

## Problem Set #2: RB for Linear Affine Elliptic

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Course: *Calcul Scientifique 3* – Professor: *Pr. Christophe Prud'homme*  
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### Question a)

Show that the operation count for the on-line stage of your code is independent of  $N$ .

For each step of the online stage, let's count the number of floating point operations (multiplications and additions):

1. Form  $A_N(\mu)$  from  $A_N(\mu) = \sum_{q=1}^Q \Theta^q(\mu) A_N^q$ : requires  $QN^2$  multiplications, and  $(Q-1)N^2$  additions, hence  $(2Q-1)N^2$  flops in total
2. Solve the  $N \times N$  linear system  $A_N(\mu)u_N(\mu) = F_N$ : requires at most  $N^3$  flops. In the case of the  $LU$  decomposition (where  $L$  has 1's along its diagonal), the cost of the decomposition is  $\frac{2N^3}{3} - \frac{N^2}{2} - \frac{N}{6}$  flops, the cost for the descent algorithm is  $N(N+1)$ , and the cost for the ascent is  $N(N+1) + N$
3. Evaluate the output  $T_{rootN}(\mu) = L_N^T u_N(\mu)$ : requires  $2N-1$  flops as a dot product

In conclusion, the operation count for the on-line stage is independent of  $N$ , it is equal to

$$(2Q-1)N^2 + \frac{2N^3}{3} - \frac{N^2}{2} - \frac{N}{6} + 2N(N+1) + N + 2N - 1$$

which yields

$$\frac{2}{3}N^3 + (2Q + \frac{1}{2})N^2 + \frac{29}{6}N - 1$$

roughly equal to

$$c_1 N^{\gamma_1} + c_2 N^{\gamma_2} + c_3 N^{\gamma_3}$$

with:

$$\begin{cases} c_1 = \frac{29}{6}, & \gamma_1 = 1 \\ c_2 = 2Q + \frac{1}{2}, & \gamma_2 = 2 \\ c_3 = \frac{2}{3}, & \gamma_3 = 3 \end{cases} \quad (Q = 6)$$

### Question b)

1.

Generate the reduced basis matrix  $Z$  and all necessary reduced basis quantities.

For  $N = 8$ ,  $\mu = 1$  and  $\mu = 10$ , let's compare the condition number of  $A_N(\mu)$ , noted  $\text{Cond}(A_N(\mu))$ , when the  $Z$  matrix is taken directly from the "snapshots" (No G-S), and when  $Z$  is orthonormalized using the Gram-Schmidt (G-S) process.  $\gamma$  and  $\alpha$  are respectively the continuity (Lipschitz constant) and the coercivity constants for  $A_N$ .

■  $\mu = 1$ :

- **No G-S**:  $\text{Cond}(A_N(\mu)) = 33575189921.6$
- **with G-S**:  $\text{Cond}(A_N(\mu)) = 1.0000000000959741$
- **Upper bound**:  $\frac{\gamma(\mu)}{\alpha(\mu)} = 1.0000000000000868$

■  $\mu = 10$ :

- **No G-S**:  $\text{Cond}(A_N(\mu)) = 23018985185.0$
- **with G-S**:  $\text{Cond}(A_N(\mu)) = 9.9286$
- **Upper bound**:  $\frac{\gamma(\mu)}{\alpha(\mu)} = 10.000$

It can be observed that the condition number is bounded by a function of  $\mu$  when the Gram-Schmidt orthonormalization is applied to  $Z$  (specifically  $\mu \mapsto \frac{1}{\mu}$  if  $\mu < 1$  and  $\mu \mapsto \mu$  if  $\mu \geq 1$ ).

This fits the results from the previous Problem Set, indicating that  $\frac{\gamma(\mu)}{\alpha(\mu)}$  should be an upper bound for  $A_N$ 's condition number (the upper bound is computed by solving a generalized eigen value problem  $(A_N(\mu) - \lambda A_N(\bar{\mu}))x = 0$ , for  $x \in X^e$ ).

**Without orthonormalization:** Since  $\mu_1, \mu_2$  were taken as snapshots to build the RB basis, one component of  $u_N(\mu_1)$  and  $u_N(\mu_2)$  must be equal to 1 while all the others are close to 0. This is what is observed. As for  $\mu_3 = 1.0975$  which is not in 'sample1', the resulting  $u_N(\mu_3)$  doesn't contain 0's nor 1's. Instead, the result is a combination of all the snapshots in  $Z$ , inducing a huge loss in accuracy.

**With orthonormalization:** Here the components in  $Z$  that do not count as part of the solution are less pronounced (closer to 0). For example, since  $u_N(\mu_1)$  is the first snapshot, its first component is 1 and the rest are 0 (close to the floating point precision). The same result is observed for  $u_N(\mu_2)$ , which is a combination of the first and second snapshots.

2.

Let's verify the output.

For  $\mu = 1.5$ ,  $\text{Bi} = 0.1$ , the computed value on a coarse grid is effectively

$$T_{\text{root}N}(\mu) = 1.531074970789645$$

3.

Convergence study over a test sample.

Figure fig. 1 shows the convergence of the maximum relative error in the energy norm and the maximum relative output error as a function of  $N$ . As expected, it proves the errors decrease as our reduced basis' dimension  $N$  increases.

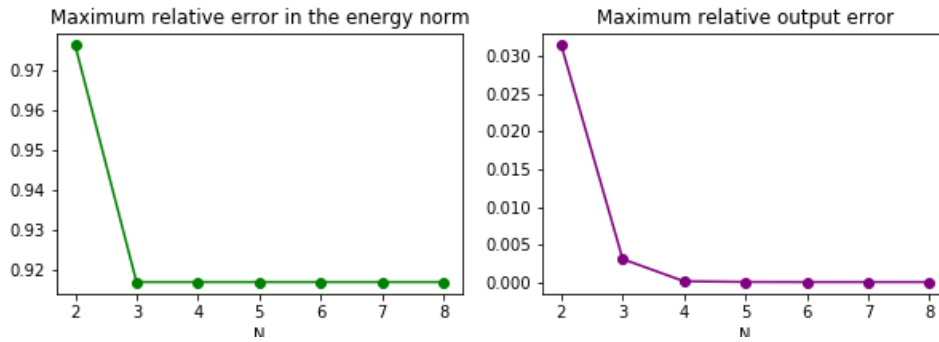


Figure 1: Maximum relative error in the energy norm and the maximum relative output error as a function of  $N$ , applied to sample 1. This plot is identical for a coarse, a medium, and fine FE triangulation

Now let's compare the convergence in energy norm (in *log* mode) when the matrix  $Z$  is (not) orthonormalized. fig. 2 shows a much faster convergence (and a considerably lower error) when the matrix  $Z$  is orthonormalized. This justifies the use of orthonormalization since question *b*)1.

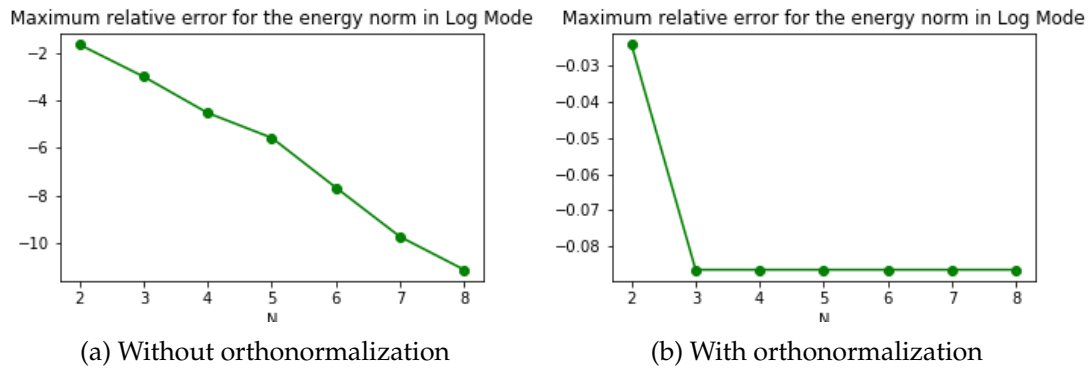


Figure 2: Comparison of energy norm error convergence in log mode when the RB matrix  $Z$  is orthonormalized, and when it is not.

4.

Average CPU time comparison.

From fig. 3, the relation between the computation and  $N$  cannot easily be deduced. However, it clearly indicates how much faster the reduced basis' online stage is, compared to the finite element's computation of the exact solution.

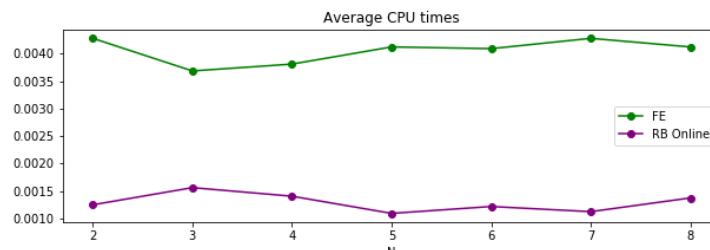


Figure 3: Average CPU time over test sample1 required to solve the reduced basis online stage with direct solution of the FE approximation as a function of  $N$ . This comparison is only valid on a coarse FE triangulation

5.

Required value of  $N$  for a 1% accuracy.

On a coarse triangulation, as long as  $N$  is greater or equal to 2, we have a relative accuracy of less than 1%. Moreover, the average time saving in terms on CPU time (compared to the FE method's computation) is about 0.0028125 seconds.

6.

Dependence of  $\mathcal{N}$  on the results.

Repeating steps 3. to 5. on medium and fine triangulations we get the following results.

■ COARSE:

- Maximum relative errors: see fig. 1
- CPU Time comparison: see fig. 3
- Achieved accuracy: 0.3056515255907647 %
- Required  $N$ : 3
- CPU time savings: 0.002864583333333327 sec

■ MEDIUM:

- Maximum relative errors: see fig. 1
- CPU Time comparison: see fig. 4
- Achieved accuracy: 0.3022017037569751 %
- Required  $N$ : 3
- CPU time savings: 0.012812499999999998 sec

■ FINE:

- Maximum relative errors: see fig. 1
- CPU Time comparison: see fig. 5
- Achieved accuracy: 0.300010213328605 %
- Required  $N$ : 3
- CPU time savings: 0.067875 sec

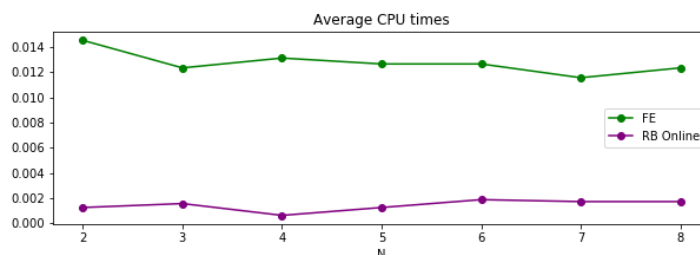


Figure 4: Average CPU time comparison on a medium FE triangulation

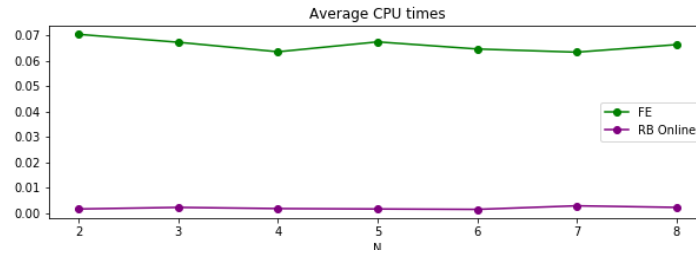


Figure 5: Average CPU time comparison on a fine FE triangulation

Unsurprisingly, the time required to compute the FE direct solution increases considerably (see figs. 3 to 5) while the time required by for the RB approximation is fairly constant around 0.002 second. This apparent non-dependence on  $N$  (on the triangulation) is once again observed on the maximum and relative errors in the RB approximation (the same figure (fig. 1) for all 3 triangulations).

As for the accuracy, we notice that while the required minimal  $N$  most still equal 3 to have a 1% output accuracy, the achieved accuracy clearly decreases with  $N$  for the wanted  $N = 3$  (a 0% accuracy means the RB approximation is identical to the exact FE computation). With this output precision increase, the CPU time saved increases. In summary, **the finer the FE triangulation, the greater the need for a reduced basis approximation**. This is exactly what was expected.

### Question c)

1.

Let's verify the output on  $\Gamma_{root}$

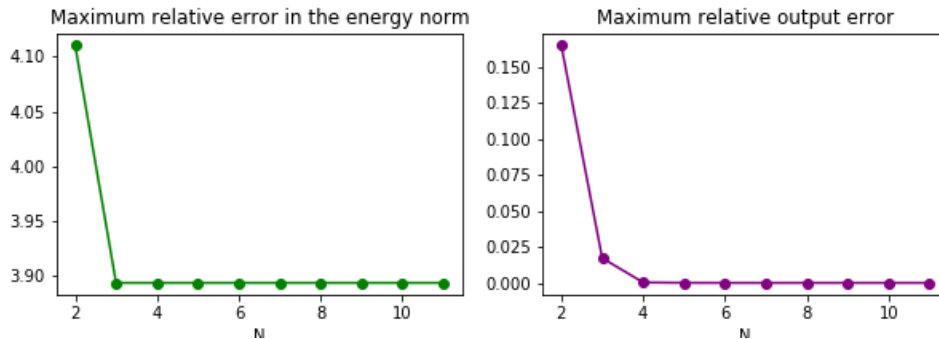
For  $\mu = 0.4, 0.6, 0.8, 1.2, 0.15$ , the computed value on a medium grid is effectively

$$T_{rootN}(\mu) = 1.51561$$

2.

Convergence study over a test sample.

Figure fig. 6 shows the convergence of the maximum relative error in the energy norm and the maximum relative output error as a function of  $N$ .


 Figure 6: Maximum relative error in the energy norm and the maximum relative output error as a function of  $N$ , applied to sample 2.

We can see that the maximum relative errors in the energy norm and output error condirebably decrease as  $N$  gets bigger.

3.

Cost minimisation.

Applying the bisection method with a tolerance of  $10^{-16}$ , we find that the optimal cost is  $C = 1.4655$ , obtained for the Biot number  $Bi = 0.40295$ .

### Question d)

1.

Convergence study over a test sample.

Figure fig. 7 shows the convergence of the maximum relative error in the energy norm and the maximum relative output error as a function of  $N$ .

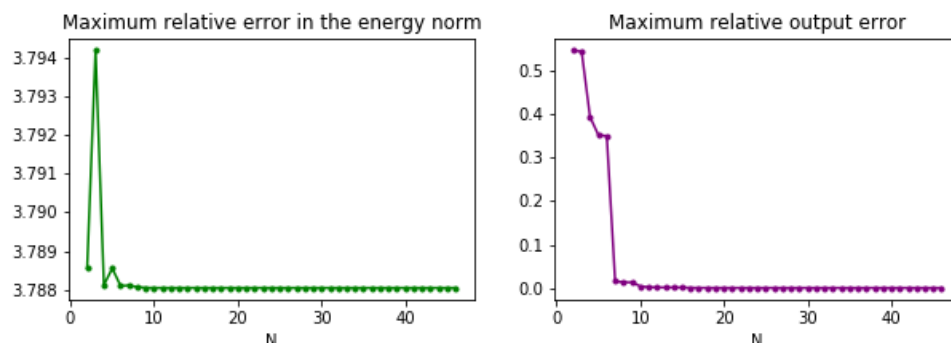


Figure 7: Maximum relative error in the energy norm and the maximum relative output error as a function of  $N$ , applied to sample 3.

As we noticed before, the maximum relative errors in the energy norm and output error decrease as  $N$  gets bigger (although not by much). However, when comparing it to figs. 1 and 6, it is clear that the errors reach quite high values.