## Adversarial-Examples

June 10, 2018

```
In [1]: import numpy as np
        import matplotlib.pyplot as plt
        import pandas as pd
        import random
        import tensorflow as tf
        from tensorflow.contrib.tensor_forest.python import tensor_forest
        from tensorflow.python.ops import resources
        from tensorflow.examples.tutorials.mnist import input_data
In [2]: np.random.seed(1)
0.1 1. Obtain the MNIST dataset and normalize it for use with a classifier.
In [4]: # The mnist dataset is already normalized
        mnist = input_data.read_data_sets("./data/", one_hot=True)
Extracting ./data/train-images-idx3-ubyte.gz
Extracting ./data/train-labels-idx1-ubyte.gz
Extracting ./data/t10k-images-idx3-ubyte.gz
Extracting ./data/t10k-labels-idx1-ubyte.gz
```

## 0.2 2. Select two different machine learning classification models

#### 0.2.1 A: Logistic regression

```
# Set model weights
    self.W = tf.Variable(tf.zeros([input_size, output_size]))
    self.b = tf.Variable(tf.zeros([output_size]))
    # Construct model
    self.pred = tf.nn.softmax(tf.matmul(self.x, self.W) + self.b)
    self.correct_pred = tf.equal(tf.argmax(self.pred, 1), tf.argmax(self.y, 1))
    self.accuracy = tf.reduce_mean(tf.cast(self.correct_pred, tf.float32))
    # Minimize error using cross entropy
    self.loss = tf.reduce_mean(-tf.reduce_sum(self.y*tf.log(self.pred), reduction_in
    # Gradient Descent
    self.optimizer = tf.train.GradientDescentOptimizer(self.learning_rate).minimize(
    # Calculate loss with respect to input
    self.gradient_input = tf.gradients(self.loss, self.x)[0]
    # Initialize the variables (i.e. assign their default value)
    self.init = tf.global_variables_initializer()
def fit(self, images, labels, sess = None):
    sessionCreated = False
    if sess is None:
        sess = tf.Session()
        sess.run(self.init)
        sessionCreated = True
    # Training cycle
    for epoch in range(self.training_epochs):
        avg_loss = 0.
        total_batch = int(len(images)/self.batch_size)
        # Loop over all batches
        for i in range(total_batch):
            batch_xs = images[i*self.batch_size: (i+1)*self.batch_size]
            batch_ys = labels[i*self.batch_size: (i+1)*self.batch_size]
            # Run optimization op (backprop) and loss op (to get loss value)
            _, acc, c = sess.run([self.optimizer, self.accuracy, self.loss], feed_di
                                                           self.y: batch_ys})
            # Compute average loss
            avg_loss += c / total_batch
        # Display logs per epoch step
```

```
if self.display_step > 0 and (epoch+1) % self.display_step == 0:
            print "Epoch: {}, loss: {:.4f}, acc:{:.4f}".format(epoch+1, avg_loss, ac
    if sessionCreated:
        sess.close()
def measure_accuracy(self, images, labels, sess=None):
    sessionCreated = False
    if sess is None:
        sess = tf.Session()
        sess.run(self.init)
        sessionCreated = True
    print "Test accuracy:", sess.run(self.accuracy,
                                     feed_dict = {self.x:images, self.y:labels})
    if sessionCreated:
        sess.close()
def get_adversarial_images(self, images, labels, sess=None):
    sessionCreated = False
    if sess is None:
        sess = tf.Session()
        sess.run(self.init)
        sessionCreated = True
    pred_y = []
    adv_x = []
    adv_y = []
    for index, [image, label] in enumerate(zip(images, labels)):
        pred, grad = sess.run([self.pred, self.gradient_input], feed_dict = {
            self.x:np.expand_dims(image, 0), self.y:np.expand_dims(label, 0)})
        adversarial_img_op = image + 0.2 * tf.sign(grad)
        adversarial_img = adversarial_img_op.eval(session=sess)
        ad_pred = sess.run(self.pred, feed_dict = {
            self.x:adversarial_img, self.y:np.expand_dims(label, 0)})
        pred_y.append(pred[0])
        adv_x.append(adversarial_img[0])
        adv_y.append(ad_pred[0])
```

```
if sessionCreated:
    sess.close()
return pred_y, adv_x, adv_y
```

#### 0.2.2 B: Convolutional Neural Network

```
In [8]: # REF: https://qithub.com/aymericdamien/TensorFlow-Examples/blob/master/notebooks/3_Neur
        class CNN():
            def __init__(self, input_size, output_size, learning_rate=0.001,
                         training_epochs= 1, batch_size=200, dropout=0.75, display_step=10):
                self.learning_rate = learning_rate
                self.training_epochs = training_epochs
                self.batch_size = batch_size
                self.display_step = display_step
                self.dropout = dropout
                self.x = tf.placeholder(tf.float32, [None, input_size])
                self.y = tf.placeholder(tf.float32, [None, output_size])
                self.keep_prob = tf.placeholder(tf.float32) # dropout (keep probability)
                # Create some wrappers for simplicity
                def conv2d(x, W, b, strides=1):
                    # Conv2D wrapper, with bias and relu activation
                    x = tf.nn.conv2d(x, W, strides=[1, strides, strides, 1], padding='SAME')
                    x = tf.nn.bias_add(x, b)
                    return tf.nn.relu(x)
                def maxpool2d(x, k=2):
                    # MaxPool2D wrapper
                    return tf.nn.max_pool(x, ksize=[1, k, k, 1], strides=[1, k, k, 1],
                                          padding='SAME')
                # Create model
                def conv_net(x, weights, biases, dropout):
                    # MNIST data input is a 1-D vector of 784 features (28*28 pixels)
                    # Reshape to match picture format [Height x Width x Channel]
                    # Tensor input become 4-D: [Batch Size, Height, Width, Channel]
                    x = tf.reshape(x, shape=[-1, 28, 28, 1])
                    # Convolution Layer
                    conv1 = conv2d(x, weights['wc1'], biases['bc1'])
                    # Max Pooling (down-sampling)
                    conv1 = maxpool2d(conv1, k=2)
                    # Convolution Layer
```

```
conv2 = conv2d(conv1, weights['wc2'], biases['bc2'])
    # Max Pooling (down-sampling)
    conv2 = maxpool2d(conv2, k=2)
    # Fully connected layer
    # Reshape conv2 output to fit fully connected layer input
    fc1 = tf.reshape(conv2, [-1, weights['wd1'].get_shape().as_list()[0]])
    fc1 = tf.add(tf.matmul(fc1, weights['wd1']), biases['bd1'])
    fc1 = tf.nn.relu(fc1)
    # Apply Dropout
    fc1 = tf.nn.dropout(fc1, dropout)
    # Output, class prediction
    out = tf.add(tf.matmul(fc1, weights['out']), biases['out'])
    return out
# Store layers weight & bias
self.weights = {
    # 5x5 conv, 1 input, 32 outputs
    'wc1': tf.Variable(tf.random_normal([5, 5, 1, 32])),
    # 5x5 conv, 32 inputs, 64 outputs
    'wc2': tf.Variable(tf.random_normal([5, 5, 32, 64])),
    # fully connected, 7*7*64 inputs, 1024 outputs
    'wd1': tf.Variable(tf.random_normal([7*7*64, 1024])),
    # 1024 inputs, 10 outputs (class prediction)
    'out': tf.Variable(tf.random_normal([1024, output_size]))
}
self.biases = {
    'bc1': tf.Variable(tf.random_normal([32])),
    'bc2': tf.Variable(tf.random_normal([64])),
    'bd1': tf.Variable(tf.random_normal([1024])),
    'out': tf.Variable(tf.random_normal([output_size]))
}
# Construct model
self.logits = conv_net(self.x, self.weights, self.biases, self.keep_prob)
self.prediction = tf.nn.softmax(self.logits)
# Define loss and optimizer
self.loss_op = tf.reduce_mean(tf.nn.softmax_cross_entropy_with_logits(
    logits=self.logits, labels=self.y))
# Calculate loss with respect to input
self.gradient_input = tf.gradients(self.loss_op, self.x)[0]
self.optimizer = tf.train.AdamOptimizer(learning_rate=self.learning_rate)
self.train_op = self.optimizer.minimize(self.loss_op)
```

```
# Evaluate model
    self.correct_pred = tf.equal(tf.argmax(self.prediction, 1), tf.argmax(self.y, 1)
    self.accuracy = tf.reduce_mean(tf.cast(self.correct_pred, tf.float32))
    # Initialize the variables (i.e. assign their default value)
    self.init = tf.global_variables_initializer()
def fit(self, images, labels, sess = None):
    sessionCreated = False
    if sess is None:
        sess = tf.Session()
        sess.run(self.init)
        sessionCreated = True
    # Training cycle
    for step in range(1, self.training_epochs+1):
        total_batch = int(len(images)/self.batch_size)
        # Loop over all batches
        for i in range(total_batch):
            batch_x = images[i*self.batch_size: (i+1)*self.batch_size]
            batch_y = labels[i*self.batch_size: (i+1)*self.batch_size]
            # Run optimization op (backprop)
            sess.run(self.train_op, feed_dict={self.x: batch_x, self.y: batch_y, sel
            count = step*i
            if self.display_step>0 and (count % self.display_step == 0 or count == 1
                # Calculate batch loss and accuracy
                loss, acc = sess.run([self.loss_op, self.accuracy], feed_dict={self.
                                                                      self.y: batch_y
                                                                      self.keep_prob:
                print "Epoch: {}, loss: {:.4f}, acc:{:.4f}".format(count, loss, acc)
    if sessionCreated:
        sess.close()
def measure_accuracy(self, images, labels, sess=None):
    sessionCreated = False
    if sess is None:
        sess = tf.Session()
        sess.run(self.init)
```

```
sessionCreated = True
    print "Test accuracy:", sess.run(self.accuracy,
             feed_dict = {self.x:images[0:256],
                          self.y:labels[0:256], self.keep_prob: 1.0})
    if sessionCreated:
        sess.close()
def get_adversarial_images(self, images, labels, sess=None):
    sessionCreated = False
    if sess is None:
        sess = tf.Session()
        sess.run(self.init)
        sessionCreated = True
    pred_y = []
    adv_x = []
    adv_y = []
    for index, [image, label] in enumerate(zip(images, labels)):
        pred, grad = sess.run([self.prediction, self.gradient_input], feed_dict = {
            self.x:np.expand_dims(image, 0), self.y:np.expand_dims(label, 0), self.k
        adversarial_img_op = image + 0.2 * tf.sign(grad)
        adversarial_img = adversarial_img_op.eval(session=sess)
        ad_pred = sess.run(self.prediction, feed_dict = {
            self.x:adversarial_img, self.y:np.expand_dims(label, 0), self.keep_prob:
        pred_y.append(pred[0])
        adv_x.append(adversarial_img[0])
        adv_y.append(ad_pred[0])
    if sessionCreated:
        sess.close()
    return pred_y, adv_x, adv_y
```

# C: Random forest (Did not use this for adversarial example because tf.gradients(...) throws error for tensor\_forest)

```
def __init__(self, input_size, output_size, training_epochs= 500,
             batch_size=1024, num_trees=10, max_nodes = 1000, display_step=1):
    self.training_epochs = training_epochs
    self.batch_size = batch_size
    self.num_trees = num_trees
    self.max_nodes = max_nodes
    self.display_step = display_step
    # Input and Target data
    self.x = tf.placeholder(tf.float32, shape=[None, input_size])
    # For random forest, labels must be integers (the class id)
    self.y = tf.placeholder(tf.int32, shape=[None])
    # Random Forest Parameters
    self.hparams = tensor_forest.ForestHParams(num_classes=output_size,
                                  num_features=input_size,
                                  num_trees=self.num_trees,
                                  max_nodes=self.max_nodes).fill()
    # Build the Random Forest
    self.forest_graph = tensor_forest.RandomForestGraphs(self.hparams)
    # Get training graph and loss
    self.train = self.forest_graph.training_graph(self.x, self.y)
    self.loss = self.forest_graph.training_loss(self.x, self.y)
    # Measure the accuracy
    self.infer, _, _ = self.forest_graph.inference_graph(self.x)
    self.correct_pred = tf.equal(tf.argmax(self.infer, 1), tf.cast(self.y, tf.int64)
    self.accuracy = tf.reduce_mean(tf.cast(self.correct_pred, tf.float32))
    # Initialize the variables (i.e. assign their default value) and forest resource
    self.init = tf.group(tf.global_variables_initializer(),
        resources.initialize_resources(resources.shared_resources()))
def fit(self, sess = None):
    sessionCreated = False
    if sess is None:
        sess = tf.Session()
        sess.run(self.init)
        sessionCreated = True
    # Training
    for i in range(1, self.training_epochs + 1):
        # Prepare Data
        # Get the next batch of MNIST data (only images are needed, not labels)
```

```
batch_x, batch_y = mnist.train.next_batch(self.batch_size)
                    _, l = sess.run([self.train, self.loss], feed_dict={self.x: batch_x, self.y:
                    if self.display_step >0 and (i % self.display_step == 0 or i == 1):
                        acc = sess.run(self.accuracy, feed_dict={self.x: batch_x, self.y: np.arg
                        print "Step {}, loss: {:.4f}, acc: {:.4f}".format(i+1, 1, acc)
                if sessionCreated:
                    sess.close()
            def measure_accuracy(self, sess=None):
                sessionCreated = False
                if sess is None:
                    sess = tf.Session()
                    sess.run(self.init)
                    sessionCreated = True
                print "Test accuracy:", sess.run(self.accuracy,feed_dict = {self.x:mnist.test.im
                if sessionCreated:
                    sess.close()
0.3 3. Train both models and achieve a "decent" testing accuracy (over 90%)
0.3.1 A: Logistic regression
In [11]: clf_reg = LogisticRegression(mnist.train.images.shape[1], 10, training_epochs=25, displ
         with tf.Session() as sess:
             # Run the initializer
```

```
sess.run(clf_reg.init)
             clf_reg.fit(mnist.train.images, mnist.train.labels, sess)
             clf_reg.measure_accuracy(mnist.test.images, mnist.test.labels, sess)
Test accuracy: 0.9145
```

#### 0.3.2 B: Convolutional Neural Network

```
In [12]: clf_cnn = CNN(mnist.train.images.shape[1], 10, display_step=0)
         with tf.Session() as sess:
             # Run the initializer
             sess.run(clf_cnn.init)
```

#### C: Random forest

## 0.4 4. Generate 100 adversarial examples for each model

From the adversarial examples generated using both the models, we can see that Logistic regression model generates better adversarial examples compared to Convolutional Neural Network. In case of CNN we get higher accuracy for the test dataset. However, due to vanishing gradient, CNN causes no change to to input image based on which adversarial examples are generated.

Adversarial examples in case of CNN can be generated using very small number of epochs and training data. In that case the model is not trained well and it's prediction is not good for neither original image nor the adversarial example.

```
In [13]: # Helper function for visualization
```

```
def show_images(images, labels, n, title="Label"):
    plt.figure(figsize=(20,4))
    for index, (image, label) in enumerate(zip(images[0:n], labels[0:n])):
        plt.subplot(1, n, index + 1)
        plt.imshow(np.reshape(image, (28,28)), cmap=plt.cm.gray)
        plt.title('%s: %i\n' % (title, label), fontsize = 12)
    plt.show()

def show_proba(images, labels, probabilities, n, title="Label"):
    plt.figure(figsize=(20,4))
    for index, (image, label, proba) in enumerate(zip(images[0:n], labels[0:n], probabilities)
    plt.subplot(1, n, index + 1)

#y_proba = classifier.predict_proba([image])[0]
    plt.bar(np.arange(10), proba)
```

```
# print y_proba
plt.title('%s: %i\n' % (title, label), fontsize = 12)
plt.show()
```

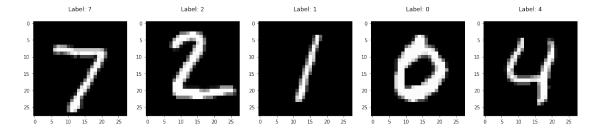
#### 0.4.1 A: Logistic regression

#### Generate 100 examples

#### Visualize 5 for analysis

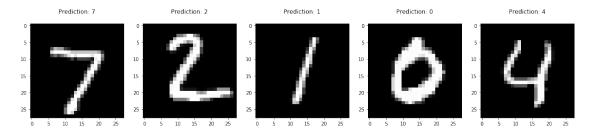
#### **Actual labels**

In [15]: show\_images(mnist.test.images, np.argmax(mnist.test.labels, axis=1), 5)



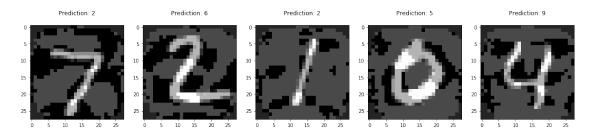
#### **Predicted labels**

In [16]: show\_images(mnist.test.images[0:100], np.argmax(reg\_pred\_y, axis=1), 5, title="Predicti")



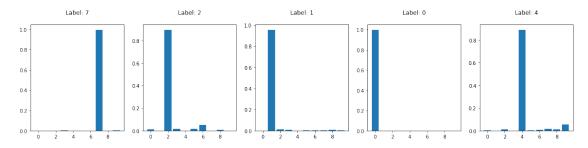
## Adversarial images with predicted labels

In [17]: show\_images(reg\_adv\_x, np.argmax(reg\_adv\_y, axis=1), 5, title="Prediction")



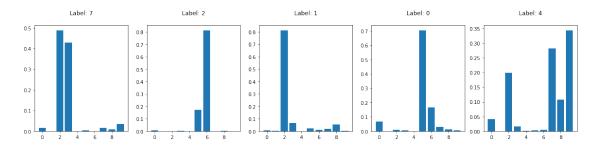
## Probability for original images

In [18]: show\_proba(mnist.test.images[0:100], np.argmax(mnist.test.labels[0:100], axis=1), reg\_p



## Probability for adversarial images

In [19]: show\_proba(reg\_adv\_x, np.argmax(mnist.test.labels[0:100], axis=1), reg\_adv\_y, 5)



#### Accuracy for the adversarial images

Adversarial accuracy: 0.0

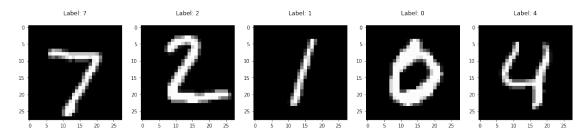
#### 0.4.2 B: Convolutional Neural Network

### **Generate 100 examples**

## Visualize 5 for analysis

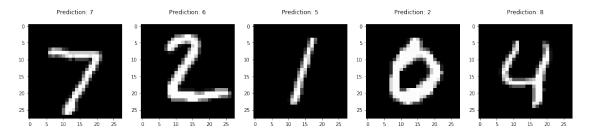
#### **Actual labels**

In [24]: show\_images(mnist.test.images[0:100], np.argmax(mnist.test.labels, axis=1), 5)



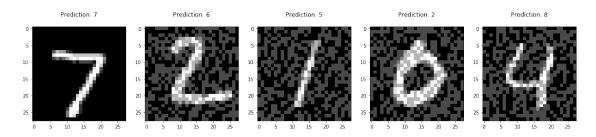
**Predicted labels** Most predictions are poor because the network was intentionaly trained with less data and for few epochs to generate adversarial examples

In [25]: show\_images(mnist.test.images[0:100], np.argmax(cnn\_pred\_y, axis=1), 5, title="Prediction")



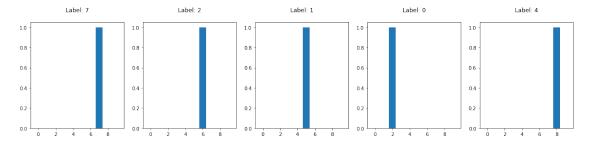
## Adversarial images with predicted labels

In [26]: show\_images(cnn\_adv\_x, np.argmax(cnn\_adv\_y, axis=1), 5, title="Prediction")



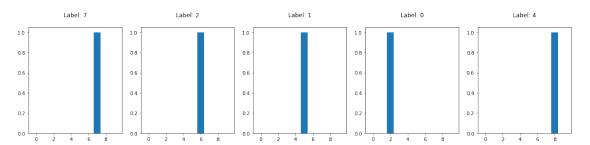
## Probability for original image

In [27]: show\_proba(mnist.test.images[0:100], np.argmax(mnist.test.labels[0:100], axis=1), cnn\_p



#### Probability for adversarial images

In [28]: show\_proba(cnn\_adv\_x, np.argmax(mnist.test.labels[0:100], axis=1), cnn\_adv\_y, 5)



#### Accuracy for the adversarial images

Adversarial accuracy: 0.78

## 0.5 5. Use the adversarial examples of A with model B and of B with model A

The accuracy value below shows that the adversarial examples of Logistic regression fools Convolutional Neural Network but not vice versa. In the previous section we also found that accuracy of CNN for adversarial examples generated by itself is 78% whereas accuracy of Logistic regression for it's adversarial examples is zero.

#### 0.5.1 Adversarial examples of Convolutional Neural Network used with Logistic regression

```
In [32]: clf_reg = LogisticRegression(mnist.train.images.shape[1], 10, training_epochs=25, displ
    with tf.Session() as sess:
        # Run the initializer
        sess.run(clf_reg.init)
```

clf\_reg.fit(mnist.train.images, mnist.train.labels, sess)

Adversarial accuracy: 0.95

#### 0.5.2 Adversarial examples of Logistic regression used with Convolutional Neural Network

Adversarial accuracy: 0.22

## 0.6 6. Generate new adversarial examples and evaluate

## 0.6.1 Generate new examples using Logistic regression

We used 1000 adversarial examples to reduce processing time

```
In []: new_images = []
    new_labels = []

clf_reg = LogisticRegression(mnist.train.images.shape[1], 10, training_epochs=25, display

with tf.Session() as sess:
    # Run the initializer
    sess.run(clf_reg.init)

clf_reg.fit(mnist.train.images, mnist.train.labels, sess)

for index, [image, label] in enumerate(zip(mnist.train.images[0:1000], mnist.train.labels.append(image)
    new_labels.append(label)

for index, [image, label] in enumerate(zip(mnist.train.images, mnist.train.labels)):
    grad = sess.run([clf_reg.gradient_input], feed_dict = {
```

clf\_reg.x:np.expand\_dims(image, 0), clf\_reg.y:np.expand\_dims(label, 0)})

```
adversarial_img_op = image + 0.2 * tf.sign(grad[0])
adversarial_img = adversarial_img_op.eval(session=sess)
new_images.append(adversarial_img[0])
new_labels.append(label)
```

#### 0.6.2 Evaluation with new adversarial examples

#### **Logistic regression**

```
In [51]: clf_reg = LogisticRegression(mnist.train.images.shape[1], 10, training_epochs=25, displ
         with tf.Session() as sess:
             # Run the initializer
             sess.run(clf_reg.init)
             clf_reg.fit(new_images, new_labels, sess)
             clf_reg.measure_accuracy(mnist.test.images, mnist.test.labels, sess)
```

Test accuracy: 0.9069

#### Convolutional Neural Network

```
In [52]: clf_cnn = CNN(mnist.train.images.shape[1], 10, display_step=0)
         with tf.Session() as sess:
             # Run the initializer
             sess.run(clf_cnn.init)
             clf_cnn.fit(new_images, new_labels, sess)
             clf_cnn.measure_accuracy(mnist.test.images, mnist.test.labels, sess)
```

Test accuracy: 0.91015625

- The evaluation above shows that the classification accuracy decreases for both the models in case of adversarial examples added in training set. This happens because the models tend to overfit.
- The model is less susceptible to adversarial examples after training with new examples.
- Yes we can do regularization to avoid overfitting. The CNN model uses dropout for regularization.