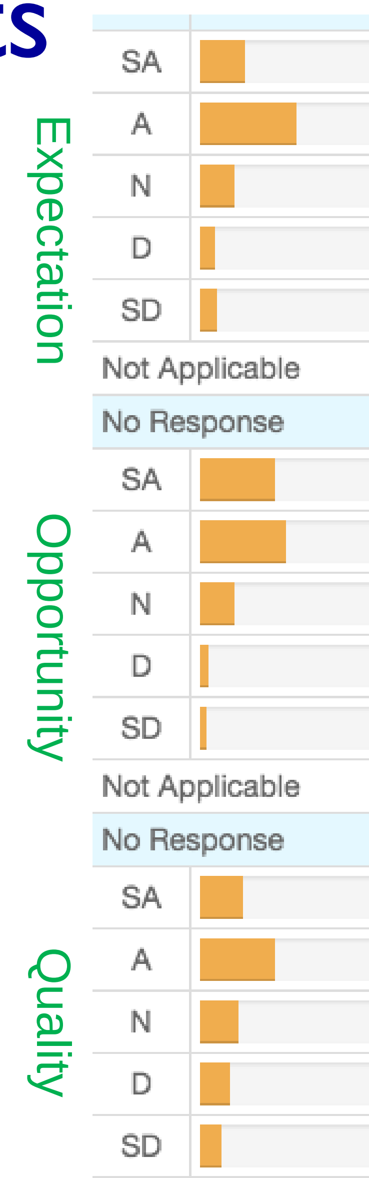
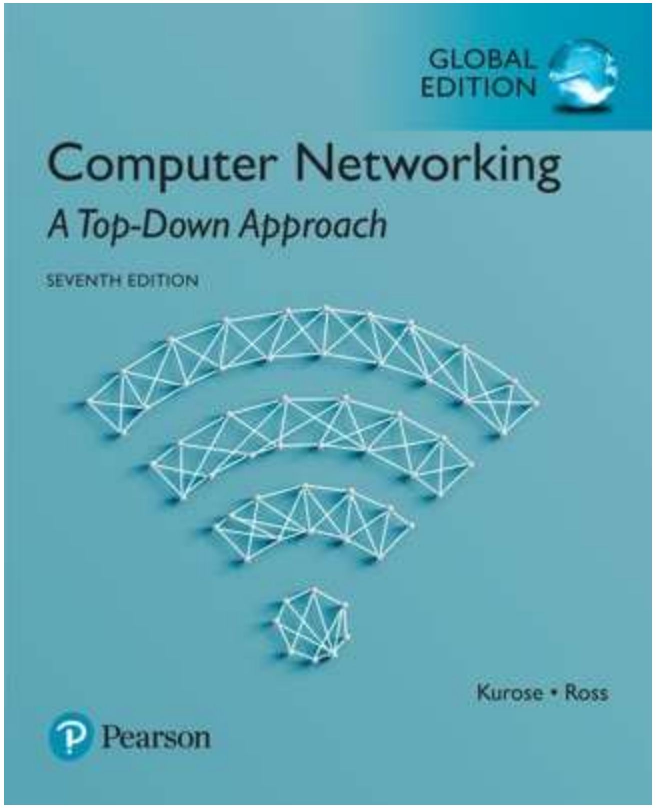
Early Feedback Survey Results

- Generally Positive - Thank You!
  - Knew what is expected
  - Made most of the learning opportunities
  - Learned a lot - Well Done!
- Issues:
  - Too much, too fast? - teaching < 2/3 textbook
  - Require self-study with textbook? - Yes
  - Tutorial/Lab - need improvement - Yes
  - Practice quiz easy, real quiz harder - Yes
- Keep up the effort!



Chapter 5 Network Layer: The Control Plane

Adapted by RenPing.Liu@uts.edu.au
5 May 2019



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- If you use these slides (e.g., in a class) that you mention their source (after all, we'd like people to use our book!)
- If you post any slides on a www site, that you note that they are adapted from (or perhaps identical to) our slides, and note our copyright of this material.

Thanks and enjoy! JFK/KWR

Computer Networking: A Top Down Approach

7th edition
Jim Kurose, Keith Ross
Pearson/Addison Wesley
April 2016

Chapter 5: outline

5.1 introduction

5.2 routing protocols

- link state
- distance vector

5.3 intra-AS routing in the Internet: OSPF

5.4 routing among the ISPs: BGP

~~5.5 The SDN control plane~~

5.6 ICMP: The Internet Control Message Protocol

5.7 Network management and SNMP

Network-layer functions

Recall: two network-layer functions:

- *forwarding:* move packets from router's input to appropriate router output

data plane

- *routing:* determine route taken by packets from source to destination

control plane

Two approaches to structuring network control plane:

- per-router control (traditional)
- logically centralized control (software defined networking)

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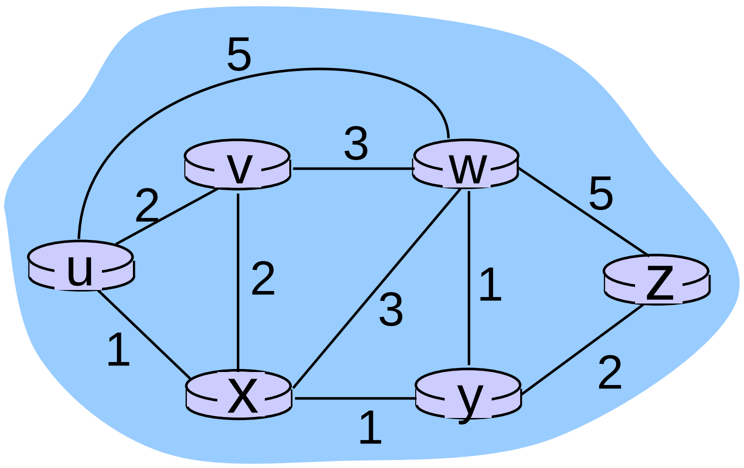
Routing protocols

Routing protocol goal: determine "good" paths (equivalently, routes), from sending hosts to receiving host, through network of routers

- path: sequence of routers packets will traverse in going from given initial source host to given final destination host
- "good" measures: "shortest", "least cost", "fastest", "least congested"
- routing: a "top-10" networking challenge!

Graph abstraction of the network

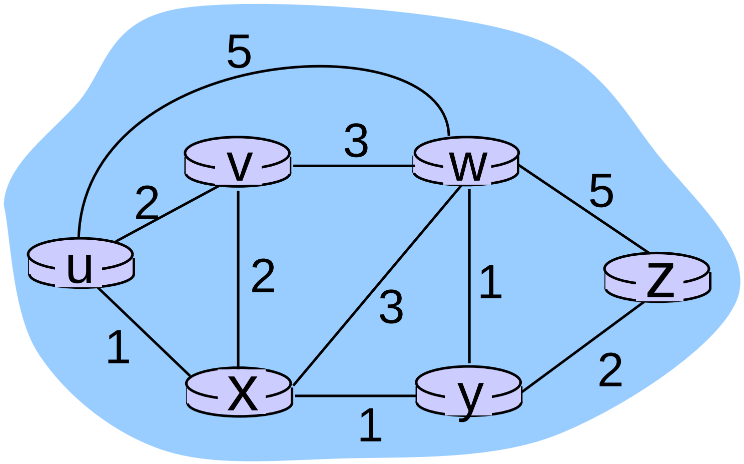


graph: G = (N,E)

N = set of routers = { u, v, w, x, y, z }

E = set of links ={ (u,v), (u,x), (v,x), (v,w), (x,w), (x,y), (w,y), (w,z), (y,z) }

Graph abstraction: costs



c(x,x') = cost of link (x,x')
e.g., c(w,z) = 5

- cost could always be 1, or
- related to distance / delay
- inversely related to bandwidth,
- related to congestion

cost of path $(x_1, x_2, x_3, \ldots, x_p) = c(x_1,x_2) + c(x_2,x_3) + \ldots + c(x_{p-1},x_p)$

key question: what is the least-cost path between u and z ?
routing algorithm: algorithm that finds that least cost path

Routing algorithm classification

Q: global or decentralized information?

global or centralized:

- all routers have complete topology, link cost info
- "link state" algorithms

decentralized or distributed:

- router knows physically-connected neighbors, link costs to neighbors
- iterative process of computation, exchange of info with neighbors
- "distance vector" algorithms

Q: static or dynamic?

static:

- routes change slowly over time

dynamic:

- routes change more quickly
  - periodic update
  - in response to link cost changes

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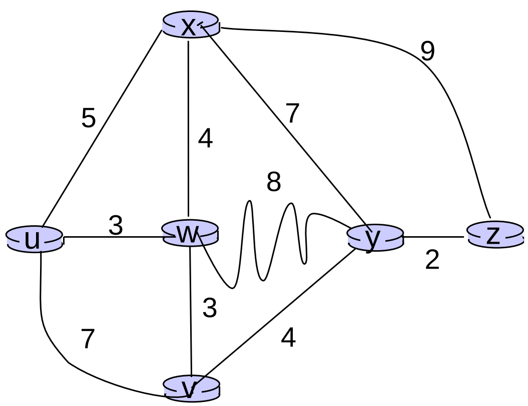
A link-state routing algorithm

Centralized routing algorithm with Global network topology information

--- Dijkstra's algorithm

- net topology, link costs known to all nodes
  - accomplished via "link state broadcast"
  - all nodes have same info
- computes least cost paths from one node ('source") to all other nodes
  - gives *forwarding table* for that node
- iterative: after k iterations, know least cost path to k dest.'s



Dijkstra's algorithm: example

Step	N*	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	7,u	3,u	5,u	∞	∞
1	uw	6,w		5,u	11,w	∞
2	uwx	6,w			11,w	14,x
3	uwxv				10,v	14,x
4	uwxvy					12,y
5	uwxvyz					

updated

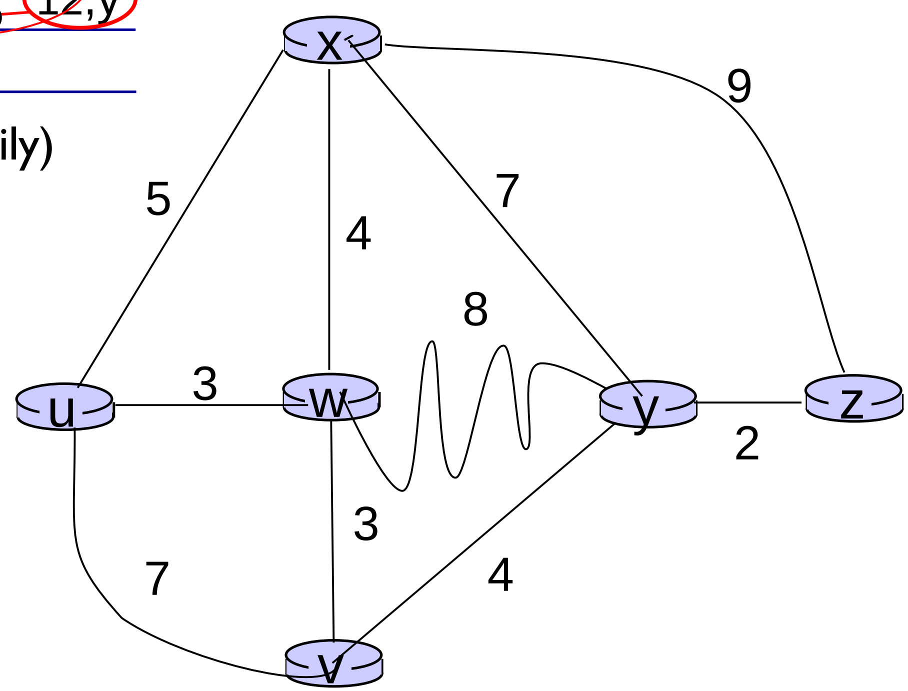
new neighb

0. Init: N*={source: u}
1. List neighbors of N*
   write/update: D(n), p(n)
2. Select min dist neighbor➔N*
   until N* has all nodes

- ties can exist (can be broken arbitrarily)

notation:

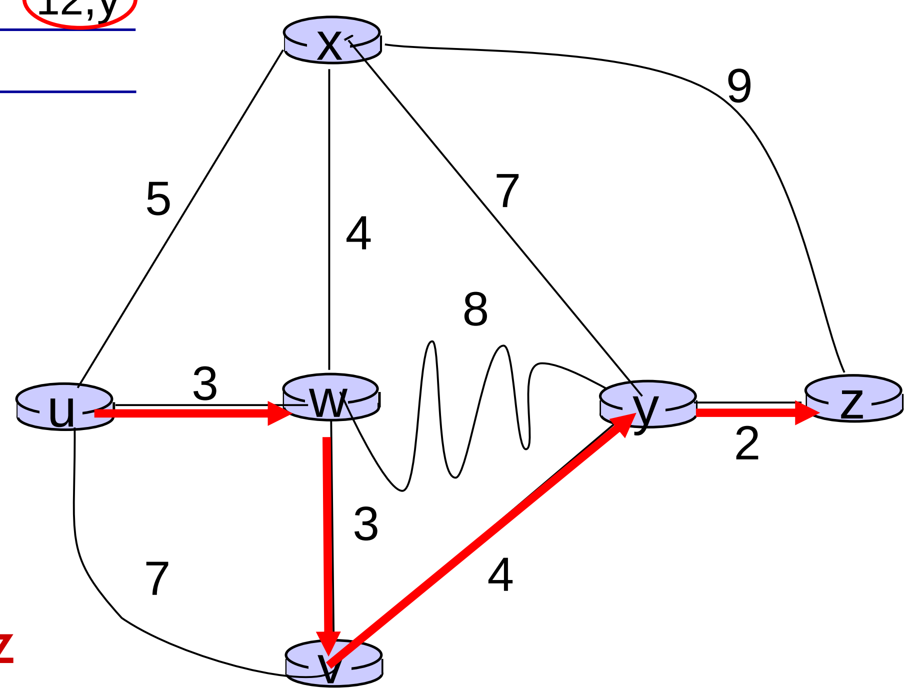
- N*: set of nodes whose least cost path are known, initial 'u'
- D(n): current value of cost of path from source 'n' to node 'u'
- p(n): predecessor node along path from source 'n' to 'u'



Dijkstra's algorithm: example

Step	N*	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	7,u	3,u	5,u	∞	∞
1	uw	6,w		5,u	11,w	∞
2	uwx	6,w			11,w	14,x
3	uwxv				10,v	14,x
4	uwxvy					12,y
5	uwxvyz					

0. Init: N*={source: u}
1. List neighbors of N*
   write: D(x), p(x)
2. Sel min dist neighbor → N*
   until N* has all nodes



build shortest paths:

- construct shortest path tree by tracing predecessor nodes: p(n)
- example: u → … → z

u → w → v → y → z

Dijsktra's algorithm

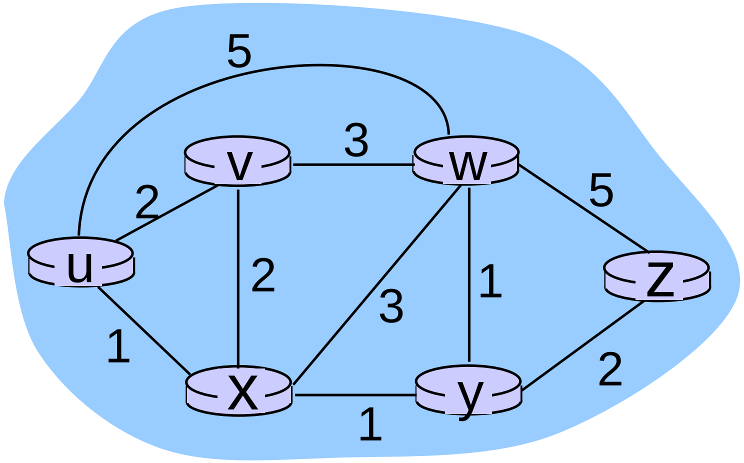
```
Initialization:
  N' = {u}
  for all nodes v
    if v adjacent to u
        then D(v) = c(u,v)
    else D(v) = ∞

Loop
  find w not in N' such that D(w) is a minimum
  add w to N'
  update D(v) for all v adjacent to w and not in N' :
      D(v) = min( D(v), D(w) + c(w,v) )
  /* new cost to v is either old cost to v or known
   shortest path cost to w plus cost from w to v */
until all nodes in N'
```

Dijkstra's algorithm: another example

Step	N*	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw					4,y
5	uxyvwz					

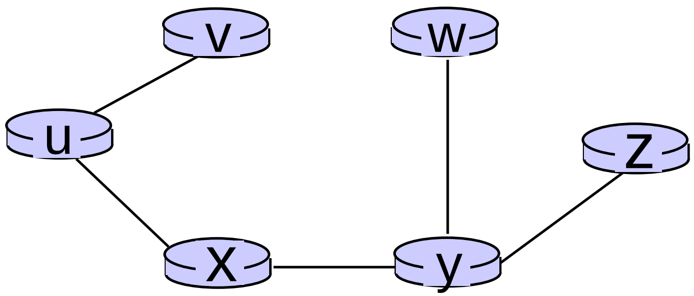
ties can exist (can be broken arbitrarily)



* Check out the online interactive exercises for more examples: http://gaia.cs.umass.edu/kurose_ross/interactive/

Dijkstra's algorithm: example (2)

resulting shortest-path tree from u:



resulting forwarding table in u: u→x→y→z

destination	link
v	(u,v)
x	(u,x)
y	(u,x)
w	(u,x)
z	(u,x)

Dijkstra's algorithm, discussion

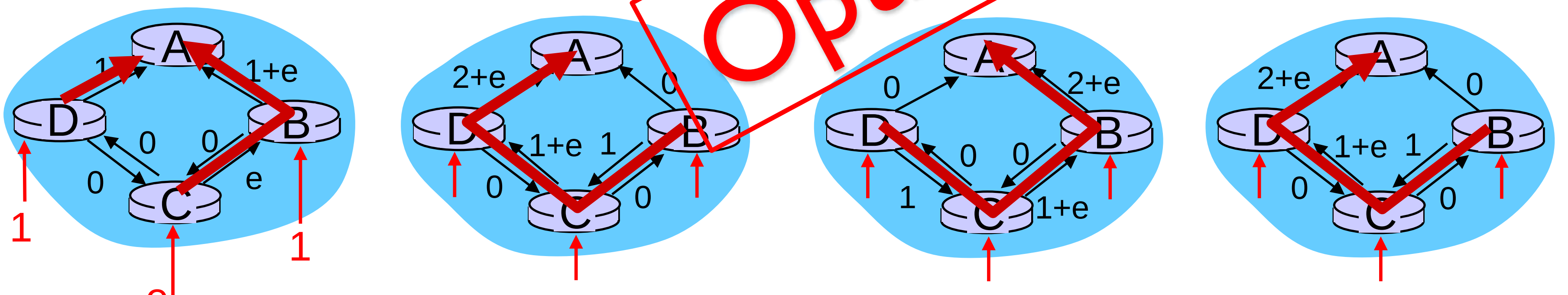
algorithm complexity: n nodes

- each iteration: need to check all nodes, w, not in N
- n(n+1)/2 comparisons: $O(n^2)$
- more efficient implementations possible: O(nlogn)

oscillations possible:

- e.g., support link cost equals amount of carried traffic:

Optional – not tested



initially

given these costs, find new routing…. resulting in new costs

given these costs, find new routing…. resulting in new costs

given these costs, find new routing…. resulting in new costs

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Distance vector algorithm

- Decentralized routing algorithm:
  - No global topology info
  - Only neighbouring info
  - Rely on neighbour's route to dest.

- Example: Sydney to Brisbane:

  which route, how far? Ask neighbours:
  - via Newcastle = 200km + 800km = 1000km
  - via Orange = 300km + 1000km = 1300km
  - via Goulbourn = 200km + 1200km = 1400km
  - via Wollongong = 100km + 1100km = 1200km

Distance vector algorithm

Bellman-Ford equation (dynamic programming)

let

$d_x(y)$:= cost of least-cost path from x to y

then

$$d_x(y) = \min_v \{c(x,v) + d_v(y)\}$$

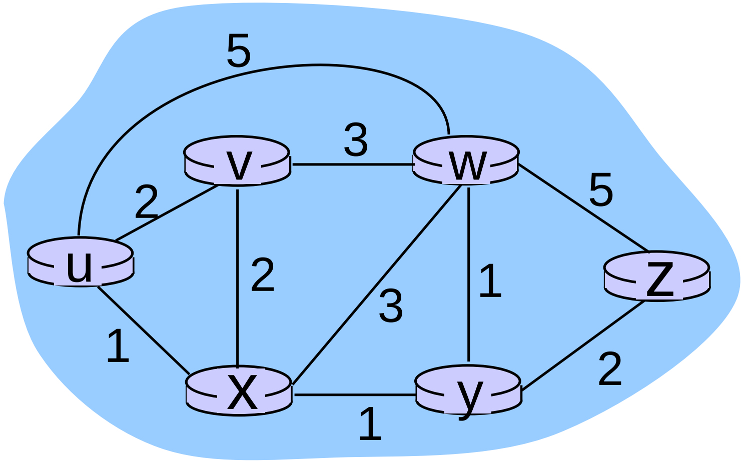
shift responsibility to neighbours

cost from neighbor v to destination y

cost to neighbor v

min taken over all neighbors v of x

Bellman-Ford example: u→z



u has three neighbours: v, x, w

u knows their distance to z:

$d_v(z) = 5,\ d_x(z) = 3,\ d_w(z) = 3$

B-F equation says:

$$d_u(z) = \min \{ c(u,v) + d_v(z),\ c(u,x) + d_x(z),\ c(u,w) + d_w(z) \}$$
$$= \min \{2 + 5,\ 1 + 3,\ 5 + 3\} = 4$$

node achieving minimum is next hop in shortest path, used in forwarding table

u→x→y→z

Distance vector algorithm

- $D_x(y)$ = estimate of least cost from x to y
  - x maintains distance vector $\mathbf{D}_x = [D_x(y): y \in N]$
- node x:
  - knows cost to each neighbor v: $c(x,v)$
  - maintains its neighbors' distance vectors. For each neighbor v, x maintains
    $\mathbf{D}_v = [D_v(y): y \in N]$

Distance vector algorithm

key idea:

- from time-to-time, each node sends its own distance vector estimate to neighbors
- when x receives new DV estimate from neighbor, it updates its own DV using B-F equation:

$$D_x(y) \leftarrow \min_v\{c(x,v) + D_v(y)\} \quad \text{for each node } y \in N$$

- under minor, natural conditions, the estimate $D_x(y)$ *converge to the actual least cost* $d_x(y)$

Distance vector algorithm

iterative, asynchronous:
each local iteration caused by:

- local link cost change
- DV update message from neighbor

distributed:

- each node notifies neighbors *only* when its DV changes
  - neighbors then notify their neighbors if necessary

each node:

wait for (change in local link cost or msg from neighbor)

recompute estimates

if DV to any dest has changed, *notify* neighbors

$$D_x(y) = \min\{c(x,y) + D_y(y),\ c(x,z) + D_z(y)\}$$
$$= \min\{2+0\ ,\ 7+1\} = 2$$

$$D_x(z) = \min\{c(x,y) + D_y(z),\ c(x,z) + D_z(z)\}$$
$$= \min\{2+1\ ,\ 7+0\} = 3$$

node x table

from \ cost to	x	y	z
x	0	2	7
y	∞	∞	∞
z	∞	∞	∞

from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	7	1	0

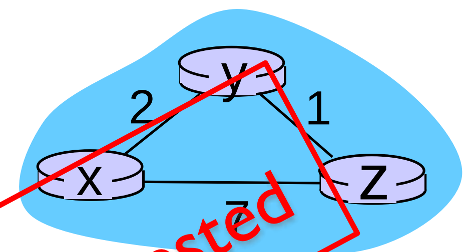
node y table

from \ cost to	x	y	z
x	∞	∞	∞
y	2	0	1
z	∞	∞	∞

node z table

from \ cost to	x	y	z
x	∞	∞	∞
y	∞	∞	∞
z	7	1	0

time



Optional – not tested

$$D_x(y) = \min\{c(x,y) + D_y(y),\ c(x,z) + D_z(y)\}$$
$$= \min\{2+0\ ,\ 7+1\} = 2$$

$$D_x(z) = \min\{c(x,y) + D_y(z),\ c(x,z) + D_z(z)\}$$
$$= \min\{2+1\ ,\ 7+0\} = 3$$

node x table

from \ cost to	x	y	z
x	0	2	7
y	∞	∞	∞
z	∞	∞	∞

from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	7	1	0

from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	3	1	0

node y table

from \ cost to	x	y	z
x	∞	∞	∞
y	2	0	1
z	∞	∞	∞

from \ cost to	x	y	z
x	0	2	7
y	2	0	1
z	7	1	0

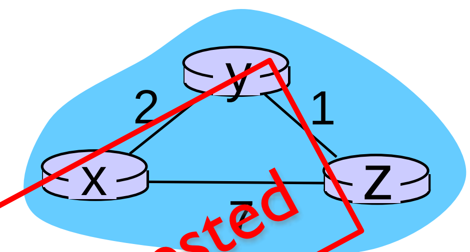
from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	3	1	0

node z table

from \ cost to	x	y	z
x	∞	∞	∞
y	∞	∞	∞
z	7	1	0

from \ cost to	x	y	z
x	0	2	7
y	2	0	1
z	3	1	0

from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	3	1	0



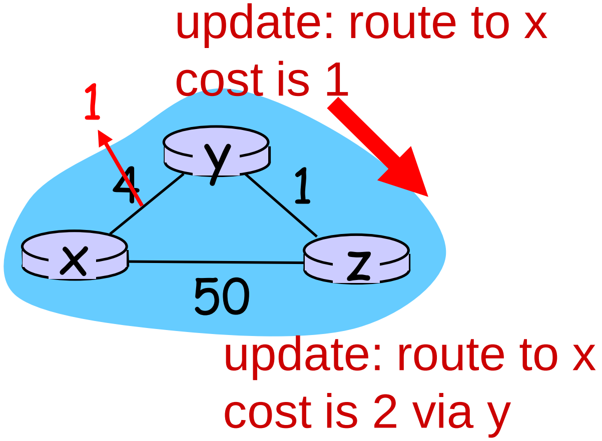
time

Optional – not tested

Distance vector: link cost changes

link cost changes:

- node detects local link cost change
- updates routing info, recalculates distance vector
- if DV changes, notify neighbors



"good news travels fast"

t_0 : y detects link-cost change, updates its DV, sends routing update to its neighbors, z

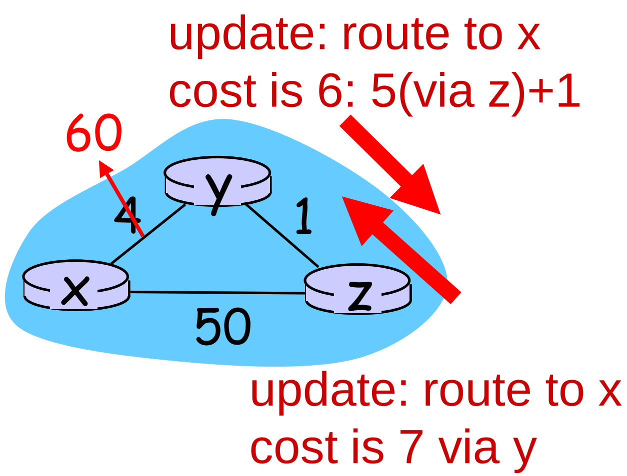
t_1 : z receives update from y, updates its table, computes new least cost to x , sends routing update to its neighbors .

* Check out the online interactive exercises for more examples: http://gaia.cs.umass.edu/kurose_ross/interactive/

Distance vector: link cost changes

link cost changes:

- node detects local link cost change
- *bad news travels slow* - "count to infinity" problem!
- many iterations before algorithm stabilizes: read textbook



t_0 : *y* detects link-cost change, updates its DV=6: 5(via z)+1, sends routing update to its neighbors z

t_1 : *z* receives update from *y*, updates its table, computes new least cost to *x* , sends routing update to its neighbors y.

Solution: poisoned reverse:

- If Z routes through Y to get to X :
  - Z tells Y its (Z's) distance to X is infinite (so Y won't route to X via Z)
- will this completely solve count to infinity problem?

Comparison of LS and DV algorithms

message complexity

- ***LS:*** with n nodes, E links, O(nE) msgs sent
- ***DV:*** exchange between neighbors only
  - convergence time varies

speed of convergence

- ***LS:*** $O(n^2)$ algorithm requires O(nE) msgs
  - may have oscillations
- ***DV:*** convergence time varies
  - may be routing loops
  - count-to-infinity problem

robustness: what happens if router malfunctions?

LS:

- node can advertise incorrect *link* cost
- each node computes only its *own* table

DV:

- DV node can advertise incorrect *path* cost
- each node' s table used by others
  - error propagate thru network

Chapter 5-part1: summary

- approaches to network control plane
  - per-router control (traditional)
- link state: Dijkstra
- distance vector