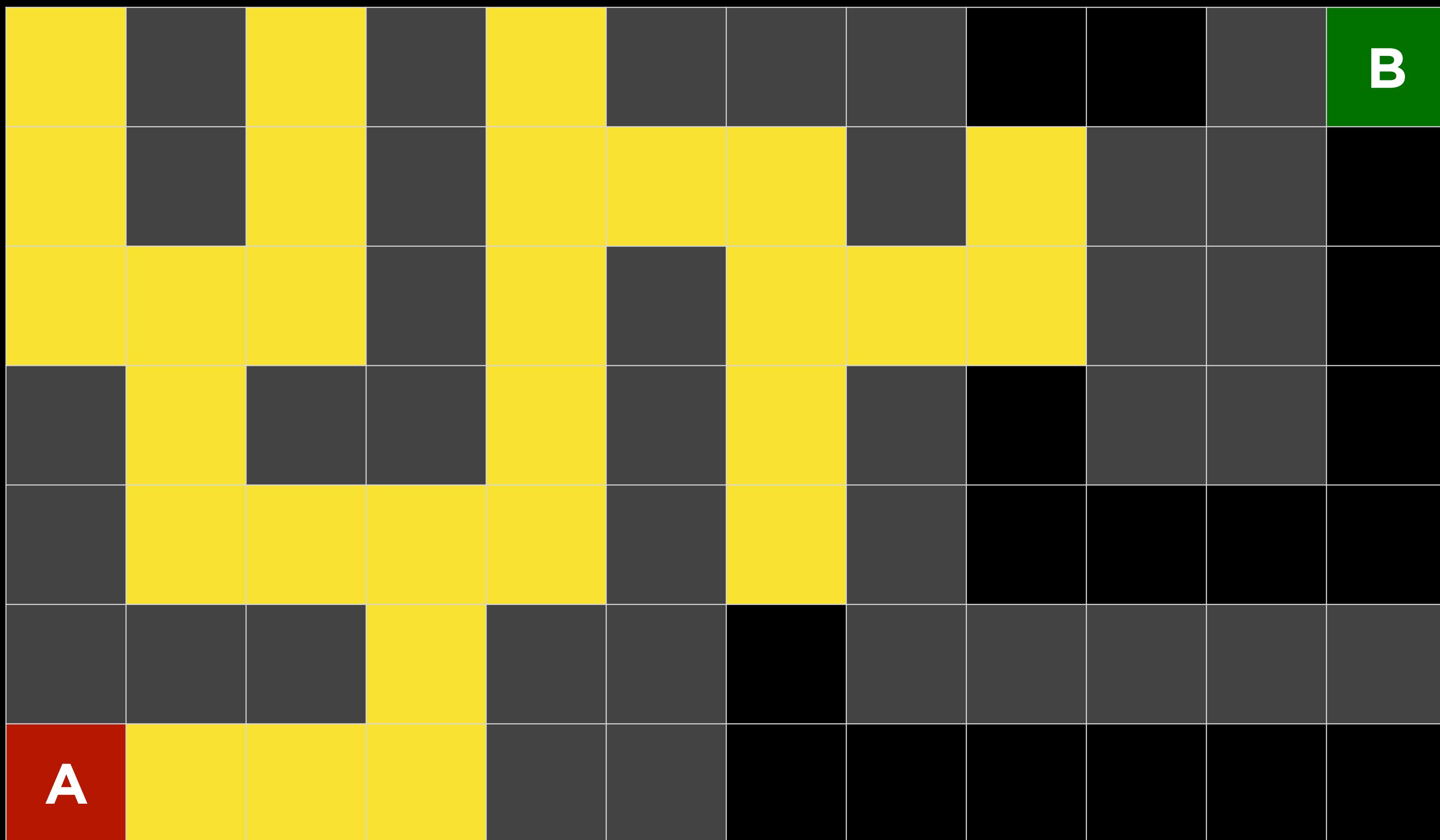
# Breadth-First Search



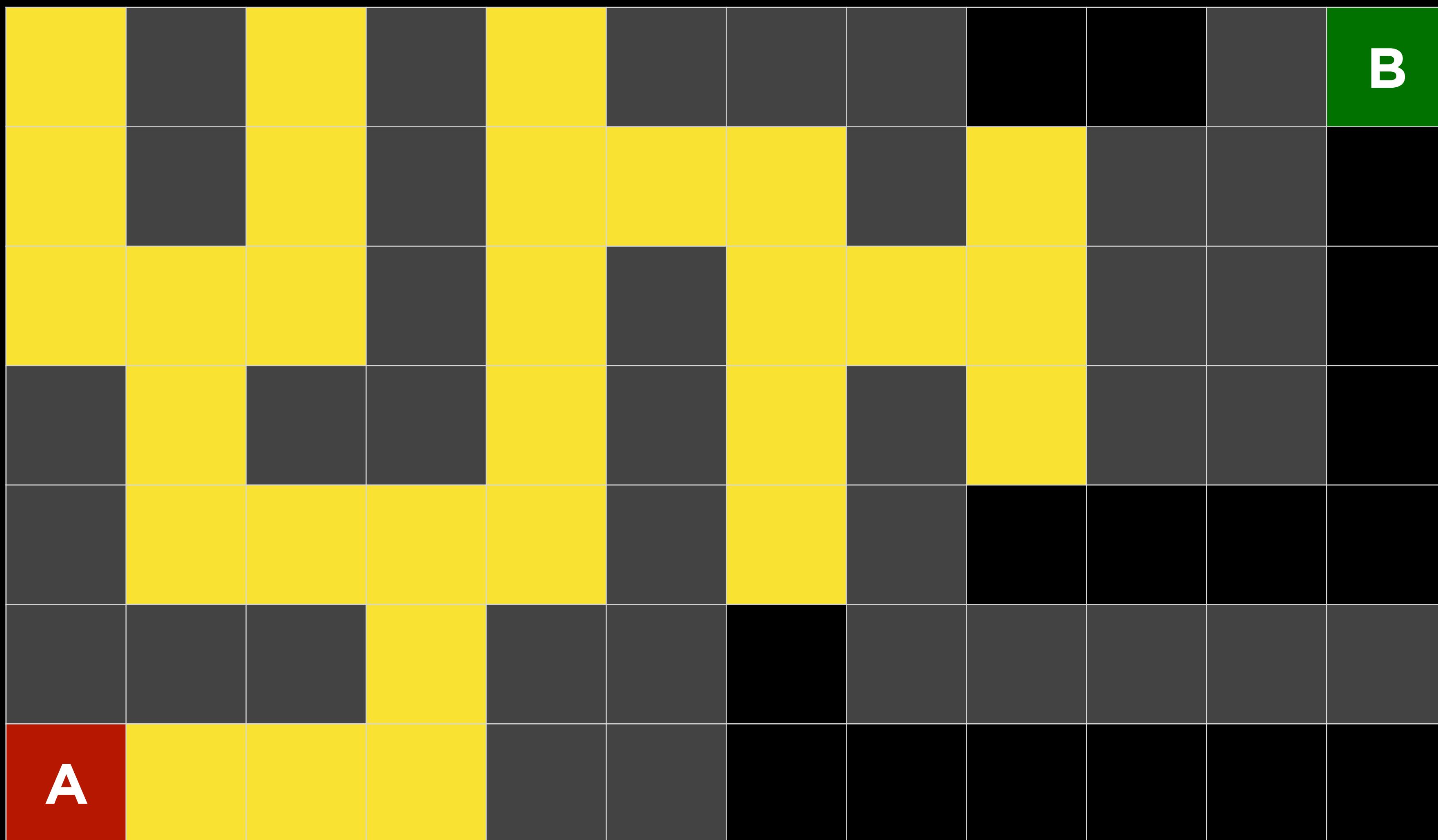
# Breadth-First Search



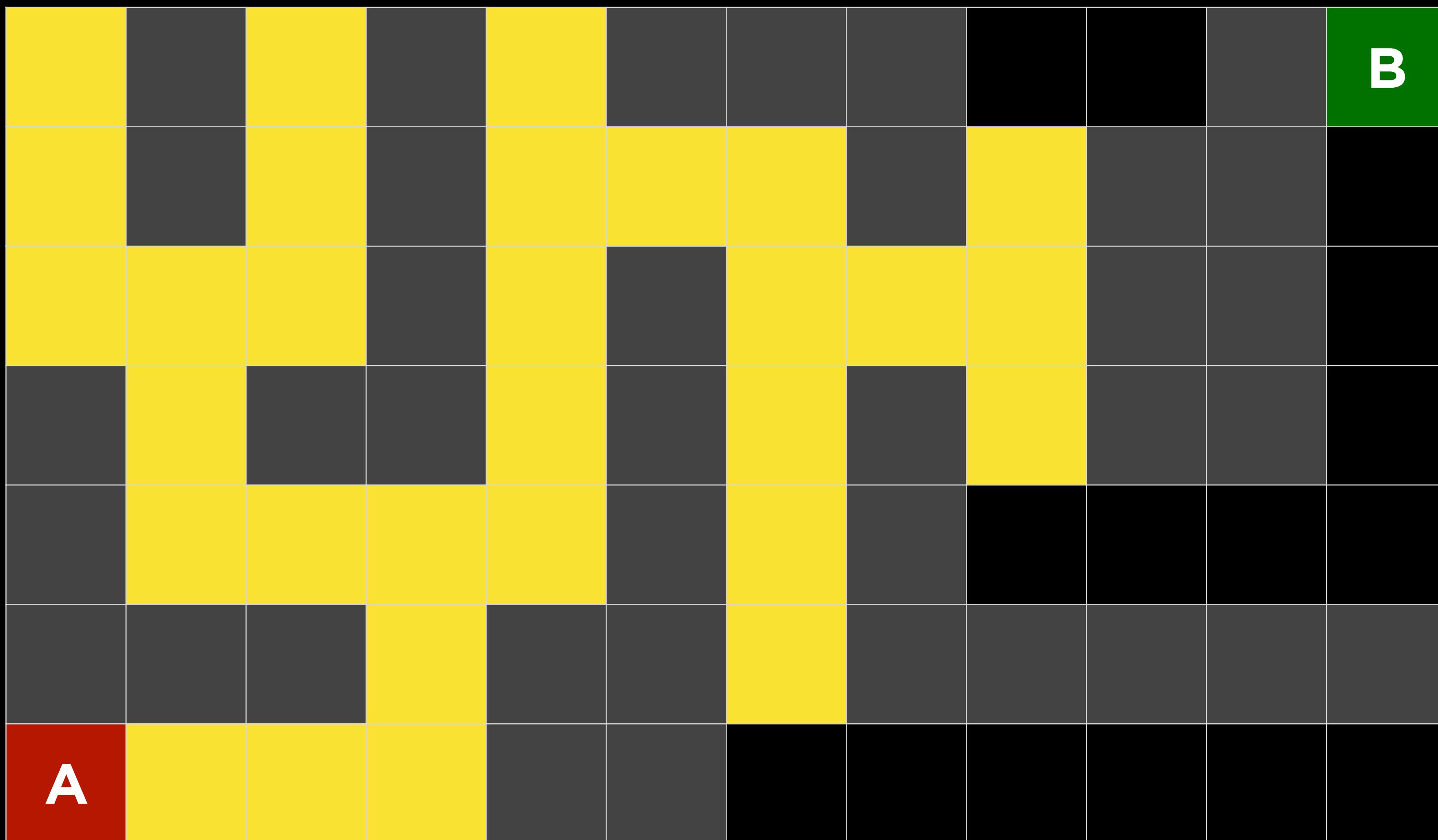
# Breadth-First Search



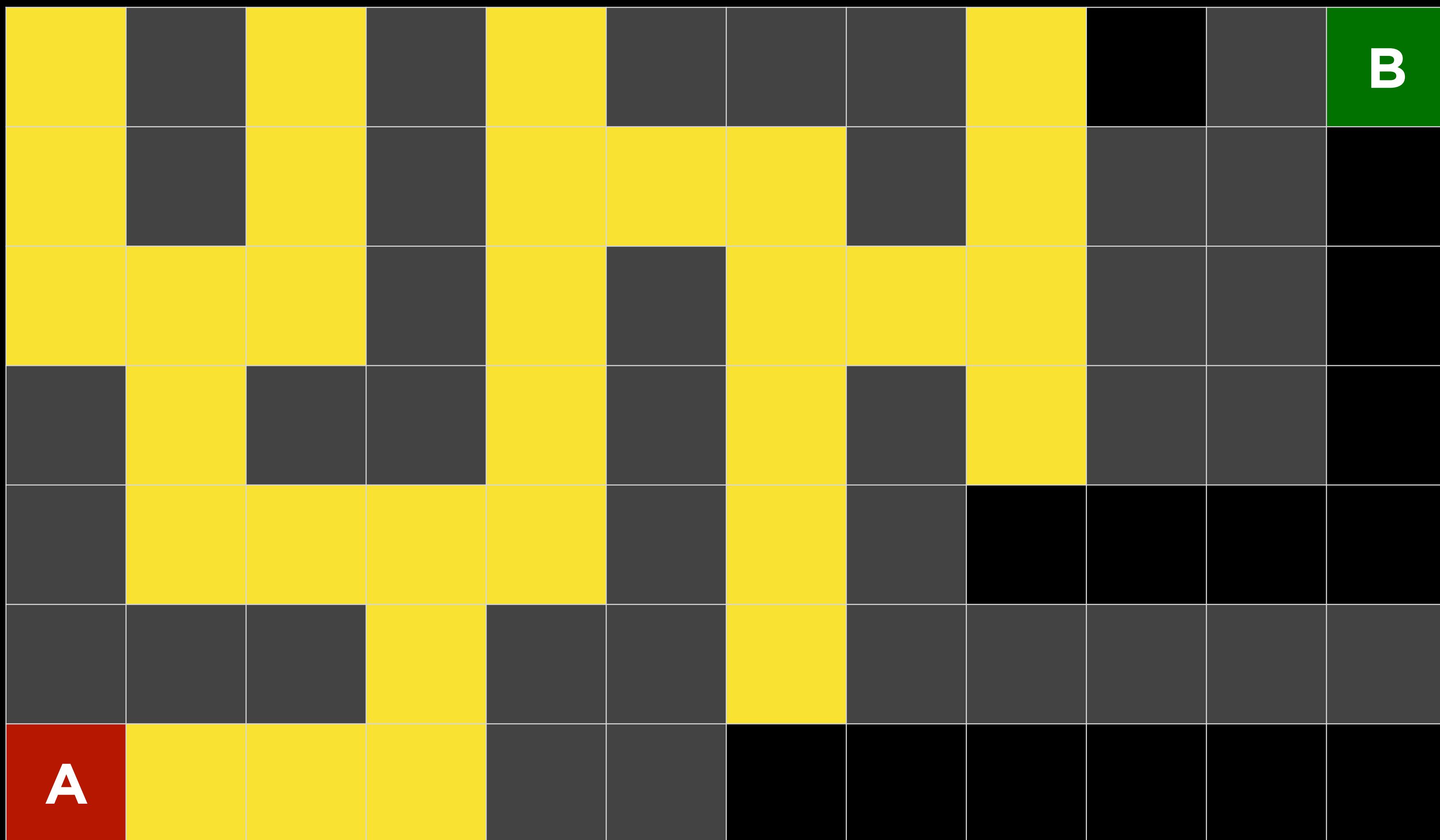
# Breadth-First Search



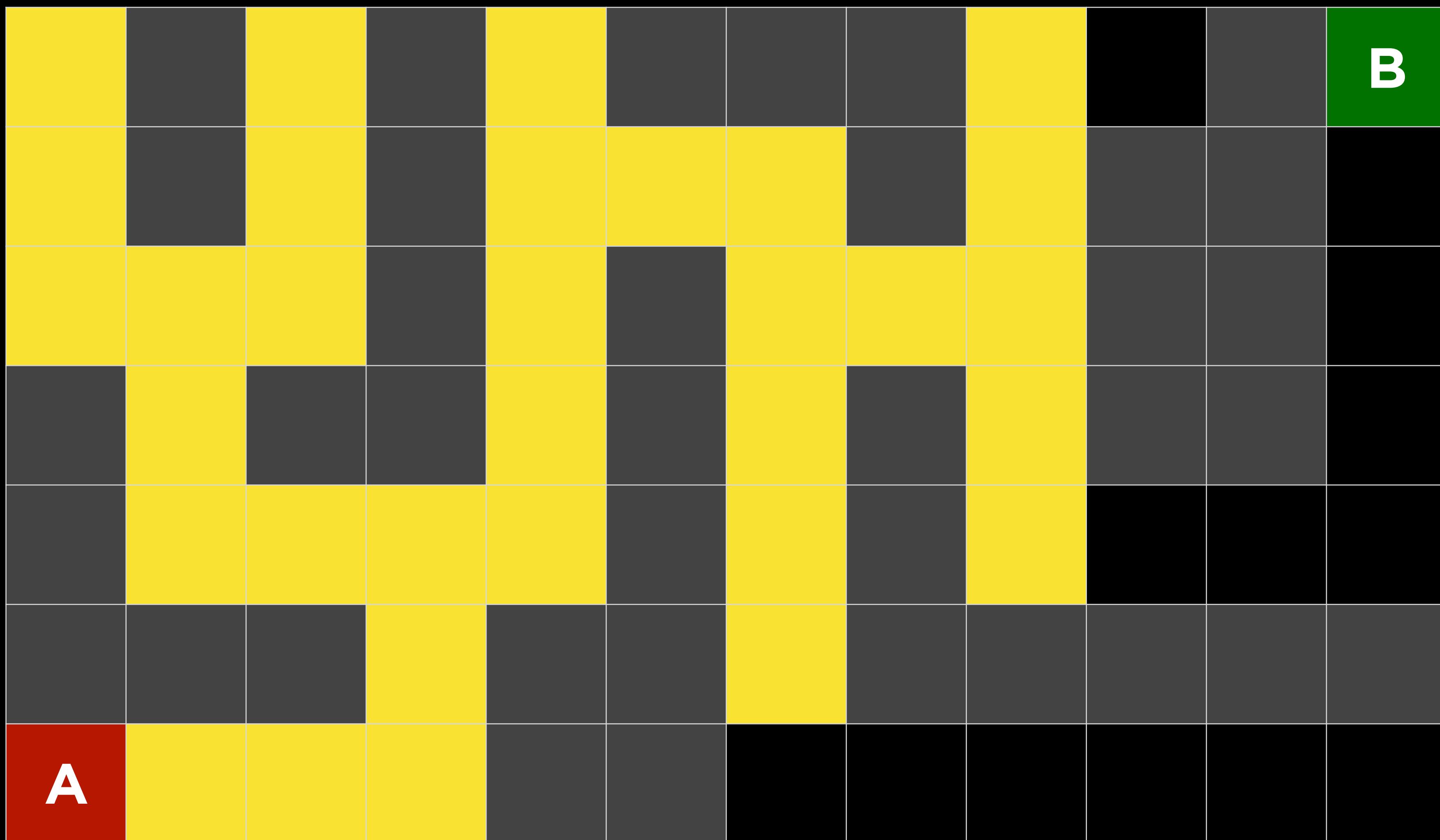
# Breadth-First Search



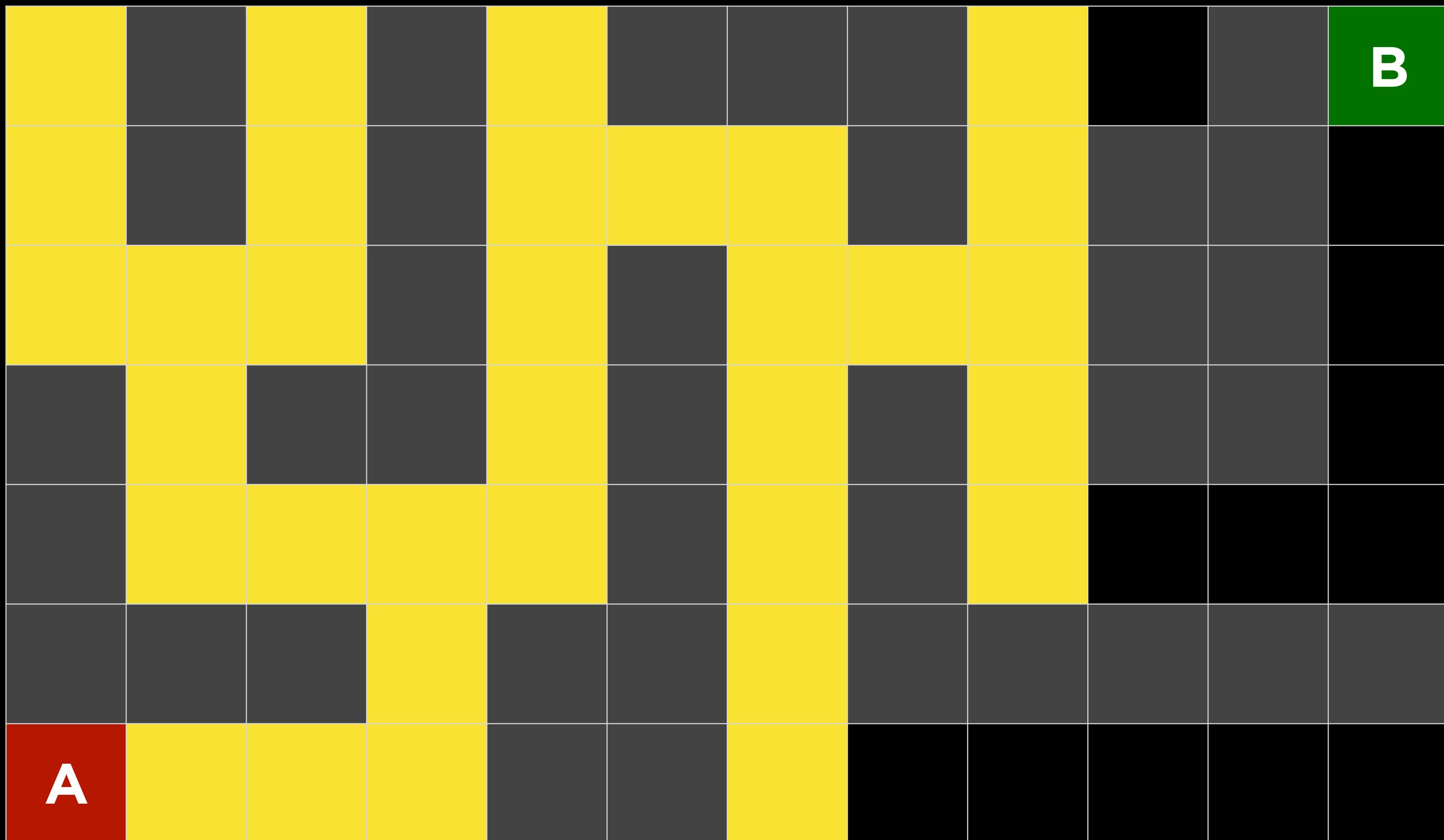
# Breadth-First Search



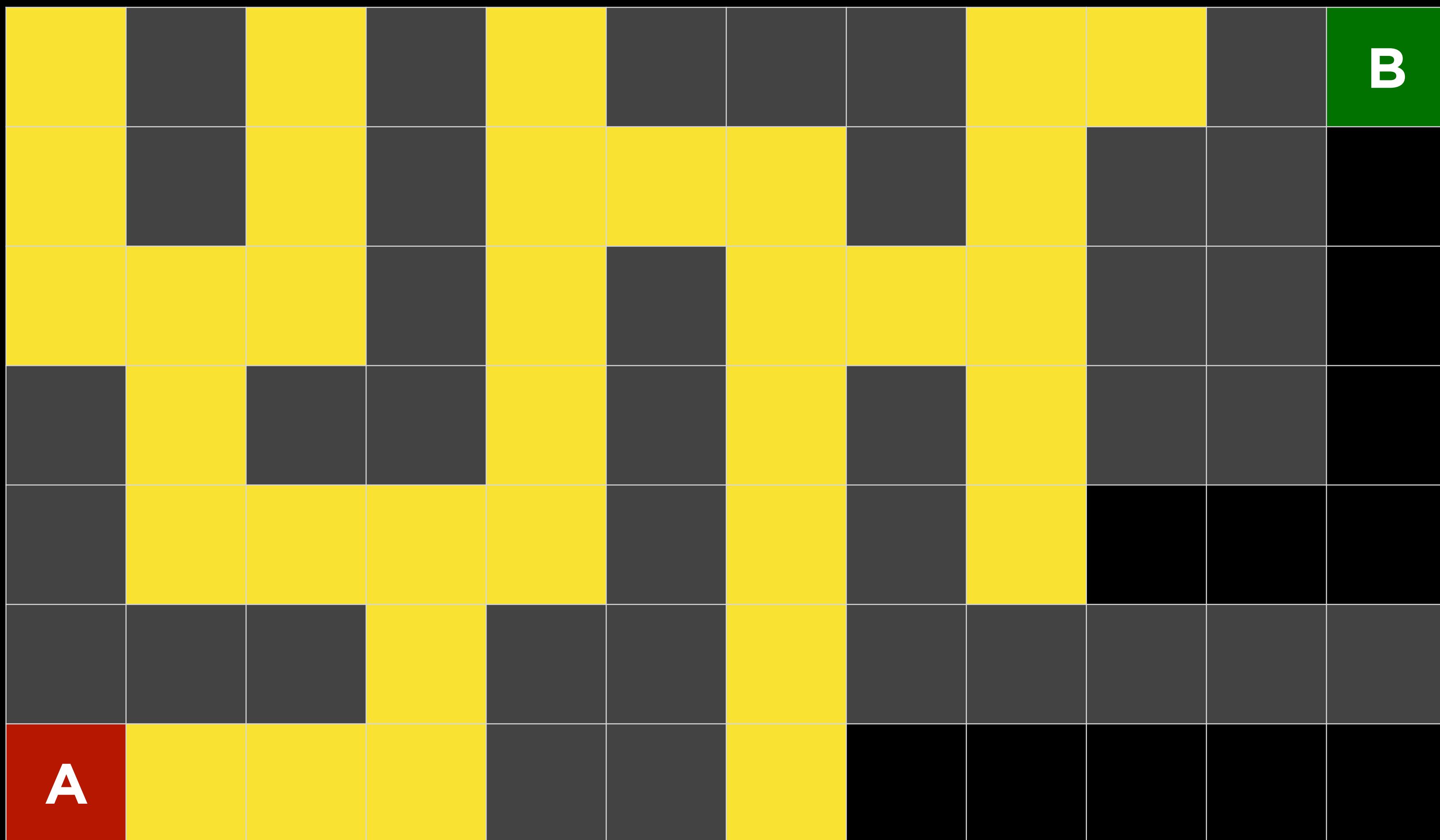
# Breadth-First Search



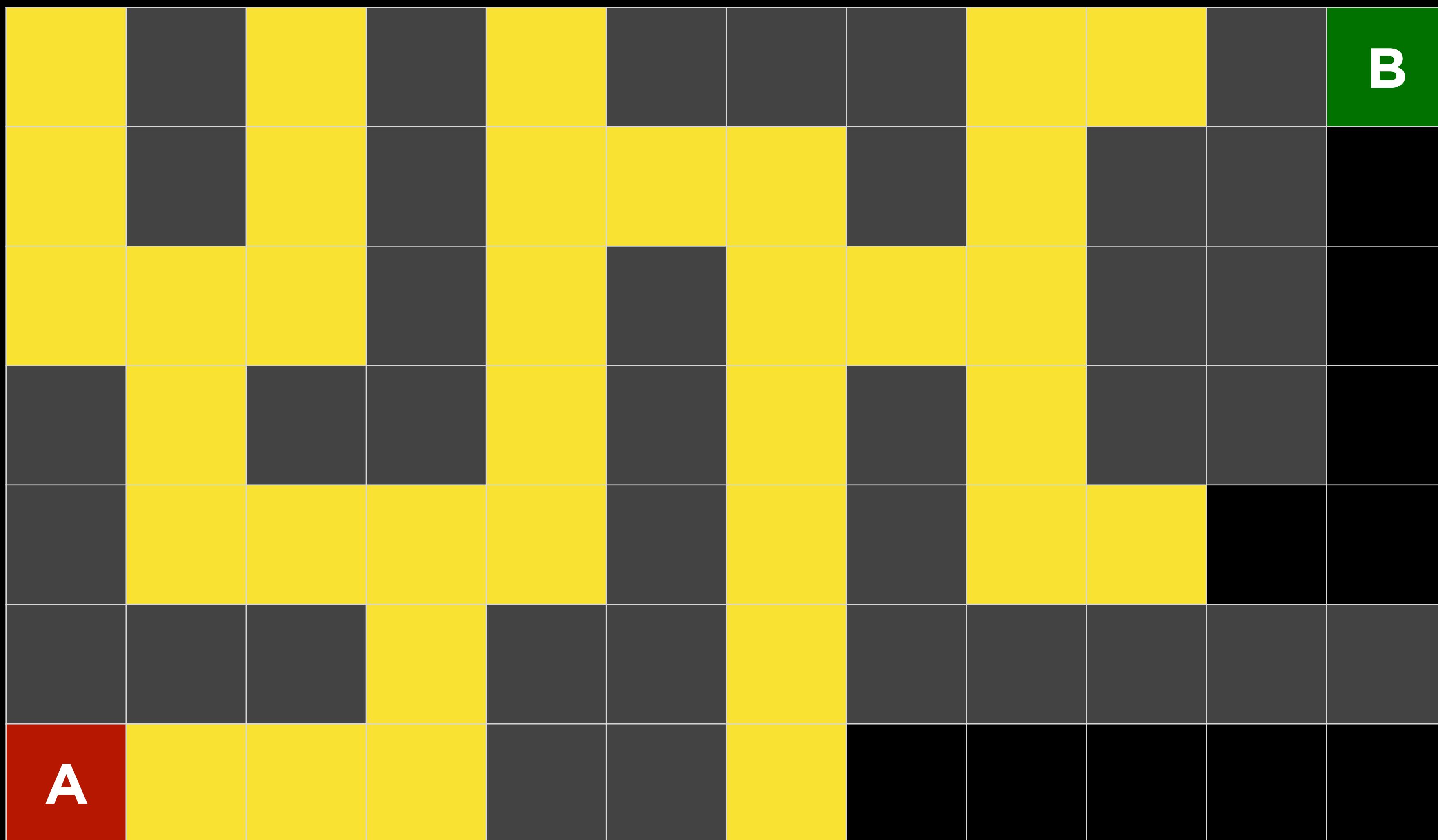
# Breadth-First Search



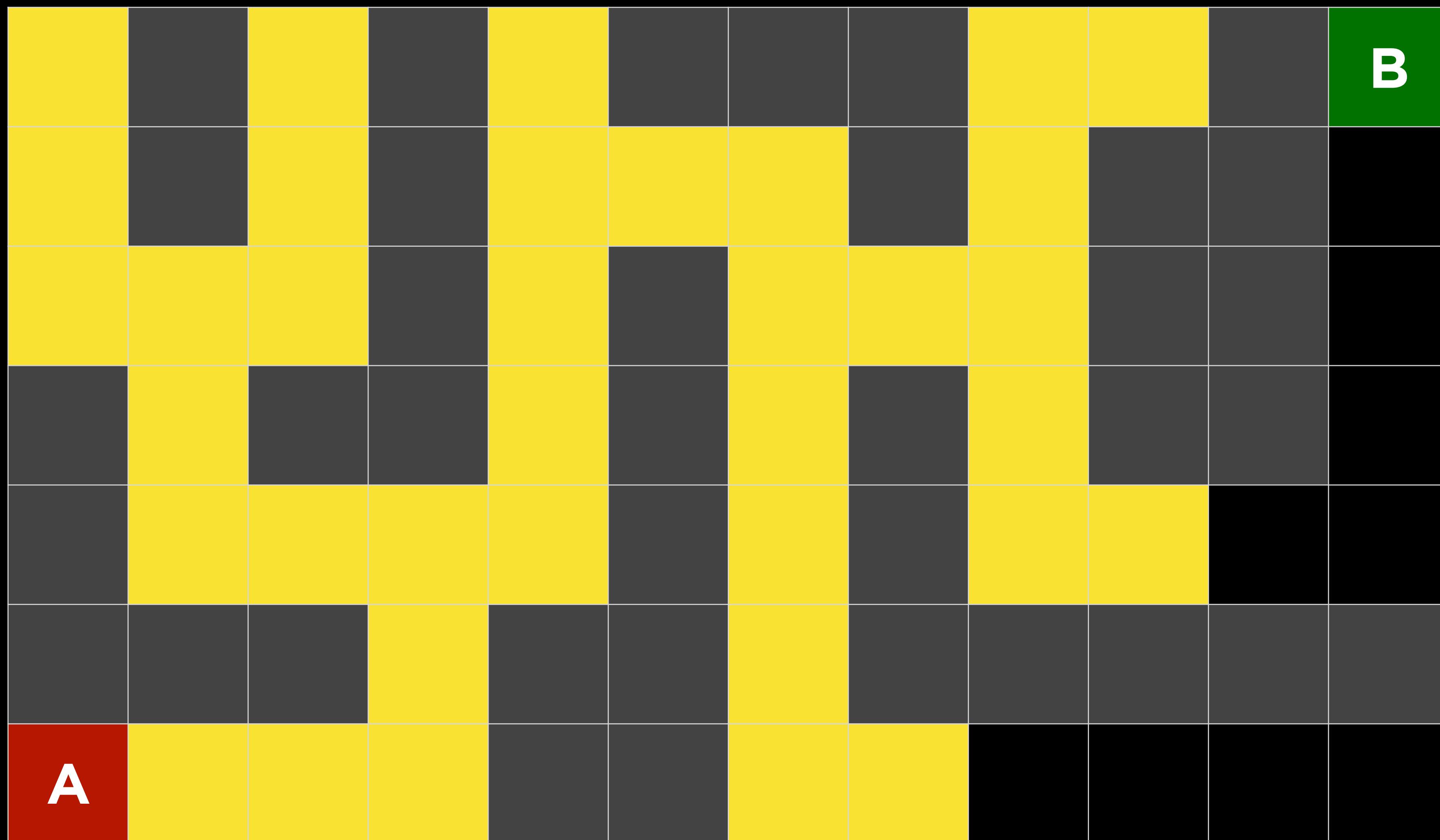
# Breadth-First Search



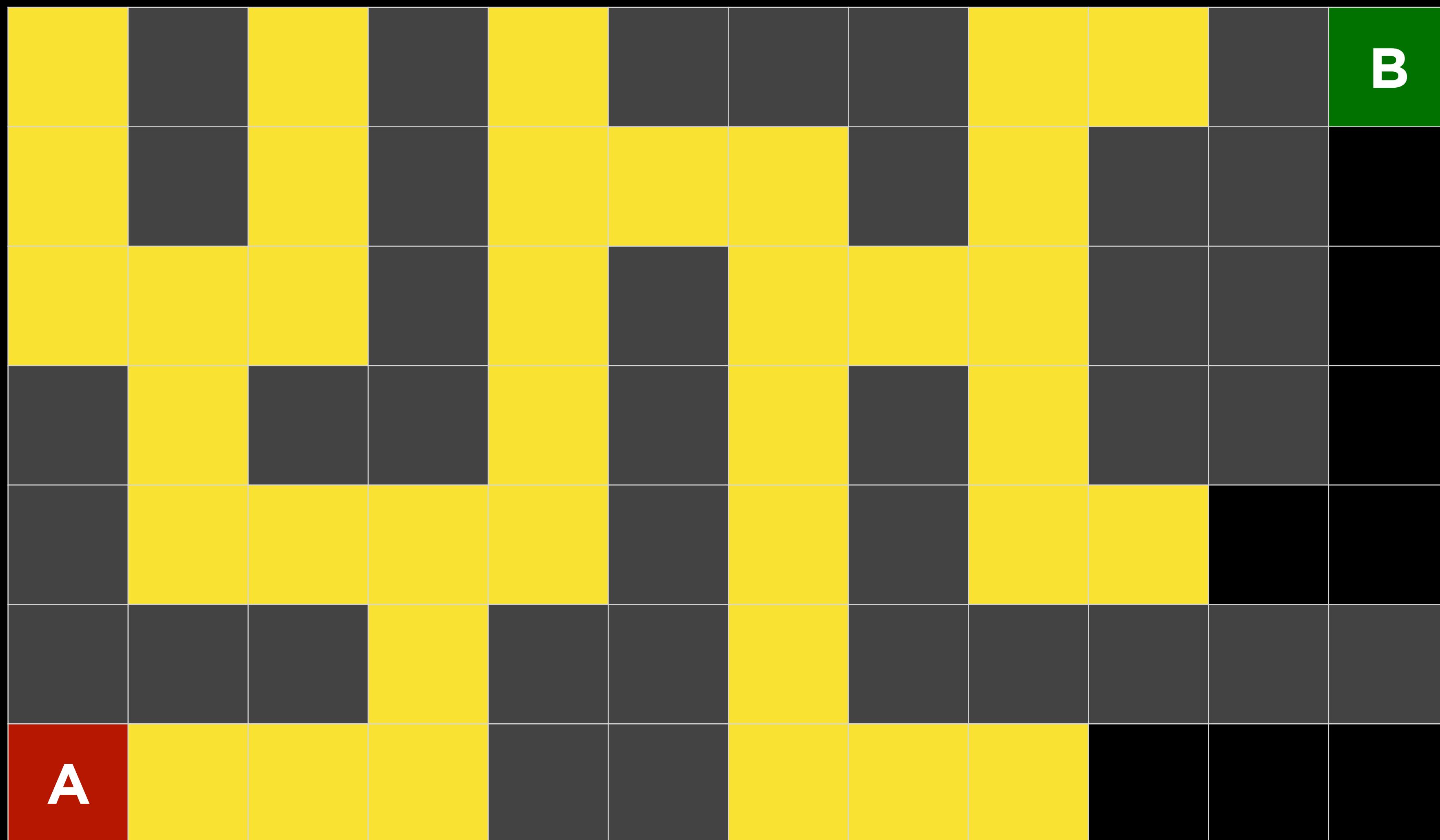
# Breadth-First Search



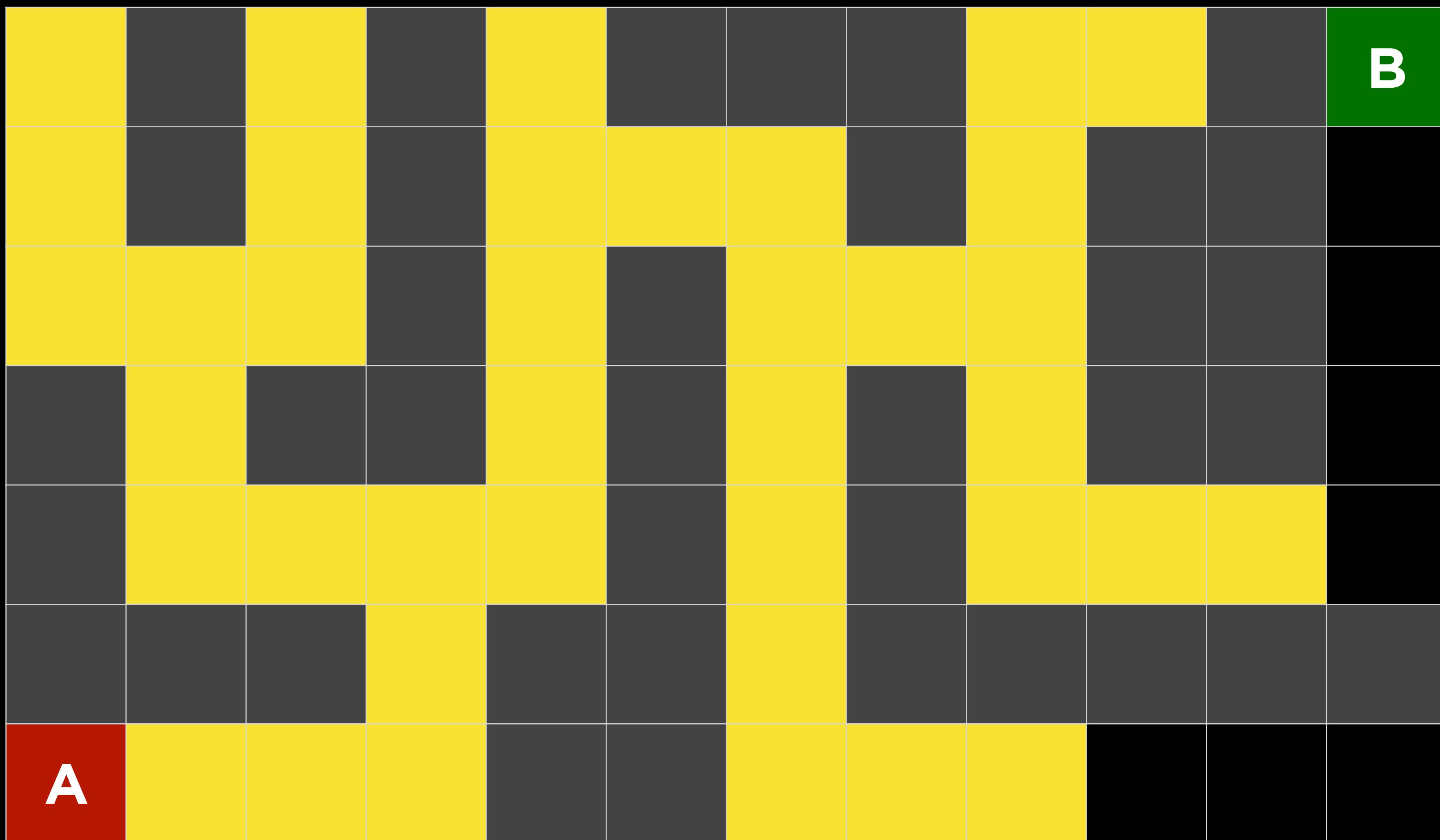
# Breadth-First Search



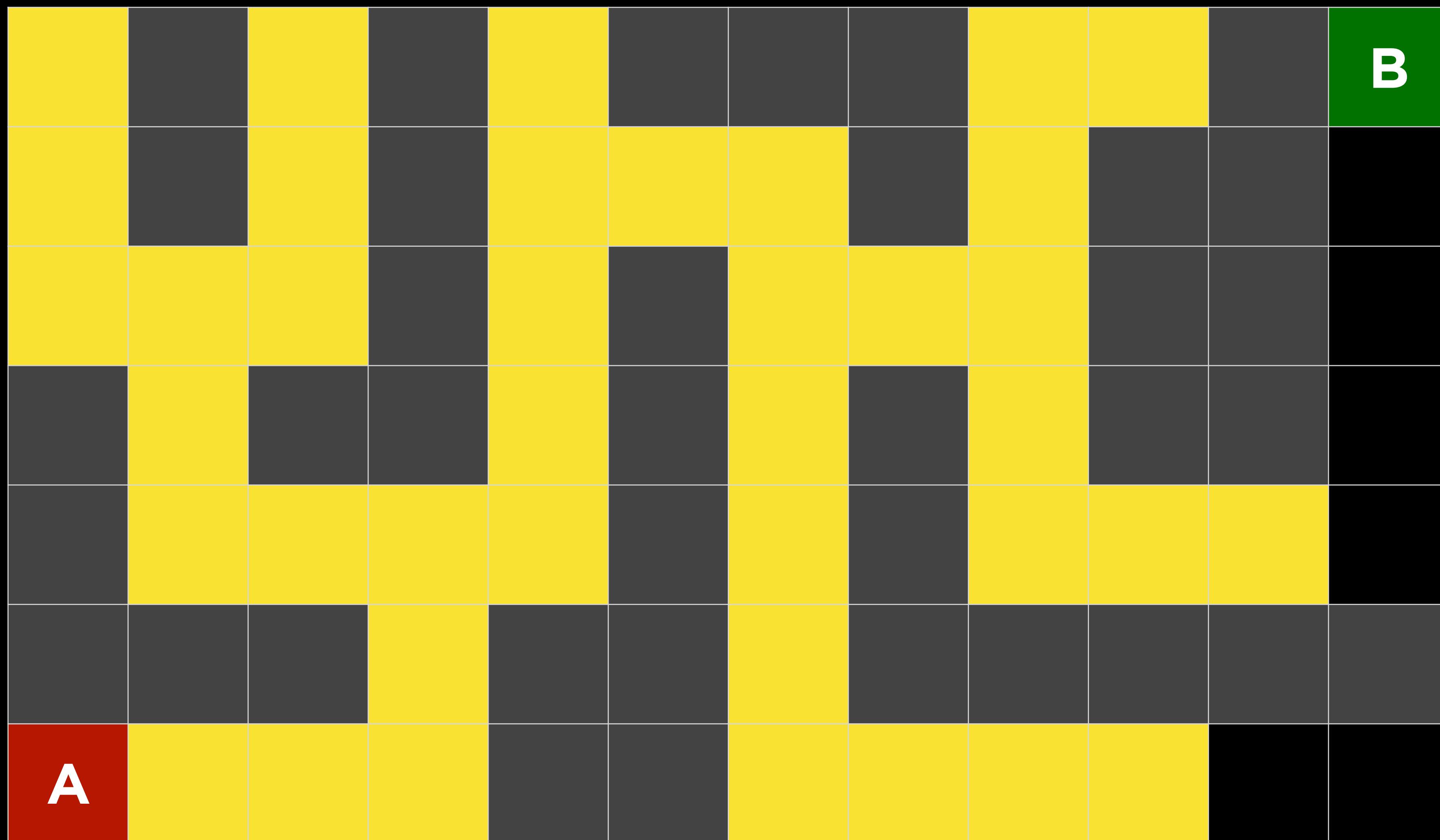
# Breadth-First Search



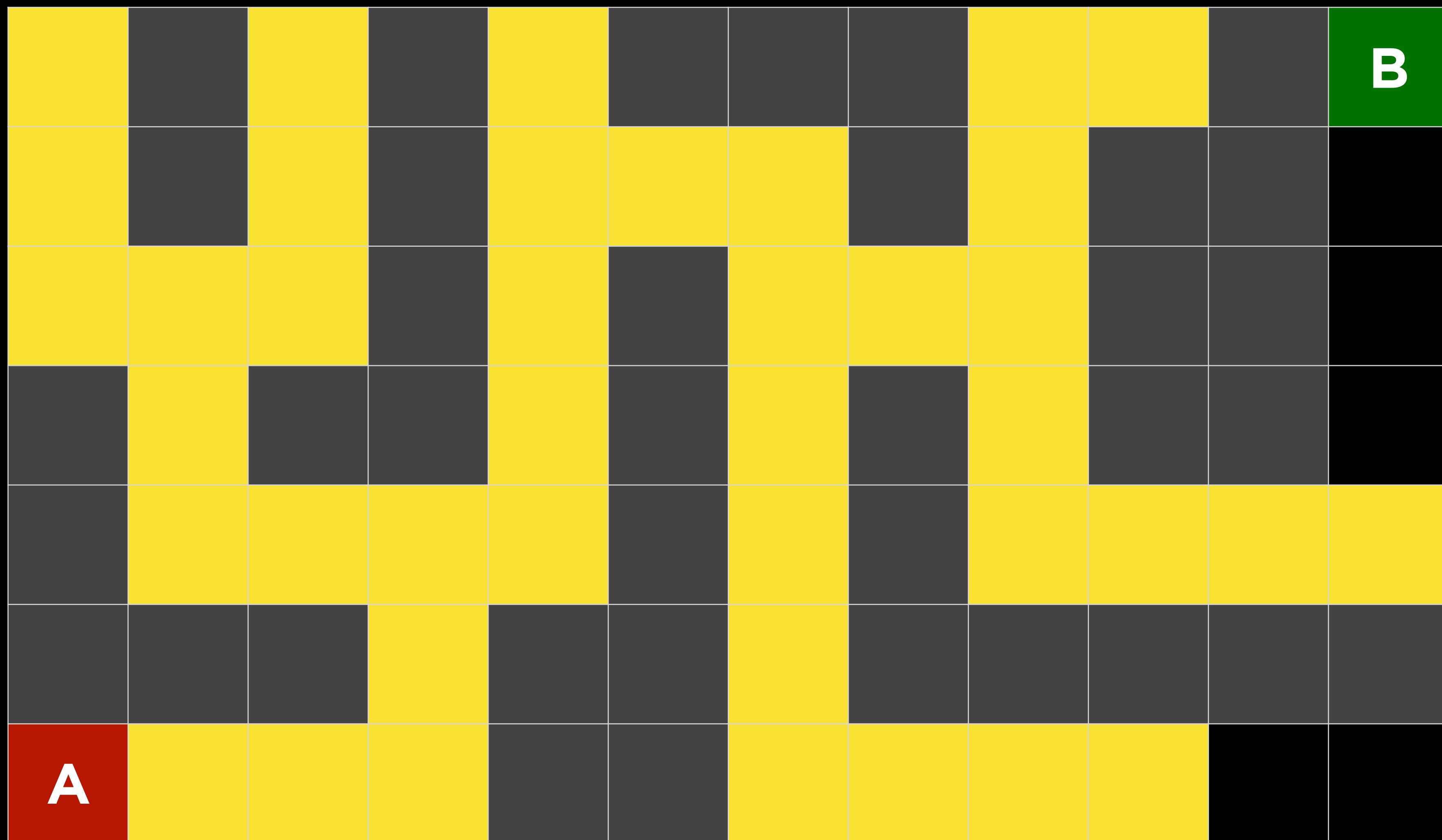
# Breadth-First Search



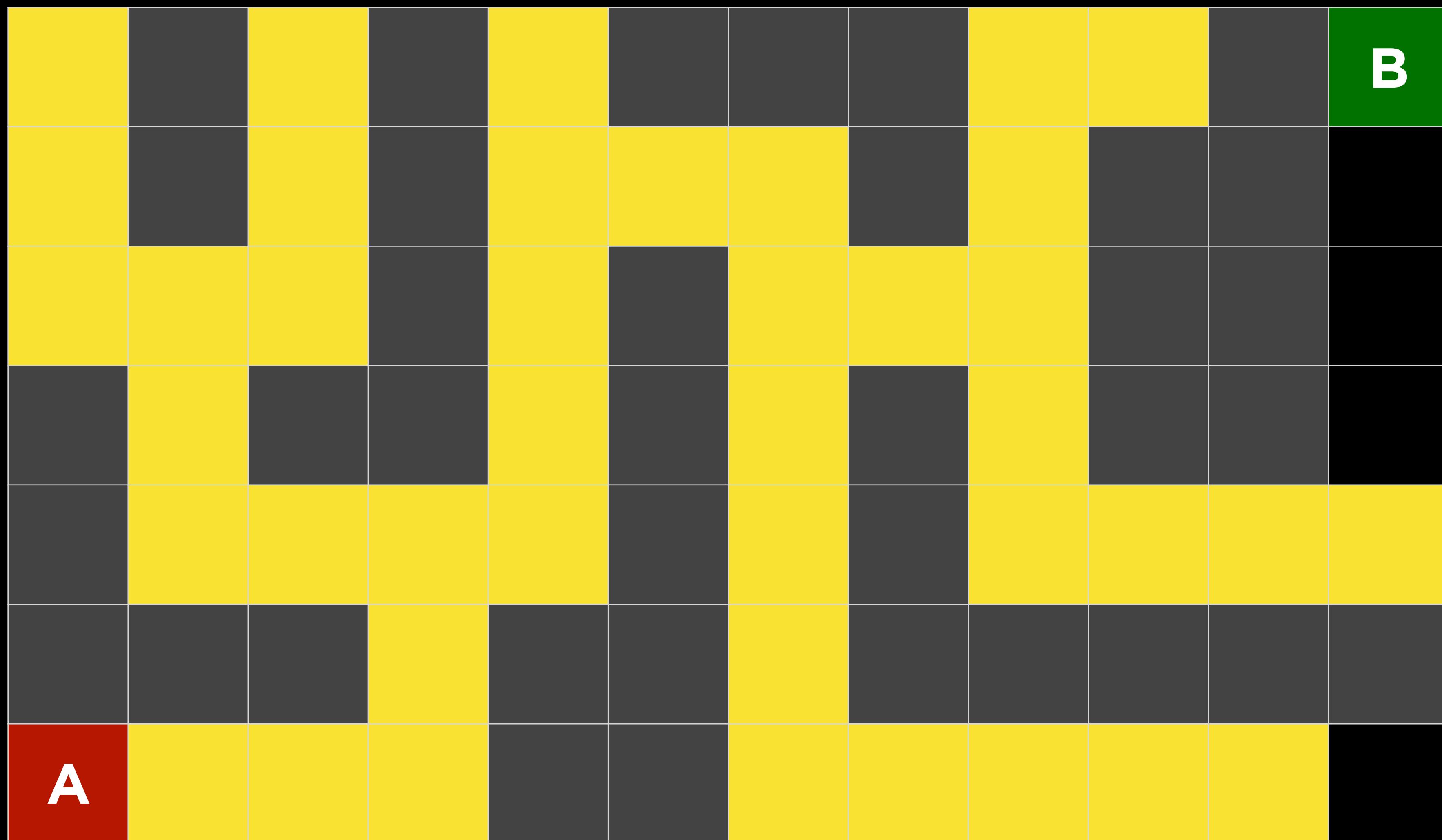
# Breadth-First Search



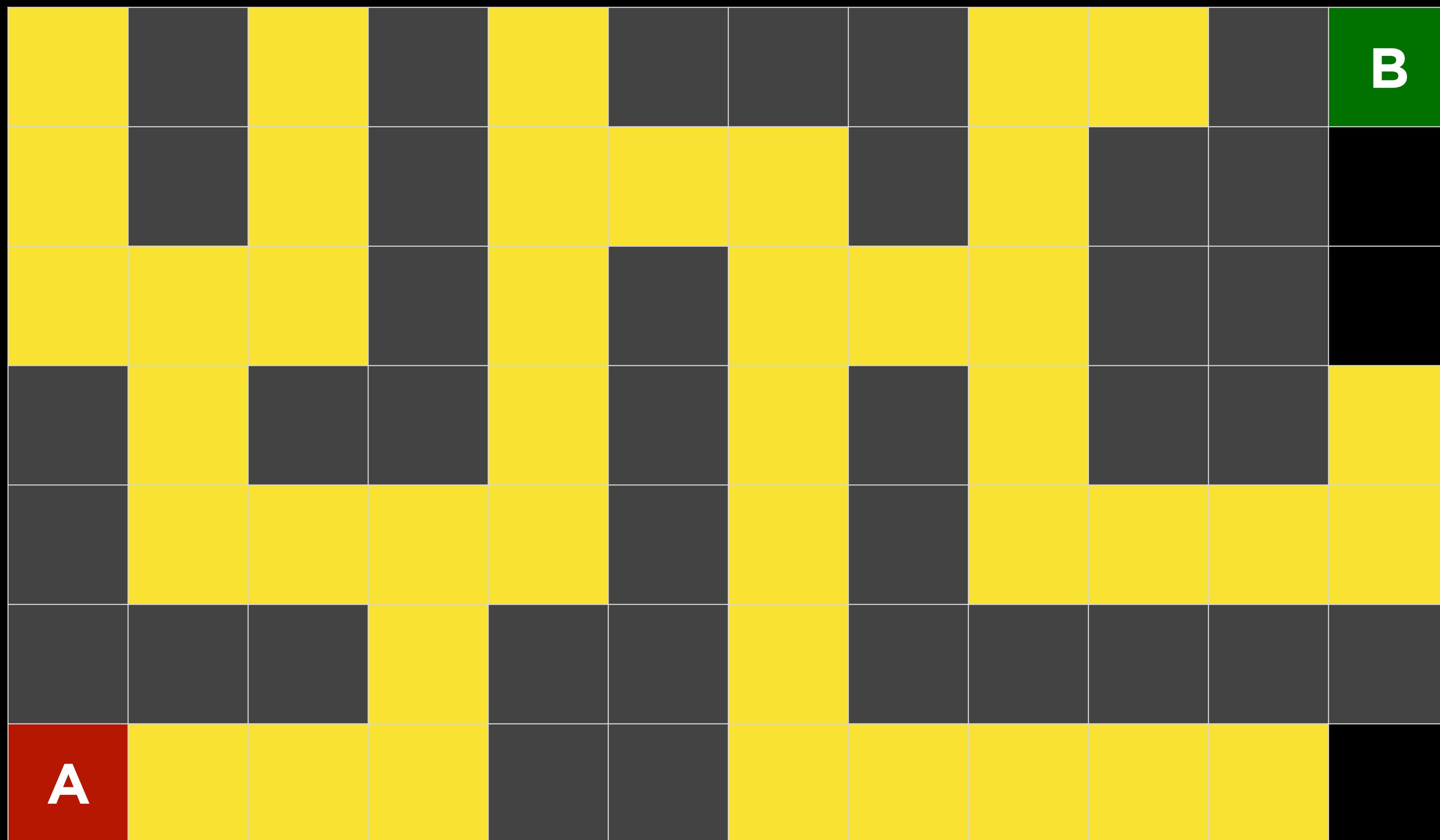
# Breadth-First Search



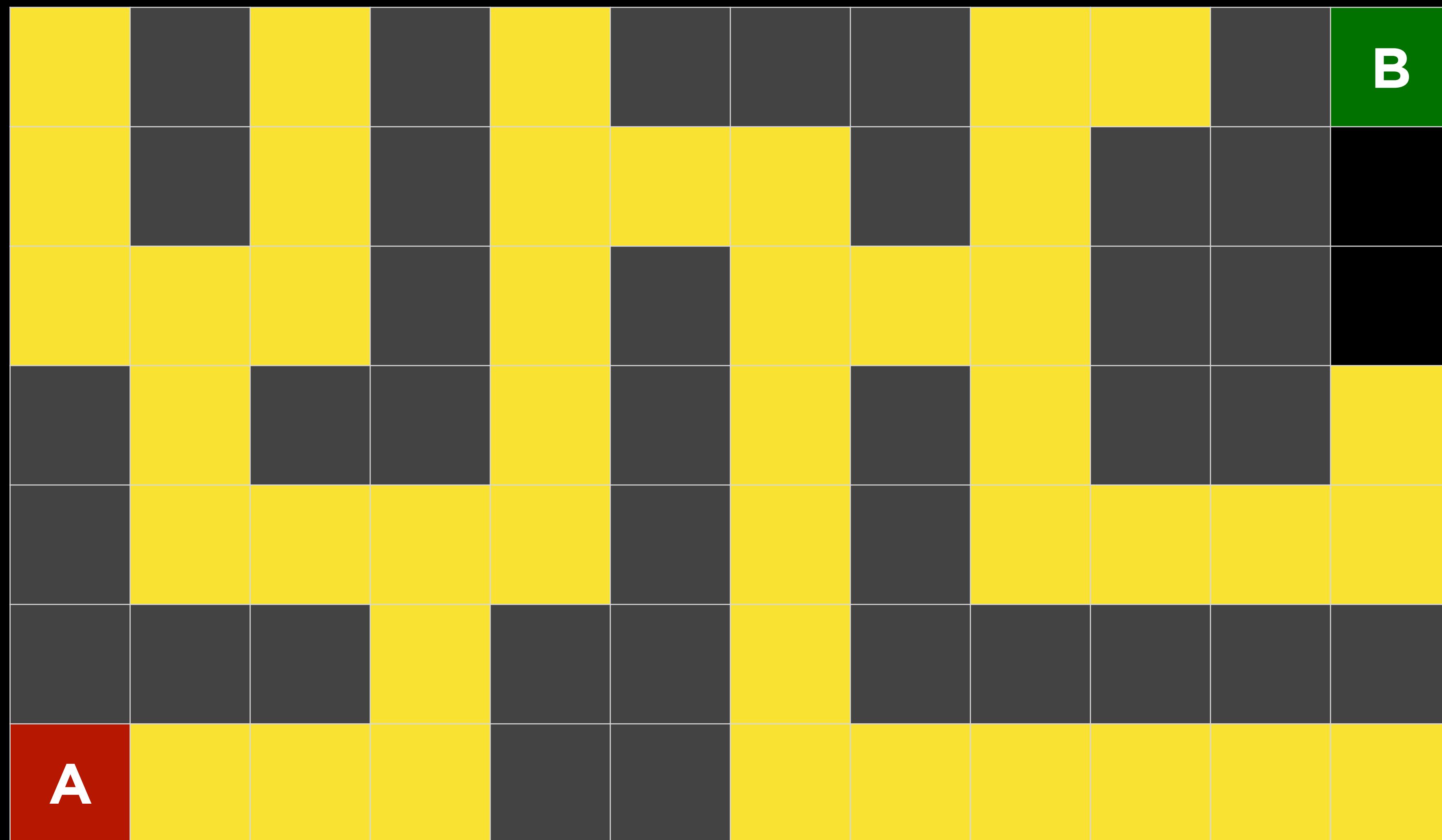
# Breadth-First Search



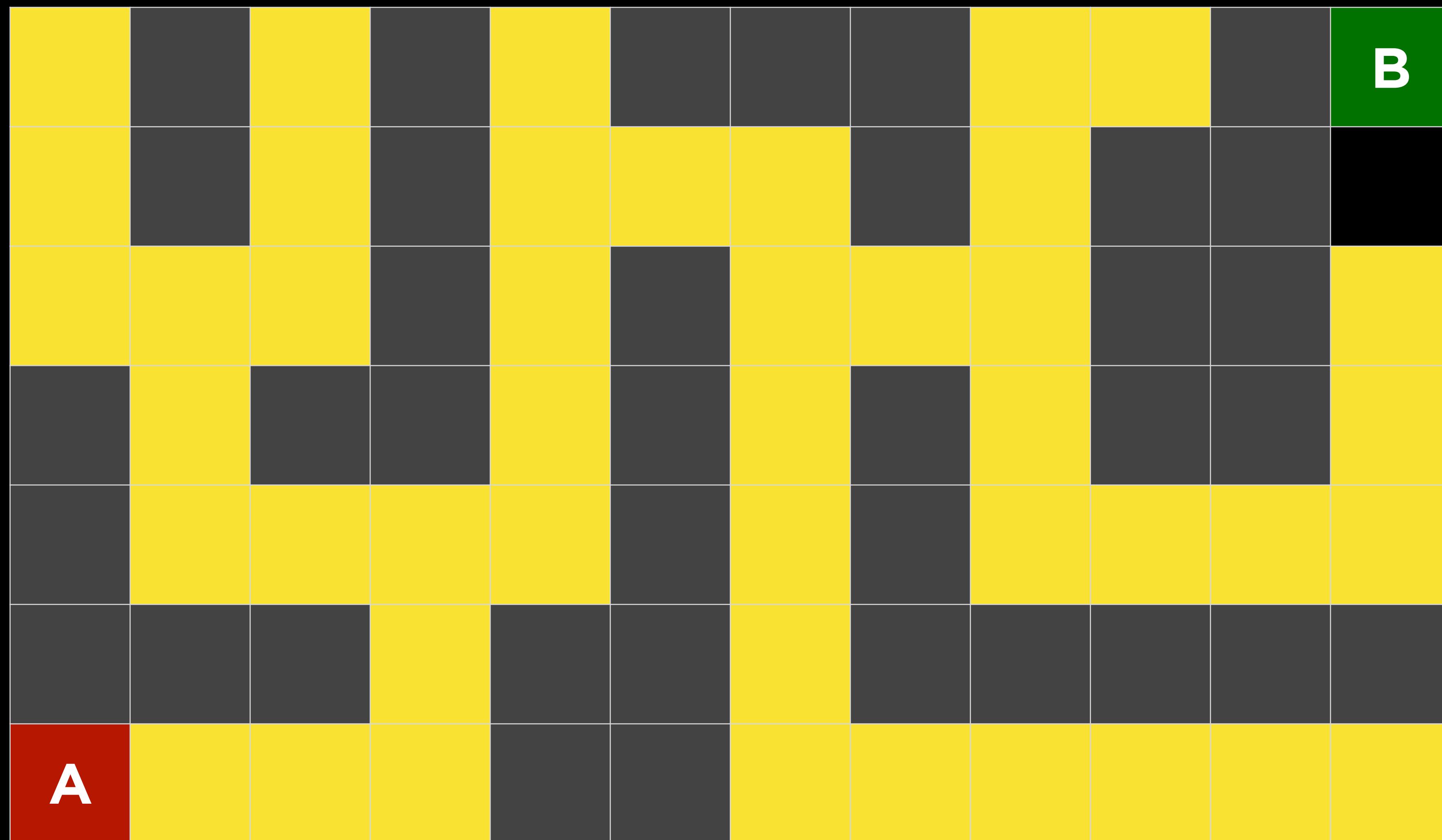
# Breadth-First Search



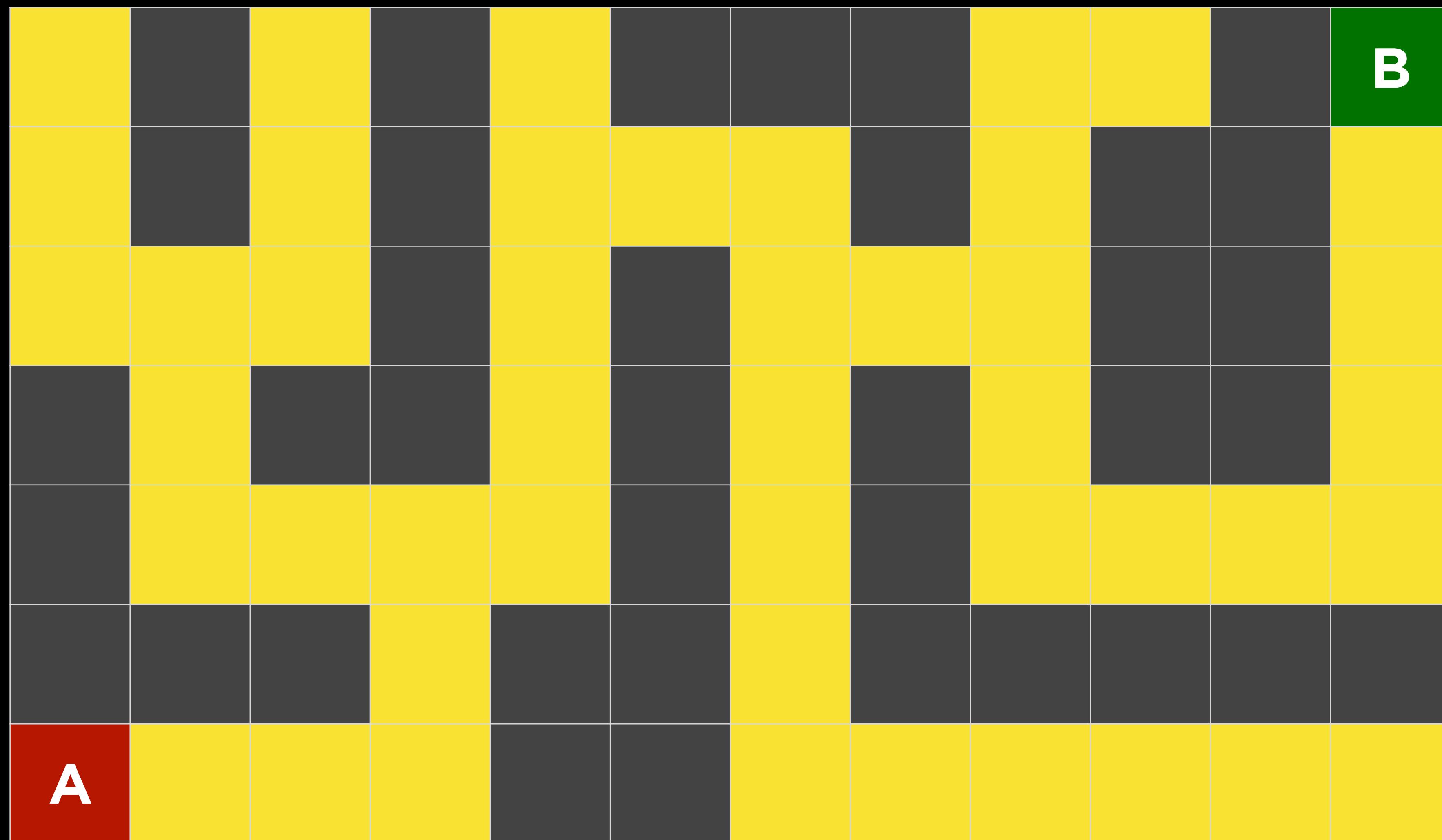
# Breadth-First Search



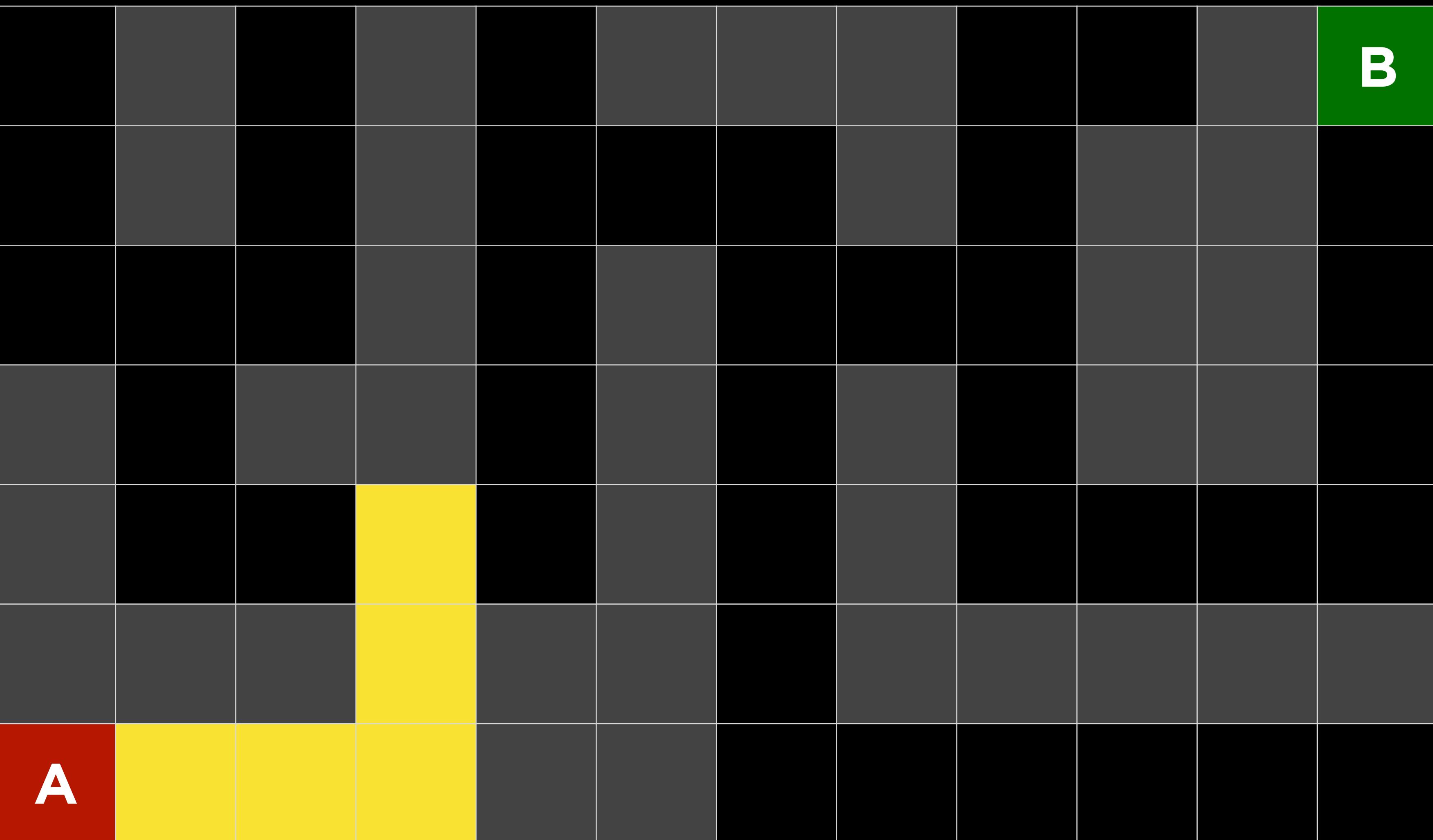
# Breadth-First Search



# Breadth-First Search



# Breadth-First Search



# uninformed search

search strategy that uses no problem-specific knowledge

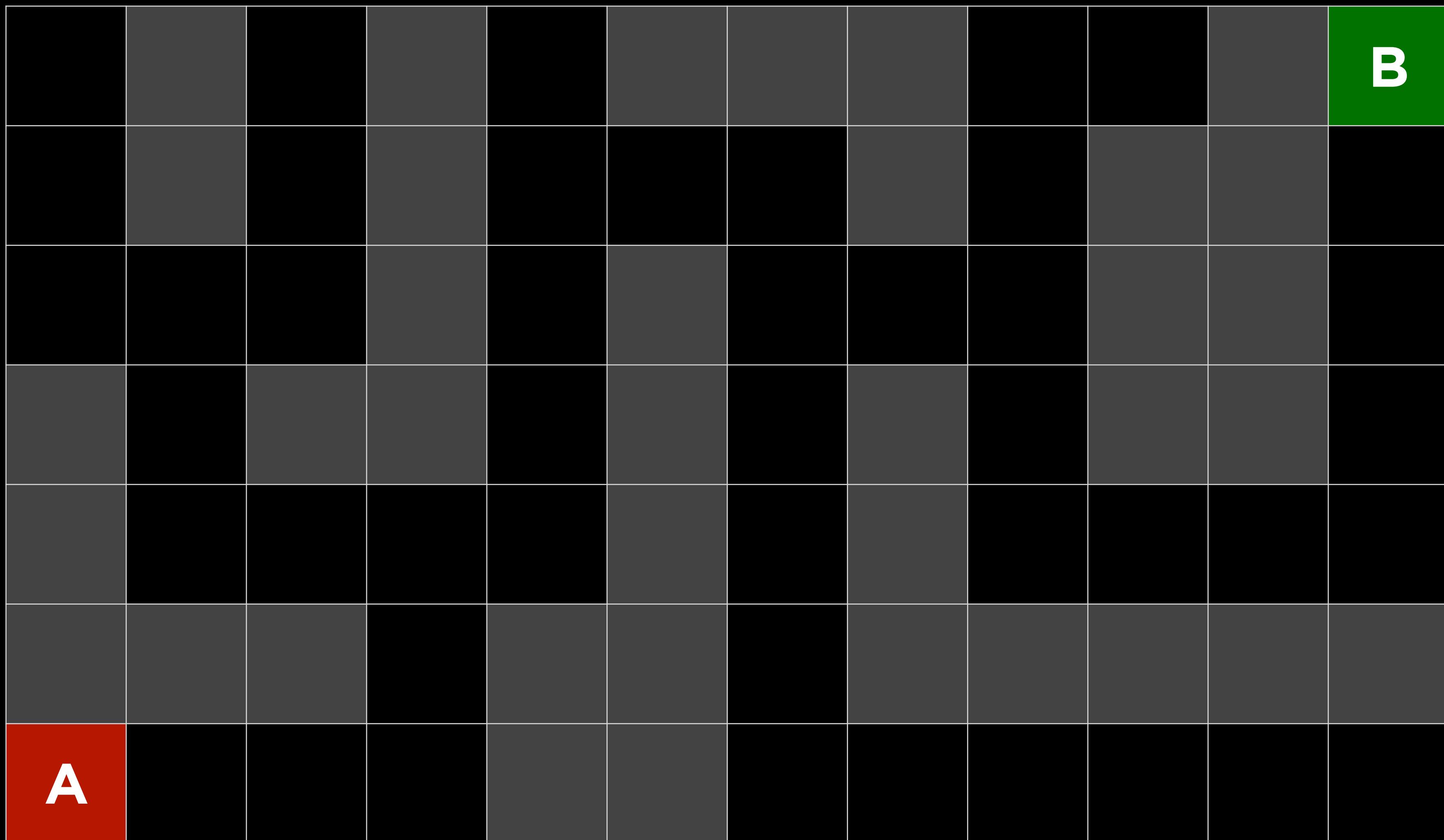
# informed search

search strategy that uses problem-specific knowledge to find solutions more efficiently

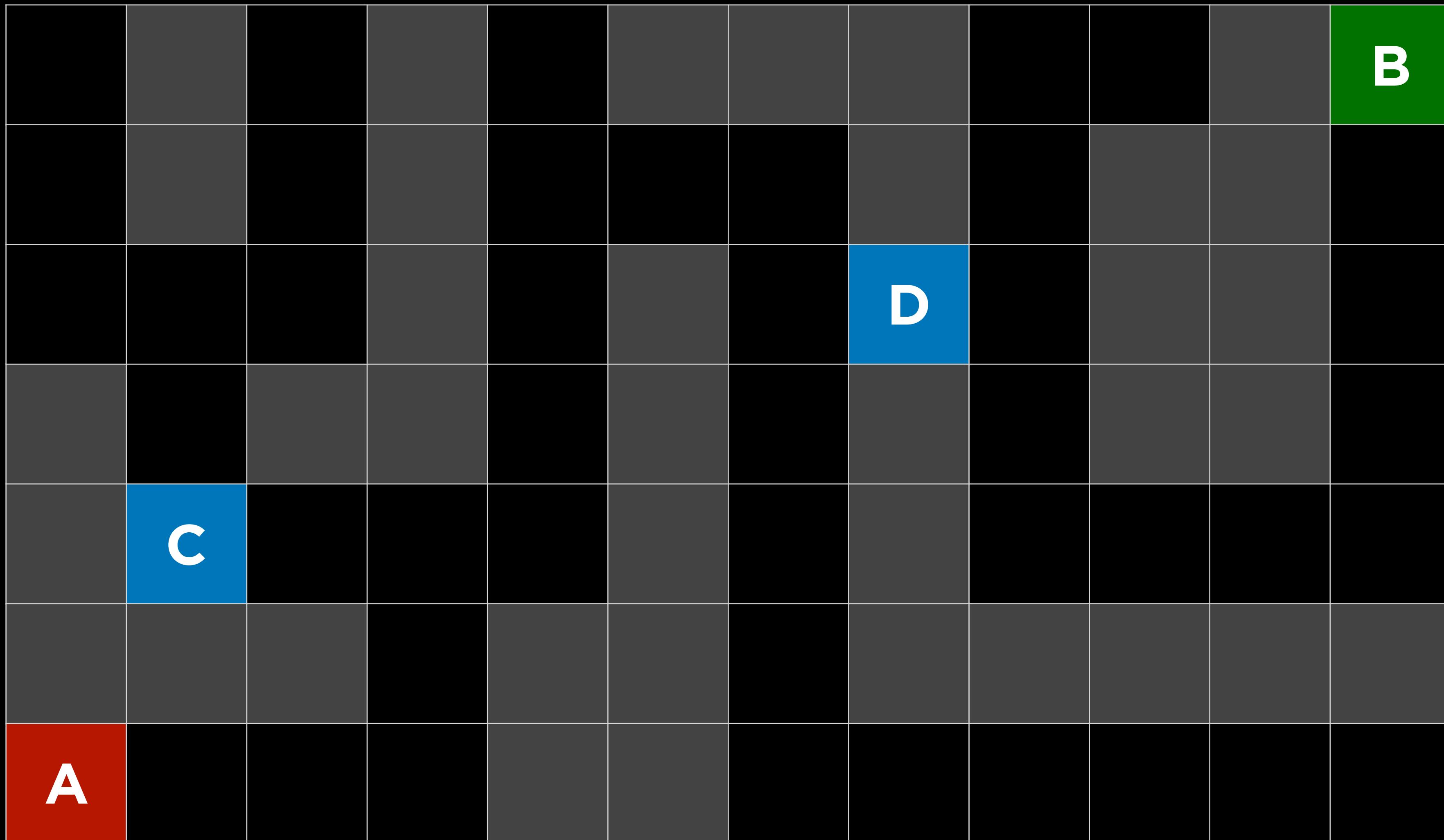
# greedy best-first search

search algorithm that expands the node  
that is closest to the goal, as estimated by a  
heuristic function  $h(n)$

# Heuristic function?

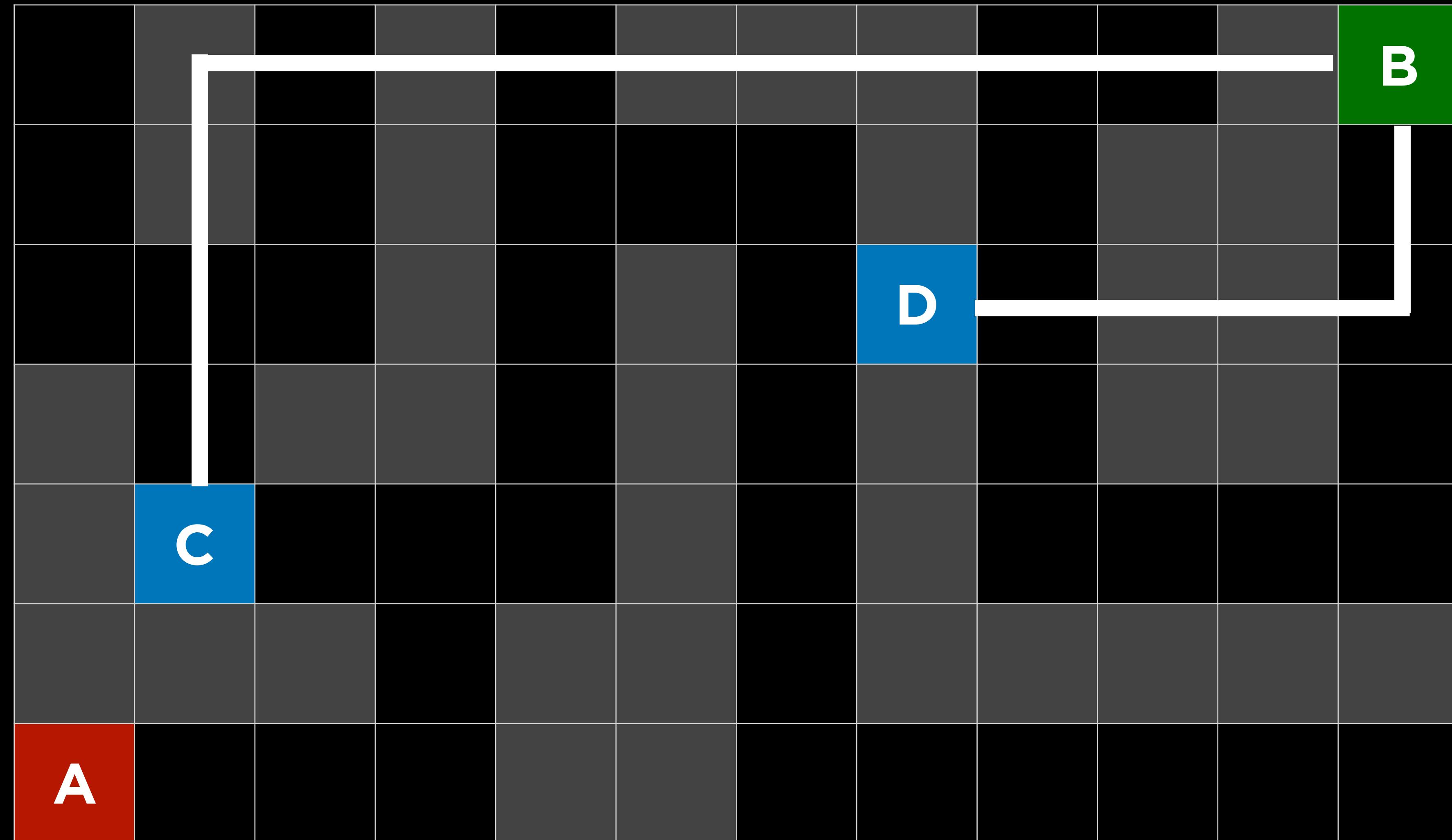


# Heuristic function?



$\text{manhattan}(\text{D}) < \text{manhattan}(\text{C})$

Heuristic function? Manhattan distance.



# Greedy Best-First Search

problem with manhattan distance shown  
ignoring walls

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
				13		10					
A	16	15	14			11	10	9	8	7	6

# Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
				13		10					
A	16	15	14			11	10	9	8	7	6

# Greedy Best-First Search

11		9		7				3	2		<b>B</b>
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
				13		10					
<b>A</b>	16	15	14			11	10	9	8	7	6

# Greedy Best-First Search

11		9		7				3	2		B	
12		10		8	7	6		4			1	
13	12	11		9		7	6	5			2	
	13			10		8		6			3	
	14	13	12	11		9		7	6	5	4	
				13		10						
A	16	15	14				11	10	9	8	7	6

# Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
				13			10				
A	16	15	14				11	10	9	8	7

# Greedy Best-First Search

11		9		7				3	2		B	
12		10		8	7	6		4			1	
13	12	11		9		7	6	5			2	
	13			10		8		6			3	
	14	13	12	11		9		7	6	5	4	
			13			10						
A	16	15	14				11	10	9	8	7	6

# Greedy Best-First Search

11		9		7				3	2		B	
12		10		8	7	6		4			1	
13	12	11		9		7	6	5			2	
	13			10		8		6			3	
	14	13	12	11		9		7	6	5	4	
				13		10						
A	16	15	14				11	10	9	8	7	6

# Greedy Best-First Search

11		9		7				3	2		B	
12		10		8	7	6		4			1	
13	12	11		9		7	6	5			2	
	13			10			8	6			3	
	14	13	12	11			9	7	6	5	4	
				13			10					
A	16	15	14				11	10	9	8	7	6

# Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
				13		10					
A	16	15	14			11	10	9	8	7	6

# Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
				13		10					
A	16	15	14			11	10	9	8	7	6

# Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
				13		10					
A	16	15	14			11	10	9	8	7	6

# Greedy Best-First Search

11		9		7					3	2		B
12		10		8	7	6		4				1
13	12	11		9		7	6	5				2
	13			10		8		6				3
	14	13	12	11		9		7	6	5	4	
				13		10						
A	16	15	14			11	10	9	8	7	6	

# Greedy Best-First Search

11		9		7					3	2		B
12		10		8	7	6		4				1
13	12	11		9		7	6	5				2
	13			10		8		6				3
	14	13	12	11		9		7	6	5	4	
				13		10						
A	16	15	14			11	10	9	8	7	6	

# Greedy Best-First Search

$$\min(6,8,13) = 6$$

11		9		7					3	2		B
12		10		8	7	6		4				1
13	12	11		9		7	6	5				2
	13			10		8		6				3
	14	13	12	11		9		7	6	5	4	
			13			10						
A	16	15	14			11	10	9	8	7	6	

# Greedy Best-First Search

11		9		7					3	2		B
12		10		8	7	6		4				1
13	12	11		9		7	6	5				2
	13			10		8		6				3
	14	13	12	11		9		7	6	5	4	
				13		10						
A	16	15	14			11	10	9	8	7	6	

# Greedy Best-First Search

11		9		7					3	2		B
12		10		8	7	6		4				1
13	12	11		9		7	6	5				2
	13			10		8		6				3
	14	13	12	11		9		7	6	5	4	
				13		10						
A	16	15	14			11	10	9	8	7	6	

# Greedy Best-First Search

11		9		7					3	2		B
12		10		8	7	6		4				1
13	12	11		9		7	6	5				2
	13			10		8		6				3
	14	13	12	11		9		7	6	5	4	
				13		10						
A	16	15	14			11	10	9	8	7	6	

# Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
				13		10					
A	16	15	14			11	10	9	8	7	6

# Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
				13		10					
A	16	15	14			11	10	9	8	7	6

# Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
				13		10					
A	16	15	14			11	10	9	8	7	6

# Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
				13		10					
A	16	15	14			11	10	9	8	7	6

# Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
				13		10					
A	16	15	14			11	10	9	8	7	6

# Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
				13		10					
A	16	15	14			11	10	9	8	7	6

# Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
				13		10					
A	16	15	14			11	10	9	8	7	6

# Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
				13		10					
A	16	15	14			11	10	9	8	7	6

# Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
				13		10					
A	16	15	14			11	10	9	8	7	6

# Greedy Best-First Search

11		9		7				3	2		B
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
				13		10					
A	16	15	14			11	10	9	8	7	6

Will Greedy Best-First Search find the optimal solution?

## Greedy Best-First Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	16	15	14		12	11	10	9	8	7	6

# Greedy Best-First Search

6 steps needed to reach 13 is much less than steps needed to reach 12

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		11							5	3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	16	15	14		12	11	10	9	8	7	6

# Greedy Best-First Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
				13		11					5
A	16	15	14		12	11	10	9	8	7	6

# A\* search

search algorithm that expands node with  
lowest value of  $g(n) + h(n)$

$g(n)$  = cost to reach node

$h(n)$  = estimated cost to goal

# A\* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	16	15	14		12	11	10	9	8	7	6

# A\* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	1+16	15	14		12	11	10	9	8	7	6

# A\* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	1+16	2+15	14		12	11	10	9	8	7	6

# A\* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		11							5	3
	14	13	12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		11							5	3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		10	9	8	7	6	5	4		2
	13		6+11	6 + 11 = 17					5		3
$6 + 13 = 19$	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	9	8	7	6	5	4		2
	13		6+11							5	3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	8	7	6	5	4		2
	13		6+11							5	3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	9+8	7	6	5	4		2
	13		6+11							5	3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	9+8	10+7	6	5	4		2
	13		6+11							5	3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	9+8	10+7	11+6	5	4		2
	13		6+11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	4		2
	13		6+11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

$$14 + 5 = 19$$

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	13		6+11						5		3
6 + 13 = 19	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

$$15 + 6 = 21$$

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	13		6+11						14+5		3
$6 + 13 = 19$	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	13		6+11						14+5		3
	14	6+13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

alternate between paths in favor of smaller sums

increasing Manhattan distance will make non-optimal path's sum too expensive

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	13		6+11						14+5		3
7 + 14 = 21	14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	12			7+10	8+9	9+8	10+7	11+6	12+5	13+4	2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	10	9	8	7	6	5	4	3	2	1	B
	11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	10	9	8	7	6	5	4	3	2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	11+10	9	8	7	6	5	4	3	2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	11+10	12+9	8	7	6	5	4	3	2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	11+10	12+9	13+8	7	6	5	4	3	2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	11+10	12+9	13+8	14+7	6	5	4	3	2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	11+10	12+9	13+8	14+7	15+6	5	4	3	2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	11+10	12+9	13+8	14+7	15+6	16+5	4	3	2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	11+10	12+9	13+8	14+7	15+6	16+5	17+4	3	2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	11+10	12+9	13+8	14+7	15+6	16+5	17+4	18+3	2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

	11+10	12+9	13+8	14+7	15+6	16+5	17+4	18+3	19+2	1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

# A\* Search

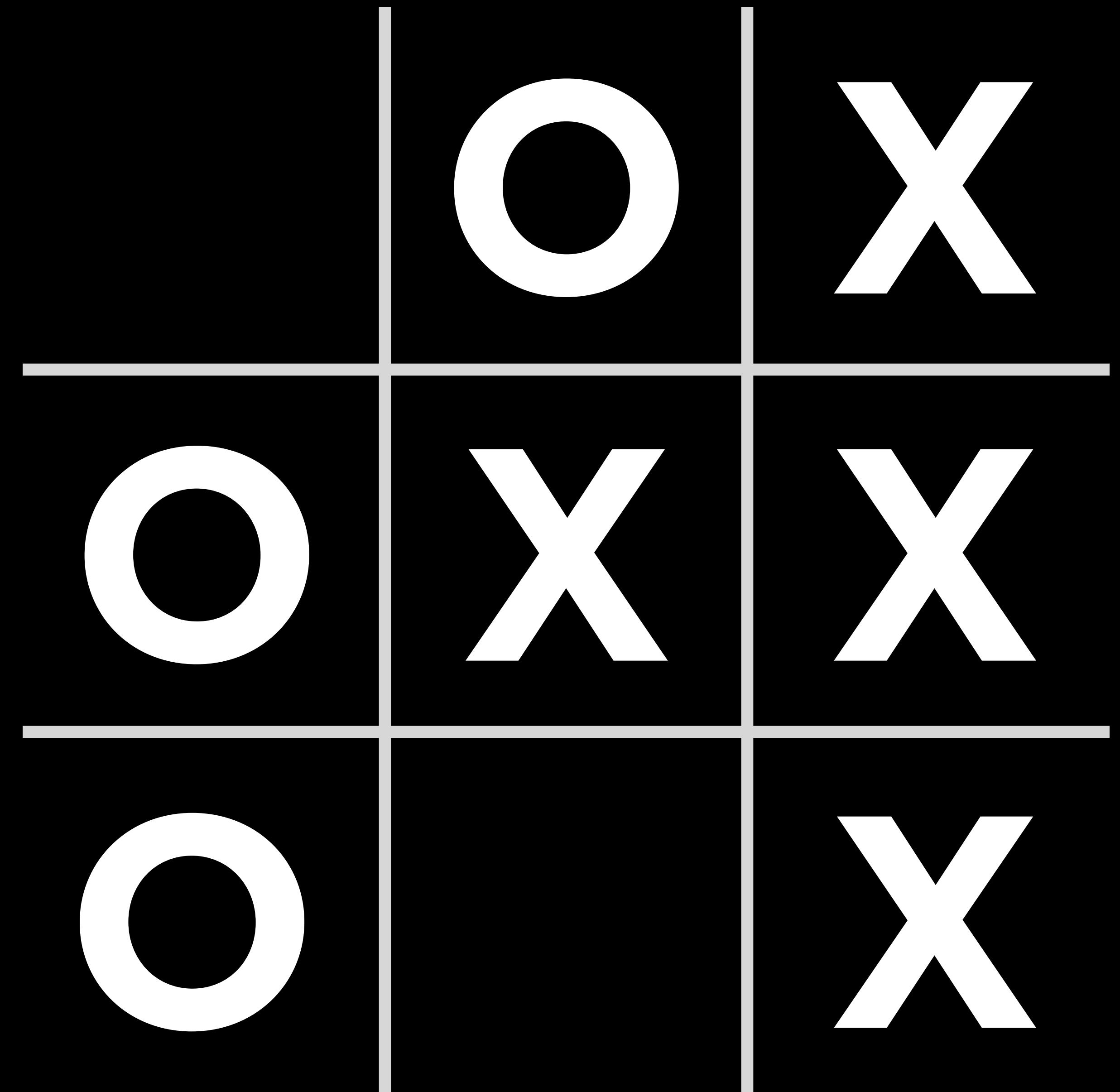
	11+10	12+9	13+8	14+7	15+6	16+5	17+4	18+3	19+2	20+1	B
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

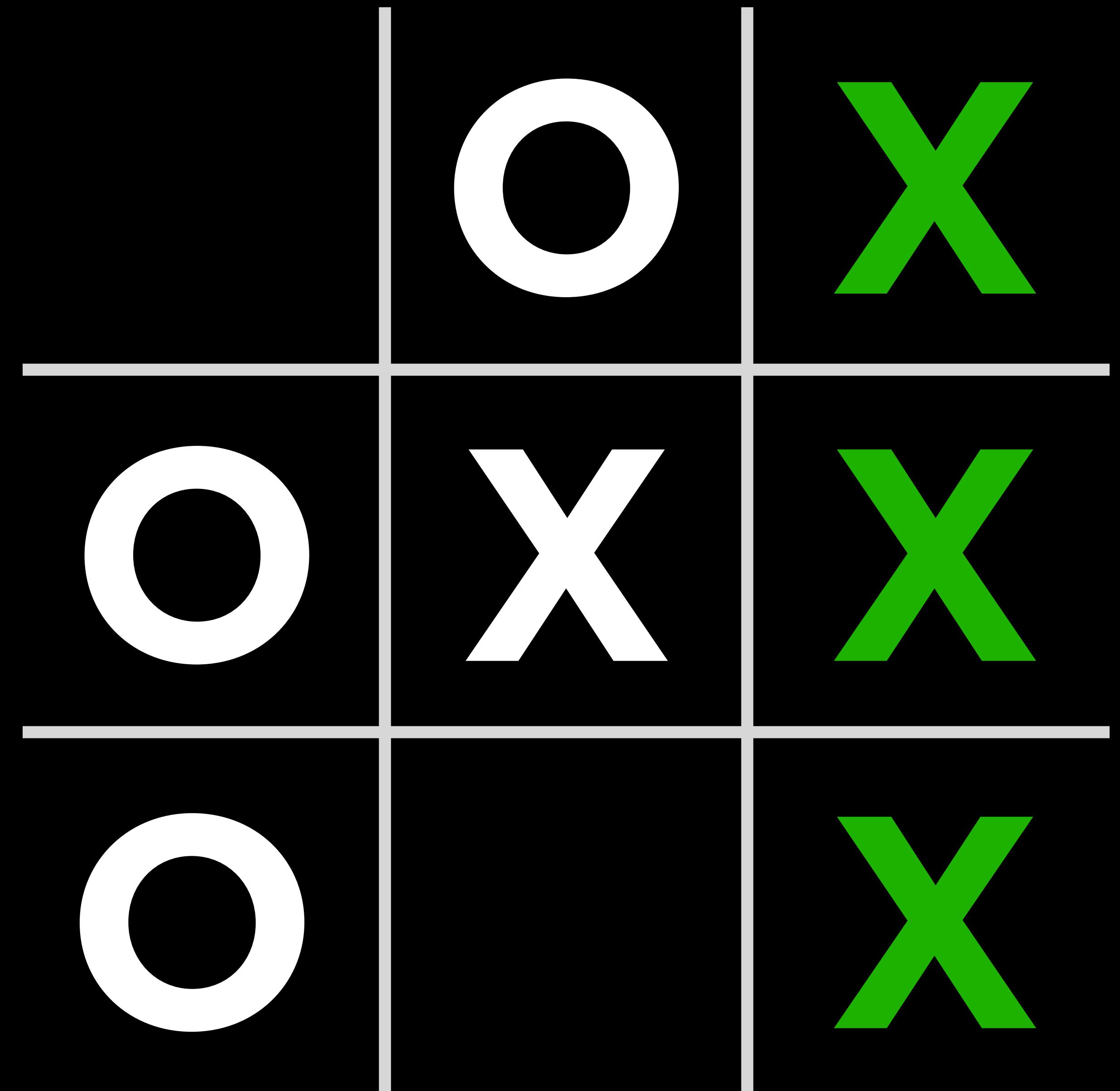
# A\* search

optimal if

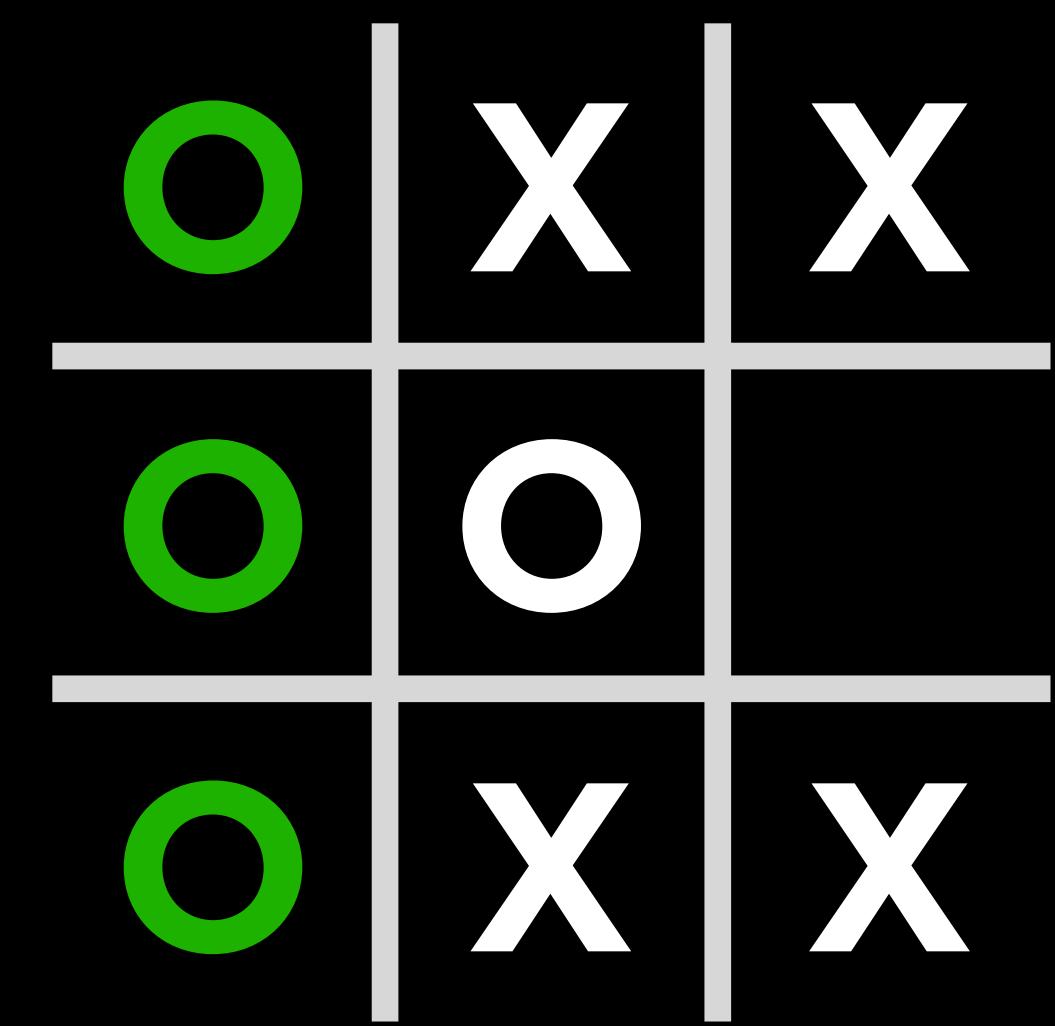
- $h(n)$  is admissible (never overestimates the true cost), and underestimates are acceptable
- $h(n)$  is consistent (for every node  $n$  and successor  $n'$  with step cost  $c$ ,  $h(n) \leq h(n') + c$ )

# Adversarial Search

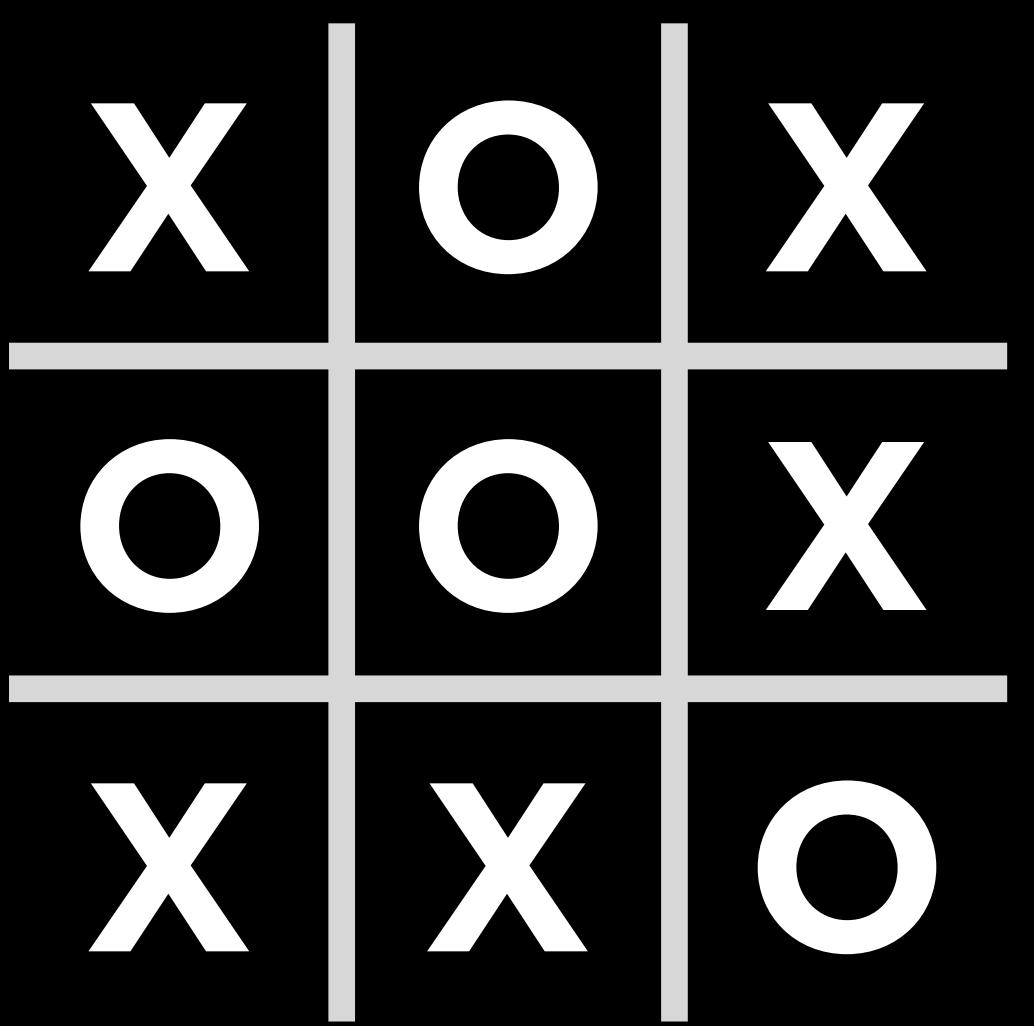




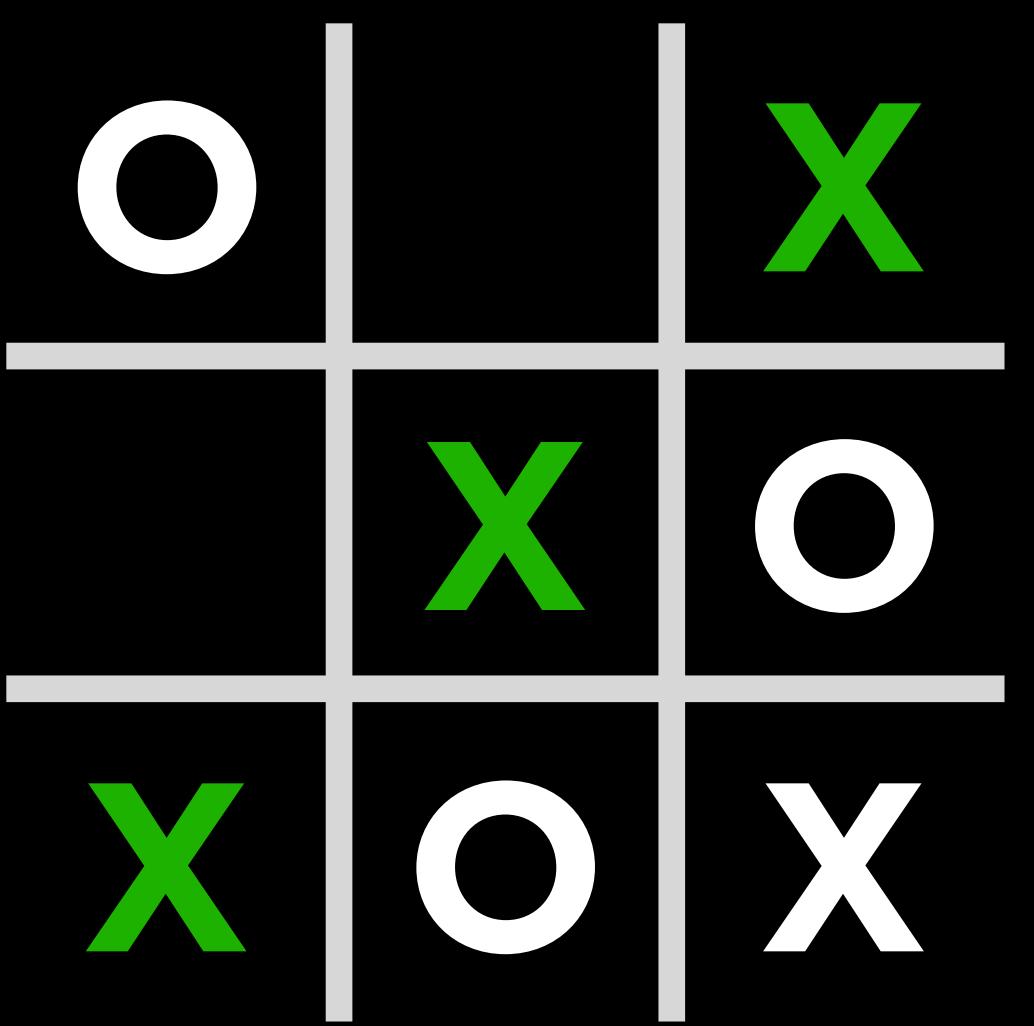
# Minimax



-1



0



1

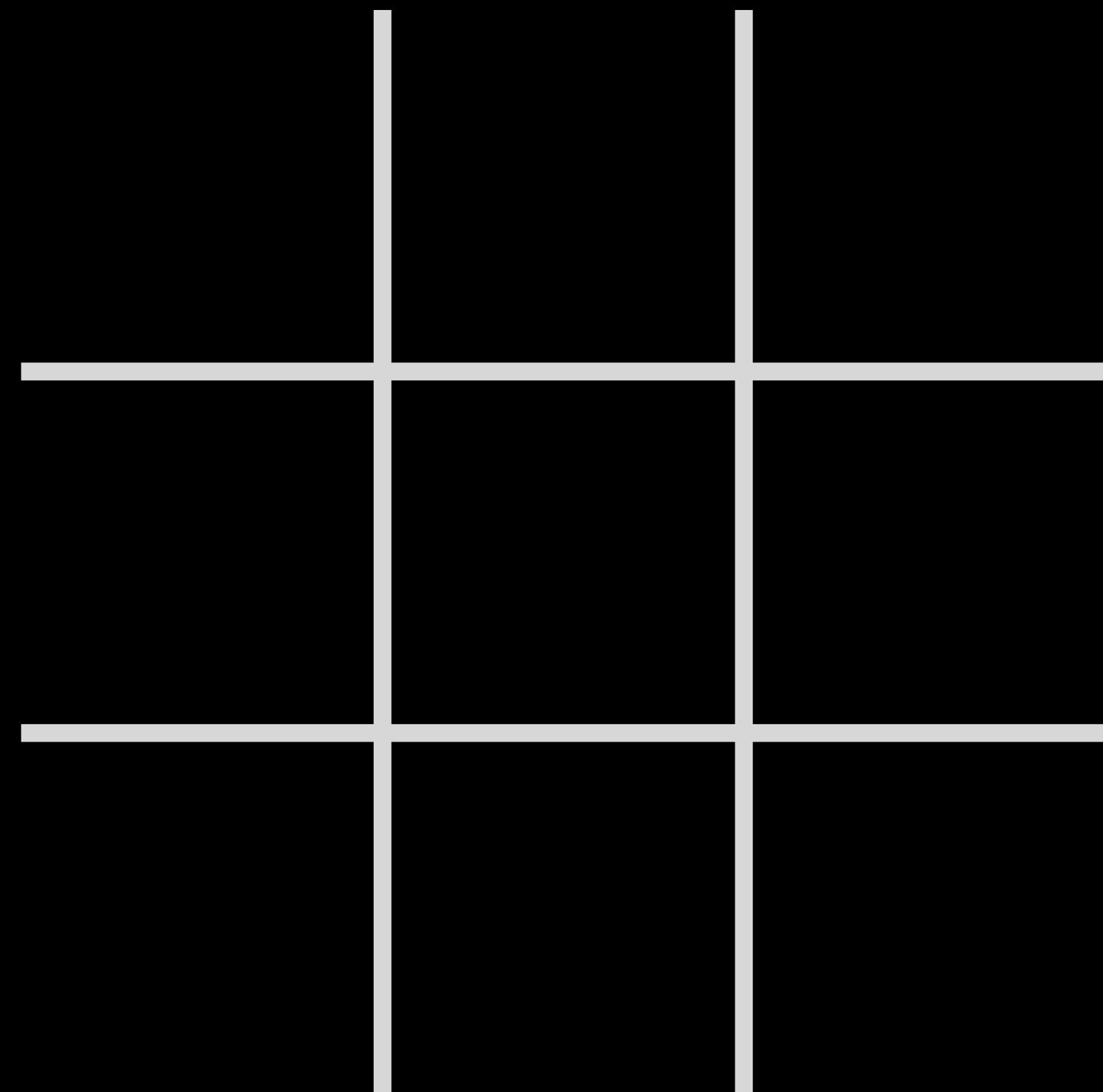
# Minimax

- MAX (X) aims to maximize score.
- MIN (O) aims to minimize score.

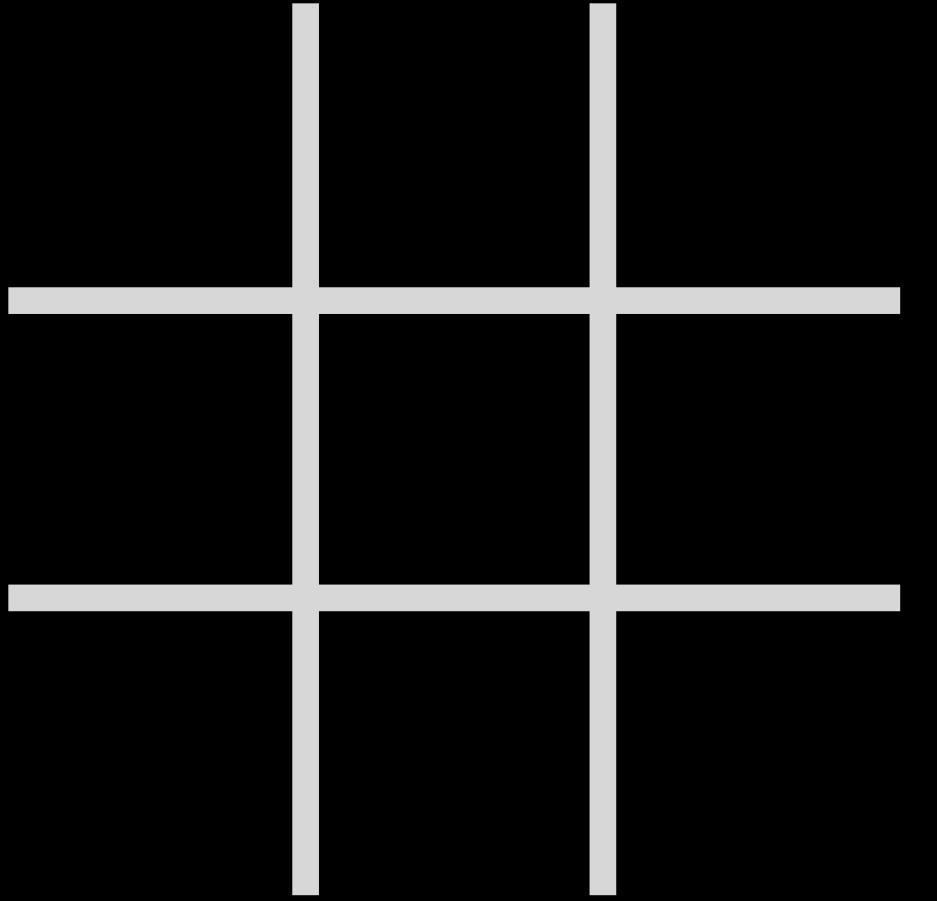
# Game

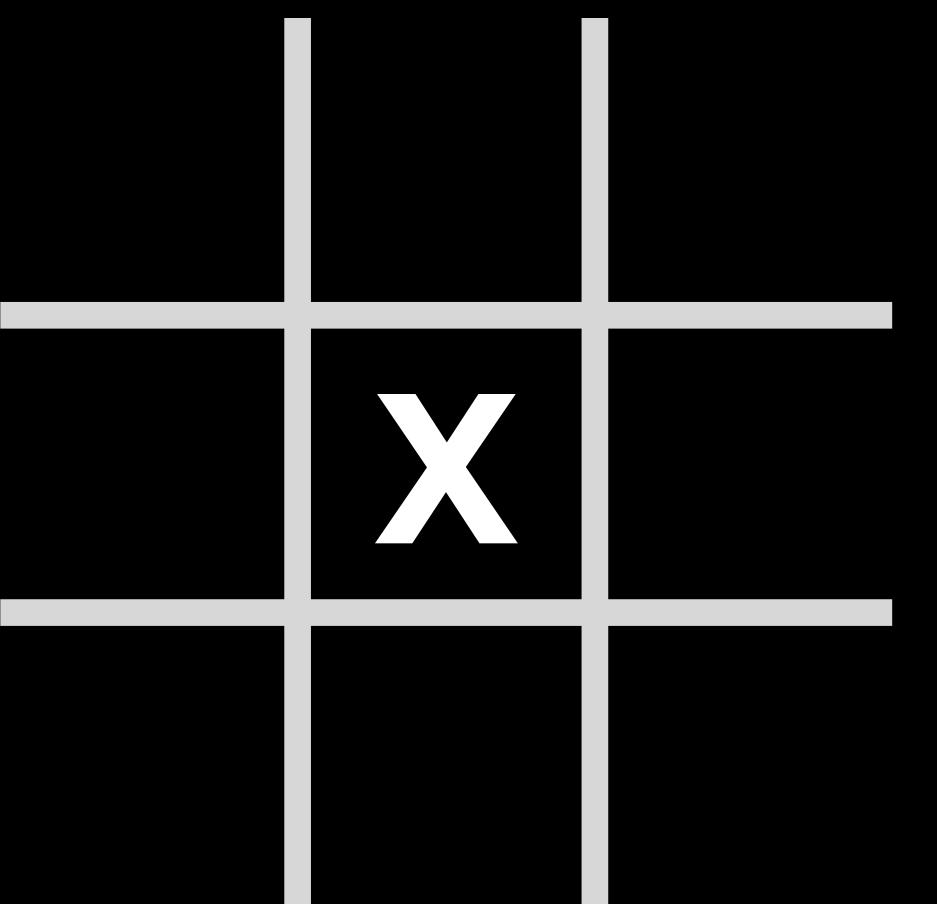
- $S_0$  : initial state
- $\text{PLAYER}(s)$  : returns which player to move in state  $s$
- $\text{ACTIONS}(s)$  : returns legal moves in state  $s$
- $\text{RESULT}(s, a)$  : returns state after action  $a$  taken in state  $s$
- $\text{TERMINAL}(s)$  : checks if state  $s$  is a terminal state
- $\text{UTILITY}(s)$  : final numerical value for terminal state  $s$

# Initial State



PLAYER( $s$ )

PLAYER(  ) = X

PLAYER(  ) = O

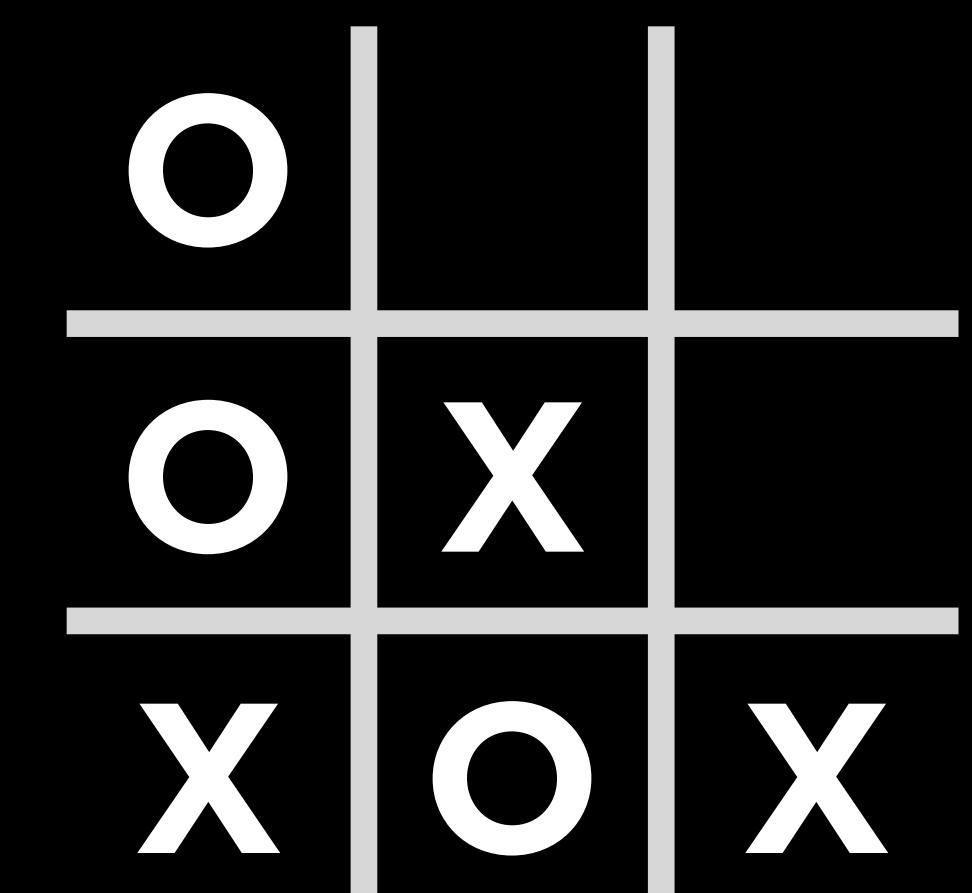
# ACTIONS( $s$ )

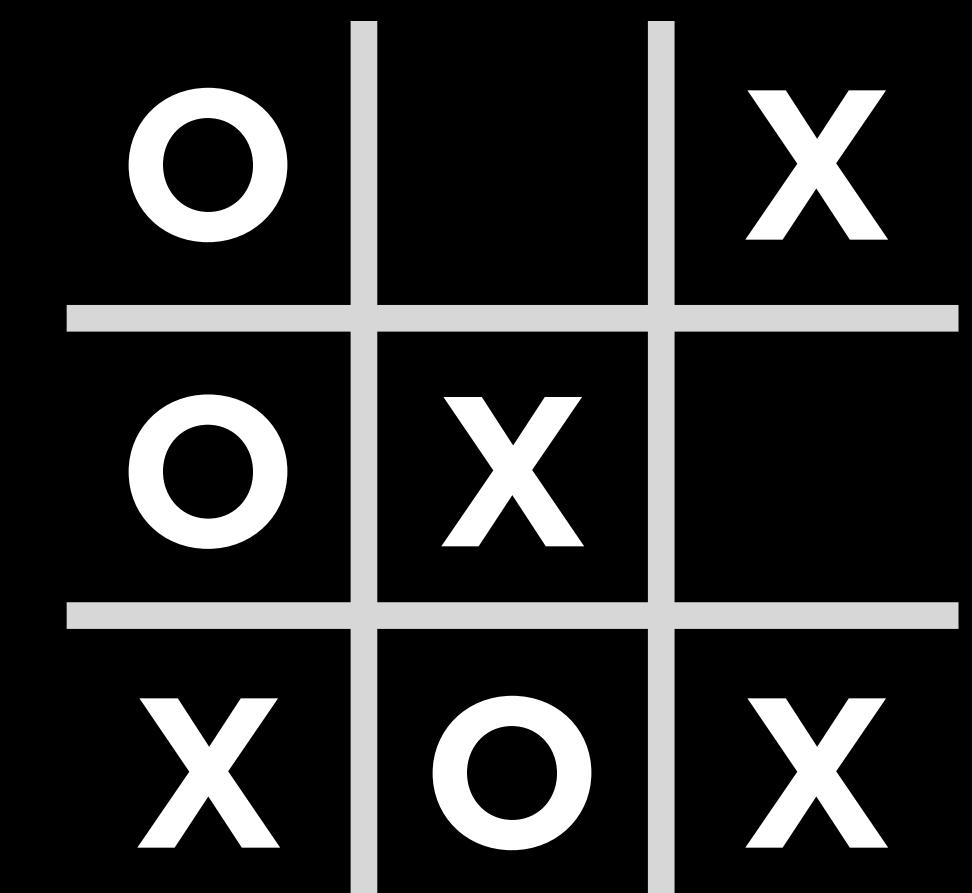
$$\text{ACTIONS}\left(\begin{array}{|c|c|c|} \hline & x & o \\ \hline o & x & x \\ \hline x & & o \\ \hline \end{array}\right) = \left\{ \begin{array}{|c|c|c|} \hline & o & \\ \hline & & \\ \hline & & \\ \hline \end{array}, \begin{array}{|c|c|c|} \hline & & \\ \hline & & \\ \hline & & o \\ \hline \end{array} \right\}$$

RESULT( $s$ ,  $a$ )

$$\text{RESULT}\left(\begin{array}{|c|c|c|} \hline & \text{x} & \text{o} \\ \hline \text{o} & \text{x} & \text{x} \\ \hline \text{x} & & \text{o} \\ \hline \end{array}, \begin{array}{|c|c|c|} \hline & \text{o} & \\ \hline & \# & \# \\ \hline \end{array}\right) = \begin{array}{|c|c|c|} \hline \text{o} & \text{x} & \text{o} \\ \hline \text{o} & \text{x} & \text{x} \\ \hline \text{x} & & \text{o} \\ \hline \end{array}$$

**TERMINAL( $s$ )**

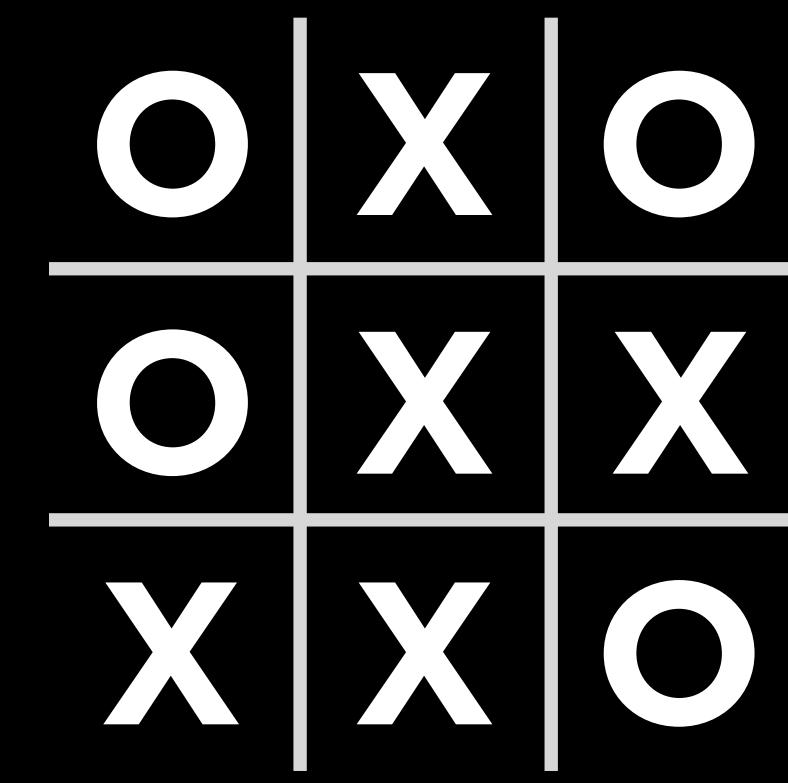
**TERMINAL(**  **) = false**

**TERMINAL(**  **) = true**

UTILITY( $s$ )

$$\text{UTILITY}( \begin{array}{|c|c|c|} \hline \text{o} & & \text{x} \\ \hline \text{o} & \text{x} & \\ \hline \text{x} & \text{o} & \text{x} \\ \hline \end{array} ) = 1$$

$$\text{UTILITY}( \begin{array}{|c|c|c|} \hline \text{o} & \text{x} & \text{x} \\ \hline \text{x} & \text{o} & \\ \hline \text{o} & \text{x} & \text{o} \\ \hline \end{array} ) = -1$$



VALUE: 1

PLAYER( $s$ ) = O

MIN-VALUE:

0

X	O
O	X
X	O

MAX-VALUE:

1

O	X	O
O	X	X
X		O

MAX-VALUE:

0

X	O
O	X
X	O

VALUE:

1

O	X	O
O	X	X
X	X	O

VALUE:

0

X	X	O
O	X	X
X	O	O

PLAYER( $s$ ) = O

MIN-VALUE:

0

X	O
O	X
X	O

MAX-VALUE:

1

O	X	O
O	X	X
X		O

MAX-VALUE:

0

X	O
O	X
X	O

VALUE:

1

O	X	O
O	X	X
X	X	O

VALUE:

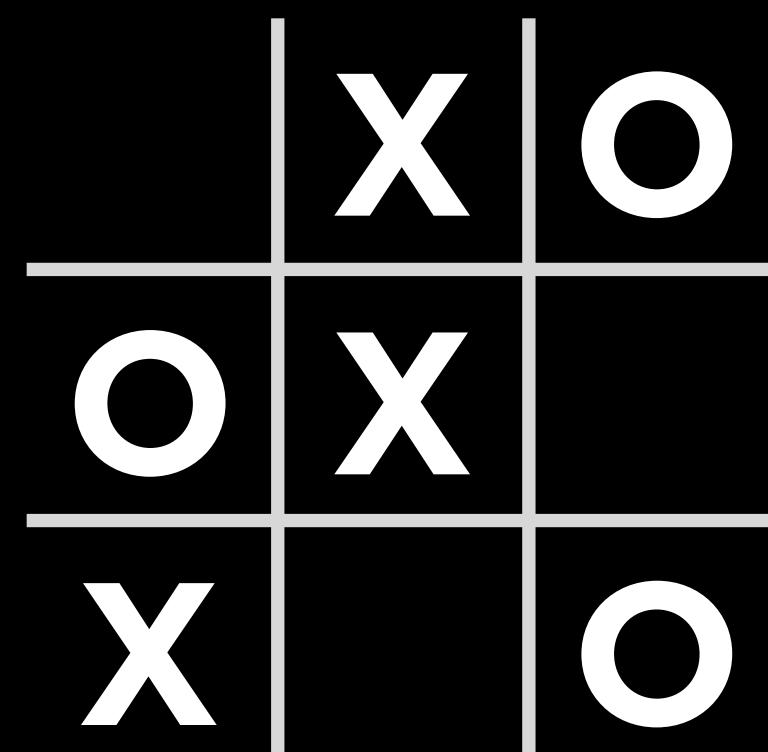
0

X	X	O
O	X	X
X	O	O

PLAYER( $s$ ) = X

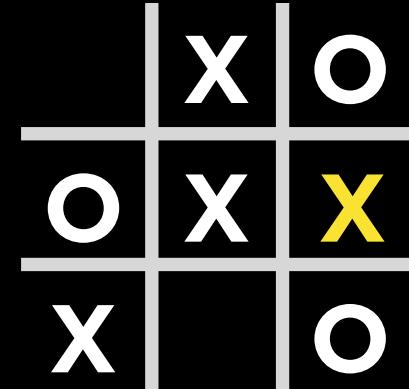
# MAX-VALUE:

1

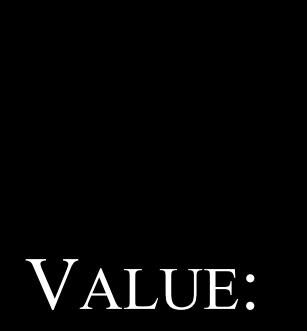
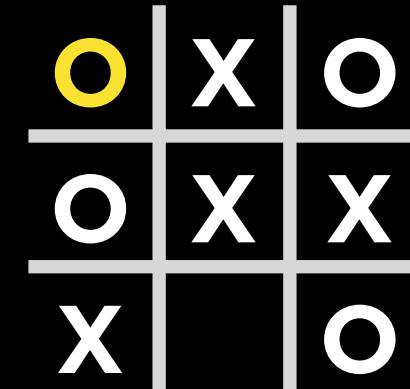


## MIN-VALUE:

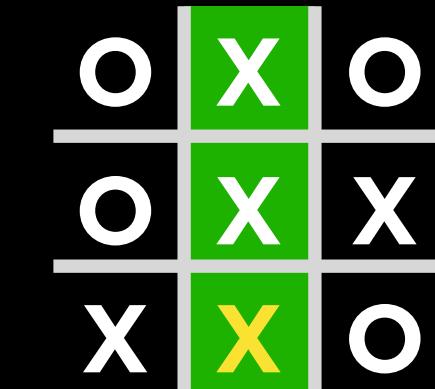
8



1

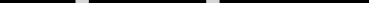


1

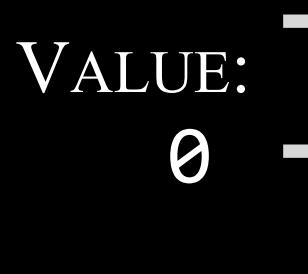
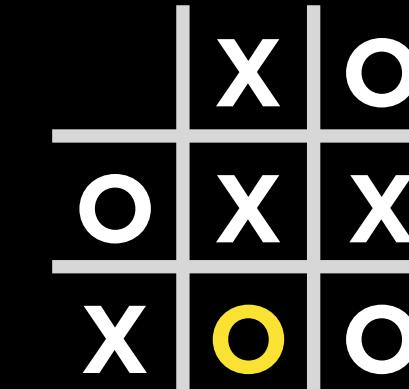


MIN-VALUE:

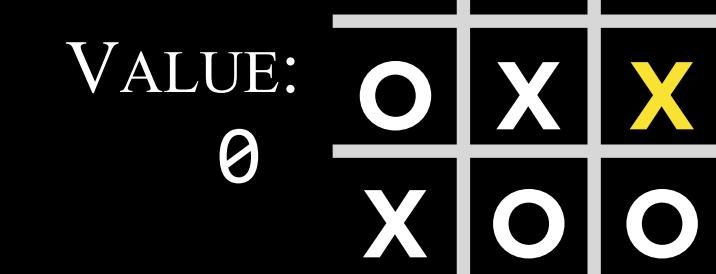
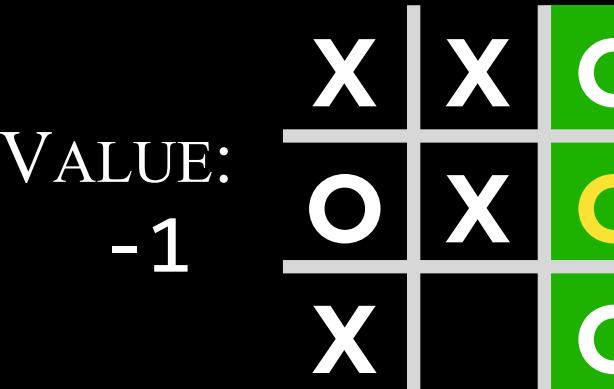
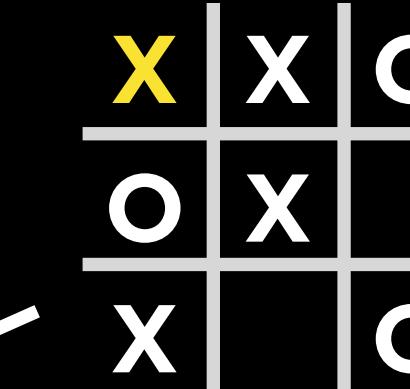
	X	O	
θ	O	X	X
X		O	

MAX-VALUE:  MAX-VALUE

8

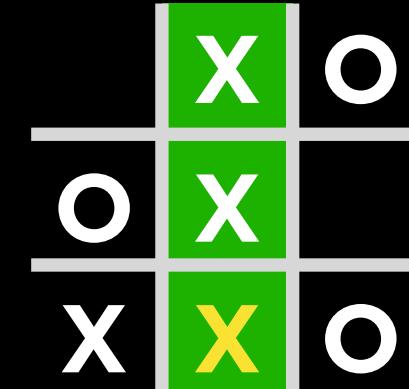


MIN-VALUE

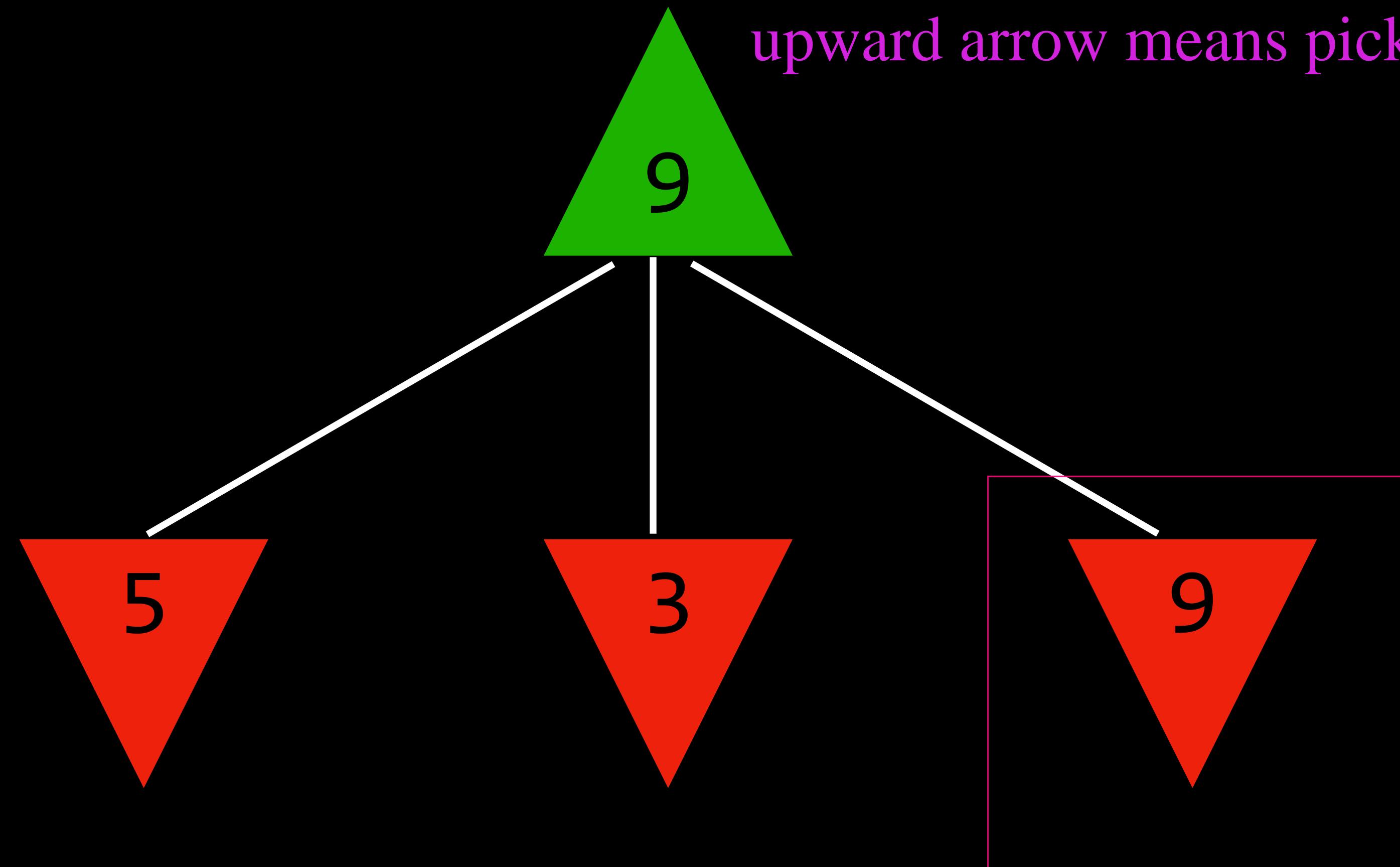


## VALUE:

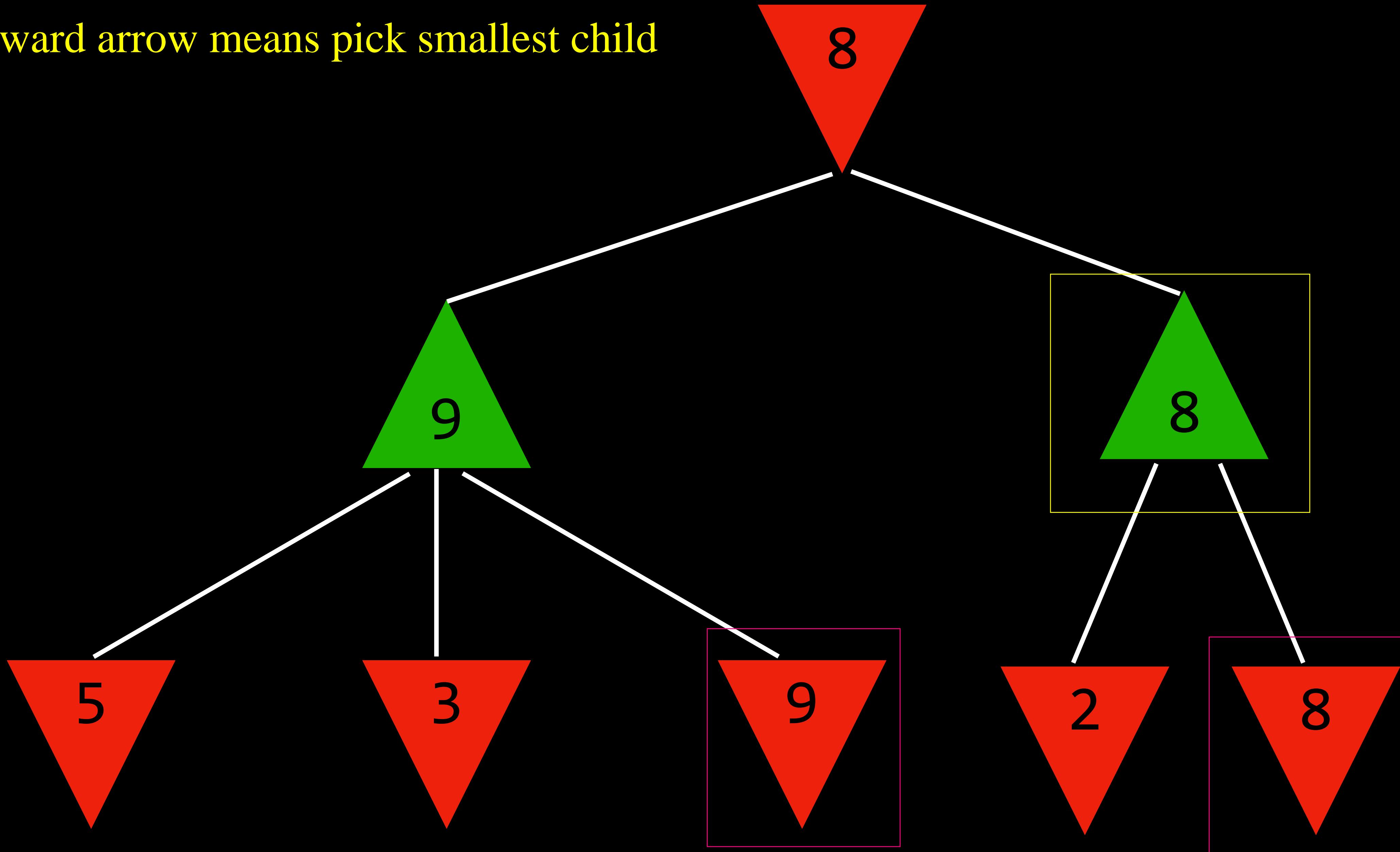
1



upward arrow means pick largest child



downward arrow means pick smallest child



# Minimax

- Given a state  $s$ :
  - MAX picks action  $a$  in  $\text{ACTIONS}(s)$  that produces highest value of  $\text{MIN-VALUE}(\text{RESULT}(s, a))$
  - MIN picks action  $a$  in  $\text{ACTIONS}(s)$  that produces smallest value of  $\text{MAX-VALUE}(\text{RESULT}(s, a))$   
assuming opponent will choose action to maximize  $\text{RESULT}$

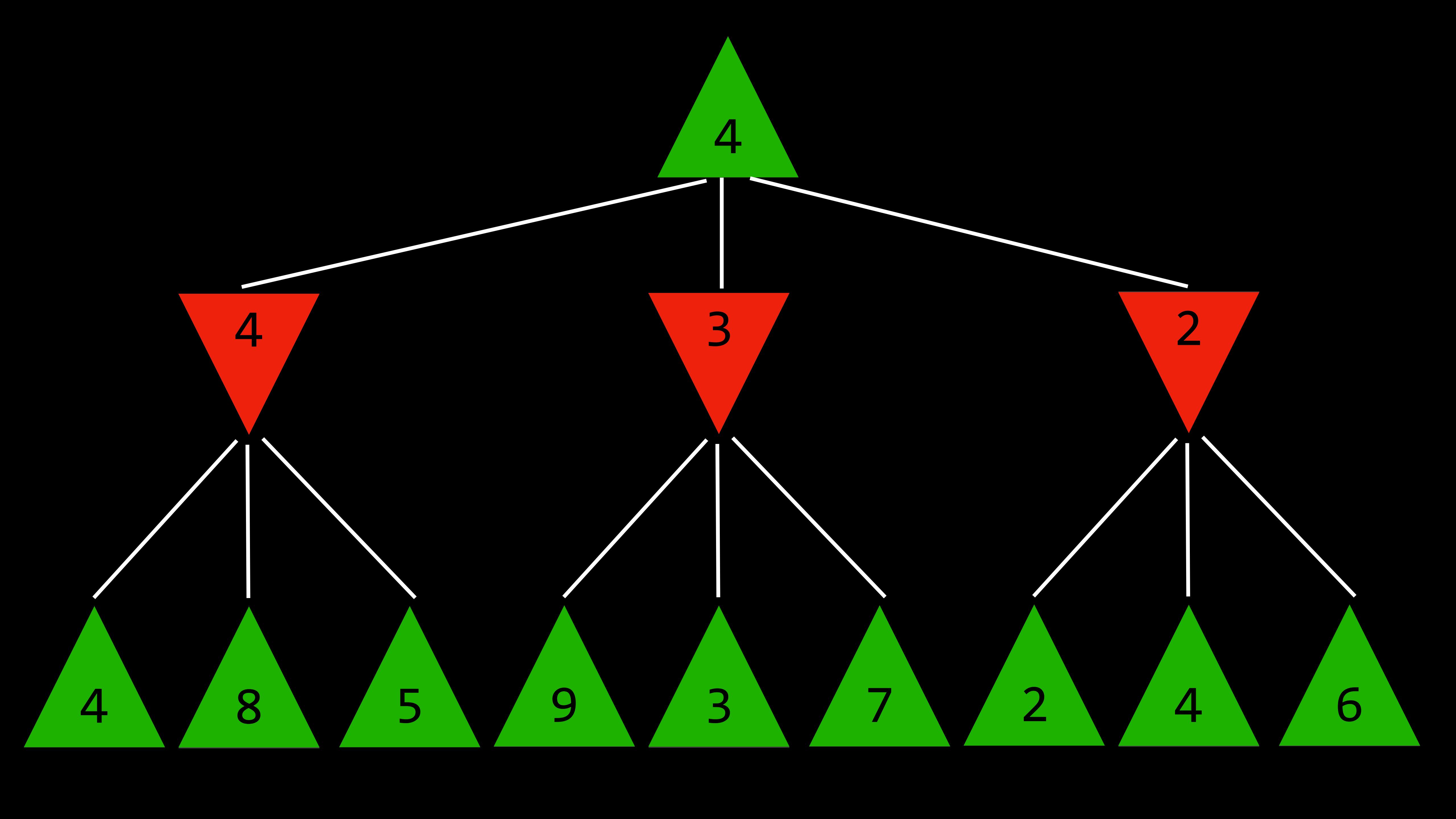
# Minimax

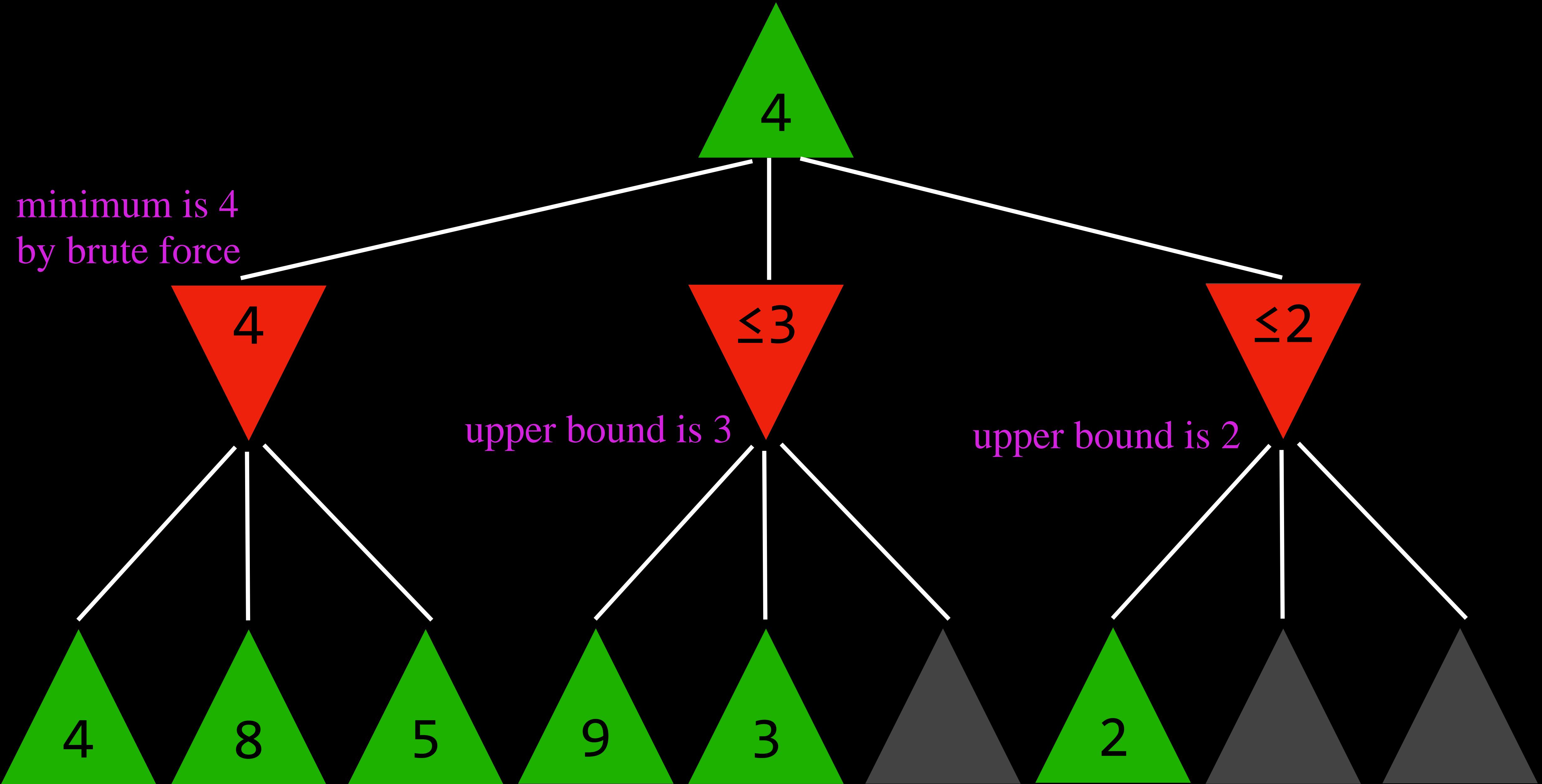
```
function MAX-VALUE(state):  
    if TERMINAL(state):  
        return UTILITY(state)  
  
    v = -∞ initialize Value as low as possible  
    for action in ACTIONS(state):  
        v = MAX(v, MIN-VALUE(RESULT(state, action)))  
    return v
```

# Minimax

```
function MIN-VALUE(state):  
    if TERMINAL(state):  
        return UTILITY(state)  
  
     $v = \infty$   
  
    for action in ACTIONS(state):  
         $v = \text{MIN}(v, \text{MAX-VALUE}(\text{RESULT}(\textit{state}, \textit{action}))))$   
  
    return  $v$ 
```

# Optimizations





# Alpha-Beta Pruning

255,168

total possible Tic-Tac-Toe games

288,000,000,000

total possible chess games  
after four moves each

$10^{29000}$

total possible chess games  
(lower bound)

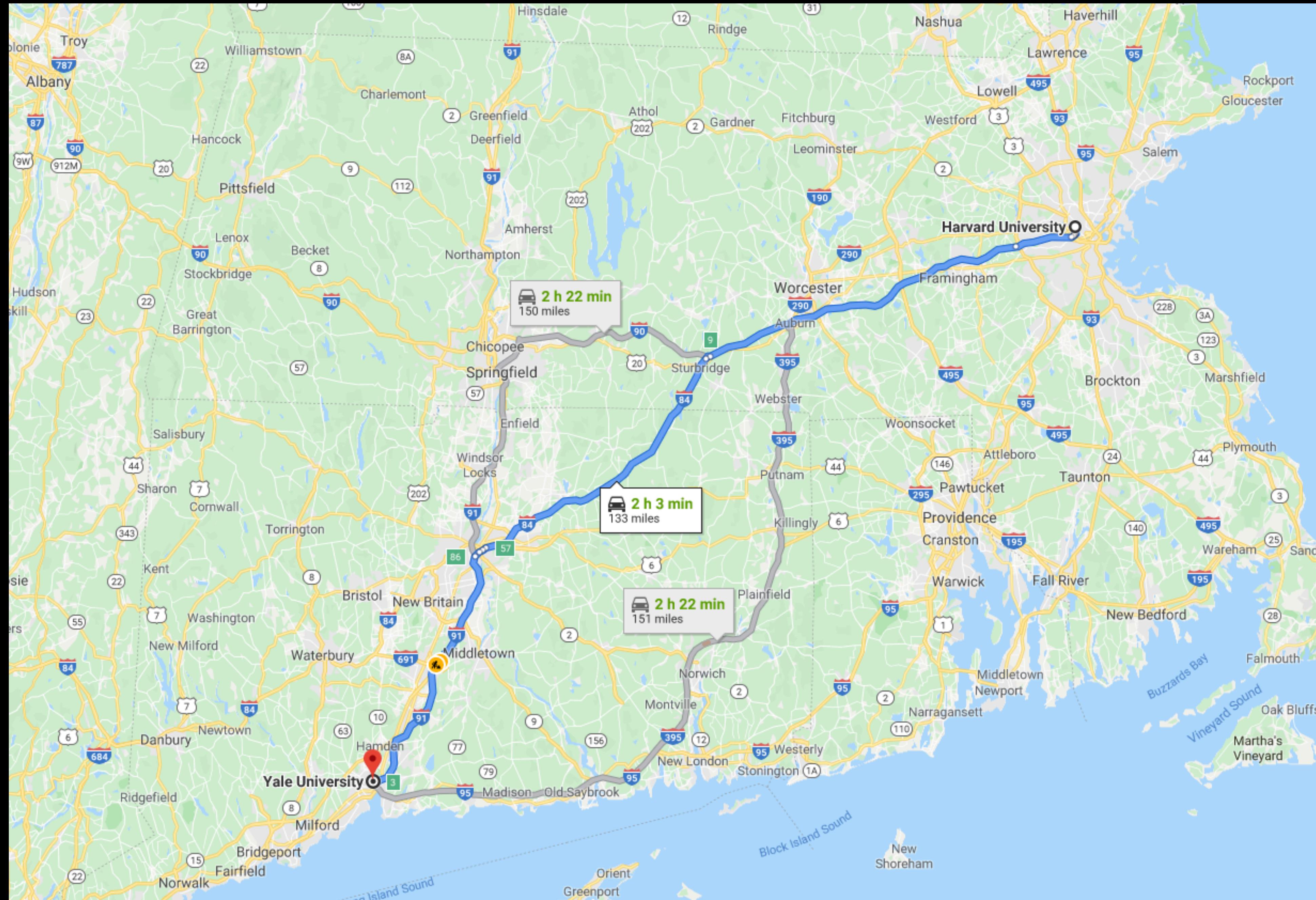
# Depth-Limited Minimax

we limit the depth of minimax and choose best outcome for that depth  
we've considered best outcome if game over,  
but if game is not over, we'll need an evaluation function

# evaluation function

function that estimates the expected utility  
of the game from a given state

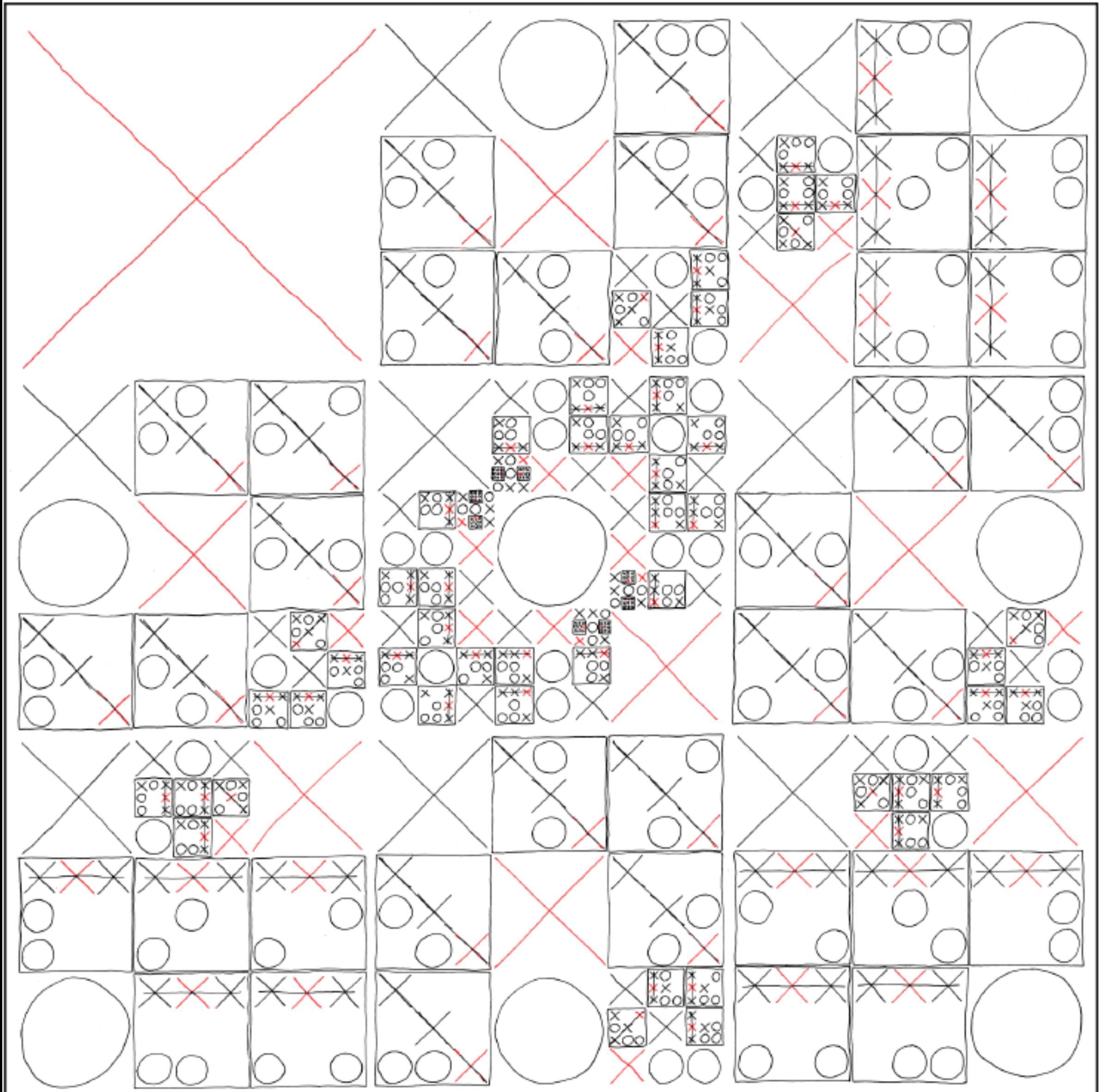
we need a function to estimate probability of winning [-1,1] for any state  
where 1 is max player, -1 is min player



## COMPLETE MAP OF OPTIMAL TIC-TAC-TOE MOVES

YOUR MOVE IS GIVEN BY THE POSITION OF THE LARGEST RED SYMBOL  
ON THE GRID. WHEN YOUR OPPONENT PICKS A MOVE, ZOOM IN ON  
THE REGION OF THE GRID WHERE THEY WENT. REPEAT.

MAP FOR X:



# Search

Introduction to  
**Artificial Intelligence**  
with Python