

Geometry for NAE-DESC

Magnetic axis:

We are using Cartesian coordinates as our basis (phi is the cylindrical phi on magnetic axis, we shall try to use ϕ_c for the cylindrical angle at x)

In[*]:=

```
r0[phi_] :=  
  R0[phi] {Cos[phi], Sin[phi], 0} + Z0[phi] {0, 0, 1};
```

where we have used,

In[*]:=

```
radial = {Cos[phi], Sin[phi], 0};  
toroidal = {-Sin[phi], Cos[phi], 0};  
vertical = {0, 0, 1};
```

The Frenet-Serret basis vectors are then (note here and in rest of document, “Th” is actually referring to phi),

In[*]:=

```
normal = kR[phi] radial +  
  kTh[phi] toroidal + kZ[phi] vertical;  
binormal = tR[phi] radial +  
  tTh[phi] toroidal + tZ[phi] vertical;  
tangent = bR[phi] radial +  
  bTh[phi] toroidal + bZ[phi] vertical;
```

First order

- Definition of position:

Here the coordinate ϕ is the cylindrical ϕ on the magnetic axis.
Then, the first order displacement with respect to the axis is,

```
In[*]:= X1 = X1c[ $\phi$ ] Cos[ $\theta$ ] + X1s[ $\phi$ ] Sin[ $\theta$ ];
Y1 = Y1c[ $\phi$ ] Cos[ $\theta$ ] + Y1s[ $\phi$ ] Sin[ $\theta$ ];
x1[ $\phi$ _,  $\theta$ _] :=  $\epsilon$  X1 normal +  $\epsilon$  Y1 binormal;
```

so that,

```
In[*]:= x[ $\phi$ _,  $\theta$ _] := r0[ $\phi$ ] + x1[ $\phi$ ,  $\theta$ ];
R[ $\phi$ _,  $\theta$ _] := Sqrt[x[ $\phi$ ,  $\theta$ ][[1]]2 + x[ $\phi$ ,  $\theta$ ][[2]]2 +
    x[ $\phi$ ,  $\theta$ ][[3]]2];
Z[ $\phi$ _,  $\theta$ _] := x[ $\phi$ ,  $\theta$ ][[3]];
TanPhiCyl[ $\phi$ _,  $\theta$ _] :=  $\frac{x[ $\phi$ ,  $\theta$ ][[2]]}{x[ $\phi$ ,  $\theta$ ][[1]]};$ 
```

■ Expansion of R:

Then let us expand R in powers of ϵ , recalling that ϕ here is parametrising the axis cylindrical angle,

```
In[*]:= Clear[R1stExp]
R1stExp =
    FullSimplify[Series[R[ $\phi$ ,  $\theta$ ], { $\epsilon$ , 0, 2}]]
```

Out[*]=

$$\begin{aligned}
& \sqrt{R0[\phi]^2} + \frac{1}{\sqrt{R0[\phi]^2}} R0[\phi] \\
& (kR[\phi] (\cos[\theta] X1c[\phi] + \sin[\theta] X1s[\phi]) + \\
& \quad tR[\phi] (\cos[\theta] Y1c[\phi] + \sin[\theta] Y1s[\phi])) \\
& \epsilon + \frac{1}{2 \sqrt{R0[\phi]^2}} \\
& (kTh[\phi] (\cos[\theta] X1c[\phi] + \sin[\theta] X1s[\phi]) + \\
& \quad tTh[\phi] (\cos[\theta] Y1c[\phi] + \\
& \quad \sin[\theta] Y1s[\phi]))^2 \epsilon^2 + 0[\epsilon]^3
\end{aligned}$$

Defining a function with the expression to second order,

In[*]:=

```

R1stExpFun[ $\phi$ _,  $\theta$ _] := R0[ $\phi$ ] +
  (kR[ $\phi$ ] (Cos[ $\theta$ ] X1c[ $\phi$ ] + Sin[ $\theta$ ] X1s[ $\phi$ ]) +
    tR[ $\phi$ ] (Cos[ $\theta$ ] Y1c[ $\phi$ ] + Sin[ $\theta$ ] Y1s[ $\phi$ ]))
   $\epsilon$  +  $\frac{1}{2 R0[\phi]}$ 
  (kTh[ $\phi$ ] (Cos[ $\theta$ ] X1c[ $\phi$ ] + Sin[ $\theta$ ] X1s[ $\phi$ ]) +
    tTh[ $\phi$ ] (Cos[ $\theta$ ] Y1c[ $\phi$ ] +
      Sin[ $\theta$ ] Y1s[ $\phi$ ]))^2  $\epsilon^2$ ;

```

■ Expansion of the cylindrical angle:

It is now the turn to compute the cylindrical angle at the point of the surface that corresponds to the particular parametrisation used for the axis,

In[]:=

```
TanPhi1stExp =
  Series[TanPhiCyl[ $\phi$ ,  $\theta$ ], { $\epsilon$ , 0, 2}];
```

Which eliminating the secular ϕ piece leaves, to second order

In[]:=

```
Phi1stExp = FullSimplify[
  ArcTan[TanPhi1stExp] - ArcTan[Tan[ $\phi$ ]]]
```

Out[]:=

$$\begin{aligned} & \frac{1}{R0[\phi]} (\text{Cos}[\theta] \text{kTh}[\phi] \times X1c[\phi] + \text{kTh}[\phi] \text{Sin}[\theta] \\ & \quad X1s[\phi] + \text{Cos}[\theta] \text{tTh}[\phi] \times Y1c[\phi] + \\ & \quad \text{Sin}[\theta] \text{tTh}[\phi] \times Y1s[\phi]) \in - \frac{1}{R0[\phi]^2} \\ & \quad (\text{kR}[\phi] (\text{Cos}[\theta] X1c[\phi] + \text{Sin}[\theta] X1s[\phi]) + \\ & \quad \text{tR}[\phi] (\text{Cos}[\theta] Y1c[\phi] + \text{Sin}[\theta] Y1s[\phi])) \\ & \quad (\text{kTh}[\phi] (\text{Cos}[\theta] X1c[\phi] + \text{Sin}[\theta] X1s[\phi]) + \\ & \quad \text{tTh}[\phi] (\text{Cos}[\theta] Y1c[\phi] + \text{Sin}[\theta] Y1s[\phi])) \\ & \quad \epsilon^2 + 0[\epsilon]^3 \end{aligned}$$

From which we construct the cylindrical angle difference

$$\phi_c - \phi_{c,axis},$$

In[*]:=

Phi1stExpFun[ϕ _, θ _] :=

$$\begin{aligned} & \frac{1}{R0[\phi]} (\text{Cos}[\theta] \text{kTh}[\phi] \times X1c[\phi] + \text{kTh}[\phi] \text{Sin}[\theta] \\ & \quad \times X1s[\phi] + \text{Cos}[\theta] \text{tTh}[\phi] \times Y1c[\phi] + \\ & \quad \text{Sin}[\theta] \text{tTh}[\phi] \times Y1s[\phi]) \epsilon - \frac{1}{R0[\phi]^2} \\ & \quad (\text{kR}[\phi] (\text{Cos}[\theta] X1c[\phi] + \text{Sin}[\theta] X1s[\phi]) + \\ & \quad \text{tR}[\phi] (\text{Cos}[\theta] Y1c[\phi] + \text{Sin}[\theta] Y1s[\phi])) \\ & \quad (\text{kTh}[\phi] (\text{Cos}[\theta] X1c[\phi] + \text{Sin}[\theta] X1s[\phi]) + \\ & \quad \text{tTh}[\phi] \\ & \quad (\text{Cos}[\theta] Y1c[\phi] + \text{Sin}[\theta] Y1s[\phi])) \epsilon^2; \end{aligned}$$

- Evaluating R as a function of ϕ_c :
- Expansion of Z:
- Define $\nu = \phi_b - \phi_c$ (in terms of ϕ on axis):

We can also define $\nu = \phi_b - \phi_c$, between the boozing angle and the cylindrical angle. Of course, the cylindrical angle here is that at x. Thus, $\nu = \phi_b - \phi_c(x) = \phi_b - \phi_c(0) - (\phi_c(x) - \phi_c(0))$. Now the latter is just what we computed above for

In[*]:=

$$(*\text{nuOrder1} = -\frac{\epsilon \text{x1Th}[\phi, \theta]}{R0[\phi]}; *)$$

Second order:

- Defining position:

As we did at first order, we define the position once again, but

this time, with the same basis

```
In[*]:= ClearAll["Global'*"]
radial = {Cos[ϕ], Sin[ϕ], 0};
toroidal = {-Sin[ϕ], Cos[ϕ], 0};
vertical = {0, 0, 1};
```

defining more abstractly,

```
In[*]:= r0[ϕ_] := R0[ϕ] radial + Z0[ϕ] vertical
x1[ϕ_, θ_] :=
  ϵ ( x1R[ϕ, θ] radial + x1Th[ϕ, θ] toroidal +
      x1Z[ϕ, θ] vertical)
x2[ϕ_, θ_] :=
  ϵ2 (x2R[ϕ, θ] radial + x2Th[ϕ, θ] toroidal +
      x2Z[ϕ, θ] vertical)
```

Instead of,

In[*]:=

```
(*x2[φ_,θ_] :=
  ε² (X20[φ]+X2c[φ]Cos[2θ]+X2s[φ]Sin[2θ])
    {kR[φ]Cos[φ]-Sin[φ]kTh[φ],
     kR[φ]Sin[φ]+Cos[φ]kTh[φ],kZ[φ]}+
  ε² (Y20[φ]+Y2c[φ]Cos[2θ]+Y2s[φ]Sin[2θ])
    {tR[φ]Cos[φ]-Sin[φ]tTh[φ],
     tR[φ]Sin[φ]+Cos[φ]tTh[φ],tZ[φ]}+
  ε² (Z20[φ]+Z2c[φ]Cos[2θ]+Z2s[φ]Sin[2θ])
    {bR[φ]Cos[φ]-Sin[φ]bTh[φ],
     bR[φ]Sin[φ]+Cos[φ]bTh[φ],bZ[φ]}*)
```

Then, as before

In[*]:=

```
x[φ_, θ_] := r0[φ] + x1[φ, θ] + x2[φ, θ]
R[φ_, θ_] := Sqrt[x[φ, θ][[1]] × x[φ, θ][[1]] +
  x[φ, θ][[2]] × x[φ, θ][[2]]
Z[φ_, θ_] := x[φ, θ][[3]];
TanPhiCyl[φ_, θ_] :=  $\frac{x[\phi, \theta][[2]]}{x[\phi, \theta][[1]]}$ 
```

■ Expansion R (in terms of the cylindrical angle on axis):

Let us expand in ϵ^2 ,

In[*]:=

```
R2ndExp = Normal[
  FullSimplify[Series[R[φ, θ], {ε, 0, 3}]]]
```

Out[]:=

$$\begin{aligned}
& \sqrt{R0[\phi]^2} + \frac{\epsilon R0[\phi] \times x1R[\phi, \theta]}{\sqrt{R0[\phi]^2}} + \\
& \frac{\epsilon^2 (x1Th[\phi, \theta]^2 + 2 R0[\phi] \times x2R[\phi, \theta])}{2 \sqrt{R0[\phi]^2}} + \\
& \frac{1}{2 R0[\phi]^3} \epsilon^3 \sqrt{R0[\phi]^2} x1Th[\phi, \theta] \\
& (-x1R[\phi, \theta] \times x1Th[\phi, \theta] + \\
& 2 R0[\phi] \times x2Th[\phi, \theta])
\end{aligned}$$

In[]:=

Simplify[R2ndExp]

Out[]:=

$$\begin{aligned}
& \frac{1}{2 R0[\phi] \sqrt{R0[\phi]^2}} \\
& (2 R0[\phi]^3 - \epsilon^3 x1R[\phi, \theta] x1Th[\phi, \theta]^2 + \\
& 2 \epsilon R0[\phi]^2 (x1R[\phi, \theta] + \epsilon x2R[\phi, \theta]) + \\
& \epsilon^2 R0[\phi] \times x1Th[\phi, \theta] \\
& (x1Th[\phi, \theta] + 2 \epsilon x2Th[\phi, \theta]))
\end{aligned}$$

which we may cast into a function,

In[*]:=

```

R2ndExpFun[ϕ_, θ_] := R0[ϕ] + ε x1R[ϕ, θ] +
  
$$\frac{\epsilon^2 (x1Th[\phi, \theta]^2 + 2 R0[\phi] \times x2R[\phi, \theta])}{2 R0[\phi]} +$$

  
$$\frac{1}{2 R0[\phi]^2} \epsilon^3 x1Th[\phi, \theta] (-x1R[\phi, \theta] \times$$

  
$$x1Th[\phi, \theta] + 2 R0[\phi] \times x2Th[\phi, \theta]);$$


```

■ Z expansion (in terms of the cylindrical angle on axis):

In[*]:=

```

Z2ndExp = Normal[
  FullSimplify[Series[Z[ϕ, θ], {ε, 0, 3}]]]

```

Out[*]=

```

ε x1Z[ϕ, θ] + ε2 x2Z[ϕ, θ] + Z0[ϕ]

```

and constructing a function out of it,

In[*]:=

```

Z2ndExpFun[ϕ_, θ_] :=
  ε x1Z[ϕ, θ] + ε2 x2Z[ϕ, θ] + Z0[ϕ]

```

■ ϕ expansion (in terms of the cylindrical angle on axis):

Doing the same for the cylindrical angle at the surface,

In[*]:=

```

Phi2ndExp = Normal[FullSimplify[
  ArcTan[Series[TanPhiCyl[ϕ, θ],
    {ε, 0, 3}]] - ArcTan[Tan[ϕ]]]]]

```

Out[*]=

$$\begin{aligned}
& \frac{\epsilon \, x1Th[\phi, \theta]}{R0[\phi]} + \frac{1}{R0[\phi]^2} \\
& \epsilon^2 \left(-x1R[\phi, \theta] \times x1Th[\phi, \theta] + \right. \\
& \quad \left. R0[\phi] \times x2Th[\phi, \theta] \right) - \frac{1}{3 R0[\phi]^3} \\
& \epsilon^3 \left(-3 x1R[\phi, \theta]^2 x1Th[\phi, \theta] + x1Th[\phi, \theta]^3 + \right. \\
& \quad 3 R0[\phi] \times x1Th[\phi, \theta] \times x2R[\phi, \theta] + \\
& \quad \left. 3 R0[\phi] \times x1R[\phi, \theta] \times x2Th[\phi, \theta] \right)
\end{aligned}$$

which cast into a function,

In[*]:=

$$\begin{aligned}
\text{Phi2ndExpFun}[\phi_ , \theta_] &:= \frac{\epsilon \, x1Th[\phi, \theta]}{R0[\phi]} + \\
& \frac{1}{R0[\phi]^2} \epsilon^2 \left(-x1R[\phi, \theta] \times x1Th[\phi, \theta] + \right. \\
& \quad \left. R0[\phi] \times x2Th[\phi, \theta] \right) - \frac{1}{3 R0[\phi]^3} \epsilon^3 \\
& \left(-3 x1R[\phi, \theta]^2 x1Th[\phi, \theta] + x1Th[\phi, \theta]^3 + \right. \\
& \quad 3 R0[\phi] \times x1Th[\phi, \theta] \times x2R[\phi, \theta] + \\
& \quad \left. 3 R0[\phi] \times x1R[\phi, \theta] \times x2Th[\phi, \theta] \right);
\end{aligned}$$

■ ϕ expansion (in terms of ϕ_c):

We now do, for evaluating the difference in ϕ but at ϕ_c (using ϕ in the expression as the true cylindrical angle)

In[*]:=

deltaPhi2 =

**Series[Phi2ndExpFun[ϕ_c - Phi2ndExpFun[ϕ_c -
Phi2ndExpFun[ϕ_c , θ], θ], θ], { ϵ , 0, 2}]**

Out[*]=

$$\begin{aligned} & \frac{x1Th[\phi_c, \theta] \epsilon}{R0[\phi_c]} + \\ & \frac{1}{R0[\phi_c]^3} \left(-R0[\phi_c] \times x1R[\phi_c, \theta] \times x1Th[\phi_c, \theta] + \right. \\ & \quad R0[\phi_c]^2 x2Th[\phi_c, \theta] + \\ & \quad x1Th[\phi_c, \theta]^2 R0'[\phi_c] - R0[\phi_c] \times \\ & \quad \left. x1Th[\phi_c, \theta] x1Th^{(1,0)}[\phi_c, \theta] \right) \epsilon^2 + O[\epsilon]^3 \end{aligned}$$

- v expansion (in terms of the cylindrical angle on axis):
- v expansion (in terms of ϕ_c , the true on-surface cylindrical angle)
- R expansion (in terms of ϕ_c , the true on-surface cylindrical angle):

To find the form of the function $R(\phi_c)$, where of course ϕ_c is the cylindrical angle of x, we note that at this point we have things as a function of $\phi = \phi_c - \text{Phi1stExp}$. So,

In[*]:=

**DeltaR = Series[R2ndExpFun[
 ϕ_c - Phi2ndExpFun[ϕ_c - Phi2ndExpFun[
 ϕ_c - Phi2ndExpFun[ϕ_c , θ], θ], θ],
 θ] - R0[ϕ_c], { ϵ , 0, 2}]**

Out[*]=

$$\begin{aligned}
& \left(x1R[\phi_c, \theta] - \frac{x1Th[\phi_c, \theta] R0'[\phi_c]}{R0[\phi_c]} \right) \epsilon + \\
& \left(\frac{x1Th[\phi_c, \theta]^2 + 2 R0[\phi_c] \times x2R[\phi_c, \theta]}{2 R0[\phi_c]} + \right. \\
& \quad \frac{x1Th[\phi_c, \theta]^2 R0''[\phi_c]}{2 R0[\phi_c]^2} - \\
& \quad \frac{x1Th[\phi_c, \theta] x1R^{(1,0)}[\phi_c, \theta]}{R0[\phi_c]} + \\
& \quad \frac{1}{R0[\phi_c]^3} R0'[\phi_c] \left(R0[\phi_c] \times x1R[\phi_c, \theta] \times \right. \\
& \quad \quad x1Th[\phi_c, \theta] - R0[\phi_c]^2 x2Th[\phi_c, \theta] - \\
& \quad \quad x1Th[\phi_c, \theta]^2 R0'[\phi_c] + R0[\phi_c] \times x1Th[\\
& \quad \quad \quad \left. \phi_c, \theta] x1Th^{(1,0)}[\phi_c, \theta] \right) \left. \right) \epsilon^2 + O[\epsilon]^3
\end{aligned}$$

So,

In[*]:=

DeltaR2 = Coefficient[DeltaR, ϵ^2];

We may rewrite it in the following more succinct form

In[]:=

DeltaR2man =

$$\begin{aligned}
& -\frac{1}{2} D[D[R0[\phi_c], \phi_c], \phi_c] \frac{x1Th[\phi_c, \theta]^2}{R0[\phi_c]^2} - \\
& \left(\frac{x2Th[\phi_c, \theta]}{R0[\phi_c]} - \frac{x1R[\phi_c, \theta] \times x1Th[\phi_c, \theta]}{R0[\phi_c]^2} \right) \\
& D[R0[\phi_c], \phi_c] - \frac{x1Th[\phi_c, \theta]}{R0[\phi_c]} \\
& D\left[x1R[\phi_c, \theta] - \frac{x1Th[\phi_c, \theta]}{R0[\phi_c]} D[R0[\phi_c], \phi_c], \right. \\
& \left. \phi_c\right] + \left(x2R[\phi_c, \theta] + \frac{x1Th[\phi_c, \theta]^2}{2 R0[\phi_c]} \right);
\end{aligned}$$

Which may be shown to be identical,

In[]:=

Simplify[DeltaR2 - DeltaR2man]

Out[]:=

0

- Z expansion (in terms of ϕ_c , the true on-surface cylindrical angle):

In[]:=

```

DeltaZ = Series[Z2ndExpFun[
  phi_c - Phi2ndExpFun[phi_c - Phi2ndExpFun[
    phi_c - Phi2ndExpFun[phi_c, theta], theta], theta],
  theta] - Z0[phi_c], {epsilon, 0, 2}]

```

Out[*]=

$$\begin{aligned}
& \left(x1Z[\phi_c, \theta] - \frac{x1Th[\phi_c, \theta] Z0'[\phi_c]}{R0[\phi_c]} \right) \epsilon + \\
& \left(x2Z[\phi_c, \theta] + \frac{x1Th[\phi_c, \theta]^2 Z0''[\phi_c]}{2 R0[\phi_c]^2} + \right. \\
& \quad \frac{1}{R0[\phi_c]^3} Z0'[\phi_c] \left(R0[\phi_c] \times x1R[\phi_c, \theta] \times \right. \\
& \quad \quad x1Th[\phi_c, \theta] - R0[\phi_c]^2 x2Th[\phi_c, \theta] - \\
& \quad \quad x1Th[\phi_c, \theta]^2 R0'[\phi_c] + R0[\phi_c] \times \\
& \quad \quad \quad x1Th[\phi_c, \theta] x1Th^{(1,0)}[\phi_c, \theta] \left. \right) - \\
& \quad \left. \frac{x1Th[\phi_c, \theta] x1Z^{(1,0)}[\phi_c, \theta]}{R0[\phi_c]} \right) \epsilon^2 + O[\epsilon]^3
\end{aligned}$$

So,

In[*]:= **DeltaZ2 = Coefficient[DeltaZ, ϵ^2];**

Which may be more succinctly rewritten as,

In[*]:=

DeltaZ2man =

$$\begin{aligned}
& x2Z[\phi_c, \theta] - \frac{x1Th[\phi_c, \theta]}{R0[\phi_c]} D\left[x1Z[\phi_c, \theta] - \right. \\
& \quad \left. \frac{x1Th[\phi_c, \theta]}{R0[\phi_c]} D[Z0[\phi_c], \phi_c], \phi_c\right] - \\
& \quad \left(\frac{x2Th[\phi_c, \theta]}{R0[\phi_c]} - \frac{x1R[\phi_c, \theta] \times x1Th[\phi_c, \theta]}{R0[\phi_c]^2} \right) \\
& \quad D[Z0[\phi_c], \phi_c] - \\
& \quad \frac{x1Th[\phi_c, \theta]^2}{2 R0[\phi_c]^2} D[D[Z0[\phi_c], \phi_c], \phi_c];
\end{aligned}$$

Which can be shown explicitly to be equivalent,

In[*]:=

Simplify[DeltaZ2 - DeltaZ2man]

Out[*]=

0

■ Other (not checked)

To separate the different harmonics,

In[*]:=

```

x1th = X1thc[φ] Cos[θ] + X1ths[φ] Sin[θ];
x1R = X1Rc[φ] Cos[θ] + X1Rs[φ] Sin[θ];
x2th = X2thc[φ] Cos[2 θ] +
        X2ths[φ] Sin[2 θ] + X2th0[φ];
x2R = X2Rc[φ] Cos[2 θ] +
        X2Rs[φ] Sin[2 θ] + X2R0[φ];
x1z = X1zc[φ] Cos[θ] + X1zs[φ] Sin[θ];
x2z = X2zc[φ] Cos[2 θ] +
        X2zs[φ] Sin[2 θ] + X2z0[φ];

```

In[*]:=

$$\begin{aligned}
\text{delR2} = & -\frac{1}{2} D[D[R0[\phi], \phi], \phi] \frac{x1th^2}{R0[\phi]^2} - \\
& \left(\frac{x2th}{R0[\phi]} - \frac{x1R x1th}{R0[\phi]^2} \right) D[R0[\phi], \phi] - \\
& \frac{x1th}{R0[\phi]} D\left[x1R - \frac{x1th}{R0[\phi]} D[R0[\phi], \phi], \phi\right] + \\
& \left(x2R + \frac{x1th^2}{2 R0[\phi]} \right);
\end{aligned}$$

In[*]:=

$$\begin{aligned} \text{delZ2} = & -\frac{1}{2} D[D[Z0[\phi], \phi], \phi] \frac{x1th^2}{R0[\phi]^2} - \\ & \left(\frac{x2th}{R0[\phi]} - \frac{x1R x1th}{R0[\phi]^2} \right) D[Z0[\phi], \phi] - \\ & \frac{x1th}{R0[\phi]} D\left[x1z - \frac{x1th}{R0[\phi]} D[Z0[\phi], \phi], \phi\right] + x2z; \end{aligned}$$

In[*]:=

Collect[TrigReduce[delR2],
{Cos[2 θ], Sin[2 θ]}]

Out[*]=

$$\begin{aligned} & \frac{X1thc[\phi]^2}{4 R0[\phi]} + \frac{X1ths[\phi]^2}{4 R0[\phi]} + \\ & X2R0[\phi] + \frac{X1Rc[\phi] \times X1thc[\phi] R0'[\phi]}{2 R0[\phi]^2} + \\ & \frac{X1Rs[\phi] \times X1ths[\phi] R0'[\phi]}{2 R0[\phi]^2} - \frac{X2th0[\phi] R0'[\phi]}{R0[\phi]} - \\ & \frac{X1thc[\phi]^2 R0'[\phi]^2}{2 R0[\phi]^3} - \frac{X1ths[\phi]^2 R0'[\phi]^2}{2 R0[\phi]^3} - \\ & \frac{X1thc[\phi] X1Rc'[\phi]}{2 R0[\phi]} - \frac{X1ths[\phi] X1Rs'[\phi]}{2 R0[\phi]} + \\ & \frac{X1thc[\phi] R0'[\phi] X1thc'[\phi]}{2 R0[\phi]^2} + \\ & \frac{X1ths[\phi] R0'[\phi] X1ths'[\phi]}{2 R0[\phi]^2} + \end{aligned}$$

$$\begin{aligned}
& \frac{X1thc[\phi]^2 R0''[\phi]}{4 R0[\phi]^2} + \frac{X1ths[\phi]^2 R0''[\phi]}{4 R0[\phi]^2} + \\
& \sin[2\theta] \left(\frac{X1thc[\phi] \times X1ths[\phi]}{2 R0[\phi]} + \right. \\
& \quad X2Rs[\phi] + \frac{X1Rs[\phi] \times X1thc[\phi] R0'[\phi]}{2 R0[\phi]^2} + \\
& \quad \frac{X1Rc[\phi] \times X1ths[\phi] R0'[\phi]}{2 R0[\phi]^2} - \\
& \quad \frac{X2ths[\phi] R0'[\phi]}{R0[\phi]} - \\
& \quad \frac{X1thc[\phi] \times X1ths[\phi] R0'[\phi]^2}{R0[\phi]^3} - \\
& \quad \frac{X1ths[\phi] X1Rc'[\phi]}{2 R0[\phi]} - \frac{X1thc[\phi] X1Rs'[\phi]}{2 R0[\phi]} + \\
& \quad \frac{X1ths[\phi] R0'[\phi] X1thc'[\phi]}{2 R0[\phi]^2} + \\
& \quad \frac{X1thc[\phi] R0'[\phi] X1ths'[\phi]}{2 R0[\phi]^2} + \\
& \quad \left. \frac{X1thc[\phi] \times X1ths[\phi] R0''[\phi]}{2 R0[\phi]^2} \right) + \\
& \cos[2\theta] \left(\frac{X1thc[\phi]^2}{4 R0[\phi]} - \frac{X1ths[\phi]^2}{4 R0[\phi]} + \right. \\
& \quad X2Rc[\phi] + \frac{X1Rc[\phi] \times X1thc[\phi] R0'[\phi]}{2 R0[\phi]^2} -
\end{aligned}$$

$$\begin{aligned}
& \frac{X1Rs[\phi] \times X1ths[\phi] R0'[\phi]}{2 R0[\phi]^2} - \\
& \frac{X2thc[\phi] R0'[\phi]}{R0[\phi]} - \frac{X1thc[\phi]^2 R0'[\phi]^2}{2 R0[\phi]^3} + \\
& \frac{X1ths[\phi]^2 R0'[\phi]^2}{2 R0[\phi]^3} - \frac{X1thc[\phi] X1Rc'[\phi]}{2 R0[\phi]} + \\
& \frac{X1ths[\phi] X1Rs'[\phi]}{2 R0[\phi]} + \\
& \frac{X1thc[\phi] R0'[\phi] X1thc'[\phi]}{2 R0[\phi]^2} - \\
& \frac{X1ths[\phi] R0'[\phi] X1ths'[\phi]}{2 R0[\phi]^2} + \\
& \left. \frac{X1thc[\phi]^2 R0''[\phi]}{4 R0[\phi]^2} - \frac{X1ths[\phi]^2 R0''[\phi]}{4 R0[\phi]^2} \right)
\end{aligned}$$

■ R20

$ln[8] :=$

$$\begin{aligned}
& \frac{X1thc[\phi]^2}{4 R0[\phi]} + \frac{X1ths[\phi]^2}{4 R0[\phi]} + X2R0[\phi] + \frac{X1Rc[\phi] \times X1thc[\phi] R0'[\phi]}{2 R0[\phi]^2} + \\
& \frac{X1Rs[\phi] \times X1ths[\phi] R0'[\phi]}{2 R0[\phi]^2} - \frac{X2th0[\phi] R0'[\phi]}{R0[\phi]} - \frac{X1thc[\phi]^2 R0'[\phi]^2}{2 R0[\phi]^3} - \frac{X1ths[\phi]^2 R0'[\phi]^2}{2 R0[\phi]^3} - \\
& \frac{X1thc[\phi] X1Rc'[\phi]}{2 R0[\phi]} - \frac{X1ths[\phi] X1Rs'[\phi]}{2 R0[\phi]} + \frac{X1thc[\phi] R0'[\phi] X1thc'[\phi]}{2 R0[\phi]^2} + \\
& \frac{X1ths[\phi] R0'[\phi] X1ths'[\phi]}{2 R0[\phi]^2} + \frac{X1thc[\phi]^2 R0''[\phi]}{4 R0[\phi]^2} + \frac{X1ths[\phi]^2 R0''[\phi]}{4 R0[\phi]^2}
\end{aligned}$$

Out[*]:=

$$\begin{aligned}
& \frac{X1thc[\phi]^2}{4 R0[\phi]} + \frac{X1ths[\phi]^2}{4 R0[\phi]} + X2R0[\phi] + \frac{X1Rc[\phi] \times X1thc[\phi] R0'[\phi]}{2 R0[\phi]^2} + \\
& \frac{X1Rs[\phi] \times X1ths[\phi] R0'[\phi]}{2 R0[\phi]^2} - \frac{X2th0[\phi] R0'[\phi]}{R0[\phi]} - \frac{X1thc[\phi]^2 R0'[\phi]^2}{2 R0[\phi]^3} - \frac{X1ths[\phi]^2 R0'[\phi]^2}{2 R0[\phi]^3} - \\
& \frac{X1thc[\phi] X1Rc'[\phi]}{2 R0[\phi]} - \frac{X1ths[\phi] X1Rs'[\phi]}{2 R0[\phi]} + \frac{X1thc[\phi] R0'[\phi] X1thc'[\phi]}{2 R0[\phi]^2} + \\
& \frac{X1ths[\phi] R0'[\phi] X1ths'[\phi]}{2 R0[\phi]^2} + \frac{X1thc[\phi]^2 R0''[\phi]}{4 R0[\phi]^2} + \frac{X1ths[\phi]^2 R0''[\phi]}{4 R0[\phi]^2}
\end{aligned}$$

In[*]:=

■ R2c

In[*]:=

$$\begin{aligned}
& \frac{X1thc[\phi]^2}{4 R0[\phi]} - \frac{X1ths[\phi]^2}{4 R0[\phi]} + X2Rc[\phi] + \\
& \frac{X1Rc[\phi] \times X1thc[\phi] R0'[\phi]}{2 R0[\phi]^2} - \frac{X1Rs[\phi] \times X1ths[\phi] R0'[\phi]}{2 R0[\phi]^2} - \\
& \frac{X2thc[\phi] R0'[\phi]}{R0[\phi]} - \frac{X1thc[\phi]^2 R0'[\phi]^2}{2 R0[\phi]^3} + \frac{X1ths[\phi]^2 R0'[\phi]^2}{2 R0[\phi]^3} - \\
& \frac{X1thc[\phi] X1Rc'[\phi]}{2 R0[\phi]} + \frac{X1ths[\phi] X1Rs'[\phi]}{2 R0[\phi]} + \\
& \frac{X1thc[\phi] R0'[\phi] X1thc'[\phi]}{2 R0[\phi]^2} - \frac{X1ths[\phi] R0'[\phi] X1ths'[\phi]}{2 R0[\phi]^2} + \\
& \frac{X1thc[\phi]^2 R0''[\phi]}{4 R0[\phi]^2} - \frac{X1ths[\phi]^2 R0''[\phi]}{4 R0[\phi]^2}
\end{aligned}$$

Out[*]=

$$\begin{aligned}
& \frac{X1thc[\phi]^2}{4 R0[\phi]} - \frac{X1ths[\phi]^2}{4 R0[\phi]} + X2Rc[\phi] + \frac{X1Rc[\phi] \times X1thc[\phi] R0'[\phi]}{2 R0[\phi]^2} - \\
& \frac{X1Rs[\phi] \times X1ths[\phi] R0'[\phi]}{2 R0[\phi]^2} - \frac{X2thc[\phi] R0'[\phi]}{R0[\phi]} - \frac{X1thc[\phi]^2 R0'[\phi]^2}{2 R0[\phi]^3} + \frac{X1ths[\phi]^2 R0'[\phi]^2}{2 R0[\phi]^3} - \\
& \frac{X1thc[\phi] X1Rc'[\phi]}{2 R0[\phi]} + \frac{X1ths[\phi] X1Rs'[\phi]}{2 R0[\phi]} + \frac{X1thc[\phi] R0'[\phi] X1thc'[\phi]}{2 R0[\phi]^2} - \\
& \frac{X1ths[\phi] R0'[\phi] X1ths'[\phi]}{2 R0[\phi]^2} + \frac{X1thc[\phi]^2 R0''[\phi]}{4 R0[\phi]^2} - \frac{X1ths[\phi]^2 R0''[\phi]}{4 R0[\phi]^2}
\end{aligned}$$

■ R2s

In[*]:=

$$\frac{X1thc[\phi] \times X1ths[\phi]}{2 R0[\phi]} + X2Rs[\phi] +$$

$$\begin{aligned}
& (X1Rs[\phi] \times X1thc[\phi] R0'[\phi]) / \\
& (2 R0[\phi]^2) + \\
& (X1Rc[\phi] \times X1ths[\phi] R0'[\phi]) / \\
& (2 R0[\phi]^2) - \\
& \frac{X2ths[\phi] R0'[\phi]}{R0[\phi]} - \frac{1}{R0[\phi]^3} \\
& X1thc[\phi] \times X1ths[\phi] R0'[\phi]^2 - \\
& \frac{X1ths[\phi] X1Rc'[\phi]}{2 R0[\phi]} - \\
& \frac{X1thc[\phi] X1Rs'[\phi]}{2 R0[\phi]} + \\
& (X1ths[\phi] R0'[\phi] X1thc'[\phi]) / \\
& (2 R0[\phi]^2) + \\
& (X1thc[\phi] R0'[\phi] X1ths'[\phi]) / \\
& (2 R0[\phi]^2) +
\end{aligned}$$

$$\frac{(X1thc[\phi] \times X1ths[\phi] R0''[\phi])}{(2 R0[\phi]^2)}$$

Out[]=

$$\begin{aligned} & \frac{X1thc[\phi] \times X1ths[\phi]}{2 R0[\phi]} + X2Rs[\phi] + \frac{X1Rs[\phi] \times X1thc[\phi] R0'[\phi]}{2 R0[\phi]^2} + \\ & \frac{X1Rc[\phi] \times X1ths[\phi] R0'[\phi]}{2 R0[\phi]^2} - \frac{X2ths[\phi] R0'[\phi]}{R0[\phi]} - \frac{X1thc[\phi] \times X1ths[\phi] R0'[\phi]^2}{R0[\phi]^3} - \\ & \frac{X1ths[\phi] X1Rc'[\phi]}{2 R0[\phi]} - \frac{X1thc[\phi] X1Rs'[\phi]}{2 R0[\phi]} + \frac{X1ths[\phi] R0'[\phi] X1thc'[\phi]}{2 R0[\phi]^2} + \\ & \frac{X1thc[\phi] R0'[\phi] X1ths'[\phi]}{2 R0[\phi]^2} + \frac{X1thc[\phi] \times X1ths[\phi] R0''[\phi]}{2 R0[\phi]^2} \end{aligned}$$

In[]:=

Collect[TrigReduce[de1Z2],
{Cos[2 θ], Sin[2 θ]}]

Out[*]=

$$\begin{aligned}
& X2z0[\phi] - \frac{X1thc[\phi] X1zc'[\phi]}{2 R0[\phi]} - \frac{X1ths[\phi] X1zs'[\phi]}{2 R0[\phi]} + \\
& \frac{X1Rc[\phi] \times X1thc[\phi] Z0'[\phi]}{2 R0[\phi]^2} + \frac{X1Rs[\phi] \times X1ths[\phi] Z0'[\phi]}{2 R0[\phi]^2} - \frac{X2th0[\phi] Z0'[\phi]}{R0[\phi]} - \\
& \frac{X1thc[\phi]^2 R0'[\phi] Z0'[\phi]}{2 R0[\phi]^3} - \frac{X1ths[\phi]^2 R0'[\phi] Z0'[\phi]}{2 R0[\phi]^3} + \frac{X1thc[\phi] X1thc'[\phi] Z0'[\phi]}{2 R0[\phi]^2} + \\
& \frac{X1ths[\phi] X1ths'[\phi] Z0'[\phi]}{2 R0[\phi]^2} + \frac{X1thc[\phi]^2 Z0''[\phi]}{4 R0[\phi]^2} + \frac{X1ths[\phi]^2 Z0''[\phi]}{4 R0[\phi]^2} + \\
& \text{Sin}[2 \theta] \left(X2zs[\phi] - \frac{X1ths[\phi] X1zc'[\phi]}{2 R0[\phi]} - \frac{X1thc[\phi] X1zs'[\phi]}{2 R0[\phi]} + \right. \\
& \frac{X1Rs[\phi] \times X1thc[\phi] Z0'[\phi]}{2 R0[\phi]^2} + \frac{X1Rc[\phi] \times X1ths[\phi] Z0'[\phi]}{2 R0[\phi]^2} - \frac{X2ths[\phi] Z0'[\phi]}{R0[\phi]} - \\
& \frac{X1thc[\phi] \times X1ths[\phi] R0'[\phi] Z0'[\phi]}{R0[\phi]^3} + \frac{X1ths[\phi] X1thc'[\phi] Z0'[\phi]}{2 R0[\phi]^2} + \\
& \left. \frac{X1thc[\phi] X1ths'[\phi] Z0'[\phi]}{2 R0[\phi]^2} + \frac{X1thc[\phi] \times X1ths[\phi] Z0''[\phi]}{2 R0[\phi]^2} \right) + \\
& \text{Cos}[2 \theta] \left(X2zc[\phi] - \frac{X1thc[\phi] X1zc'[\phi]}{2 R0[\phi]} + \frac{X1ths[\phi] X1zs'[\phi]}{2 R0[\phi]} + \right. \\
& \frac{X1Rc[\phi] \times X1thc[\phi] Z0'[\phi]}{2 R0[\phi]^2} - \frac{X1Rs[\phi] \times X1ths[\phi] Z0'[\phi]}{2 R0[\phi]^2} - \frac{X2thc[\phi] Z0'[\phi]}{R0[\phi]} - \\
& \frac{X1thc[\phi]^2 R0'[\phi] Z0'[\phi]}{2 R0[\phi]^3} + \frac{X1ths[\phi]^2 R0'[\phi] Z0'[\phi]}{2 R0[\phi]^3} + \frac{X1thc[\phi] X1thc'[\phi] Z0'[\phi]}{2 R0[\phi]^2} - \\
& \left. \frac{X1ths[\phi] X1ths'[\phi] Z0'[\phi]}{2 R0[\phi]^2} + \frac{X1thc[\phi]^2 Z0''[\phi]}{4 R0[\phi]^2} - \frac{X1ths[\phi]^2 Z0''[\phi]}{4 R0[\phi]^2} \right)
\end{aligned}$$

■ Z20

In[]:=

$$\begin{aligned}
& X2z0[\phi] - \frac{X1thc[\phi] X1zc'[\phi]}{2 R0[\phi]} - \\
& \frac{X1ths[\phi] X1zs'[\phi]}{2 R0[\phi]} + \frac{X1Rc[\phi] \times X1thc[\phi] Z0'[\phi]}{2 R0[\phi]^2} + \\
& \frac{X1Rs[\phi] \times X1ths[\phi] Z0'[\phi]}{2 R0[\phi]^2} - \frac{X2th0[\phi] Z0'[\phi]}{R0[\phi]} - \\
& \frac{X1thc[\phi]^2 R0'[\phi] Z0'[\phi]}{2 R0[\phi]^3} - \frac{X1ths[\phi]^2 R0'[\phi] Z0'[\phi]}{2 R0[\phi]^3} + \\
& \frac{X1thc[\phi] X1thc'[\phi] Z0'[\phi]}{2 R0[\phi]^2} + \frac{X1ths[\phi] X1ths'[\phi] Z0'[\phi]}{2 R0[\phi]^2} + \\
& \frac{X1thc[\phi]^2 Z0''[\phi]}{4 R0[\phi]^2} + \frac{X1ths[\phi]^2 Z0''[\phi]}{4 R0[\phi]^2}
\end{aligned}$$

Out[]:=

$$\begin{aligned}
& X2z0[\phi] - \frac{X1thc[\phi] X1zc'[\phi]}{2 R0[\phi]} - \frac{X1ths[\phi] X1zs'[\phi]}{2 R0[\phi]} + \\
& \frac{X1Rc[\phi] \times X1thc[\phi] Z0'[\phi]}{2 R0[\phi]^2} + \frac{X1Rs[\phi] \times X1ths[\phi] Z0'[\phi]}{2 R0[\phi]^2} - \frac{X2th0[\phi] Z0'[\phi]}{R0[\phi]} - \\
& \frac{X1thc[\phi]^2 R0'[\phi] Z0'[\phi]}{2 R0[\phi]^3} - \frac{X1ths[\phi]^2 R0'[\phi] Z0'[\phi]}{2 R0[\phi]^3} + \frac{X1thc[\phi] X1thc'[\phi] Z0'[\phi]}{2 R0[\phi]^2} + \\
& \frac{X1ths[\phi] X1ths'[\phi] Z0'[\phi]}{2 R0[\phi]^2} + \frac{X1thc[\phi]^2 Z0''[\phi]}{4 R0[\phi]^2} + \frac{X1ths[\phi]^2 Z0''[\phi]}{4 R0[\phi]^2}
\end{aligned}$$

■ Z2s

In[]:=

$$\begin{aligned}
X2zs[\phi] &- \frac{X1ths[\phi] X1zc'[\phi]}{2 R0[\phi]} - \frac{X1thc[\phi] X1zs'[\phi]}{2 R0[\phi]} + \\
& (X1Rs[\phi] \times X1thc[\phi] Z0'[\phi]) / (2 R0[\phi]^2) + \\
& (X1Rc[\phi] \times X1ths[\phi] Z0'[\phi]) / (2 R0[\phi]^2) - \frac{X2ths[\phi] Z0'[\phi]}{R0[\phi]} - \\
& (X1thc[\phi] \times X1ths[\phi] R0'[\phi] Z0'[\phi]) / R0[\phi]^3 + \\
& (X1ths[\phi] X1thc'[\phi] Z0'[\phi]) / (2 R0[\phi]^2) + \\
& (X1thc[\phi] X1ths'[\phi] Z0'[\phi]) / (2 R0[\phi]^2) + \\
& (X1thc[\phi] \times X1ths[\phi] Z0''[\phi]) / (2 R0[\phi]^2)
\end{aligned}$$

Out[]:=

$$\begin{aligned}
X2zs[\phi] &- \frac{X1ths[\phi] X1zc'[\phi]}{2 R0[\phi]} - \frac{X1thc[\phi] X1zs'[\phi]}{2 R0[\phi]} + \frac{X1Rs[\phi] \times X1thc[\phi] Z0'[\phi]}{2 R0[\phi]^2} + \\
& \frac{X1Rc[\phi] \times X1ths[\phi] Z0'[\phi]}{2 R0[\phi]^2} - \frac{X2ths[\phi] Z0'[\phi]}{R0[\phi]} - \frac{X1thc[\phi] \times X1ths[\phi] R0'[\phi] Z0'[\phi]}{R0[\phi]^3} + \\
& \frac{X1ths[\phi] X1thc'[\phi] Z0'[\phi]}{2 R0[\phi]^2} + \frac{X1thc[\phi] X1ths'[\phi] Z0'[\phi]}{2 R0[\phi]^2} + \frac{X1thc[\phi] \times X1ths[\phi] Z0''[\phi]}{2 R0[\phi]^2}
\end{aligned}$$

■ Z2c

In[]:=

$$\begin{aligned}
& X2zc[\phi] - \frac{X1thc[\phi] X1zc'[\phi]}{2 R0[\phi]} + \frac{X1ths[\phi] X1zs'[\phi]}{2 R0[\phi]} + \\
& (X1Rc[\phi] \times X1thc[\phi] Z0'[\phi]) / (2 R0[\phi]^2) - \\
& (X1Rs[\phi] \times X1ths[\phi] Z0'[\phi]) / (2 R0[\phi]^2) - \frac{X2thc[\phi] Z0'[\phi]}{R0[\phi]} - \\
& \frac{X1thc[\phi]^2 R0'[\phi] Z0'[\phi]}{2 R0[\phi]^3} + \frac{X1ths[\phi]^2 R0'[\phi] Z0'[\phi]}{2 R0[\phi]^3} + \\
& (X1thc[\phi] X1thc'[\phi] Z0'[\phi]) / (2 R0[\phi]^2) - \\
& (X1ths[\phi] X1ths'[\phi] Z0'[\phi]) / (2 R0[\phi]^2) + \\
& \frac{X1thc[\phi]^2 Z0''[\phi]}{4 R0[\phi]^2} - \frac{X1ths[\phi]^2 Z0''[\phi]}{4 R0[\phi]^2}
\end{aligned}$$

Out[]:=

$$\begin{aligned}
& X2zc[\phi] - \frac{X1thc[\phi] X1zc'[\phi]}{2 R0[\phi]} + \frac{X1ths[\phi] X1zs'[\phi]}{2 R0[\phi]} + \\
& \frac{X1Rc[\phi] \times X1thc[\phi] Z0'[\phi]}{2 R0[\phi]^2} - \frac{X1Rs[\phi] \times X1ths[\phi] Z0'[\phi]}{2 R0[\phi]^2} - \frac{X2thc[\phi] Z0'[\phi]}{R0[\phi]} - \\
& \frac{X1thc[\phi]^2 R0'[\phi] Z0'[\phi]}{2 R0[\phi]^3} + \frac{X1ths[\phi]^2 R0'[\phi] Z0'[\phi]}{2 R0[\phi]^3} + \frac{X1thc[\phi] X1thc'[\phi] Z0'[\phi]}{2 R0[\phi]^2} - \\
& \frac{X1ths[\phi] X1ths'[\phi] Z0'[\phi]}{2 R0[\phi]^2} + \frac{X1thc[\phi]^2 Z0''[\phi]}{4 R0[\phi]^2} - \frac{X1ths[\phi]^2 Z0''[\phi]}{4 R0[\phi]^2}
\end{aligned}$$