```
1
       PROGRAM PLC PRG
 2
 3
          OpenGate: BOOL;
                                     //ENTRANCE sensor, this contact detects vehicle
       wanting to enter
          RedLightEnt : BOOL ;
                                     //ENTRANCE stop light, this coil controls the
       Red light at the
 5
           GreenLightEnt: BOOL; //ENTRANCE go light, this coil controls the Green
       light at the
 6
          TimeDelay: BOOL;
                                //ENTRANCE, this coil begins the timer which delays
       the open signal for the entrance gate
 7
           TON 0 : TON ;
                                     //ENTRANCE , the timer to control the entrance
       gate
8
          EntAnimator : CTUD;
                                     //ENTRANCE CTUD to control motor precisely
9
                                 //ENTRANCE coil to start motor - opens gate.
           CountOpen: BOOL;
1.0
           CloseGate : BOOL ;
                                 //ENTRANCE sensor, this contact detects vehicle has
       entered and it is now safe to close the gate
11
           CountClose: BOOL; //ENTRANCE coil to start motor - close gate.
12
           BlinkerOpen : TON ;
                                 //ENTRANCE timer to control CTUD open signal - Count
       up
13
           BlinkerClose: TON;
                                     //ENTRANCE Timer to control CTUD close signal -
       Count down
14
          GateCountValue : WORD ; //ENTRANCE
1.5
           CloseLimit: BOOL; //ENTRANCE coil to detect gate is done closing
                                  //ENTRANCE coil to detect gate is done opening
16
           OpenLimit: BOOL;
17
           OpenExGate : BOOL ;
                                     //EXIT sensor, this contact detects vehicle
       wanting to exit
                                          //EXIT coil to start motor - opens gate.
18
          CountExOpen : BOOL ;
                                          //EXIT coil to start motor - close gate.
19
           CountExClose : BOOL ;
20
           CloseExGate : BOOL ;
                                          //EXIT sensor, this contact detects vehicle
       has exited and it is now safe to close the gate
                                         //EXIT timer to control CTUD open signal -
21
          BlinkerExOpen : TON;
       Count up
          BlinkerExClose : TON ;
                                    //EXIT Timer to control CTUD close signal -
       Count down
23
           OpenExLimit : BOOL ;
                                          //EXIT coil to detect gate is done opening
           CloseExLimit : BOOL ;
                                          //EXIT coil to detect gate is done closing
25
           ExGateCountValue : WORD ;
                                          //EXIT
26
           ExtAnimator : CTUD;
                                           //EXIT CTUD to control motor precisely
27
           RedLightEx : BOOL ;
                                      //EXIT stop light, this coil controls the Red
       light
                                          //EXIT go light, this coil controls the
28
           GreenLightEx : BOOL ;
       Green light
29
           SpikesAnimator: CTUD;
                                          //Spikes Barrier CTUD to control the spikes
       motor precisely
30
           SpikesBarrierAngle : WORD ;
                                          //Spikes Barrier
31
           SpikeOpenLimit : BOOL ;
                                          //Spikes Barrier coil to detect spikes is
       done deploying
32
          SpikeCloseLimit : BOOL ;
                                             //Spikes Barrier coil to detect spikes
       is done retracting
33
          CDSpikes: BOOL;
                                             //Spikes Barrier coil to start motor -
       retract barrier
                                             //Spikes Barrier timer to control the
34
          BlinkerSpikes: TON;
```

```
CTUD retract signal - Count down
35
          CUSpikes : BOOL ;
                                            //Spikes Barrier coil to start motor -
       deploy barrier
36
          BlinkerSpikesClose: TON; //Spikes Barrier timer to control the CTUD
       deploy signal - Count down
37
          CTUD 0 : CTUD ;
                                     //ParkingVariable CTUD to track the number of
       vehicles that have entered and exited
38
          ParkingIncrement : BOOL ;
                                        //ParkingVariable coil to increment number
       of vehicles present in the parking
39
          ParkingDecrement: BOOL; //ParkingVariable coil to decrement number
       of vehicles present in the parking
          Vehicles: WORD ; //ParkingVariable number of vehicles present in
40
       parking stored in word form.
          VehiclesINT : INT ;
                                    //ParkingVariable integer variable to store
41
       number of vehicles present.
42
          SevenSegmentDisplay: INT;
                                        //SevSeg integer variable to store the
       difference between parking available and vehicles present
          SevSeg_0 : SevSeg ;
43
                                        //SevSeg instance of 7 segement display from
       function block created
44
          EnableDisplay: BOOL;
                                        //SevSeg enable coil for the 7 segment
       display
45
           SevSeg 1 : SevSeg ;
                                         //SevSeg instance of 7 segement display from
       function block created
       END_VAR
46
47
```











