				LIFE INSURANCE C	ORPORATION OF INDIA
The relo	Lion betu	seen The	input	$\alpha(t)$ an	id the
output	y(+) of	a systim	n has	The form	N
	y (t) =	The state of the s	*** ******* * *************************		
Mathematic	cally, y (+)	=T[x(4)]		-	,
Like,	signals	systems	may	also	be
broadly	signals classified	inder			
	(à) Con	linuous-l	ine sy	slim	7.11.
. 5 %	(h) N°.	y(+) = T	[x4)] V	4 Q 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	
		creti - lu			
1.00	1 2 3	y(m) =			
				4 4 4	

Both continuous-line and discrete-line
Systems may be classified as under-
D'emped parameter and distributed parameter system.
& Statio (memoryless) and dynamic (memory) system.
3 Causal and non-causal system:
4) Linear and non-linear system.
(5) Junie - invarié and and time varying system.
6) Stable and unstable system.
(7) Inverlible and non-inverlible system.
(8) FIR and IIR system.

D LUMPED parameter and DISTRIBUTED parameter systems:
systems:
- Systems in which each part component is
lumped at one point in space - dumped parameter
systems. Described by ordinary differential egns.
- Systems in which signals are functions of
space as well as lime. These are called distributed
parameter systems. Described by partial diffreque.
Détatic and Dynamic System: -
- A system is deze 15 said to be static
or memoreyless, if the response is due to
present input alone; i.e. fore a static or
memoryless system, the output at any instant

d (on on) depends only on the input applied at that instant t (one n) but not on the past on future valuel of input. 7(1) = 2(4) y(1) = x2(1) nemory system if the rusponse depends upon past on future values. inputs. lg!- g(1) = a(1-1)y(1) = x(1) + x(1+2).

· · · · · · · · · · · · · · · · · · ·		FILE HISTINANCE CONTONATION
8. find whether the following dynamic ore not:	systim	s are
olynamic ore not:		
		A Principal Annual Annu
		and the state of t
$\widehat{A} \text{u(4)} = 2 \left(1 - 2 \right)$	ternocations are relative as a classic effects between the process finances in	
(a) $y(4) = x(4-3)$		
(6) w(1) - a(0+)		
(6) y(t) = x(2t)		j
3	11 2	•
$(3) y(1) = d^{2}n(1) + 2x(1)$	1	
CT	J. ·	
(d) y(m) = 2(n+2)		-
		· · · · · · · · · · · · · · · · · · ·
$(p) y(n) = \alpha^2(n)$		
$y(n) = x^{2}(n)$		
$(2) \cdot (2) = \alpha (m \cdot 2) + \alpha (m)$	ý	
$(f) y(n) = \alpha(n-2) + \alpha(n)$		
V		
		. (
	- 1	
Late day and the control of the cont	3	
	/	1

(3) Causal and Non-Causal systems: -· A system is said to be causal if the output of the system at any time to depends only on the present and the part Values of the input but not on the inputs y(t) = x(t-2) + 2x(t)y(t) = + x(t)y(n) = nx(n)y(m) = x(n-2) + x(m-1)A system is see paid to be non-causal The output of the system at any time '1' depends of on The future inputs.

eq:
$$y(t) = \alpha(1+2) + \alpha(1)$$
 $y(t) = x^{2}(1) + 1\alpha(1+1)$
 $y(n) = \alpha(n) + \alpha(2n)$

8 Check whether the following systems are causal or not:

(a) $y(t) = x^{2}(1) + \alpha(1-4)$

(b) $y(t) = \alpha(2-t) + \alpha(1-4)$

(c) $y(t) = x(2-t) + \alpha(1-4)$

(d) $y(t) = \alpha(1/2)$

(e) $y(n) = x(2n)$

(f) $y(n) = \alpha(-n)$.

(a) ty inen, $y(x) = x^{2}(1) + x(1-4)$ for 1 = -2, $y(-2) = x^{2}(-2) + x(-6)$ for 1 = 0, $y(0) = x^{2}(0) + x(-4)$ for 1 = 2, $y(2) = x^{2}(2) + x(-2)$.

2. For all values of 1, the output depends only on the present and past values of input. So, the system is causal.

B Guin, $y(t) = \chi(2-t) + \chi(t-4)$ For t = 1, $y(-1) = \chi(3) + \chi(-5)$ For t = 0, $y(0) = \chi(2) + \chi(-4)$ For t = 1, $y(1) = \chi(1) + \chi(-3)$ For some values of t, the output depends on the future i/p. i: Systim is mon-causal.