#### Numerical Techniques 2023-2024

# 2. The oscillation equation and time differencing

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#### Previously on Numerical Techniques...

- Positioning of the course in the postgraduate program
- Discretization and finite differences
- Consistency, convergence and stability
- Von Neumann analysis and Courant number  $\mu=c\frac{\Delta t}{\Delta x}$ , linking spatial resolution to temporal resolution
- Example of upstream scheme for 1D advection equation
- Don't worry about math too much!

## Today's content...

- The oscillation equation
- Errors due to time discretization: amplitude and phase
- Concrete schemes
  - Single stage, two timelevel
     Forward, backward, trapezium
  - Multistage, two timelevel
     Heun, Matsuno, Runge-Kutta
  - ► Single stage, three timelevel Leapfrog, Adams-Bashforth
  - Filter for computational modes

#### The oscillation equation

The oscillation equation is given by:

$$\frac{d\psi}{dt} = i\kappa\psi$$

Although much simpler than the partial differential equations (PDE's) in atmospheric modeling, the oscillation equation is very relevant:

- Wave-dominated hyperbolic PDE's can be decoupled in advection equations
- The advection equation in Fourier expansion looks like the oscillation equation

## From advection equation to oscillation equation

The advection equation

$$\frac{\partial \psi}{\partial t} + c \frac{\partial \psi}{\partial x} = 0$$

in Fourier expansion  $\left(\psi(x,t)=\sum_{k=-\infty}^{\infty}\hat{\psi}_k(t)e^{ikx}
ight)$  looks like

$$\frac{d\hat{\psi}_k}{dt} = -ikc\,\hat{\psi}_k$$

which is actually the oscillation equation

$$\frac{d\psi}{dt} = i\kappa\psi$$

• The influence of the space discretization is removed by the Fourier transform, so we can now focus on the *time differencing*.

#### The oscillation equation: time evolution

• The exact time evolution of the solution is

$$\psi(t_0 + \Delta t) = e^{i\kappa\Delta t}\psi(t_0) \equiv A_e\psi(t_0)$$

- For an approximate (numerical) solution,  $\phi^{n+1} = A\phi^n$ .
- ullet The quality of the approximation will depend on the difference between A and  $A_e$ .
- Note: we will use the exponential notation of a complex number:

$$A = |A|e^{i\theta}$$

with

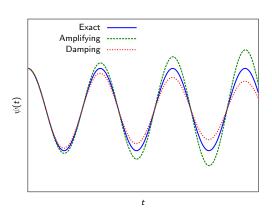
$$|A| = \sqrt{\mathcal{R}\{A\}^2 + \mathcal{I}\{A\}^2}$$
  $heta = \operatorname{arg}(A) = \operatorname{arctan}\left(rac{\mathcal{I}\{A\}}{\mathcal{R}\{A\}}
ight)$ 

#### The oscillation equation: time evolution

Approximation of exact solution  $A_e=e^{i\kappa\Delta t}$  by numerical solution  $A=|A|e^{i\theta}$ :

#### Amplitude

A  > 1	amplifying		
A  = 1	neutral		
A  < 1	damping		



## The oscillation equation: time evolution

Approximation of exact solution  $A_e = e^{i\kappa\Delta t}$  by numerical solution  $A = |A|e^{i\theta}$ :

Amplitude

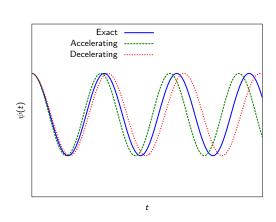
$$|A|>1$$
 amplifying  $|A|=1$  neutral  $|A|<1$  damping

 Phase speed: error is characterized by the *relative* phase change

$$R = \frac{\theta}{\kappa \Delta t}$$

Then

$$R > 1$$
 accelerating  $R < 1$  decelerating



#### Classes of schemes

We will now review several schemes:

- Single stage, two-time-level schemes
- Multistage schemes
- Three-time-level schemes

## Single stage two-time-level schemes

• For the generic equation

$$\frac{d\psi}{dt} = F(\psi)$$

the single-stage two-time-level schemes have the form

$$\frac{\phi^{n+1} - \phi^n}{\Delta t} = \alpha F(\phi^n) + \beta F(\phi^{n+1})$$

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Some terminology:

$$lpha=1$$
  $eta=0$  forward differencing  $lpha=0$   $eta=1$  backward differencing  $lpha=rac{1}{2}$   $eta=rac{1}{2}$  trapezoidal differencing

# Single stage two-time-level schemes: amplification factor

• For the oscillation equation the right-hand side is simply  $F(\psi) = i\kappa\psi$ , so the single-stage two-time-level schemes become

$$(1 - i\beta\kappa\Delta t)\phi^{n+1} = (1 + i\alpha\kappa\Delta t)\phi^{n}$$

• The amplification factor is then

$$A \equiv \frac{\phi^{n+1}}{\phi^n} = \frac{1 + i\alpha\kappa\Delta t}{1 - i\beta\kappa\Delta t}$$

## Single stage two-time-level schemes: accuracy

 The order of accuracy is identified when taking the Taylor expansion of the amplification factor A:

$$A = 1 + i(\alpha + \beta)\kappa\Delta t - (\alpha + \beta)\beta(\kappa\Delta t)^{2} + O(\Delta t^{3})$$

while the exact amplification factor is:

$$A_e = e^{i\kappa\Delta t} = 1 + i\kappa\Delta t - \frac{1}{2}(\kappa\Delta t)^2 + O(\Delta t^3)$$

so

- forward and backward schemes are first order accurate
- trapezium scheme is second order accurate

## Single stage two-time-level schemes: stability

• The modulus of the amplification factor is

$$|A|^2 = \frac{1 + \alpha^2 \kappa^2 \Delta t^2}{1 + \beta^2 \kappa^2 \Delta t^2}$$

- So the stability properties are:
  - Forward scheme ( $\alpha = 1, \beta = 0$ )  $\Rightarrow$  unstable (amplifying)
  - ▶ Trapezium scheme ( $\alpha = \beta = 1/2$ )  $\Rightarrow$  stable (neutral)
  - ▶ Backward scheme ( $\alpha = 0, \beta = 1$ )  $\Rightarrow$  stable (damping)

## Single stage two-time-level schemes: phase error

• The relative phase change is

$$R \equiv rac{\mathsf{arg}(A)}{\kappa \Delta t} = rac{1}{\kappa \Delta t} rctan \left(rac{\left(lpha + eta
ight)\kappa \Delta t}{1 - lpha eta \left(\kappa \Delta t
ight)^2}
ight)$$

• For the forward scheme ( $\alpha=1,\beta=0$ ) and the backward scheme ( $\alpha=0,\beta=1$ ),

$$R_{ ext{forward}} = R_{ ext{backward}} = rac{\operatorname{arctan} \kappa \Delta t}{\kappa \Delta t}$$

Using the Taylor expansion of arctan:

$$\arctan x = x - \frac{x^3}{3} + \dots$$

it follows that for good numerical resolution ( $\kappa \Delta t \ll 1$ ),

$$R_{ ext{forward}} = R_{ ext{backward}} pprox 1 - rac{\left(\kappa \Delta t
ight)^2}{3}$$

So the forward scheme and the backward scheme are decelerating.

## Single stage two-time-level schemes: phase error

• For the trapezium scheme ( $\alpha = \beta = 1/2$ ),

$$egin{align*} R_{\mathsf{trapezoidal}} = & rac{1}{\kappa \Delta t} \operatorname{arctan} \left( rac{\kappa \Delta t}{1 - rac{\kappa^2 \Delta t^2}{4}} 
ight) \ & pprox 1 - rac{\left(\kappa \Delta t
ight)^2}{12} \ \end{aligned}$$

So the trapezium scheme is also decelerating, but the phase error is less than with the forward and the backward schemes.

#### Important remark:

For the backward and the trapezoidal scheme,  $F(\phi^{n+1})$  is needed to compute  $\phi^{n+1}$ :

$$\frac{\phi^{n+1} - \phi^n}{\Delta t} = \alpha F(\phi^n) + \beta F(\phi^{n+1})$$

Such schemes are called *implicit* schemes. Schemes for which only  $\phi^n$  is needed, are called *explicit* schemes.

For the oscillation equation  $F(\psi) = i\kappa\psi$ , so the solution is trivial. For other expressions for  $F(\psi)$ , this will not be the case!

#### Important remark:

For the backward and the trapezoidal scheme,  $F(\phi^{n+1})$  is needed to compute  $\phi^{n+1}$ :

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Implicit schemes are much more stable, but the cost-per-timestep is higher.

Some examples of challenges for implicit schemes:

• nonlinear systems, e.g.  $F(\psi) = \sin(\psi)$ 

$$\frac{\phi^{n+1}-\phi^n}{\Delta t} = \frac{1}{2}\sin\left(\phi^n\right) + \frac{1}{2}\sin\left(\phi^{n+1}\right)$$

This usually has to be solved iteratively.

Some examples of challenges for implicit schemes:

- nonlinear systems
- systems with multiple variables become *coupled*, e.g. shallow water equations with 2 variables *u* and *h* (cfr. Lesson 5):

$$\frac{u^{n+1} - u^n}{\Delta t} = -g \frac{\partial}{\partial x} \left( h^n + h^{n+1} \right)$$
$$\frac{h^{n+1} - h^n}{\Delta t} = -H \frac{\partial}{\partial x} \left( u^n + u^{n+1} \right)$$

A linear system has to be solved.

Some examples of challenges for implicit schemes:

- nonlinear systems
- systems with multiple variables become coupled
- for systems involving spatial derivatives, the gridpoints become coupled, e.g. advection equation:

$$\frac{\phi_j^{n+1} - \phi_j^n}{\Delta t} = -\frac{c}{2} \left( \frac{\phi_{j+1}^n - \phi_{j-1}^n}{2\Delta x} + \frac{\phi_{j+1}^{n+1} - \phi_{j-1}^{n+1}}{2\Delta x} \right)$$

A (LARGE!) tridiagonal system has to be solved.

Multistage methods evaluate the RHS  $F(\phi)$  several times instead of one single time.

Example: Heun scheme (also called Runge-Kutta-2) which replaces  $\phi^{n+1}$  in the RHS of the trapezium scheme by a forward estimate:

$$\begin{split} \tilde{\phi}^{n+1} &= \phi^n + \Delta t F(\phi^n) \\ \phi^{n+1} &= \phi^n + \frac{\Delta t}{2} \left[ F(\phi^n) + F(\tilde{\phi}^{n+1}) \right] \end{split}$$

forward estimate of  $\phi^{n+1}$ 

trapezium-like timestep

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**Exercise**: what is the amplification factor of the Heun scheme applied to the oscillation equation  $F(\psi) = i\kappa\psi$ ?

Substituting  $F(\psi) = i\kappa\psi$  in the Heun scheme gives:

$$\begin{split} \tilde{\phi} &= (1 + i\kappa \Delta t)\phi^n \\ \phi^{n+1} &= \phi^n + \frac{i\kappa \Delta t}{2} \left(\phi^n + \tilde{\phi}\right) \end{split}$$

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Substituting  $\tilde{\phi}$  in the second equation gives

$$\phi^{n+1} = \left(1 + i\kappa\Delta t - \frac{(\kappa\Delta t)^2}{2}\right)\phi^n$$

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So the amplification factor is

$$A = \frac{\phi^{n+1}}{\phi^n} = 1 + i\kappa\Delta t - \frac{1}{2}(\kappa\Delta t)^2$$

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So the amplification factor is

$$A = \frac{\phi^{n+1}}{\phi^n} = 1 + i\kappa\Delta t - \frac{1}{2}(\kappa\Delta t)^2$$

which is second-order accurate (compare with Taylor expansion of exact amplification factor).

The modulus is

$$|A|^2=1+rac{1}{4}\left(\kappa\Delta t
ight)^4>1$$

So the Heun scheme is unconditionally unstable!

#### Multistage methods: Matsuno scheme

The Matsuno scheme combines a forward estimate with a backward step:

$$ilde{\phi}^{n+1} = \phi^n + \Delta t F(\phi^n)$$
 forward estimate of  $\phi^{n+1}$   $\phi^{n+1} = \phi^n + \Delta t F(\tilde{\phi}^{n+1})$  backward-like timestep

The amplification factor is

$$A = 1 + i\kappa\Delta t - (\kappa\Delta t)^2$$

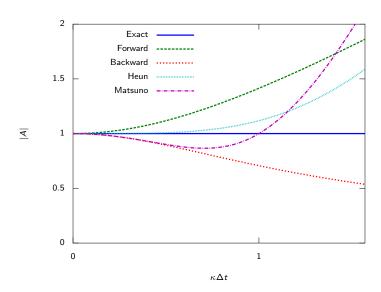
which is first-order accurate.

The modulus is

$$|A|^2 = 1 - (\kappa \Delta t)^2 + (\kappa \Delta t)^4$$

So the Matsuno scheme is conditionally stable:  $\kappa \Delta t < 1$ 

# Multistage methods: amplification



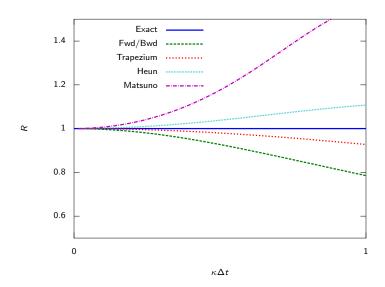
## Multistage methods: phase change

Approximated for  $\kappa \Delta t \ll 1$ ,

$$R_{\mathsf{Heun}} pprox 1 + rac{1}{6} \left( \kappa \Delta t 
ight)^2 \ R_{\mathsf{Matsuno}} pprox 1 + rac{2}{3} \left( \kappa \Delta t 
ight)^2$$

So the Heun scheme has less phase change than the Matsuno scheme.

# Multistage methods: phase change



#### Multistage methods: Runge-Kutta-4

The following scheme is quite popular because it's 4th order accurate:

$$q_1 = \Delta t F(\phi^n)$$

$$q_2 = \Delta t F(\phi^n + q_1/2)$$

$$q_3 = \Delta t F(\phi^n + q_2/2)$$

$$q_4 = \Delta t F(\phi^n + q_3)$$

$$\phi^{n+1} = \phi^n + \frac{1}{6}(q_1 + 2q_2 + 2q_3 + q_4)$$

This scheme is conditionally stable ( $|\kappa \Delta t| < 2.828$ ).

The drawback of multistage methods is that the right hand side  $F(\psi)$  needs to be evaluated several times. This makes them suitable for toy-models, but not for operational 3D NWP models.

It is possible to reuse information from the previous timestep  $\phi^{n-1}$ :

$$\phi^{n+1} = \alpha_1 \phi^n + \alpha_2 \phi^{n-1} + \beta_1 \Delta t F(\phi^n) + \beta_2 \Delta t F(\phi^{n-1})$$

Such a scheme will be at least second-order if

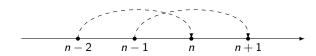
$$\alpha_1 = 1 - \alpha_2$$
  $\beta_1 = \frac{1}{2}(\alpha_2 + 3)$   $\beta_2 = \frac{1}{2}(\alpha_2 - 1)$ 

We limit ourselves to the following (second order) schemes:

	$\alpha_1$	$\alpha_2$	$\beta_1$	$\beta_2$
Leapfrog	0	1	2	0
Adams-Bashforth	1	0	$\frac{3}{2}$	$-\frac{1}{2}$

The leapfrog scheme for the oscillation equation:

$$\phi^{n+1} = \phi^{n-1} + 2i\kappa \Delta t \phi^n$$



The amplification factor satisfies

$$A^2 - 2i\kappa\Delta tA - 1 = 0$$

SO

$$A_{\pm} = i\kappa\Delta t \pm \sqrt{1 - \kappa^2 \Delta t^2}$$

which is second-order accurate.

There are 2 solutions corresponding to 2 'modes'. If  $\kappa\Delta t\to 0$  then  $A_+\to 1$  and  $A_-\to -1$ . Therefore,

$$A_+ \sim ext{physical mode}$$

 $A_ \sim$  purely artificial 'computational' mode

- If  $|\kappa \Delta t| \le 1$ ,  $|A_+| = |A_-| = 1$  so the scheme is stable.
- If  $\kappa \Delta t > 1$

$$|A_{+}| = \left|i\kappa\Delta t + i\sqrt{\left(\kappa^{2}\Delta t^{2} - 1
ight)}
ight| > |i\kappa\Delta t| > 1$$

So the scheme is unstable.

• If  $\kappa \Delta t < -1$  then  $|A_-| > 1$  so the computational mode is unstable.

The computational mode is easy to analyse in the case  $\kappa = 0$ :

$$\phi^{n+1} = \phi^{n-1}$$

and the roots are  $A_+ = 1, A_- = -1$ For the initial condition  $\phi^0 = C$ :

$$\phi^2 = \phi^4 = \phi^6 = \dots = C$$

 $\phi^1$  is usually determined by another two-time-level scheme:  $\phi^1=C+\epsilon$  with  $\epsilon$  some error. Then

$$\phi(t) = \{ C, C + \epsilon, C, C + \epsilon, C, C + \epsilon \dots \}$$

So the error  $\epsilon$  stays in the solution.

The relative phase change of the physical mode of the leapfrog scheme is given by

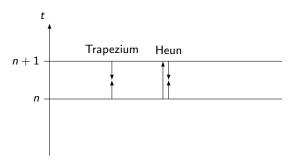
$$egin{align*} R_{\mathsf{leapfrog}} &= rac{1}{\kappa \Delta t} rctan \left( rac{\kappa \Delta t}{\sqrt{1 - \kappa^2 \Delta t^2}} 
ight) \ &pprox 1 + rac{1}{6} \left( \kappa \Delta t 
ight)^2 \end{aligned}$$

So the leapfrog scheme is accelerating.

#### 3TL schemes: Adams-Bashforth

The trapezium scheme is very attractive (neutral, 2nd order, small phase error), but it is implicit: it requires  $F(\phi^{n+1})$  to determine  $\phi^{n+1}$ .

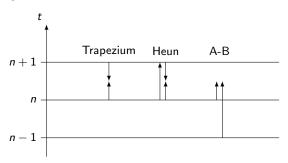
The Heun scheme attempts to approximate the trapezium scheme by using a forward estimate in the RHS:



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The Adams-Bashforth scheme estimates  $F\left(\phi^{n+\frac{1}{2}}\right)$  by extrapolating from  $F\left(\phi^{n}\right)$  and  $F\left(\phi^{n-1}\right)$ .

The Adams-Bashforth scheme writes:

$$F\left(\phi^{n+\frac{1}{2}}\right) = \frac{3}{2}F\left(\phi^{n}\right) - \frac{1}{2}F\left(\phi^{n-1}\right)$$
$$\phi^{n+1} = \phi^{n} + \Delta t F\left(\phi^{n+\frac{1}{2}}\right)$$

For the oscillation equation, the amplification factor satisfies

$$\emph{A}^2 - \left(1 + \frac{3}{2}i\kappa\Delta t\right)\emph{A} + \frac{1}{2}i\kappa\Delta t = 0$$

with two modes.

$$A_{\pm}=rac{1}{2}\left[1+rac{3}{2}i\kappa\Delta t\pm\sqrt{1-rac{9}{4}\left(\kappa\Delta t
ight)^{2}+i\kappa\Delta t}
ight]$$

#### 3TL schemes: Adams-Bashforth

For good temporal resolution  $\kappa \Delta \leq 1$ ,

$$egin{aligned} |A_{+}|_{ ext{A-B2}} &pprox 1 + rac{1}{4} \left(\kappa \Delta t
ight)^4 \ |A_{-}|_{ ext{A-B2}} &pprox rac{1}{2} \kappa \Delta t \ R_{ ext{A-B2}} &pprox 1 + rac{5}{12} \left(\kappa \Delta t
ight)^2 \end{aligned}$$

In NWP application we want strict stability, so this weak instability makes Adams-Bashforth unattractive.

In contrast, the leapfrog mode contains the artificial computational mode. However, this mode can be controlled by a Robert-Asselin filter.

#### The Robert-Asselin filter

We modify the leapfrog-scheme by adding a filter step:

$$\phi^{n+1} = \overline{\phi^{n-1}} + 2\Delta t F(\phi^n)$$
$$\overline{\phi^n} = \phi^n + \gamma \left( \overline{\phi^{n-1}} - 2\phi^n + \phi^{n+1} \right)$$

normal leapfrog

apply filter

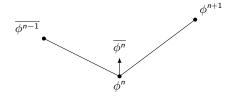
where typically  $\gamma=0.06$  in meteorological models.

We modify the leapfrog-scheme by adding a filter step:

$$\begin{split} \phi^{n+1} &= \overline{\phi^{n-1}} + 2\Delta t F(\phi^n) & \text{normal leapfrog} \\ \overline{\phi^n} &= \phi^n + \gamma \left( \overline{\phi^{n-1}} - 2\phi^n + \phi^{n+1} \right) & \text{apply filter} \end{split}$$

where typically  $\gamma = 0.06$  in meteorological models.

The term  $\overline{\phi^{n-1}}-2\phi^n+\phi^{n+1}$  can be interpreted as a temporal filter that damps the high frequencies (esp. the  $2\Delta t$ -mode): if  $\overline{\phi^{n-1}}>\phi^n$  and  $\phi^{n+1}>\phi^n$ , then  $\overline{\phi^n}$  will be increased:



Amplification of Asselin-leapfrog:

$$A_{\pm} = \gamma + i\kappa\Delta t \pm \sqrt{(1-\gamma)^2 - \kappa^2\Delta t^2}$$

For small  $\kappa \Delta t$ ,

$$egin{aligned} A_{+} &pprox 1 + i\kappa\Delta t - rac{(\kappa\Delta t)^2}{2(1-\gamma)} \ A_{-} &pprox -1 + 2\gamma + i\kappa\Delta t + rac{(\kappa\Delta t)^2}{2(1-\gamma)} \end{aligned}$$

while expansion of the exact solution is:

$$A_e = e^{i\kappa\Delta t} = 1 + i\kappa\Delta t - \frac{1}{2}(\kappa\Delta t)^2 - i\frac{1}{6}(\kappa\Delta t)^3 + O[(\kappa\Delta t)^4]$$

So the Robert-Asselin filter degrades the accuracy of the scheme from 2nd order to 1st order.

The modulus of the amplification factor becomes:

$$egin{split} |A_+| &pprox 1 - rac{\gamma}{2(1-\gamma)}(\kappa \Delta t)^2 \ |A_-| &pprox (1-2\gamma) + rac{\gamma}{2-6\gamma+4\gamma^2}(\kappa \Delta t)^2 \end{split}$$

Note that the computational mode is (slightly) damped.

The relative phase change becomes:

$$R_+pprox 1+rac{1+2\gamma}{6(1-\gamma)}(\kappa\Delta t)^2$$

#### Summary

- We work on the oscillation equation, to focus on the time differencing aspect
- A scheme is characterized by
  - amplitude: amplifying, neutral or damping
  - relative phase change: accelerating or decelerating
  - explicitness or implicitness
  - order of accuracy
- Concrete examples:
  - ► Two time-level schemes: forward, backward, trapezium
  - Multistage schemes: Heun, Matsuno, Runge-Kutta-4
  - ► Three time-level schemes: leapfrog and Adams-Bashforth
    - ⇒ computational mode, filter
- There is no 'best' scheme: every scheme has disadvantages.
- What matters is methodology!