```
pressure_data = cell2mat(DATAforStudentsS3);
location_of_port = cell2mat(DATAforStudentsS1);
cylinder diameter = 100*10^-3;
cylinder_span = 305*10^-3;
Cp = [pressure data(1,2:end)./pressure data(1,1);pressure data(2,2:end)./pressure data(2,1);pressure data(3,2:end).\checkmark
/pressure data(3,1)];
Cd = zeros(3,1);
for j = 1:3
    for i = 1:30
        Cd(j,1) = Cd(j,1) + Cp(j,i)*cos(location_of_port(i,2));
    end
end
Cd = Cd.*(-0.5);
big data = cell2mat(DATAforStudents);
figure(1)
plot(location_of_port(:,2),Cp(1,:))
hold on
grid on
plot(location_of_port(:,2),Cp(2,:))
plot(location of port(:,2),Cp(3,:))
scatter(location of port(:,2),Cp(1,:))
hold on
grid on
scatter(location_of_port(:,2),Cp(2,:))
scatter(location of port(:,2),Cp(3,:))
hold off
Cp\_big = zeros(151,30);
for k = 1:151
    Cp_big(k,:) = big_data(k,2:end)./big_data(k,1);
Cd_big = zeros(151,1);
for j = 1:151
    for i = 1:30
        Cd big(j,1) = Cd big(j,1) + Cp big(j,i)*cos(location of port(i,2));
    end
end
```

```
Cd_big = Cd_big.*(-0.5);
% figure
% hold on
% grid on
% for n = 1:151
      plot(location_of_port(:,2),Cp_big(n,:));
% end
% hold off
rho = 1.2;
v = 0.15*10^{-4};
D = 100*10^{-3};
dynamic_pressure = cell2mat(DATAforStudents(:,1));
U = sqrt((2*dynamic_pressure)/rho);
Re = (U*D)/v;
figure(2)
scatter(Re,Cd_big)
set(gca,'xscale','log')
set(gca,'yscale','log')
grid on
```