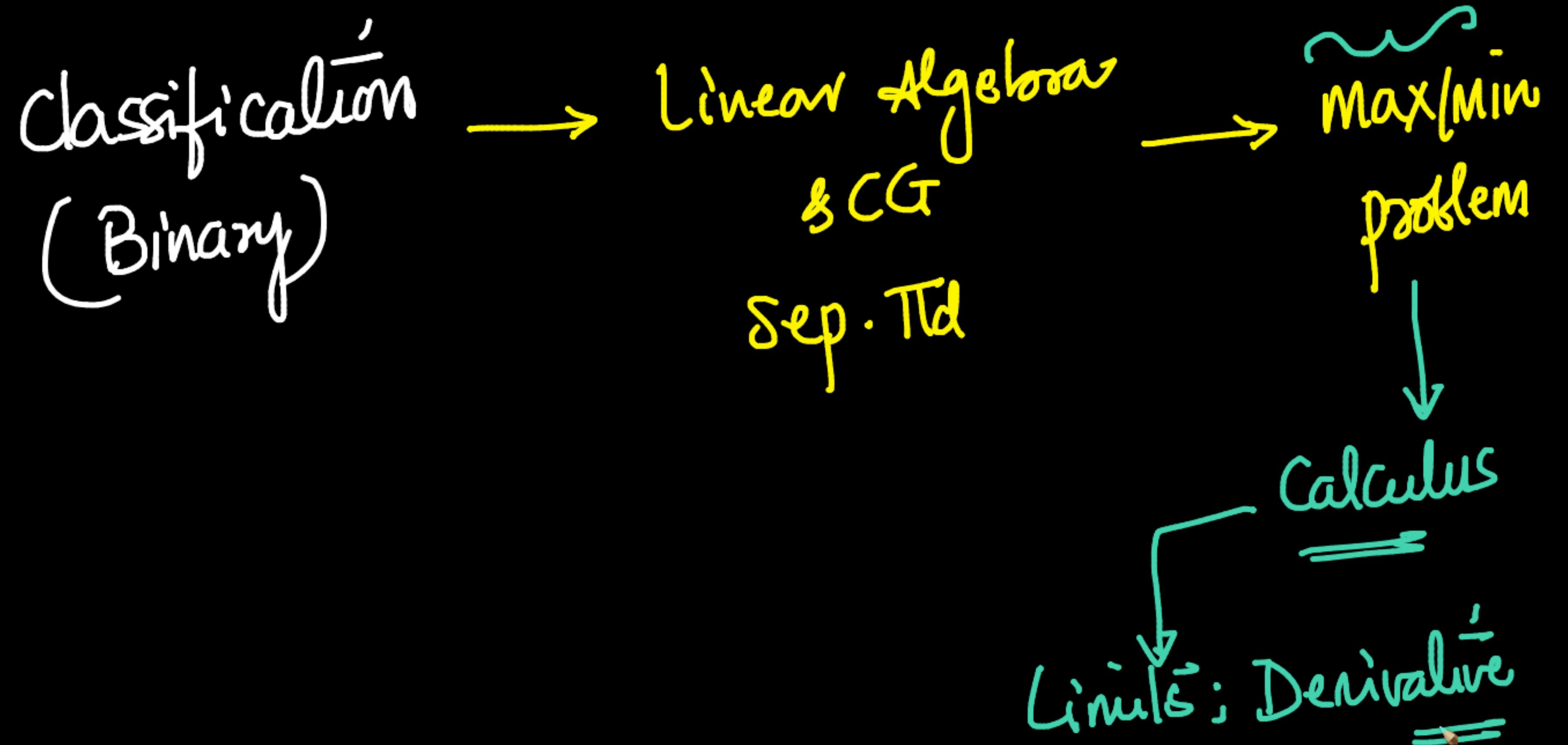
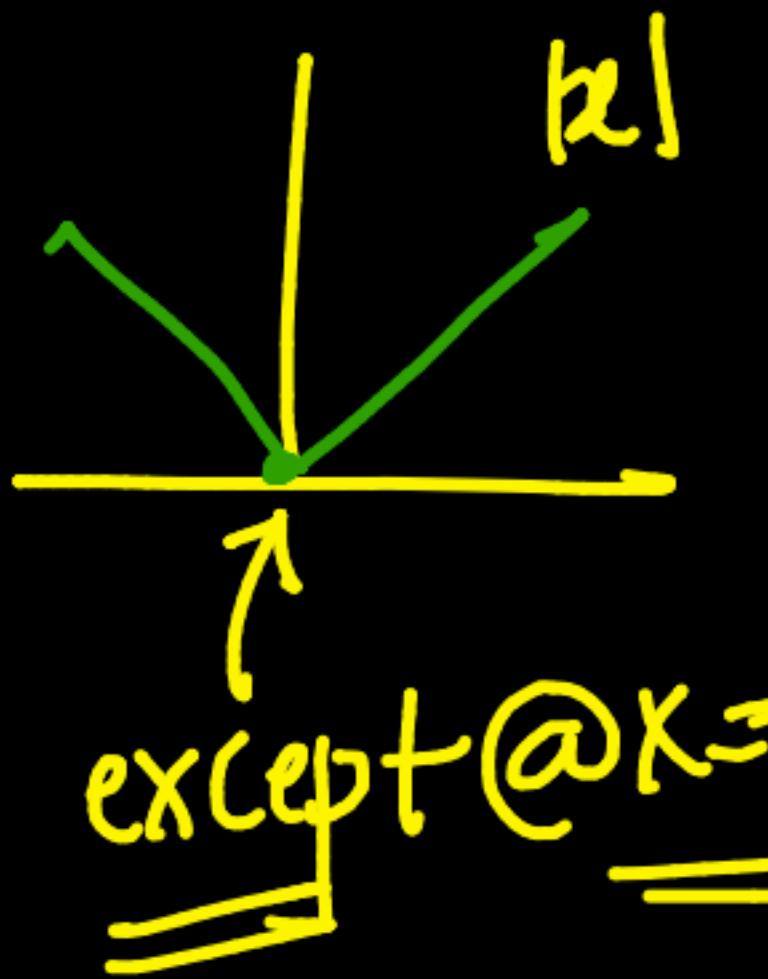


Big-picture



DIFFERENTIABILITY

$|x|$ is not diff. @ $x=0$



$$\lim_{\Delta x \rightarrow 0} \frac{|x + \Delta x| - |x|}{\Delta x}$$

was not defined

$|x|$ is not diff @ $x=0$
 x^2 is diff. -- @ everywhere in the domain

Defn

Domain

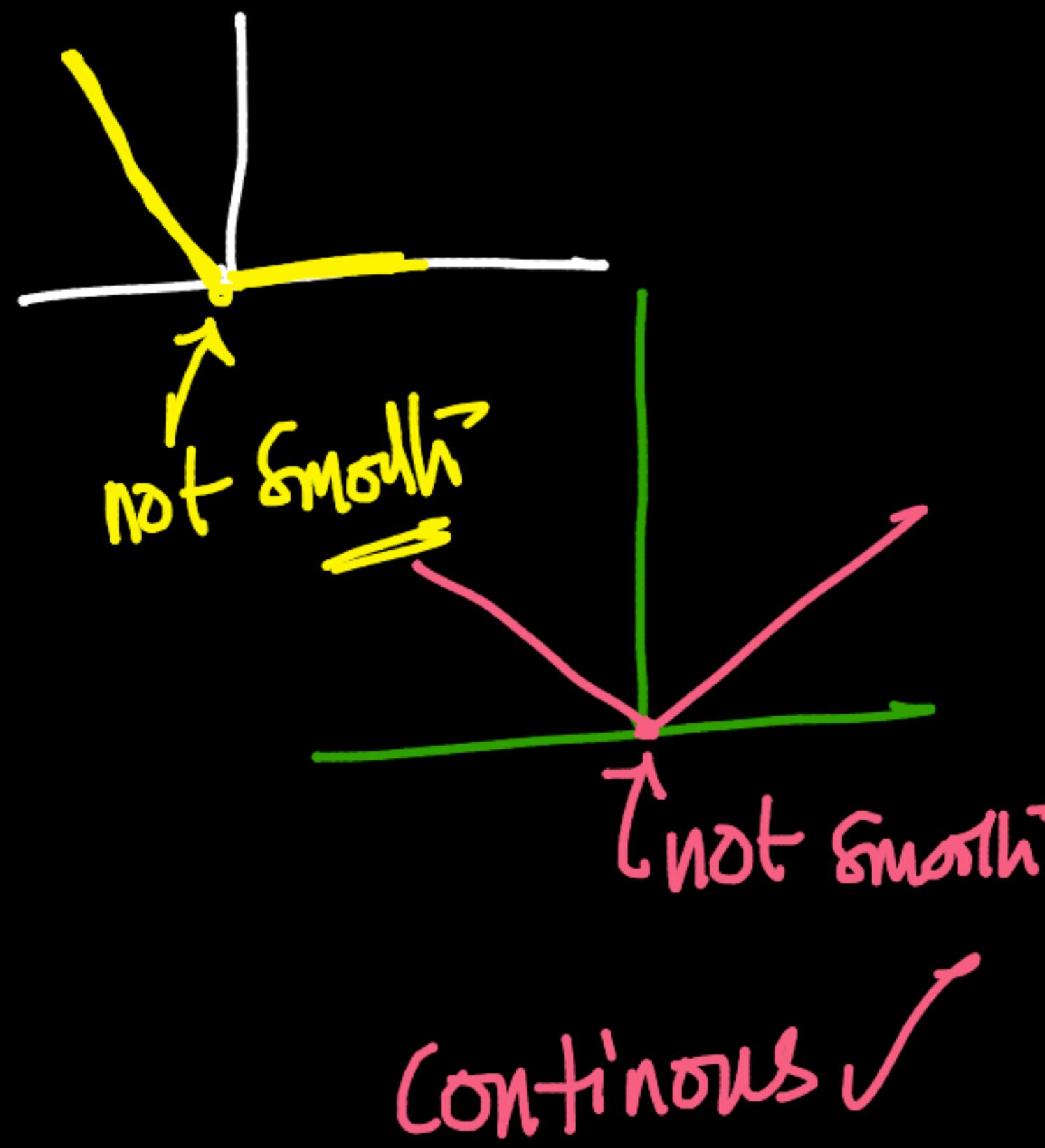
$f(x)$ is diff... if @

$\lim_{\Delta x \rightarrow 0} \frac{f(x + \Delta x) - f(x)}{\Delta x}$

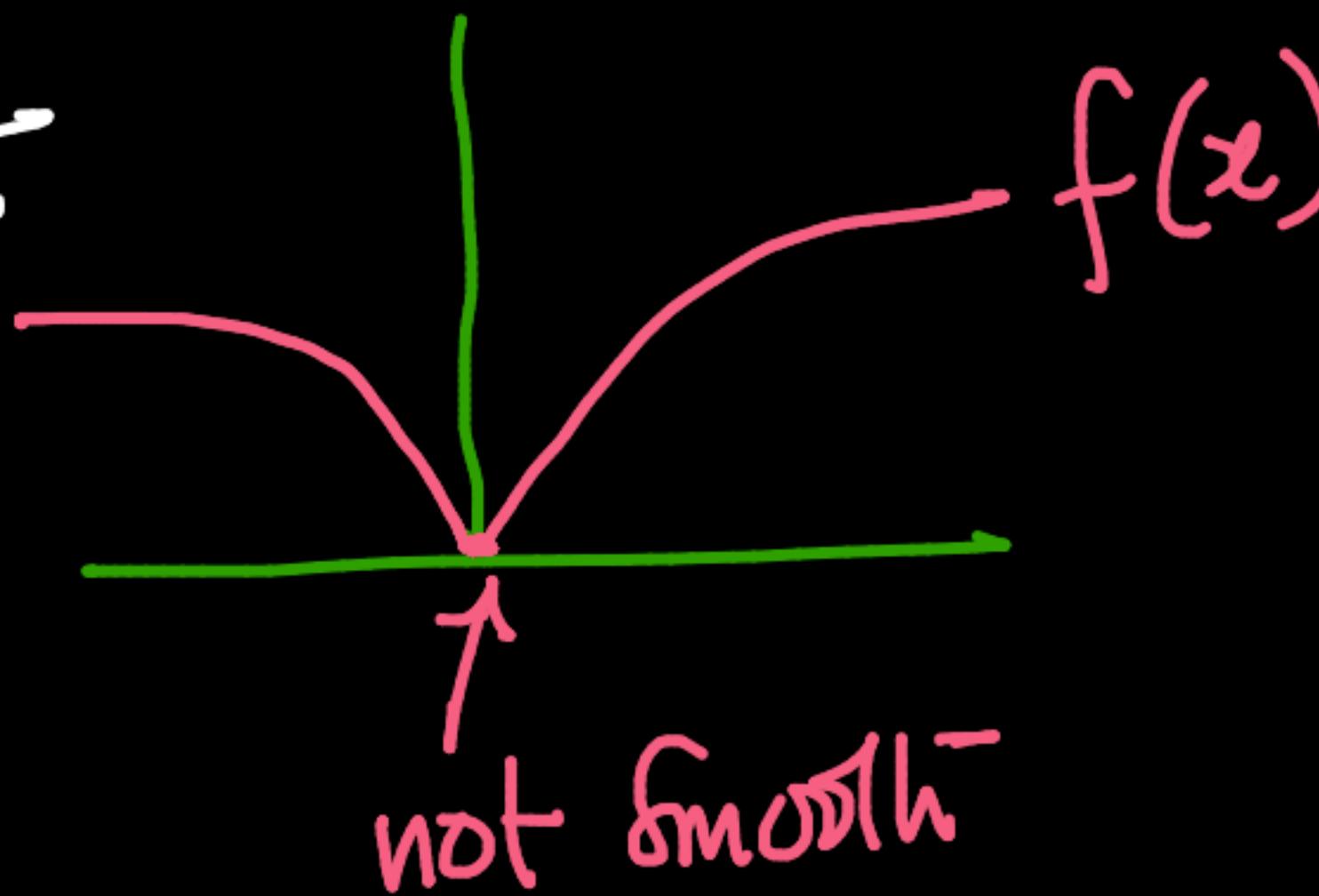
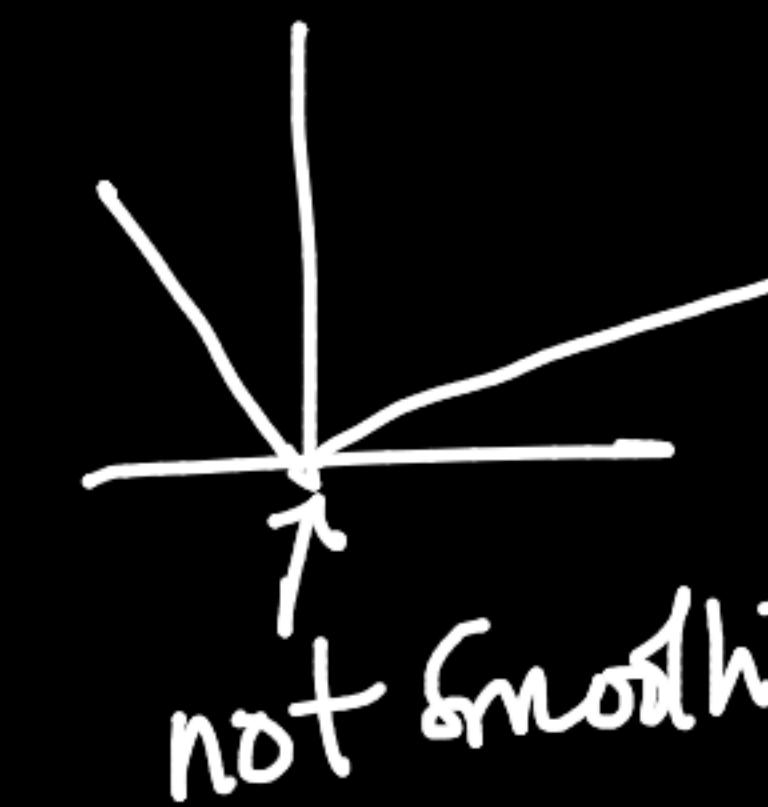
L.S.L R.S.L

Math

exists @ all x =



continuous ✓



Geom -intuition

$f(x)$

✓ { DIFFerentiability = continuous & 'smooth'



Notation:

$$\frac{d}{dx} f(x) = \frac{df}{dx} = f' = y' = \frac{dy}{dx}$$

y

$$f(x)=y$$



Rules:

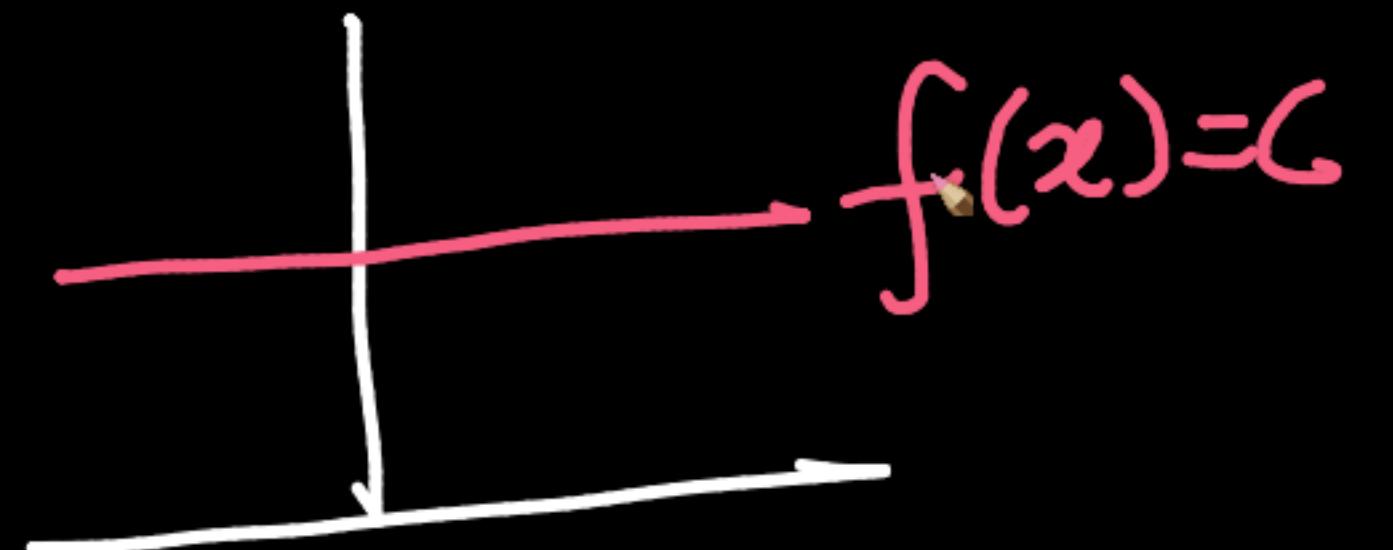
$$\frac{d}{dx} [f(x) + g(x)] = \frac{d}{dx} f(x) + \frac{d}{dx} g(x)$$

→ $(f+g)' = f' + g'$

Q

C: constant

$$\frac{dc}{dx} = 0$$



product rule:

③

$$\frac{d}{dx} [f(x) \cdot g(x)] = f(x) \frac{dg}{dx} + g(x) \frac{df}{dx}$$

$$\frac{d}{dx}(x^2) = \frac{d}{dx}(x \cdot x) = x \cdot 1 + x \cdot 1 = 2x$$

$$\frac{d}{dx} x^n = n x^{n-1}$$

n ≠ 0



$$\frac{d}{dx} (x \cdot \log x) = x \cdot \frac{1}{x} + \log x \cdot 1$$

$\downarrow \qquad \downarrow$

$$f(x) \ g(x) = \underline{\underline{1 + \log(x)}}$$

CHAIN - RULE

$$\left\{ \frac{d}{dx} f(g(x)) = f'(g(x)) \cdot g'(x) \right.$$

[most widely used]

e.g.: $\frac{d}{dx} (\log(x^2)) = \frac{1}{x^2} \cdot 2x = \frac{2}{x}$

$g(x) = x^2$
 $f = \log$

Let $x^2 = u$

$\frac{d}{dx} (\log x^2)$ \rightarrow natural-log

↓

ln

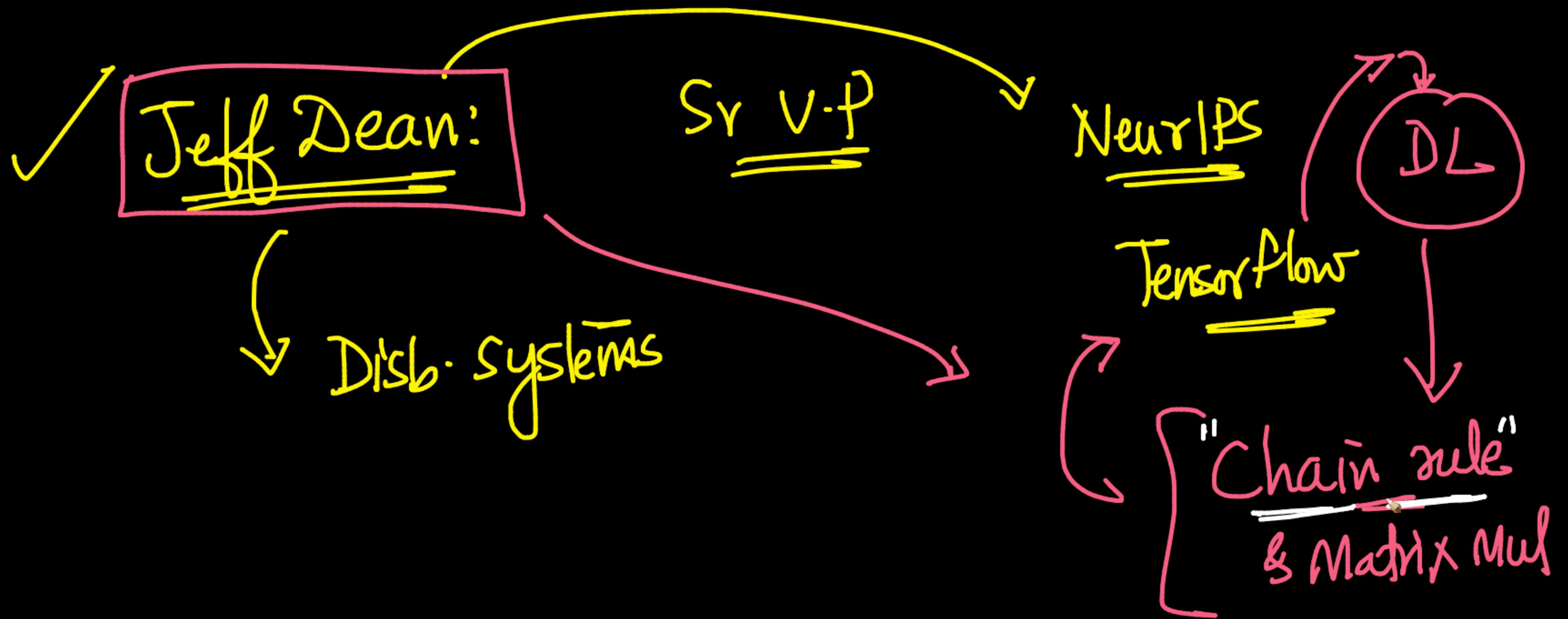
$$\frac{d}{dx} \log(x^2) = \frac{d}{dx} \log(u) = \frac{d \log(u)}{du} \cdot \frac{du}{dx}$$

$$= \frac{1}{u} \cdot 2x$$

$$= \frac{2x}{x^2} = \frac{2}{x}$$

outer
inner

$\frac{d}{dx} \log(x^2) = \frac{1}{x^2} \cdot 2x = \frac{2}{x}$



Quotient rule:

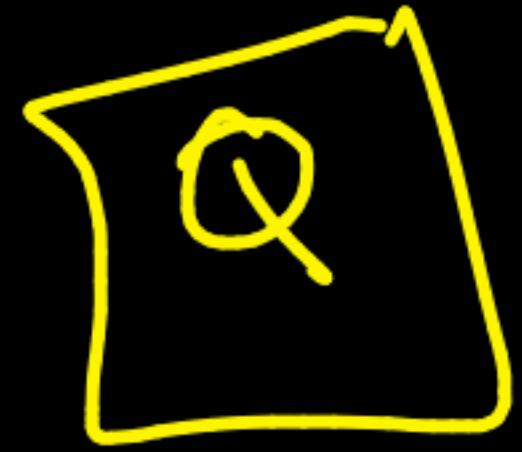
$$\frac{d}{dx} \frac{f(x)}{g(x)} = \frac{f'(x)g(x) - g'(x)f(x)}{[g(x)]^2}$$

product!

$$G \cdot f(x) \cdot \frac{1}{g(x)}$$

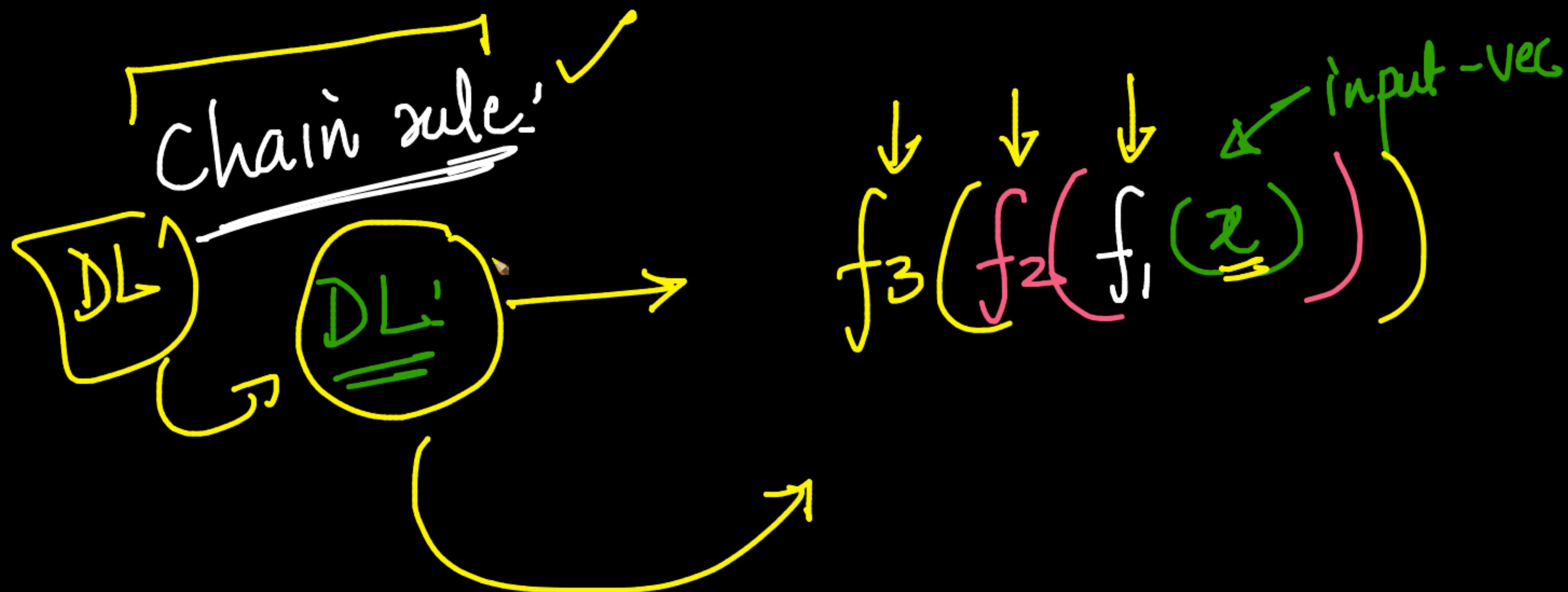
Q

$$\frac{d}{dx} \frac{\log(x)}{x} = \frac{\frac{1}{x} \cdot x - 1 \cdot \log(x)}{x^2} = \frac{1 - \log(x)}{x^2}$$



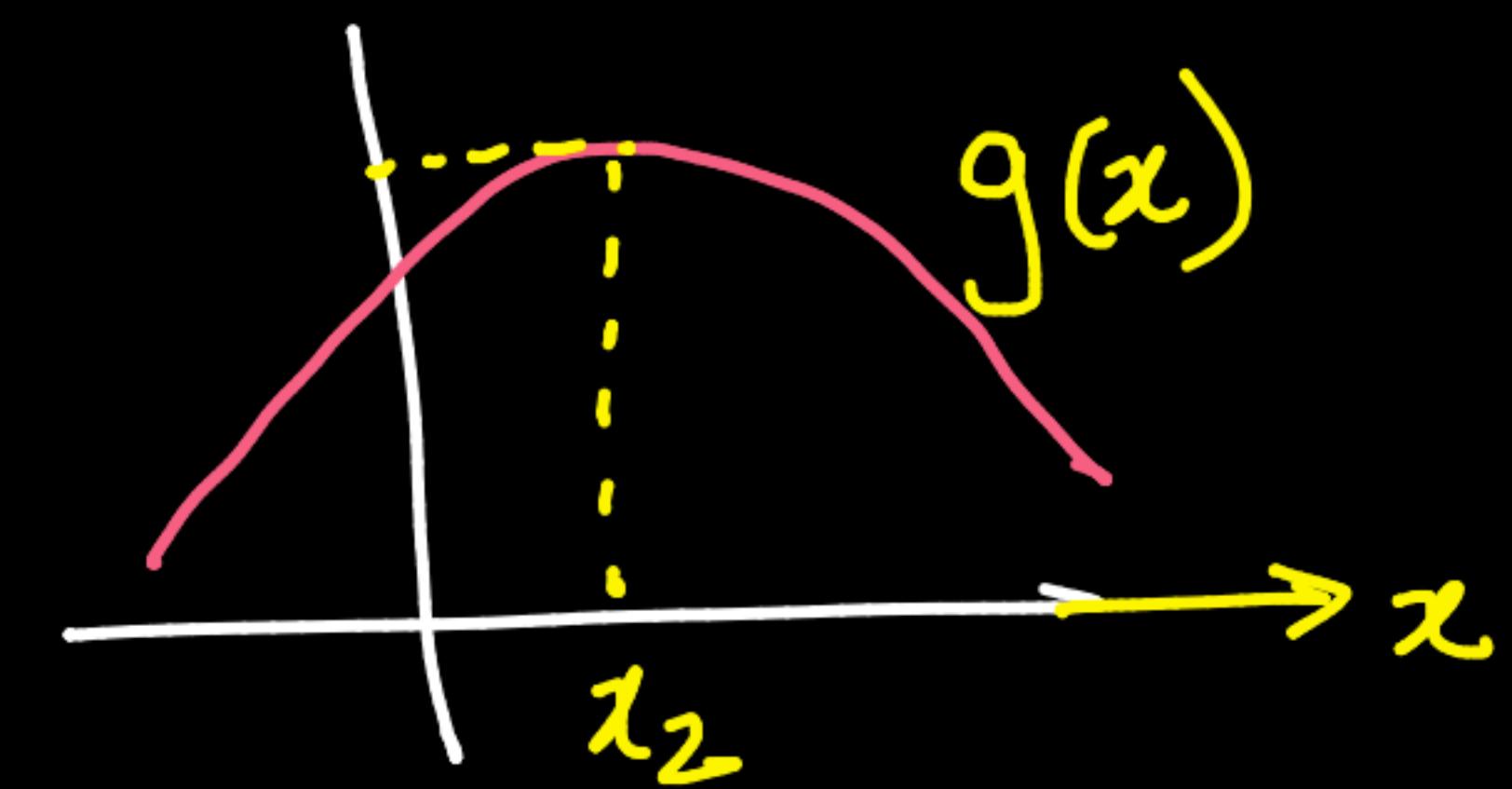
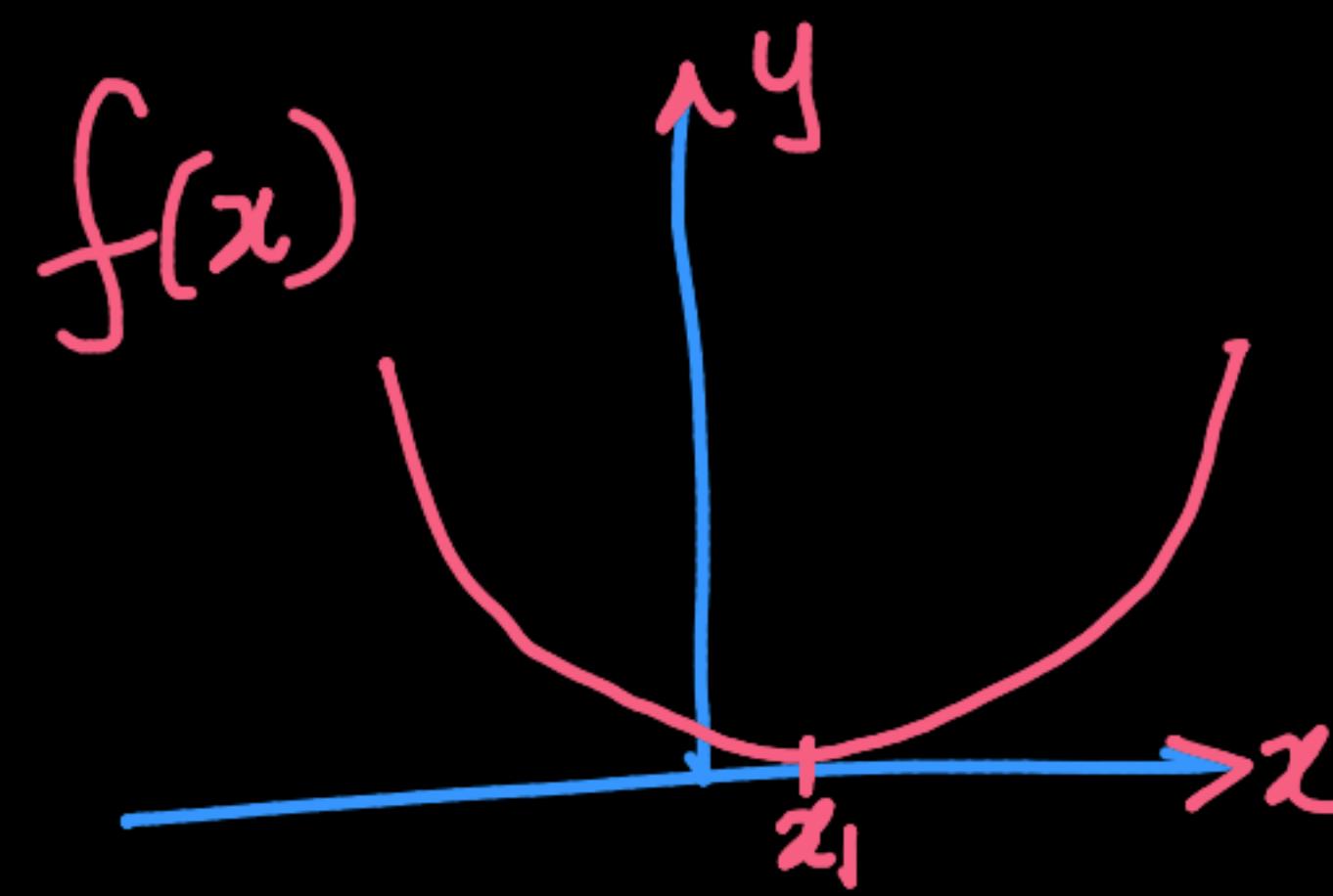
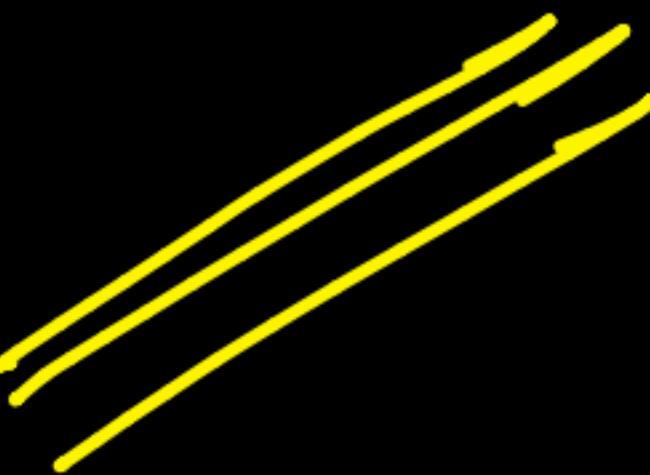
$$\frac{d}{dx} \left(\frac{x}{\log x} \right) = \frac{1 \cdot \log(x) - \frac{1}{x} \cancel{\log x}}{(\log x)^2}$$

$$= \frac{\log -1}{(\log x)^2}$$

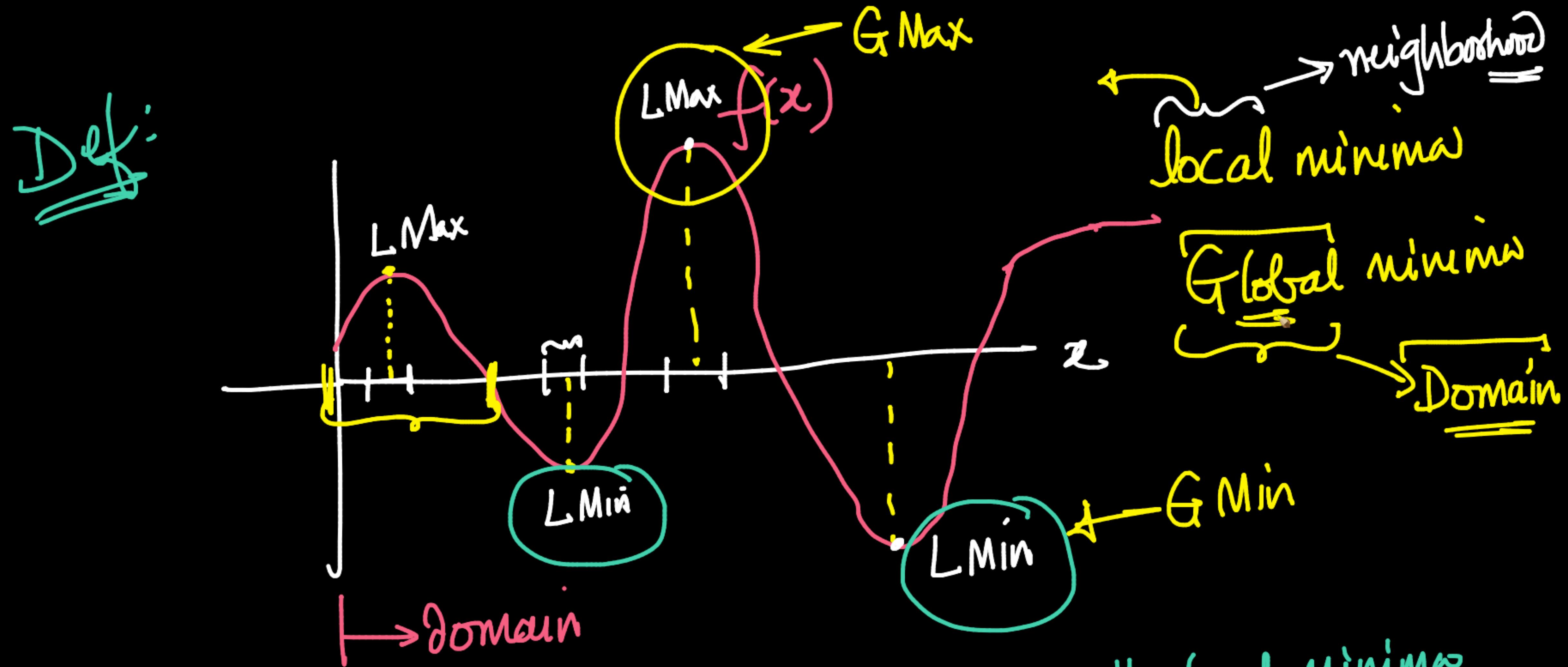


$\frac{d}{dx} f(x) \rightarrow \underline{\text{code}}$

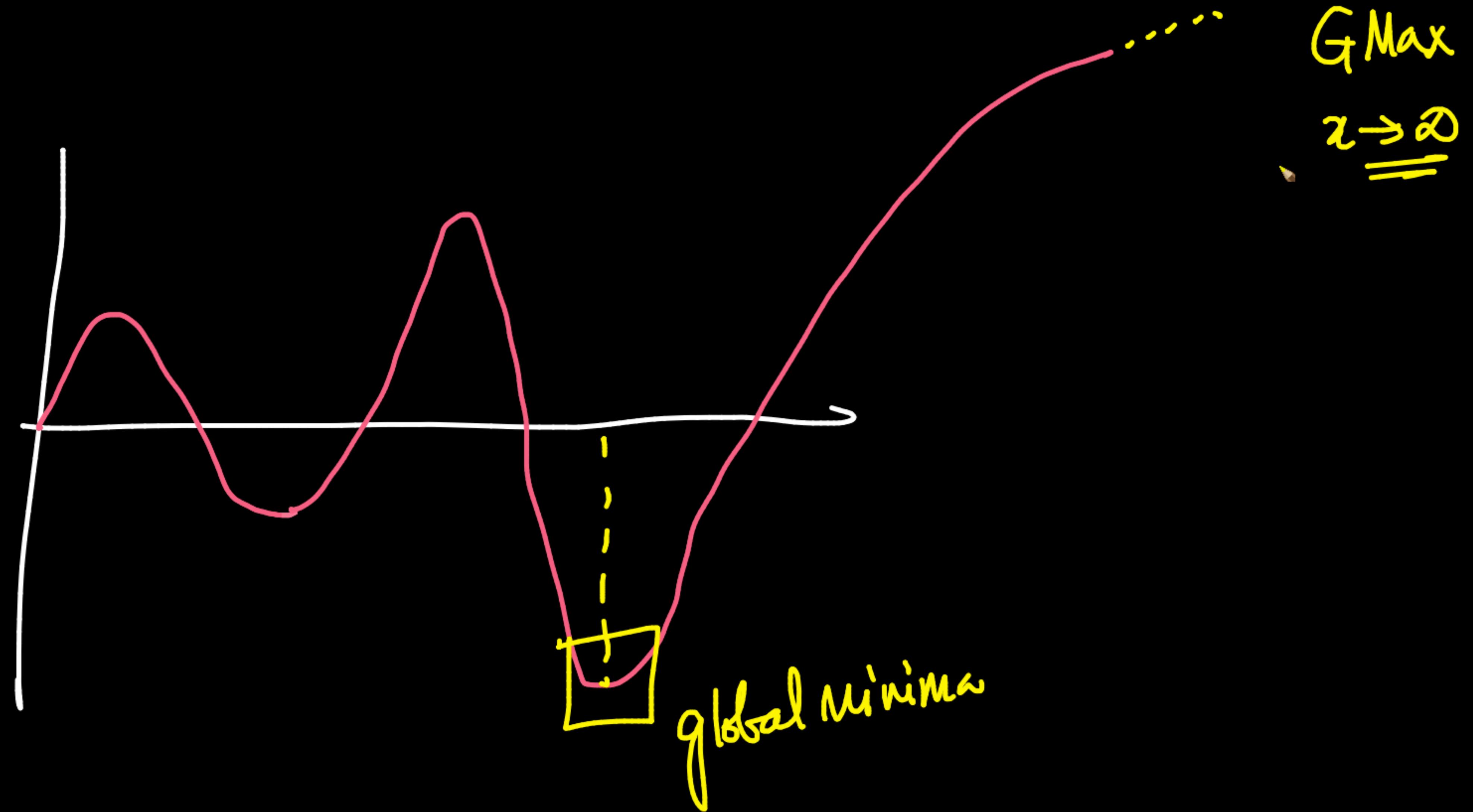
MAXIMA & MINIMA

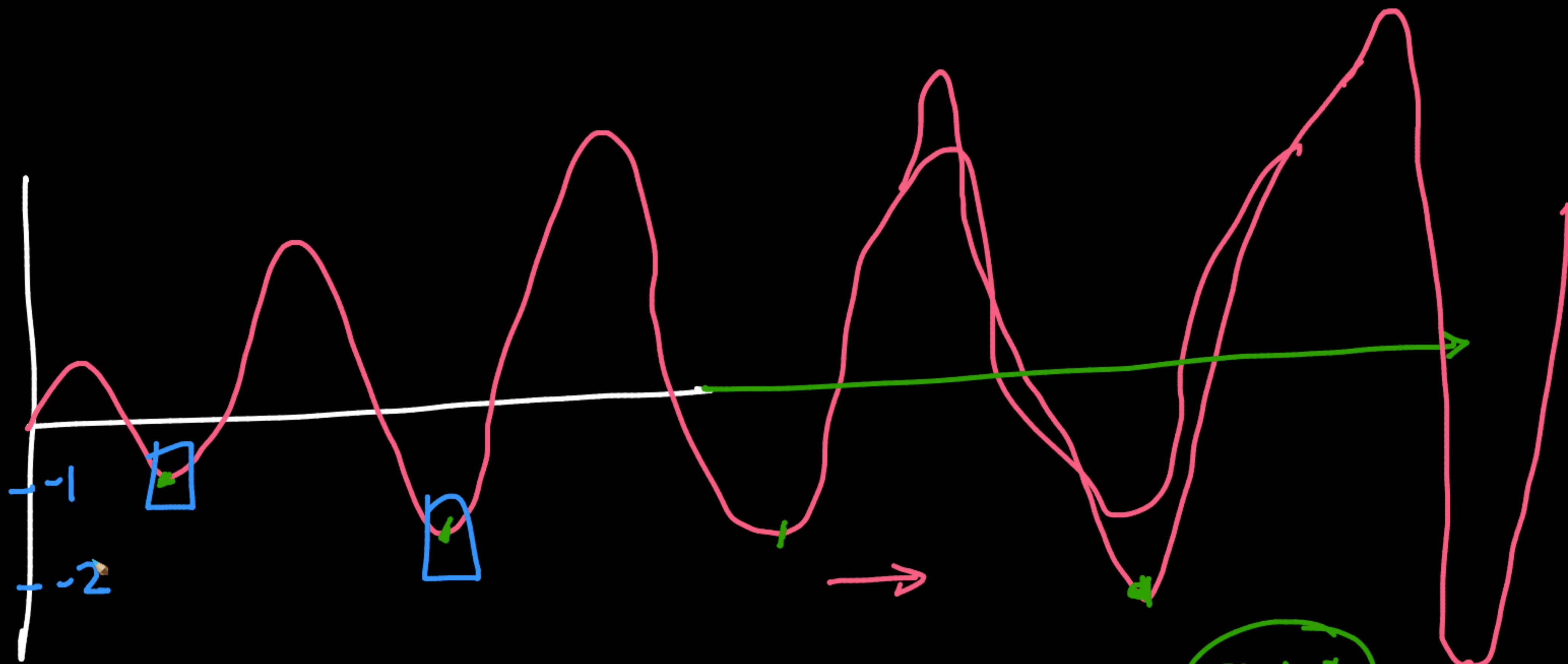


$g(x)$ has a Maxima @
 $x = x_2$

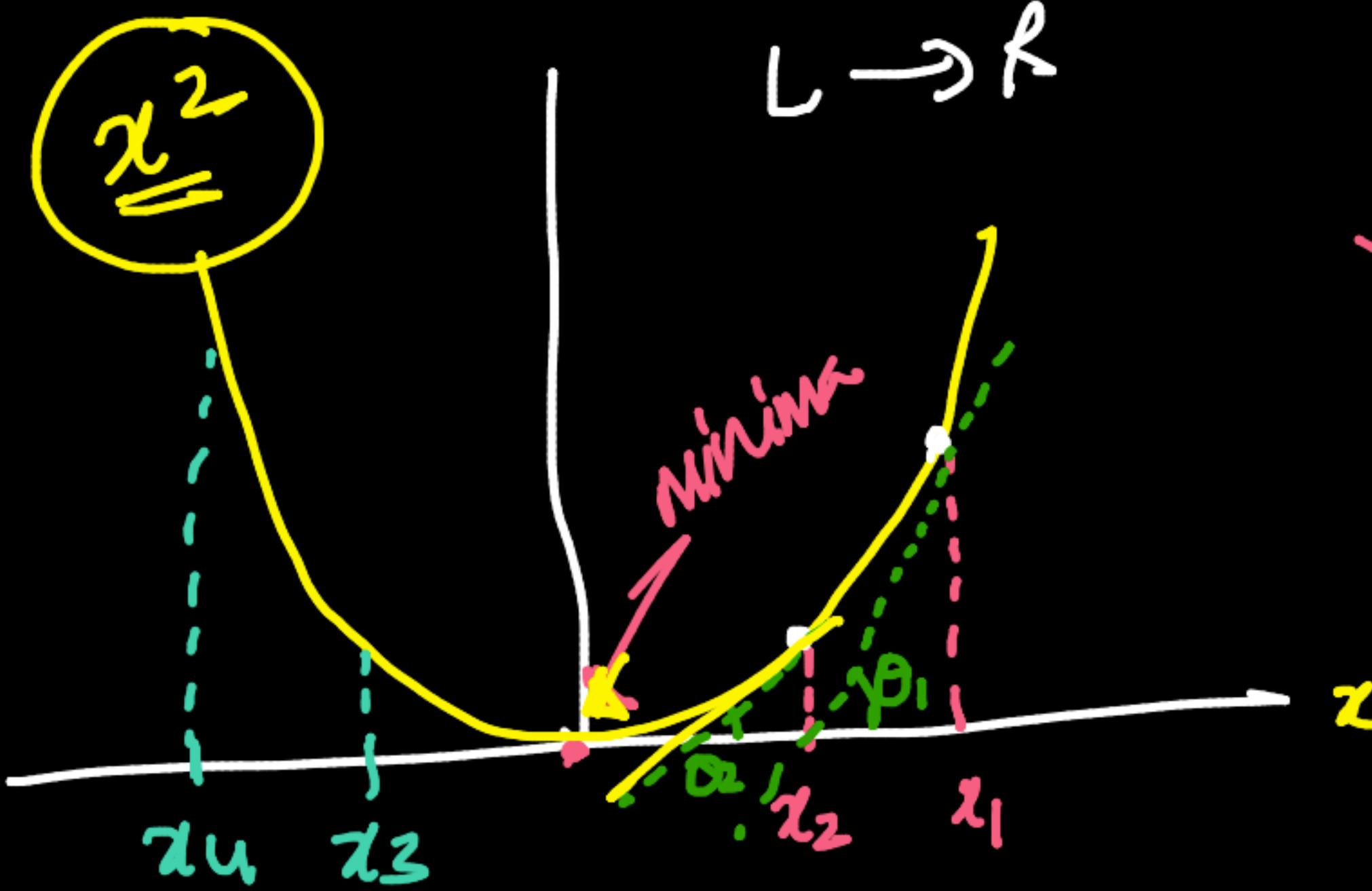


min amongst all local minima
= Global minima

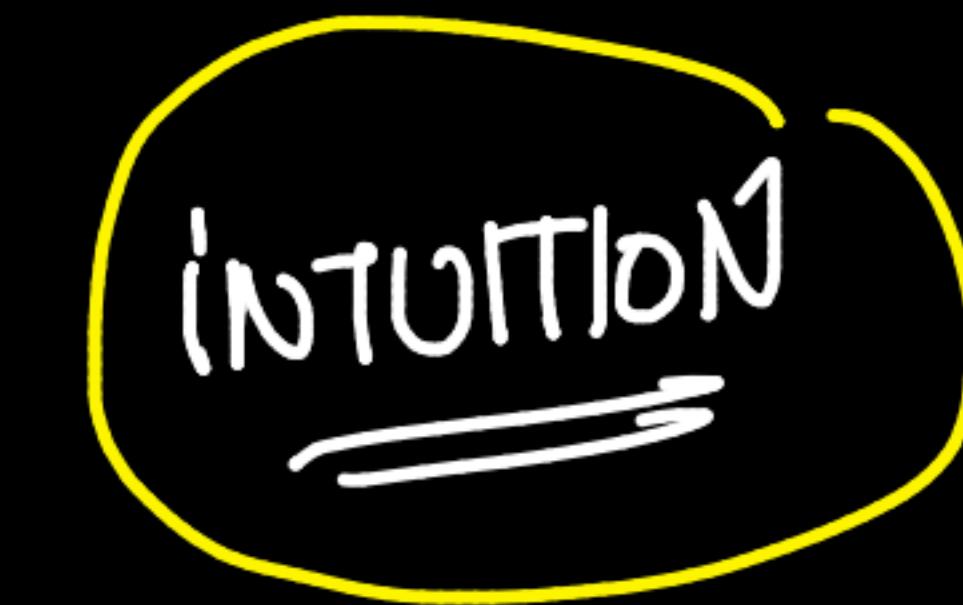




$\left\{ \begin{array}{l} G_{\text{Min}} \rightarrow x \rightarrow \infty \\ G_{\text{Max}} \rightarrow x \rightarrow \infty + \delta \end{array} \right.$



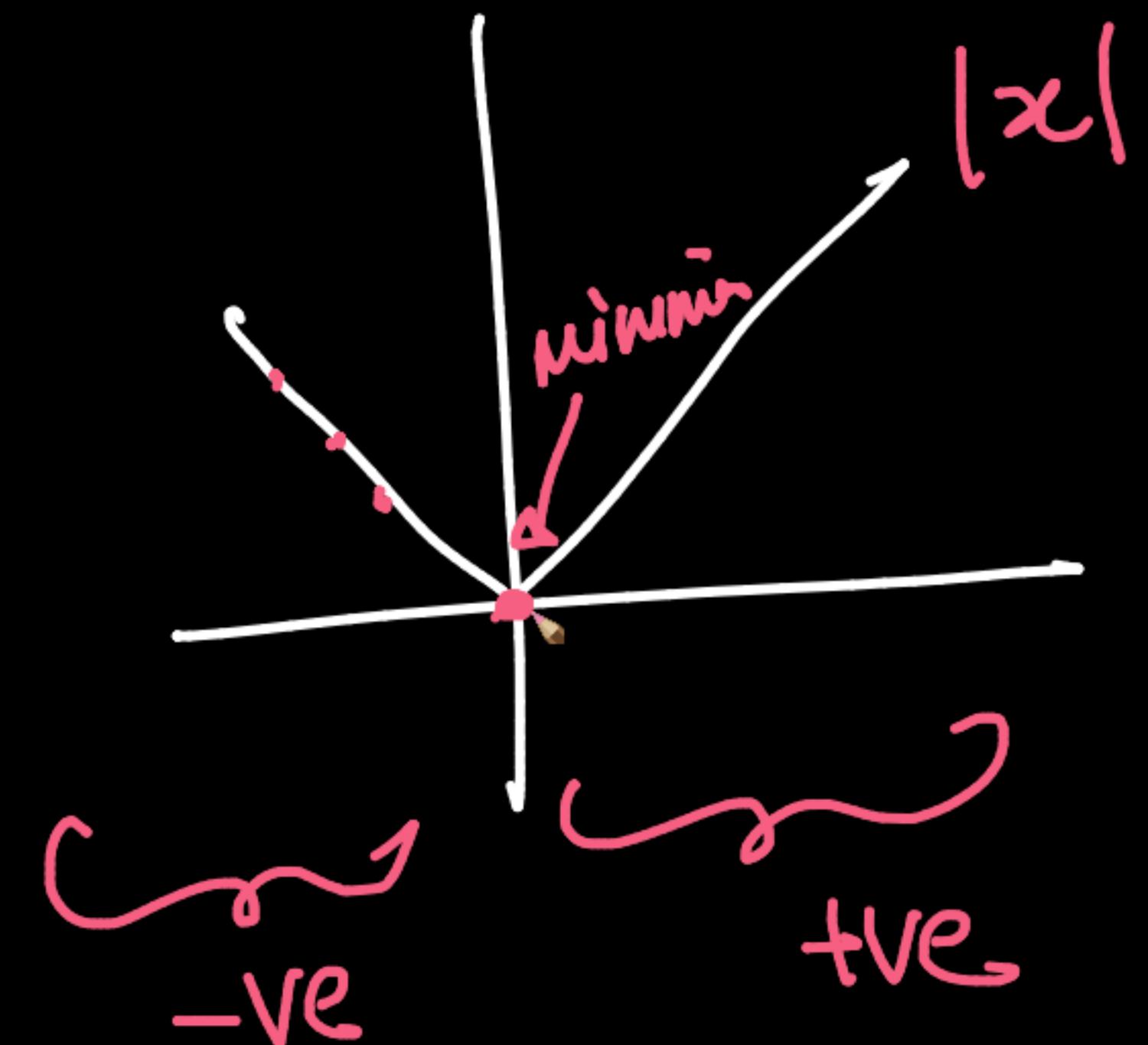
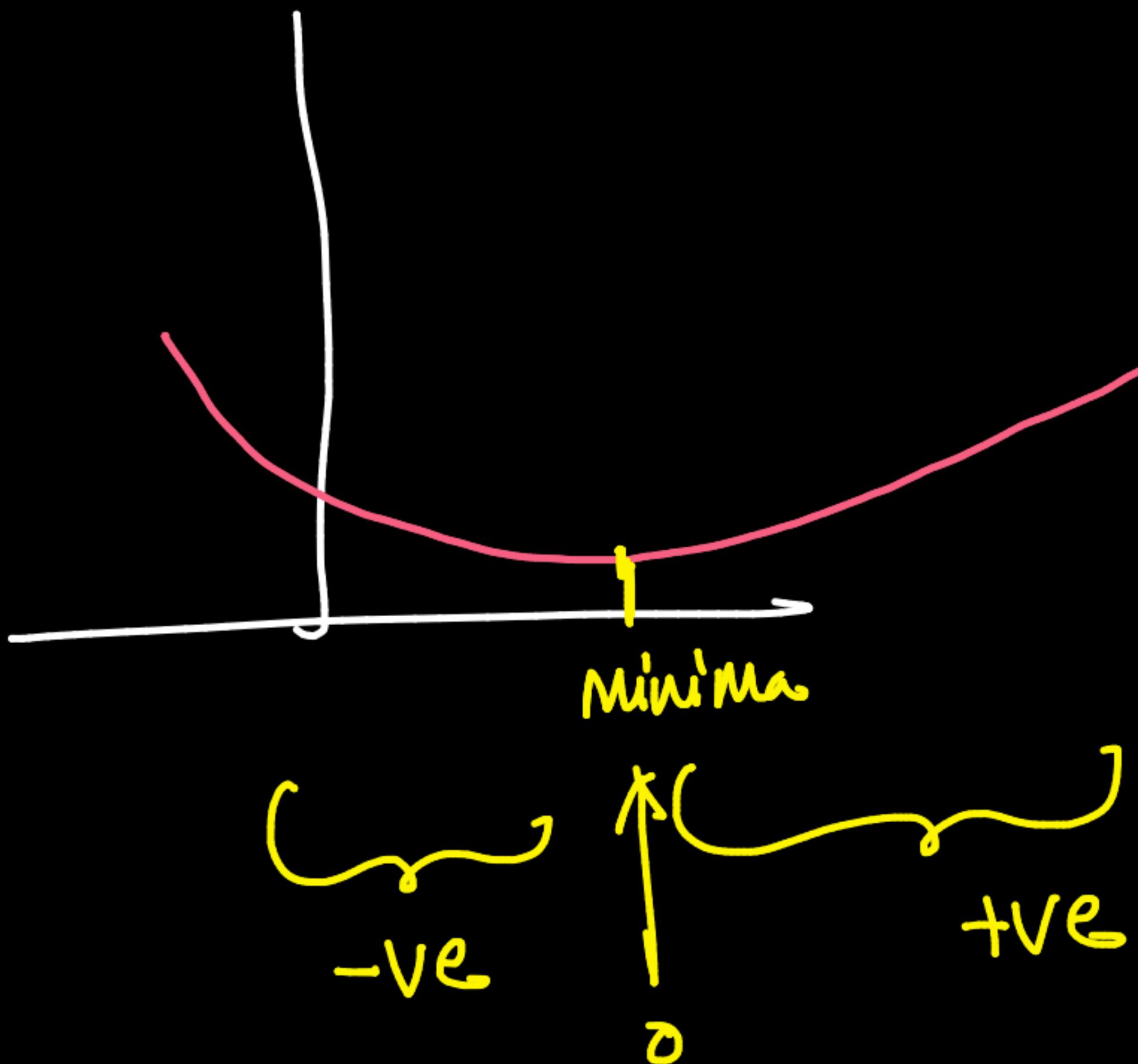
{ How to find
Maximas & Minima

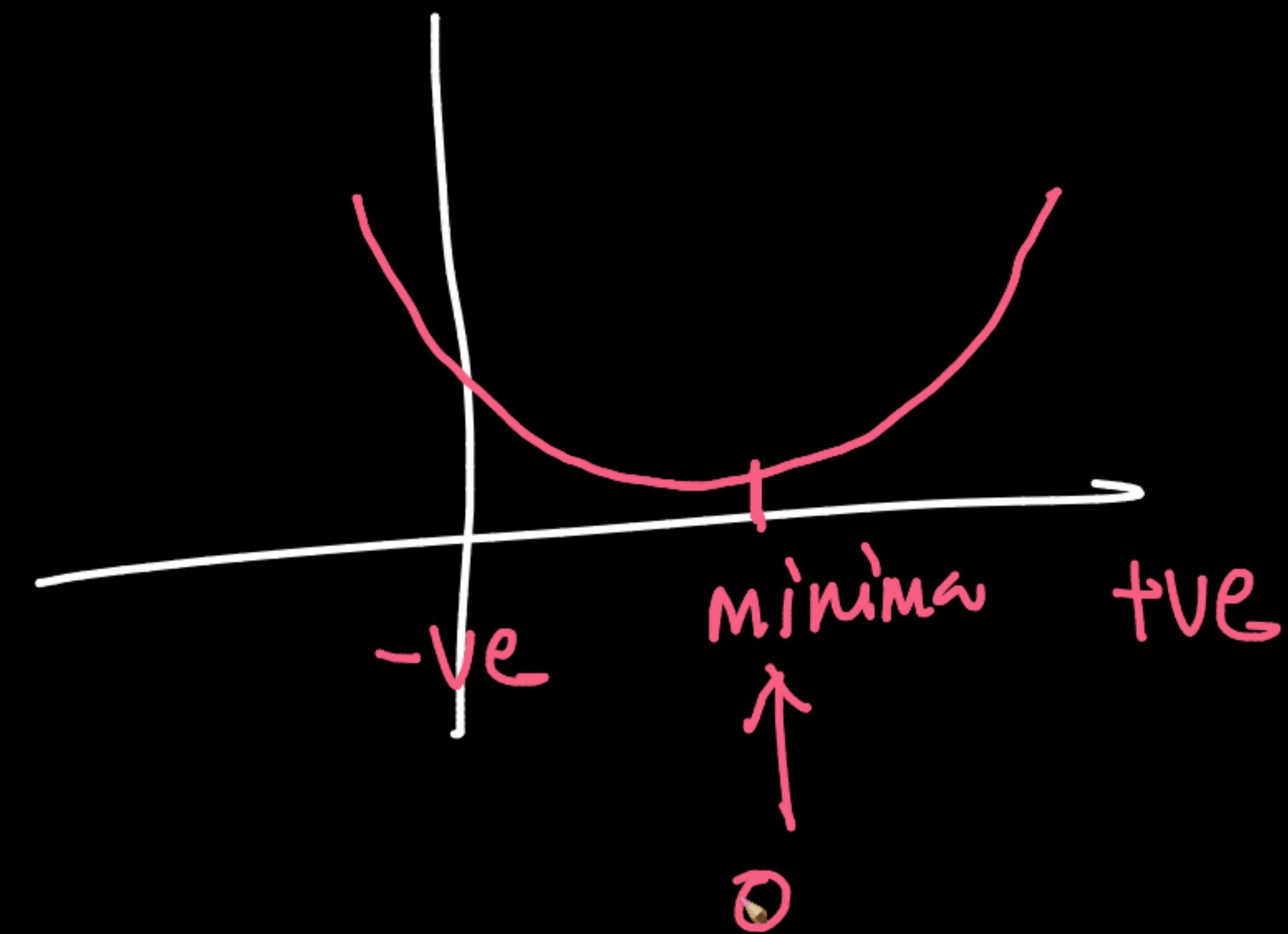


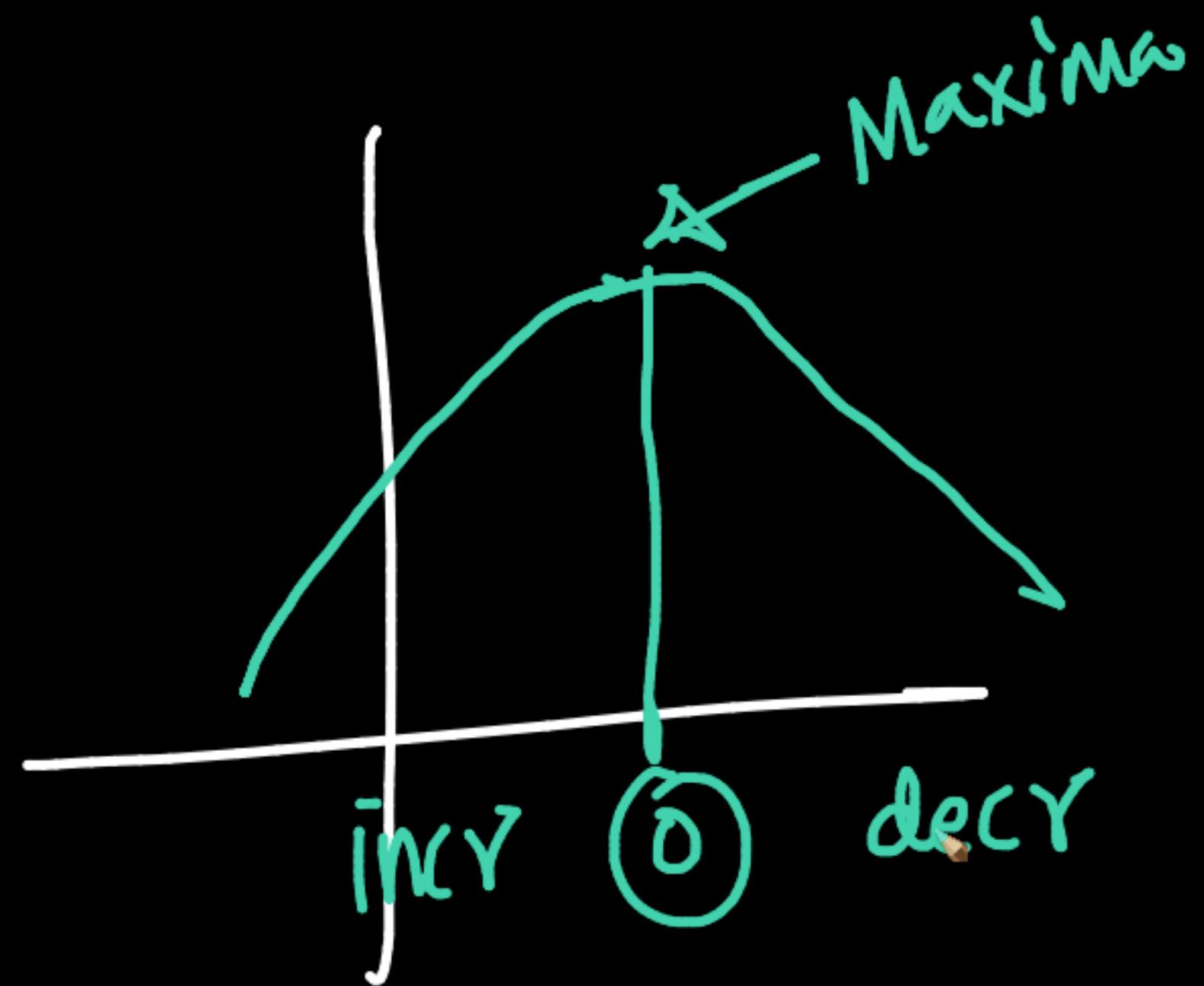
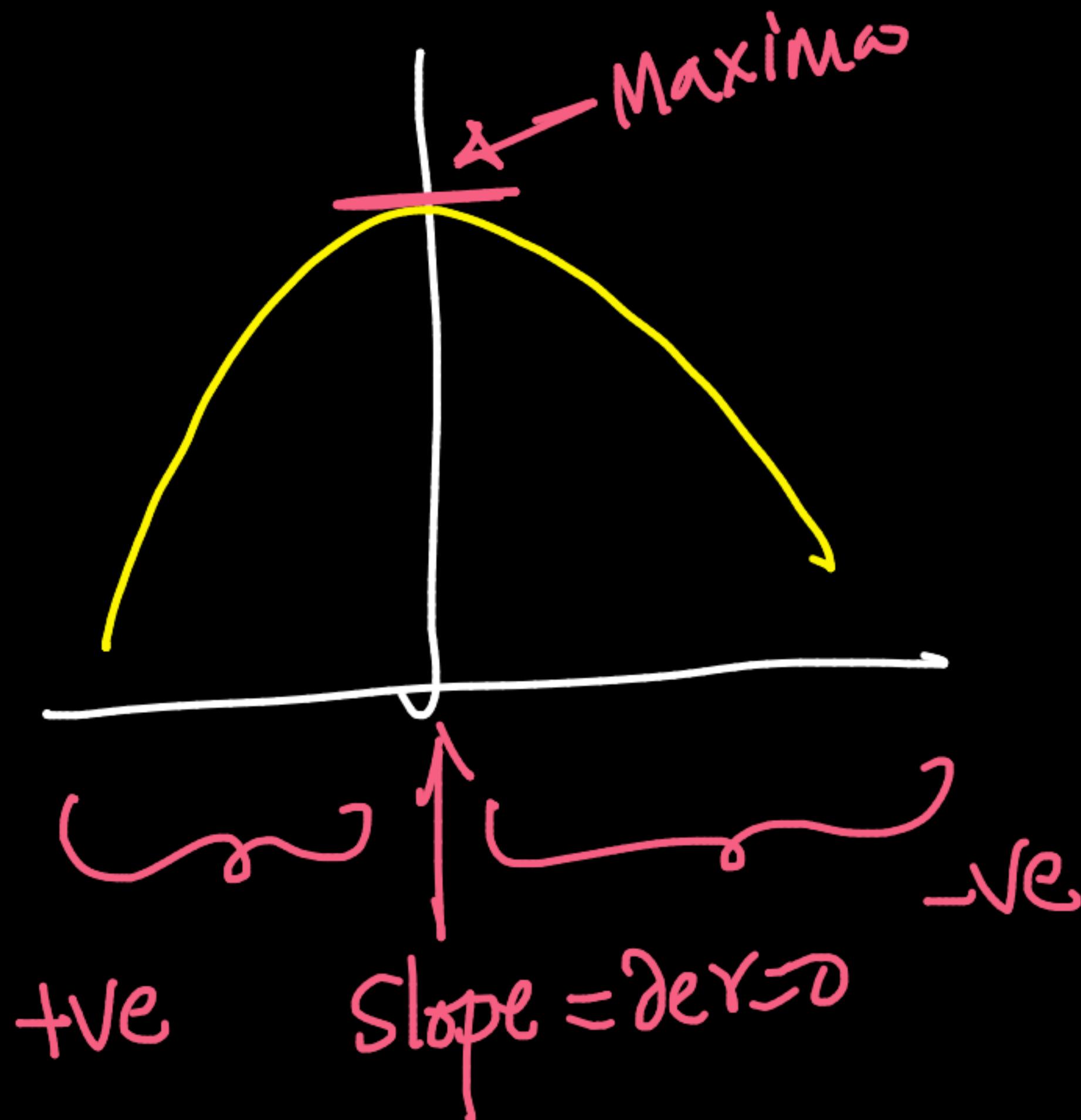
der → -ve
(Inv)

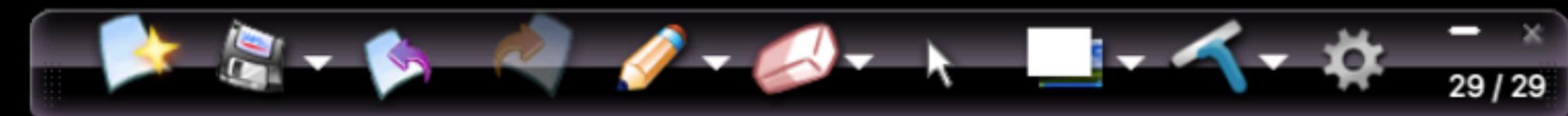
0 ← tve
(inc)

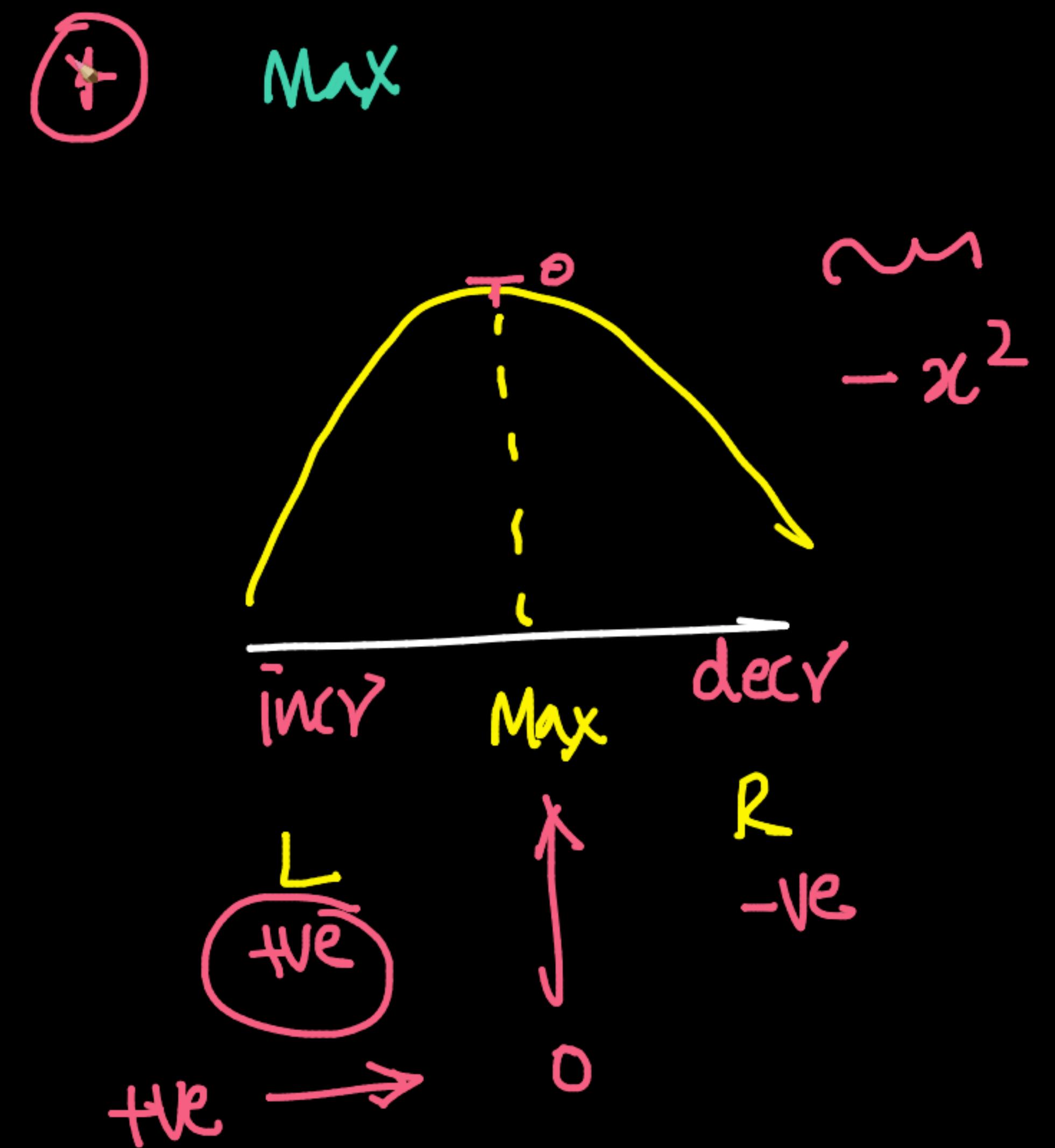
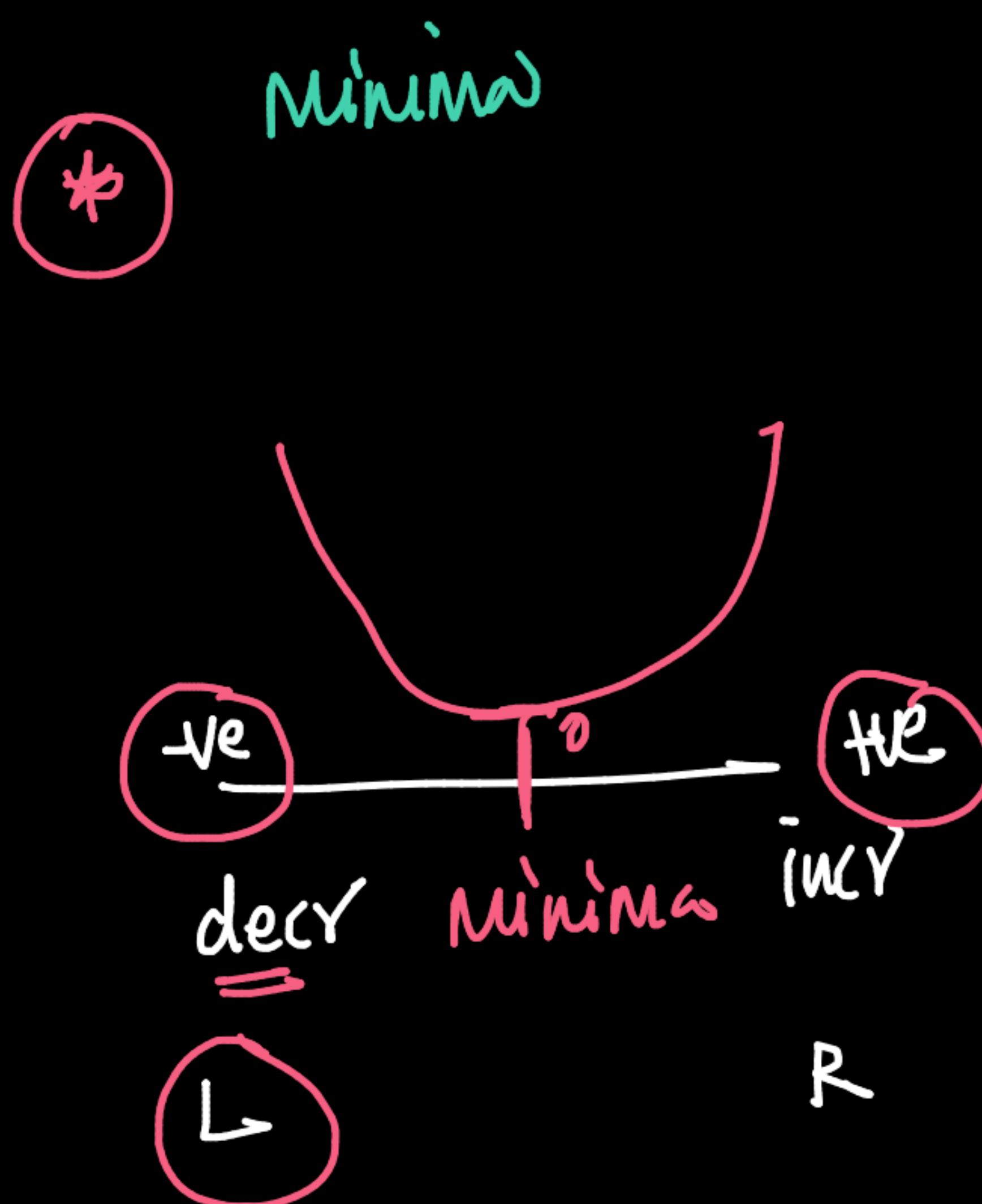
der@ x_1 > der@ x_2
 $0 < \theta_2 < \theta_1 < 90^\circ$
 $\tan \theta_2 < \tan \theta_1$

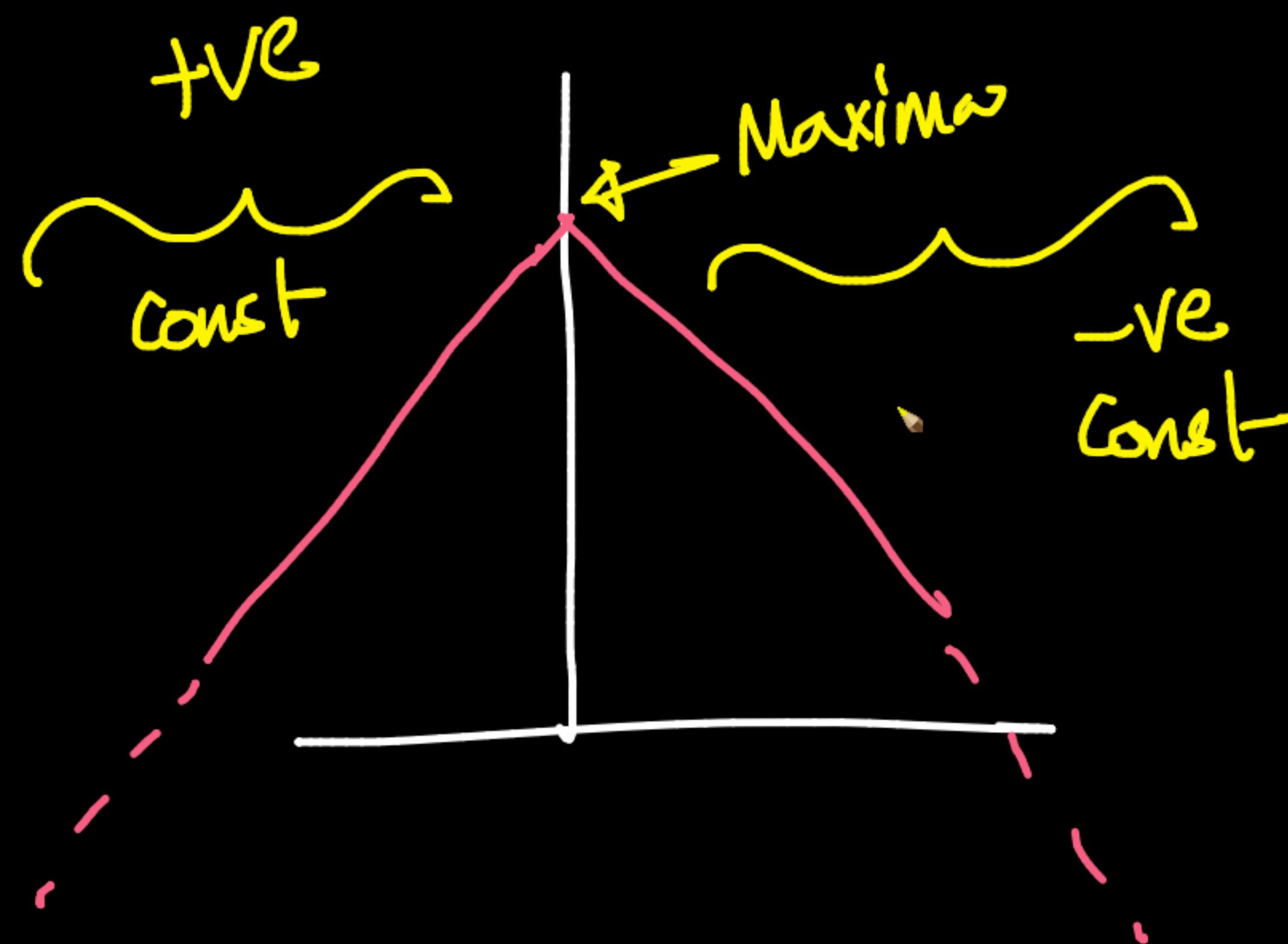










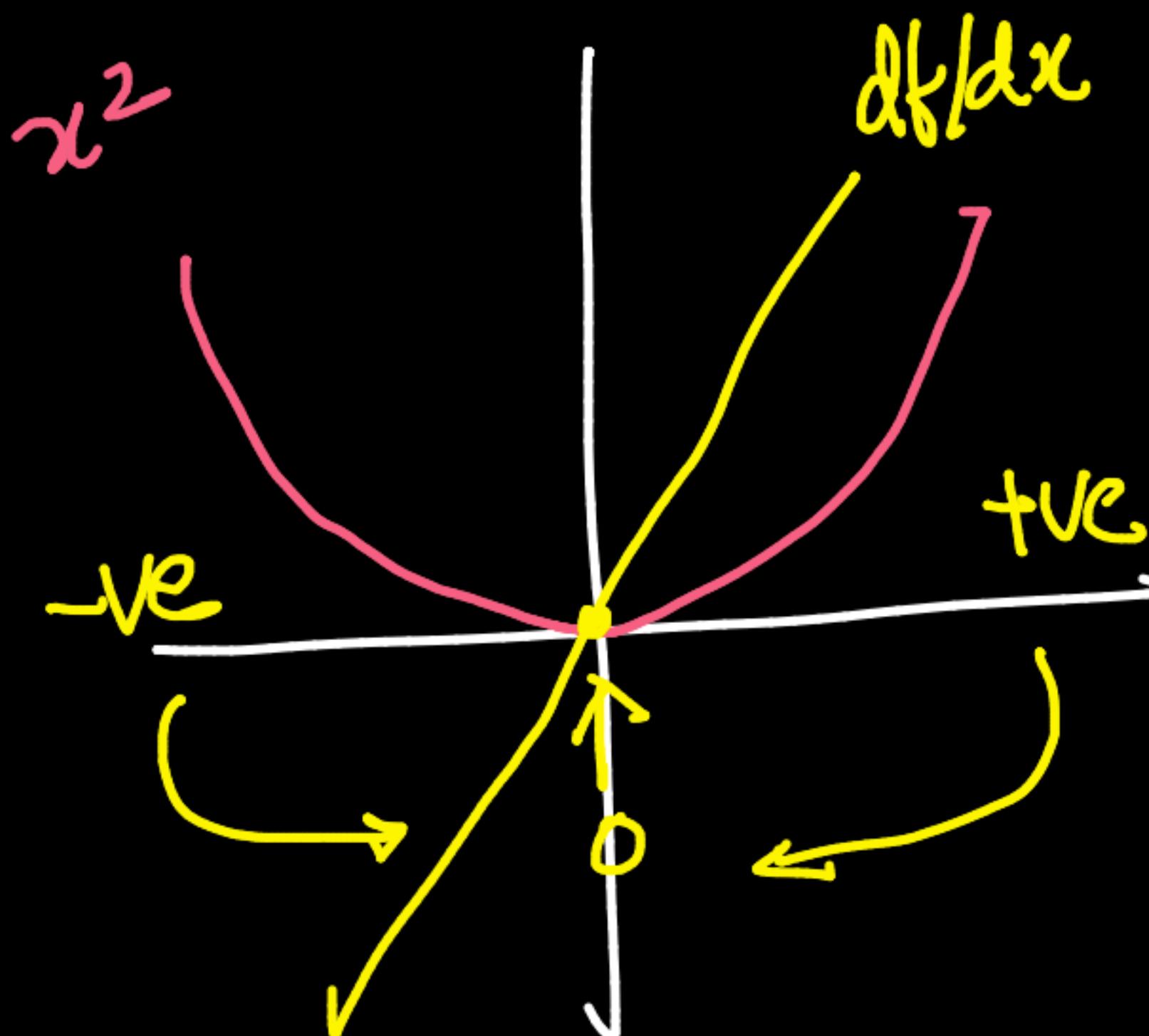


$$f(x) = x^2$$

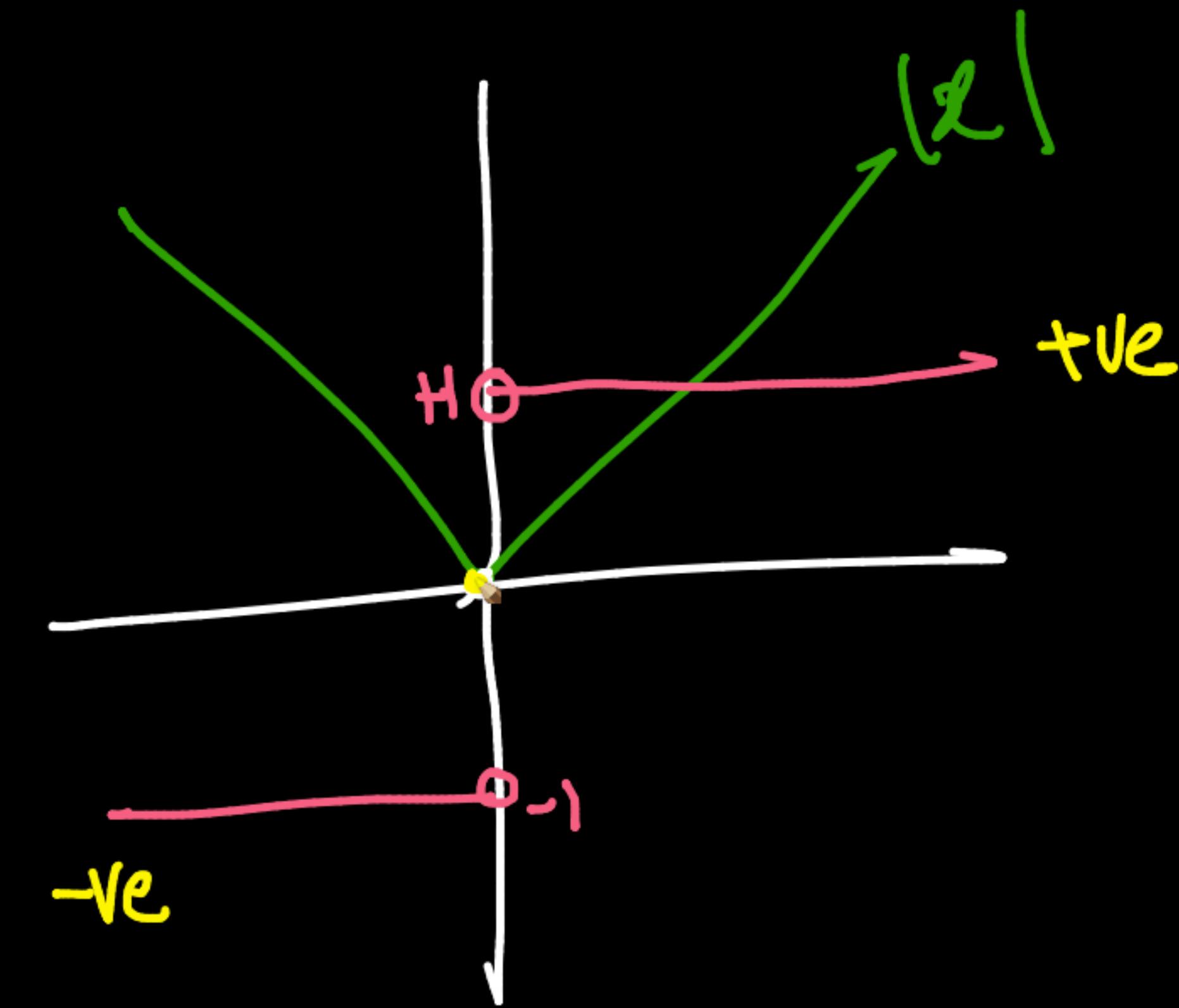
$$\frac{df}{dx} = 2x$$

$$g(x) = \frac{df}{dx}$$

$$f(x) = x^2$$



$$f(x) = |x|$$

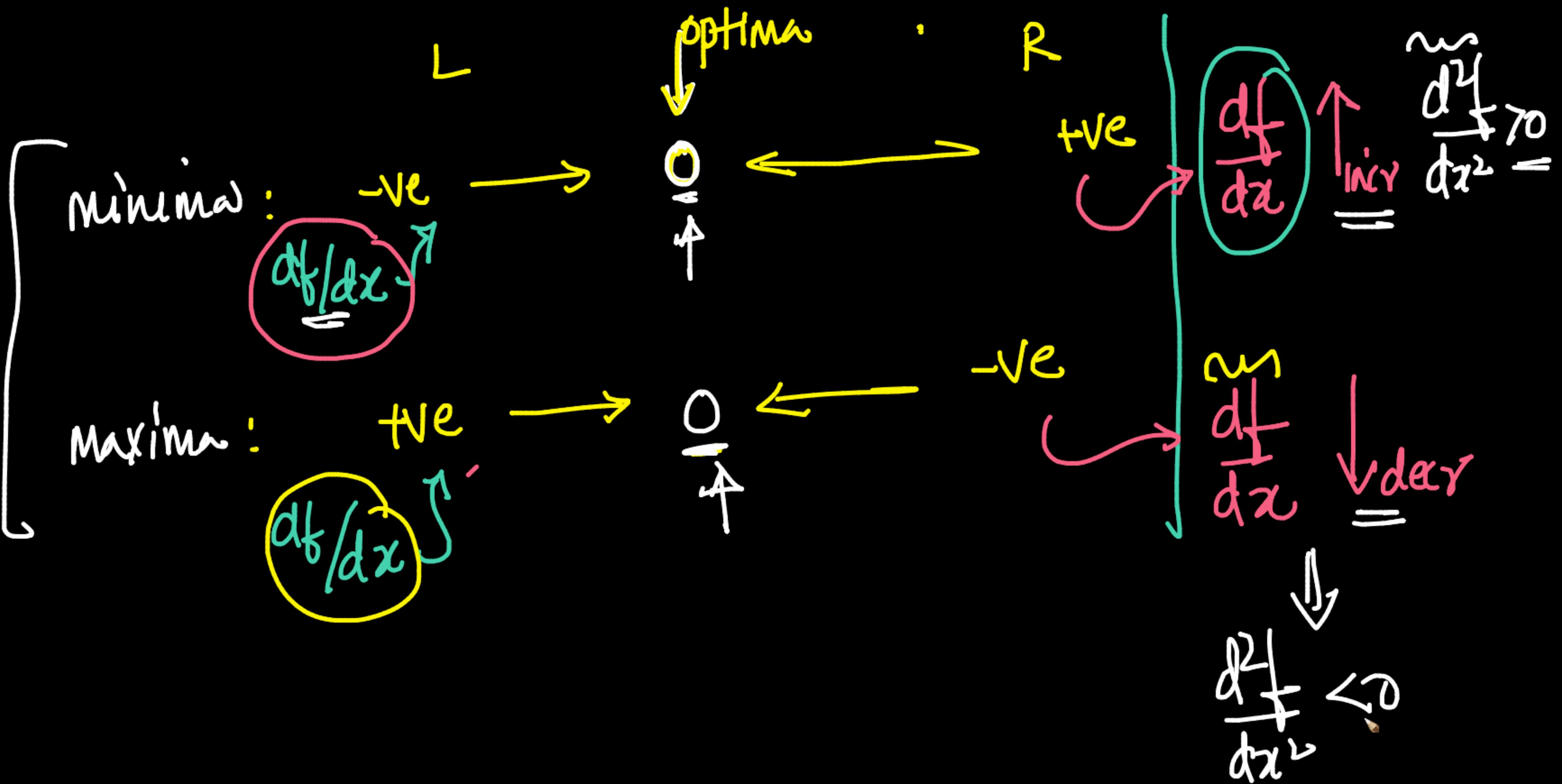


$$\frac{df}{dx} \Big|_{x=x_1} = 0$$

then

optima
Maxima or Minima
@ x_1
or saddle point
little later

inflection points
stationary pts



$$f(x) = x^2$$

$\frac{df}{dx} = 0$

$\frac{d}{dx} x^2 = 2x = 0$

$x=0$

optim ω

Eqn

$g(x)$

Minima:

$\frac{d}{dx} \frac{df}{dx} = \frac{d^2 f}{dx^2}$ is +ve

Maxima:

$\frac{d}{dx} \frac{df}{dx} = \frac{d^2 f}{dx^2}$ is -ve

$$f(x) = x^2 - 2x + 6$$

$$\frac{df}{dx} = 2x - 2$$

$$\frac{d^2f}{dx^2} = 2$$

$\frac{d^2f}{dx^2}|_{x_1}$ is -ve

Minima @ x_1

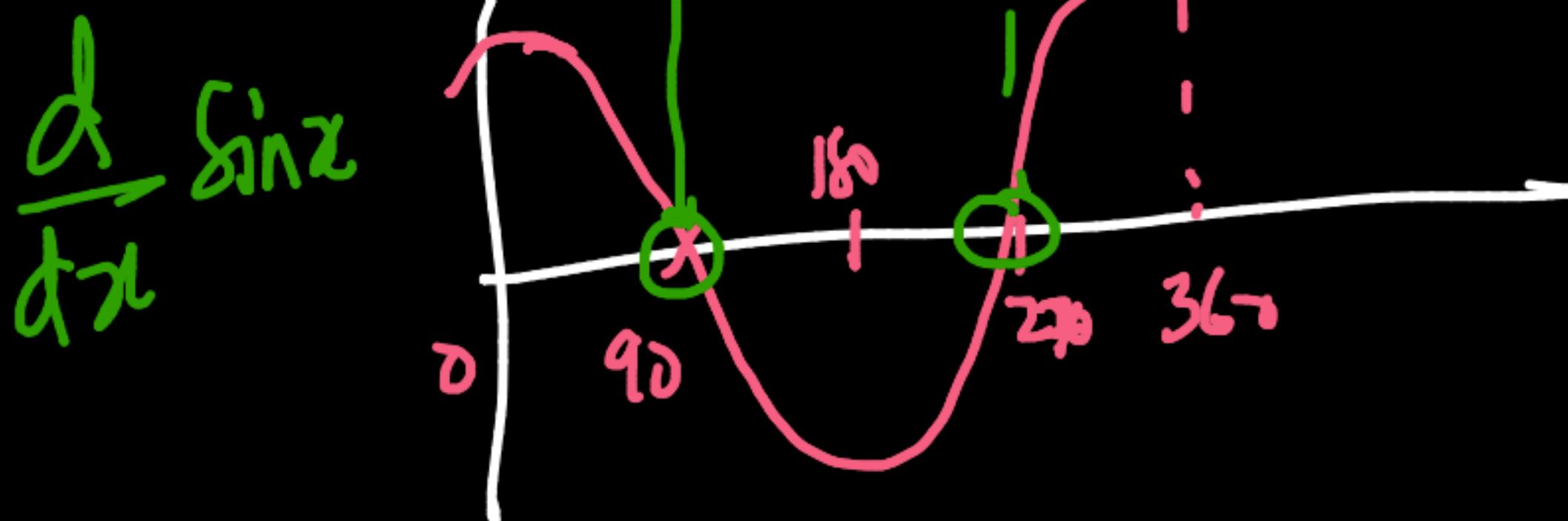
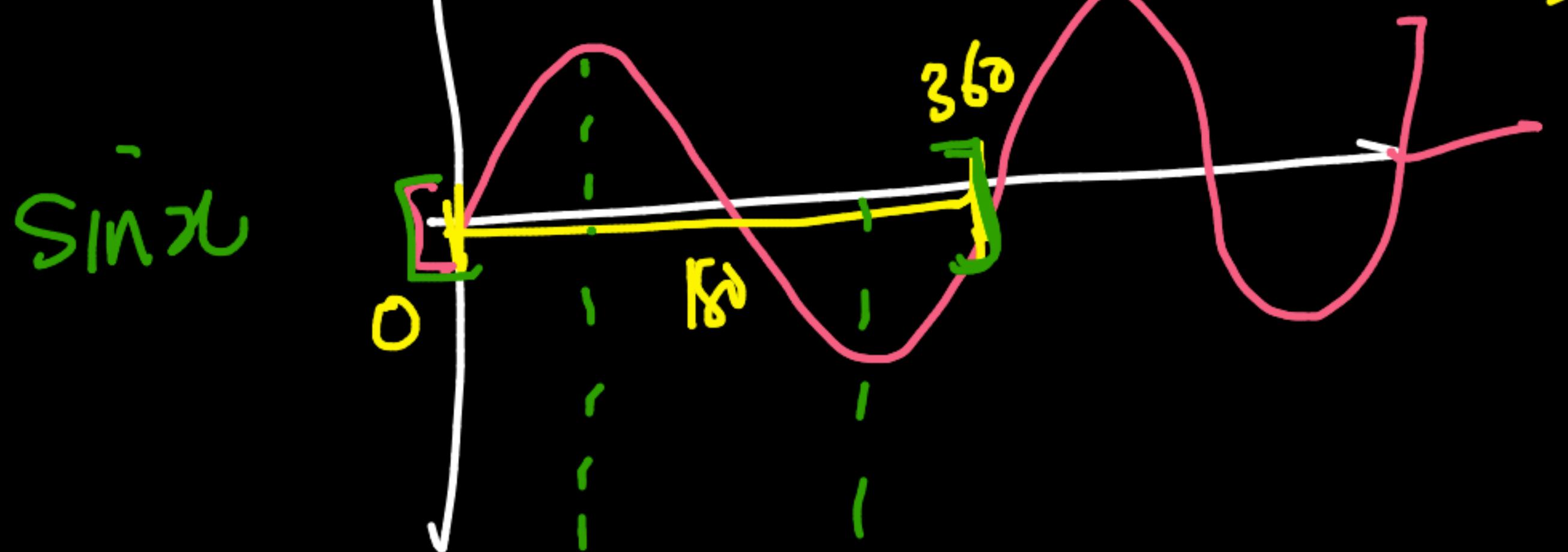
$$\left. \frac{df}{dx} \right|_{x_1} = 0$$

$$\left. \frac{d^2f}{dx^2} \right|_{x_1} \text{ is +ve}$$

Maxima @ x_1

$$\left. \frac{df}{dx} \right|_{x_1} = 0$$

$$\frac{d \sin(x)}{dx} = \cos(x)$$



∞ -many
minimas &
Maximas.

(e.g)

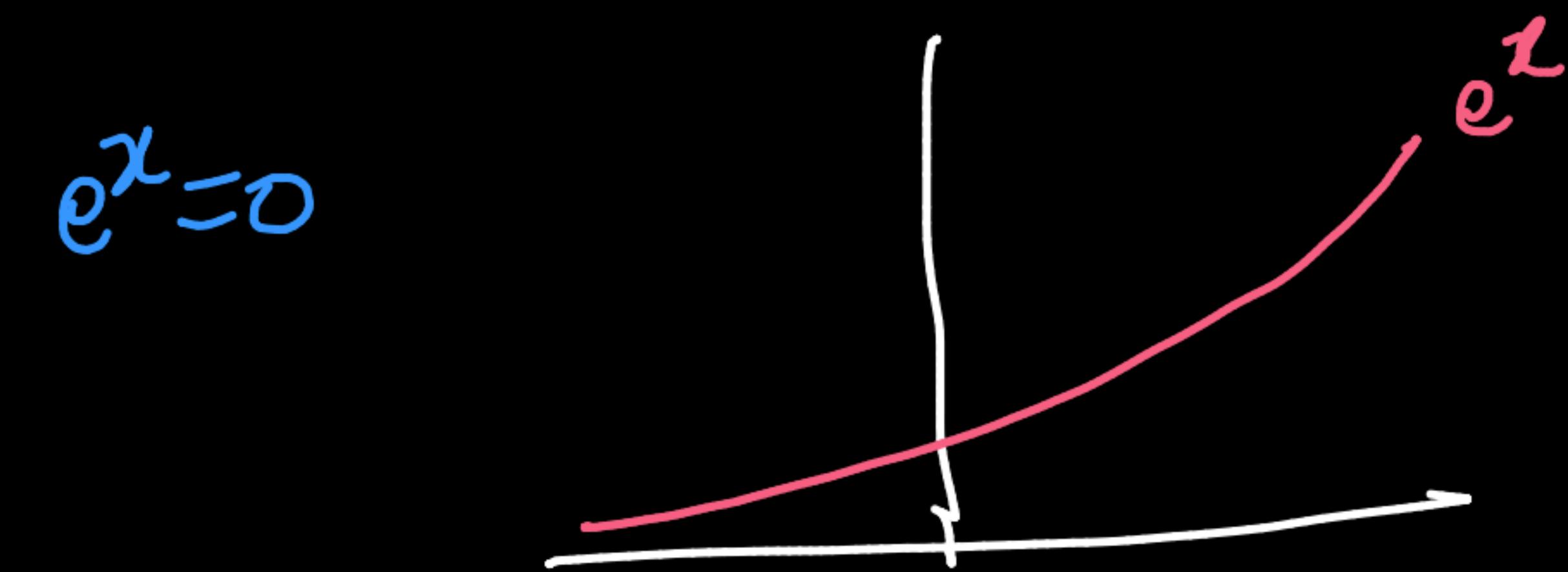
$$\log\left(\frac{1+\exp(x)}{u}\right) = f(x)$$

(minima & maxima)

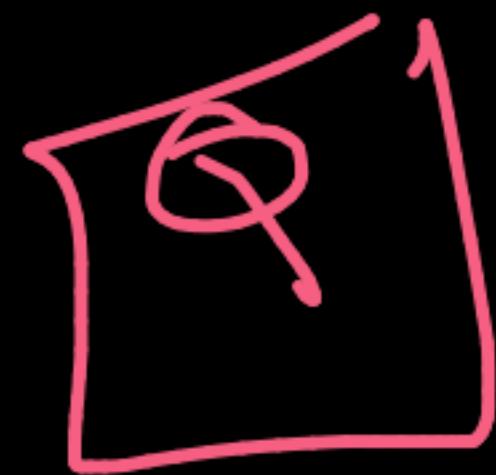
$$\frac{df}{dx} = \frac{1}{1+\exp(x)} \cdot \exp(x) = 0$$

$$\left\{ \begin{array}{l} \exp(x) = 0 \\ 1 + \exp(x) \end{array} \right.$$

$$\left\{ \begin{array}{l} \exp(x) = 0 \\ 1 + \exp(x) \end{array} \right. \quad \leftarrow \text{optimas}$$



$e^x \rightarrow 0$ as $x \rightarrow -\infty$



$$f(x) = \underbrace{(10 - (2x+3))^2}_{\text{optima}}$$

$$\frac{df}{dx} = 2(10 - (2x+3)) \cdot (-2)$$

$$= \boxed{\cancel{2}(10 - (2x+3)) = 0}$$

$$2x+3 = 0 \Rightarrow x = -\frac{3}{2}$$

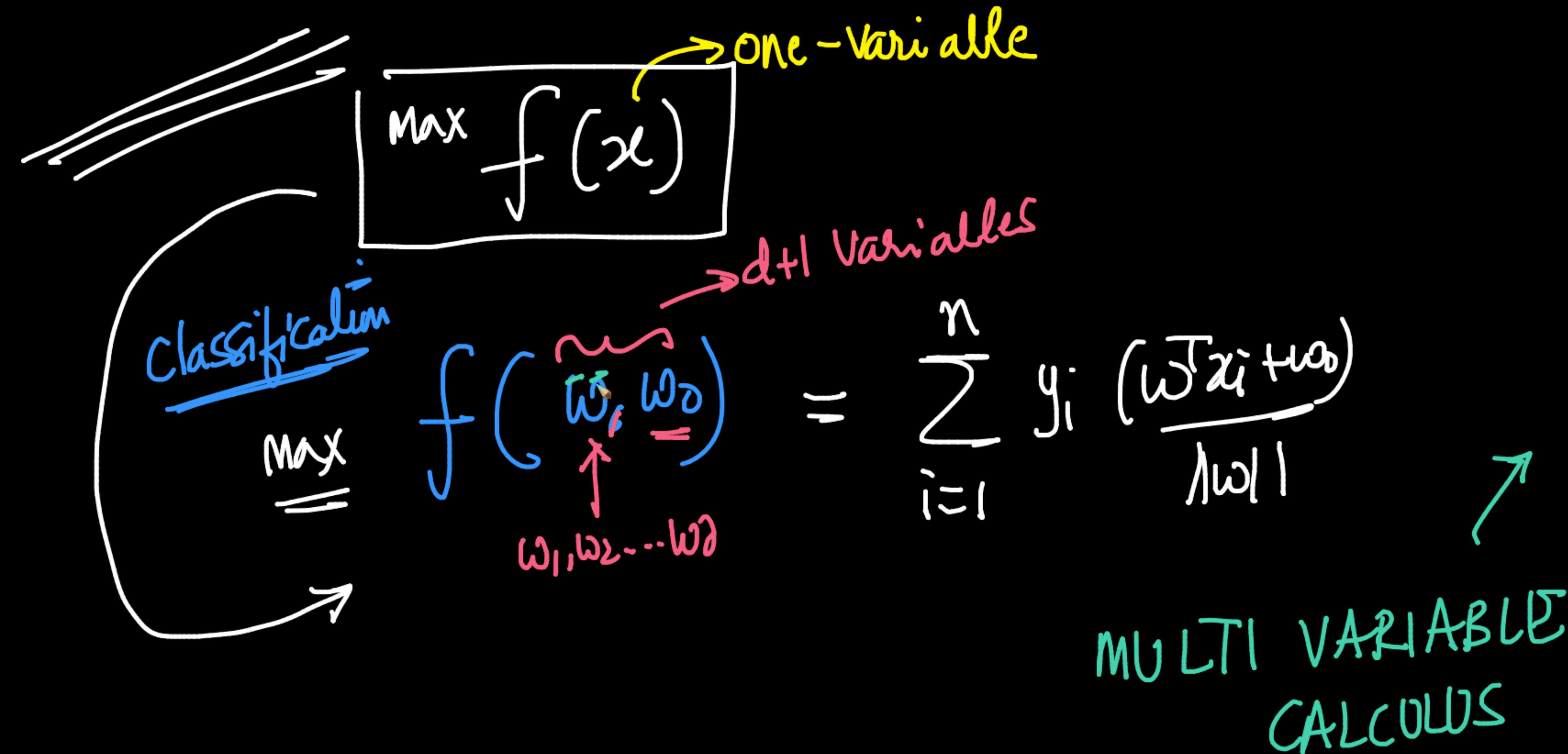
(one)

$$\frac{d}{dx} \left(\frac{df}{dx} \right) = \frac{d}{dx} \left(-4(10 - (2x+3)) \right)$$

$$= \underbrace{6+8+0}_{=8} > 0$$

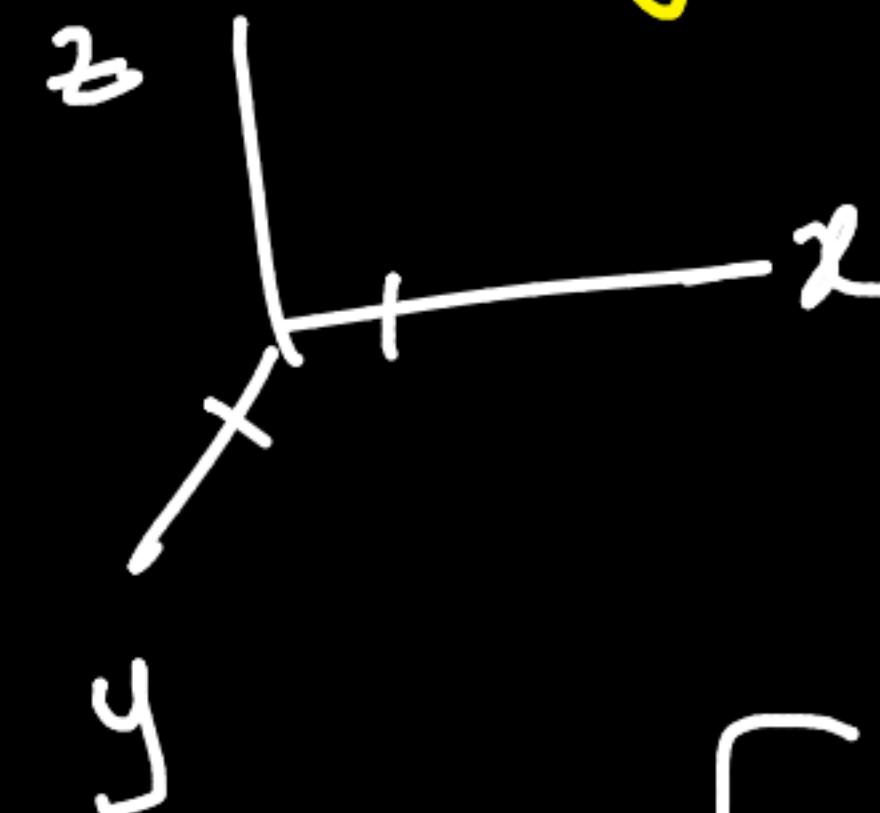
minima @ $x = 7/2$

Let $\frac{d^2f}{dx^2} = 8x \Big|_{x=7/2} = \frac{8 \times 7}{2}$



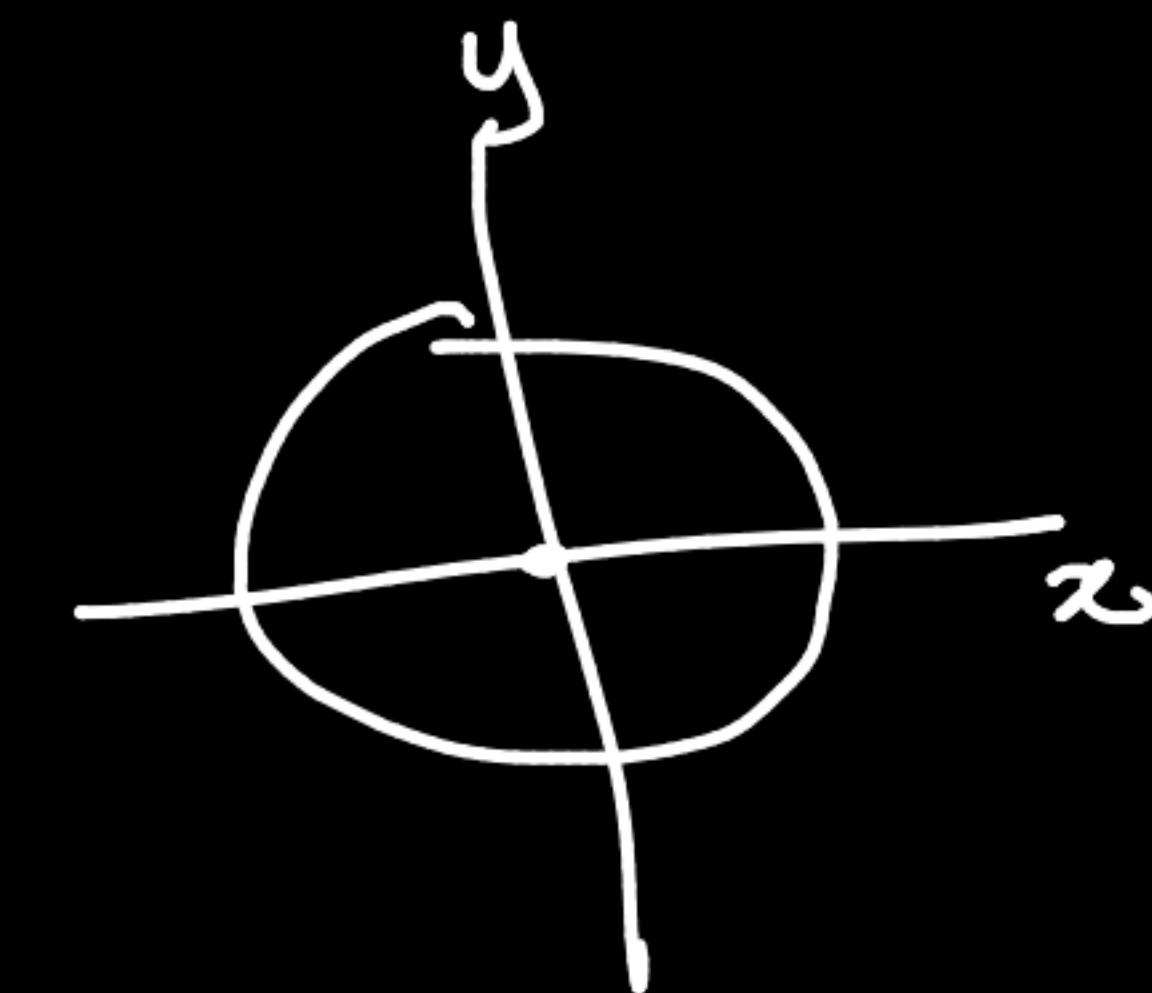
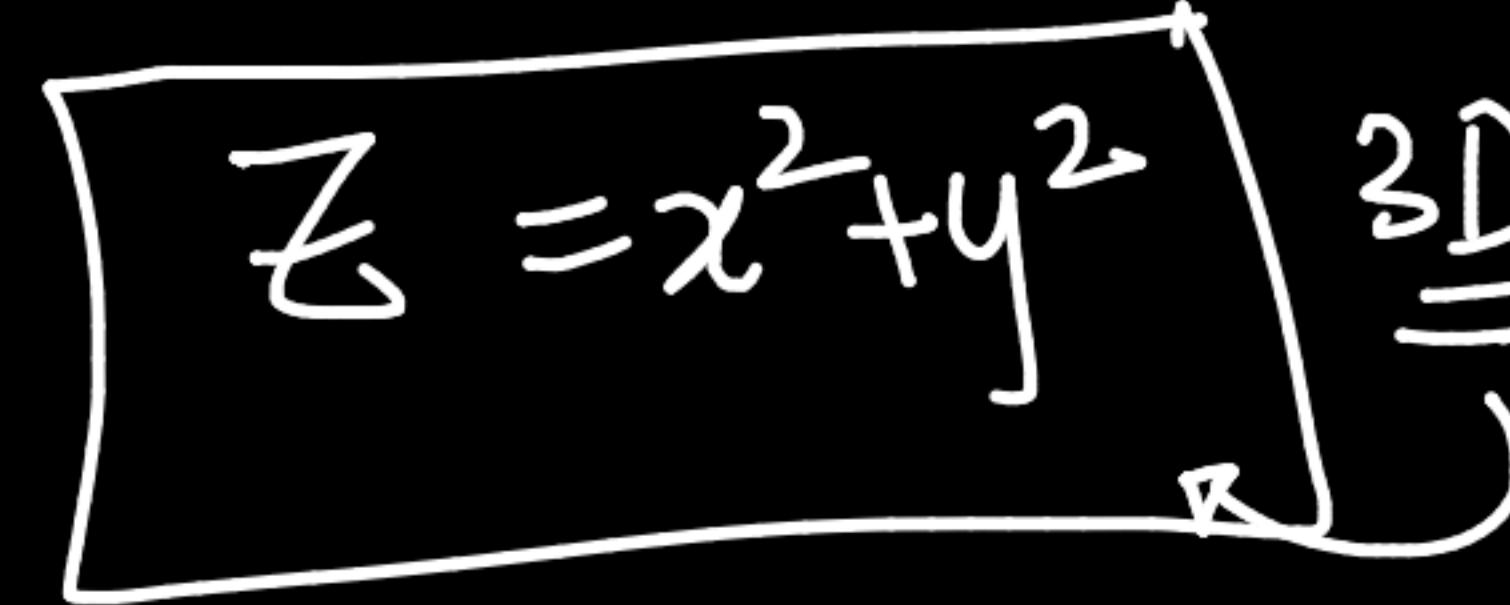
2D

$$\boxed{Z = f(x,y) = x^2 + y^2}$$

3D

Circle!
2D

$$\boxed{x^2 + y^2 = r^2}$$



*dependent
on x & y*

$$z = f(x, y) = x^2 + y^2$$

*z & y are
-indp of
one another*

$$\frac{df}{dx}$$

$$\frac{df}{dy}$$

Notations:

Del $\nabla f = \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{bmatrix} \xrightarrow{\text{doh}} \begin{array}{l} \text{2D-Vector} \\ \text{partial -der} \end{array}$

Def

$$\nabla f = \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{bmatrix}$$

$$f(w_0, w_1, w_2, \dots, w_d)$$

d+1-var

$$\nabla f = \begin{bmatrix} \frac{\partial f}{\partial w_0} \\ \frac{\partial f}{\partial w_1} \\ \vdots \\ \frac{\partial f}{\partial w_d} \end{bmatrix}$$

d+1

minima for $f(x,y) = \overbrace{x^2+y^2}^{\text{wavy line}}$

$$\frac{\partial f}{\partial x} = 2x + 0 = 0$$

y as a constant

$$\frac{\partial f}{\partial y} = 0 + 2y$$

x as constant

One-way!



MVC

@ optimia:

$$\frac{df}{dx} = 0$$

@ optimia:

$$\begin{cases} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{cases} =$$

$$\begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$f(x) = x^2 + y^2$$

ignoring y

$$\begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{bmatrix} = \begin{bmatrix} 2x \\ 2y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

ignoring x

$$\Rightarrow x, y = (0, 0)$$

↑
optimization

Geom:-

✓ { minima → each axis
visualize → hide on axis

Notation:

$$[\underline{x}_1 \quad \underline{x}_2]^T = \underline{x}$$

$$Z = \underbrace{x_1^2 + x_2^2}_{\text{(let)}} \quad (\text{let})$$

$$\nabla Z = \begin{bmatrix} \frac{\partial Z}{\partial x_1} \\ \frac{\partial Z}{\partial x_2} \end{bmatrix}$$

$$f(w_0, w_1, \dots, w_d)$$

$$\nabla_{\underline{w_0 \dots w_d}} f = \nabla_{\underline{\underline{w_i}}} f = \left[\begin{array}{c} \frac{\partial f}{\partial w_0} \\ \frac{\partial f}{\partial w_1} \\ \vdots \\ \frac{\partial f}{\partial w_d} \end{array} \right]$$

OPTIMA

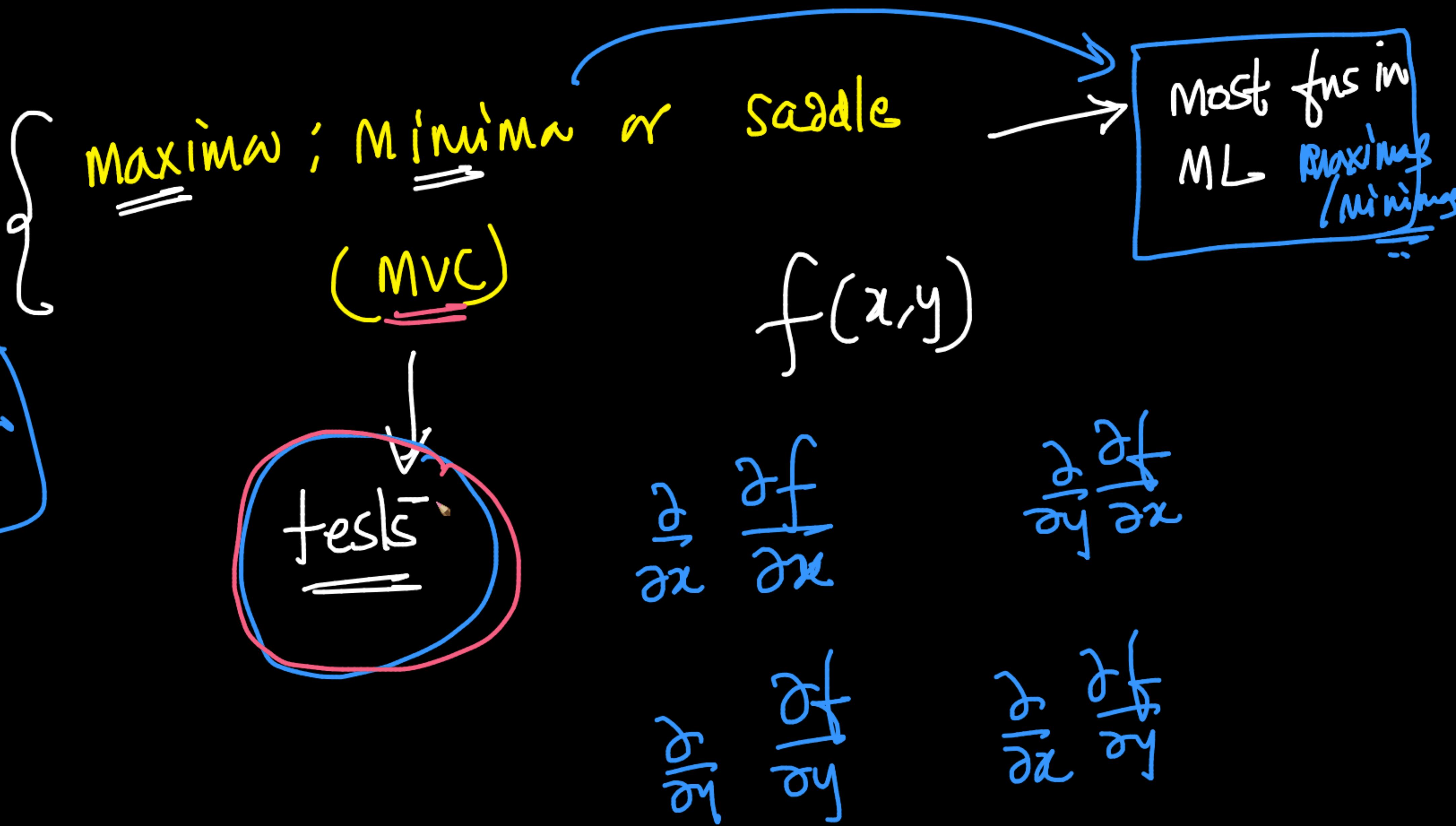
$$\nabla_x z = 0$$

↑
vector

Q1

$$Z = x^2 + y^2 - 2x + 2y + 6$$

$$\nabla Z = \begin{bmatrix} 2x - 2 \\ 2y + 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \begin{cases} x = 1 \\ y = -1 \end{cases}$$



min Ma: $\frac{df}{dx} = 0 \& \frac{d^2f}{dx^2} > 0$

max Ma: $\frac{df}{dx} = 0 \& \frac{d^2f}{dx^2} < 0$

$$\underline{f(x) = x^3}$$

$$\frac{df}{dx} = 3x^2 = 0 \Rightarrow x=0$$

$$\frac{d^2f}{dx^2} = 6x @ x=0$$

$$\boxed{+0}$$

neither $+ve$ nor $-ve$

Exception:
(Saddle point(s))

$$\frac{df}{dx} = 0$$

NOT Maximum

not Minimum

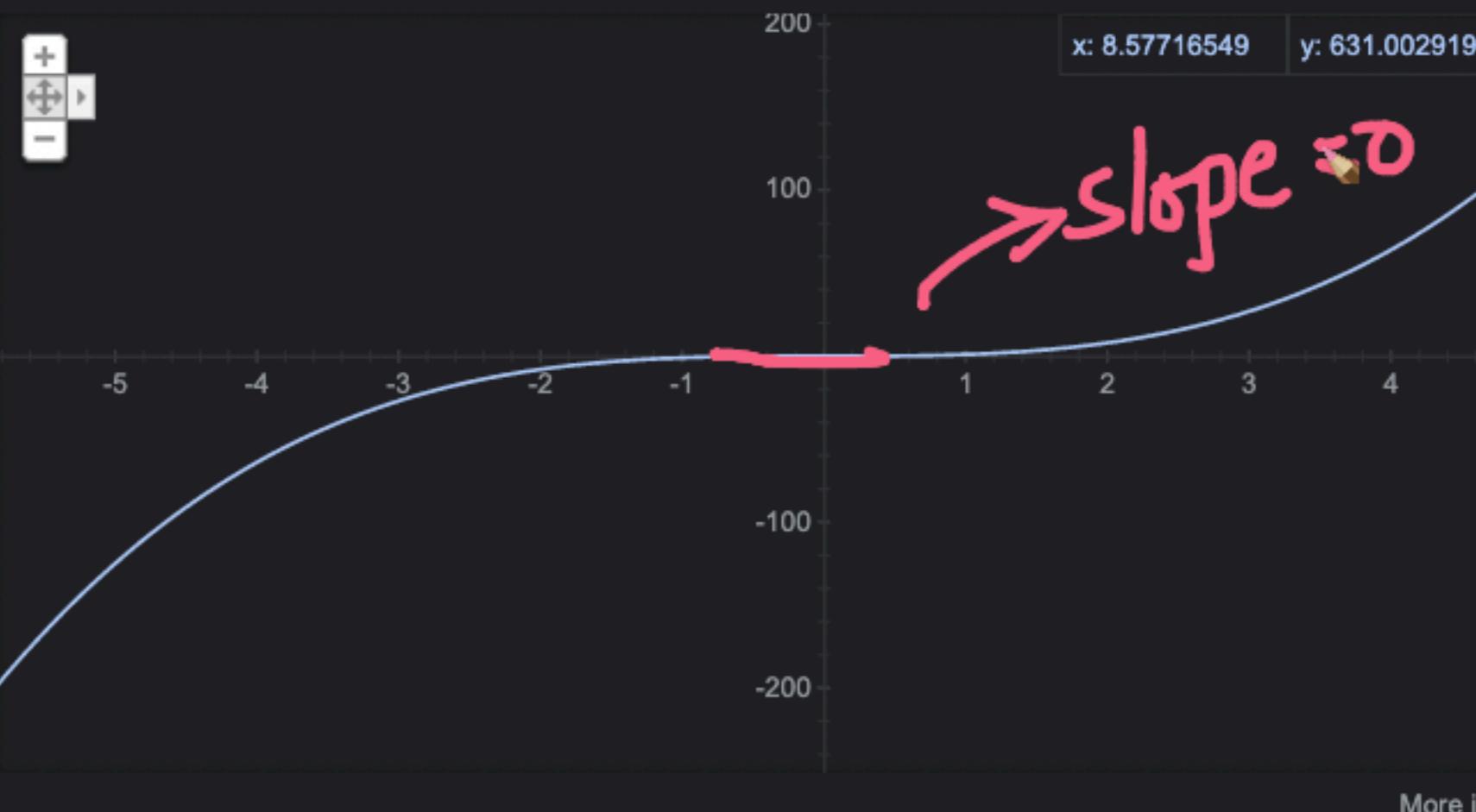
$$\nabla f = \vec{0}$$

All Shopping Images News Maps More

Tools

About 69,80,00,000 results (0.52 seconds)

Graph for x^3



People also ask

How do I plot x 3?

What does X 3 mean on a graph?

What is an x 3 graph called?

How do you plot in math?

Feedback

GradientDescent.ipynb - Colab | Untitled1.ipynb - Colaboratory | plot(x^3) - Google Search +
← → ⌂ google.com/search?q=plot%28x%5E3%29&rlz=1C5CHFA_enIN958IN958&ei=TOtBYtbvIczI2roP9KWuiAs&ved=0ahUKEwjWxYPFpen2AhVMsVYBHfSSC7EQ4dUDCA8&uact=5&oq=plot%28x%5E3%29&gs_lcp=Cgdnd3Mtd2I6EAMyB... ⌂ ⌂ ⌂ Update ⌂

Google

plot(x^3)

All Shopping Images News Maps More Tools

About 69,80,00,000 results (0.52 seconds)

Graph for x^3

x: 0.539342956 y: 0.156889917

More info

People also ask :

- How do I plot x^3 ?
- What does X 3 mean on a graph?
- What is an x^3 graph called?
- How do you plot in math?

Feedback

<https://www.wolframalpha.com/examples/math/>

GradientDescent.ipynb - Colab | Untitled1.ipynb - Colaboratory | plot(x^3) - Google Search +
← → ⌂ google.com/search?q=plot%28x%5E3%29&rlz=1C5CHFA_enIN958IN958&ei=TOtBYtbvIczI2roP9KWuiAs&ved=0ahUKEwjWxYPFpen2AhVMsVYBHfSSC7EQ4dUDCA8&uact=5&oq=plot%28x%5E3%29&gs_lcp=Cgdnd3Mtd2I6EAMyB... ⌂ ⌂ ⌂ Update ⌂

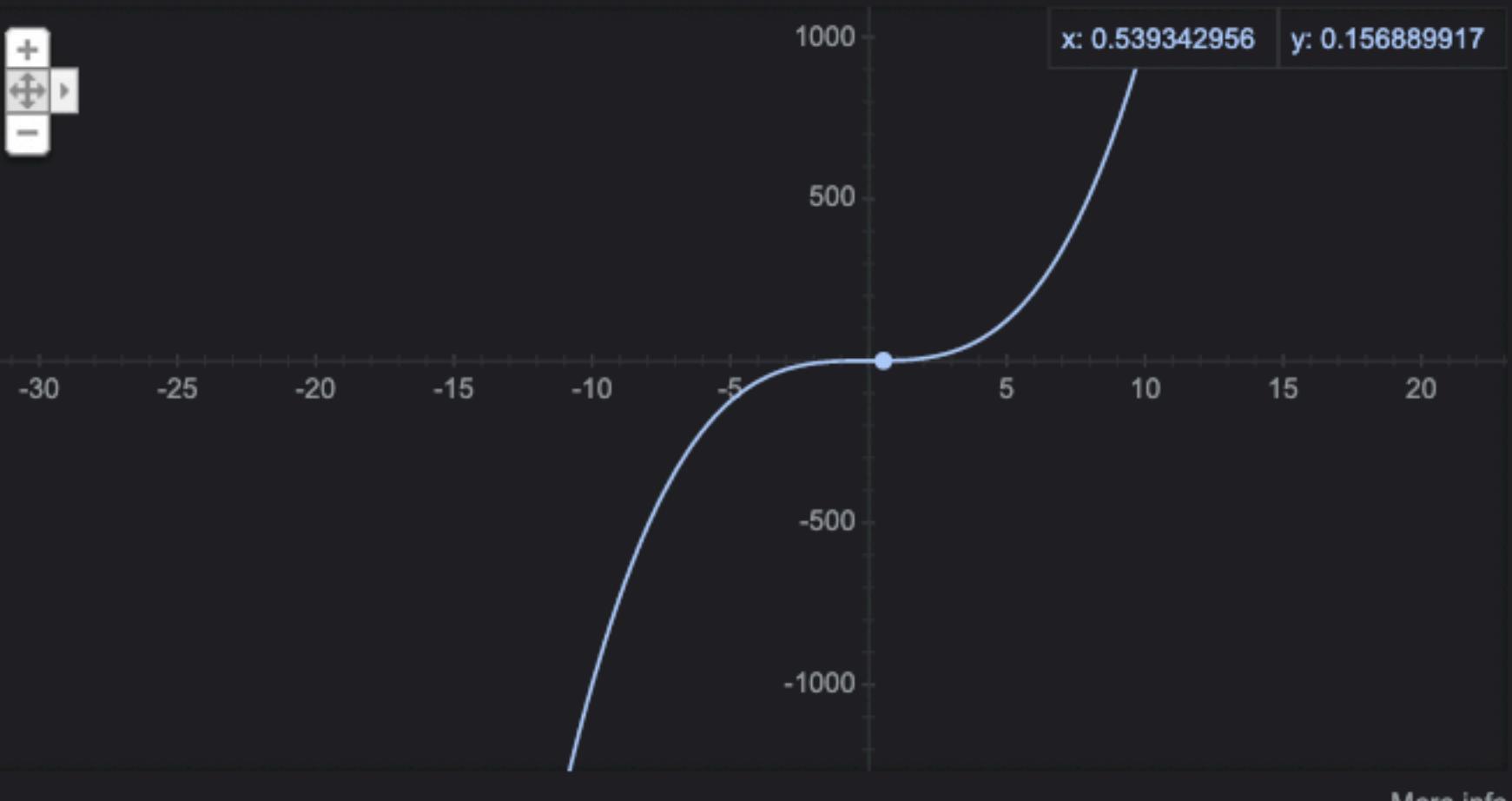
Google

plot(x^3)

All Shopping Images News Maps More Tools

About 69,80,00,000 results (0.52 seconds)

Graph for x^3



x: 0.539342956 y: 0.156889917

More info

People also ask :

- How do I plot x^3 ?
- What does X^3 mean on a graph?
- What is an x^3 graph called?
- How do you plot in math?

Feedback

<https://www.wolframalpha.com/examples/math/>

3D

f(x) =

$$f(x) = x^4$$

$$\frac{df}{dx} = 4x^3 = 0 \quad @ x=0$$

$$\frac{d^2f}{dx^2} = 12x^2 \quad @ x=0 = \boxed{0}$$

+ve ↗
→ -ve ↙

mimima

GradientDescent.ipynb - Colab | Untitled1.ipynb - Colaboratory | plot(x^4) - Google Search +

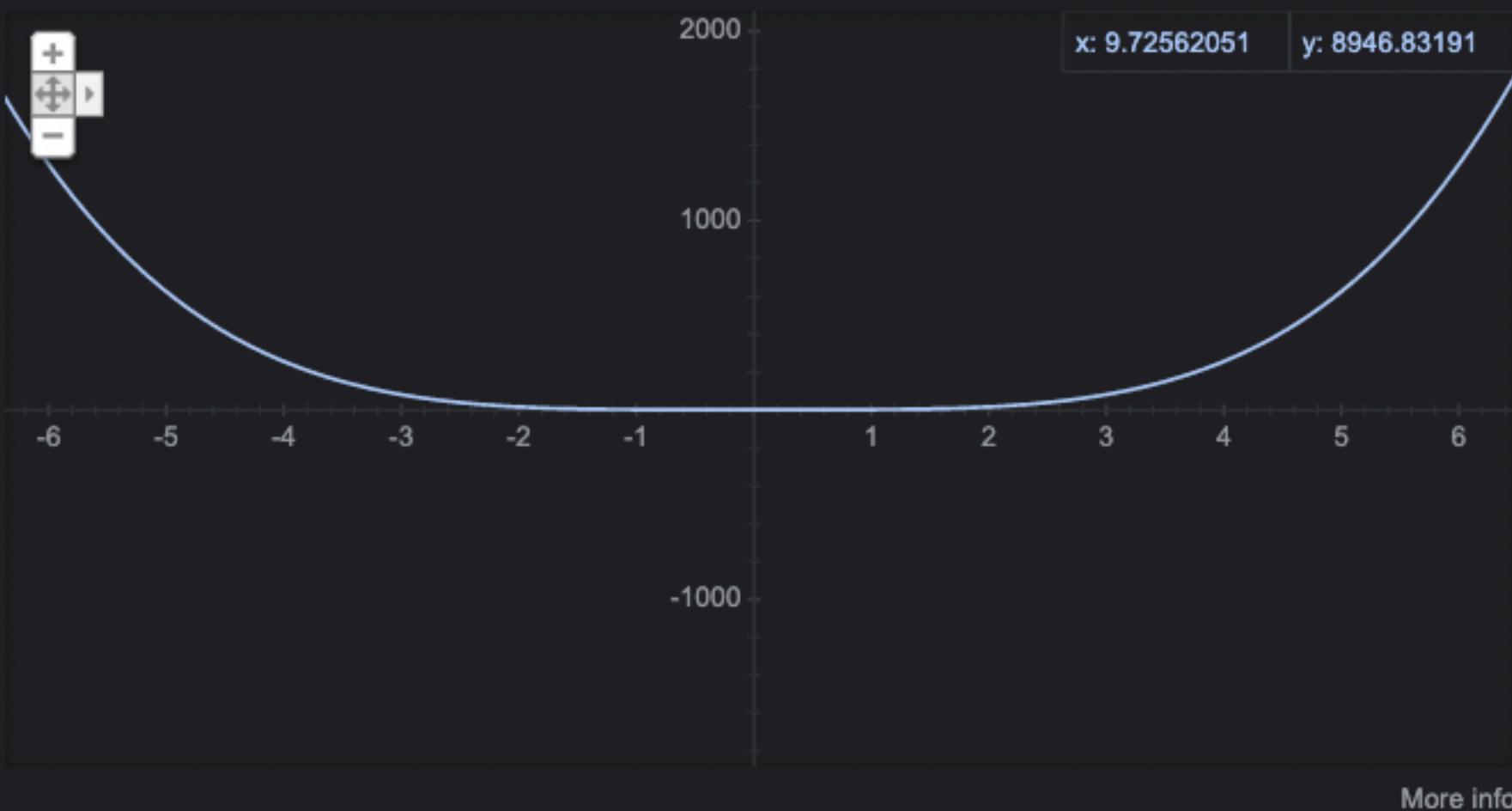
← → ⌂ google.com/search?q=plot%28x%5E4%29&rlz=1C5CHFA_enIN958IN958&ei=Zu5BYoXME6ixmAUs5igAg&ved=0ahUKEwiFI8O_qOn2AhWoGKYKHe4ZBiQQ4dUDCA8&uact=5&oq=plot%28x%5E4%29&gs_lcp=Cgdnd3Mtd2I6EAMy... Update :

Google plot(x^4)

All Shopping Images Maps News More Tools

About 6,02,00,00,000 results (0.54 seconds)

Graph for x^4



<https://www.mathway.com> › popular-problems › Algebra

Graph $x=4$ | Mathway

Since $x=4$ $x = 4$ is a vertical line, there is no y-intercept and the slope is undefined. Slope:

Undefined. y-intercept: No y-intercept. image of graph.



$$f(x) = x^4$$

$$\frac{\partial f}{\partial x} =$$

People also ask :

How do you plot x^4 ?

Is x^4 horizontal or vertical?

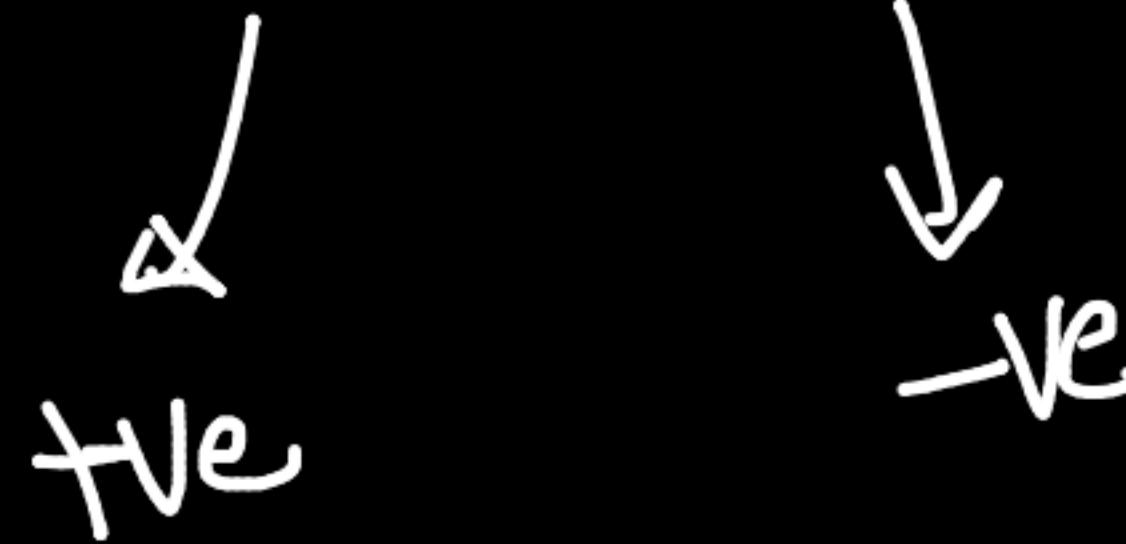
How do you plot in math?



Special - cases:



Minima & Maxima → first non-zero higher
order derivatives



Sabuj

$$f(x) = x^4$$

$$\frac{df}{dx} = 4x^3 = 0$$

$$\frac{d^2f}{dx^2} = 12x^2 \rightarrow 0$$

$$x=0$$

$$\frac{\partial^2 f}{\partial x^3} = 24x \rightarrow 0$$

$$\frac{\partial^4 f}{\partial x^4} = 24 > 0$$

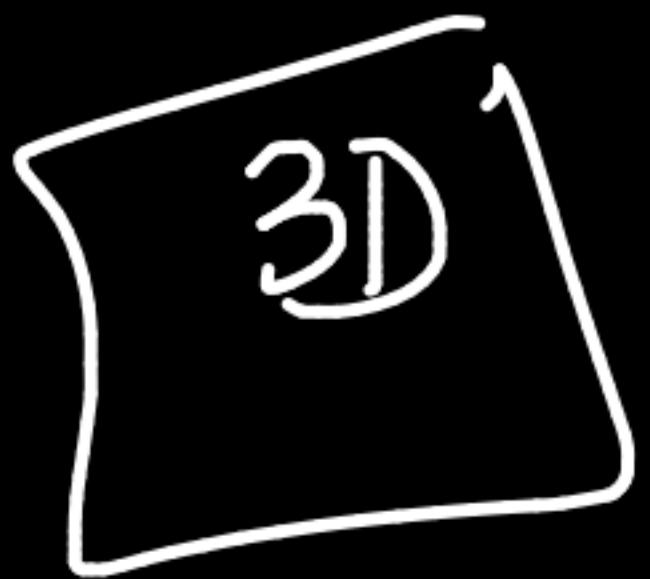


minimum

$$f(x) = x^3$$

→ odd
↳ even

2nd order test ✓
higher order test
=



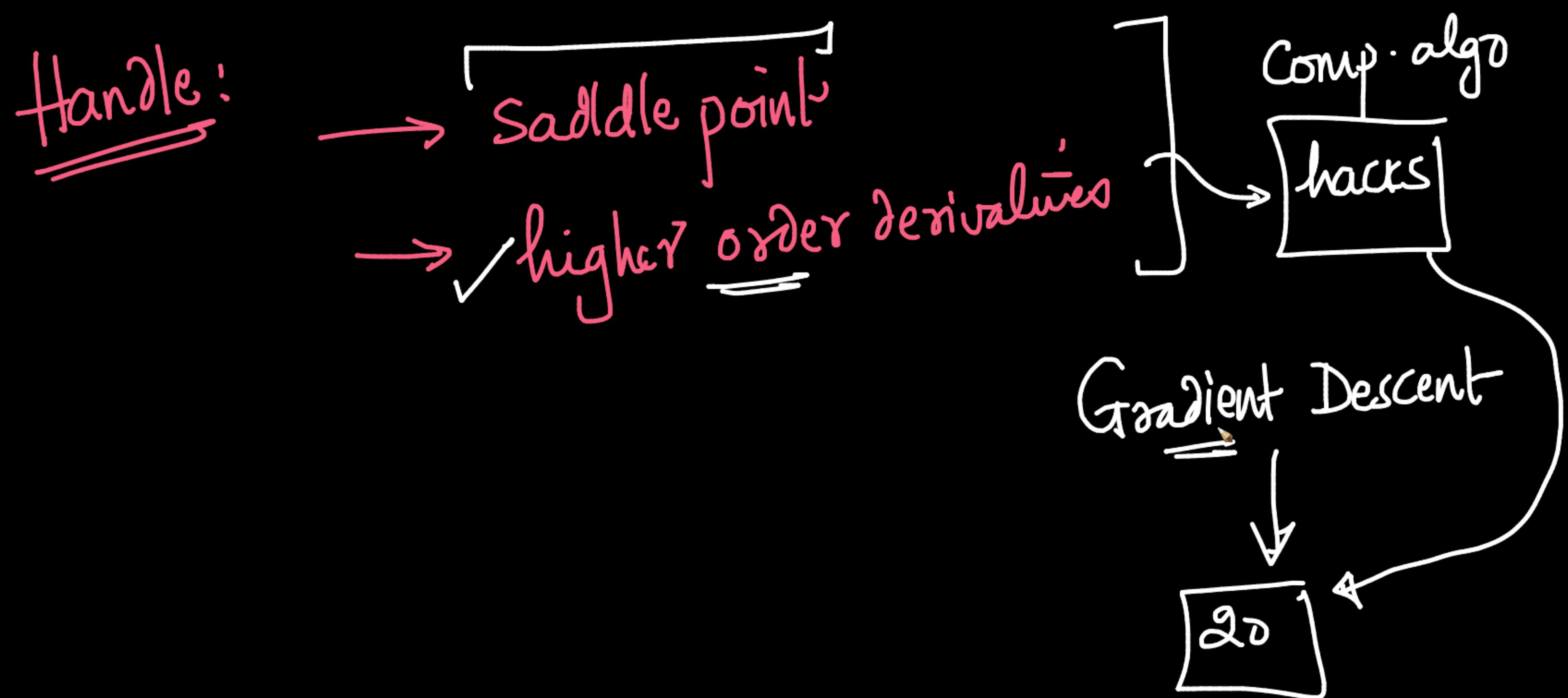
$$f(x,y) = x^2 - y^2$$

↑ ←
minima Maxima

$$\begin{cases} x=0 \\ y=0 \end{cases}$$

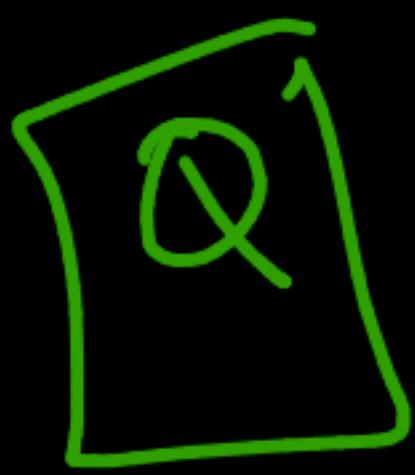
✓

$$\nabla f = \left[\begin{array}{c} \frac{\partial^2}{\partial x^2} \\ \frac{\partial^2}{\partial y^2} \end{array} \right] = \left[\begin{array}{c} 2x \\ -2y \end{array} \right] = \left[\begin{array}{c} 0 \\ 0 \end{array} \right]$$



Gradient Descent

→ Comp-algo to find the Minimas/Maximas
↳ Math → built on it



$$f(x) = x^8 + \cancel{x^7} + x^4 \quad (\text{Optima})$$

$$\frac{df}{dx} = 8x^7 + \cancel{7x^6} + 4x^3 = 0$$

$\log(x)$
 $b_0(x)$

✓ $8x^4 + \cancel{7x^3} + 4 = 0$ } solving this eqn

$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

Gradient Descent

23:11

Higher-order derivative test [edit]

The *higher-order derivative test* or *general derivative test* is able to determine whether a function's critical points are maxima, minima, or points of inflection for a wider variety of functions than the second-order derivative test. As shown below, the second-derivative test is mathematically identical to the special case of $n = 1$ in the higher-order derivative test.

Let f be a real-valued, sufficiently [differentiable function](#) on an interval $I \subset \mathbb{R}$, let $c \in I$, and let $n \geq 1$ be a [natural number](#). Also let all the derivatives of f at c be zero up to and including the n -th derivative, but with the $(n+1)$ th derivative being non-zero:

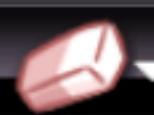
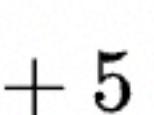
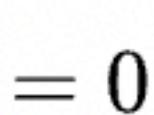
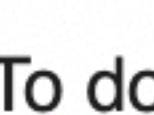
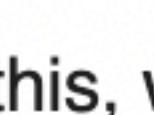
$$f'(c) = \dots = f^{(n)}(c) = 0 \quad \text{and} \quad f^{(n+1)}(c) \neq 0.$$

There are four possibilities, the first two cases where c is an extremum, the second two where c is a (local) saddle point:

- If n is [odd](#) and $f^{(n+1)}(c) < 0$, then c is a local maximum.
- If n is odd and $f^{(n+1)}(c) > 0$, then c is a local minimum.
- If n is [even](#) and $f^{(n+1)}(c) < 0$, then c is a strictly decreasing point of inflection.
- If n is even and $f^{(n+1)}(c) > 0$, then c is a strictly increasing point of inflection.

Since n must be either odd or even, this analytical test classifies any stationary point of f , so long as a nonzero derivative shows up eventually.

Example [edit]

Say, we want                   $x^6 + 5$ at the point $x = 0$. To do this, we

Higher-order derivative test [edit]

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Example [edit]

Say, we want to find the nature of the stationary point of the function $f(x) = x^6 + 5$ at the point $x = 0$. To do this, we

Higher-order derivative test [edit]

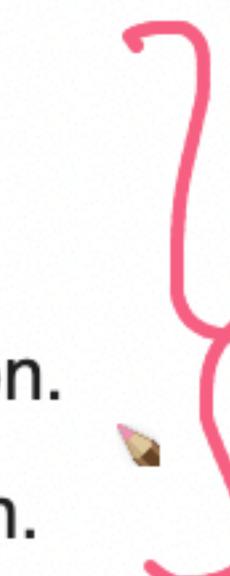
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Since n must be either odd or even, this analytical test classifies any stationary point of f , so long as a nonzero derivative shows up eventually.

Example [edit]

Say, we want $x^6 + 5$ at the point $x = 0$. To do this, we

$x=0$

$f(x) = x^4$

$f' = 3x^3$

$f'' = 9x^2$

$f''' = 18x$

$f'''' = 18$

Higher-order derivative test [edit]

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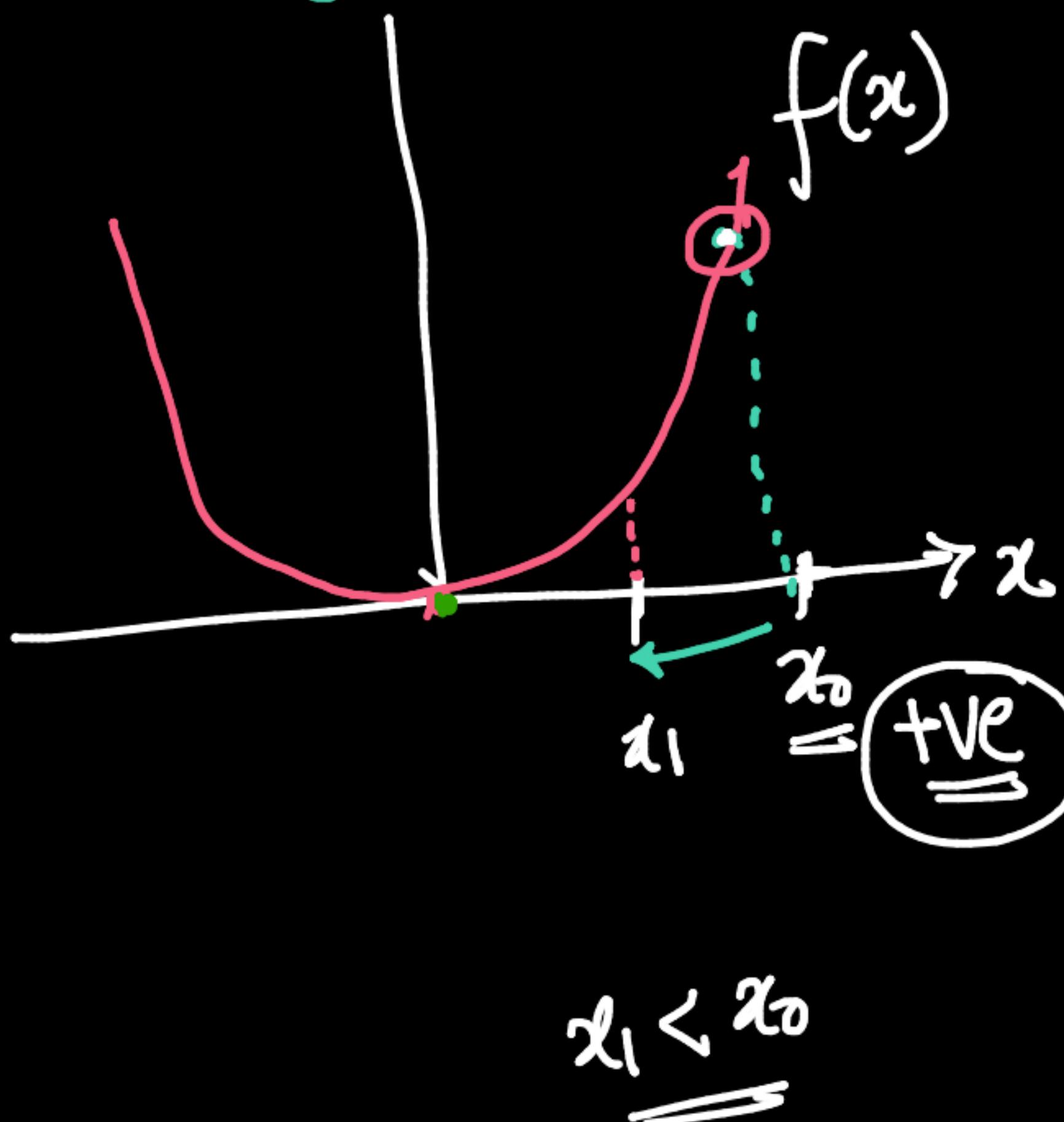
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Since n must be either odd or even, this analytical test classifies any stationary point of f , so long as a nonzero derivative shows up eventually.

Example [edit]

Say, we want $x^6 + 5$ at the point $x = 0$. To do this, we

[minima]



iterative

Gradient Descent

for min

① pick x_0 randomly

$$\frac{df}{dx} \Big|_{x_0} = \text{an } +ve \text{ const. : 0.1}$$

$$x_1 = x_0 + \eta \left(-\frac{\partial f}{\partial x} \right) \Big|_{x=x_0}$$

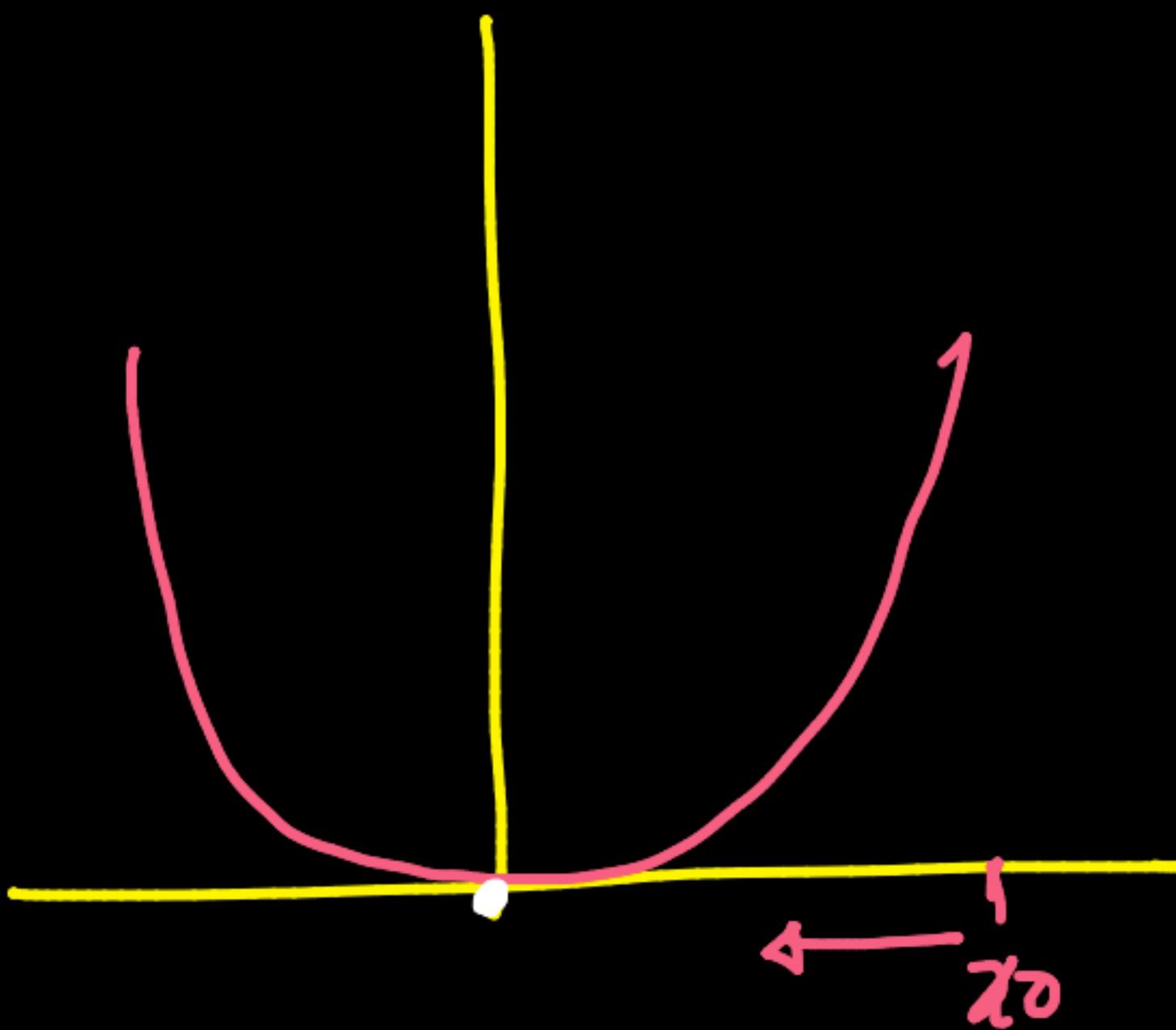
[incr $f(x)$]

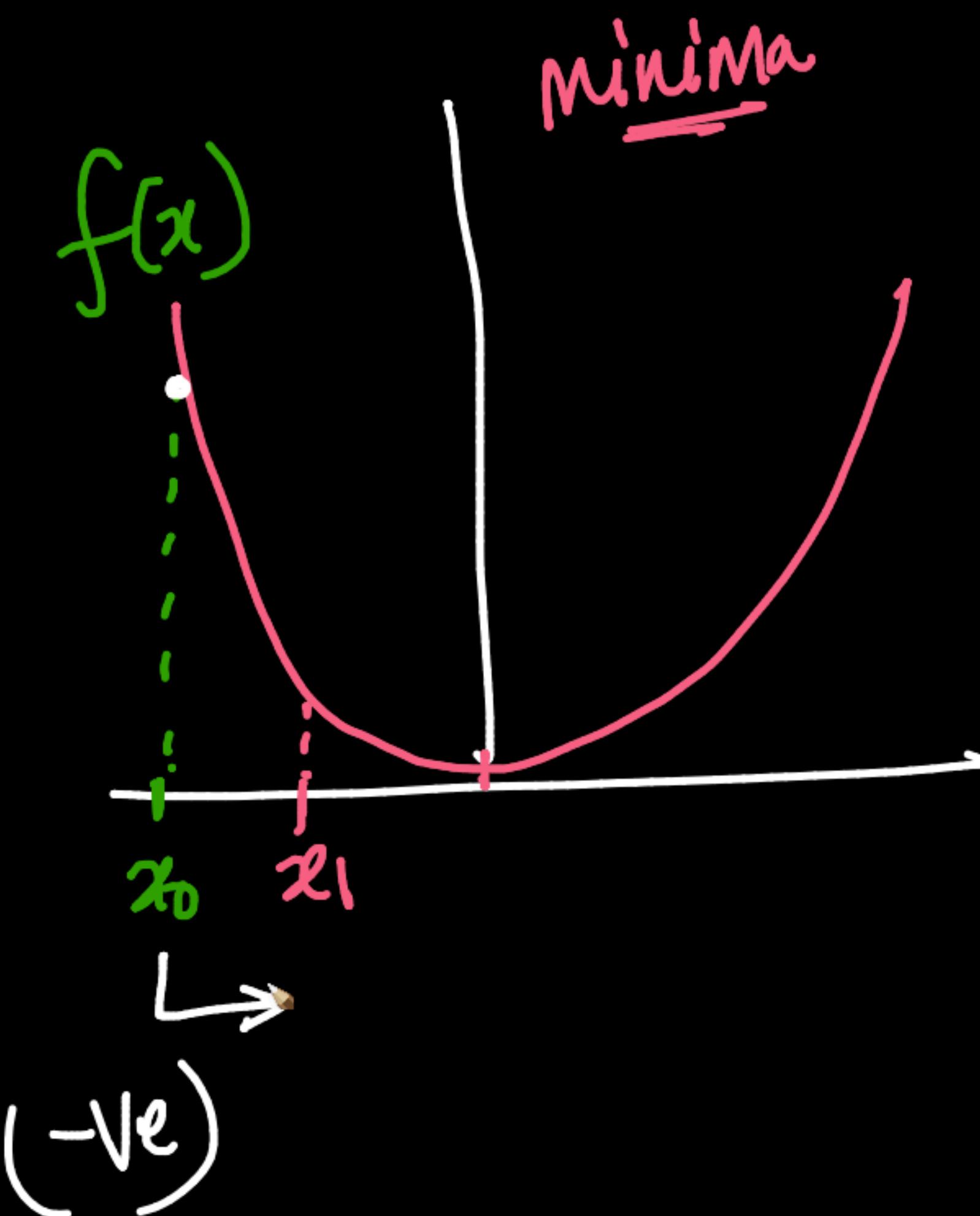
learning rate

Update eqn:

$$x_1 = x_0 + \gamma$$

$$\left(\frac{-\partial f}{\partial x} \right)_{x=x_0}$$



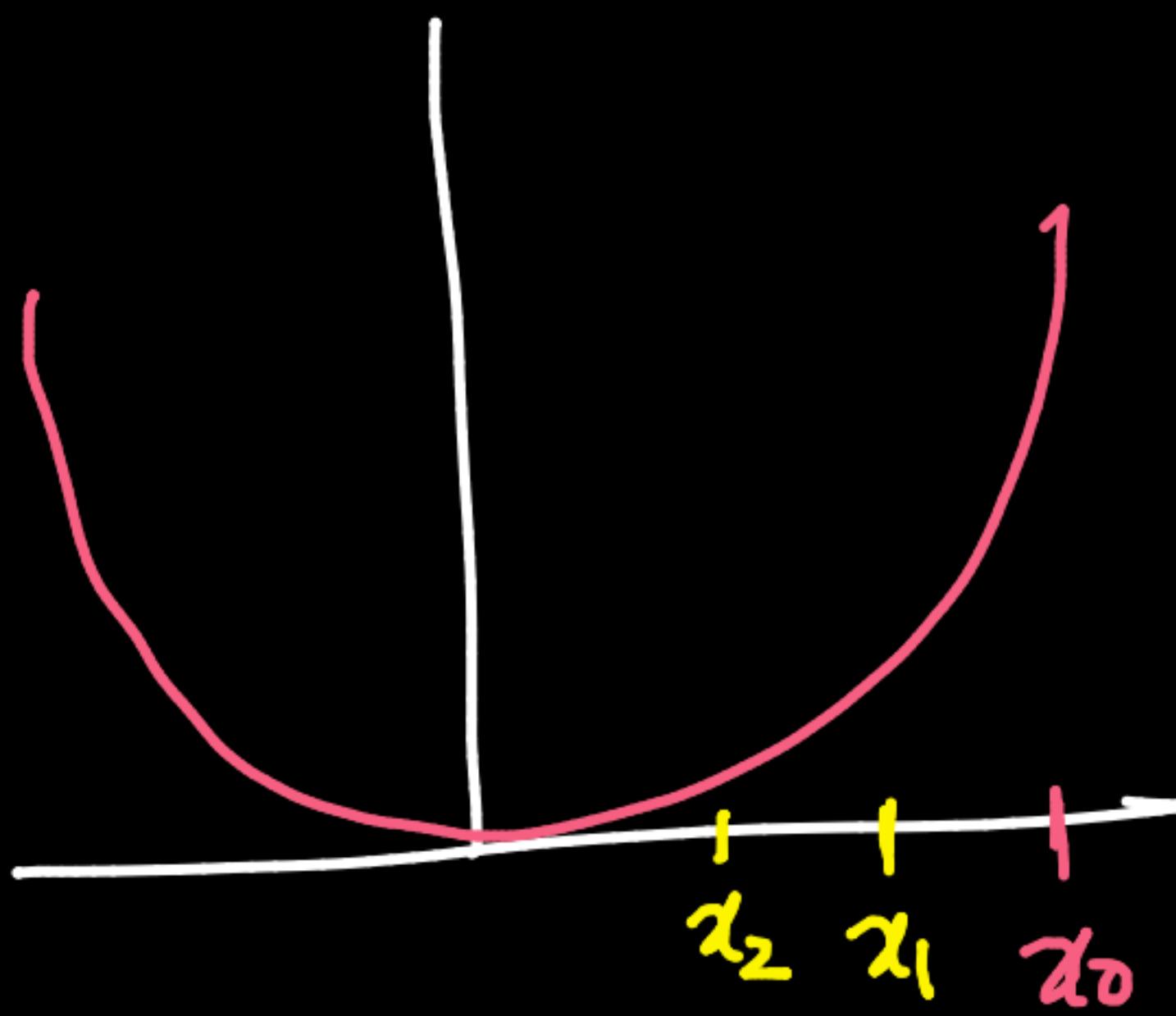


$$\frac{df}{dx} \Big|_{x_0} : \text{decr} : -\text{ve}$$

$$x_1 = x_0 + \eta \left(-\frac{\partial f}{\partial x} \right)_{x=x_0}$$

$\eta > 0$ +ve
Small

iterate



2nd-derivatives ✓

x_0 : randomly

$$x_1 = x_0 + \eta \left(-\frac{\partial f}{\partial x} \right)_{x_0}$$

$$x_2 = x_1 + \eta \left(-\frac{\partial f}{\partial x} \right)_{x_1}$$

K:

$$\frac{\partial f}{\partial x} \Big|_{x_K} \approx 0$$

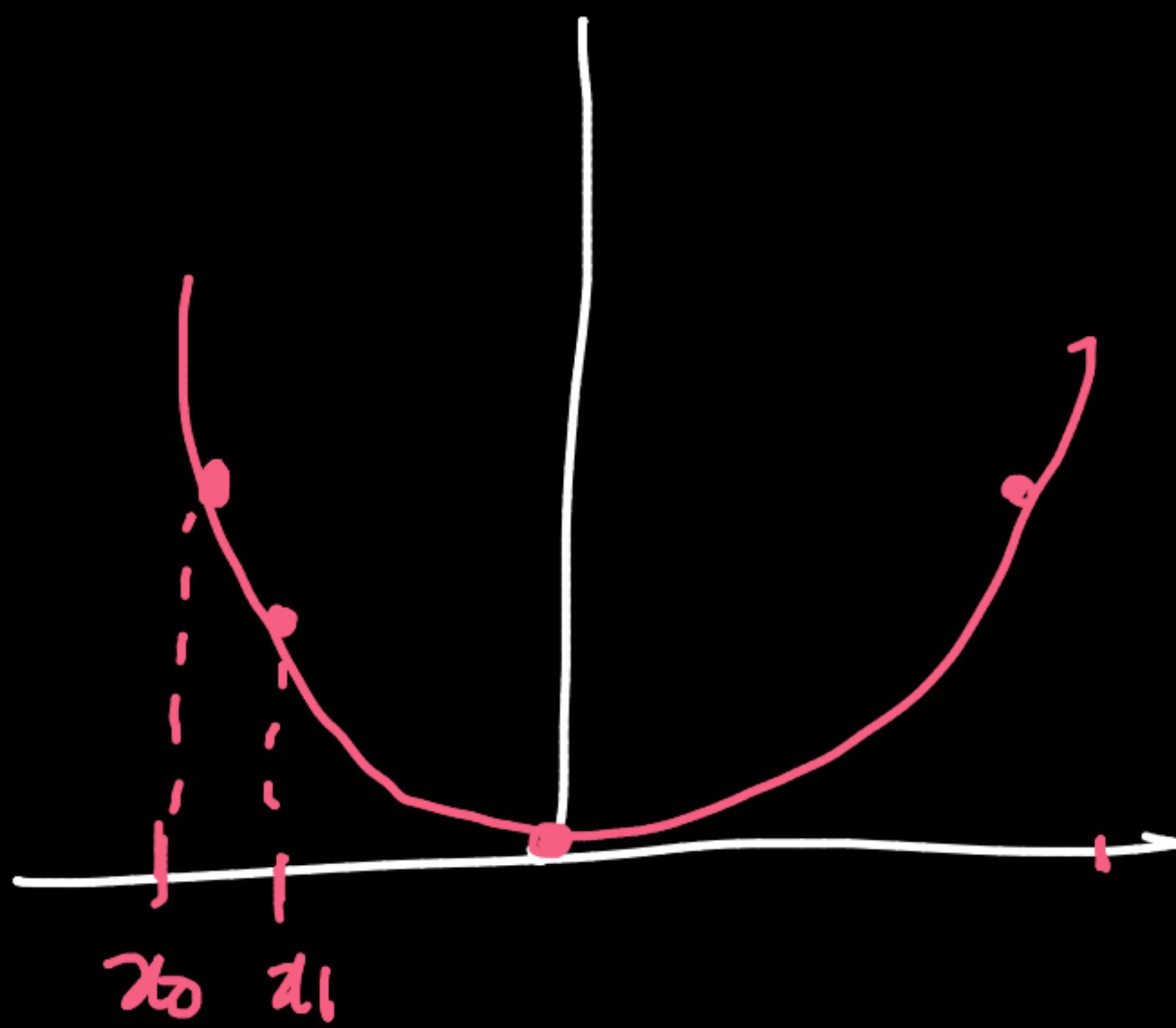
Update Eqn:

$$x_{i+1} = x_i + \eta \left. \frac{-\partial f}{\partial x} \right|_{x_i}$$

$$x_{i+1} = x_i - \eta \left. \frac{\partial f}{\partial x} \right|_{x_i}$$

$$\max_{w, w_0} f(w, w_0) = \min_{w, w_0} -f(w, w_0)$$

{ min. misclassification
rate }



ball-zolling

Gradient \Rightarrow slope
Descent \equiv
↓
down

$f(x)$: (minima) $f'(x) :=$

$\frac{df}{dx} \approx 0$

$\eta = 0.01$

$x_0 = \text{randomly initialize}$

$df/dx = f'(x_0)$

$x_{\text{old}} = x_0$

while $|df/dx - 0| > 0.0001$

$x_{\text{new}} = x_{\text{old}} - \eta f'(x_{\text{old}})$

✓

GradientDescent.ipynb - Colab Untitled1.ipynb - Colaboratory Python Get Random Float Num

colab.research.google.com/drive/1WUN4yW7_uFW2kW8cc03zwKc_Rj1E25f8#scrollTo=wzrMvzPkvlxI

Update

+ Code + Text

✓ RAM Disk

...

...

✓ 0s [1] import random
import math
import numpy

[] #define f(x)
def f(x):
 return math.pow(x, 2)+2*x+10

df_dx; we could have used the limits concepts from prev class too.
def derF(x):
 return 2*x+2

$$x^2 + 2x + 10$$

$$\frac{d}{dx} = 2x + 2 = 0$$

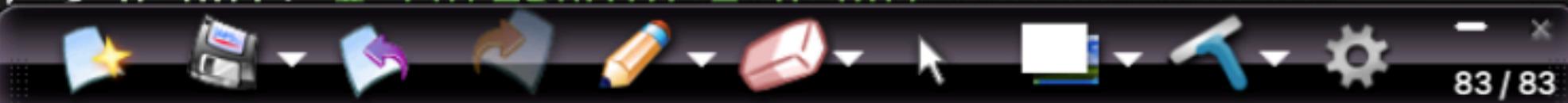
$$x = -1$$

✓ 0s [2] def gradientDescentUnivariate():

 x0 = random.random()
 i=0 # iterations
 eta = 0.01 # learning rate

 xi = x0
 df_dx = derF(xi) # df_dx at x0

 while abs(df_dx - 0.0) > 0.001: # threshold = 0.001



+ Code + Text

/ 1

▶ -0.999285227519035
0.0015883832910332796

72
-0.9993567047671316
0.0014295449619299294

73
-0.9994210342904184
0.0012865904657368699

74
-0.9994789308613765
0.001157931419163205

75
-0.9995310377752389
0.0010421382772469734

-0.999577933997715

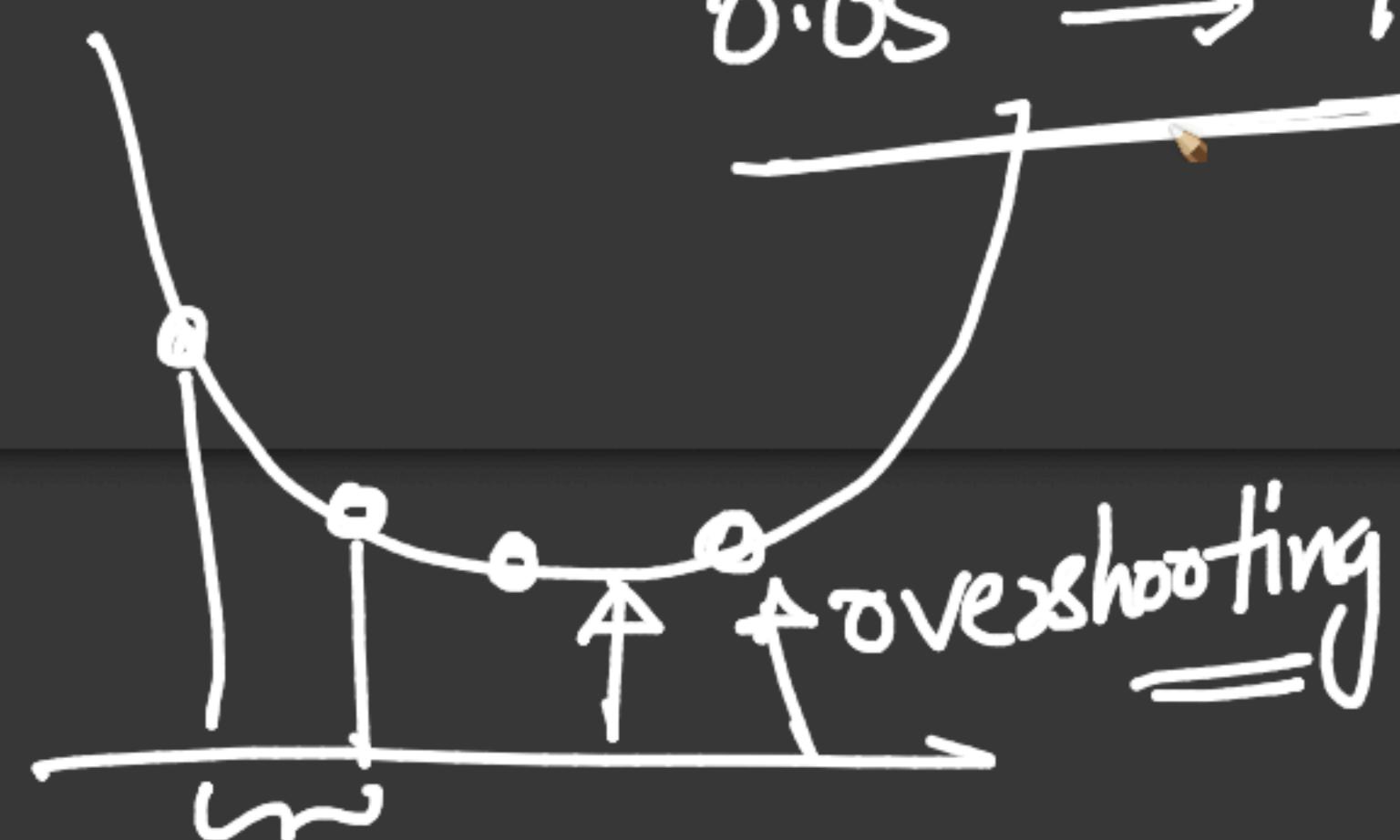
$$x_{i+1} = x_i - \gamma \frac{\partial f}{\partial x}|_{x_i}$$

#itezalins

$$0.01 \rightarrow 377$$

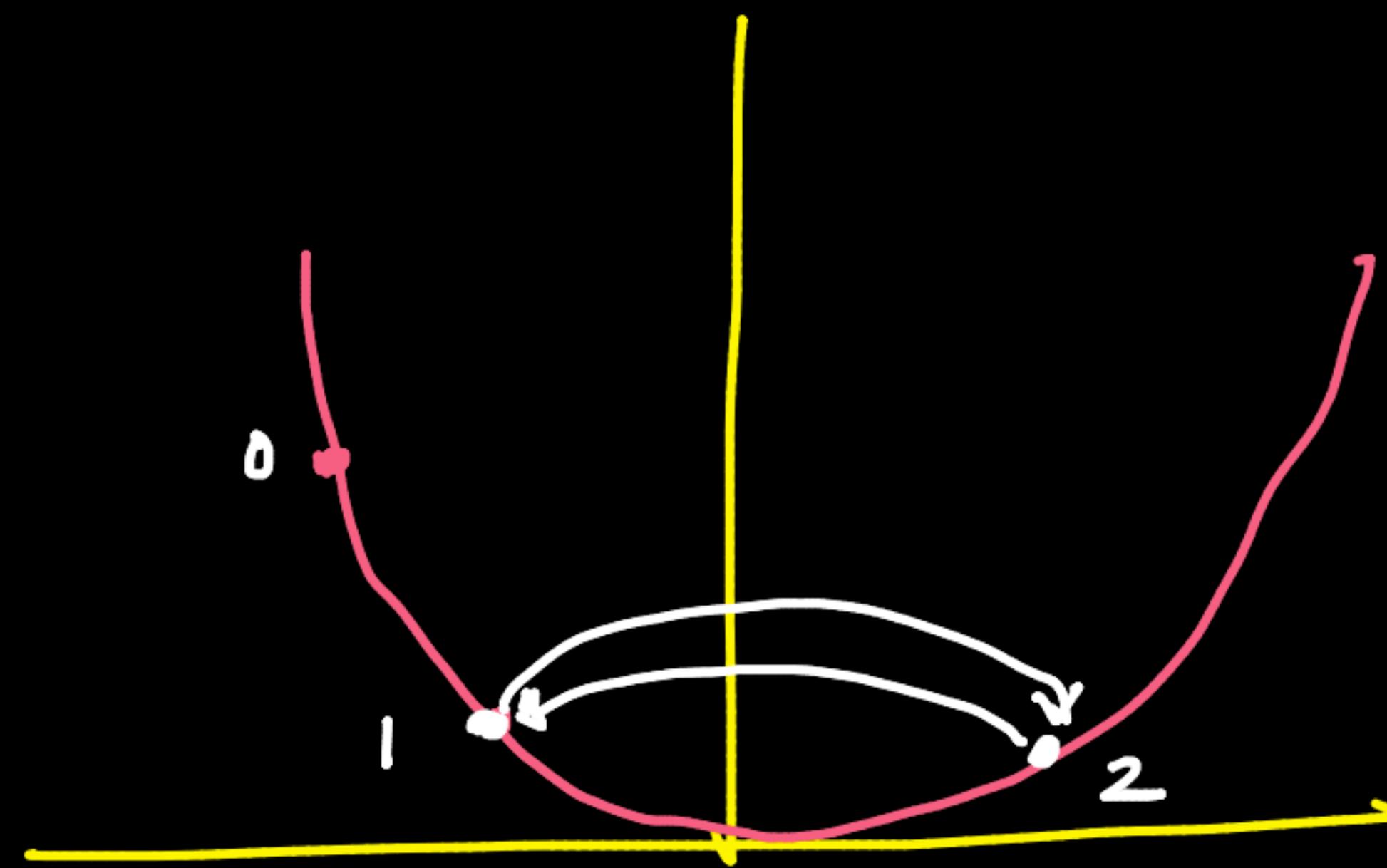
A diagram illustrating a mapping or function. On the left, the text "0.1" is written in red. A red arrow points from this text to a question mark inside a white-outlined circle. To the right of the circle is a white arrow pointing to the right.

0.05 → 75



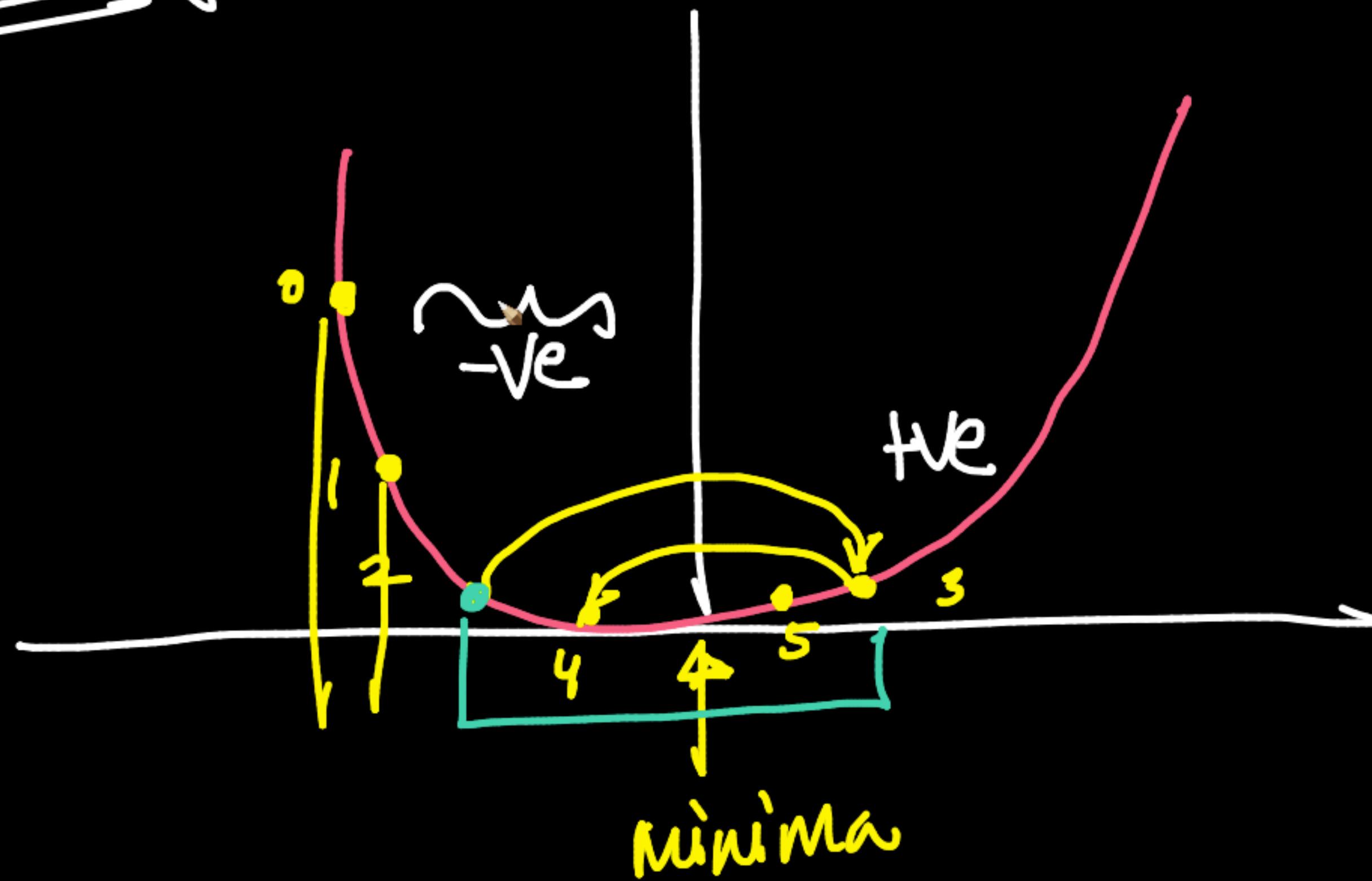
voting

oscillating



boundary cases

overshooting:

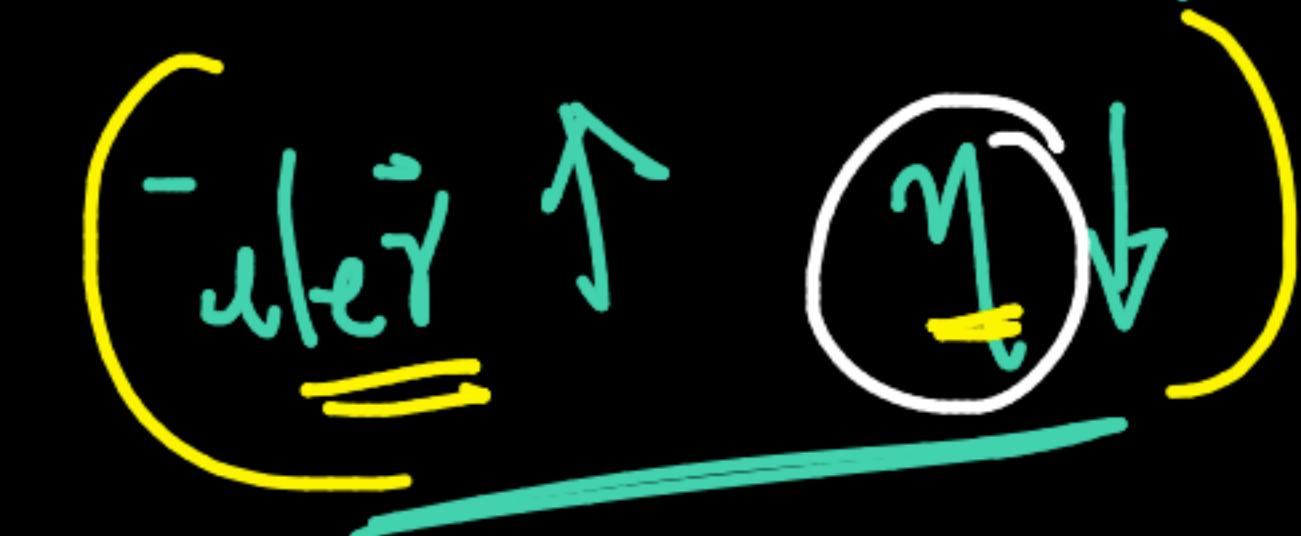


run faster

comp. hack

η : control on

η a function of
iter-number

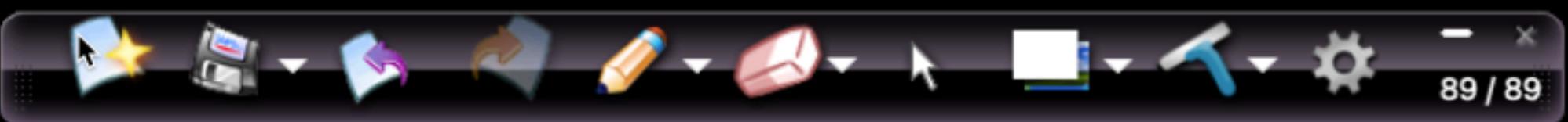


Next-class:

→ GD in MVC

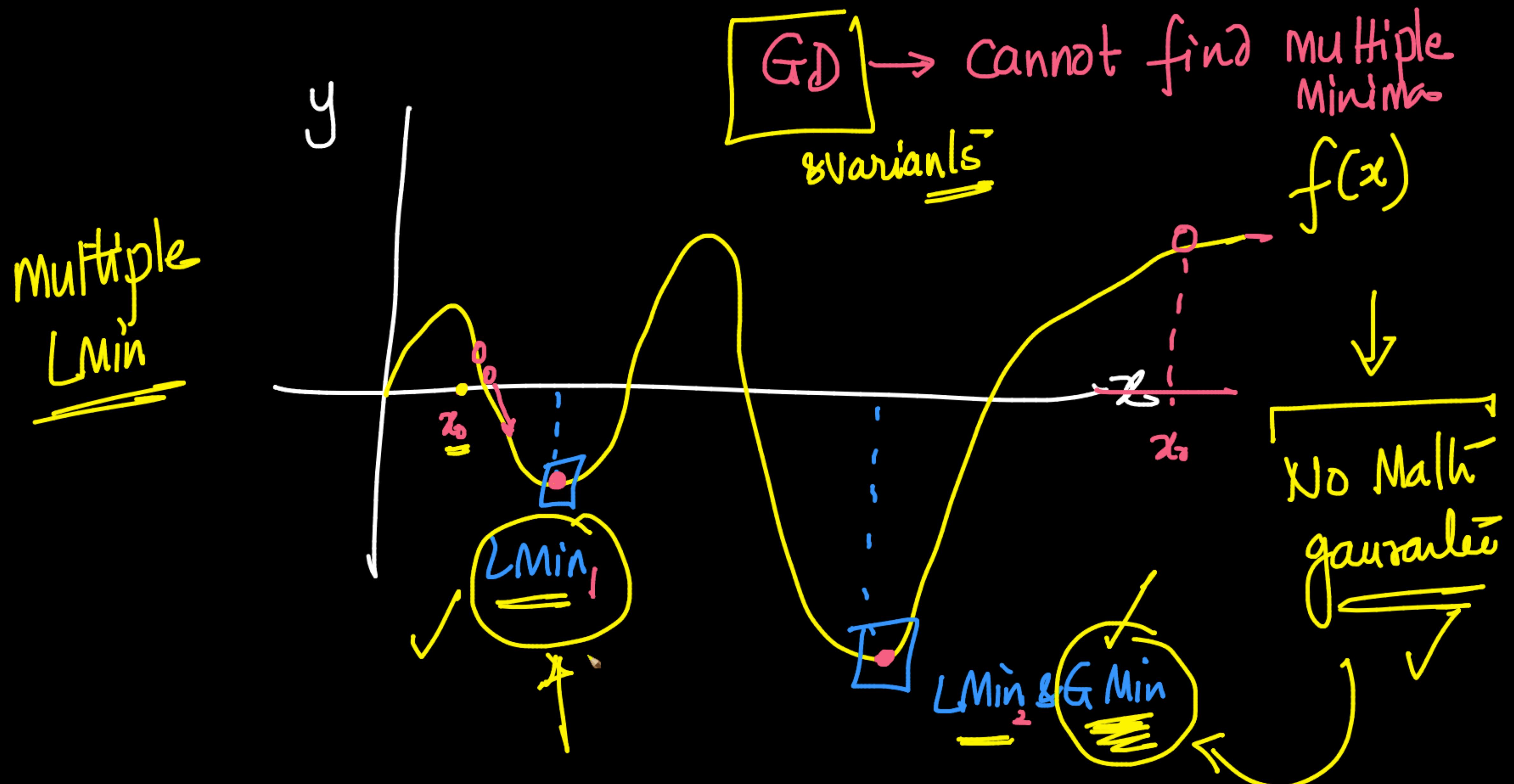
Constrained optim

→ classfr:





89 / 89



GD or variant

↓
[prog; internally ==]

