(2)a) Verdo-Truerse (At) We there be a matrix A.

is a generalisation of the n night not be invertible ( else its also defined even The pseudo - inverse (At) matrix inverse when the matrix of A is invertible,  $A^{t} = A^{-1}$ when A is not invertible.

i) For underdetermined system of eight,
(A) nxm: n < m and gank (A) = n

 $A^{\dagger} = A^{\dagger} (AA^{\dagger})^{-1}$ 

(A) nxm and sank (A) = m

AT = (ATA) TAT

Q2(6) Solve: 74+3×2=17 5x,+7x2=19 11x, + 13x2=23

Converting these egus to matix form:

$$\begin{bmatrix} 1 & 3 \\ 5 & 7 \\ 11 & 13 \end{bmatrix} \begin{bmatrix} \chi_1 \\ \chi_2 \end{bmatrix} = \begin{bmatrix} 17 \\ 19 \\ 23 \end{bmatrix}$$

$$A \qquad \chi \qquad b$$

Ax=B
To calculate  $x_1, x_2$  we need to find  $A^{-1}$  as  $x = A^{-1}b$ .

As it is over determined system of eqns because  $A_{3/2}$ ; no if rows > no if cal. and rank(A)=2 Hence the pseudo-inverse of malrix is

Af : (ATA-1)B where

A = original nation

A = Pleado Truerse

A = Transpose of A

Now formula for a would be -

$$pc = (A^T A)^A A^T \cdot b$$

$$A^{f}A = \begin{bmatrix} 1 & 5 & 1 \\ 3 & 7 & 13 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 5 & 7 \end{bmatrix} = \begin{bmatrix} 1+25+121 & 3+35+143 \\ 3+35+143 & 9+49+169 \end{bmatrix}$$

Using the property X' = Adj(X) to calculate  $(A^TA)^T$ 

$$\begin{pmatrix} A & A \end{pmatrix}^{-1} = 1 \begin{bmatrix} 227 & -181 \\ -181 & 147 \end{bmatrix}$$

Now, we use these values to calculate A+

$$A^{+} = (A^{T}A)^{-1}A^{T}$$

$$= I \begin{bmatrix} 227 - 181 \\ -181 & 147 \end{bmatrix} \begin{bmatrix} 1 & 5 & 11 \\ 3 & 7 & 13 \\ 2x3 \end{bmatrix}$$

$$= 2x3$$

$$= \int_{608} \left[ -316 - 132 \right]_{44}$$

$$= 260 \quad 124 \quad -80$$

Putting this value of At in eq. 10, we get

$$\chi = \frac{1}{608} \begin{bmatrix} -316 & -132 & 144 \\ 260 & 124 & -80 \end{bmatrix} \begin{bmatrix} 17 \\ 19 \\ 23 \end{bmatrix}$$

$$= \frac{1}{609} \left[ \frac{-316\times17}{260\times17} + \frac{132\times19}{124\times19} + \frac{144\times23}{80\times23} \right]$$

$$\chi = \begin{bmatrix} \chi_1 \\ \chi_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 608 \end{bmatrix} \begin{bmatrix} -4568 \\ 4936 \end{bmatrix} = \begin{bmatrix} -7.513 \\ 8.118 \end{bmatrix}$$



(i) Wosed from sol " (vieng rosmal eque) to solve a linear regression problem is:

$$\theta = (x^T x)^{-1} T y$$

where: (xTx) TxT: pseudo-inverse of matrix X;
y: target value

D: learning parameter

(in) Gradient deacend like iterative methods are used over dosed from solutions to raduce computational line & space complexity to solve linear regression problem for large datasets (having lash or million data points)

This is because closed from Soln night run over the entire dataset to calculate just I learning parameter, which has to be repeated for no of times egl to no of features for every learning parameter.

Space complepity with also be huge as we would require to solve the motion  $(m \times n)$ , where  $m, n \geq 10^5$  or more but gradient descend iterates over I dotta point at a lime of larms gradually.

Q2(d)

MAE:

Mean absolute overor is the average of the absolute values of diffrence of actual vs predicted values of the target

MAE = 
$$\frac{2}{2} \frac{|\hat{y}_1 - y_1|}{n}$$
  
where  $\hat{y}_1 = \text{prediction}$ ,  $\hat{y}_1$ ; true value

where y; = prediction, y; : true value
i : ith data point
n: total no of data points

MSE: the average of the squared values of diffrence of actual us predicted values of the toget for the entire tast dataset

RMSE: the quadratic mean of the diffrences between each of the actual us predicted values of the target

$$RMSD = \begin{cases} \frac{N}{2} \left( \frac{G}{3} - \frac{G}{3} \right)^2 \\ \frac{N}{N} \end{cases}$$

brew = bold - 
$$\eta \partial L(b)$$
 - gradient descend ydate of:

where  $L(b) = (y^x - h_b(u))^2$ ,

 $\eta$  is learning rate

and  $u = 3cb$ 

$$\frac{\partial L(b)}{\partial b} = 2(y^* - h_b(u)) \frac{\partial}{\partial b} [y^* - h_b(u)]$$

$$= 2(y^* - h_b(u)) - \frac{\partial}{\partial b} (h_b(u)) \cdot \frac{\partial (ab)}{\partial b}$$

$$=2(y^*-h_6(u))\left[-\frac{\partial}{\partial b}\left(h_6(u)\right)\right]\cdot x$$

given  $h_{\delta}(u) = \tanh(u)$ 

hence 
$$\frac{\partial}{\partial b} \left( h_{b}(u) \right)^{-2} = \frac{\partial}{\partial b} \tanh(a)$$

$$= 1 - \tanh^{2}(a)$$

$$= 1 - \left( h_{b}(u) \right)^{2}$$

$$= \left( 1 - h_{b}(u) \right) \left( 1 + h_{b}(u) \right)$$

$$S_{0}$$
,  $\frac{\partial}{\partial b} \left( L(b) \right) = 2 \left( g^{*} - h_{b}(u) \right) \left( 1 - h_{b}(u) \right) \left( 1 + h_{b}(u) \right) \cdot x$