



# 数学 A

$$(1) \cos n\theta + i \sin n\theta = e^{in\theta} = (e^{i\theta})^n = (\cos \theta + i \sin \theta)^n$$

$$(2) \frac{1}{\sqrt{1+x}} = 1 - \frac{1}{2}x + \frac{3}{8}x^2 - \frac{15}{48}x^3$$

$$\begin{aligned} (3) (i) \int_0^\pi e^x \sin x \, dx &= \left[ e^x \sin x \right]_0^\pi - \int_0^\pi e^x \cos x \, dx \\ &= - \left[ e^x \cos x \right]_0^\pi - \int_0^\pi e^x \sin x \, dx \\ &= -(-e^\pi - 1) - \int_0^\pi e^x \sin x \, dx \end{aligned}$$

$$\therefore \int_0^\pi e^x \sin x \, dx = \frac{e^\pi + 1}{2}$$

$$\begin{array}{ll} (ii) \quad x = \cos \theta & x \Big|_0 \rightarrow 1 \\ dx = -\sin \theta \, d\theta & 0 \Big|_{\frac{\pi}{2}} \rightarrow 0 \end{array}$$

$$\begin{aligned} \int_0^1 x \sqrt{1-x^2} \, dx &= \int_{\frac{\pi}{2}}^0 -\cos \theta \sin^2 \theta \, d\theta \\ &= \int_0^{\frac{\pi}{2}} \sin^2 \theta \cos \theta \, d\theta \\ \cos(\alpha+\beta) &= \cos \alpha \cos \beta - \sin \alpha \sin \beta = \int_0^{\frac{\pi}{2}} \frac{1-\cos 2\theta}{2} \cos \theta \, d\theta \end{aligned}$$

④  $\cos 3\theta$

$$\frac{1}{2} \cos \theta - \frac{1}{2} \cos 2\theta \cos \theta$$

$$= \frac{1}{2} \cos \theta - \frac{1}{4} (\cos 3\theta + \cos \theta)$$

$$= \frac{1}{4} \cos \theta - \frac{1}{4} \cos 3\theta$$

$$\begin{aligned}
 &= \int_0^{\frac{\pi}{2}} \frac{1}{4} \cos \theta - \frac{1}{4} \cos 3\theta \quad d\theta \\
 &= \left[ \frac{1}{4} \sin \theta \right]_0^{\frac{\pi}{2}} - \left[ \frac{1}{12} \sin 3\theta \right]_0^{\frac{\pi}{2}} \\
 &= \frac{1}{4} + \frac{1}{12} = \frac{4}{12} = \frac{1}{3},
 \end{aligned}$$

(4)  $A = \begin{pmatrix} -1 & 3 \\ 3 & -1 \end{pmatrix}$

(i) 固有值方程式  $\det(A - \lambda E) = 0$  为:

$$\begin{aligned}
 (-1 - \lambda)^2 - 9 &= 0 \\
 \lambda^2 + 2\lambda + 1 - 9 &= 0 \\
 \lambda^2 + 2\lambda - 8 &= 0 \\
 (\lambda + 4)(\lambda - 2) &= 0
 \end{aligned}$$

$$\lambda = 2, -4,$$

固有值为 2, -4

$$\lambda = 2 \text{ 或 } -4.$$

$$\begin{pmatrix} -3 & 3 \\ 3 & -3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 0$$

$$\begin{cases} -3x + 3y = 0 \\ 3x - 3y = 0 \end{cases} \rightarrow x = y.$$

固有向量求解  
 $t: \text{唯一}$

$$\lambda = -4 \text{ 或 } 2$$

$$\begin{pmatrix} 3 & 3 \\ 3 & 3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 0$$

固有向量求解  
 $t: \text{唯一}$

$$\begin{cases} 3x + 3y = 0 \\ 3x + 3y = 0 \end{cases} \rightarrow x = -y$$

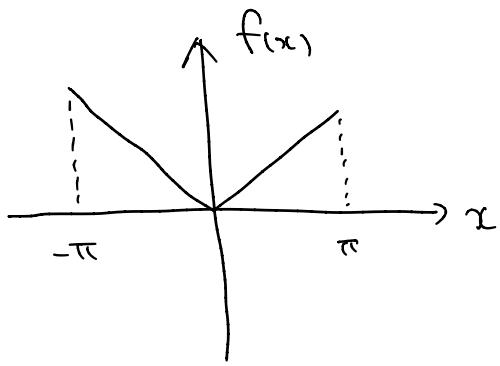
$$t \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\begin{aligned}
 \text{(iii)} \quad P' &= \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \text{ 旋转 } . \quad P'^{-1} = \frac{1}{2} \begin{pmatrix} -1 & -1 \\ -1 & 1 \end{pmatrix} \\
 D &= P'^{-1} A P' \\
 &= \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} -1 & 3 \\ 3 & -1 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{pmatrix} \\
 &= \begin{pmatrix} 2 & 2 \\ -4 & 4 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{pmatrix} \\
 &= \begin{pmatrix} 2 & 0 \\ 0 & -4 \end{pmatrix}, \quad \text{特征值 } \lambda_1 = \frac{1}{2} \begin{pmatrix} 1 & 1 \end{pmatrix},
 \end{aligned}$$

$$\begin{aligned}
 \text{(iii)} \quad Q &= -x_1^2 + 6x_1 x_2 + x_2^2 \\
 A &= \begin{pmatrix} -1 & 3 \\ 3 & -1 \end{pmatrix} \quad \underline{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \\
 &\text{ 旋转 } . \\
 Q &= \underline{x}^T A \underline{x} \\
 &= \underline{x}^T P D P^{-1} \underline{x} \\
 &= (\underline{P} \underline{x})^T \underline{D} (\underline{P}^{-1} \underline{x}) \\
 &= (\underline{P}^T \underline{x})^T \underline{D} (\underline{x}) \quad \text{特征向量 } e_1, e_2 \\
 &= \underline{y}^T \underline{D} \underline{y} \quad \underline{D} = P^T A \text{ 旋转 } . \\
 &= (y_1, y_2) \begin{pmatrix} 2 & 0 \\ 0 & -4 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \\
 &= 2 y_1^2 - 4 y_2^2
 \end{aligned}$$

$$\text{特征向量 } . \quad \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} x_1 + \frac{1}{\sqrt{2}} x_2 \\ \frac{1}{\sqrt{2}} x_1 - \frac{1}{\sqrt{2}} x_2 \end{pmatrix}$$

(5) (i)



$$a_n = \frac{1}{\pi} \int_{-\pi}^{\pi} |x| \cos nx \, dx$$

$$= \frac{2}{\pi} \int_0^{\pi} x \cos nx \, dx$$

$$\text{if } n \neq 0 \quad a_n \neq 0$$

$$a_0 = \frac{2}{\pi} \int_0^{\pi} x \, dx = \frac{2}{\pi} \left[ \frac{x^2}{2} \right]_0^{\pi} = \pi$$

$$\text{if } n \neq 0 \quad a_n \neq 0$$

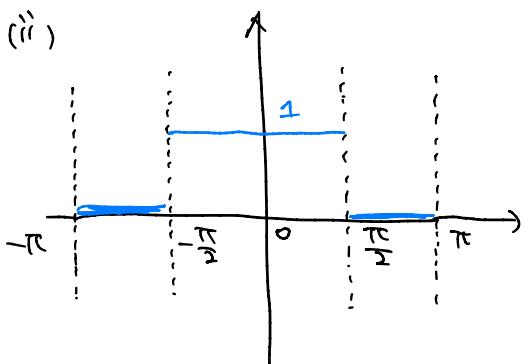
$$\begin{aligned} \int_0^{\pi} x \cos nx \, dx &= \left[ \frac{x}{n} \sin nx \right]_0^{\pi} - \int_0^{\pi} \frac{1}{n} \sin nx \, dx \\ &= 0 + \frac{1}{n^2} [\cos nx]_0^{\pi} \\ &= \frac{1}{n^2} \{ (-1)^n - 1 \} \end{aligned}$$

$$b_n = \frac{1}{\pi} \int_{-\pi}^{\pi} |x| \sin nx \, dx = 0.$$

$$\therefore f(x) = \frac{\pi}{2} + \sum_{n=1}^{\infty} \frac{1}{n^2} \{ (-1)^n - 1 \} \cos nx$$

!!

(ii)



$$\begin{aligned}
 a_n &= \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \cdot \cos nx dx \\
 &= \frac{1}{\pi} \int_0^{\pi/2} \cos nx dx \\
 &= \begin{cases} n=0 & x=0 \\ \frac{1}{\pi} \int_0^{\pi/2} dx = \frac{1}{\pi} \cdot \frac{\pi}{2} = \frac{1}{2} \\ n \neq 0 & x=\pi \end{cases} \\
 &\quad \frac{1}{\pi} \left[ \frac{1}{n} \sin nx \right]_0^{\pi/2} = \frac{2}{\pi} \sin \frac{n\pi}{2}
 \end{aligned}$$

$$b_n = \frac{2}{\pi} \int_{-\pi}^{\pi} f(x) \sin nx dx = 0$$

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$$\therefore f(x) = \frac{1}{2} + \sum_{n=1}^{\infty} \frac{2}{n\pi} \sin \frac{n\pi}{2} \cos nx$$

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# 数学 B

$$(1) \quad l = \int_0^T \sqrt{\left(\frac{dx}{ds}\right)^2 + \left(\frac{dy}{ds}\right)^2 + \left(\frac{dz}{ds}\right)^2} \ ds$$

$$\begin{cases} \frac{dx}{ds} = -a \sin s \\ \frac{dy}{ds} = a \cos s \\ \frac{dz}{ds} = b \end{cases}$$

从图上知

$$l = \int_0^T \sqrt{a^2 \sin^2 s + a^2 \cos^2 s + b^2} \ ds$$

$$= \int_0^T \sqrt{a^2 + b^2} \ ds$$

$$= \sqrt{a^2 + b^2} T$$

$$(2) \quad (1) \quad \frac{\partial u}{\partial x} = \frac{-2yz}{(x^2+y^2)^2} + \frac{8x^2yz}{(x^2+y^2)^3}$$

$$= \frac{-2yz(x^2+y^2) + 8x^2yz}{(x^2+y^2)^3}$$

$$= \frac{6x^2yz - 2y^3z}{(x^2+y^2)^3}$$

$$\frac{\partial u}{\partial y} = \frac{-2xz}{(x^2+y^2)^2} + \frac{8xy^2z}{(x^2+y^2)^3}$$

$$= \frac{-2xz(x^2+y^2) + 8xy^2z}{(x^2+y^2)^3}$$

$$= \frac{6xy^2z - 2xz^3}{(x^2+y^2)^3}$$

$$\frac{\partial u}{\partial z} = \frac{-2xy}{(x^2+y^2)^2}$$

$$\begin{aligned}\frac{\partial u}{\partial x} &= \frac{2xz}{(x^2+y^2)^2} - \frac{4x(x^2-y^2)z}{(x^2+y^2)^3} \\ &= \frac{2xz(x^2+y^2)}{(x^2+y^2)^3} - \frac{4xz(x^2-y^2)}{(x^2+y^2)^3} = \frac{-2x^3z + 6xzy^2}{(x^2+y^2)^3}\end{aligned}$$

$$\begin{aligned}\frac{\partial u}{\partial y} &= \frac{-2y^2}{(x^2+y^2)^2} - \frac{4y(x^2-y^2)z}{(x^2+y^2)^3} \\ &= \frac{-2y^2(x^2+y^2)}{(x^2+y^2)^3} - \frac{4yz(x^2-y^2)}{(x^2+y^2)^3} = \frac{-6x^2yz + 2y^3z}{(x^2+y^2)^3}\end{aligned}$$

$$\frac{\partial u}{\partial z} = \frac{x^2-y^2}{(x^2+y^2)^2}$$

$$\frac{\partial w}{\partial x} = \frac{-2xy}{(x^2+y^2)^2}$$

$$\frac{\partial w}{\partial y} = \frac{1}{x^2+y^2} - \frac{2y^2}{(x^2+y^2)^2} = \frac{x^2+y^2}{(x^2+y^2)^2} - \frac{2y^2}{(x^2+y^2)^2} = \frac{x^2-y^2}{(x^2+y^2)^2}$$

$$\frac{\partial w}{\partial z} = 0$$

(ii)  $\operatorname{div} \mathbf{v} = \left( \frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}, \frac{\partial w}{\partial z} \right)$  : 這裏的  $\mathbf{v}$  是  $\mathbf{u}$  的旋量

$$\operatorname{rot} \mathbf{v} = \begin{vmatrix} \partial_x & \partial_y & \partial_z \\ u & v & w \\ e_x & e_y & e_z \end{vmatrix}$$

$$= (\partial_y w - \partial_z w) e_x + (\partial_z u - \partial_x w) e_y + (\partial_x u - \partial_y u) e_z$$

$$= \frac{x^2-y^2}{(x^2+y^2)^2} e_x + \left[ \frac{-2xy}{(x^2+y^2)^2} - \frac{-2xy}{(x^2+y^2)^2} \right] e_y$$

$$+ \left[ \frac{-2x^3z + 6xzy^2}{(x^2+y^2)^3} - \frac{6x^2yz - 2y^3z}{(x^2+y^2)^3} \right] e_z$$

$$= \frac{x^2-y^2}{(x^2+y^2)^2} e_x \quad e_x : x \text{ の単位ベクトル}.$$

$$(3) \text{ (i)} d\tau = \omega dt + \varepsilon \omega^2$$

$$\frac{dx}{dt} = \frac{dx}{d\tau} \frac{d\tau}{dt} = \omega \frac{dx}{d\tau}$$

$$\frac{d}{dt} \left( \frac{dx}{dt} \right) = \omega \frac{d}{dt} \left( \frac{dx}{d\tau} \right) = \omega \frac{d\tau}{dt} \frac{d}{d\tau} \left( \frac{dx}{d\tau} \right) = \omega^2 \frac{d^2x}{d\tau^2}$$

从上式得

$$\omega^2 \frac{d^2x}{d\tau^2} + x + \varepsilon x^3 = 0 \quad \text{--- (4)}$$

(ii)

$$x = x_0 + \varepsilon x_1 + \dots \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{由 (4) 得 } x_0 \text{ 及 } x_1.$$

$$\begin{aligned} & (1 + \varepsilon \omega_1 + \dots)^2 \left( \frac{d^2x_0}{d\tau^2} + \varepsilon \frac{d^2x_1}{d\tau^2} + \dots \right) \\ & + (x_0 + \varepsilon x_1 + \dots) + \varepsilon (x_0 + \varepsilon x_1 + \dots)^3 = 0. \end{aligned}$$

$\varepsilon \neq 0$  时由 (iii).

$$\frac{d^2x_0}{d\tau^2} + x_0 = 0$$

$\varepsilon = 1$  时由 (iv).

$$\frac{d^2x_1}{d\tau^2} + (\omega_1 + \omega_1) \frac{d^2x_0}{d\tau^2} + x_1 + x_0^3 = 0$$

$$\therefore \frac{d^2x_1}{d\tau^2} + x_1 = -2\omega_1 \frac{d^2x_0}{d\tau^2} - x_0^3$$

(iii) (A) 为  $x_0$  的方程

$$x_0(\tau) = A e^{i\tau} + B e^{-i\tau}$$

$$\therefore x_0(t) = A e^{i\omega t} + B e^{-i\omega t}$$

$$\begin{aligned} \text{解得 } A + B &= a \\ A - B &= 0 \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \rightarrow A = B = \frac{a}{2}$$

$$x_0(t) = \frac{a}{2} e^{i\omega t} + \bar{e}^{-i\omega t} = a \cos \omega t$$

(iv) (B) は (A) の解であることを示す。

$$\frac{d^2x}{dt^2} = -\omega_1^2 x$$

$$\frac{d^2x_1}{dt^2} + x_1 = 2\omega_1 \alpha \cos \omega t - \alpha^3 \cos^3 \omega t$$

$$(2) \text{ は } \frac{d^2x_1}{dt^2} + x_1 = 0 \quad \text{を満たす} \quad x_1 = A e^{i\omega t} + B e^{-i\omega t} \\ = y_1 + y_2$$

$\therefore$  2. 特殊解と一般解。

$$\begin{aligned} f_{012} &= 2\omega_1 \alpha \cos \omega t - \alpha^3 \cos \omega t \cos^2 \omega t \\ &= 2\omega_1 \alpha \cos \omega t - \alpha^3 \cos \omega t \cdot \frac{1 - \cos 2\omega t}{2} \\ &= 2\omega_1 \alpha \cos \omega t - \frac{1}{2} \alpha^3 \cos \omega t + \frac{1}{2} \alpha^3 \cos \omega t \cos 2\omega t \end{aligned}$$

$$\left. \begin{aligned} \cos(\alpha+\beta) &= \cos \alpha \cos \beta - \sin \alpha \sin \beta \quad \text{を} \\ \cos \omega t \cos 2\omega t &= \frac{1}{2} (\cos 3\omega t + \cos \omega t) \end{aligned} \right)$$

$$\begin{aligned} &= 2\omega_1 \alpha \cos \omega t - \frac{1}{2} \alpha^3 \cos \omega t + \frac{1}{4} \alpha^3 \cos 3\omega t + \frac{1}{4} \alpha^3 \cos \omega t \\ &= 2\omega_1 \alpha \cos \omega t - \frac{1}{4} \alpha^3 \cos \omega t + \frac{1}{4} \alpha^3 \cos 3\omega t \end{aligned}$$

よって。

$$W = \begin{vmatrix} y_1 & y_2 \\ y'_1 & y'_2 \end{vmatrix} =$$