

Series 2

1) Solve:

a)
$$\begin{bmatrix} 1 & 0 \\ 2 & 3 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 3 & 0.5 \\ 0.5 & 2 \\ -0.5 & 1 \end{bmatrix}$$

b)
$$\left(\left(\begin{bmatrix} 0.5 & -1 & -2 \\ 1 & 0.5 & -1 \\ 2 & 1 & -0.5 \end{bmatrix}^T \right)^T \right)^T$$

c)
$$\begin{bmatrix} 1 & 0 & 30 \\ 0 & 1 & 15 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

d)
$$\begin{bmatrix} 1 & -1 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}^{T} \begin{bmatrix} 1 & 0 & 30 \\ 0 & 1 & 15 \\ 0 & 0 & 1 \end{bmatrix}$$

- 2) Reuse the code of Series 1, Ex. 2 to implement a new class for modeling 3x3 matrices. This new class should feature:
 - 1) Matrix by vector multiplication.
 - 2) Matrix by matrix multiplication.
 - 3) Matrix transpose.

Validate your code by repeating exercise 1) using your classes.

- 3) Repeat exercise 2) using the vector and matrix classes provided by the GLM library (http://glm.g-truc.net). Compare your software design with the one adopted in GLM.
- 4) Let a triangle be defined by its vertices $\mathbf{a} = [-15\ 0\ -50]$, $\mathbf{b} = [15\ 0\ -50]$ and $\mathbf{c} = [0\ 15\ -50]$. Use GLM to compute the position of its vertices in *clip coordinates* after being modified by a perspective projection matrix with a field of view of 45°, an aspect-ratio of 1, near plane at 1 and far plane at 100 units.

Add then the following operations to the pipeline (first one by one, then all together):

 T_1 = isotropic scaling of 0.5, T_2 = rotation of 90° on Z, T_3 = translation of 10 units on X.