

Machine Learning

K Nearest Neighbors

K Nearest Neighbors

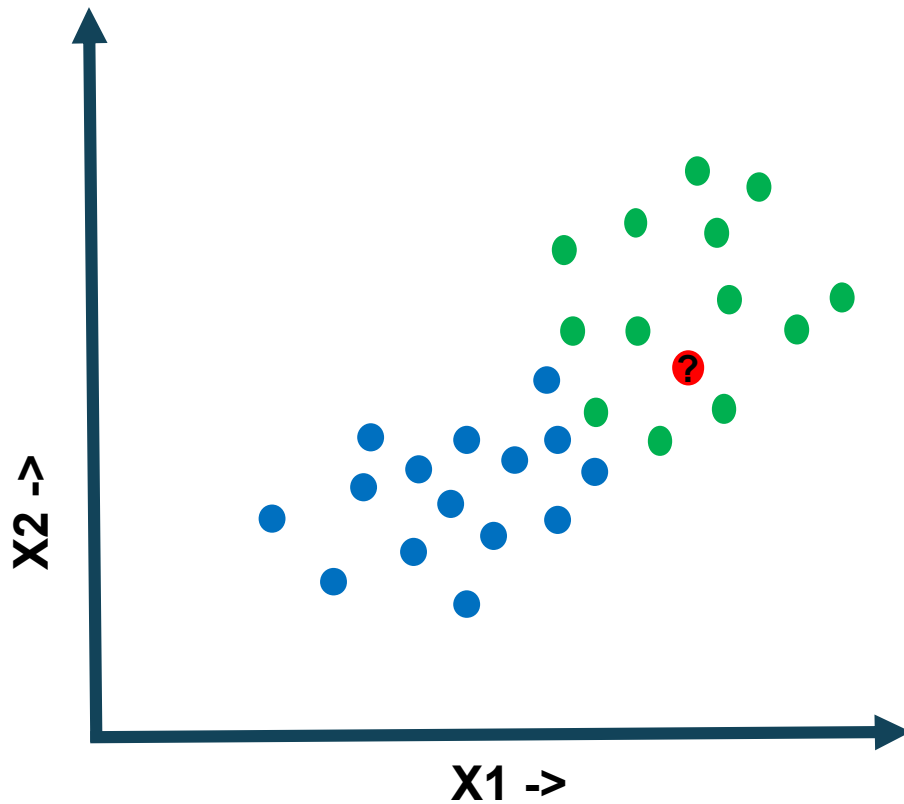
- A supervised learning method
- Though it is a supervised learning method, it is a 'lazy learner', i.e. does not construct a model using training data
- Classification is determined based on a majority vote of the nearest neighbors of each point
- Suitable for classification where items in a class tend to be fairly homogenous on the values of attributes
- Not suitable if the data is too noisy or the target classes do not have clear demarcation in terms of attribute values

K Nearest Neighbors

- Nonparametric model: distribution-free tests because no assumption of the data needing to follow a specific distribution
- Commonly used for classification
- Can also be used for regression

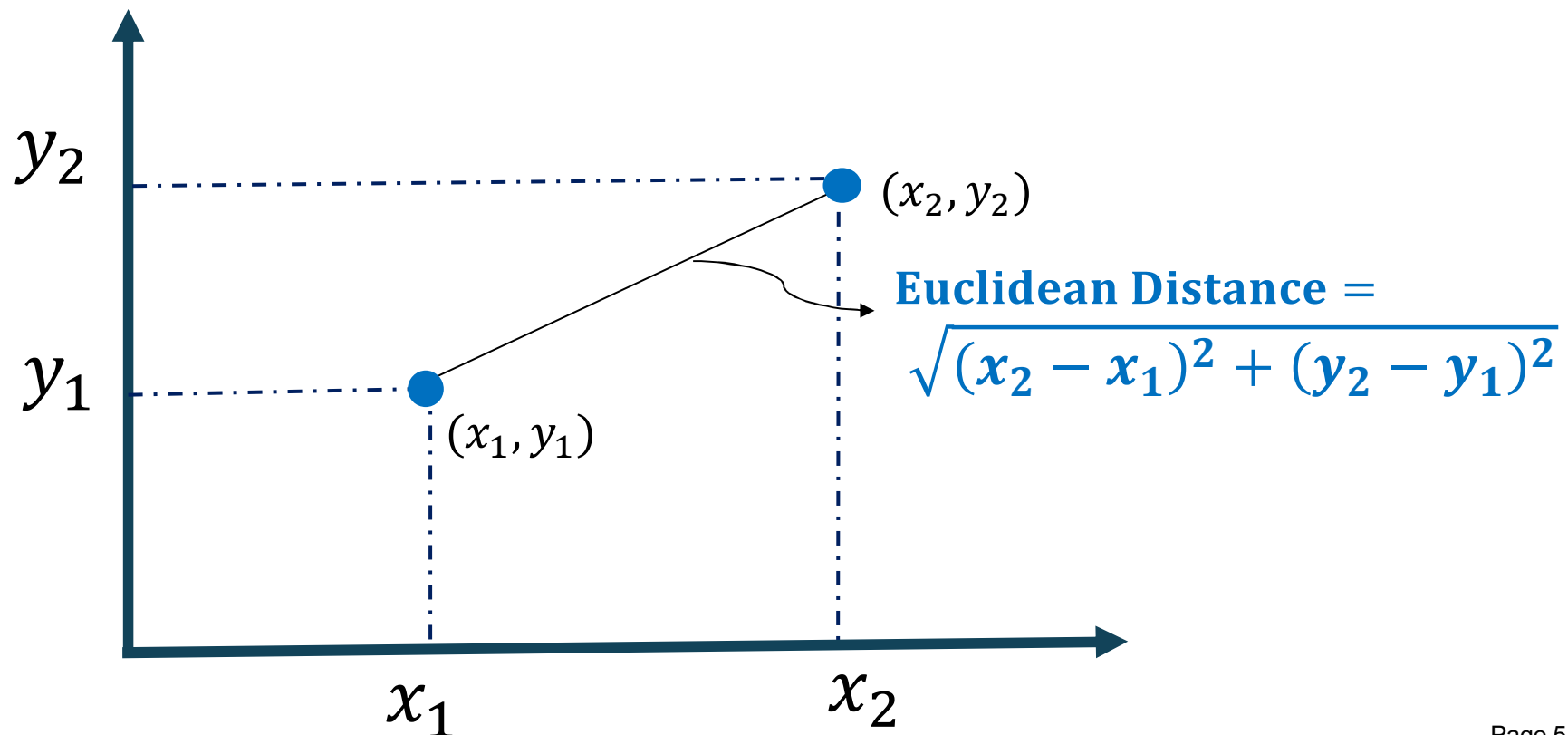
K Nearest Neighbors

- New data point is assigned a class which has the most data points in the nearest neighbors of the point



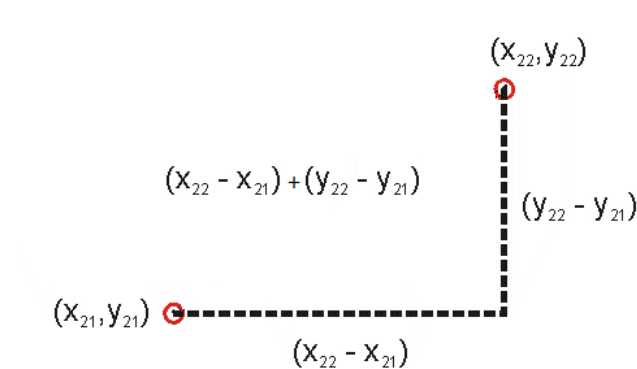
K Nearest Neighbors

- Nearest neighbors are calculated based on shortest distance.
- Most commonly used distance measure is Euclidean distance (default)



K Nearest Neighbors

- Manhattan / Taxi Distance: Also called L1 norm. It is the sum of the differences in each dimension.



- Mahalanobis distance – takes into account the covariance between attributes
- Jaccard distance (for Boolean data) = number of non-equal dimensions / number of nonzero dimensions.
- Matching distance (for Boolean data) = number of non-equal dimensions / number of dimensions

K Nearest Neighbors

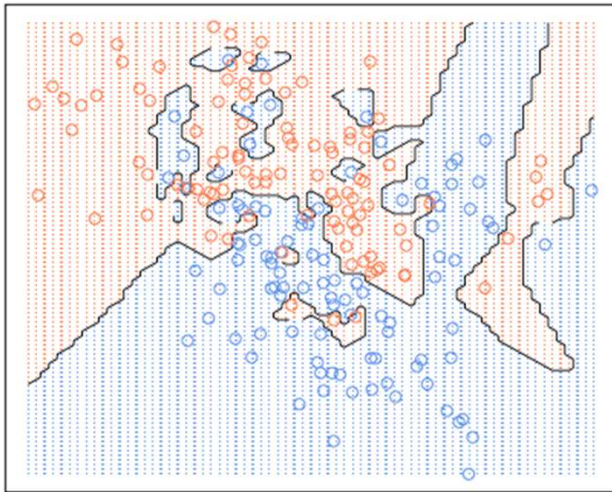
- To ensure all the dimensions have similar scale, it is necessary to normalize the data. Common way to normalize data is
 - Z-score standardization using formula $z_i = \frac{x_i - \bar{x}}{s}$
 - Min-max scaler
 - $X_{std} = (X - \min) / (\max - \min)$

K Nearest Neighbors

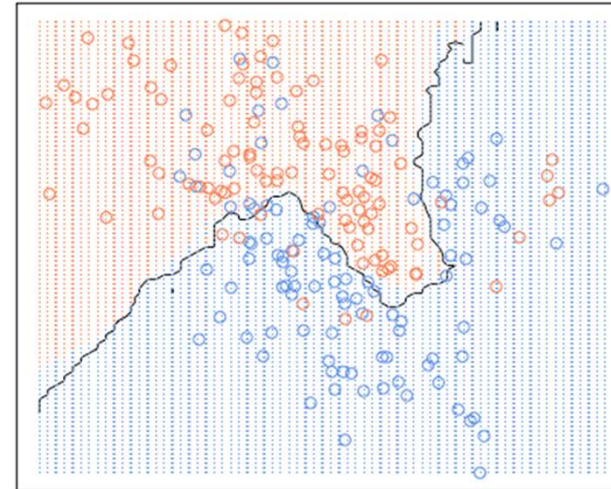
- Advantages -
 - Makes no assumptions about distributions of data
 - Easy to understand and implement
 - Not impacted by outliers
 - Able to segregate classes using non-linear boundary
- Dis-advantages -
 - Determining the optimal value of K is a challenge
 - Not effective when the class distributions have large overlap
 - Does not output any models. Calculates distances for every new point. Hence very computation intensive

Selecting value of K

nearest neighbour ($k = 1$)



20-nearest neighbour



- K is a hyperparameter must be picked in order to get the best possible fit for the data set
- K controls the shape of the decision boundary we talked about earlier
- A small value of k means that noise will have a higher influence on the result

K Nearest Neighbors

- Hands-on exercise

Confusion Matrix

		Predicted		
		A	B	C
Actual	A	15	0	0
	B	0	19	2
	C	0	0	17

- Classification accuracy = correct predictions / total predictions
- Precision is the proportion of the predicted positive cases that were correct.
 - Precision of C = $17 / (17+2)$
- Recall is the proportion of positive cases that were correctly identified
 - Recall for B = $19 / (19+2)$
- F1 Score = $2 * (\text{Recall} * \text{Precision}) / (\text{Recall} + \text{Precision})$

Confusion Matrix

		Predicted	
		Positive	Negative
Actual	Positive	TP	FN
	Negative	FP	TN

$$\text{Accuracy} = \frac{TP + TN}{TP + TN + FP + FN}$$

$$\text{Recall} = \frac{TP}{TP + FN}$$

$$\text{Precision} = \frac{TP}{TP + FP}$$

- True Positive (TP) : Observation is positive, and is predicted to be positive.
 - False Negative (FN) : Observation is positive, but is predicted negative.
 - True Negative (TN) : Observation is negative, and is predicted to be negative.
 - False Positive (FP) : Observation is negative, but is predicted positive.
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- Note that in binary classification, recall of the positive class is also known as “sensitivity”; recall of the negative class is “specificity”.
 - High recall, low precision: This means that most of the positive examples are correctly recognized (low FN) but there are a lot of false positives.
 - Low recall, high precision: This shows that we miss a lot of positive examples (high FN) but those we predict as positive are indeed positive (low FP)