



# Background subtraction and Morphological operation

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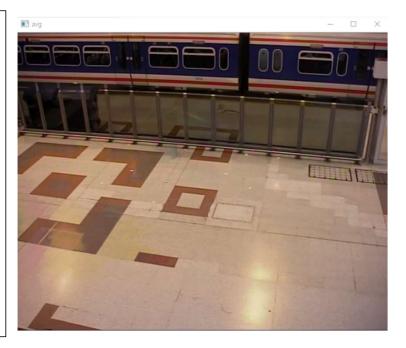
- Example code
  - Generating average image

```
int main() {
    VideoCapture capture("background.mp4");
    Mat image, sum, avg;
    int cnt = 2;

    capture >> avg;

    while (true) {
        if (!capture.read(image)) break;
        add(image / cnt, avg*(cnt - 1) / cnt, avg);

        imshow("avg", avg);
        cnt++;
        waitKey(33);
    }
}
```





Example code(using absdiff)

```
int main() {
      VideoCapture capture("background.mp4");
      Mat background, image, gray, result, foregroundMask, foregroundImg;
      //set the first frame as background
      capture >> background;
      cvtColor(background, background, CV_BGR2GRAY);
      while (true) {
             if (capture.grab() == 0) break;
             capture.retrieve(image);
             cvtColor(image, gray, CV_BGR2GRAY);
             absdiff(background, gray, foregroundMask);
             threshold(foregroundMask, foregroundMask, 50, 255, CV THRESH BINARY);
             foregroundMask.copyTo(foregroundImg);
             gray.copyTo(foregroundImg, foregroundMask);
             imshow("foregroundImg", foregroundImg);
             imshow("foregroundMask", foregroundMask);
             imshow("background", background);
             waitKey(33);
```















• Example code(using absdiff)











- Example code
  - openCV MoG2

```
int main() {
      Ptr<BackgroundSubtractor> bg model = createBackgroundSubtractorMOG2();
      Mat image, foregroundMask, backgroundImg, foregroundImg;
      VideoCapture cap("background.mp4");
      while (true) {
            cap >> image;
            resize(image, image, Size(640, 480));
            if (foregroundMask.empty())
                  foregroundMask.create(image.size(), image.type());
            // image: Next video frame. Floating point frame will be used without scaling and //should be in range [0,255].
            // foregroundMask: The output foreground mask as an 8-bit binary image.
            bg model->apply(image, foregroundMask);
            GaussianBlur(foregroundMask, foregroundMask, Size(11, 11), 3.5, 3.5);
            threshold(foregroundMask, foregroundMask, 10, 255, THRESH_BINARY);
            foregroundImg = Scalar::all(0);
            image.copyTo(foregroundImg, foregroundMask);
            // backgroundImg: The output background image.
            bg_model->getBackgroundImage(backgroundImg);
```







- Example code
  - openCV MoG2

```
imshow("foreground mask", foregroundMask);
imshow("foreground image", foregroundImg);
if (!backgroundImg.empty()) {
     imshow("mean background image", backgroundImg);
waitKey(33);
```



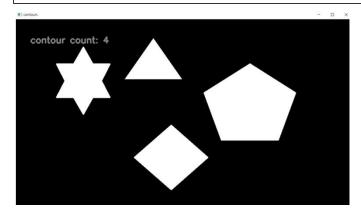




# Counting the number of objects

```
int main() {
    Mat gray = imread("contours.png", 0);
    Mat result;
    threshold(gray, result, 230, 255, THRESH_BINARY_INV);
    vector < vector < Point > > contours;
    vector < Vec4i > hierarchy;
    findContours(result, contours, hierarchy, CV_RETR_EXTERNAL, CV_CHAIN_APPROX_SIMPLE);

    putText(result, format("contour count: %d", contours.size()), Point(50, 80), FONT_HERSHEY_SIMPLEX, 1, Scalar(12 8), 4);
    imshow("contours", result);
    waitKey(0);
}
```











# University Net votor of objects

#### Retrival Modes

Enumerator		
RETR_EXTERNAL Python: cv.RETR_EXTERNAL	retrieves only the extreme outer contours. It sets <code>hierarchy[i][2]=hierarchy[i][3]=-1</code> for all the contours.	
RETR_LIST Python: cv.RETR_LIST	retrieves all of the contours without establishing any hierarchical relationships.	
RETR_CCOMP Python: cv.RETR_CCOMP	retrieves all of the contours and organizes them into a two-level hierarchy. At the top level, there are external boundaries of the components. At the second level, there are boundaries of the holes. If there is another contour inside a hole of a connected component, it is still put at the top level.	
RETR_TREE Python: cv.RETR_TREE	retrieves all of the contours and reconstructs a full hierarchy of nested contours.	
RETR_FLOODFILL Python: cv.RETR_FLOODFILL		

### Approximation modes

Enumerator	
CHAIN_APPROX_NONE Python: cv.CHAIN_APPROX_NONE	stores absolutely all the contour points. That is, any 2 subsequent points $(x1,y1)$ and $(x2,y2)$ of the contour will be either horizontal, vertical or diagonal neighbors, that is, $max(abs(x1-x2),abs(y2-y1))==1$ .
CHAIN_APPROX_SIMPLE Python: cv.CHAIN_APPROX_SIMPLE	compresses horizontal, vertical, and diagonal segments and leaves only their end points. For example, an up-right rectangular contour is encoded with 4 points.
CHAIN_APPROX_TC89_L1 Python: cv.CHAIN_APPROX_TC89_L1	applies one of the flavors of the Teh-Chin chain approximation algorithm [201]
CHAIN_APPROX_TC89_KCOS Python: cv.CHAIN_APPROX_TC89_KCOS	applies one of the flavors of the Teh-Chin chain approximation algorithm [201]





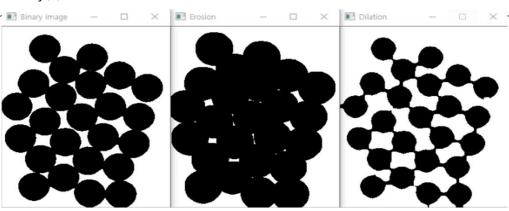
# Counting the number of objects

```
int main() {
     Mat gray = imread("contours.png", 0);
     Mat result:
     threshold(gray, result, 180, 255, THRESH BINARY INV);
     vector<vector<Point>> contours;
     vector < Vec4i > hierarchy;
     findContours(result, contours, hierarchy, CV RETR EXTERNAL, CV CHAIN APPROX SIMPLE);
     //defining bounding rectangle
     vector<Rect> boundRect(contours.size());
     for (int i = 0; i < contours.size(); i++)
           boundRect[i] = boundingRect(Mat(contours[i]));
     //draw rectangles on the contours
     for (int i = 0; i < contours.size(); i++)
           rectangle(result, boundRect[i].tl(), boundRect[i].br(), Scalar(0, 0, 255), 2, 8, 0);
     imshow("contours", result);
     waitKey(0);
```



## Erosion and dilation

```
Mat image, erosion, dilation;
Mat element = getStructuringElement(MORPH_ELLIPSE, Size(10, 10));
//Other options:MORPH_RECT, MORPH_CROSS
image = imread("water_coins.jpg", 0);
threshold(image, image, 128, 255, THRESH_BINARY);
erode(image, erosion, element);
dilate(image, dilation, element);
imshow("Binary image", image);
imshow("Erosion", erosion);
imshow("Dilation", dilation);
waitKey(0);
                          Erosion
                                                    Dilation
```











## Erosion and dilation

```
Mat image, opening, closing, element;
image = imread("water_coins.jpg", 0);
threshold(image, image, 128, 255, THRESH_BINARY);
element = getStructuringElement(MORPH_ELLIPSE, Size(7, 7));
morphologyEx(image, closing, MORPH_CLOSE, element);
morphologyEx(image, opening, MORPH_OPEN, element);
imshow("Binary image", image);
imshow("opening", opening);
imshow("closing", closing);
waitKey(0);
```

