## Dr Debajyoti **Karmaker** PhD, MS, BS Computer Science

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i Born 29<sup>th</sup> September 1984, Bangladesh



I am a Postdoctoral Research Fellow at Australian National University (ANU), currently hosted by Dr. Hanna Kurniwati. Before joining ANU, I completed my Ph.D. from The University of Queensland (UQ) on September, 2019, under the supervision of Prof. Mandyam V. Srinivasan. My research interests are in computer vision, machine learning, and deep learning. I am particularly interested in the areas of collision avoidance strategies, Robust Decision-making and Learning, and Object detection. Before starting my PhD, I was working as a lecturer at the American International University-Bangladesh (AIUB) - in the department of Computer Science. I also worked as a software engineer at Infra Blue Technology (IBT Games).

## **Q** Research Interest

- > Computer Vision
- > Machine Learning
- > Deep Learning
- > Biologically-inspired mid-air collision avoidance strategies for Unmanned Aircraft Systems (UAS)
- > Decision-making under uncertainty



## CURRENT POSITION

## > Postdoctoral Research Fellow

Robust Decision-making and Learning (RDL) Lab Australian National University (ANU), Australia. https://cecs.anu.edu.au/people/debajyoti-karmaker



## WORK EXPERIENCE

## August 2019 May 2018

## Research Assistant, QUEENSLAND BRAIN INSTITUTE (QBI), Australia

- > Conduct experimental investigation of visually guided bird flight
- > Develop computer vision algorithms for reliable automated detection of birds in videos and still images, automatic identification and localization of their parts (head, tail, wingtips)
- > Data analysis and modeling of biologically inspired guidance laws and algorithms for avoiding mid-air collisions in unmanned aircraft systems (UAS)

#### May 2015

## Assistant Professor, Department of Computer Science, American International University (AIUB), Bangladesh

## September 2013

- > Developing materials for lectures, tutorials, assignments, lab demonstrations and exams.
- > Deliver lectures and motivate students to take part in classroom discussions.
- > Conduct independent research and supervise final year undergraduate research projects.
- > Assist students during course enrollment.
- > Organize workshops and seminars.

## August 2013 September 2010

## Lecturer, Department of Computer Science, AMERICAN INTERNATIONAL UNIVERSITY (AIUB), Bangladesh

- > Deliver lectures and motivate students to take part in classroom discussions.
- > Provide students with academic advices during consultation hours.
- > Assist students during course enrollment.
- > Organize workshops and seminars.

## August 2010 September 2008

#### Software Engineer, INFRA BLUE TECHNOLOGY (IBT GAMES), Bangladesh

- > Coordinate with the Technical Director on current programming tasks.
- > Collaborate with other programmers to design and implement features.
- > Quickly produce well-organized, optimized, and documented source code.
- > Create and document software tools required by artists or other developers.
- > Debug existing source code and polish feature sets.
- > Contribute to technical design documentation.
- > Work independently when required.
- > Continuously learn and improve skills.

PHP Python Data analysis Communication Explanation Leadership Team work



September 2019 | PhD in Computer Science, The University of Queensland (UQ), Australia

July 2015 | Thesis topic: Mid-air Collision Avoidance in Budgerigars and Potential Applications to UAV Guidance

Supervisor: Professor Mandyam Srinivasan

January 2011 M. Sc in Computer Science, AMERICAN INTERNATIONAL UNIVERSITY (AIUB), Bangladesh

**June 2009** Thesis: A fine grained technique for viral marketing based on social network: A machine learning approach.

Supervisor: Dr. Saiedur Rahman

February 2009 | B. Sc in Computer Science & Software Engineering, AMERICAN INTERNATIONAL UNIVERSITY (AIUB),

Bangladesh

**January 2005** Thesis: Global Motion tracking with six parameter model.

Supervisor: Dr. Ashfagur Rahman



## RESEARCH PUBLICATIONS

December 2018 D Karmaker, J Groening, I Schiffner, M Wilson, M V Srinivasan, Budgerigars adopt robust, but idiosyncratic

flight paths, Nature Scientific reports, doi: 10.1038/s41598-020-59013-3

December 2018 D Karmaker, I Schiffner, M Wilson, M V Srinivasan, Image denoising with Weighted ORientation-

Matched Filters (WORM), 15th IEEE International Conference on Robotics and Biomimetics (IEEE ROBIO), doi:

10.1109/ROBIO.2018.8665336

November 2018 D Karmaker, I Schiffner, M Wilson, M V Srinivasan, The bird gets caught by the WORM: tracking multiple

deformable objects in noisy environments using Weight ORdered logic Maps , 13th International Sympo-

sium on Visual Computing (ISVC), doi: 10.1007/978-3-030-03801-4\_30

January 2018 T L Molloy, G S Garden, T Perez, I Schiffner, D Karmaker, M V Srinivasan, An Inverse Differential Game Ap-

proach to Modelling Bird Mid-Air Collision Avoidance Behaviours , 8th IFAC Symposium on System Identi-

fication SYSID, doi: 10.1016/j.ifacol.2018.09.164

January 2016 D Karmaker, I Schiffner, R Strydom, M V Srinivasan, WHoG: A weighted HoG-based scheme for the detec-

tion of birds and identification of their poses in natural environments , 14th International Conference on

Control, Automation, Robotics and Vision (ICARCV), doi: 10.1109/ICARCV.2016.7838650

December 2015 MF Zaman, ST Mossarrat, FIslam, D Karmaker, Real-time hand detection and tracking with depth values,

International Conference on (ICAEE), doi: 10.1109/ICAEE.2015.7506813

May 2015 MA Imran, MSU Miah, H Rahman, A Bhowmik, D Karmaker, Face recognition using eigenfaces, Interna-

tional Journal of Computer Applications, Volume: 118 – No. 5

April 2015 D Karmaker, AZME Chowdhury, MSU Miah, MA Imran, MH Rahman, Cricket shot classification using mo-

tion vector, 2nd International Conference on Computing Technology and Information Management (ICCTIM),

doi: 10.1109/ICCTIM.2015.7224605

December 2014 MAU Rahman, MSU Miah, MAFahad, DKarmaker, SHIMPG: Simple human interaction with machine

using Physical Gesture, 13th International Conference on Control Automation Robotics & Vision (ICARCV), doi:

10.1109/ICARCV.2014.7064322

October 2011 H Rahman, D Karmaker, M S Rahaman, N Sultana, SMESRT: A protocol for multiple event-to-sink relia-

bility in WSN, International Journal of Engineering and Technology, Volume: 1 – No. 1

August 2011 D Karmaker, H Rahman, M S Rahaman, M K Bari, A fine grained technique for viral marketing based on

social network: A machine learning approach, International Journal of Science and Technology, Volume:

1 - No. 5

## PAPERS UNDER SUBMISSION

1. D Karmaker, I Schiffner, and M V Srinivasan. "Budgerigars adopt robust, but idiosyncratic flight paths"

Accepted for Nature Scientific Reports, 2019

Project paage: https://debajyotikarmaker.github.io/profile/preset\_path.html

2. **D Karmaker**, I Schiffner, J Groening, and M V Srinivasan. "Stretching Time and Space: How flying Budgerigars evade a moving obstacle"

Submitted to Proceedings of the Royal Society, 2019

Project paage: https://debajyotikarmaker.github.io/profile/pendulum.html

3. D Karmaker, and M V Srinivasan. "Ballistic collision avoidance in Budgerigars"

Submitted to Nature Communications, 2019

Project paage: https://debajyotikarmaker.github.io/profile/ballistic.html

4. D Karmaker, I Schiffner, J Groening, and M V Srinivasan. "Guidance laws for avoiding a bird-like obstacle"

Submitted to Journal of Experimental Biology, 2019

Project paage: https://debajyotikarmaker.github.io/profile/guidance\_law.html

## **Q** Conference Attendance, Posters and Talks

| December, 2018 | Oral presentation - "Image denoising with Weighted ORientation-Matched filters (WORM)" @ 15th IEEE International Conference on Robotics and Biomimetics (IEEE ROBIO), Kuala Lumpur, Malaysia   |
|----------------|--|
| December, 2018 | Annual Presentation @ Boeing Defence Australia (BDA), Brisbane, Australia  |
| November, 2018 | Oral presentation - "The bird gets caught by the WORM: tracking multiple deformable objects in noisy environments using Weight ORdered logic Maps" @ 13th International Symposium, International Symposium on Visual Computing (ISVC), Las Vegas, NV, USA      |
| July, 2018     | Poster presentation - "Budgerigar flight: Guidance laws for avoiding an stationary obstacle" @ International Conference of Neuroethology (ICN), Brisbane, Australia  |
| July, 2018     | Poster presentation - "Budgerigar flight: Guidance laws for avoiding an stationary obstacle" @ Queensland Brain Institute & Munich Center for Neurosciences (QBI-MCN), Brisbane, Australia   |
| May, 2018      | Tutorial on Deep Learning for Robotics Perception in the International Conference on Robotics and Automation (ICRA), Brisbane, Australia   |
| December, 2017 | Annual Presentation @ Boeing Defence Australia (BDA), Brisbane, Australia  |
| December, 2016 | Annual Presentation @ Boeing Defence Australia (BDA), Brisbane, Australia  |
| November, 2016 | Poster presentation - "WHoG: A weighted HoG-based scheme for the detection of birds and identification of their poses in natural environments" @ 9th Australasian Workshop on Neuro-Engineering and Computational Neuroscience (NeuroEng), Brisbane, Australia |
| November, 2016 | Workshop on Deep Learning: An Introduction for Neuroscientists and Modellers ( <b>NeuroEng</b> ), Brisbane, Australia  |
| November, 2016 | Oral presentation - "WHoG: A weighted HoG-based scheme for the detection of birds and identification of their poses in natural environments" @ 14th International Conference on Control, Automation, Robotics and Vision (ICARCV), Phuket, Thailand            |
| December, 2014 | Oral presentation - "SHIMPG: Simple human interaction with machine using physical gesture" @ 13th International Conference on Control, Automation, Robotics and Vision (ICARCV), Marina Bay Sands, Singapore   |

## TEACHING EXPERIENCE

## > Courses instructed as Assistant Professor at AIUB (September 2013 – May 2015)

- Computer Vision and Pattern Recognition (CSC 4138)
- Algorithms (CSC 2211)
- Web Technologies (CSC 3222)
- Programming Language 1 (CSC 1102)
- Programming Language 2 (CSC 1203)
- Object Oriented Programming 1 (CSC 2209)
- Object Oriented Programming 2 (CSC 3115)

## > Courses instructed as Lecturer at AIUB (September 2010 - August 2013)

- Programming Language 1 (CSC 1102)
- Programming Language 2 (CSC 1203)
- Object Oriented Programming 1 (CSC 2209)
- Web Technologies (CSC 3222)

# **?** ACHIEVEMENTS AND AWARDS

2018 QBI Travel Allowance

2015 – 2018 UQ International Scholarship (UQI)

2015 – 2018 Boeing - UQ Research Alliance PhD Scholarship

2014 Research Support grant (American International University-Bangladesh (AIUB))

2011 Chairmans Award (American International University-Bangladesh (AIUB))

2011 Summa Cum Laude (American International University-Bangladesh (AIUB))

# **S**KILLS

Deep Learning Frameworks TensorFlow, Keras, PyTorch

**Programming** Python, MATLAB, C, C++, Java, Microsoft .Net (C#)

Web Development PHP, java Script, ASP .Net, J2EE, Flash, Flex, Action Script, CSS

Database Oracle Database, MySQL, Microsoft SQL Server

Software Microsoft Office (Word, Excel, Powerpoint), ET<sub>E</sub>X, Adobe (Photoshop, Illustrator)

Development tools Eclipse, Visual Studio, gcc, SVN, git, Spyder, Jupyter Notebook, Visual Studio Code

Operating Systems Mac OS X, Windows (98 – 10), Linux (Ubuntu, CentOS, Arch)

## **+** STRENGTHS

- > Strong problem solving skill
- > Excellent presentation skill and proficient in technical writing

- > Self-motivated and ability to work both independently or in a team
- > Strong interpersonal and leadership qualities

# EXTRA-CURRICULAR ACTIVITIES

- > Strong problem solving skill
- > Excellent presentation skill and proficient in technical writing
- > Self-motivated and ability to work both independently or in a team
- > Strong interpersonal and leadership qualities

## 66 RÉFÉRENCES

#### Prof. Mandyam V. Srinivasan

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