

CONTACT INFORMATION	NVIDIA Seattle 4545 Roosevelt Way NE #400 Seattle, WA 98105	yux@nvidia.com http://yuxng.github.io/ Google Scholar
RESEARCH INTERESTS	Computer Vision, Robotics, Machine Learning, Deep Learning	
EDUCATION	University of Michigan , Ann Arbor, Michigan, USA Ph.D. in Electrical Engineering: Systems Dissertation: 3D Object Representations for Recognition Advisor: Prof. Silvio Savarese Fudan University , Shanghai, China M.S. in Computer Science Dissertation: Graphic Models for Semantic Context Modeling in Automatic Image Annotation Advisor: Prof. Xiangdong Zhou Fudan University , Shanghai, China B.S. in Computer Science	Sep 2010 – Dec 2015 Sep 2007 – Jul 2010 Sep 2003 – Jul 2007
EXPERIENCE	NVIDIA Research , Seattle, Washington, USA <i>Research Scientist</i> University of Washington , Seattle, Washington, USA <i>Postdoctoral Researcher</i> • Advisor: Prof. Dieter Fox Stanford University , Stanford, California, USA <i>Postdoctoral Researcher</i> • Advisor: Prof. Silvio Savarese Stanford University , Stanford, California, USA <i>Visiting Student Researcher</i> • Advisor: Prof. Silvio Savarese NEC Laboratories America, Inc. , Cupertino, California, USA <i>Summer Research Intern</i> • Department: Media Analytics	Jan 2018 – present Aug 2016 – Dec 2017 Jan 2016 – Jul 2016 Sep 2013 – Dec 2015 Jun 2015 – Sep 2015 May 2014 – Aug 2014
PUBLICATIONS	Object Discovery in Videos as Foreground Motion Clustering Christopher Xie, <i>Yu Xiang</i> , Dieter Fox and Zaid Harchaoui In <i>IEEE Conference on Computer Vision and Pattern Recognition (CVPR)</i> , 2019. Neural Autonomous Navigation with Riemannian Motion Policy Xiangyun Meng, Nathan Ratliff, <i>Yu Xiang</i> and Dieter Fox In <i>International Conference on Robotics and Automation (ICRA)</i> , 2019. Deep Object Pose Estimation for Semantic Robotic Grasping of Household Objects Jonathan Tremblay, Thang To, Balakumar Sundaralingam, <i>Yu Xiang</i> , Dieter Fox and Stan Birchfield In <i>Conference on Robot Learning (CoRL)</i> , 2018. DeepIM: Deep Iterative Matching for 6D Pose Estimation Yi Li, Gu Wang, Xiangyang Ji, <i>Yu Xiang</i> and Dieter Fox In <i>European Conference on Computer Vision (ECCV)</i> , 2018 (Oral). PoseCNN: A Convolutional Neural Network for 6D Object Pose Estimation in Cluttered Scenes <i>Yu Xiang</i> , Tanner Schmidt, Venkatraman Narayanan and Dieter Fox In <i>Robotics: Science and Systems (RSS)</i> , 2018.	

Recurrent Autoregressive Networks for Online Multi-Object Tracking

Kuan Fang, Yu Xiang, Xiaocheng Li and Silvio Savarese

In *IEEE Winter Conference on Applications of Computer Vision (WACV)*, 2018.

DA-RNN: Semantic Mapping with Data Associated Recurrent Neural Networks

Yu Xiang and Dieter Fox

In *Robotics: Science and Systems (RSS)*, 2017.

Subcategory-aware Convolutional Neural Networks for Object Proposals and Detection

Yu Xiang, Wngun Choi, Yuanqing Lin and Silvio Savarese

In *IEEE Winter Conference on Applications of Computer Vision (WACV)*, pp. 924–933, 2017.

Anticipating Accidents in Dashcam Videos

Fu-Hsiang Chan, Yu-Ting Chen, Yu Xiang and Min Sun

In *Asian Conference on Computer Vision (ACCV)*, pp. 136–153, 2016 (Oral).

ObjectNet3D: A Large Scale Database for 3D Object Recognition

Yu Xiang, Wonhui Kim, Wei Chen, Jingwei Ji, Christopher Choy, Hao Su, Roozbeh Mottaghi, Leonidas Guibas and Silvio Savarese

In *European Conference on Computer Vision (ECCV)*, pp. 160–176, 2016 (Spotlight Oral).

Pose Estimation Errors, the Ultimate Diagnosis

Carolina Redondo-Cabrera, Roberto López-Sastre, Yu Xiang, Tinne Tuytelaars and Silvio Savarese

In *European Conference on Computer Vision (ECCV)*, pp. 118–134, 2016.

Deep Metric Learning via Lifted Structured Feature Embedding

Hyun Oh Song, Yu Xiang, Stefanie Jegelka and Silvio Savarese

In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, pp. 4004–4012, 2016 (Spotlight Oral).

Learning to Track: Online Multi-Object Tracking by Decision Making

Yu Xiang, Alexandre Alahi and Silvio Savarese

In *International Conference on Computer Vision (ICCV)*, pp. 4705–4713, 2015 (Oral).

Data-Driven 3D Voxel Patterns for Object Category Recognition

Yu Xiang, Wngun Choi, Yuanqing Lin and Silvio Savarese

In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, pp. 1903–1911, 2015 (Oral).

A Coarse-to-Fine Model for 3D Pose Estimation and Sub-category Recognition

Roozbeh Mottaghi, Yu Xiang and Silvio Savarese

In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, pp. 418–426, 2015.

Monocular Multiview Object Tracking with 3D Aspect Parts

Yu Xiang*, Changkyu Song*, Roozbeh Mottaghi and Silvio Savarese (*equal contribution)

In *European Conference on Computer Vision (ECCV)*, pp. 220–235, 2014.

Beyond PASCAL: A Benchmark for 3D Object Detection in the Wild

Yu Xiang, Roozbeh Mottaghi and Silvio Savarese

In *IEEE Winter Conference on Applications of Computer Vision (WACV)*, pp. 75–82, 2014.

Object Detection by 3D Aspectlets and Occlusion Reasoning

Yu Xiang and Silvio Savarese

In *IEEE Workshop on 3D Representation and Recognition (3dRR)*, pp. 530–537, 2013.

Object Co-detection

Sid Yingze Bao, Yu Xiang and Silvio Savarese

In *European Conference on Computer Vision (ECCV)*, vol. 7572, pp. 86–101, 2014.

Estimating the Aspect Layout of Object Categories

Yu Xiang and Silvio Savarese

In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, pp. 3410–3417, 2012.

Semantic Context Modeling with Maximal Margin Conditional Random Fields for Automatic Image Annotation

Yu Xiang, Xiangdong Zhou, Zuotao Liu, Tat-Seng Chua and Chong-Wah Ngo

In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, pp. 3368–3375, 2010.

Learning Contextual Metrics for Automatic Image Annotation

Zuotao Liu, Xiangdong Zhou, Yu Xiang and Yan-Tao Zheng

In *Advances in Multimedia Information Processing - PCM*, vol. 6297, pp. 124–135, 2010.

A Revisit of Generative Model for Automatic Image Annotation using Markov Random Fields

Yu Xiang, Xiangdong Zhou, Zuotao Liu, Tat-Seng Chua and Chong-Wah Ngo

In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, pp. 1153–1160, 2009.

Adaptive Model for Web Image Semantic Automatic Image Annotation

Hongtao Xu, Xiangdong Zhou, Yu Xiang and Baile Shi

In *Journal of Software (in Chinese)*, vol. 21, no. 9, pp. 2183–2195, 2009.

Exploiting Flickr's Related Tags for Semantic Annotation of Web Images

Hongtao Xu, Xiangdong Zhou, Yu Xiang and Baile Shi

In *ACM International Conference on Image and Video Retrieval (CIVR)*, no. 46, 2009.

Automatic Web Image Annotation via Web-Scale Image Semantic Space Learning

Hongtao Xu, Xiangdong Zhou, Lan Lin, Yu Xiang and Baile Shi

In *Advances in Data and Web Management*, vol. 5446, pp. 211–222, 2009.

TEACHING EXPERIENCE

Artificial Intelligence, University of Washington, Seattle, Washington, USA

2017

Guest Lectures for Prof. Dieter Fox

Computer Vision, University of Washington, Seattle, Washington, USA

2017

Guest Lecture for Prof. Linda Shapiro

Computer Vision, Stanford University, Stanford, California, USA

2016

Guest Lectures for Prof. Silvio Savarese

The C Programming Language, Fudan University, Shanghai, China

Sep 2009 – Jan 2010

Teaching Assistant

AWARDS AND HONORS

Outstanding Master's Thesis Award of Shanghai

2012

PROFESSIONAL SERVICE

Journal Reviewer

- International Journal of Robotics Research (IJRR)
- IEEE Robotics and Automation Letters (RA-L)
- IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI)
- International Journal of Computer Vision (IJCV)
- Computer Vision and Image Understanding (CVIU)
- IEEE Transactions on Circuits and Systems for Video Technology (TCSVT)
- IEEE Transactions on Multimedia (TMM)
- IEEE Transactions on Signal Processing (TSP)

Conference Reviewer

- Robotics: Science and Systems Conference (RSS)
- IEEE International Conference on Robotics and Automation (ICRA)
- International Conference on Intelligent Robots and Systems (IROS)
- IEEE Conference on Computer Vision and Pattern Recognition (CVPR)
- International Conference on Computer Vision (ICCV)
- European Conference on Computer Vision (ECCV)
- Asian Conference on Computer Vision (ACCV)
- British Machine Vision Conference (BMVC)
- International Conference on 3D Vision (3DV)
- Neural Information Processing Systems (NIPS)

Program Chair

- 5th International IEEE Workshop on 3D Representation and Recognition, 2015

Program Committee

- 4th International IEEE Workshop on 3D Representation and Recognition, 2013

Tutorial Organizer

- 3D Object Geometry from Single Image Tutorial at International Conference on 3D Vision, 2016

TALKS

Perceiving the 3D World from Images and Videos

In Nvidia Research, Redmond, Washington, 11/07/2017; University of Michigan, 3/15/2018.

3D Object Recognition and Scene Understanding from RGB-D Videos

In GRASP Lab at University of Pennsylvania, 10/11/2017; Microsoft Research, Redmond, 10/17/2017; Vision Lab at Stanford University, 10/23/2017.

3D Object Recognition and Scene Understanding

In Mitsubishi Electric Research Laboratories, Boston, Massachusetts, 7/14/2017.

DA-RNN: Semantic Mapping with Data Associated Recurrent Neural Networks

In Robotics: Science and Systems, Massachusetts Institute of Technology, Massachusetts, 7/13/2017.

Subcategory-aware Convolutional Neural Networks for Object Proposals and Detection

In IEEE Winter Conference on Applications of Computer Vision, Santa Rosa, California, 3/29/2017.

Tutorial on 3D Object Recognition

In International Conference on 3D Vision, Stanford University, 10/28/2016.

3D Object Representations for Recognition

In Carnegie Mellon University, 3/28/2016; University of Toronto, 4/4/2016; Massachusetts Institute of Technology, 4/12/2016; University of California, Berkeley, 4/21/2016; University of Illinois at Urbana-Champaign, 5/5/2016; University of Washington, 5/31/2016.

3D Object Detection and Pose Estimation

In the 1st International Workshop on Recovering 6D Object Pose in conjunction with ICCV, Santiago, Chile, 12/17/2015.

Learning to Track: Online Multi-Object Tracking by Decision Making

In International Conference on Computer Vision, Santiago, Chile, 12/16/2015.

Data-Driven 3D Voxel Patterns for Object Category Recognition

In IEEE Conference on Computer Vision and Pattern Recognition, Boston, Massachusetts, 06/08/2015.

Monocular Multiview Object Tracking with 3D Aspect Parts

In the 1st Stanford-SNU Workshop on Automated Driving, Stanford University, 02/24/2015.

Beyond PASCAL: A Benchmark for 3D Object Detection in the Wild

In IEEE Winter Conference on Applications of Computer Vision, Steamboat Springs, Colorado, 03/24/2014.

Object Detection by 3D Aspectlets and Occlusion Reasoning

In the 4th International IEEE Workshop on 3D Representation and Recognition in conjunction with ICCV, Sydney, Australia, 12/08/2013.

Estimating the Aspect Layout of Object Categories

In Midwest Vision Workshop, University of Illinois at Urbana-Champaign, 09/21/2012.