

# AE-777A (Optimal Space Flight Control)

## Practice Quiz

### Quiz Procedure

1. Clearly write out your solution to the quiz problems within the specified time on blank sheets of paper. (Marks will be given only for complete calculation/derivation steps.)
2. Take *low-resolution* pictures of your solution, convert them into a single PDF file (about 1MB), and send it to me by email (ashtew@iitk.ac.in) from your *registered* email account.
3. The time limit will be *strictly enforced*, and late submissions will *not* be accepted.

**Practice Quiz (Time 60 min)**

*(Marks for each part are indicated in parentheses.)*

For a system governed by the following differential equations:

$$\dot{\xi}_1 = \xi_1^3 + \xi_2$$

$$\dot{\xi}_2 = \eta - \xi_1 + \xi_2^2$$

where  $\xi_1(t) \in \mathbb{R}$  and  $\xi_2(t) \in \mathbb{R}$  are state variables, and  $\eta(t) \in \mathbb{R}$  is the control input:

- (a) Linearize the system about the reference solution,  $\xi_1 = c = \text{const.}$ ,  $\xi_2 = 0$ , and determine the state-space coefficient matrices,  $A$  and  $B$  of the linearized system. (8)
- (b) Determine the state response,  $x_1(t) = \xi_1(t) - c$ ,  $x_2(t) = \xi_2(t)$ , of the linearized system when a unit impulse function,  $\eta(t) = \delta(t)$ , is applied at  $t = 0$ , with zero initial condition,  $x_1(0) = x_2(0) = 0$ . (15)
- (c) Investigate the stability of the linearized system. (7)
- (d) Investigate the controllability of the linearized system. (7)
- (e) Is the linearized system observable with  $y = \xi_2$  being the only output? (8)
- (f) If possible, design a state-feedback regulator for the linearized system such that the closed-loop characteristic polynomial is the following:

$$s^2 + 2s + 2 = 0$$

(15)

*Please send your solution to me (ashtew@iitk.ac.in) before 1:00 p.m. today.*