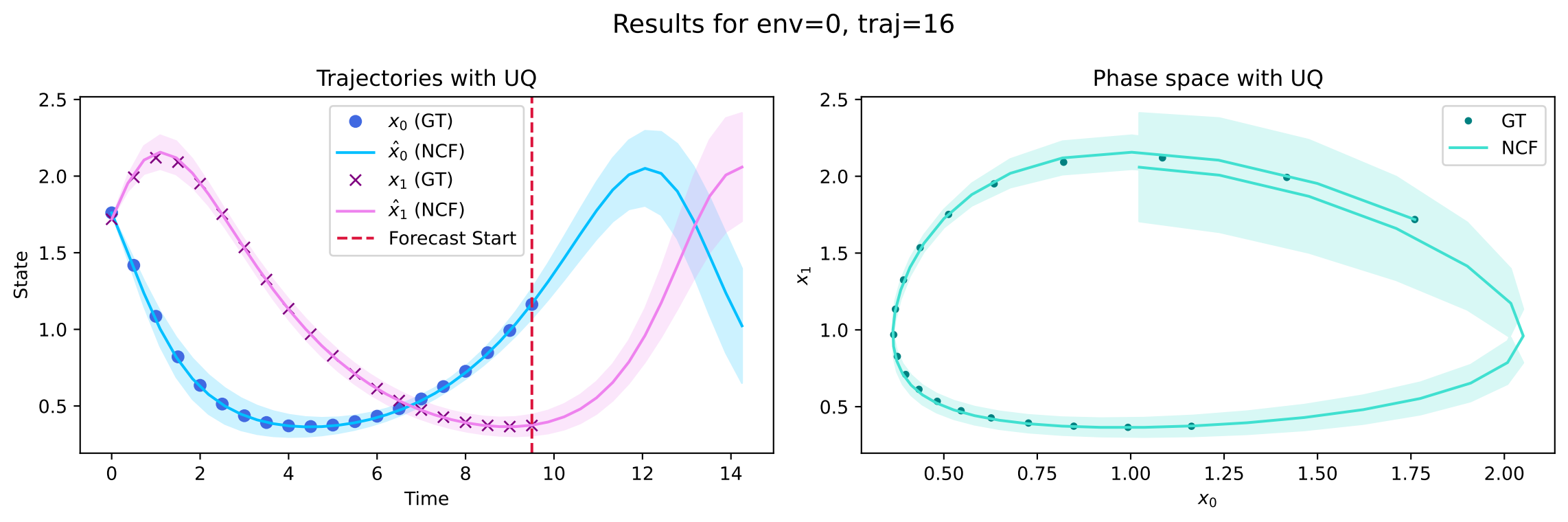
Results for env=0, traj=16
Trajectories with UQ
x_0 (GT)
$\hat{x}_0$ (NCF)
x_1 (GT)
$\hat{x}_1$ (NCF)
Forecast Start
State
Time
Phase space with UQ
GT
NCF
x_1
x_0