Abelian Sandpile Basics

2018

Abelian Sandpile Model

- ▶ Rough model of a pile of sand, based on a finite directed (multi-) graph *G*, with vertices *V* and edges *E*.
- Chips (grains of sand) are stacked on the vertices.
- ▶ Chips can flow to other vertices via edges of *G*.
- Originally studied on uniform grids.
- Also known as the chip-firing game.

Chip-Firing

- Let n_i be the number of chips on vertex v_i
- ▶ Let $e_i = \{e \in E : e \text{ starts at } v_i\}$
- ▶ If a vertex $n_i \ge |e_{v_i}|$ it can **fire**.
- When a vertex fires, it transfers a chip down each of its outbound edges.

Chip-Firing Example

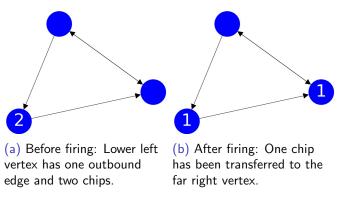


Figure: Firing example.

Chip Configuration

- ▶ A **configuration** is the set of pairs $\{(v_i, n_{i,t}) : v_i \in V\}$, where $n_{i,t}$ is the number of chips on v_i at time/iteration t.
- If we fix an ordering of V, use a vector: $c_t = (n_{0,t}, n_{1,t}, ..., n_{N,t})$

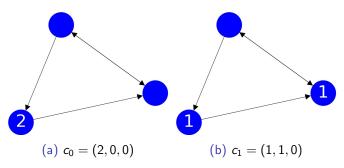
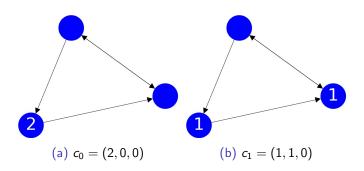


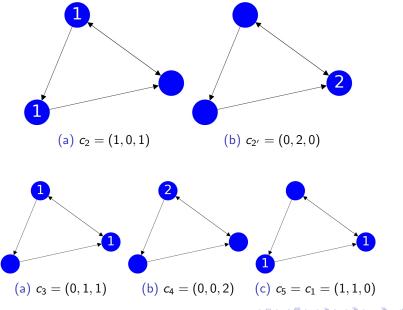
Figure: Vertices indexed counter-clockwise starting from lower left vertex

Does it Stabilize?

- A configuration is **stable** if none of the vertices can be fired, e.g. n_i < |e_{v_i}| ∀ i.
- Stabilization is a sequence of vertex firings that result in a stable configuration.



Is it stable?



A Sink Vertex

- A vertex v of G with no outbound edges ($e_v = 0$) is known as a **sink**.
- Sink vertices never fire.
- If every vertex has a direct path to a sink it is the universal sink.
- ► **Every** configuration on a directed graph with a universal sink stabilizes.
- From now on, all graphs will have a universal sink.

Sink Example

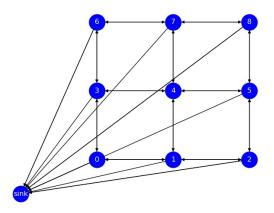


Figure: Directed graph with a sink. $|e_{v_i}| = 4$ for all non-sink vertices. Vertices are labeled with their index/ID.

Chip Configuration Revisited

▶ The sink vertex is excluded from the configuration vector

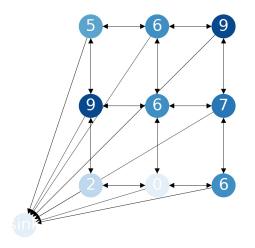


Figure: $c_t = (2, 0, 6, 9, 6, 7, 5, 6, 9)$, indexed as on previous slide.

Reduced Laplacian

▶ *D* is the out-degree matrix of *G*:

$$D_{i,j} = \left\{ \begin{array}{cc} |e_{v_i}| & : i = j \\ 0 & : i \neq j \end{array} \right.$$

- $ightharpoonup e_{v_i,v_j} = \text{edges from } v_i \text{ to } v_j$
- ▶ *A* is the adjacency matrix of *G*:

$$A_{i,j} = \left\{ egin{array}{ll} |e_{v_i,v_j}| & : i
eq j \\ 0 & : ext{ otherwise} \end{array}
ight.$$

▶ The **reduced Laplacian** is the matrix L = D - A with rows/columns corresponding to the sink removed.

Reduced Laplacian Example

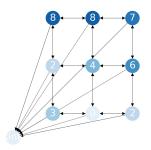


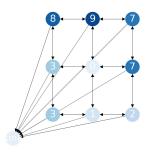
Firing and the Reduced Laplacian

- Let L_i be the row of the reduced Laplacian corresponding to v_i
- ▶ If vertex *v_j* fires at time/iteration *t*:

$$c_{t+1} = c_t - L_j$$

$$L_4 = (0, -1, 0, -1, 4, -1, 0, -1, 0)$$





$$c_t = (3, 0, 2, 2, 4, 6, 8, 8, 7)$$
 $c_{t+1} = (3, 1, 2, 3, 0, 7, 8, 9, 7)$

Stabilizing Flipbook

Firing History

- ► The vertices fired were: [0, 1, 2, 1, 0, 2, 3, 3, 4, 4, 1, 5, 4, 5, 6, 3, 0, 6, 7, 7, 4, 5, 2, 1, 7, 6, 3, 4, 8, 8, 5, 7, 8]
- ► The **history** is the number of times each vertex fired in a stabilization:

```
\{0: 3, 1: 4, 2: 3, 3: 4, 4: 5, 5: 4, 6: 3, 7: 4, 8: 3\}
```

An Alternate Stabilizing Flipbook

Firing History

- ► The vertices fired were: [8, 7, 6, 7, 8, 6, 5, 5, 4, 4, 7, 3, 4, 3, 2, 5, 8, 2, 1, 1, 4, 3, 6, 7, 1, 2, 5, 4, 0, 0, 3, 1, 0]
- history:

```
\{0: 3, 1: 4, 2: 3, 3: 4, 4: 5, 5: 4, 6: 3, 7: 4, 8: 3\}
```

- **▶** !
- From a given starting configuration, all stabilizations reach the same final configuration
- Each vertex fires the same number of times in all stabilizations

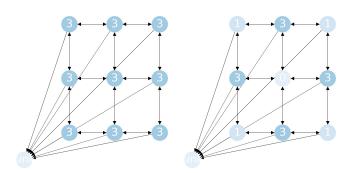
Chip Addition Operator

- ▶ If c is a configuration, let c^o denote its stabilization.
- Let $\mathbb{1}_{v_i}$ denote the configuration with 1 chip on v_i and 0 on all others.
- ▶ The **chip addition operator**, $E_{v_i}(c)$ adds one chip to c on the vertex v_i , then stabilizes:

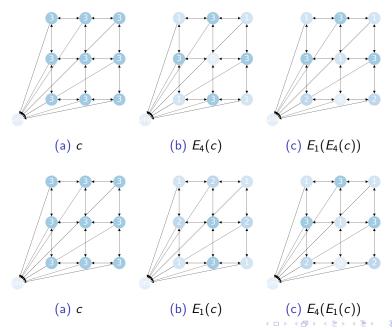
$$E_{v_i}(c) = (c + \mathbb{1}_{v_i})^o$$

Chip Addition Operator Example

- c = (3, 3, 3, 3, 3, 3, 3, 3, 3, 3)
- $E_4(c) = (1,3,1,3,0,3,1,3,1)$
- ► History: {0: 1, 1: 1, 2: 1, 3: 1, 4: 2, 5: 1, 6: 1, 7: 1, 8: 1}



Chip Addition Operator Composition



Abelian Sandpile Model

- Move chips on a directed graph
- Stabilization is well defined
- Chip firing operators commute
- Sink vertex
- Next up, self-optimized criticality