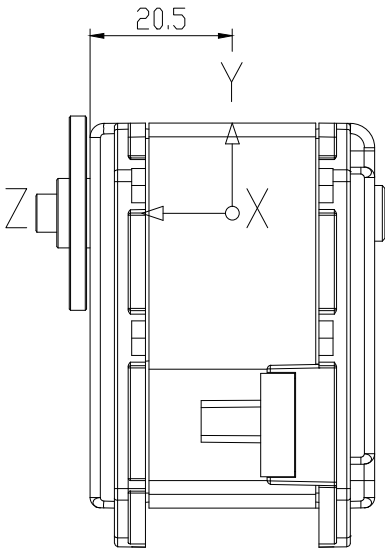
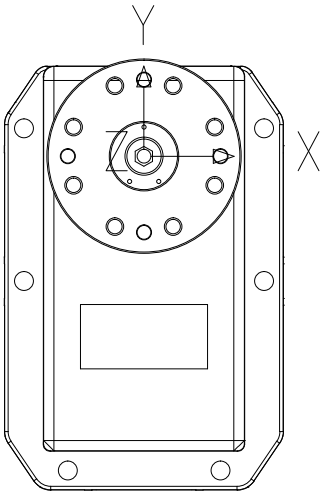


WEIGHT  
129.5g

CENTER OF GRAVITY with respect to coordinate frame:  
X Y Z 1.5830659e-01 -1.7024195e+01 1.6784123e+00 MM

INERTIA at CENTER OF GRAVITY with respect to coordinate frame: (GRAM \* MM^2)

INERTIA TENSOR:  
Ixx Ixy Ixz 5.6457584e+04 -6.5234321e+02 6.4699697e+02  
Iyx Iyy Iyz -6.5234321e+02 2.9325728e+04 -5.8929492e+03  
Izx Izy Izz 6.4699697e+02 -5.8929492e+03 4.5111809e+04



[FOR REFERENCE ONLY]

Title		Material	Scale	Unit	Sheet	ROBOTS
RX-64						
DC05_M901	Date		NOMSCALE	MM	3 of 3	

