Numerical Techniques 2023-2024

1. Discretization and stability

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Content

- Discretization
- A prototype system: the 1D advection equation
- An example of a numerical scheme: the upstream scheme
- Accuracy and consistency
- Convergence
- Stability

Discretization

- Meteorological fields (temperature, wind, pressure, humidity, . . .) are continuous in time and space.
- On a computer you cannot represent a continuous field; you would need an infinity of points.
- So a field will be discretized, i.e. it is represented by the values in a set of discrete points:



replacing the continuous coordinate x by discrete points $i\Delta x$ labeled by i. Note that i is variable, and Δx is constant!

• similarly in 2D: $i\Delta x, j\Delta y$

• discretizing time: $n\Delta t$

Discretization of derivatives: finite differences

- Many physical laws are differential equations
- Some definition of the derivative in x:

$$\frac{df}{dx}(x_0) = \lim_{\delta x \to 0} \frac{f(x_0 + \delta x) - f(x_0)}{\delta x}$$

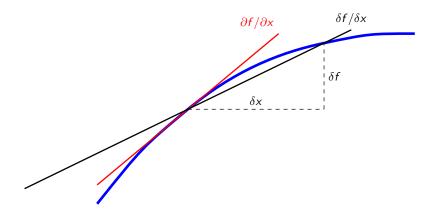
$$\frac{df}{dx}(x_0) = \lim_{\delta x \to 0} \frac{f(x_0) - f(x_0 - \delta x)}{\delta x}$$

$$\frac{df}{dx}(x_0) = \lim_{\delta x \to 0} \frac{f(x_0 + \delta x) - f(x_0 - \delta x)}{2\delta x}$$

• On our discrete grid we can't take the limit $\delta x \to 0$, so the derivative is computed with a finite value $\delta x \to \Delta x$ (i.e. the grid distance).

Discretization of derivatives: finite differences

• The limit is then better approximated by increasing the resolution



The 1D advection equation

We will now consider the 1D advection equation with constant advection

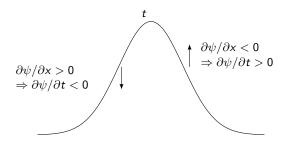
$$\frac{\partial \psi}{\partial t} + c \frac{\partial \psi}{\partial x} = 0$$

Why?

- hyperbolic systems can be decomposed into decoupled equations of this type
- most systems studied with atmospheric models are hyperbolic.

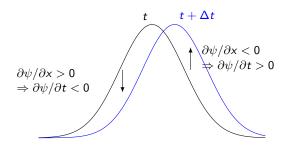
Physical interpretation of the advection equation:

- ψ is any (meteorological) field: temperature, pressure, humidity, pollutant concentration, . . .
- c is the wind speed.
- time evolution: the field is *transported* with speed *c*:



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The 1D advection equation

The exact solution of the advection equation

$$\frac{\partial \psi}{\partial t} + c \frac{\partial \psi}{\partial x} = 0$$

is given by

$$\psi(x,t)=\psi(x-ct,t=0)$$

The upstream scheme

Let us call ϕ_j^n the solution of the discretized system at time $n\Delta t$ and at grid point $j\Delta x$.

We replace the derivatives by,

$$\frac{\partial \psi}{\partial t} \to \frac{\phi_j^{n+1} - \phi_j^n}{\Delta t}$$
$$\frac{\partial \psi}{\partial x} \to \frac{\phi_j^n - \phi_{j-1}^n}{\Delta x}$$

in the advection equation:

$$\frac{\phi_j^{n+1} - \phi_j^n}{\Delta t} + c \frac{\phi_j^n - \phi_{j-1}^n}{\Delta x} = 0$$

This is called the upstream scheme.

The upstream scheme

This equation can be solved w.r.t. ϕ_i^{n+1} :

$$\phi_j^{n+1} = (1 - \mu)\phi_j^n + \mu\phi_{j-1}^n$$

with $\mu = c\Delta t/\Delta x$.

So if the solution is known at time $t = n\Delta t$, then it can be calculated at $t = (n+1)\Delta t$.

The upstream scheme

 But we see that increasing the spatial resolution doesn't necessarily improve the solution !?

We say that the discretized system becomes unstable.

- Stability is a central concept in this course. This lesson will (try to) explain why.
- For this we need additional concepts: accuracy, consistency and convergence.

Using a Taylor expansion

$$f(x_0 + \Delta x) = f(x_0) + \Delta x \frac{df}{dx}(x_0) + \frac{\Delta x^2}{2} \frac{d^2 f}{dx^2}(x_0) + \frac{\Delta x^3}{6} \frac{d^3 f}{dx^3}(x_0) + \dots$$

the error in the approximation of the derivative is

$$\frac{f(x_0 + \Delta x) - f(x_0)}{\Delta x} - \frac{df}{dx}(x_0) = \frac{\Delta x}{2} \frac{d^2 f}{dx^2}(x_0) + \frac{\Delta x^2}{6} \frac{d^3 f}{dx^3}(x_0) + \dots$$

The leading term is proportional to Δx , so this is called a first-order accurate method.

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Considering the centered finite-difference approximation

$$\frac{f(x_0 + \Delta x) - f(x_0 - \Delta x)}{2\Delta x} - \frac{df}{dx}(x_0) = \frac{\Delta x^2}{6} \frac{d^3 f}{dx^3}(x_0) + \frac{\Delta x^4}{120} \frac{d^5 f}{dx^5}(x_0) + \dots$$

we see that it is second-order accurate.

By using more information (more gridpoints), it is possible to obtain a more accurate approximation for the derivative:

$$\begin{aligned} \frac{df}{dx}(x_0) &= \frac{4}{3} \left(\frac{f(x_0 + \Delta x) - f(x_0 - \Delta x)}{2\Delta x} \right) \\ &- \frac{1}{3} \left(\frac{f(x_0 + 2\Delta x) - f(x_0 - 2\Delta x)}{4\Delta x} \right) + O[\Delta x^4] \end{aligned}$$

A scheme is called *consistent* if the truncation error converges to zero when $\Delta x \to 0$ and $\Delta t \to 0$.

For example, the truncation error for the upstream scheme is:

$$\frac{\psi_j^{n+1} - \psi_j^n}{\Delta t} + c \frac{\psi_j^n - \psi_{j-1}^n}{\Delta x} = \frac{\Delta t}{2} \frac{\partial^2 \psi}{\partial t^2} - c \frac{\Delta x}{2} \frac{\partial^2 \psi}{\partial x^2} + \dots$$

where ψ denotes the exact solution.

Convergence

A finite-difference scheme is called *convergent* of order (p,q) if in the limit $\Delta t, \Delta x \to 0$, the numerical solution ϕ_j^n satisfies

$$\|\psi(\mathsf{n}\Delta t, j\Delta x) - \phi_j^{\mathsf{n}}\| = O[\Delta t^{\mathsf{p}}] + O[\Delta x^{\mathsf{q}}]$$

Convergence vs. consistence

Consistency tells you something about the equations, convergence tells you about the solution.

The upstream scheme example shows that these two are not identical: it is consistent but not convergent.

There's a problem with the usability of convergence: it relies on the exact solution, which is unknown in most cases.

Lax theorem

The Lax equivalence theorem says that:

If a finite-difference scheme is linear, stable, and consistent, then it is convergent

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Importance: in practice we never know the true solution, but we can check if the scheme is *consistent* and *stable*.

But when is a scheme stable?

Numerical stability

A sufficient condition for stability is that

$$\|\phi^n\| \le \|\phi^0\|$$
 for all timesteps $n > 0$

Again, we don't need to know the true solution for this!

Checking stability

- It is difficult to check the evolution of $\|\phi^n\|$ in general.
- Von Neumann proposed to check stability by considering harmonic functions:

$$\phi(x) = \exp(ikx) = \cos(kx) + i\sin(kx)$$

If a scheme is stable for all harmonic functions (i.e. all values of k), then it is also stable for all (non-harmonic) functions.

• Because harmonic functions are eigenfunctions of the differential operator, one can express their time evolution as a multiplication with an *amplification factor* A_k :

$$\phi^n = A_k \phi^{n-1} = (A_k)^n \phi^0$$

• So stability requires $||A_k|| \le 1$, for all k.

Let us consider again the upstream scheme for the advection equation:

$$\phi_j^{n+1} = (1 - \mu)\phi_j^n + \mu\phi_{j-1}^n$$

with $\mu = c\Delta t/\Delta x$.

What is the amplification factor?

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What is the amplification factor?

First, assume that $\phi_i^n = (A_k)^n e^{ikj\Delta x}$, so

$$(A_k)^{n+1}e^{ikj\Delta x}=(A_k)^n(1-\mu)e^{ikj\Delta x}+(A_k)^n\mu e^{ik(j-1)\Delta x}$$

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The amplification factor A_k then becomes

$$A_k = 1 - \mu + \mu e^{-ik\Delta x}$$

= $(1 - \mu + \mu \cos k\Delta x) - i\mu \sin k\Delta x$

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This will be ≤ 1 for all values of k if

$$\mu (1 - \mu) \ge 0$$

i.e. if

$$0 \le \frac{c\Delta t}{\Delta x} \le 1$$

- So the upstream scheme is *conditionally stable*, i.e. stability depends on the values of c, Δx and Δt .
- In general,
 - higher spatial resolution is less stable
 - smaller timesteps is more stable
 - higher velocity is less stable
- $\mu = \frac{c\Delta t}{\Delta x}$ is called the Courant number.
- The condition $\mu \leq 1$ is called the Courant-Fredrichs-Lewy (CFL) criterion.

Starting from a discretized equation:

- Check if the scheme is linear and consistent
- **②** Fill in a harmonic solution $\phi_i^n = (A_k)^n e^{i kj\Delta x}$ in the discretized equation
- **3** Calculate (the modulus of) the amplification factor A_k
- If $|A_k| \le 1$, the scheme is stable
- If the scheme is stable and consistent, it is convergent
- If the scheme is convergent, the error on the solution can be reduced by increasing the resolution

Summary

- Discretization of a continuous function on a grid
- Approximation of derivatives with finite differences
- Accuracy and Consistency of a scheme (error on equations)
- Convergence of a scheme (error on solution)
- Stability of a scheme: Von Neumann analysis, Courant number and CFL criterion
- Applied to the upstream scheme to solve the 1D advection equation