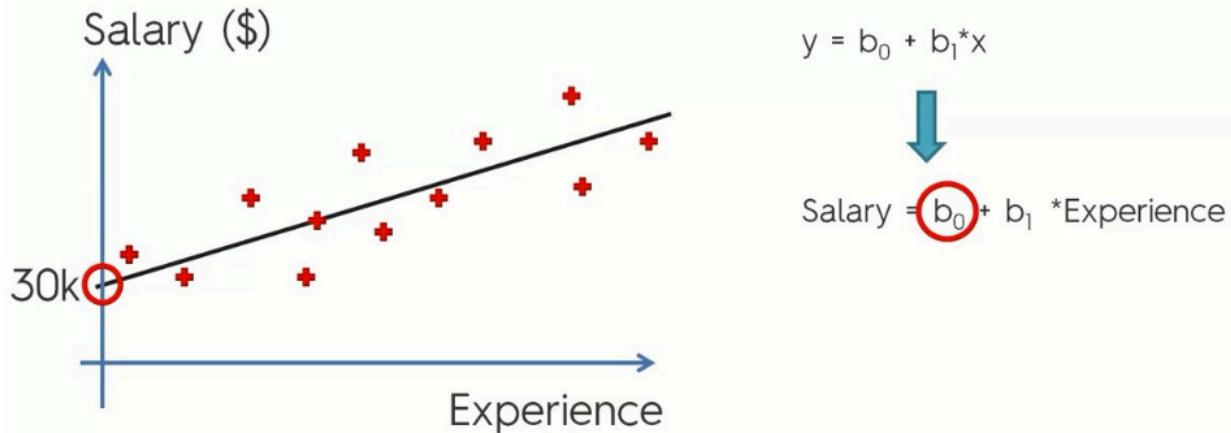


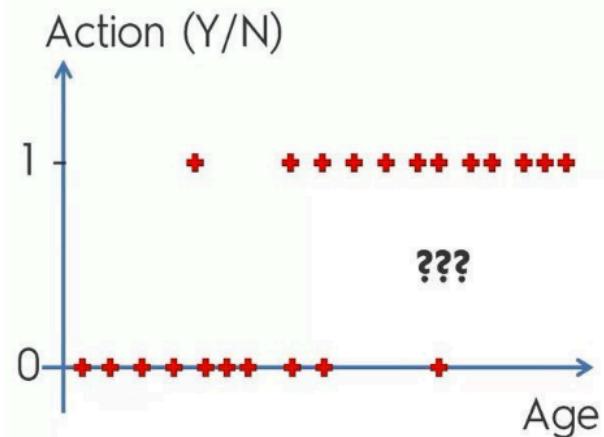
Logistic Regression

Simple Linear Regression:

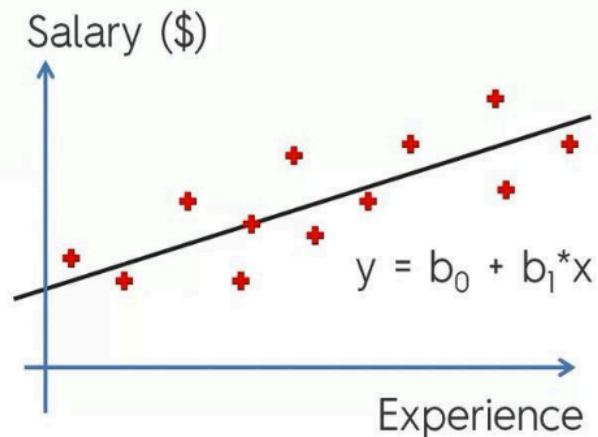


Logistic R vs Linear R

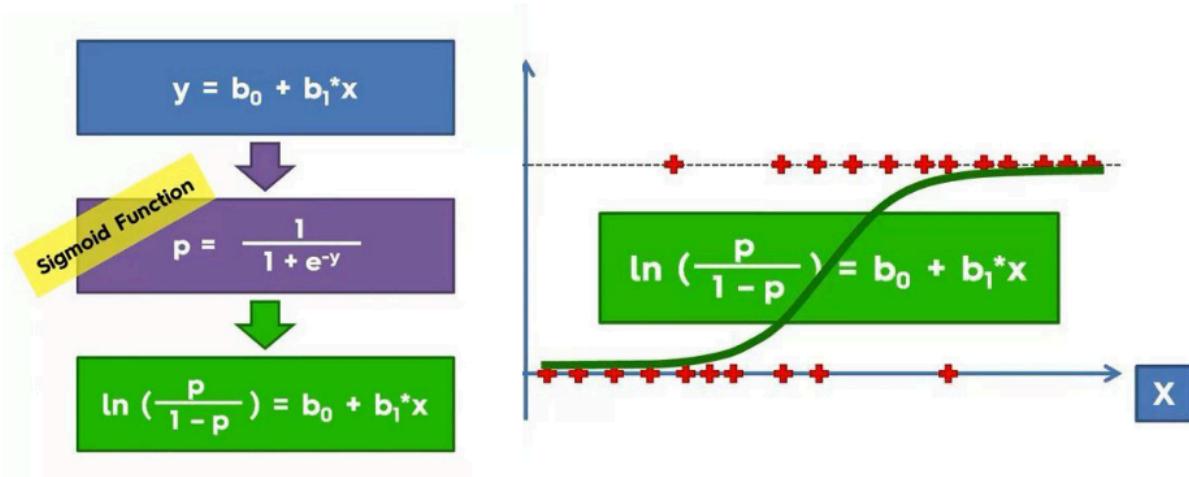
This is new:



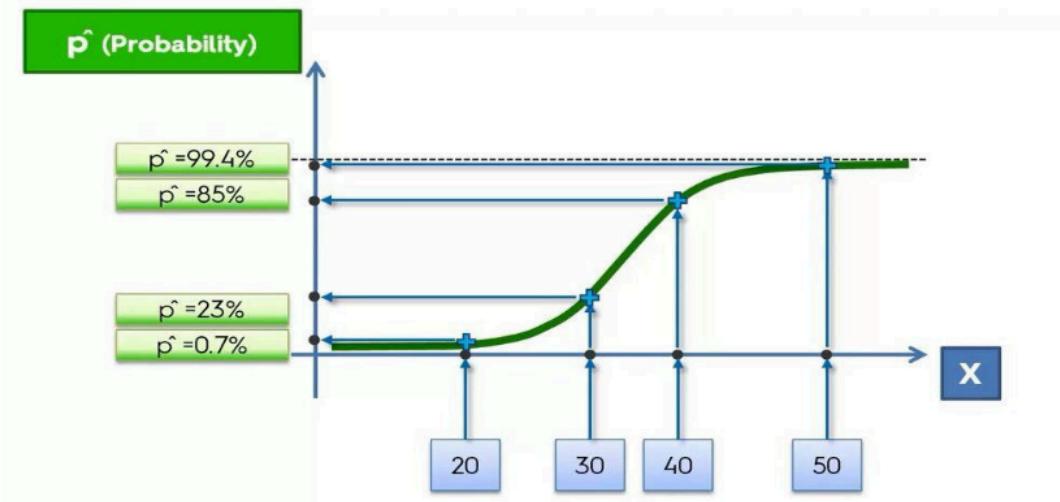
We know this:



Logistic Regression Formula



Logistic Regression working



Bayes' theorem

In probability theory and statistics, Bayes' theorem describes the probability of an event, based on prior knowledge of conditions that might be related to the event

$$P(A|B) = P(A) P(B|A)$$

$$P(B)$$

Bayes' theorem



Machine 1

30 Bread per hour



Machine 2

20 Bread per hour

Bayes' theorem

Machine1: 30 Breads / hr

Machine2: 20 Breads /hr

Out of all product parts:

We can SEE that 1% are defective

Out of all defective parts:

We can See that 50% came from Machine1

And 50% came from Machine2

What is probability that a part produced by machine1

Is defective =?

$$\Rightarrow P(\text{Machine1}) = 30/50 = 0.6$$

$$\Rightarrow P(\text{Machine2}) = 20/50 = 0.4$$

$$\Rightarrow P(\text{Defect}) = 1\% \Rightarrow$$

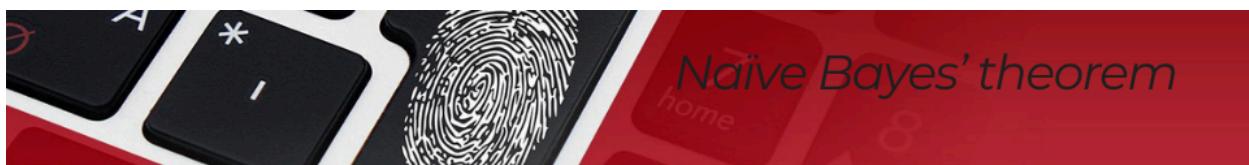
$$P(\text{Machine1} | \text{Defect}) = 50\%$$

$$\Rightarrow P(\text{Machine2} | \text{Defect}) =$$

$$50\%$$

$$\Rightarrow P(\text{Defect} | \text{Machine2}) = ?$$

$$P(\text{Defect} | \text{Machine2}) = \frac{P(\text{Machine2} | \text{Defect}) * P(\text{Defect})}{P(\text{Machine2})} \quad P(\text{Defect} | \text{Machine2}) = \frac{0.5 * 0.01}{0.4} = 0.0125 \Rightarrow 1.25\%$$

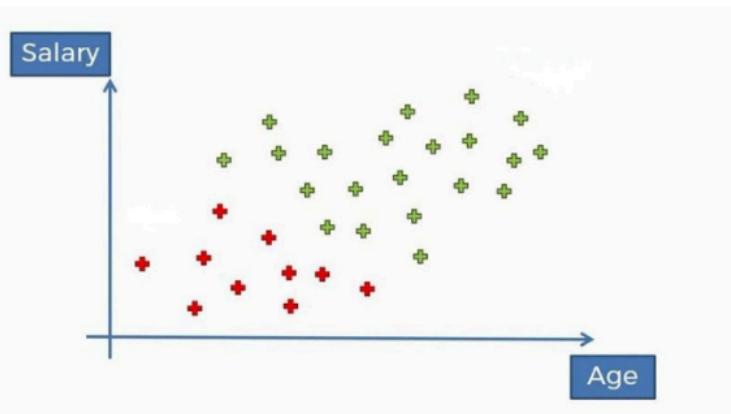


It is a classification technique based on Bayes' Theorem with an assumption of independence among predictors. In simple terms, a Naive Bayes classifier assumes that the presence of a particular feature in a class is unrelated to the presence of any other feature.

$$P(A|B) = \frac{P(A) P(B|A)}{P(B)}$$

$$\begin{aligned}
 \text{Posterior Probability} &\quad \text{Likelihood } 0.3 \\
 P(\text{ClassA} | X) &= \frac{P(X | \text{ClassA}) * P(\text{ClassA})}{P(X)} \quad \text{Prior Probability } 0.33 \\
 &\quad \text{Marginal Probability } 0.13
 \end{aligned}$$

Fahad Hussain



$$P(\text{ClassA}) = 10 / 30 = 0.33$$

$$P(\text{ClassB}) = 20 / 30 = 0.66$$

$$\text{Using Circle } P(X) = 4 / 30 = 0.13$$

$$\text{Using Circle } P(X) = 4 / 30 = 0.13$$

Using Ciriclewith Red Data

$$P(X | \text{ClassA}) = 3 / 10 = 0.3$$

Using Ciriclewith Red Data

$$P(X | \text{ClassB}) = 1 / 20 = 0.05$$

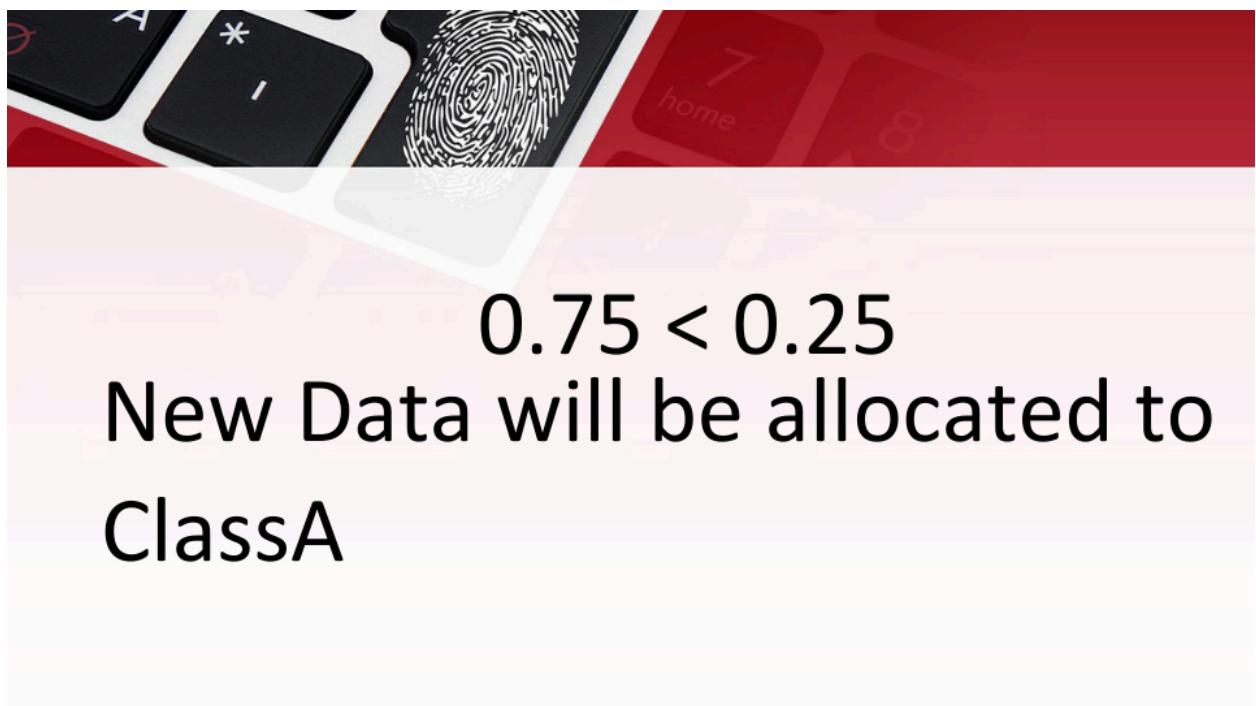
$$P(\text{ClassB} | X) = \frac{P(X | \text{ClassB}) * P(\text{ClassB})}{P(X)}$$

Posterior Probability

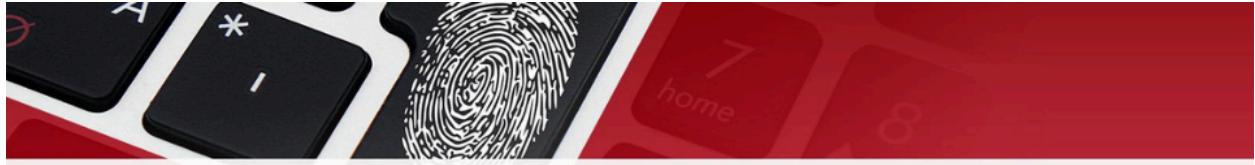
Likelihood

Prior Probability

Marginal Probability



0.75 < 0.25
New Data will be allocated to
ClassA

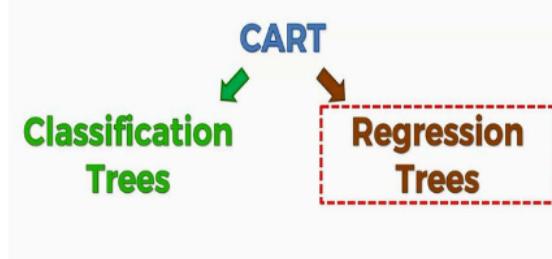


There are three types of Naive Bayes model under the scikit-learn library:

- **Gaussian**: It is used in classification and it assumes that features follow a normal distribution.
- **Multinomial**: It is used for discrete counts. For example, let's say, we have a text classification problem. Here we can consider Bernoulli trials which is one step further and instead of "word occurring in the document", we have "count how often word occurs in the document", you can think of it as "number of times outcome number x_i is observed over the n trials".
- **Bernoulli**: The binomial model is useful if your feature vectors are binary (i.e. zeros and ones). One application would be text classification with 'bag of words' model where the 1s & 0s are "word occurs in the document" and "word does not occur in the document" respectively.

Decision Tree Classifier

A Classification And Regression Tree (CART), is a predictive model, which explains how an outcome variable's values can be predicted based on other values. ACART output is a decision tree where each fork is a split in a predictor variable and each end node contains a prediction for the outcome variable



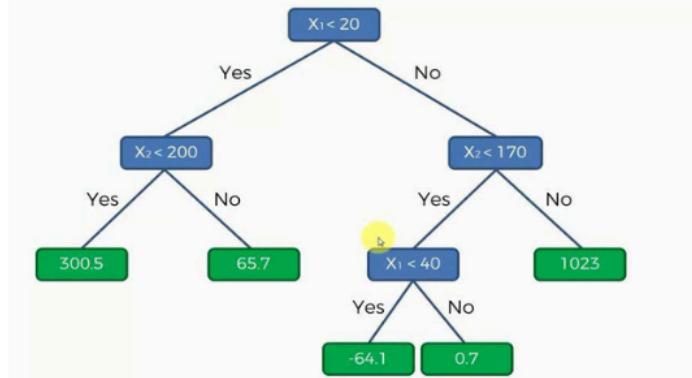
Decision Tree Classifier

Decision Tree Learning Algorithm

- There are many specific decision-tree algorithms. Notable ones include:
 - ID3 (Iterative Dichotomiser 3)
 - C4.5 (successor of ID3)
 - CART (Classification And Regression Tree)
 - CHAID (Chi-squared Automatic Interaction Detector). Performs multi-level splits when computing classification trees.
 - MARS: extends decision trees to handle numerical data better.

ID3 Decision Tree Classifier

ID3: The core algorithm for building decision trees is called **ID3**. Developed by J. R. Quinlan, this algorithm employs a top-down, greedy search through the space of possible branches with no backtracking. ID3 uses *Entropy* and *Information Gain* to construct a decision tree.



Concept to map Decision Tree

Information Gain: The information gain is based on the decrease in entropy after a data-set is split on an attribute. Constructing a decision tree is all about finding attribute that returns the highest information gain (i.e., the most homogeneous branches)

OR [a measure of the decrease in disorder achieved by partitioning the original dataset]

Entropy : Entropy, as it relates to machine learning, is a measure of the randomness in the information being processed. The higher the entropy, the harder it is to draw any conclusions from that information. Flipping a coin is an example of an action that provides information that is random. ... This is the essence of entropy.

. Or [is a measure of disorder in a dataset]

ID3 Decision Tree Classifier



Concept to map Decision Tree

$$E(S) = \sum_{i=1}^c -p_i \log_2 p_i$$

Play Golf	
Yes	No
9	5

L →

$$\begin{aligned} \text{Entropy(PlayGolf)} &= \text{Entropy}(5,9) \\ &= \text{Entropy}(0.36, 0.64) \\ &= -(0.36 \log_2 0.36) - (0.64 \log_2 0.64) \\ &= 0.94 \end{aligned}$$

$$\begin{aligned}
 &= -p / p + n * \log(p / p + n) - n / p + n * \log(n / p + n) \\
 &= -9 / 14 + 5 * \log(9 / 14) - 5 / 14 + 5 * \log(5 / 14) \\
 \text{Here } p &= 9, n = 5 \quad \text{also for log2 = log(?) / log(2)}
 \end{aligned}$$

Concept to map Decision Tree

$$E(T, X) = \sum_{c \in X} P(c) E(c)$$

$$-\log_5 \frac{2}{5} - \frac{3}{5} \log \frac{3}{5} = 0.970$$

		Play Golf		
		Yes	No	
Outlook	Sunny	3	2	5
	Overcast	4	0	4
	Rainy	2	3	5
				14

↓

$$-\log_5 \frac{4}{5} - \frac{3}{5} \log 0 = 0$$

$$-\log_5 \frac{3}{5} - \frac{2}{5} \log 2/5 = 0.970$$

$$\begin{aligned}
 E(\text{PlayGolf, Outlook}) &= P(\text{Sunny}) * E(3,2) + P(\text{Overcast}) * E(4,0) + P(\text{Rainy}) * E(2,3) \\
 &= (5/14) * 0.971 + (4/14) * 0.0 + (5/14) * 0.971 \\
 &= 0.693
 \end{aligned}$$

Concept to map Decision Tree

$$E(T, X) = \sum_{c \in X} P(c)E(c)$$

		Play Golf		
		Yes	No	
Outlook	Sunny	3	2	5
	Overcast	4	0	4
	Rainy	2	3	5
				14



$$\begin{aligned}
 E(\text{PlayGolf}, \text{Outlook}) &= P(\text{Sunny}) * E(3,2) + P(\text{Overcast}) * E(4,0) + P(\text{Rainy}) * E(2,3) \\
 &= (5/14) * 0.971 + (4/14) * 0.0 + (5/14) * 0.971 \\
 &= 0.693
 \end{aligned}$$

$$\text{Entropy } E(A) = \pi_i + ni / p + n * (I(p,n))$$

Concept to map Decision Tree

		Play Golf		Gain = 0.247
		Yes	No	
Outlook	Sunny	3	2	
	Overcast	4	0	
	Rainy	2	3	

		Play Golf		Gain = 0.029
		Yes	No	
Temp.	Hot	2	2	
	Mild	4	2	
	Cool	3	1	

Information Gain

$$Gain(T, X) = Entropy(T) - Entropy(T, X)$$

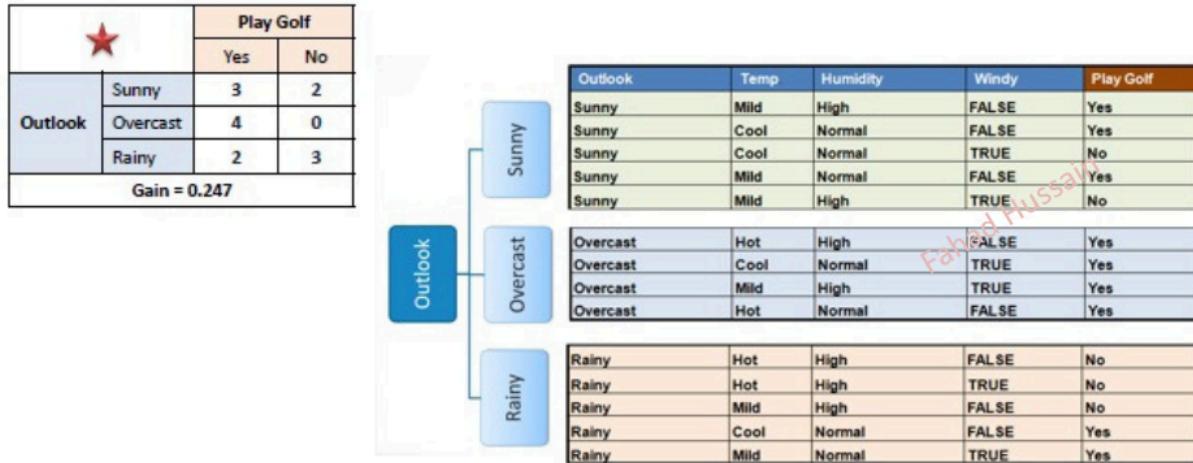
		Play Golf		Gain = 0.152
		Yes	No	
Humidity	High	3	4	
	Normal	6	1	

		Play Golf		Gain = 0.048
		Yes	No	
Windy	False	6	2	
	True	3	3	

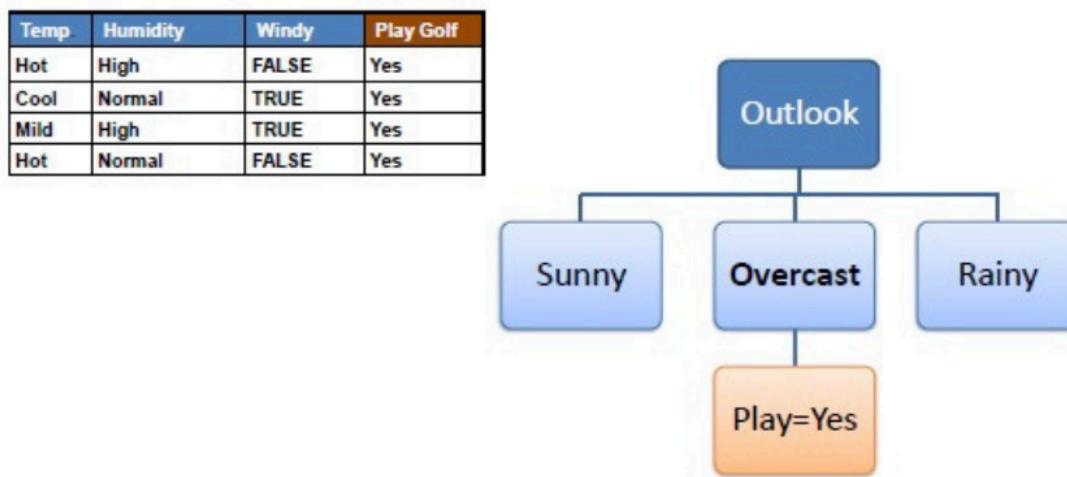
$$G(\text{PlayGolf}, \text{Outlook}) = E(\text{PlayGolf}) - E(\text{PlayGolf}, \text{Outlook})$$

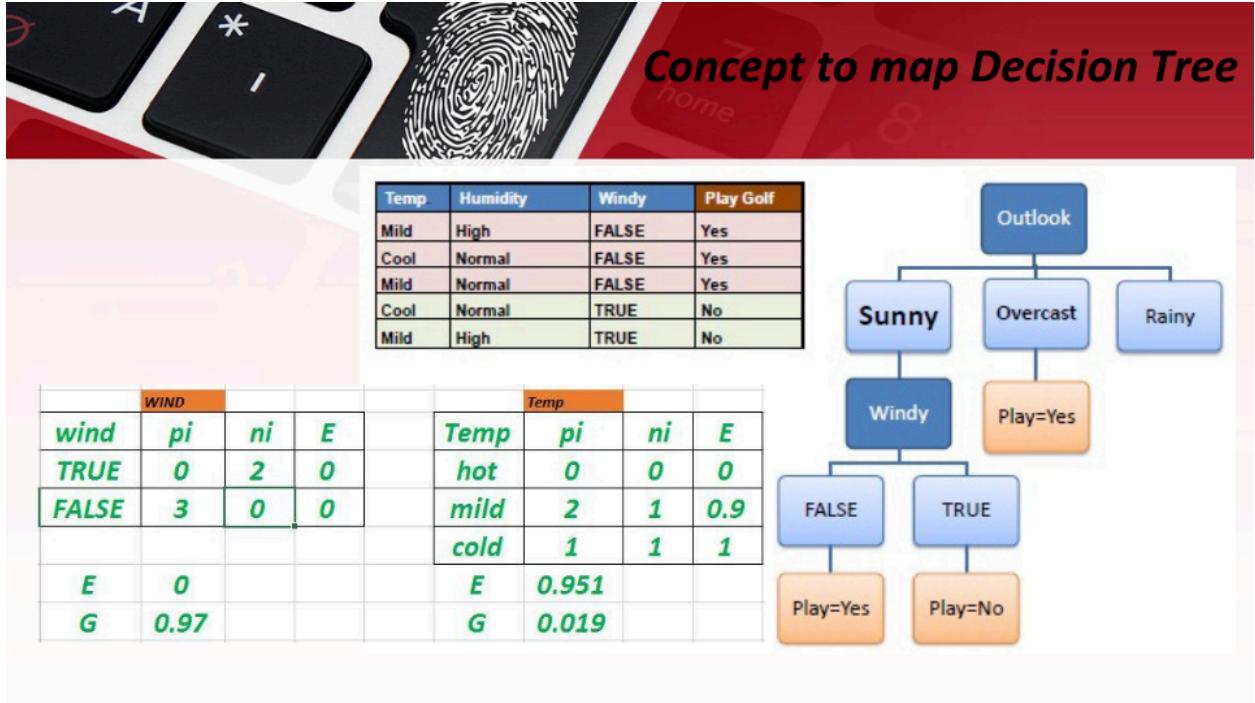
$$= 0.940 - 0.693 = 0.247$$

Concept to map Decision Tree



Concept to map Decision Tree





Concept to map Decision Tree

A decision tree can easily be transformed to a set of rules by mapping from the root node to the leaf nodes one by one.

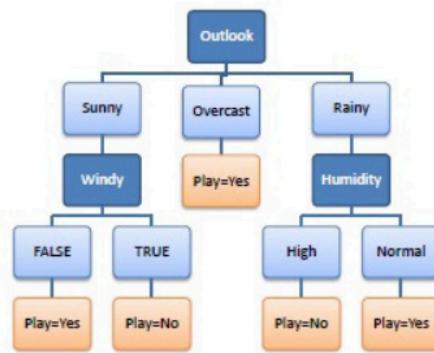
R₁: IF (Outlook=Sunny) AND (Windy=FALSE) THEN Play=Yes

R₂: IF (Outlook=Sunny) AND (Windy=TRUE) THEN Play=No

R₃: IF (Outlook=Overcast) THEN Play=Yes

R₄: IF (Outlook=Rainy) AND (Humidity=High) THEN Play=No

R₅: IF (Outlook=Rain) AND (Humidity=Normal) THEN Play=Yes



Concept to map Decision Tree

Gini Index

Gini index says, if we select two items from a population at random then they must be of same class and probability for this is 1 if population is pure.

It can be used only if the target variable is a binary variable Classification and regression Tree (CART).

Concept to map Decision Tree

$$Gini(D) = 1 - \sum_{i=1}^m p_i^2,$$

$$Gini(D) = 1 - \left(\frac{9}{14}\right)^2 - \left(\frac{5}{14}\right)^2 = 0.459$$

RandomForestTree Classifier

In statistics and machine learning, ensemble methods use multiple learning algorithms to obtain better predictive performance than could be obtained from any of the constituent learning algorithms alone.

Steps to make RandomForestTree Classifier

STEP 1: Pick at random K data points from the Training set.

STEP 2: Build the Decision Tree associated to these K data points.

STEP 3: Choose the number Ntreeof trees you want to build and repeat STEPS 1 & 2

STEP 4: For a new data point, make each one of your Nstreetrees predict the category to which the data points belongs, and assign the new data point to the category that wins the majority vote.

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