

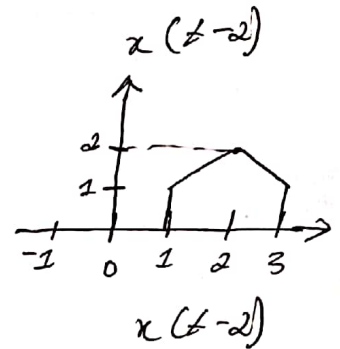
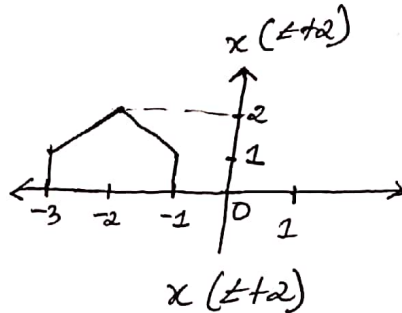
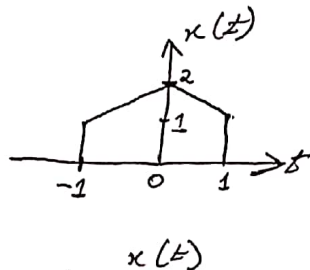
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Subject: Basics of Signal Systems, Semester:- 3rd

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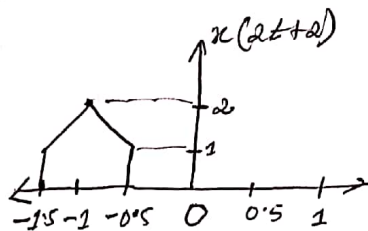
CIF-1

1. Soln:-



(i) For $x(2t+2)$

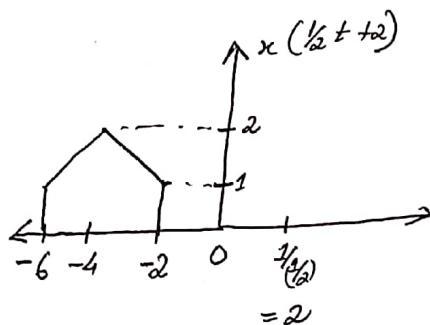
$$x(t) \rightarrow x(t+2) \rightarrow x(2t+2)$$



[Dividing t by 2]

(ii) For $x(\frac{1}{2}t+2)$

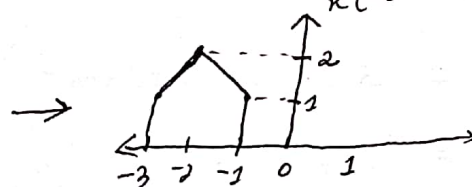
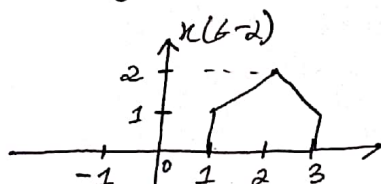
$$x(t) \rightarrow x(t+2) \rightarrow x(\frac{1}{2}t+2)$$



[Stretching t by $\frac{1}{2}$]

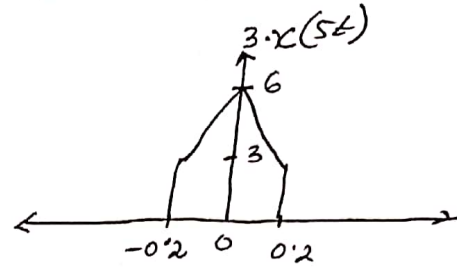
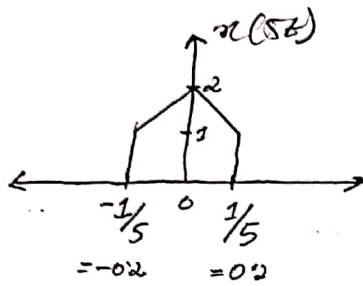
(iii) For $x(-t-2)$

$$x(t) \rightarrow x(t-2) \rightarrow x(-t-2)$$



1. (iv) Soln: for $3 \cdot x(5t)$

$$x(t) \rightarrow x(5t) \rightarrow 3 \cdot x(5t)$$



3) (i) Soln: Given,

$$x(t) = \cos t + \sin t + \cos t \sin t$$

Now,

$$x(-t) = \cos(-t) + \sin(-t) + \cos(-t) \sin(-t)$$

$$= \cos t - \sin t + \cos t (-\sin t)$$

$$= \cos t - \sin t - \cos t \sin t$$

$$\therefore x_{\text{even}}(t) = \frac{x(t) + x(-t)}{2}$$

$$= \frac{\cos t + \sin t + \cos t \sin t + \cos t - \sin t - \cos t \sin t}{2}$$

$$= \frac{2 \cos t}{2}$$

$$= \cos t$$

$$\& x_{\text{odd}}(t) = \frac{x(t) - x(-t)}{2}$$

$$= \frac{\cos t + \sin t + \cos t \sin t - \cos t + \sin t + \cos t \sin t}{2}$$

$$= \sin t + \cos t \sin t$$

$$= \sin t (1 + \cos t)$$

3. (ii) Soln: Given, $x(n) = \{-2, 1, 2, -1, 3\}$

Now, $x(-n) = \{3, -1, 2, 1, -2\}$

$$x_{\text{even}}(n) = \frac{x(n) + x(-n)}{2}$$

~~$$= \{1, 0, 2, 0, 1\}$$~~

$$= \frac{1}{2} [1, 0, 4, 0, 1]$$

$$= [0.5, 0, 2, 0, 0.5]$$

$$= \{0, 2, 0\}$$

$$x_{\text{odd}}(n) = \frac{x(n) - x(-n)}{2}$$

$$= \frac{1}{2} [-5, 2, 0, -2, 5]$$

$$= [-2.5, 1, 0, -1, 2.5]$$

$$= \{1, 0, -1\}$$

2) Soln: Given, $x(n) = 2e^{i3\pi n}$

Now, Energy of the signal, $E = \sum_{n=-L}^L [x(n)]^2$

$$= \sum_{n=-L}^L [2e^{i3\pi n}]^2 = \sum_{n=-L}^L [2e^{i6\pi n}]^2$$

$$= L$$

And, power of the signal, $P = \frac{1}{2T} \sum_{n=-T}^T [x(n)]^2$

$$= \frac{1}{2T} \sum_{n=-T}^T [2e^{i3\pi n}]^2$$

$$= \frac{1}{2} \sum_{n=-T}^T (2e^{i3\pi n})$$

which is finite. i.e.

$$P < \infty$$

∴ $x(n)$ is a power signal

4. (i) Solⁿ Given,

$$x(t) = \cos\left(\frac{1}{3}t\right) + \sin\left(\frac{1}{4}t\right)$$

Now, Let, $x_1(t) = \cos\left(\frac{1}{3}t\right)$ & $x_2(t) = \sin\left(\frac{1}{4}t\right)$

Now, $\omega_1 = \frac{1}{3}$

& $\omega_2 = \frac{1}{4}$

∴ $2\pi f_1 = \frac{1}{3}$

∴ $2\pi f_2 = \frac{1}{4}$

⇒ $f_1 = \frac{1}{6\pi}$

⇒ $f_2 = \frac{1}{8\pi}$

or, $T_1 = 6\pi$ seconds.

i.e. $T_2 = 8\pi$ seconds.

Now, $\frac{T_1}{T_2} = \frac{6\pi}{8\pi} = \frac{6}{8} = \frac{3}{4} = \text{rational.}$

Hence, $x(t)$ is periodic

4. (ii). Solⁿ: Given,

$$x(t) = u(t) - u(t-10)$$

Let, $x_1(t) = u(t)$

& $x_2(t) = u(t-10)$

Now, $u(t) = \begin{cases} 1, & t \geq 0 \\ 0, & t < 0 \end{cases}$

$$u(t-10) = \begin{cases} 1, & t \geq 10 \\ 0, & t < 10 \end{cases}$$

i.e. $u(t)$ is not periodic.

i.e. $u(t-10)$ is not periodic.

Hence,

$x(t) = u(t) - u(t-10)$ is not periodic.

5) Solⁿ

Given,

$$x(t) = \frac{d^3 y(t)}{dt^3} + 4 \cdot \frac{d^2 y(t)}{dt^2} + 5 \cdot \frac{dy(t)}{dt} + dy^2(t)$$

(a) for, ~~at~~

$$x(-1) = \frac{d^3 y(-1)}{dt^3} + 4 \cdot \frac{d^2 y(-1)}{dt^2} + 5 \cdot \frac{dy(-1)}{dt} + dy^2(-1)$$

$$x(0) = \frac{d^3 y(0)}{dt^3} + 4 \cdot \frac{d^2 y(0)}{dt^2} + 5 \cdot \frac{dy(0)}{dt} + dy^2(0)$$

$$x(1) = \frac{d^3 y(1)}{dt^3} + 4 \cdot \frac{d^2 y(1)}{dt^2} + 5 \cdot \frac{dy(1)}{dt} + dy^2(1)$$

As the present of S depend only on present ips
 o. The system is static.

(b) ∴ The coefficients of $x(t)$ are independent of time (t) ,

∴ The system is linear.

(c) As at any instant of time (t) , the present i/p depends only on the present i/p and doesn't need future i/p.

∴ The system is casual.

(d) Here let
$$y(t) = \frac{d^3 y(t)}{dt^3} + 4 \cdot \frac{d^2 y(t)}{dt^2} + 5 \cdot \frac{dy(t)}{dt} + 2y''(t)$$

~~$$y(t, T) = \frac{d^3 y(t, T)}{dt^3}$$~~

∴ $y(t, T) = y(t - T)$

∴ The system is time-invariant

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