

Hardware details

1.Motor:

Dc geared motor (TG-30P-BE-120-D050)

24V

Rpm 29.4

33W



Alternative:

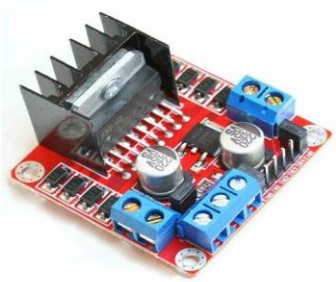
12v 60 rpm high torque dc gear motor gw370

Link:

<https://www.daraz.com.bd/products/reversible-high-torque-turbo-worm-geared-motor-dc-motor-gw370-12v-30rpm-i134650765.html>

Motor driver:

L298N H-Bridge Dual Motor Driver, Stepper Motor Driver



Link:

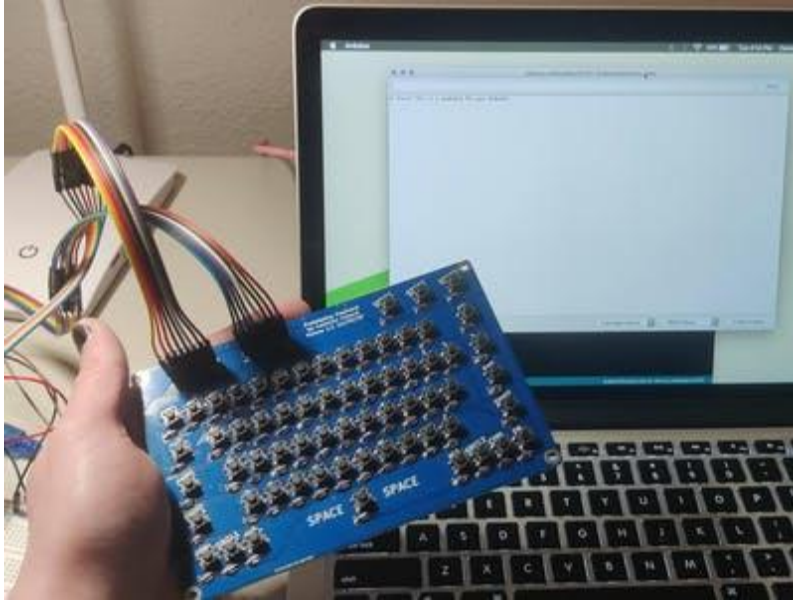
<https://store.roboticsbd.com/motor-driver/376-l298n-h-bridge-dual-motor-driver-stepper-motor-driver-robotics-bangladesh.html>

Battery

12V -7.5 Ah



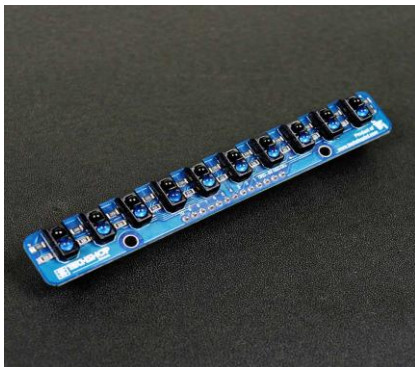
Custom keyboard :



We will try to make with our own design and circuit schematic and printed board

For patient entry

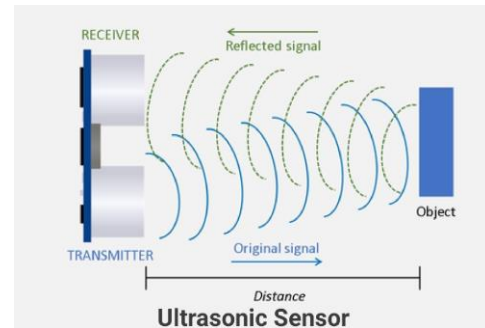
IR sensor array



For line following

Ultra sound sensor

HC-SR04 Ultrasonic Sensor Distance Measuring Module 3.3V / 5V Compatible for Arduino



For object detection

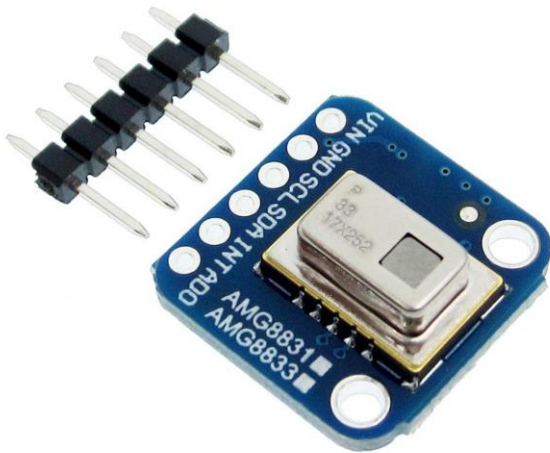
Future adding's will try to go with jetson nano for Image prosses :

Link:

<https://www.amazon.com/NVIDIA-Jetson-Nano-Developer-945-13450-0000-100/dp/B084DSDDL7>



Thermal camera:



AMG8833 IR 8x8 Thermal Imager Array Temperature Sensor Module for Arduino Raspberry Pi

For tracking patients with fever

For robot body we will use stainless steel.