# NN\_DebarajBarua\_NareshKumarGurulingan\_061117

November 11, 2017

- 1 Hochschule Bonn-Rhein-Sieg
- 2 Neural Networks, WS17/18
- 3 Assignment 05 (06-november-2017)
- 3.1 Debaraj Barua, Naresh Kumar Gurulingan

```
In [183]: import numpy as np
    import matplotlib.pyplot as plt
    import sympy as sp
    import IPython
    sp.init_printing()
```

**3.2 Question 1:** 

Read Haykin NN edition 2: chapter 3.1-3.5. Make a summary

# 3.3 Question 2 (Haykin Edition:2, Ex: 3.1):

Explore the method of steepest descent involving a single weight w by considering the following cost function:

$$\varepsilon(w) = \frac{1}{2}\sigma^2 - r_{xd}w + \frac{1}{2}r_xw^2$$

where,  $\sigma^2$ ,  $r_{xd}$  and  $r_x$  are constants.

## **Answer 2:**

#### Out[184]:

$$1.0r_xw - r_{xd}$$

So, Gradient,

$$\nabla \varepsilon(w) = \frac{\partial \varepsilon(w)}{\partial w}$$
$$= -r_{xd} + r_x w$$

According to steepest descent method, weight vector is updated in the direction of the steepest descent, i.e., in the direction opposite to the gradient vector.

So,  $\Delta w = -\eta \nabla \varepsilon(w)$ , where  $\eta$  is the learning rate Now, updated weight is:

$$w(n+1) = w(n) + \Delta w$$
  
=  $w(n) - \eta(-r_{xd} + r_x w)$ 

# 3.4 Question 3 (Haykin Edition:2, Ex: 3.2):

Consider the cost function

$$\varepsilon(w) = \frac{1}{2}\sigma^2 - r_{xd}^T w + \frac{1}{2}w^T R_x w$$

where,  $\sigma^2$ ,  $r_{xd}$  and  $r_x$  are constants.

$$r_{xd} = \begin{bmatrix} 0.8182\\ 0.354 \end{bmatrix}$$

$$R_x \begin{bmatrix} 1 & 0.8182\\ 0.8182 & 1 \end{bmatrix}$$

## 3.4.1 3(a)

Find the optimum value of  $w^*$  for which  $\varepsilon(w)$  reaches it's maximum value.

**Answer 3(a):**  $\varepsilon(w)$  will reach maximum value when it's Jacobian will be zero.

```
In [185]: s=sp.symbols('s')
    w=sp.MatrixSymbol('w',2,1)
    r_xd=sp.Matrix([[0.8182],[0.354]])
    R_x=sp.Matrix([[1,0.8182],[0.8182,1]])

e=1./2.*s**2-r_xd.T.dot(sp.Matrix(w))+1./2.*sp.Matrix(w).T.dot(R_x.dot(sp.Matrix(w)))
    e=sp.Matrix([e])
    symbolic_jacobian=e.jacobian(w)
    print "Jacobian Matrix is:"
    symbolic_jacobian
```

```
Jacobian Matrix is:
```

## Out[185]:

```
\begin{bmatrix} -0.8182 + 0.5 (2w_{0,0} + 1.6364w_{1,0}) & -0.354 + 0.5 (1.6364w_{0,0} + 2w_{1,0}) \end{bmatrix}
```

optimum values of weight, w\*:

### Out[186]:

```
[\{w_{0,0}: 1.59902944424901, \quad w_{1,0}: -0.954325891284541\}]
```

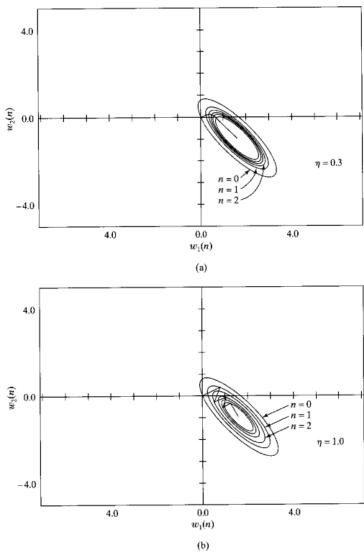
#### 3.4.2 3(b)

Use the method of steepest descent to compute  $w^*$  for the following two values of learning rate parameter:

```
(i) $\eta=0.3$<<p>(ii) $\eta=1.0$
```

For each case, plot the trajectory traced the evolution of the weight vector w(n) in the W-Plane. *Note*: The trajectories obtained for cases (i) and (ii) of part (b) should correspond to the picture in Fig. 3.2

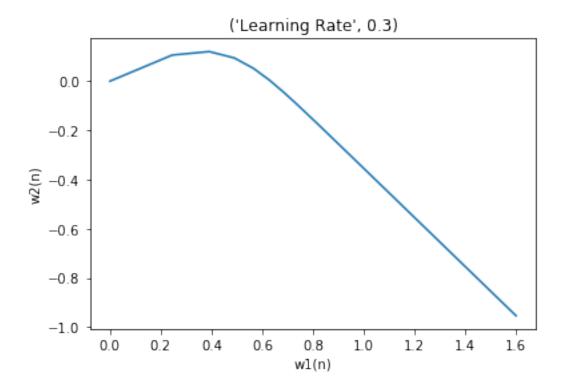
```
In [187]: IPython.display.Image("images/HaykinFig3.2.png")
Out[187]:
```



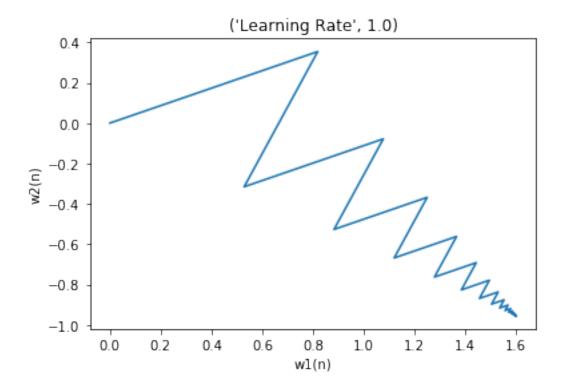
**FIGURE 3.2** Trajectory of the method of steepest descent in a two-dimensional space for two different values of learning-rate parameter: (a)  $\eta=0.3$ , (b)  $\eta=1.0$ . The coordinates  $w_1$  and  $w_2$  are elements of the weight vector  $\mathbf{w}$ .

## Answer 3(b):

```
print "Learning Rate: ", eta
              while (found_optimum==False and iteration<max_iteration):</pre>
                  iteration+=1
                  delta_wt=delta_wt_func(weight)
                  if(abs(delta_wt.all())<1e-5):</pre>
                      If absolute change in weight is less than 10^(-5),
                      we consider we have reached the optimal solution
                      print "Reached optimum value"
                      print "Absolute change in weight is less than 10^(-5), exiting loop."
                      found_optimum=True
                      break
                  else:
                      weight+=-eta*delta_wt.T
                      wt_matrix=np.vstack((wt_matrix,weight.T))
              if iteration==max_iteration:
                  print "Max iteration reached!"
              print "optimum values of weight, w*:",np.array(weight).T
              print "Total iterations required:",iteration
              print wt_matrix.shape
              plt.plot(wt_matrix[:,0],wt_matrix[:,1])
              plt.xlabel("w1(n)")
              plt.ylabel("w2(n)")
              plt.title(("Learning Rate",eta))
              plt.show()
          initial_weight = sp.Matrix([[0],[0]])
          print initial_weight.shape
          eta1 = 0.3
          eta2 = 1.0
          max_iteration =1000
          steepest_desc(initial_weight,eta1,max_iteration)
          steepest_desc(initial_weight,eta2,max_iteration)
(2, 1)
Learning Rate: 0.3
Reached optimum value
Absolute change in weight is less than 10<sup>(-5)</sup>, exiting loop.
optimum values of weight, w*: [[1.59897673946915 -0.954273186504682]]
Total iterations required: 181
(181, 2)
```



Learning Rate: 1.0
Reached optimum value
Absolute change in weight is less than 10^(-5), exiting loop.
optimum values of weight, w\*: [[1.59899794732667 -0.954307093426509]]
Total iterations required: 55
(55, 2)



## 3.5 Question 4 (Haykin Edition:2, Ex: 3.4):

The correlation matrix  $R_x$  of the input vector x(n) in the LMS algorithm is defined by

$$R_{x} = \begin{bmatrix} 1 & 0.5 \\ 0.5 & 1 \end{bmatrix}$$

Define the range of values for the learning-rate parameter  $\eta$  of the LMS algorithm for it to be convergent in the mean square.

**Answer 4:** LMS algorithm is convergent in mean square in the below mentioned region:

$$0<\eta<\frac{2}{\lambda_{max}}$$

Where,  $\lambda_{max}$  is the largest eigen value of the correlation matrix of the input vector.

Ramge of values for learning rate: [0, 1.33333333333]

# 3.6 Question 5 (Haykin Edition:2, Ex: 3.8):

The ensemble-averaged counterpart of the sum of error squares viewed as a cost function is the mean-square value of the error signal:

$$J(w) = \frac{1}{2}E[e^{2}(n)]$$
  
=  $\frac{1}{2}E[(d(n) - x^{T}(n)w)^{2}]$ 

### 3.6.1 5(a)

Assuming that the input vector x(n) and the desired response d(n) are drawn from a stationary environment, show that

$$J(w) = \frac{1}{2}\sigma_d^2 - r_{xd}^T w + \frac{1}{2}w^T R_x w$$

where,

$$\sigma_d^2 = E[d^2(n)]$$

$$r_{xd} == E[x(n)d(n)]$$

$$R_x == E[x(n)x^T(n)]$$

Answer 5(a):

## 3.6.2 5(b)

For this cost function, show that the gradient vector and the Hessian matrix of J(w) are as follows, respectively:

$$g = -r_{xd} + R_x w$$
$$H = R_x$$

**Answer 5(b):** Similar to Section ??,

Gradient is given by differentiating with respect to w(n),

$$g = \nabla \varepsilon(w) = -r_{xd} + R_x w$$

For Hessian, we differntiate it again to get,

$$H = \nabla \nabla \varepsilon(w) = R_r$$

## 3.6.3 5(c)

In the LMS/Newton algorithm, the gradient vector g is replaced by its instantaneous value (Widrow and Stearns, 1985). Show that this algorithm, incorporating a learning rate parameter  $\eta$ , is described by

$$\hat{w}(n+1) = \hat{w}(n) + \eta R_x^{-1} x(n) (d(n) - x^T(n) w(n))$$

The inverse of the correlation matrix  $R_x$ , assumed to be positive definite, is calculated ahead of time.

Answer 5(c):		