

# Numerical Techniques 2025–2026

## 4. Spectral models

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Postgraduate Studies in Weather and Climate Modeling

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- Spectral decomposition: principle
- Discretization and truncation: FFT
- Accuracy of spectral derivatives
- Aliasing and nonlinearity
- Spectral models

- Spectral decomposition: principle
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- Accuracy of spectral derivatives
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Note: spectral decomposition plays an important role in

- (approximate) analytical solutions: see Dynamic Meteorology
- understanding the behaviour of numerical schemes: see previous lessons
- the development of spectral atmospheric models

- Harmonic functions ( $\sin x$ ,  $\cos x$ ,  $\exp ix$ ) have some interesting properties

- ▶ periodic, wave-like
- ▶ they don't change (a lot) when taking the derivative:

$$\frac{d}{dx} \sin kx = k \cos kx$$

$$\frac{d}{dx} \cos kx = -k \sin kx$$

$$\frac{d}{dx} \exp ikx = ik \exp ikx$$

We say that these functions are *eigenfunctions* of the differential operator

- Spectral decomposition allows us to use these properties for arbitrary functions!

- **Decomposition**

- Discretization

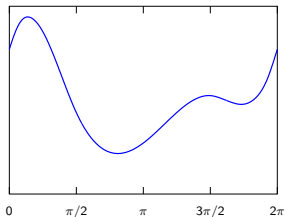
- Accuracy

- Aliasing

- Spectral models

## Decomposition in harmonic functions

- Consider a periodic function  $f(x)$  with period  $2\pi$ :



- Then we can *decompose* this function in harmonic functions with wavenumber  $k = 0, 1, \dots$ :

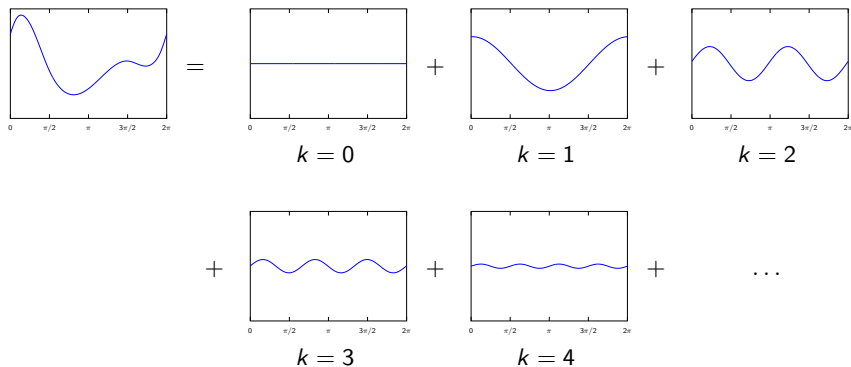
$$f(x) = \sum_{k=0}^{\infty} a_k \cos(k x) + b_k \sin(k x)$$

Or, using the exponential notation for harmonic functions ( $e^{i\theta} = \cos \theta + i \sin \theta$ ):

$$f(x) = \sum_{k=-\infty}^{\infty} \alpha_k \exp(i k x)$$

# Decomposition in harmonic functions

- For example:



(Think of distinguishing low and high tones in music...)

- Decomposition
- **Discretization**
- Accuracy
- Aliasing
- Spectral models



- On a computer, the function  $f(x)$  needs to be discretized, and the infinite summation needs to be truncated:

$$f(x_j) = \sum_{k=-K}^K \alpha_k \exp(i k x_j)$$

- To uniquely determine the coefficients  $\alpha_k$ , the number of gridpoints must be equal to the number of waves, i.e.  $N = 2K + 1$ , so  $\Delta x = \pi/K$ .
- For a uniform grid spacing, the highest resolvable wave has wavenumber  $K$ , i.e. period  $2\Delta x$ . We call this the Nyquist wavenumber. Waves with higher wavenumbers will be aliased (see further).
- Note that we now have information *between* gridpoints !?

- The Fourier coefficients are calculated with a Galerkin approach as

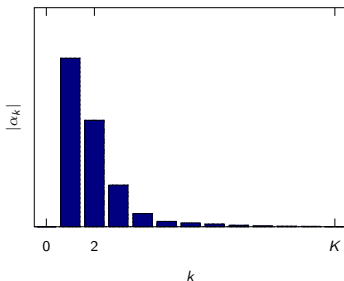
$$\alpha_k = \frac{1}{N} \sum_{j=1}^N f(x_j) e^{-ikx_j}$$

(note the symmetry with the composition formula).

- Efficient algorithms exist to perform the spectral decomposition (i.e. calculate the coefficients  $\alpha_k$ ), or the spectral composition (i.e. determine the values  $f(x_j)$  from the coefficients  $\alpha_k$ ) in  $O(N \log N)$  operations:

## Fast Fourier Transforms (FFT)

- When plotting the spectral coefficients  $\alpha_k$  against the wavenumbers, one obtains the *spectrum* of the function  $f(x)$ :

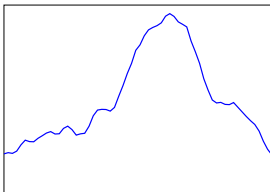


- The spectrum is a measure for the energy distribution over the different scales. For many physical variables, the spectrum quickly decreases for large wavenumbers.

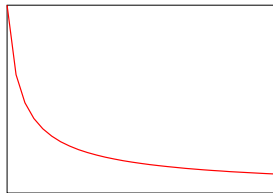
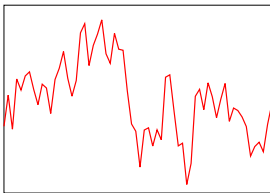
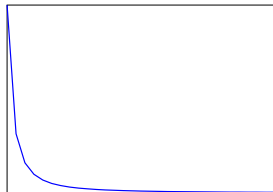
## Relation between the smoothness and the spectrum

- The spectrum of a smooth function decays quickly
- Rougher functions have a wider spectrum

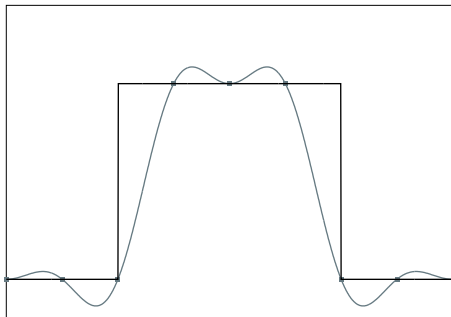
**Field**



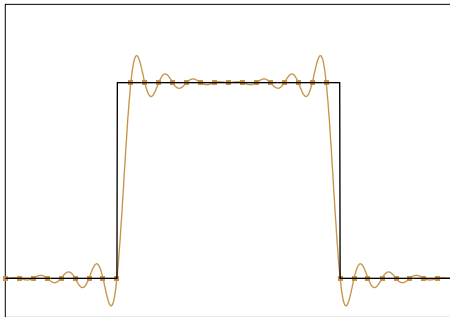
**Spectrum**



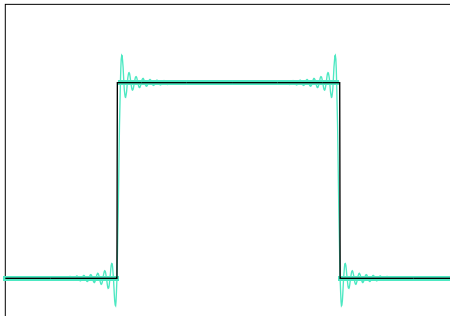
- When modeling a *discontinuity* with harmonic functions, the approximation will contain *overshoots*



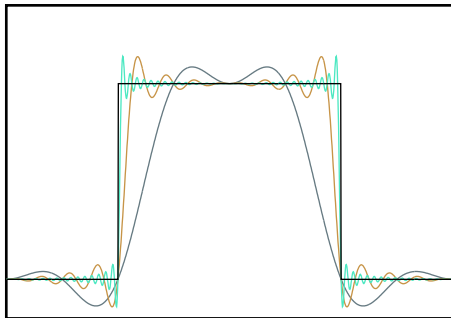
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- These overshoots don't disappear when going to a higher resolution. They even get worse!



- Decomposition
- Discretization
- **Accuracy**
- Aliasing
- Spectral models

- Let us consider  $\psi(x)$  on a domain  $0 \leq x \leq 2\pi$ , then

$$\psi(x) = \sum_{k=-\infty}^{\infty} \alpha_k e^{ikx}$$

and

$$\frac{\partial \psi}{\partial x} = \sum_{k=-\infty}^{\infty} ik \alpha_k e^{ikx}$$

- If we discretize the function and truncate the Fourier series, the error of the representation of the derivative is given by

$$E = \sum_{|k| > K} ik\alpha_k e^{ikx}$$

- If the  $p$ -th order derivative is continuous and all the lower order derivatives are continuous, it's possible to show that

$$|\alpha_k| \leq \frac{C}{|k|^p}$$

for a finite  $C$  (cfr. decaying spectrum).

- Remember that the maximum wavenumber  $K$  is related to the grid distance  $\Delta x$ :

$$K \sim \frac{1}{\Delta x}$$

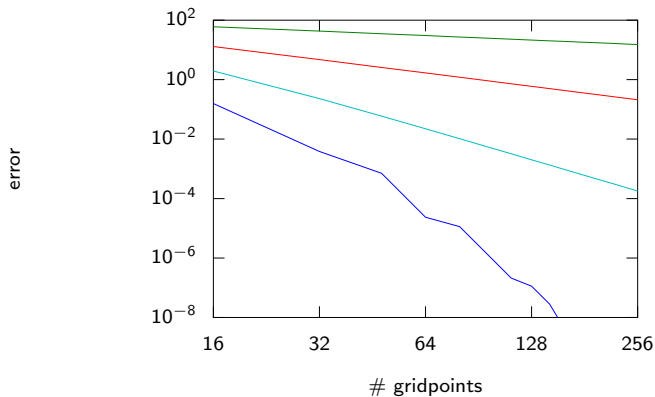
- So the error on the derivative is bound by

$$|E| \leq \tilde{C} (\Delta x)^{p-2}$$

with  $\tilde{C}$  a finite constant.

- This means that
  - the order of accuracy of the spectral method is determined by the smoothness of  $\psi$
  - if  $\psi$  is infinitely differentiable then the spatial derivatives are represented by infinite-order accuracy !

Comparison of spectral derivatives with 1st, 2nd and 4th order schemes:



## Consequence for time differencing

- We need to choose a smaller time step than for centered space differencing. For instance for a mode with  $\kappa = ck$ , we have seen before that the stability requirement is  $|\kappa\Delta t| \leq 1$ . For the  $2\Delta x$ -mode, this corresponds to:

$$\left| \frac{c\Delta t}{\Delta x} \right| \leq \frac{1}{\pi}$$

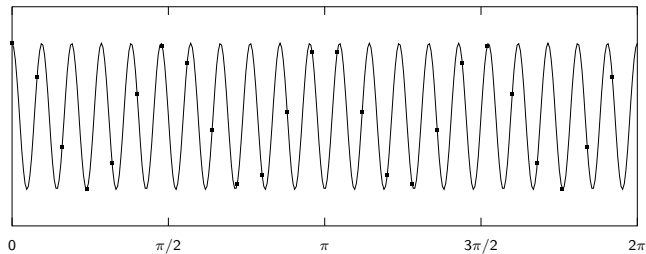
- For leapfrog time integration with centered differences:

second-order	$\left  \frac{c\Delta t}{\Delta x} \right  \leq 1$
fourth-order	$\left  \frac{c\Delta t}{\Delta x} \right  \leq 0.73$
sixth-order	$\left  \frac{c\Delta t}{\Delta x} \right  \leq 0.63$
$\vdots$	
$\infty$ -order	$\left  \frac{c\Delta t}{\Delta x} \right  \leq \frac{1}{\pi}$

- There is no such thing as a free lunch...

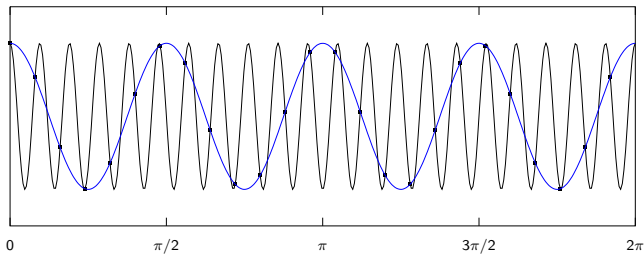
- Decomposition
- Discretization
- Accuracy
- **Aliasing**
- Spectral models

- Sampling a wave with wavenumber  $k = 21$  on a grid with  $K = 12$ , so  $N = 2K + 1 = 25$  gridpoints:



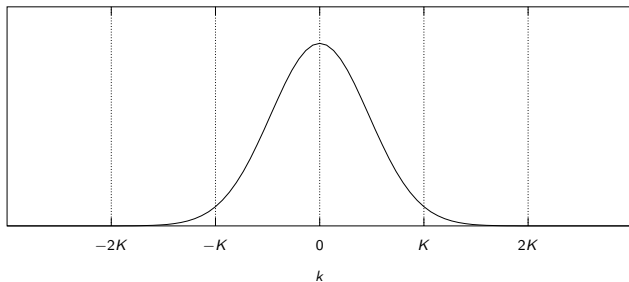


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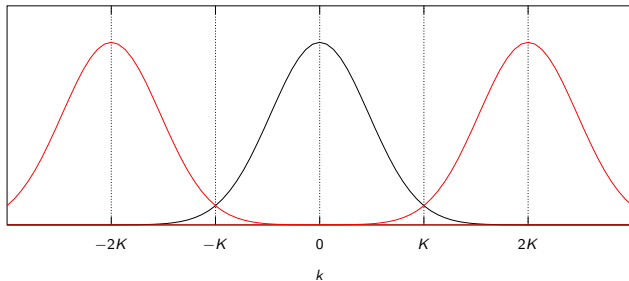


- These points lie exactly on a wave with wavenumber  $k' = 4$ . So the high-frequency wave *appears* as a lower frequency wave; this is *aliasing*.

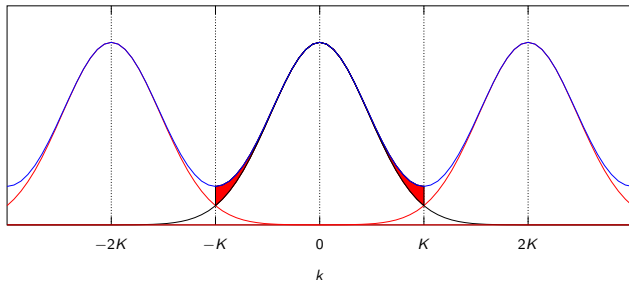
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- The part of the spectrum that is truncated ( $|k| > K$ ) ‘contaminates’ the part where  $|k| < K$ .

- Aliasing mainly poses problems when multiplying fields: let  $\phi_1(x) = e^{i k_1 x}$  and  $\phi_2(x) = e^{i k_2 x}$ . Then

$$\phi_1(x)\phi_2(x) = e^{i(k_1+k_2)x}$$

- A multiplication of two fields changes the wavenumber. If  $|k_1 + k_2| > K$ , aliasing will occur.

- Besides aliasing, there is an additional problem with nonlinearity in spectral space. Take, for instance, the advection equation with a nonconstant speed:

$$\frac{\partial \phi(x, t)}{\partial t} + c(x, t) \frac{\partial \phi(x, t)}{\partial x} = 0$$

with

$$\phi(x, t) = \sum_{k_1=-K}^K \hat{\phi}_{k_1}(t) e^{ik_1 x} \quad c(x, t) = \sum_{k_2=-K}^K \hat{c}_{k_2}(t) e^{ik_2 x}$$

- Then the equation for each wave component  $\hat{\phi}_k(t)$  is:

$$\frac{d\hat{\phi}_k}{dt} + \sum_{\substack{k_1 + k_2 = k \\ |k_1|, |k_2| \leq K}} i k_1 \hat{c}_{k_2} \hat{\phi}_{k_1} = 0$$

- In other words, one has to consider *all possible combinations* of  $k_1$  and  $k_2$  that may contribute to each wave component.

- For instance, to write the equation for the spectral coefficient  $\hat{\phi}_2$  of a wave with wavenumber  $k = 2$ , one has to consider
  - ▶  $\hat{c}_0 \hat{\phi}_2$
  - ▶  $\hat{c}_1 \hat{\phi}_1$
  - ▶  $\hat{c}_2 \hat{\phi}_0$
  - ▶  $\hat{c}_3 \hat{\phi}_{-1}$
  - ▶ ...
- We say that multiplication is *not local* in spectral space.

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  - ▶  $\dots$
- We say that multiplication is *not local* in spectral space.
- For a grid with  $N$  gridpoints, this means that multiplication in spectral space takes  $\mathcal{O}(N^2)$  operations, while in gridpoint space, it only takes  $\mathcal{O}(N)$  operations.



- Note that 'multiplication' and 'taking derivative' behave oppositely in gridpoint and in spectral space:

operation	Gridpoint space	Spectral space
multiplication	local	nonlocal
derivative	(weakly) nonlocal	local

- Make sure to perform the operations in the appropriate 'space'.

- Aliasing can be avoided by truncating the spectrum well before the Nyquist wavenumber  $K$ .
- For example, let  $k_{max} = K/2$ , then a multiplication will produce fields with a maximal wavenumber  $2k_{max} = K$ , and no aliasing will occur.
- The condition can even be relaxed to  $k_{max} = 2K/3$ . Why?  
(hint: look at the interpretation of aliasing in terms of a periodic spectrum)

Check Durran's book for a mathematical derivation.

- Decomposition
- Discretization
- Accuracy
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- **Spectral models**

- Considering the advection equation

$$\frac{\partial \phi}{\partial t} + c \frac{\partial \phi}{\partial x} = \text{RHS}$$

- A typical timestep organization of a spectral model of this problem looks like

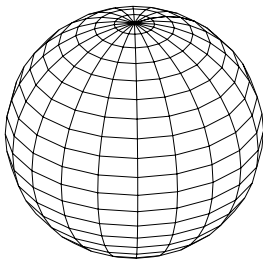
- |  |   |                 |
|--|---|-----------------|
| ❶ Spectral truncation: $\hat{\phi}_k = \hat{c}_k = 0$ for $k > 2K/3$ | } | Spectral space  |
| ❷ Derivative of $\phi$ : multiply $\hat{\phi}_k$ by $ik$ .           |   |                 |
| ❸ Inverse FFT  |   |                 |
| ❹ Compute the product $c(x_j)\partial\phi(x_j)/\partial x$           | } | Gridpoint space |
| ❺ Add additional forcings $RHS$ (physics parameterizations)          |   |                 |
| ❻ Forward FFT  | } | Spectral space  |
| ❼ Implicit time step scheme  |   |                 |

- Besides the accuracy and efficiency of the derivatives, there are other advantages of spectral models:
  - ▶ No **dispersion** (e.g. negative group speed!) due to spatial discretization.
  - ▶ The inversion of the differential operators like the Laplace operator  $\nabla^2$  (see Dyn. Met.), which appears in **implicit schemes**.

In gridpoint space, this requires the inversion of a HUGE  $(n_x n_y) \times (n_x n_y)$  sparse matrix.

In spectral space, this matrix becomes diagonal, and its inversion is trivial. This means *implicit* time-integration schemes can be used much more easily.

- With a regular global grid, the spatial resolution is not uniform on the globe: near the **pole**, the resolution becomes very high ( $\Delta x \rightarrow 0$ ).



Note that stability (thus the timestep  $\Delta t$ ) is determined by the *smallest*  $\Delta x$  across the domain.

- This so-called 'pole-problem' does not occur in a spectral model.

- In a spherical geometry, spectral decomposition looks like:

$$\psi(\lambda, \mu) = \sum_{m=-\infty}^{\infty} \sum_{n=|m|}^{\infty} \hat{\psi}_{m,n} Y_{m,n}(\lambda, \mu)$$

- The base functions  $Y$  are the eigenfunctions of the Laplace operator (*spherical harmonics*):

$$Y_{m,n}(\lambda, \mu) \equiv P_{m,n}(\mu) e^{im\lambda}$$

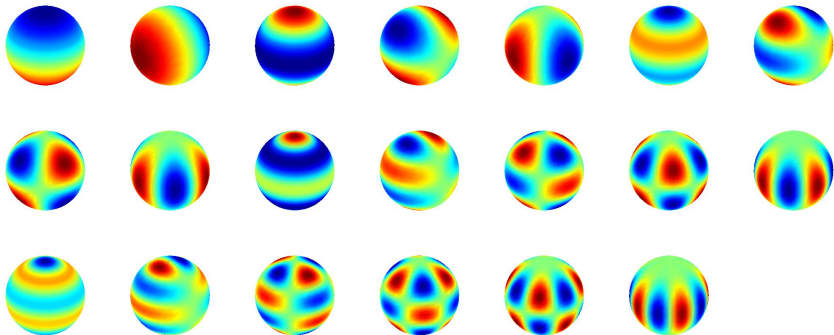
- The functions  $P_{m,n}$  are the associated Legendre functions

$$P_{m,n}(\mu) = \left[ \frac{2n+1}{2} \frac{(n-m)!}{(n+m)!} \right]^{\frac{1}{2}} (1-\mu^2)^{\frac{m}{2}} \frac{d^m}{d\mu^m} P_n(\mu)$$

where the functions  $P_n$  are Legendre polynomials

$$P_n(\mu) = \frac{1}{2^n n!} \frac{d^n}{d\mu^n} [(\mu^2 - 1)^n]$$

- Some spherical harmonics:





- Some properties of spherical harmonics:

- ▶ orthogonality of associated Legendre functions

$$\int_{-1}^1 P_{m,n}(\mu) P_{m,s}(\mu) d\mu = \delta_{n,s}$$

- ▶ orthogonality of spherical harmonics

$$\frac{1}{2\pi} \int_{-1}^1 \int_{-\pi}^{\pi} Y_{m,n}(\lambda, \mu) Y_{r,s}^*(\lambda, \mu) d\lambda d\mu = \delta_{m,r} \delta_{n,s}$$

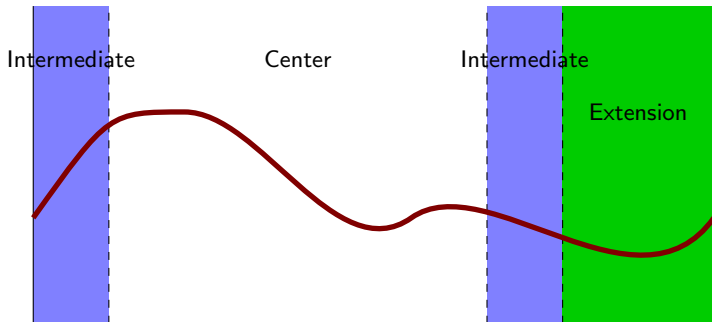
- ▶ Laplacian of spherical harmonics

$$\nabla^2 Y_{m,n} = -\frac{n(n+1)}{a^2} Y_{m,n}$$

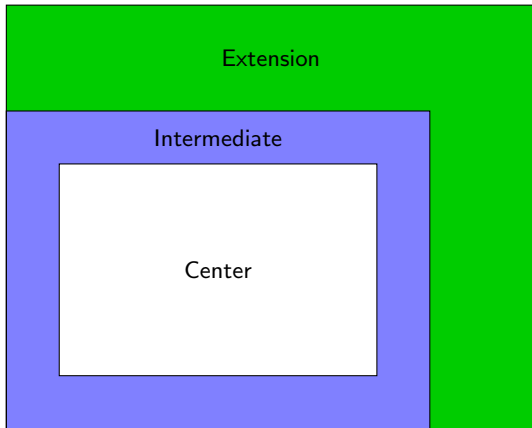
- Note that these properties have analogies in Fourier-space!

- In a spectral limited-area model (LAM) one has to
  - ▶ impose lateral boundary conditions
  - ▶ make the fields periodic to be able to apply the FFT's
- Remark: use of Chebyshev polynomials instead of harmonic functions could avoid need for periodization (student's project)

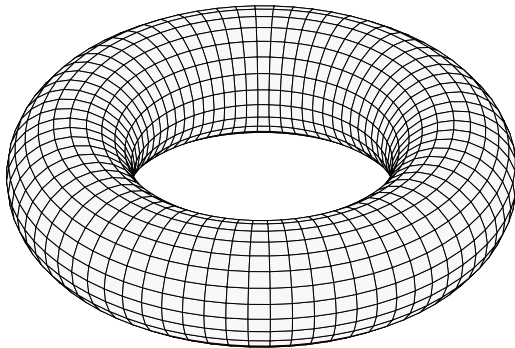
- A spectral limited area model (LAM) domain is organized in 3 zones:



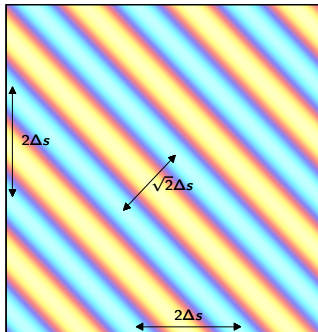
- ▶ The Intermediate zone is used to apply lateral boundary conditions (see later).
- ▶ In the extension zone, the fields are artificially extended such that they become periodic.
- ▶ The center zone is the physical part of the model.



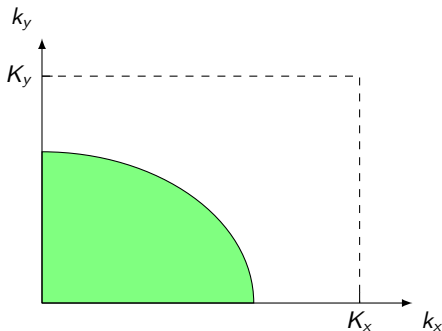
(...so in some sense we are working on a torus ...)



- Avoiding aliasing:  $k_{x,y} \leq 2K_{x,y}/3$
- In 2D, the resolution is not the same in all directions



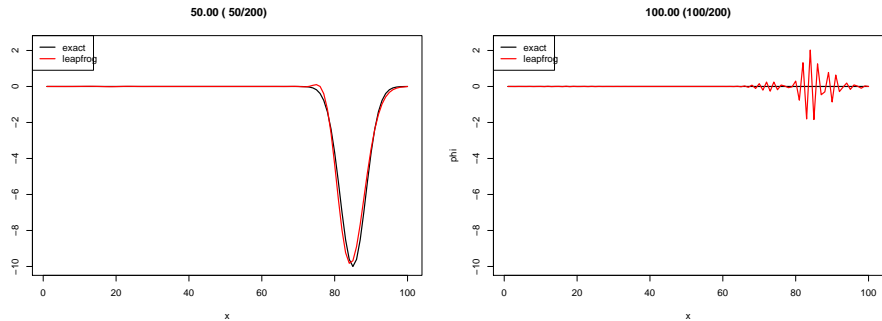
- Avoiding aliasing:  $k_{x,y} \leq 2K_{x,y}/3$
- In 2D, the resolution is not the same in all directions
- This is solved by an *elliptic truncation* in spectral space



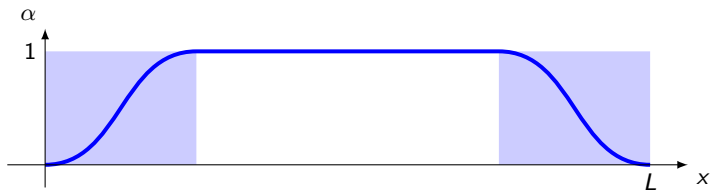
- A LAM needs lateral boundary conditions, usually provided by a global model running at lower resolution.
- When applying LBC's only at the boundary points, *spurious reflections* will arise due to inconsistency between boundary points and the internal points.



Example: a depression right before and after leaving a LAM domain:



- Davies' solution: apply the boundary conditions in a gentle way, i.e. through relaxation in the intermediate zone:



- Mathematically, the coupling looks like

$$\psi = \alpha \tilde{\psi} + (1 - \alpha) \psi_{LS}$$

where  $\tilde{\psi}$  is the solution with periodic boundary conditions, and  $\psi_{LS}$  is the large-scale solution.

- This coupling is done *every time step*, but  $\psi_{LS}$  is interpolated in time because of data limits (e.g. 3h).

- This strategy can also be derived mathematically by starting from a modified equation:

$$\frac{\partial \psi}{\partial t}(x, t) + U \frac{\partial \psi}{\partial x}(x, t) = -K(x) [\psi(x, t) - \psi_{LS}(x, t)]$$

- The RHS represents a *relaxation term* which penalizes differences (at the boundary) between the LAM solution  $\psi$  and the large-scale solution  $\psi_{LS}$ . This scheme was proposed by Davies (1983).
- The function  $K(x)$  ultimately determines the relaxation function  $\alpha(x)$ .
- Interested? See student's project.

- Concept of spectral decomposition
- Accuracy of derivatives is of infinite order
- Excellent for implicit times schemes!
- Aliasing due to nonlinearity (multiplication) and solution by truncating the spectrum
- Global spectral models with spherical harmonics
- Limited area models:
  - ▶ extension zone for periodization
  - ▶ relaxation zone for boundary conditions